

# Semiconductors

Part 2

May 1980

Rectifier diodes

Regulator diodes

High-voltage rectifier stacks

Thyristors

Triacs





## POWER DIODES, THYRISTORS, TRIACS

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**SELECTION GUIDE** 

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**GENERAL SECTION**

**A**

**RECTIFIER DIODES**

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## DATA HANDBOOK SYSTEM

Our Data Handbook System is a comprehensive source of information on electronic components, sub-assemblies and materials; it is made up of three series of handbooks each comprising several parts.

ELECTRON TUBES	BLUE
SEMICONDUCTORS AND INTEGRATED CIRCUITS	RED
COMPONENTS AND MATERIALS	GREEN

The several parts contain all pertinent data available at the time of publication, and each is revised and reissued periodically.

Where ratings or specifications differ from those published in the preceding edition they are pointed out by arrows. Where application information is given it is advisory and does not form part of the product specification.

If you need confirmation that the published data about any of our products are the latest available, please contact our representative. He is at your service and will be glad to answer your inquiries.

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October 1977

## ELECTRON TUBES (BLUE SERIES)

Starting in 1980, new part numbers and corresponding codes are being introduced. The former code of the preceding issue is given in brackets under the new code.

Part 1	February 1980	T1 02-80 (ET1a 12-75)	Tubes for r.f. heating
Part 2	April 1980	T2 04-80 (ET1b 08-77)	Transmitting tubes for communications
Part 2a	November 1977	ET2a 11-77	<b>Microwave tubes</b> Communication magnetrons, magnetrons for microwave heating, klystrons, travelling-wave tubes, diodes, triodes T-R switches
Part 2b	May 1978	ET2b 05-78	<b>Microwave semiconductors and components</b> Gunn, Impatt and noise diodes, mixer and detector diodes, backward diodes, varactor diodes, Gunn oscillators, sub-assemblies, circulators and isolators
Part 3	January 1975	ET3 01-75	Special Quality tubes, miscellaneous devices
Part 4	March 1975	ET4 03-75	Receiving tubes
Part 5a	October 1979	ET5a 10-79	<b>Cathode-ray tubes</b> Instrument tubes, monitor and display tubes, C.R. tubes for special applications
Part 5b	December 1978	ET5b 12-78	Camera tubes and accessories, image intensifiers
Part 6	January 1977	ET6 01-77	<b>Products for nuclear technology</b> Channel electron multipliers, neutron tubes, Geiger-Müller tubes
Part 7a	March 1977	ET7a 03-77	<b>Gas-filled tubes</b> Thyratrons, industrial rectifying tubes, ignitrons, high-voltage rectifying tubes
Part 7b	May 1979	ET7b 05-79	<b>Gas-filled tubes</b> Segment indicator tubes, indicator tubes, switching diodes, dry reed contact units
Part 8	July 1979	ET8 07-79	<b>Picture tubes and components</b> Colour TV picture tubes, black and white TV picture tubes, monitor tubes, components for colour television, components for black and white television.
Part 9	March 1978	ET9 03-78	<b>Photomultiplier tubes; phototubes</b>

## SEMICONDUCTORS AND INTEGRATED CIRCUITS (RED SERIES)

Starting in 1980, new part numbers and corresponding codes are being introduced. The former code of the preceding issue is given in brackets under the new code.

<b>Part 1</b>	<b>March 1980</b>	<b>S1 03-80</b> <b>(SC1b 05-77)</b>	<b>Diodes</b> Small-signal germanium diodes, small-signal silicon diodes, special diodes, voltage regulator diodes (< 1,5 W), voltage reference diodes, tuner diodes, rectifier diodes
<b>Part 2</b>	<b>May 1980</b>	<b>S2 05-80</b> <b>(SC1a 08-78)</b>	<b>Power diodes, thyristors, triacs</b> Rectifier diodes, voltage regulator diodes (> 1,5 W), rectifier stacks, thyristors, triacs
<b>Part 2</b>	<b>June 1979</b>	<b>SC2 06-79</b>	<b>Low-frequency power transistors</b>
<b>Part 3</b>	<b>January 1978</b>	<b>SC3 01-78</b>	<b>High-frequency, switching and field-effect transistors*</b>
<b>Part 3</b>	<b>April 1980</b>	<b>S3 04-80</b> <b>(SC2 11-77, partly)</b> <b>(SC3 01-78, partly)</b>	<b>Small-signal transistors</b>
<b>Part 4a</b>	<b>December 1978</b>	<b>SC4a 12-78</b>	<b>Transmitting transistors and modules</b>
<b>Part 4b</b>	<b>September 1978</b>	<b>SC4b 09-78</b>	<b>Devices for optoelectronics</b> Photosensitive diodes and transistors, light-emitting diodes, photocouplers, infrared sensitive devices, photoconductive devices
<b>Part 4c</b>	<b>July 1978</b>	<b>SC4c 07-78</b>	<b>Discrete semiconductors for hybrid thick and thin-film circuits</b>
<b>Part 5a</b>	<b>November 1976</b>	<b>SC5a 11-76</b>	<b>Professional analogue integrated circuits</b>
<b>Part 5b</b>	<b>March 1977</b>	<b>SC5b 03-77</b>	<b>Consumer integrated circuits</b> Radio, audio, television
<b>Part 6</b>	<b>October 1977</b>	<b>SC6 10-77</b>	<b>Digital integrated circuits</b> LOCMOS HE4000B family
<b>Part 6b</b>	<b>August 1979</b>	<b>SC6b 08-79</b>	<b>ICs for digital systems in radio and television receivers</b>
<b>Signetics integrated circuits</b>			Bipolar and MOS memories 1979 Bipolar and MOS microprocessors 1978 Analogue circuits 1979 Logic - TTL 1978

\* Field-effect transistors and wideband transistors will be transferred to S5 and SC3c respectively. The old book SC3 01-78 should be kept until then.

## COMPONENTS AND MATERIALS (GREEN SERIES)

Starting in 1980, new part numbers and corresponding codes are being introduced. The former code of the preceding issue is given in brackets under the new code.

Part 1	July 1979	CM1 07-79	<b>Assemblies for industrial use</b> PLC modules, high noise immunity logic FZ/30 series, NORbits 60-series, 61-series, 90-series, input devices, hybrid integrated circuits, peripheral devices
Part 3a	September 1978	CM3a 09-78	<b>FM tuners, television tuners, surface acoustic wave filters</b>
Part 3b	October 1978	CM3b 10-78	<b>Loudspeakers</b>
Part 4a	November 1978	CM4a 11-78	<b>Soft Ferrites</b> Ferrites for radio, audio and television, beads and chokes, Ferroxcube potcores and square cores, Ferroxcube transformer cores
Part 4b	February 1979	CM4b 02-79	<b>Piezoelectric ceramics, permanent magnet materials</b>
Part 6	April 1977	CM6 04-77	<b>Electric motors and accessories</b> Small synchronous motors, stepper motors, miniature direct current motors
Part 7	September 1971	CM7 09-71	<b>Circuit blocks</b> Circuit blocks 100 kHz-series, circuit blocks 1-series, circuit blocks 10-series, circuit blocks for ferrite core memory drive
Part 7a	January 1979	CM7a 01-79	<b>Assemblies</b> Circuit blocks 40-series and CSA70 (L), counter modules 50-series, input/output devices
Part 8	June 1979	CM8 06-79	<b>Variable mains transformers</b>
Part 9	August 1979	CM9 08-79	<b>Piezoelectric quartz devices</b> Quartz crystal units, temperature compensated crystal oscillators
Part 10	April 1978	CM10 04-78	<b>Connectors</b>
Part 11	December 1979	CM11 12-79	<b>Non-linear resistors</b> Voltage dependent resistors (VDR), light dependant resistors (LDR), negative temperature coefficient thermistors (NTC), positive temperature coefficient thermistors (PTC)
Part 12	November 1979	CM12 11-79	<b>Variable resistors and test switches</b>
Part 13	December 1979	CM13 12-79	<b>Fixed resistors</b>
Part 14	April 1980	C14 04-80 (CM2b 02-78)	<b>Electrolytic and solid capacitors</b>
Part 15	May 1980	C15 05-80 (CM2b 02-78)	<b>Film capacitors, ceramic capacitors, variable capacitors</b>

## INDEX OF TYPE NUMBERS

## Data Handbooks Semiconductors

The inclusion of a type number in this publication does not necessarily imply its availability.

type no.	part	section	type no.	part	section	type no.	part	section
AA119	S1	PC	BAV20	S1	WD	BB405G	S1	T
AAZ13	S1	GB	BAV21	S1	WD	BBY31	4c	Mm
AAZ15	S1	GB	BAV45	S1	Sp	BC107	S3	Sm
AAZ17	S1	GB	BAV70	4c	Mm	BC108	S3	Sm
AAZ18	S1	GB	BAV99	4c	Mm	BC109	S3	Sm
BA182	S1	T	BAW56	4c	Mm	BC140	S3	Sm
BA220	S1	WD	BAW62	S1	WD	BC141	S3	Sm
BA221	S1	WD	BAX12	S1	WD	BC146	S3	Sm
BA223	S1	T	BAX12A	S1	WD	BC147	S3	Sm
BA243	S1	T	BAX13	S1	WD	BC148	S3	Sm
BA244	S1	T	BAX14A	S1	WD	BC149	S3	Sm
BA280	S1	T	BAX16	S1	WD	BC157	S3	Sm
BA314	S1	Vrg	BAX17	S1	WD	BC158	S3	Sm
BA315	S1	Vrg	BAX18A	S1	WD	BC159	S3	Sm
BA316	S1	WD	BB105B	S1	T	BC160	S3	Sm
BA317	S1	WD	BB105G	S1	T	BC161	S3	Sm
BA318	S1	WD	BB106	S1	T	BC177	S3	Sm
BA379	S1	T	BB109G	S1	T	BC178	S3	Sm
BAS11	S1	WD	BB110B	S1	T	BC179	S3	Sm
BAS16	4c	Mm	BB110G	S1	T	BC200	S3	Sm
BAT17	4c	Mm	BB119	S1	T	BC264A	SC3	FET
BAT18	4c	Mm	BB204B	S1	T	BC264B	SC3	FET
BAV10	S1	WD	BB204G	S1	T	BC264C	SC3	FET
BAV18	S1	WD	BB212	S1	T	BC264D	SC3	FET
BAV19	S1	WD	BB405B	S1	T	BC327	S3	Sm

FET = Field-effect transistors

GB = Germanium gold bonded diodes

Mm = Discrete semiconductors for hybrid  
thick and thin-film circuits

PC = Germanium point contact diodes

Sm = Small-signal transistors

Sp = Special diodes

T = Tuner diodes

Vrg = Voltage regulator diodes

WD = Silicon whiskerless diodes

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type no.	part	section	type no.	part	section	type no.	part	section
BC328	S3	Sm	BCX55	4c	Mm	BD231	SC2	P
BC337	S3	Sm	BCX56	4c	Mm	BD232	SC2	P
BC338	S3	Sm	BCY30A	S3	Sm	BD233	SC2	P
BC368	S3	Sm	BCY31A	S3	Sm	BD234	SC2	P
BC369	S3	Sm	BCY32A	S3	Sm	BD235	SC2	P
BC375	S3	Sm	BCY33A	S3	Sm	BD236	SC2	P
BC376	S3	Sm	BCY34A	S3	Sm	BD237	SC2	P
BC546	S3	Sm	BCY56	S3	Sm	BD238	SC2	P
BC547	S3	Sm	BCY57	S3	Sm	BD291	SC2	P
BC548	S3	Sm	BCY58	S3	Sm	BD292	SC2	P
BC549	S3	Sm	BCY59	S3	Sm	BD293	SC2	P
BC550	S3	Sm	BCY70	S3	Sm	BD294	SC2	P
BC556	S3	Sm	BCY71	S3	Sm	BD295	SC2	P
BC557	S3	Sm	BCY72	S3	Sm	BD296	SC2	P
BC558	S3	Sm	BCY78	S3	Sm	BD329	SC2	P
BC559	S3	Sm	BCY79	S3	Sm	BD330	SC2	P
BC560	S3	Sm	BCY87	S3	Sm	BD331	SC2	P
BC635	S3	Sm	BCY88	S3	Sm	BD332	SC2	P
BC636	S3	Sm	BCY89	S3	Sm	BD333	SC2	P
BC637	S3	Sm	BD131	SC2	P	BD334	SC2	P
BC638	S3	Sm	BD132	SC2	P	BD335	SC2	P
BC639	S3	Sm	BD133	SC2	P	BD336	SC2	P
BC640	S3	Sm	BD135	SC2	P	BD337	SC2	P
BCW29;R	4c	Mm	BD136	SC2	P	BD338	SC2	P
BCW30;R	4c	Mm	BD137	SC2	P	BD433	SC2	P
BCW31;R	4c	Mm	BD138	SC2	P	BD434	SC2	P
BCW32;R	4c	Mm	BD139	SC2	P	BD435	SC2	P
BCW33;R	4c	Mm	BD140	SC2	P	BD436	SC2	P
BCW69;R	4c	Mm	BD181	SC2	P	BD437	SC2	P
BCW70;R	4c	Mm	BD182	SC2	P	BD438	SC2	P
BCW71;R	4c	Mm	BD183	SC2	P	BD645	SC2	P
BCW72;R	4c	Mm	BD201	SC2	P	BD646	SC2	P
BCX17;R	4c	Mm	BD202	SC2	P	BD647	SC2	P
BCX18;R	4c	Mm	BD203	SC2	P	BD648	SC2	P
BCX19;R	4c	Mm	BD204	SC2	P	BD649	SC2	P
BCX20;R	4c	Mm	BD226	SC2	P	BD650	SC2	P
BCX51	4c	Mm	BD227	SC2	P	BD651	SC2	P
BCX52	4c	Mm	BD228	SC2	P	BD652	SC2	P
BCX53	4c	Mm	BD229	SC2	P	BD675	SC2	P
BCX54	4c	Mm	BD230	SC2	P	BD676	SC2	P

FET = Field-effect transistors

Mm = Discrete semiconductors for hybrid thick and thin-film circuits



type no.	part	section	type no.	part	section	type no.	part	section
BD677	SC2	P	BDT91	SC2	P	BDX66C	SC2	P
BD678	SC2	P	BDT92	SC2	P	BDX67	SC2	P
BD679	SC2	P	BDT93	SC2	P	BDX67A	SC2	P
BD680	SC2	P	BDT94	SC2	P	BDX67B	SC2	P
BD681	SC2	P	BDT95	SC2	P	BDX67C	SC2	P
BD682	SC2	P	BDT96	SC2	P	BDX77	SC2	P
BD683	SC2	P	BDV64	SC2	P	BDX78	SC2	P
BD684	SC2	P	BDV64A	SC2	P	BDX91	SC2	P
BD933	SC2	P	BDV64B	SC2	P	BDX92	SC2	P
BD934	SC2	P	BDV65	SC2	P	BDX93	SC2	P
BD935	SC2	P	BDV65A	SC2	P	BDX94	SC2	P
BD936	SC2	P	BDV65B	SC2	P	BDX95	SC2	P
BD937	SC2	P	BDX35	SC2	P	BDX96	SC2	P
BD938	SC2	P	BDX36	SC2	P	BDY20	SC2	P
BD939	SC2	P	BDX37	SC2	P	BDY90	SC2	P
BD940	SC2	P	BDX42	SC2	P	BDY91	SC2	P
BD941	SC2	P	BDX43	SC2	P	BDY92	SC2	P
BD942	SC2	P	BDX44	SC2	P	BDY93	SC2	P
BD943	SC2	P	BDX45	SC2	P	BDY94	SC2	P
BD944	SC2	P	BDX46	SC2	P	BDY96	SC2	P
BD945	SC2	P	BDX47	SC2	P	BDY97	SC2	P
BD946	SC2	P	BDX62	SC2	P	BF 115	S3	Sm
BD947	SC2	P	BDX62A	SC2	P	BF 180	S3	Sm
BD948	SC2	P	BDX62B	SC2	P	BF 181	S3	Sm
BD949	SC2	P	BDX62C	SC2	P	BF 182	S3	Sm
BD950	SC2	P	BDX63	SC2	P	BF 183	S3	Sm
BD951	SC2	P	BDX63A	SC2	P	BF 194	S3	Sm
BD952	SC2	P	BDX63B	SC2	P	BF 195	S3	Sm
BD953	SC2	P	BDX63C	SC2	P	BF 196	S3	Sm
BD954	SC2	P	BDX64	SC2	P	BF 197	S3	Sm
BD955	SC2	P	BDX64A	SC2	P	BF 198	S3	Sm
BD956	SC2	P	BDX64B	SC2	P	BF 199	S3	Sm
BDT62	SC2	P	BDX64C	SC2	P	BF 200	S3	Sm
BDT62A	SC2	P	BDX65	SC2	P	BF 240	S3	Sm
BDT62B	SC2	P	BDX65A	SC2	P	BF 241	S3	Sm
BDT62C	SC2	P	BDX65B	SC2	P	BF 245A	SC3	FET
BDT63	SC2	P	BDX65C	SC2	P	BF 245B	SC3	FET
BDT63A	SC2	P	BDX66	SC2	P	BF 245C	SC3	FET
BDT63B	SC2	P	BDX66A	SC2	P	BF 256A	SC3	FET
BDT63C	SC2	P	BDX66B	SC2	P	BF 256B	SC3	FET

P = Low-frequency power transistors

Sm = Small-signal transistors

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type no.	part	section	type no.	part	section	type no.	part	section
BF256C	SC3	FET	BFQ17	4c	Mm	BFT93;R	4c	Mm
BF324	S3	Sm	BFQ18A	4c	Mm	BFW10	SC3	FET
BF327	SC3	FET	BFQ19	4c	Mm	BFW11	SC3	FET
BF336	S3	Sm	BFQ23	SC3	HFSW	BFW12	SC3	FET
BF337	S3	Sm	BFQ24	SC3	HFSW	BFW13	SC3	FET
BF338	S3	Sm	BFQ32	SC3	HFSW	BFW16A	SC3	HFSW
BF362	S3	Sm	BFQ34	SC3	HFSW	BFW17A	SC3	HFSW
BF363	S3	Sm	BFQ42	4a	Tra	BFW30	SC3	HFSW
BF419	SC2	P	BFQ43	4a	Tra	BFW45	SC3	HFSW
BF422	S3	Sm	BFR29	SC3	FET	BFW61	SC3	FET
BF423	S3	Sm	BFR30	4c	Mm	BFW92	SC3	HFSW
BF450	S3	Sm	BFR31	4c	Mm	BFW93	SC3	HFSW
BF451	S3	Sm	BFR49	SC3	HFSW	BFX29	S3	Sm
BF457	SC2	P	BFR53;R	4c	Mm	BFX30	S3	Sm
BF458	SC2	P	BFR54	S3	Sm	BFX34	S3	Sm
BF459	SC2	P	BFR64	SC3	HFSW	BFX84	S3	Sm
BF469	SC2	P	BFR65	SC3	HFSW	BFX85	S3	Sm
BF470	SC2	P	BFR84	SC3	FET	BFX86	S3	Sm
BF471	SC2	P	BFR90	SC3	HFSW	BFX87	S3	Sm
BF472	SC2	P	BFR91	SC3	HFSW	BFX88	S3	Sm
BF480	S3	Sm	BFR92;R	4c	Mm	BFX89	SC3	HFSW
BF494	S3	Sm	BFR93;R	4c	Mm	BFY50	S3	Sm
BF495	S3	Sm	BFR94	SC3	HFSW	BFY51	S3	Sm
BF496	S3	Sm	BFR95	SC3	HFSW	BFY52	S3	Sm
BF550;R	4c	Mm	BFR96	SC3	HFSW	BFY55	S3	Sm
BF622	4c	Mm	BFS17;R	4c	Mm	BFY90	SC3	HFSW
BF623	4c	Mm	BFS18;R	4c	Mm	BGY22	4a	Tra
BF926	S3	Sm	BFS19;R	4c	Mm	BGY22A	4a	Tra
BF936	S3	Sm	BFS20;R	4c	Mm	BGY23	4a	Tra
BF939	S3	Sm	BFS21	SC3	FET	BGY23A	4a	Tra
BF967	S3	Sm	BFS21A	SC3	FET	BGY32	4a	Tra
BF970	S3	Sm	BFS22A	4a	Tra	BGY33	4a	Tra
BF979	S3	Sm	BFS23A	4a	Tra	BGY35	4a	Tra
BFQ10	SC3	FET	BFS28	SC3	FET	BGY36	4a	Tra
BFQ11	SC3	FET	BFT24	SC3	HFSW	BGY37	SC3	HFSW
BFQ12	SC3	FET	BFT25;R	4c	Mm	BLV11	4a	Tra
BFQ13	SC3	FET	BFT44	S3	Sm	BLV11	4a	Tra
BFQ14	SC3	FET	BFT45	S3	Sm	BLV20	4a	Tra
BFQ15	SC3	FET	BFT46	4c	Mm	BLV21	4a	Tra
BFQ16	SC3	FET	BFT92;R	4c	Mm	BLW29	4a	Tra

FET = Field-effect transistors  
HFSW = High-frequency and switching transistors

Mm = Discrete semiconductors for hybrid  
thick and thin-film circuits

type no.	part	section	type no.	part	section	type no.	part	section
BLW31	4a	Tra	BLY87A	4a	Tra	BSR41	4c	Mm
BLW32	4a	Tra	BLY87C	4a	Tra	BSR42	4c	Mm
BLW33	4a	Tra	BLY88A	4a	Tra	BSR43	4c	Mm
BLW34	4a	Tra	BLY88C	4a	Tra	BSR50	S3	Sm
BLW60	4a	Tra	BLY89A	4a	Tra	BSR51	S3	Sm
BLW60C	4a	Tra	BLY89C	4a	Tra	BSR52	S3	Sm
BLW64	4a	Tra	BLY90	4a	Tra	BSR56	4c	Mm
BLW75	4a	Tra	BLY91A	4a	Tra	BSR57	4c	Mm
BLW76	4a	Tra	BLY91C	4a	Tra	BSR58	4c	Mm
BLW77	4a	Tra	BLY92A	4a	Tra	BSR60	S3	Sm
BLW78	4a	Tra	BLY92C	4a	Tra	BSR61	S3	Sm
BLW79	4a	Tra	BLY93A	4a	Tra	BSR62	S3	Sm
BLW80	4a	Tra	BLY93C	4a	Tra	BSS38	S3	Sm
BLW81	4a	Tra	BLY94	4a	Tra	BSS50	S3	Sm
BLW82	4a	Tra	BPW22	4b	PDT	BSS51	S3	Sm
BLW83	4a	Tra	BPW34	4b	PDT	BSS52	S3	Sm
BLW84	4a	Tra	BPX25	4b	PDT	BSS60	S3	Sm
BLW85	4a	Tra	BPX29	4b	PDT	BSS61	S3	Sm
BLW86	4a	Tra	BPX40	4b	PDT	BSS62	S3	Sm
BLW87	4a	Tra	BPX41	4b	PDT	BSS63;R	4c	Mm
BLW95	4a	Tra	BPX42	4b	PDT	BSS64;R	4c	Mm
BLW98	4a	Tra	BPX47A	4b	PDT	BSS68	S3	Sm
BLX13	4a	Tra	BPX70	4b	PDT	BSV15	S3	Sm
BLX13C	4a	Tra	BPX71	4b	PDT	BSV16	S3	Sm
BLX14	4a	Tra	BPX72	4b	PDT	BSV17	S3	Sm
BLX15	4a	Tra	BPX94	4b	PDT	BSV52;R	4c	Mm
BLX39	4a	Tra	BPX95B	4b	PDT	BSV64	S3	Sm
BLX65	4a	Tra	BR100/03	S2	Th	BSV78	SC3	FET
BLX66	4a	Tra	BR101	S3	Sm	BSV79	SC3	FET
BLX67	4a	Tra	BRY39P	S3	Sm	BSV80	SC3	FET
BLX68	4a	Tra	BRY39S	S3	Sm	BSV81	SC3	FET
BLX69A	4a	Tra	BRY39T	S2/S3	Th/Sm	BSW66A	S3	Sm
BLX91A	4a	Tra	BRY56	S3	Sm	BSW67A	S3	Sm
BLX92A	4a	Tra	BRY61	4c	Mm	BSW68A	S3	Sm
BLX93A	4a	Tra	BSR12;R	4c	Mm	BSX19	S3	Sm
BLX94A	4a	Tra	BSR30	4c	Mm	BSX20	S3	Sm
BLX95	4a	Tra	BSR31	4c	Mm	BSX21	S3	Sm
BLX96	4a	Tra	BSR32	4c	Mm	BSX45	S3	Sm
BLX97	4a	Tra	BSR33	4c	Mm	BSX46	S3	Sm
BLX98	4a	Tra	BSR40	4c	Mm	BSX47	S3	Sm

P = Low-frequency power transistors  
 PDT = Photodiodes or transistors  
 R = Rectifier diodes

Sm = Small-signal transistors  
 Th = Thyristors  
 Tra = Transmitting transistors and modules

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type no.	part	section	type no.	part	section	type no.	part	section
BSX59	S3	Sm	BU326A	SC2	P	BY476	S1	R
BSX60	S3	Sm	BU426	SC2	P	BY477	S1	R
BSX61	S3	Sm	BU426A	SC2	P	BY478	S1	R
BSY59A	S3	Sm	BU433	SC2	P	BY509	S1	R
BT136 *	S2	Tri	BUW84	SC2	P	BYV21 *	S2	R
BT137 *	S2	Tri	BUW85	SC2	P	BYV30 *	S2	R
BT138 *	S2	Tri	BUX80	SC2	P	BYV92 *	S2	R
BT139 *	S2	Tri	BUX81	SC2	P	BYV95A	S1	R
BT151 *	S2	Th	BUX82	SC2	P	BYV95B	S1	R
BT152 *	S2	Th	BUX83	SC2	P	BYV95C	S1	R
BT153	S2	Th	BUX84	SC2	P	BYV96D, E	S1	R
BT154	S2	Th	BUX85	SC2	P	BYW19 *	S2	R
BTW23 *	S2	Th	BUX86	SC2	P	BYW29 *	S2	R
BTW24 *	S2	Th	BUX87	SC2	P	BYW30 *	S2	R
BTW30S*	S2	Th	BY126M	S1	R	BYW31 *	S2	R
BTW31W*	S2	Th	BY127M	S1	R	BYW54	S1	R
BTW33 *	S2	Th	BY164	S2	R	BYW55	S1	R
BTW34 *	S2	Tri	BY179	S2	R	BYW56	S1	R
BTW38 *	S2	Th	BY184	S1	R	BYW92 *	S2	R
BTW40 *	S2	Th	BY206	S1	R	BYW95A	S1	R
BTW41 *	S2	Tri	BY207	S1	R	BYW95B	S1	R
BTW42 *	S2	Th	BY208 *	S1	R	BYW95C	S1	R
BTW43 *	S2	Tri	BY210	S1	R	BYW96D, E	S1	R
BTW45 *	S2	Th	BY223	S2	R	BYX10	S1	R
BTW47 *	S2	Th	BY224 *	S2	R	BYX22 *	S2	R
BTW92 *	S2	Th	BY225 *	S2	R	BYX25 *	S2	R
BTX18 *	S2	Th	BY226	S1	R	BYX30 *	S2	R
BTX94 *	S2	Tri	BY227	S1	R	BYX32 *	S2	R
BTY79 *	S2	Th	BY228	S1	R	BYX36 *	S1	R
BTY87 *	S2	Th	BY229 *	S2	R	BYX38 *	S2	R
BTY91 *	S2	Th	BY256	S2	R	BYX39 *	S2	R
BU126	SC2	P	BY257	S2	R	BYX42 *	S2	R
BU133	SC2	P	BY260 *	S2	R	BYX45 *	S2	R
BU204	SC2	P	BY261 *	S2	R	BYX46 *	S2	R
BU205	SC2	P	BY277 *	S2	R	BYX49 *	S2	R
BU206	SC2	P	BY409	S1	R	BYX50 *	S2	R
BU207A	SC2	P	BY409A	S1	R	BYX52 *	S2	R
BU208A	SC2	P	BY438	S1	R	BYX55 *	S1	R
BU209A	SC2	P	BY448	S1	R	BYX56 *	S2	R
BU326	SC2	P	BY458	S1	R	BYX71 *	S2	R

\* = series.

GB = Germanium gold bonded diodes

I = Infrared devices

LED = Light-emitting diodes

Mm = Discrete semiconductors for hybrid thick and thin-film circuits

P = Low-frequency power transistors

PC = Germanium point contact diodes

Ph = Photoconductive devices

PhC = Photocouplers

R = Rectifier diodes

type no.	part	section	type no.	part	section	type no.	part	section
BYX90	S1	R	CNY47	4b	PhC	OSB9310	S2	St
BYX91 *	S1	R	CNY47A	4b	PhC	OSB9410	S2	St
BYX94	S1	R	CNY48	4b	PhC	OSM9110	S2	St
BYX96 *	S2	R	CQY11B	4b	LED	OSM9210	S2	St
BYX97 *	S2	R	CQY11C	4b	LED	OSM9310	S2	St
BYX98 *	S2	R	CQY24A	4b	LED	OSM9410	S2	St
BYX99 *	S2	R	CQY46A	4b	LED	OSM9510	S2	St
BZV10	S1	Vrf	CQY47A	4b	LED	OSM9511	S2	St
BZV11	S1	Vrf	CQY49B	4b	LED	OSM9512	S2	St
BZV12	S1	Vrf	CQY49C	4b	LED	OSS9110	S2	St
BZV13	S1	Vrf	CQY50	4b	LED	OSS9210	S2	St
BZV14	S1	Vrf	CQY52	4b	LED	OSS9310	S2	St
BZV15 *	S2	Vrg	CQY54	4b	LED	OSS9410	S2	St
BZV46	S1	Vrg	CQY58	4b	LED	PH2369	S3	Sm
BZV85	S1	Vrg	CQY88	4b	LED	RPY58A	4b	Ph
BZW10	S2	TS	CQY89	4b	LED	RPY71	4b	Ph
BZW70 *	S2	TS	CQY94	4b	LED	RPY76A	4b	I
BZW86 *	S2	TS	CQY95	4b	LED	RPY82	4b	Ph
BZW91 *	S2	TS	CQY96	4b	LED	RPY84	4b	Ph
BZX61 *	S1	Vrg	CQY97	4b	LED	RPY85	4b	Ph
BZX70 *	S2	Vrg	OA47	S1	GB	RPY86	4b	I
BZX79 *	S1	Vrg	OA90	S1	PC	RPY87	4b	I
BZX84 *	4c	Mm	OA91	S1	PC	RPY88	4b	I
BZX87 *	S1	Vrg	OA95	S1	PC	RPY89	4b	I
BZX90	S1	Vrf	OA200	S1	WD			
BZX91	S1	Vrf	OA202	S1	WD			
BZX92	S1	Vrf	OM931	SC2	P			
BZX93	S1	Vrf	OM961	SC2	P			
BZX94	S1	Vrf	ORP10	4b	I			
BZY88 *	S1	Vrg	ORP13	4b	I			
BZY91 *	S2	Vrg	ORP23	4b	Ph			
BZY93 *	S2	Vrg	ORP52	4b	Ph			
BZY95 *	S2	Vrg	ORP60	4b	Ph			
BZY96 *	S2	Vrg	ORP61	4b	Ph			
CNY22	4b	PhC	ORP62	4b	Ph			
CNY23	4b	PhC	ORP66	4b	Ph			
CNY42	4b	PhC	ORP68	4b	Ph			
CNY43	4b	PhC	ORP69	4b	Ph			
CNY44	4b	PhC	OSB9110	S2	St			
CNY46	4b	PhC	OSB9210	S2	St			

\* = series.

Sm = Small-signal transistors

St = Rectifier stacks

Th = Thyristors

Tri = Triacs

TS = Transient suppressor diodes

Vrf = Voltage reference diodes

Vrg = Voltage regulator diodes

WD = Silicon whiskerless diodes

# INDEX

type no.	part	section	type no.	part	section	type no.	part	section
1N821	S1	Vrf	2N918	SC3	HFSW	2N3903	S3	Sm
1N823	S1	Vrf	2N929	S3	Sm	2N3904	S3	Sm
1N825	S1	Vrf	2N930	S3	Sm	2N3924	4a	Tra
1N827	S1	Vrf	2N1613	S3	Sm	2N3926	4a	Tra
1N829	S1	Vrf	2N1711	S3	Sm	2N3927	4a	Tra
1N914	S1	WD	2N1893	S3	Sm	2N3966	SC3	FET
1N916	S1	WD	2N2218	S3	Sm	2N4030	S3	Sm
1N3879	S2	R	2N2218A	S3	Sm	2N4031	S3	Sm
1N3880	S2	R	2N2219	S3	Sm	2N4032	S3	Sm
1N3881	S2	R	2N2219A	S3	Sm	2N4033	S3	Sm
1N3882	S2	R	2N2221	S3	Sm	2N4091	SC3	FET
1N3889	S2	R	2N2221A	S3	Sm	2N4092	SC3	FET
1N3890	S2	R	2N2222	S3	Sm	2N4093	SC3	FET
1N3891	S2	R	2N2222A	S3	Sm	2N4123	S3	Sm
1N3892	S2	R	2N2297	S3	Sm	2N4124	S3	Sm
1N3899	S2	R	2N2368	S3	Sm	2N4347	SC2	P
1N3900	S2	R	2N2369	S3	Sm	2N4391	SC3	FET
1N3901	S2	R	2N2369A	S3	Sm	2N4392	SC3	FET
1N3902	S2	R	2N2483	S3	Sm	2N4393	SC3	FET
1N3903	S2	R	2N2484	S3	Sm	2N4427	4a	Tra
1N3909	S2	R	2N2904	S3	Sm	2N4856	SC3	FET
1N3910	S2	R	2N2904A	S3	Sm	2N4857	SC3	FET
1N3911	S2	R	2N2905	S3	Sm	2N4858	SC3	FET
1N3912	S2	R	2N2905A	S3	Sm	2N4859	SC3	FET
1N3913	S2	R	2N2906	S3	Sm	2N4860	SC3	FET
1N4001			2N2906A	S3	Sm	2N4861	SC3	FET
to 4007	S1	R	2N2907	S3	Sm	2N5415	S3	Sm
1N4148	S1	WD	2N2907A	S3	Sm	2N5416	S3	Sm
1N4150	S1	WD	2N3019	S3	Sm	61SV	4b	I
1N4151	S1	WD	2N3020	S3	Sm			
1N4154	S1	WD	2N3053	S3	Sm			
1N4446	S1	WD	2N3055	SC2	P			
1N4448	S1	WD	2N3375	4a	Tra			
1N5060	S1	R	2N3439	S3	Sm			
1N5061	S1	R	2N3440	S3	Sm			
1N5062	S1	R	2N3442	SC2	P			
			2N3553	4a	Tra			
			2N3632	4a	Tra			
			2N3823	SC3	FET			
			2N3866	4a	Tra			

A = Accessories  
 DH = Diecast heatsinks  
 FET = Field-effect transistors

HE = Heatsink extrusions  
 HFSW = High-frequency and switching transistors  
 I = Infrared devices

type no.	part	section	type no.	part	section	type no.	part	section
56201c	SC2	A	56295	S2	A	56359c	SC2	A
56201d	SC2	A	56312	S2	DH	56359d	SC2	A
56201j	SC2	A	56313	S2	DH	56360a	SC2	A
56230	S2	HE	56314	S2	DH	56363	S2, SC2	A
56231	S2	HE	56315	S2	DH	56364	S2, SC2	A
56233	S2	A	56316	S2	A	56366	S2	A
56234	S2	A	56317	S2	A	56367	S2, SC2	A
56245	S3, 4a	A	56318	S2	DH	56368a	SC2	A
56246	S2, S3	A	56319	S2	DH	56368b	SC2	A
56253	S2	DH	56326	SC2	A	56369	S2, SC2	A
56256	S2	DH	56333	SC2	A	56378	SC2	A
56261a	SC2	A	56334	S2	DH	56379	SC2	A
56262A	S2	A	56339	SC2	A			
56264A	S2	A	56348	S2	DH			
56268	S2	DH	56349	S2	DH			
56271	S2	DH	56350	S2	DH			
56278	S2	DH	56352	SC2	A			
56280	S2	DH	56353	SC2	A			
56290	S2	HE	56354	SC2	A			
56293	S2	HE	56359b	SC2	A			

P = Low-frequency power transistors  
 R = Rectifier diodes  
 Sm = Small-signal transistors

Tra = Transmitting transistors and modules  
 Vrf = Voltage reference diodes  
 WD = Silicon whiskerless diodes

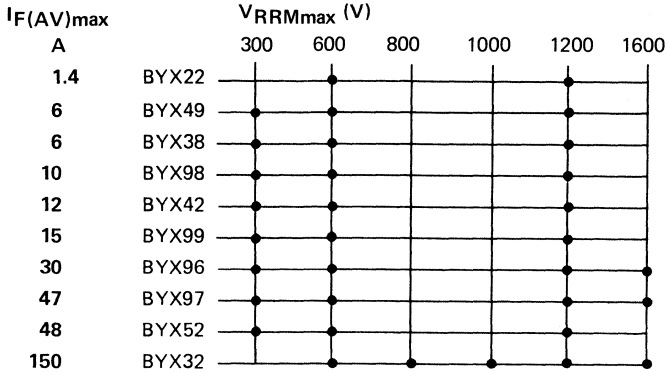




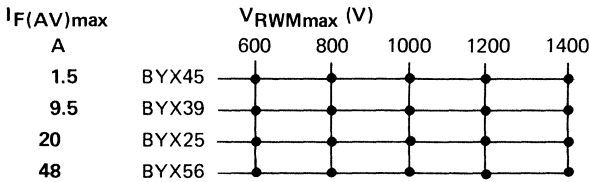
# **SELECTION GUIDE**

RECTIFIER DIODES

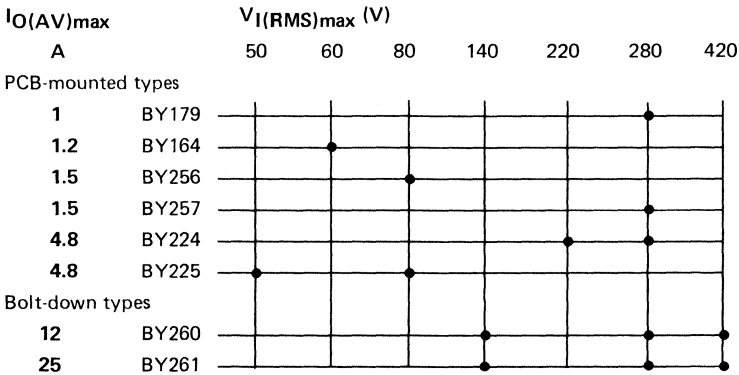
General purpose



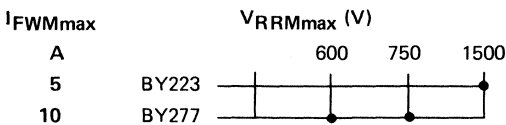
Avalanche



Bridges



Efficiency diodes



Fast-recovery rectifier diodes

Schottky types

$I_{F(AV)max}$

A

28

BYV21

$V_{RRMmax}$  (V)

30

35

40

45

Ultra-fast types

$I_{F(AV)max}$

A

7

BYW29

12

BYW30

25

BYW31

35

BYW92

$V_{RRMmax}$  (V)

50

100

150

200

300

350

400

500

600

800

1000

Super-fast types

7

BYX50

12

BYV30

35

BYV92

Very-fast types

6

1N3879

6

1N3880

6

1N3881

6

1N3882

12

1N3889

12

1N3890

12

1N3891

12

1N3892

14

BYX30\*

20

1N3899

20

1N3900

20

1N3901

20

1N3902

20

1N3903

22

BYX46\*

30

1N3909

30

1N3910

30

1N3911

30

1N3912

30

1N3913

Fast types

7

BY229

7

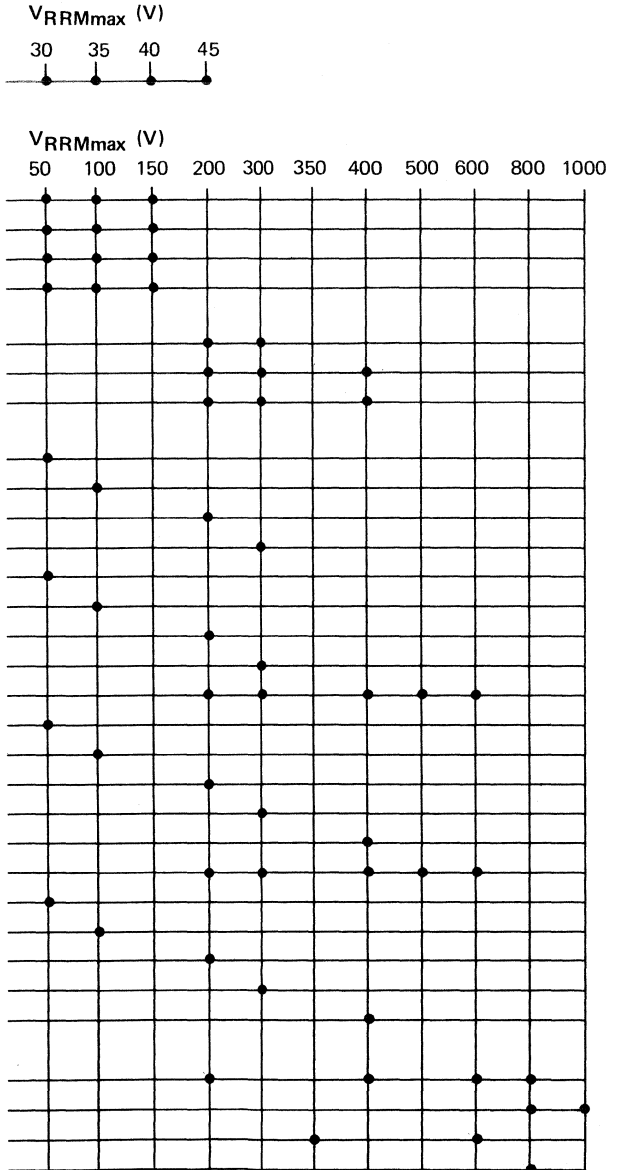
BYW19

7

BYX71

40

BYW25



\*With avalanche characteristics

# SELECTION GUIDE

## REGULATOR DIODES

Regulated voltage	Suppression stand-off voltage	REGULATOR SERVICE									
		2.5 W		15 W	—	P <sub>tot</sub> max		20 W	100 W	—	—
		SUPPRESSOR SERVICE								P <sub>RSM</sub> max	
		190 W	700 W		—	700 W	700 W	9.5 kW	25 kW	27 kW	
4.7 V	3.6 V	Type No. BZY96									
5.1 V	3.9 V										
5.6 V	4.3 V										
6.2 V	4.7 V										
6.8 V	5.1 V										
7.5 V	5.6 V										
8.2 V	6.2 V										
9.1 V	6.8 V										
10 V	7.5 V										
11 V	8.2 V										
12 V	9.1 V										
13 V	10 V										
15 V	11 V										
16 V	12 V										
18 V	13 V										
20 V	15 V			Type No. BZX70							
22 V	16 V				Type No. BZY95						
24 V	18 V					Type No. BZV15					
27 V	20 V						Type No. BZW70				
30 V	22 V							Type No. BZY93			
33 V	24 V								Type No. BZY91		
36 V	27 V									Type No. BZW86	
39 V	30 V									Type No. BZW91	
43 V	33 V										
47 V	36 V										
51 V	39 V										
56 V	43 V										
62 V	47 V										
68 V	51 V										
75 V	56 V										
82 V	62 V										
Outline		DO-1	SOD-18	DO-1	SOD-38	SOD-18	DO-4	DO-5	DO-30	DO-5	
Polarity		normal	normal	normal	both	normal	both	both	both	both	

### Transient suppressor bridges

Type No.	V <sub>I</sub> V	V <sub>O</sub> (CL) V	I <sub>(CL)SM</sub> A
BZW10-12	12	30	50
BZW10-15	15	34	40

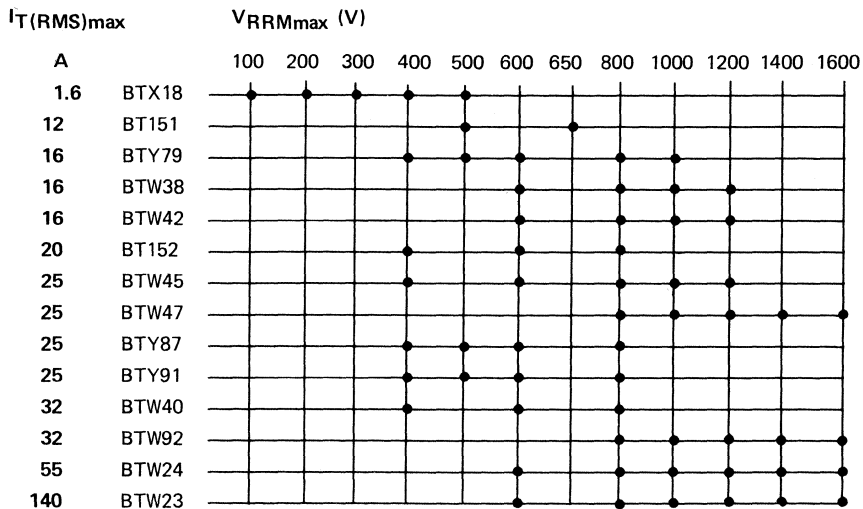
Normal polarity (cathode to stud) no end-letter  
 Reverse polarity (anode to stud) R  
 Both polarities available (R)

## HIGH-VOLTAGE RECTIFIER STACKS

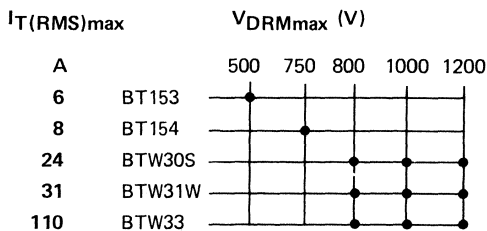
Type No.	$I_F(AV)$ max.	$V_{RWM}$ max.	Configuration
OSS9110-3 to -30	3.5 A (6 A in oil)	3 kV to 30 kV	
OSS9210-3 to -30	5 A (20 A in oil)		
OSS9310-3 to -30	4 A (12 A in oil)		
OSS9410-3 to -30	10 A (30 A in oil)		
OSB9110-4 to -30	7 A (12 A in oil)	2 kV to 15 kV	
OSB9210-4 to -30	10 A (40 A in oil)		
OSB9310-4 to -30	4 A (12 A in oil)		
OSB9410-4 to -30	20 A (60 A in oil)		
OSM9110-4 to -30	3.5 A (6 A in oil)	2 kV to 15 kV	
OSM9210-4 to -30	5 A (20 A in oil)		
OSM9310-4 to -30	4 A (12 A in oil)		
OSM9410-4 to -30	10 A (30 A in oil)		
OSM9510-8 to -12	1.5 A	8 kV to 12 kV	

THYRISTORS

General purpose thyristors



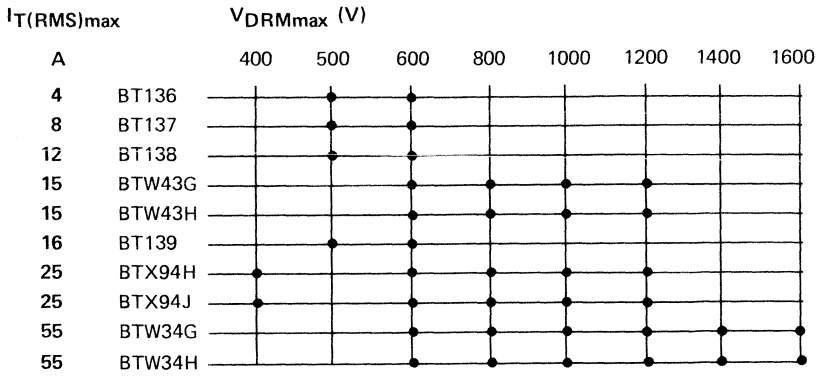
Fast turn-off thyristors



Thyristor tetrode BRY39T:  $V_{RRMmax} = 70$  V;  $I_{Tmax} = 250$  mA

Bi-directional trigger device BR100/03:  $V_{(BO)} = 28$  to 36 V;  $I_{FRMmax} = 2$  A

## TRIACS







**GENERAL SECTION**  
**Type Designation**  
**Rating Systems**  
**Letter Symbols**  
**Quality Conformance**  
**and Reliability**

**A**



**A**

## PRO ELECTRON TYPE DESIGNATION CODE FOR SEMICONDUCTOR DEVICES

This type designation code applies to discrete semiconductor devices – as opposed to integrated circuits –, multiples of such devices and semiconductor chips.

A basic type number consists of:

*TWO LETTERS FOLLOWED BY A SERIAL NUMBER*

### FIRST LETTER

The first letter gives information about the material used for the active part of the devices.

- A. GERMANIUM or other material with band gap of 0,6 to 1,0 eV.
- B. SILICON or other material with band gap of 1,0 to 1,3 eV.
- C. GALLIUM-ARSENIDE or other material with band gap of 1,3 eV or more.
- R. COMPOUND MATERIALS (e.g. Cadmium-Sulphide).

### SECOND LETTER

The second letter indicates the function for which the device is primarily designed.

- A. DIODE; signal, low power
- B. DIODE; variable capacitance
- C. TRANSISTOR; low power, audio frequency ( $R_{th\ j-mb} > 15\ ^\circ C/W$ )
- D. TRANSISTOR; power, audio frequency ( $R_{th\ j-mb} \leq 15\ ^\circ C/W$ )
- E. DIODE; tunnel
- F. TRANSISTOR; low power, high frequency ( $R_{th\ j-mb} > 15\ ^\circ C/W$ )
- G. MULTIPLE OF DISSIMILAR DEVICES – MISCELLANEOUS; e.g. oscillator
- H. DIODE; magnetic sensitive
- L. TRANSISTOR; power, high frequency ( $R_{th\ j-mb} \leq 15\ ^\circ C/W$ )
- N. PHOTO-COUPLER
- P. RADIATION DETECTOR; e.g. high sensitivity phototransistor
- Q. RADIATION GENERATOR; e.g. light-emitting diode (LED)
- R. CONTROL AND SWITCHING DEVICE; e.g. thyristor, low power ( $R_{th\ j-mb} > 15\ ^\circ C/W$ )
- S. TRANSISTOR; low power, switching ( $R_{th\ j-mb} > 15\ ^\circ C/W$ )
- T. CONTROL AND SWITCHING DEVICE; e.g. thyristor, power ( $R_{th\ j-mb} \leq 15\ ^\circ C/W$ )
- U. TRANSISTOR; power, switching ( $R_{th\ j-mb} \leq 15\ ^\circ C/W$ )
- X. DIODE: multiplier, e.g. varactor, step recovery
- Y. DIODE; rectifying, booster
- Z. DIODE; voltage reference or regulator (transient suppressor diode, with third letter W)

# TYPE DESIGNATION

The remainder of the type number is a **serial number** indicating a particular design or development and is in one of the following two groups:

- (a) A **serial number** consisting of three figures from 100 to 999.
- (b) A **serial number** consisting of one letter (Z, Y, X, W, etc.) followed by two figures.

## RANGE NUMBERS

Where there is a range of variants of a basic type of rectifier diode, thyristor or voltage regulator diode the type number as defined above is often used to identify the range; further letters and figures are added after a hyphen to identify associated types within the range. These additions are as follows:

### RECTIFIER DIODES, THYRISTORS AND TRIACS

A **group of figures** indicating the rated repetitive peak reverse voltage,  $V_{RRM}$ , or the rated repetitive peak off-state voltage,  $V_{DRM}$ , whichever value is lower, in volts for each type.

The **final letter R** is used to denote a reverse polarity version (stud-anode) where applicable. The normal polarity version (stud cathode) has no special final letter.

### REGULATOR DIODES

A **first letter** indicating the nominal percentage tolerance in the operating voltage  $V_Z$ .

- A. 1% (according to IEC 63: series E96)
- B. 2% (according to IEC 63: series E48)
- C. 5% (according to IEC 63: series E24)
- D. 10% (according to IEC 63: series E12)
- E. 20% (according to IEC 63: series E6)

A **group of figures** indicating the typical operating voltage  $V_Z$  for each type at the nominal operating current  $I_Z$  rating of the range.

The **letter V** is used to denote a decimal sign.

The **final letter R** is used to denote a reverse polarity version (stud anode) where applicable. The normal polarity version (stud cathode) has no special final letter.

#### Examples:

- |            |  |
|------------|--|
| BYX38-600  | Silicon rectifier in the BYX38 range with 600 V maximum repetitive peak voltage, normal polarity, stud connected to cathode.             |
| BTW24-800R | Silicon thyristor in the BTW24 range with 800 V maximum repetitive peak voltage, reverse polarity, stud connected to anode.              |
| BZY91-C7V5 | Silicon voltage regulator diode in the BZY91 range with 7.5 V operating $\pm 5\%$ tolerance, normal polarity, stud connected to cathode. |

## RATING SYSTEMS

The rating systems described are those recommended by the International Electrotechnical Commission (IEC) in its Publication 134.

### DEFINITIONS OF TERMS USED

*Electronic device.* An electronic tube or valve, transistor or other semiconductor device.

Note

This definition excludes inductors, capacitors, resistors and similar components.

*Characteristic.* A characteristic is an inherent and measurable property of a device. Such a property may be electrical, mechanical, thermal, hydraulic, electro-magnetic, or nuclear, and can be expressed as a value for stated or recognized conditions. A characteristic may also be a set of related values, usually shown in graphical form.

*Bogey electronic device.* An electronic device whose characteristics have the published nominal values for the type. A bogey electronic device for any particular application can be obtained by considering only those characteristics which are directly related to the application.

*Rating.* A value which establishes either a limiting capability or a limiting condition for an electronic device. It is determined for specified values of environment and operation, and may be stated in any suitable terms.

Note

Limiting conditions may be either maxima or minima.

*Rating system.* The set of principles upon which ratings are established and which determine their interpretation.

Note

The rating system indicates the division of responsibility between the device manufacturer and the circuit designer, with the object of ensuring that the working conditions do not exceed the ratings.

### ABSOLUTE MAXIMUM RATING SYSTEM

Absolute maximum ratings are limiting values of operating and environmental conditions applicable to any electronic device of a specified type as defined by its published data, which should not be exceeded under the worst probable conditions.

These values are chosen by the device manufacturer to provide acceptable serviceability of the device, taking no responsibility for equipment variations, environmental variations, and the effects of changes in operating conditions due to variations in the characteristics of the device under consideration and of all other electronic devices in the equipment.

The equipment manufacturer should design so that, initially and throughout life, no absolute maximum value for the intended service is exceeded with any device under the worst probable operating conditions with respect to supply voltage variation, equipment component variation, equipment control adjustment, load variations, signal variation, environmental conditions, and variations in characteristics of the device under consideration and of all other electronic devices in the equipment.

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### **DESIGN MAXIMUM RATING SYSTEM**

Design maximum ratings are limiting values of operating and environmental conditions applicable to a bogey electronic device of a specified type as defined by its published data, and should not be exceeded under the worst probable conditions.

These values are chosen by the device manufacturer to provide acceptable serviceability of the device, taking responsibility for the effects of changes in operating conditions due to variations in the characteristics of the electronic device under consideration.

The equipment manufacturer should design so that, initially and throughout life, no design maximum value for the intended service is exceeded with a bogey device under the worst probable operating conditions with respect to supply voltage variation, equipment component variation, variation in characteristics of all other devices in the equipment, equipment control adjustment, load variation, signal variation and environmental conditions.

### **DESIGN CENTRE RATING SYSTEM**

Design centre ratings are limiting values of operating and environmental conditions applicable to a bogey electronic device of a specified type as defined by its published data, and should not be exceeded under normal conditions.

These values are chosen by the device manufacturer to provide acceptable serviceability of the device in average applications, taking responsibility for normal changes in operating conditions due to rated supply voltage variation, equipment component variation, equipment control adjustment, load variation, signal variation, environmental conditions, and variations in the characteristics of all electronic devices.

The equipment manufacturer should design so that, initially, no design centre value for the intended service is exceeded with a bogey electronic device in equipment operating at the stated normal supply voltage.

## LETTER SYMBOLS FOR RECTIFIER DIODES, THYRISTORS AND TRIACS

### LETTER SYMBOLS FOR CURRENTS, VOLTAGES AND POWERS

Basic letters : - The basic letters to be used are:

I, i = current                      V, v = voltage                      P, p = power

Lower-case basic letters shall be used for the representation of instantaneous values which vary with time. In all other instances upper-case letters shall be used.

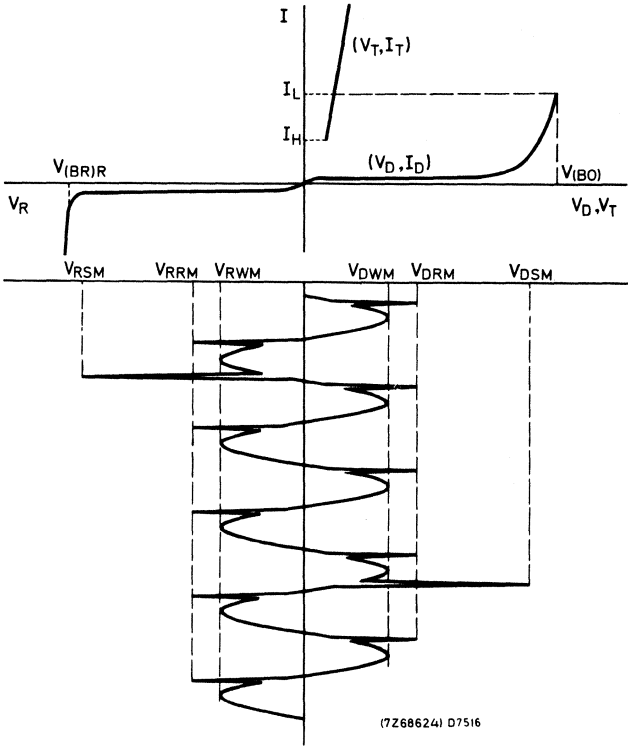
#### Subscripts

amb	Ambient
(AV), (av)	Average value
(BO)	Breakover
(BR)	Breakdown
case	Case
D, d	Forward off-state <sup>1)</sup> , non-triggered (gate voltage or current)
F, f	Forward <sup>1)</sup> , fall
G, g	Gate terminal
H	Holding
I, i	Input
J, j	Junction
L	Latching
M, m	Peak or crest value
min	Minimum
O, o	Output, open circuit
(OV)	Overload
P, p	Pulse
Q, q	Turn-off
R, r	As first subscript: reverse, rise As second subscript: repetitive, recovery
(RMS), (rms)	R.M.S. value
S, s	As first subscript: storage, stray, series, source As second subscript: non-repetitive
stg	Storage
T, t	Forward on-state <sup>1)</sup> , triggered (gate voltage or current)
th	Thermal
(TO)	Threshold
tot	Total
W	Working
Z	Reference or regulator (i.e. zener)

For power rectifier diodes, thyristors and triacs, the terminals are not indicated in the subscript, except for the gate-terminal of thyristors and triacs.

<sup>1)</sup> For the anode-cathode voltage of thyristors and triacs, F is replaced either by D or T, to distinguish between "off-state" (non-triggered) and "on-state" (triggered).

Example of the use of letter symbols



(7Z68624) D7516

Simplified thyristor characteristic together with an anode-cathode voltage as a function of time (no gate signal).



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## QUALITY CONFORMANCE AND RELIABILITY

In addition to 100% testing of all major device parameters in production department, independently controlled statistical sampling for conformance and reliability takes place using BS6001 'Sampling Procedures and Tables'. BS6001 is consistent with MIL-STD-105D, DEF 131A, ISO2859, CA-C-115. The methods used and standards applied are compatible with CECC, BS and IEC rules and procedures, and many products are available to BS9300 and CECC 50000 series detail specifications. High reliability products, which have had special inspections and 'burn-in', are also available.



# RECTIFIER DIODES

**B**



**B**

## RECTIFIER DIODES

### REVERSE RECOVERY

When a semiconductor rectifier diode has been conducting in the forward direction sufficiently long to establish the steady state, there will be a charge due to minority carriers present. Before the device can block in the reverse direction this charge must be extracted. This extraction takes the form of a transient reverse current and this, together with the reverse bias voltage results in additional power dissipation which reduces the rectification efficiency. At sine-wave frequencies up to about 400 Hz these effects can often be ignored, but at higher frequencies and for square waves the switching losses must be considered.

#### Stored charge

The area under the  $I_R$ -time curve is known as the stored charge ( $Q_s$ ) and is normally quoted in micro- or nanocoulombs. Low stored charge devices are preferred for fast switching applications.

#### Reverse recovery time

Another parameter which can be used to determine the speed of the rectifier is the reverse recovery time ( $t_{rr}$ ). This is measured from the instant the current passes through zero (from forward to reverse) to the instant the current recovers to 10% of its peak reverse value. Low reverse recovery times are associated with low stored charge devices.

The conditions which need to be specified are:

- Steady-state forward current ( $I_F$ ); high currents increase recovery time.
- Reverse bias voltage ( $V_R$ ); low reverse voltage increases recovery time.
- Rate of fall of anode current ( $dI_F/dt$ ); high rates of fall reduce recovery time, but increase stored charge.
- Junction temperature ( $T_j$ ); high temperatures increase both recovery time and stored charge.

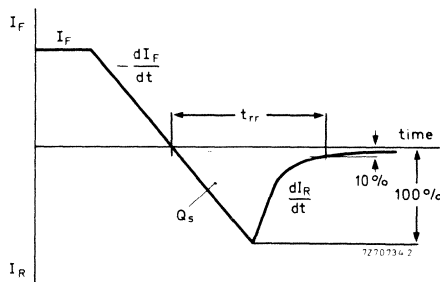


Fig. 1 Waveform showing the reverse recovery aspects.

## REVERSE RECOVERY (continued)

### Softness of recovery

In many switching circuits it is not just the magnitude but the shape of the reverse recovery characteristic that is important. If the positive-going edge of the characteristic has a fast rise time (as in a so-called 'snap-off' device) this edge may cause conducted or radiated r.f.i., or it may generate high voltages across inductors which may be in series with the rectifier. The maximum slope of the reverse recovery current ( $dI_R/dt$ ) is quoted as a measure of the 'softness' of the characteristic. Low values are less liable to give r.f.i. problems. The measurement conditions which need to be specified are as above. When stored charges are very low, e.g. for epitaxial and Schottky-barrier rectifier diodes, this softness characteristic can be ignored.

## DOUBLE-DIFFUSED RECTIFIER DIODES

A single-diffused diode with a two layer p-n structure cannot combine a high forward current density with a high reverse blocking voltage.

A way out of this dilemma is provided by the three layer double-diffused structure. A lightly doped silicon layer, called the base, is sandwiched between highly doped diffused  $p^+$  and  $n^+$  outer layers giving a  $p^+ - pn^+$  or  $p^+ - nn^+$  layer. Generally, the base gives the diode its high reverse voltage, and the two diffused regions give the high forward current rating.

Although double-diffused diodes are highly efficient, a slight compromise is still necessary. Generally, for a given silicon chip area, the thicker the base layer the higher the  $V_R$  and the lower the  $I_F$ . Reverse switching characteristics also determine the base design. Fast recovery diodes usually have n-type base regions to give 'soft' recovery. Other diodes have the base type, n or p, chosen to meet their specific requirements.

## ULTRA FAST RECTIFIER DIODES

Ultra fast rectifier diodes, made by epitaxial technology, are intended for use in applications where low conduction and switching losses are of paramount importance and relatively low reverse blocking voltage ( $V_{RWM} = 150\text{ V}$ ) is required: e.g., switched-mode power supplies operating at frequencies of about 50 kHz.

The use of epitaxial technology means that there is very close control over the almost ideal diffusion profile and base width giving very high carrier injection efficiencies leading to lower conduction losses than conventional technology permits. The well defined diffusion profile also allows a tight control of stored minority carriers in the base region, so that very fast turn-off times (35 ns) can be achieved. The range of devices also has a soft reverse recovery and a low forward recovery voltage.

## SCHOTTKY-BARRIER RECTIFIER DIODES

Schottky-barrier rectifiers find application in low-voltage switched-mode power supplies (e.g. 5 V output) where they give an increase in efficiency due to the very low forward drop, and low switching losses. Power Schottky diodes are made by a metal-semiconductor barrier process to minimise forward voltage losses, and being majority carrier devices have no stored charge. They are therefore capable of operating at extremely high speeds. Electrical performance in forward and reverse conduction is uniquely defined by the device's metal-semiconductor 'barrier height'. We have a process to minimise forward voltage, whilst maintaining reverse leakage current at full rated working voltage and  $T_j$  max at an acceptable level.

To obtain the maximum benefit from the use of Schottky devices it is recommended that particular attention be paid to the adequate suppression of voltage transients in practical circuit designs.

**SWITCHING LOSSES** (see also Fig.3)

The product of transient reverse current and reverse bias voltage is a power dissipation, most of which occurs during the fall time. In repetitive operation an average power can be calculated. This is then added to the forward dissipation to give the total power.

The conditions which need to be specified are:

- Forward current ( $I_F$ ); high currents increase switching losses.
- Rate of fall of anode current ( $dI_F/dt$ ); high rates of fall increase switching losses. This is particularly important in square-wave operation. Power losses in sine-wave operation for a given frequency are considerably less due to the much lower  $dI_F/dt$ .
- Frequency ( $f$ ); high frequency means high losses.
- Reverse bias voltage ( $V_R$ ); high reverse bias means high losses.
- Junction temperature ( $T_j$ ); high temperature means high losses.

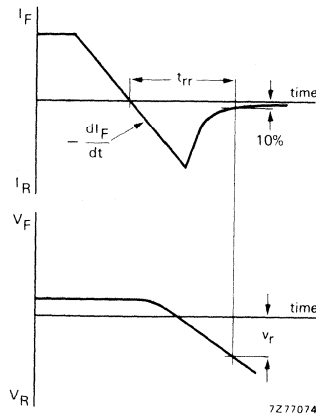


Fig. 2 Waveforms showing the reverse switching losses aspects.

SWITCHING LOSSES (continued)

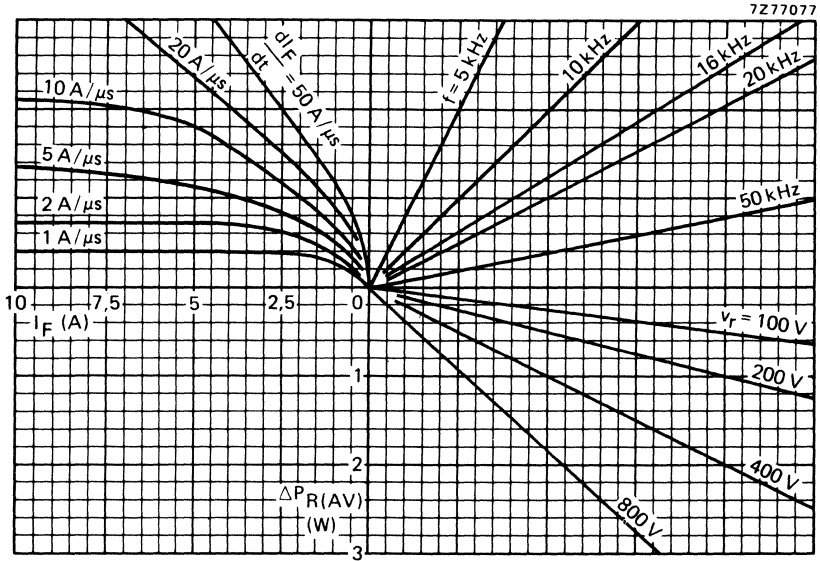


Fig. 3 **Nomogram** (example of reverse switching losses). Power loss  $\Delta P_R$ (AV) due to switching only (to be added to steady-state power losses).  $I_F$  = forward current just before switching off;  $T_j = 150$  °C.



## FORWARD RECOVERY

At the instant a semiconductor rectifier diode is switched into forward conduction there are no carriers present at the junction, hence the forward voltage drop may be instantaneously of a high value. As the stored charge builds-up, conductivity modulation takes place and the forward voltage drop rapidly falls to the steady-state value. The peak value of forward voltage drop is known as the forward recovery voltage ( $V_{fr}$ ). The time from the instant the current reaches 10% of its steady-state value to the time the forward voltage drop falls to within 10% of its final steady-state value is known as the forward recovery time ( $t_{fr}$ ).

The conditions which need to be specified are:

- Forward current ( $I_F$ ); high currents give high recovery voltages.
- Current pulse rise time ( $t_r$ ); short rise times give high recovery voltages.
- Junction temperature ( $T_j$ ); the influence of temperature is slight.

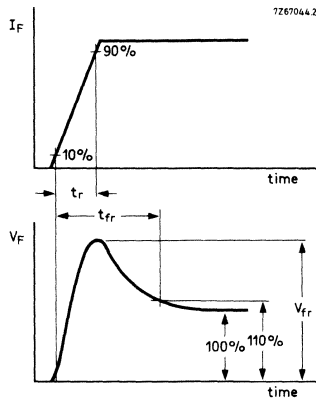


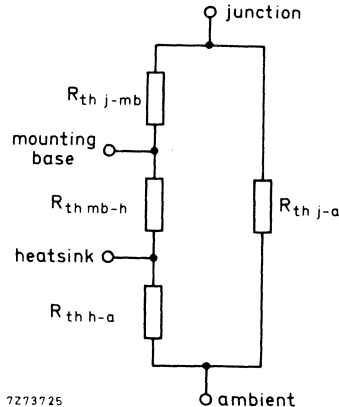
Fig. 4 Waveforms showing the forward recovery aspects.

**MOUNTING CONSIDERATIONS FOR STUD-MOUNTED DIODES**

Losses generated in a silicon device must flow through the case and to a lesser extent the leads. The greatest proportion of the losses flow out through the case into a heat exchanger which can be either free convection cooled, forced convection or even liquid cooled. For the majority of devices in our range natural convection is generally adequate, however, where other considerations such as space saving must be taken into account then methods such as forced convection etc. can be considered. The thermal path from junction to ambient may be considered as a number of resistances in series. The first thermal resistance will be that of junction to mounting base, usually denoted by  $R_{th\ j-mb}$ . The second is the contact thermal resistance  $R_{th\ mb-h}$  and finally there is the thermal resistance of the heatsink  $R_{th\ h-a}$ .

In the rating curves, the contact thermal resistance and heatsink thermal resistances are combined as a single figure -  $R_{th\ mb-a}$ .

In addition to the steady state thermal conditions of the system, consideration should also be given to the possibility of any transient thermal excursions. These can be caused for example by starting conditions or overloads and in order to calculate the effect on the device, a graph of transient thermal resistance  $Z_{th\ j-mb}$  as a function of time is given in each data sheet.



When mounting the device on the heatsink, care should be taken that the contact surfaces are free from burrs or projections of any kind and must be thoroughly clean.

In the case where an anodised heatsink is used, the anodising should be removed from the contact surface ensuring good electrical and thermal contact.

The contact surfaces should be smeared with a metallic oxide-loaded grease to ensure good heat transfer.

Where the device is mounted in a tapped hole, care should be taken that the hole is perpendicular to the surface of the heatsink. When mounting the device to the heatsink, it is essential that a proper torque wrench is used, applying the correct amount of torque as specified in the published data.

Excessive torque can distort the threads of the device and may even cause mechanical stress on the wafer, leading to the possible failure.

Where isolation of the device from the heatsink is required, it is common practice to use a mica washer between contact surfaces, and where a clearance hole is used, a p.t.f.e. insulating bush is inserted. A metallic oxide-loaded heatsink compound should be smeared on all contact surfaces, including the mica washer, to ensure optimum heat transfer. The use of ordinary silicone grease is not recommended.

## OPERATING NOTES

When there is a possibility that transients, due to the energy stored in the transformer, will exceed the maximum permissible non-repetitive peak reverse voltage <sup>1)</sup>, a damping circuit should be connected across the transformer.

Either a series RC circuit or a voltage dependent resistor may be used. Suitable component values for an RC circuit across the transformer primary or secondary may be calculated as follows:

$\frac{V_{RSM}}{V_{RWM}}$	RC across primary of transformer		RC across secondary of transformer	
	C ( $\mu F$ )	R ( $\Omega$ )	C ( $\mu F$ )	R ( $\Omega$ )
2.0	$200 \frac{I_{mag}}{V_1}$	$\frac{150}{C}$	$225 \frac{I_{mag} T^2}{V_1}$	$\frac{200}{C}$
1.5	$400 \frac{I_{mag}}{V_1}$	$\frac{225}{C}$	$450 \frac{I_{mag} T^2}{V_1}$	$\frac{275}{C}$
1.25	$550 \frac{I_{mag}}{V_1}$	$\frac{260}{C}$	$620 \frac{I_{mag} T^2}{V_1}$	$\frac{310}{C}$
1.0	$800 \frac{I_{mag}}{V_1}$	$\frac{300}{C}$	$900 \frac{I_{mag} T^2}{V_1}$	$\frac{350}{C}$

where  $I_{mag}$  = magnetising primary r.m.s. current (A)

$V_1$  = transformer primary r.m.s. voltage (V)

$V_2$  = transformer secondary r.m.s. voltage (V)

$T = V_1/V_2$

$V_{RSM}$  = the transient voltage peak produced by the transformer

$V_{RWM}$  = the actually applied crest working reverse voltage

The capacitance values calculated from the above table are minimum values; to allow for circuit variations and component tolerances, larger values should be used.

<sup>1)</sup> For controlled avalanche types read: non-repetitive peak reverse power.



## SILICON BRIDGE RECTIFIER

Plastic-encapsulated bridge rectifier comprising four silicon double-diffused diodes. It is primarily intended for use in the power supplies of many types of transistorised equipment operating at frequencies up to 400 Hz.

### QUICK REFERENCE DATA

#### Input

R.M.S. voltage	$V_I(\text{RMS})$	max.	60	V
Repetitive peak voltage	$V_{IRM}$	max.	120	V
Non-repetitive peak current	$I_{ISM}$	max.	25	A

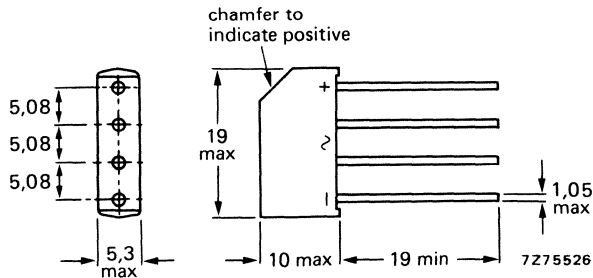
#### Output

Average current	$I_O(\text{AV})$	max.	1.2	A
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### MECHANICAL DATA

Dimensions in mm

Fig. 1 SOD-28



The sealing of the plastic envelope withstands the accelerated damp heat test of IEC recommendation 68-2 (test D, severity IV, 6 cycles).

**RATINGS**

Limiting values in accordance with the Absolute Maximum System (IEC 134)

**Input**

R.M.S. voltage	$V_I(\text{RMS})$	max.	60	V
Crest working voltage	$V_{IWM}$	max.	85	V
Repetitive peak voltage	$V_{IRM}$	max.	120	V
Non repetitive peak voltage; $t \leq 10$ ms	$V_{ISM}$	max.	120	V
Non-repetitive peak current (see also Fig.8)	$I_{ISM}$	max.	25	A

**Output**

Average current with C load	See Figs. 3, 6			
Average current with R and L load (see also Fig.5)				
$V_I(\text{RMS}) \leq 60$ V	$I_O(\text{AV})$	max.	1.2	A
Repetitive peak current	$I_{ORM}$	max.	5	A

**Temperatures**

Storage temperature	$T_{\text{stg}}$	-55 to +125	°C	
Junction temperature	$T_j$	max.	150	°C

**THERMAL RESISTANCE****Influence of mounting method**

The quoted values of  $R_{th\ j-a}$  should be used only when no leads of other dissipating components run to the same tie-point.

1. Mounted to solder tags at a lead-length  $a > 5$  mm.  $R_{th\ j-a} = 40$  °C/W
2. Mounted on printed-wiring board at  $a =$  maximum lead-length.  $R_{th\ j-a} = 50$  °C/W
3. Mounted on printed-wiring board at a lead-length  $a = 5$  mm.  $R_{th\ j-a} = 55$  °C/W
4. Mounted on printed-wiring board at a lead-length  $a = 1.5$  mm.  $R_{th\ j-a} = 60$  °C/W  
(distance  $a$  includes printed-wiring board thickness)

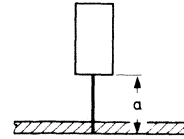
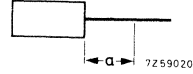


Fig.2

**MOUNTING INSTRUCTIONS**

1. The maximum permissible temperature of the soldering iron or bath is 270 °C; it must not be in contact with the joint for more than 3 seconds.
2. Avoid hot spots due to handling or mounting; the body of the device must not come into contact with or be exposed to a temperature higher than 150 °C.
3. Exert no axial pull when bending.

**CHARACTERISTICS**

Forward voltage (2 diodes in series)

$$I_F = 2 \text{ A}; T_j = 25 \text{ °C}$$

$$V_F < 2.2 \text{ V}^*$$

\*Measured under pulse conditions to avoid excessive dissipation.

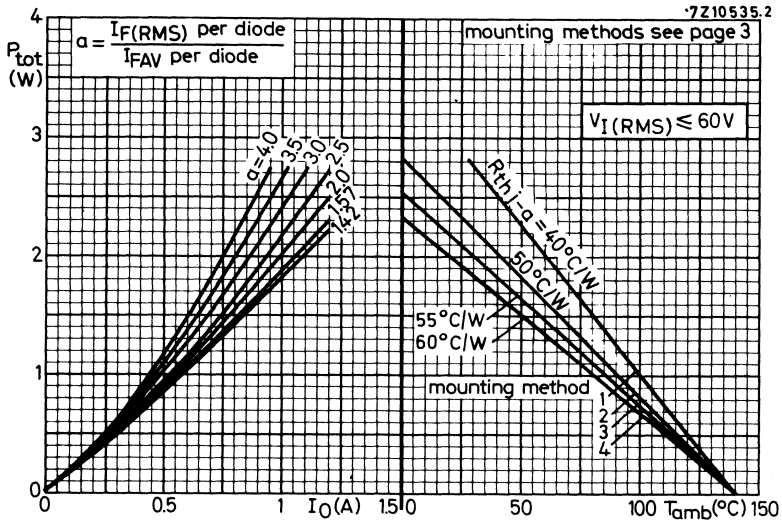


Fig.3

From the left-hand graph the total power dissipation can be found as a function of the average output current.

The parameter  $a = \frac{I_F(RMS) \text{ per diode}}{I_{FAV} \text{ per diode}}$  depends on  $\omega R_L C_L$  and  $\frac{R_t + R_{diff}}{R_L}$  and can be found from

existing graphs.

See Application Book: RECTIFIER DIODES.

Once the power dissipation is known, the max. permissible ambient temperature follows from the right-hand graph.

For the series resistance, added to limit the initial peak rectifier current, the required minimum value can be found from Fig.5.

$R_{diff}$  is shown in Fig.4.



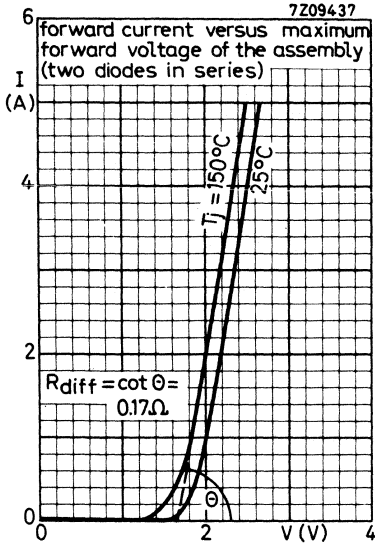


Fig.4

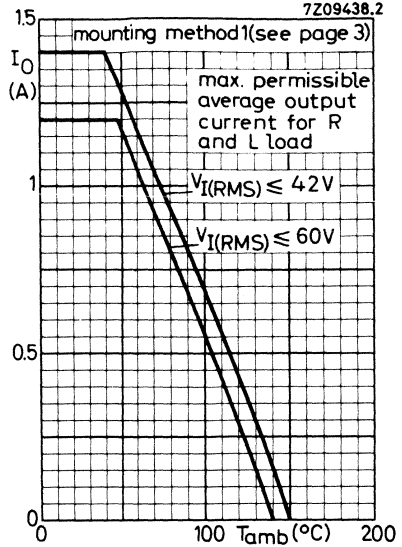


Fig.5

Example: Rectifier with C load

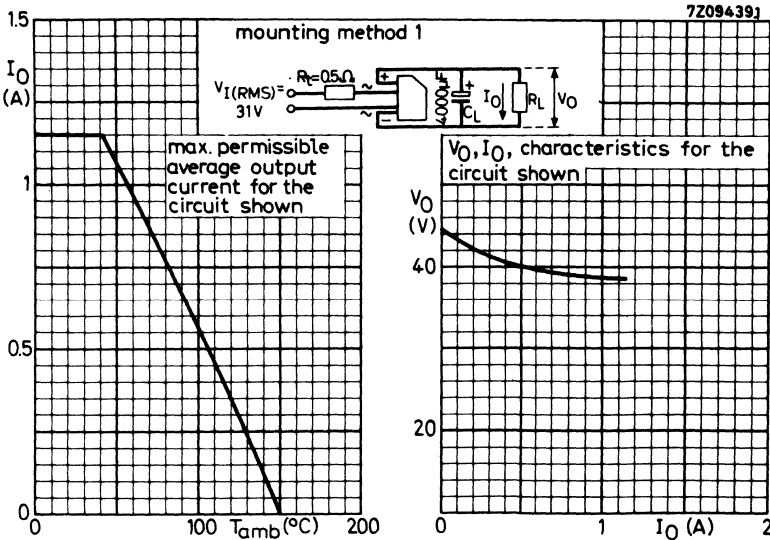


Fig.6

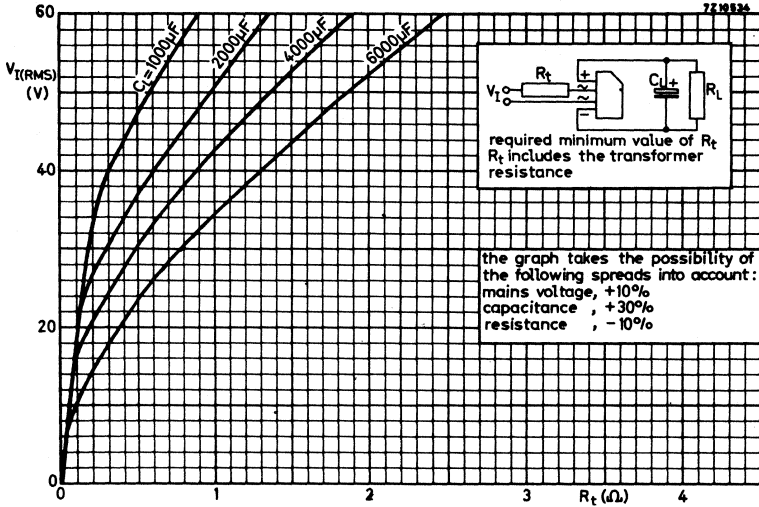


Fig.7

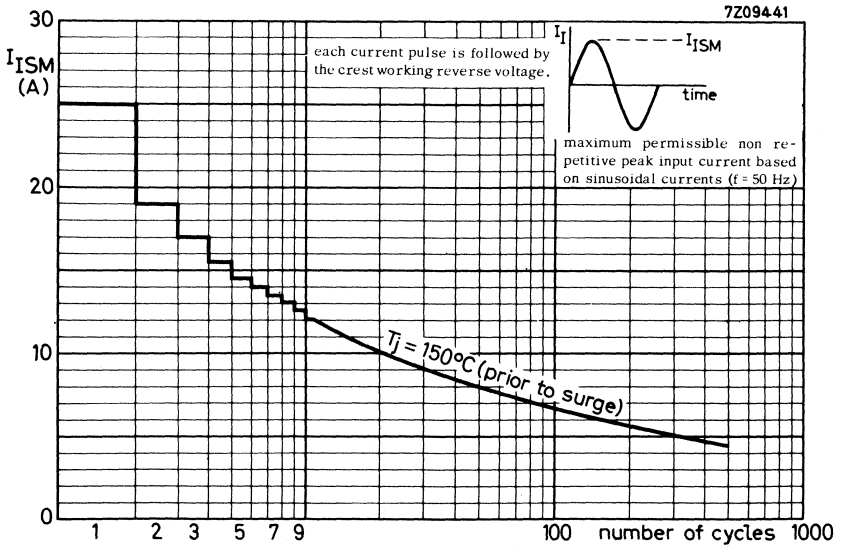


Fig.8

## SILICON BRIDGE RECTIFIER

Plastic-encapsulated bridge rectifier comprising four silicon double-diffused diodes. It is primarily intended for equipment drawing its power from mains with frequencies up to 400 Hz.

## QUICK REFERENCE DATA

## Input

R.M.S. voltage	$V_I(\text{RMS})$	max.	280	V
Repetitive peak voltage	$V_{IRM}$	max.	800	V
Non-repetitive peak current	$I_{ISM}$	max.	25	A

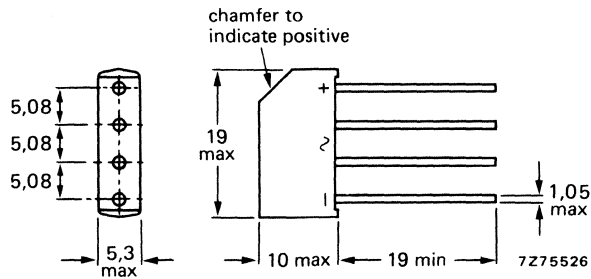
## Output

Average current	$I_{O(AV)}$	max.	1	A
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## MECHANICAL DATA

Dimensions in mm

Fig.1 SOD-28



The sealing of the plastic envelope withstands the accelerated damp heat test of IEC recommendation 68-2 (test D, severity IV, 6 cycles).

**RATINGS**

Limiting values in accordance with the Absolute Maximum System (IEC 134)

**Input**

R.M.S. voltage	$V_{I(RMS)}$	max.	280	V
Crest working voltage	$V_{IWM}$	max.	400	V
Repetitive peak voltage	$V_{IRM}$	max.	800	V
Non repetitive peak voltage; $t \leq 10$ ms	$V_{ISM}$	max.	800	V
Non repetitive peak current (see also Fig.8)	$I_{ISM}$	max.	25	A

**Output**

Average current with C load	See Figs 3, 6			
Average current with R and L load up to $T_{amb} = 40$ °C (see also Fig.5)	$I_{O(AV)}$	max.	1	A
Repetitive peak current	$I_{ORM}$	max.	5	A

**Temperatures**

Storage temperature	$T_{stg}$	-55 to +125		°C
Junction temperature	$T_j$	max.	125	°C

## THERMAL RESISTANCE

### Influence of mounting method

The quoted values of  $R_{th\ j-a}$  should be used only when no leads of other dissipating components run to the same tie-point

1. Mounted to solder tags at a lead-length  $a > 5$  mm.  $R_{th\ j-a} = 40$  °C/W
2. Mounted on printed-wiring board at  $a =$  maximum lead-length.  $R_{th\ j-a} = 50$  °C/W
3. Mounted on printed-wiring board at a lead-length  $a = 5$  mm.  $R_{th\ j-a} = 55$  °C/W
4. Mounted on printed-wiring board at a lead length  $a = 1.5$  mm.  $R_{th\ j-a} = 60$  °C/W (distance  $a$  includes printed-wiring board thickness)

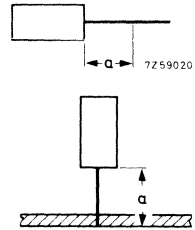


Fig.2

## MOUNTING INSTRUCTIONS

1. The maximum permissible temperature of the soldering iron or bath is 270 °C; it must not be in contact with the joint for more than 3 seconds.
2. Avoid hot spots due to handling or mounting; the body of the device must not come into contact with or be exposed to a temperature higher than 150 °C.
3. Exert no axial pull when bending.

## CHARACTERISTICS

Forward voltage (2 diodes in series)

$$I_F = 2 \text{ A}; T_j = 25 \text{ °C}$$

$$V_F < 2.2 \text{ V}^*$$

\*Measured under pulse conditions to avoid excessive dissipation.

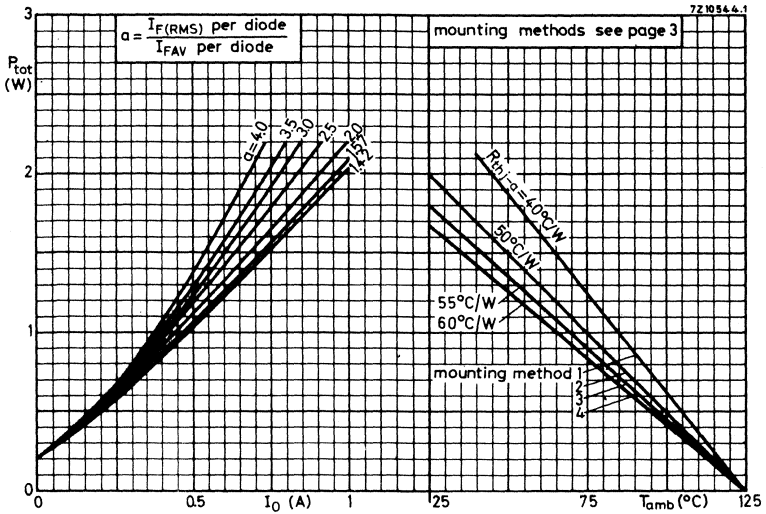


Fig.3

From the left-hand graph the total power dissipation can be found as a function of the average output current.

The parameter  $a = \frac{I_F(RMS) \text{ per diode}}{I_F(AV) \text{ per diode}}$  depends on  $\omega R_L C_L$  and  $\frac{R_t + R_{diff}}{R_L}$  and can be found from

existing graphs.

See Application Book: RECTIFIER DIODES

Once the power dissipation is known, the max. permissible ambient temperature follows from the right-hand graph.

For the series resistance, added to limit the initial peak rectifier current, the required minimum value can be found from Fig.7.

$R_{diff}$  is shown in Fig.4.

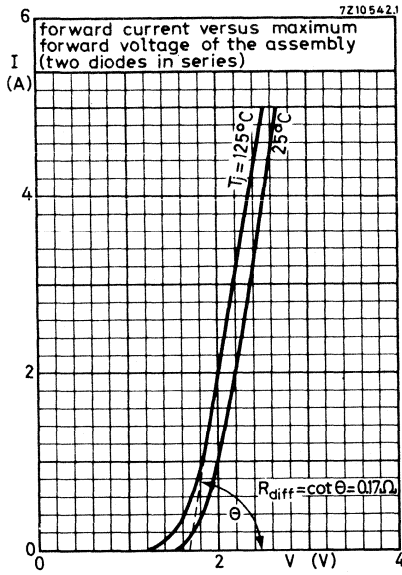


Fig.4

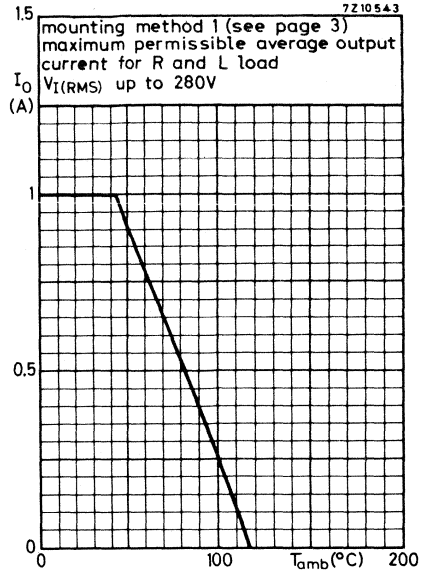


Fig.5

Example: Rectifier with C load

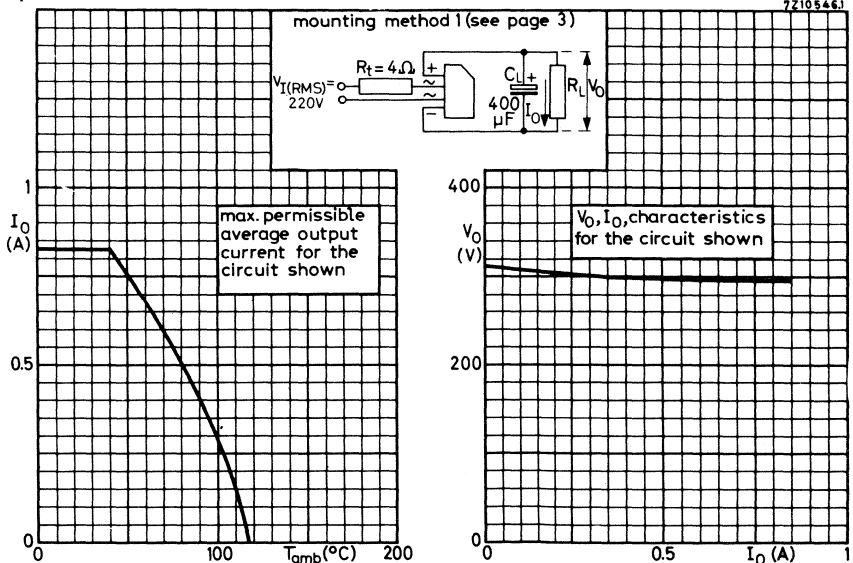


Fig.6

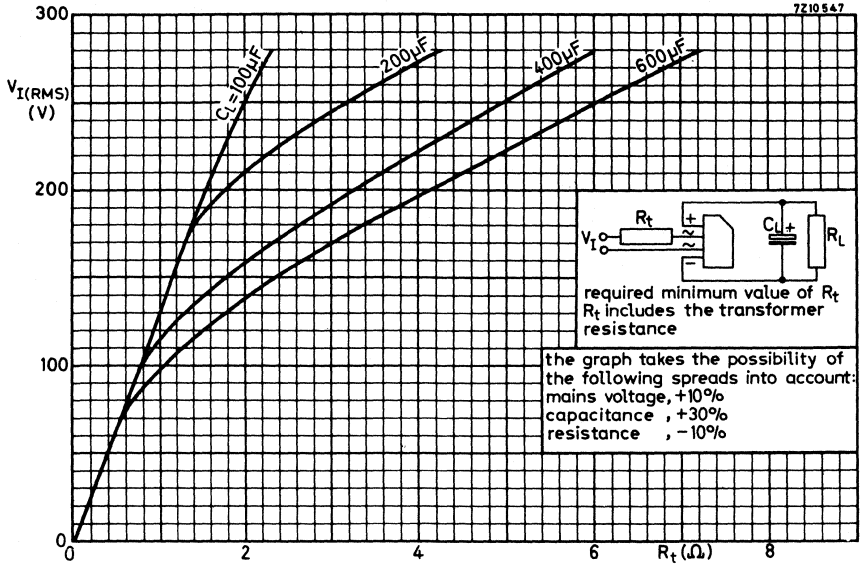


Fig.7

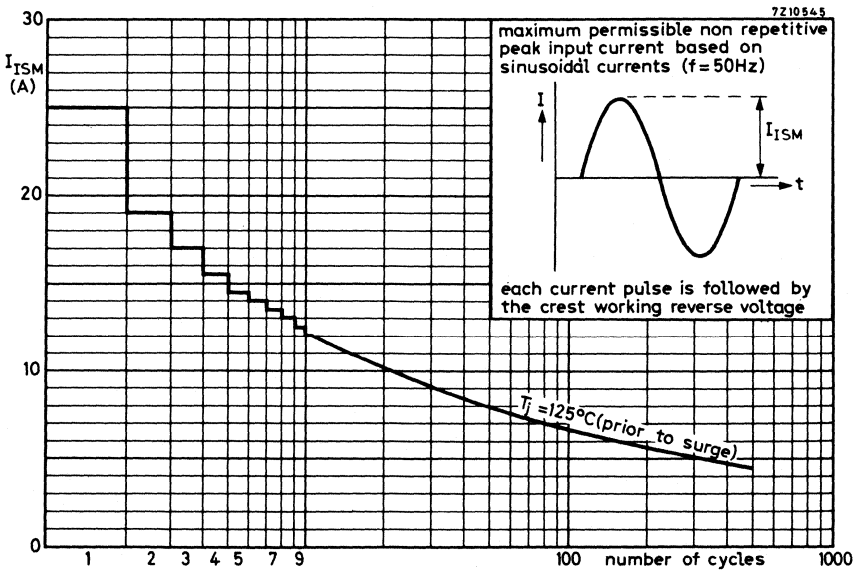


Fig.8



## PARALLEL-EFFICIENCY AND ENERGY-RECOVERY DIODE

Silicon double-diffused rectifier diode in a plastic envelope, intended for use as efficiency diode in transistorised horizontal deflection circuits of colour television receivers, and as an energy-recovery diode in thyristor commutation circuits such as 3-phase a.c. motor speed control inverters.

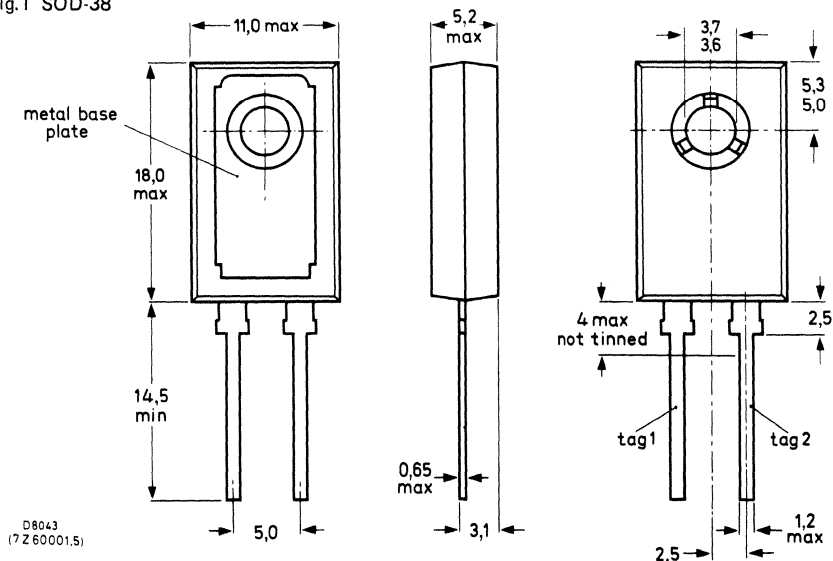
### QUICK REFERENCE DATA

Repetitive peak reverse voltage	$V_{RRM}$	max.	1500	V
Average forward current	$I_F(AV)$	max.	4.5	A
Working peak forward current	$I_{FWM}$	max.	5	A
Repetitive peak forward current ( $t_p = 100 \mu s$ )	$I_{FRM}$	max.	200	A
Reverse recovery time	$t_{rr}$	<	1.0	$\mu s$

### MECHANICAL DATA

Dimensions in mm

Fig.1 SOD-38



Polarity of connections: tag 1 = anode, tag 2 = cathode

The exposed metal base-plate is directly connected to tag 1

Net mass: 2.5 g

Torque on screw: min. 0.95 Nm  
(9.5 kg cm)  
max. 1.5 Nm  
(15 kg cm)

#### Accessories:

supplied with the device: washer 56355  
available on request: 56316 (mica insulating washer)

**RATINGS**

Limiting values in accordance with the Absolute Maximum System (IEC 134)

**Voltages**

Transient rating (subsequent to flashover)	$V_{RM}(\text{flashover})$	max.	1650 V
Non-repetitive peak reverse voltage ( $t \leq 10$ ms)	$V_{RSM}$	max.	1500 V
Repetitive peak reverse voltage	$V_{RRM}$	max.	1500 V
Working reverse voltage*	$V_{RW}$	max.	1500 V
Continuous reverse voltage	$V_R$	max.	800 V

**Currents**

Average forward current (averaged over any 20 ms period) up to $T_{mb} = 85$ °C	$I_F(AV)$	max.	4.5 A
R.M.S. forward current	$I_F(RMS)$	max.	10 A
Working peak forward current (see Fig.8)	$I_{FWM}$	max.	5 A
Repetitive peak forward current ( $t_p = 100$ $\mu$ s)	$I_{FRM}$	max.	200 A
Repetitive peak forward current	$I_{FRM}$	max.	10 A
Non-repetitive peak forward current ( $t = 10$ ms; half-sinewave) $T_j = 125$ °C prior to surge	$I_{FSM}$	max.	20 A

**Temperatures**

Storage temperature	$T_{stg}$	-40 to +125 °C
Junction temperature	$T_j$	max. 125 °C

**THERMAL RESISTANCE**

From junction to mounting base	$R_{th j-mb}$	=	4.5 °C/W
Transient thermal impedance; $t = 1$ ms	$Z_{th j-mb}$	=	0.3 °C/W

**Influence of mounting method**

1. *Heatsink mounted*

From mounting base to heatsink

a. with heatsink compound	$R_{th mb-h}$	=	1.5 °C/W
b. with heatsink compound and 56316 mica washer	$R_{th mb-h}$	=	2.7 °C/W
c. without heatsink compound	$R_{th mb-h}$	=	2.7 °C/W
d. without heatsink compound; with 56316 mica washer	$R_{th mb-h}$	=	5 °C/W

\* At  $t_p \leq 20$   $\mu$ s;  $\delta = t_p/T \leq 0.25$ ; see Fig.8.

## THERMAL RESISTANCE (continued)

## 2. Free air operation

The quoted values of  $R_{th\ j-a}$  should be used only when no leads of other dissipating components run to the same tie-points.

From junction to ambient in free air  
mounted on a printed circuit board  
at  $a$  = maximum lead length  
and with a copper laminate

- a.  $> 1\text{ cm}^2$
- b.  $< 1\text{ cm}^2$

$$R_{th\ j-a} = 50\text{ }^{\circ}\text{C/W.}$$

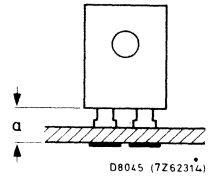
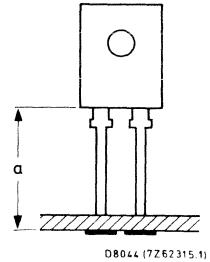
$$R_{th\ j-a} = 55\text{ }^{\circ}\text{C/W}$$

at a lead length  $a = 3\text{ mm}$   
and with a copper laminate

- c.  $> 1\text{ cm}^2$
- d.  $< 1\text{ cm}^2$

$$R_{th\ j-a} = 55\text{ }^{\circ}\text{C}$$

$$R_{th\ j-a} = 60\text{ }^{\circ}\text{C}$$



## SOLDERING AND MOUNTING NOTES

1. Soldered joints must be at least 2.5 mm from the seal.
2. The maximum permissible temperature of the soldering iron or bath is 270 °C; contact with the joint must not exceed 3 seconds.
3. The device should not be immersed in oil, and few potting resins are suitable for re-encapsulation. Advice on these materials is available on request.
4. Leads should not be bent less than 2.5 mm from the seal. Exert no axial pull when bending.
5. For good thermal contact, heatsink compound should be used between base-plate and heatsink.

**CHARACTERISTICS**

Forward voltage

$I_F = 20 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_F < 2.3 \text{ V}^*$

Reverse current

$V_R = V_{RW} \text{ max}; T_j = 125 \text{ }^\circ\text{C}$

$I_R < 0.6 \text{ mA}$

Reverse recovery when switched from

$I_{FWM} = 4 \text{ A}; -dI_F/dt = 0.2 \text{ A}/\mu\text{s}; T_j = 125 \text{ }^\circ\text{C}$   
total recovery time

$t_{tot} < 20 \text{ } \mu\text{s}$

$I_F = 2 \text{ A}; -dI_F/dt = 20 \text{ A}/\mu\text{s}; T_j = 125 \text{ }^\circ\text{C}$   
recovery time

$t_{rr} < 1.0 \text{ } \mu\text{s}$

Forward recovery time

when switched to  $I_{FRM} = 5 \text{ A}$  with  $t_r = 0.1 \text{ } \mu\text{s}; T_j = 125 \text{ }^\circ\text{C}$

$t_{fr} < 1.0 \text{ } \mu\text{s}$

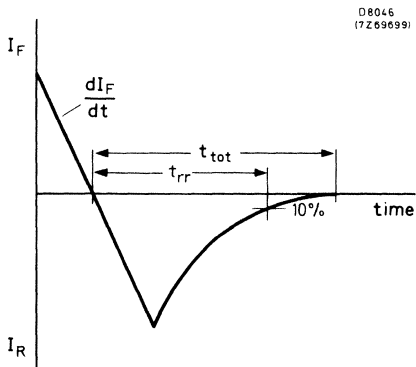


Fig.2 Definition of reverse recovery times.

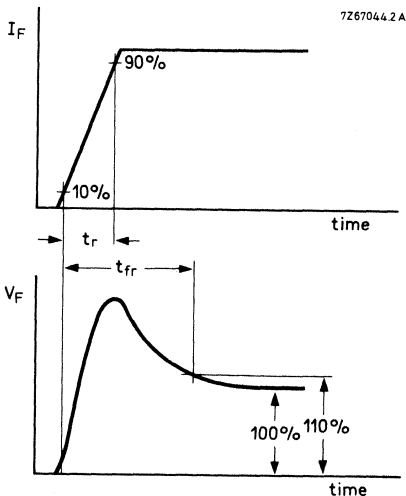


Fig.3 Definition of forward recovery time

\* Measured under pulse conditions to avoid excessive dissipation.

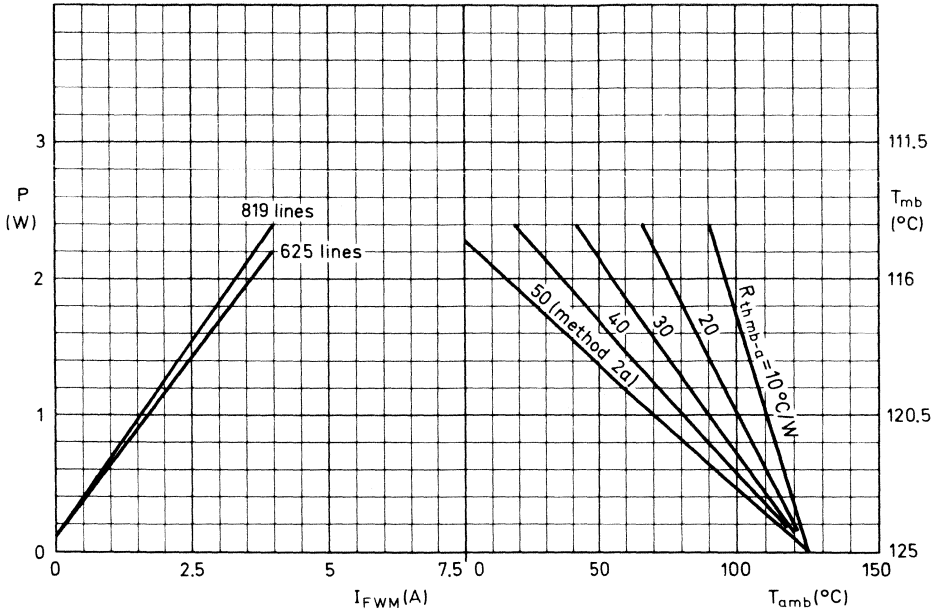


Fig.4 Interrelationship between the power dissipation (based on the waveforms shown in Fig.8) and the maximum permissible temperatures.  
 $P$  = power dissipation including switching losses.

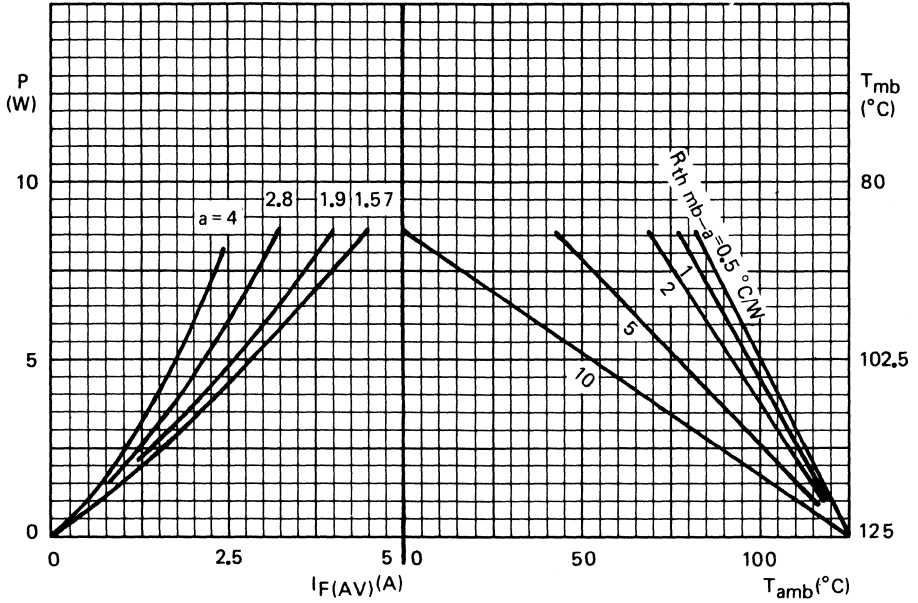


Fig.5 The right-hand part shows the interrelationship between the power dissipation (derived from the left-hand part) and the maximum permissible temperatures.

$P$  = power dissipation including switching losses.

$a$  = form factor =  $I_F(RMS)/I_F(AV)$

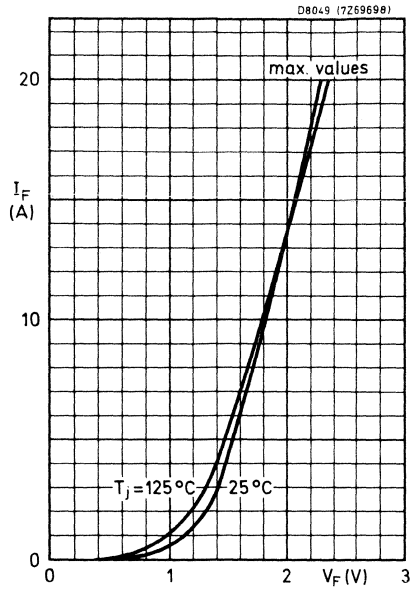


Fig.6

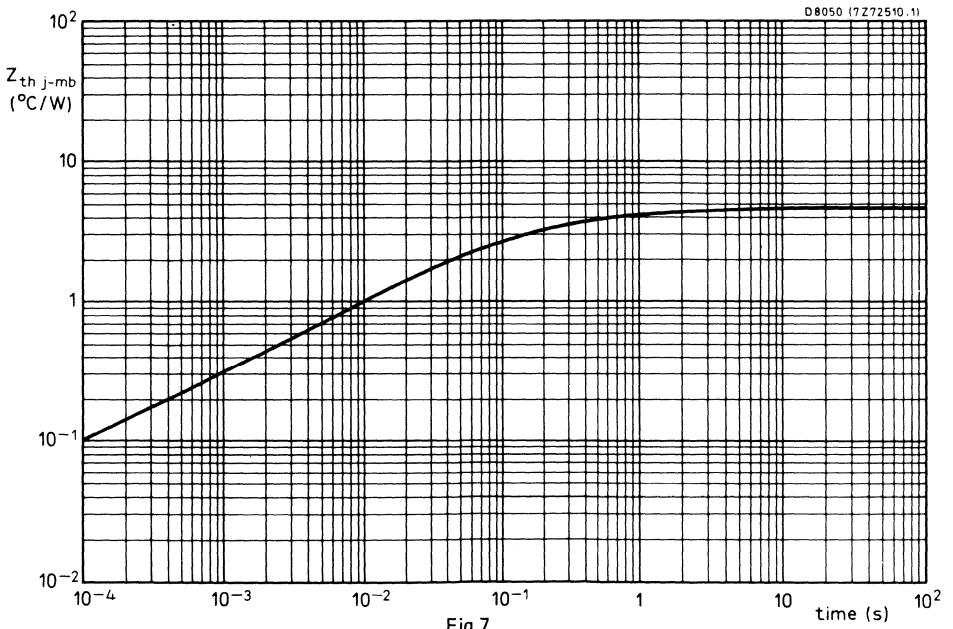


Fig.7

APPLICATION INFORMATION

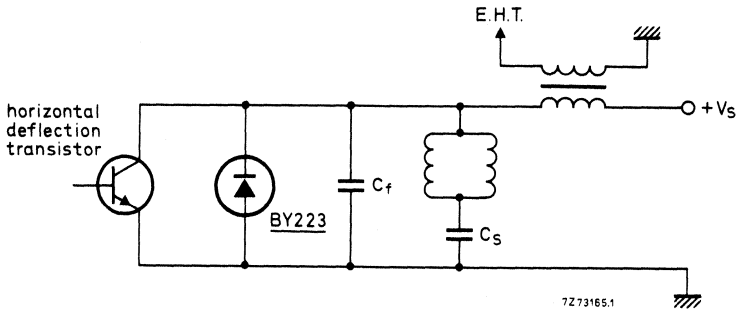
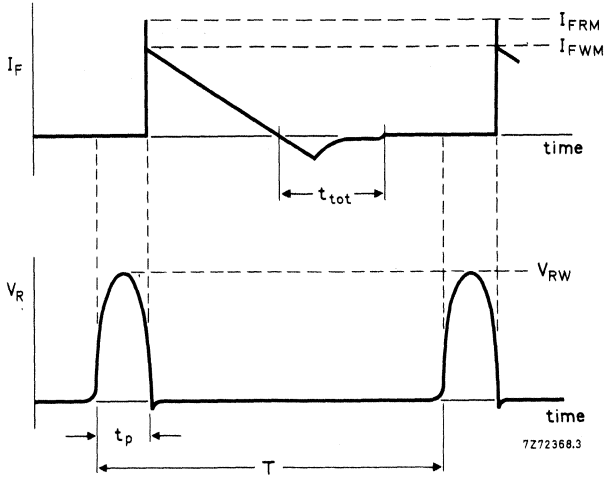


Fig.8 Basic circuit and waveforms



## SILICON BRIDGE RECTIFIERS

Ready-for-use mains full-wave bridges, each consisting of four double-diffused silicon diodes, in a plastic encapsulation. The bridges are intended for use in equipment supplied from mains with r.m.s. voltages up to 280 V and are capable of delivering up to 1000 W into capacitive loads. They may be used in free air or clipped to a heatsink.

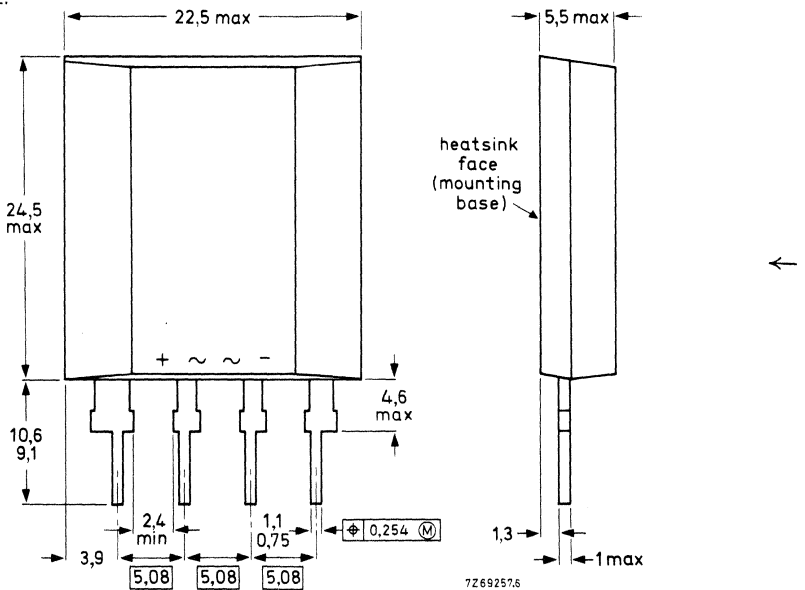
### QUICK REFERENCE DATA

Input		BY224-400	600 V
R.M.S. voltage	$V_I(\text{RMS})$	max. 220	280 V
Repetitive peak voltage	$V_{IRM}$	max. 400	600 V
Non-repetitive peak current	$I_{ISM}$	max.	100 A
Peak inrush current	$I_{IM}$	max.	200 A
Output			
Average current	$I_{O(AV)}$	max.	4,8 A

### MECHANICAL DATA (see also Fig. 1a)

Dimensions in mm

Fig. 1 SOT-112.



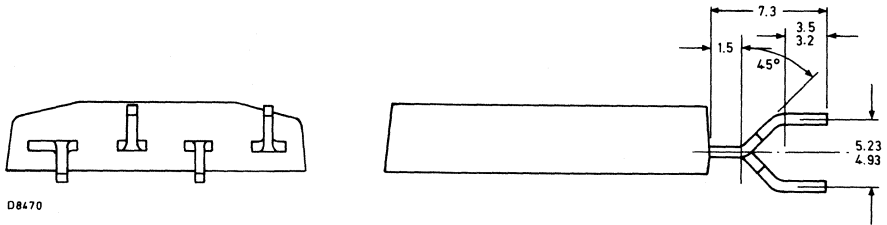
Net mass: 6,8 g

Accessories supplied on request: 56366 (clip); for mounting instructions see data 56366.

The sealing of the plastic withstands the accelerated damp heat test of IEC recommendation 68-2 (test D, severity 1V, 6 cycles).

## MECHANICAL DATA (continued)

→ Fig. 1a



A version with cranked pins (as shown in figure 1a) is available on request.

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

### Input

Non-repetitive peak voltage ( $t \leq 10$  ms)

	BY224-400	600
$V_{ISM}$	max. 400	600 V
Repetitive peak voltage	$V_{IRM}$ max. 400	600 V
Crest working voltage	$V_{IWM}$ max. 350	400 V
R.M.S. voltage (sine-wave)	$V_{I(RMS)}$ max. 220	280 V
Non-repetitive peak current		
half sine-wave; $t = 20$ ms; with reapplied $V_{IWMmax}$		
$T_j = 25$ °C prior to surge	$I_{ISM}$ max.	100 A
→ $T_j = 150$ °C prior to surge	$I_{ISM}$ max.	85 A
Peak inrush current (see Fig. 6)	$I_{IIM}$ max.	200 A
Output		
Average current (averaged over any 20 ms period; see Figs 2 and 3)		
heatsink operation up to $T_{mb} = 90$ °C	$I_{O(AV)}$ max.	4,8 A
free-air operation at $T_{amb} = 45$ °C; (mounting method 1a)	$I_{O(AV)}$ max.	2,5 A
Repetitive peak current	$I_{ORM}$ max.	50 A
Temperatures		
Storage temperature	$T_{stg}$	-40 to +150 °C
Junction temperature	$T_j$ max.	150 °C

Repetitive peak voltage

Crest working voltage

R.M.S. voltage (sine-wave)

Non-repetitive peak current

half sine-wave;  $t = 20$  ms; with reapplied  $V_{IWMmax}$

$T_j = 25$  °C prior to surge

→  $T_j = 150$  °C prior to surge

Peak inrush current (see Fig. 6)

### Output

Average current (averaged over any 20 ms period;

see Figs 2 and 3)

heatsink operation up to  $T_{mb} = 90$  °C

free-air operation at  $T_{amb} = 45$  °C;

(mounting method 1a)

Repetitive peak current

→ Temperatures

Storage temperature

Junction temperature

**THERMAL RESISTANCE**

From junction to mounting base

$$R_{th\ j-mb} = 4,0\ ^\circ C/W$$

**Influence of mounting method**

## 1. Free-air operation

The quoted values of  $R_{th\ j-a}$  should be used only when no loads of other dissipating components run to the same tie-point (see Fig. 3).

Thermal resistance from junction to ambient in free air

a. Mounted on a printed-circuit board with 4 cm<sup>2</sup> of copper laminate to + and - leads

$$R_{th\ j-a} = 19,5\ ^\circ C/W$$

b. Mounted on a printed-circuit board with minimal copper laminate

$$R_{th\ j-a} = 25\ ^\circ C/W$$

## 2. Heatsink mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. With zinc-oxide heatsink compound

$$R_{th\ mb-h} = 1,0\ ^\circ C/W$$

b. Without heatsink compound

$$R_{th\ mb-h} = 2,0\ ^\circ C/W$$

**MOUNTING INSTRUCTIONS**

1. Soldered joints must be at least 4 mm from the seal.
2. The maximum permissible temperature of the soldering iron or bath is 270 °C; contact with the joint must not exceed 3 seconds.
3. Avoid hot spots due to handling or mounting; the body of the device must not come into contact with or be exposed to a temperature higher than 150 °C. ←
4. Leads should not be bent less than 4 mm from the seal. Exert no axial pull when bending.
5. Recommended force of clip on device is 120 N (12 kgf).
6. The heatsink should be in contact with the entire mounting base of the device and heatsink compound should be used.

**CHARACTERISTICS**

Forward voltage (2 diodes in series)

$$I_F = 10\ A; T_j = 25\ ^\circ C$$

$$V_F < 2,3\ V^*$$

Reverse current (2 diodes in parallel)

$$V_R = V_{IWMmax}; T_j = 25\ ^\circ C$$

$$I_R < 200\ \mu A$$

\* Measured under pulse conditions to avoid excessive dissipation.

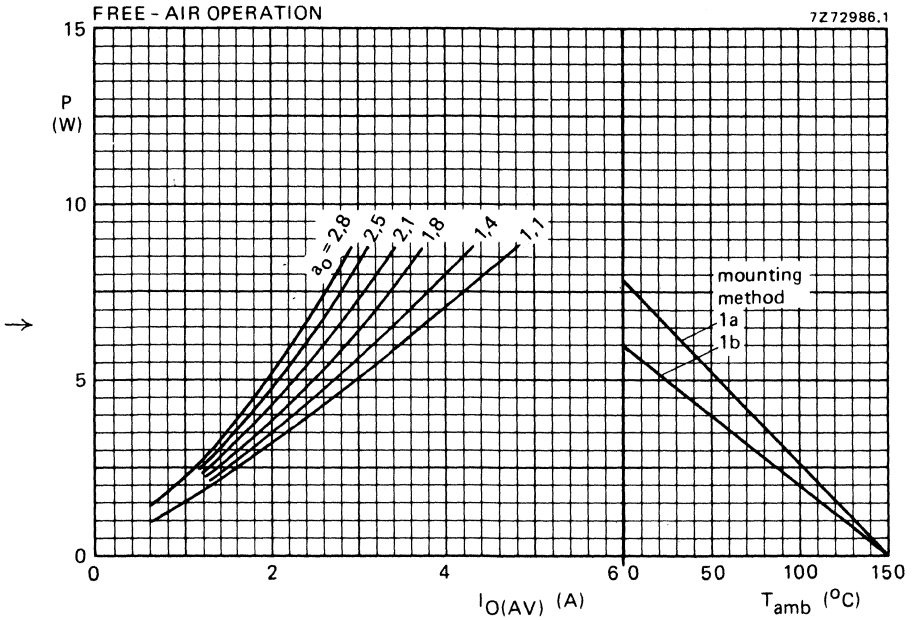


Fig. 2 The right-hand part shows the interrelationship between the power (derived from the left-hand graph) and the maximum permissible ambient temperature.

Output form factor  $a_0 = I_{O(RMS)} / I_{O(AV)} = 0,707 \times I_{F(RMS)} / I_{F(AV)}$  per diode.

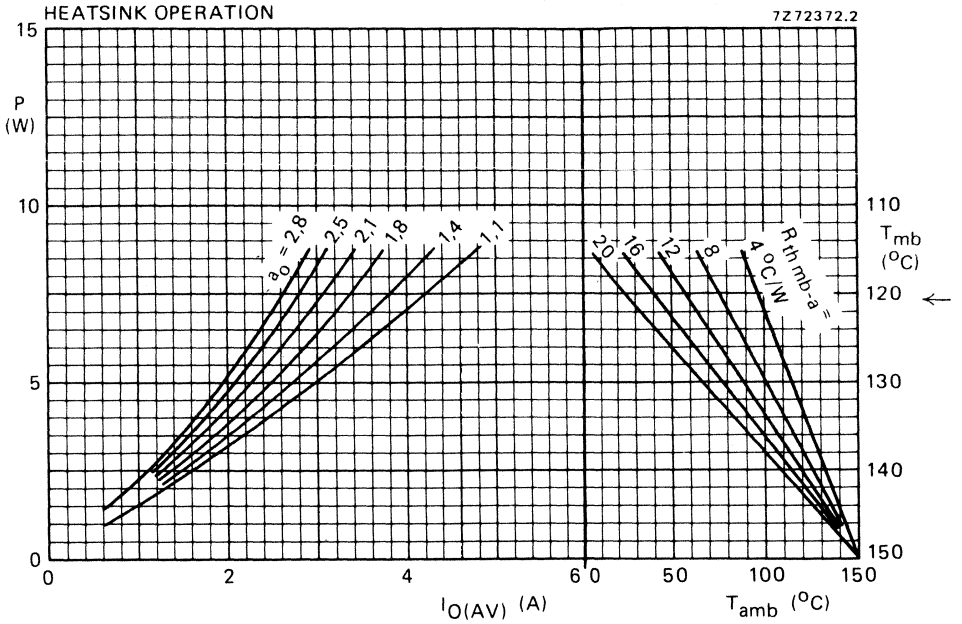


Fig. 3 The right-hand part shows the interrelationship between the power (derived from the left-hand graph) and the maximum permissible temperatures.

Output form factor  $a_0 = I_{O(RMS)}/I_{O(AV)} = 0,707 \times I_{F(RMS)}/I_{F(AV)}$  per diode.

7Z72373.2A

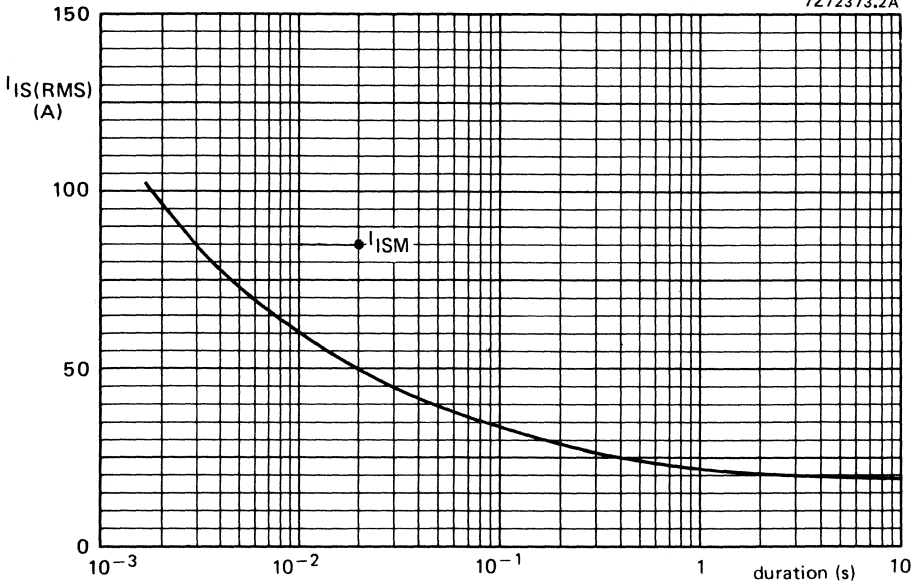


Fig.4 Maximum permissible non-repetitive r.m.s. input current based on sinusoidal currents ( $f = 50 \text{ Hz}$ );  
 $\rightarrow T_j = 150 \text{ }^\circ\text{C}$  prior to surge; with reapplied  $V_{IWMmax}$ .

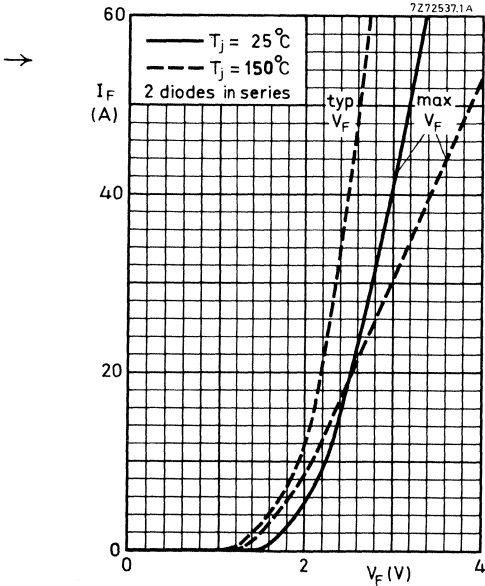
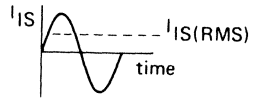
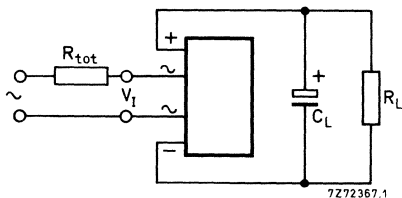
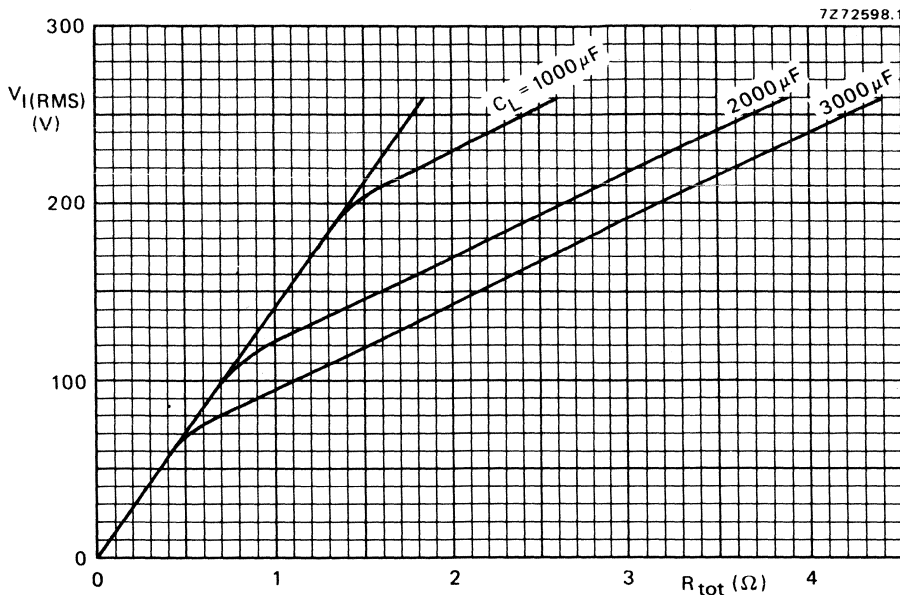


Fig.5

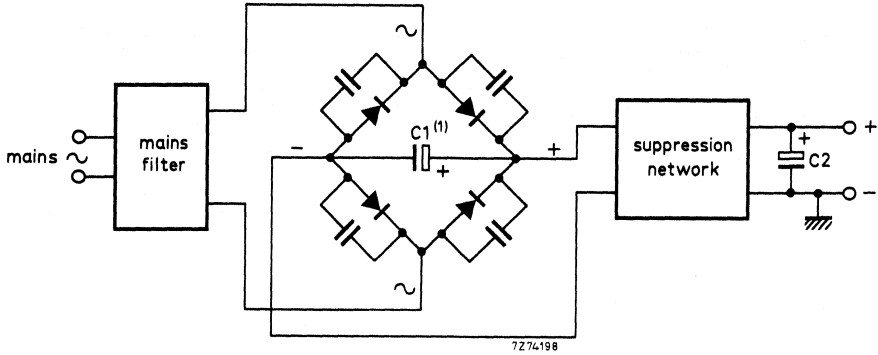


The graph takes the possibility of the following spreads into account:

- mains voltage +10%
- capacitance +50%
- resistance -10%

Fig. 6 Minimum value of the total series resistance  $R_{tot}$  (including the transformer resistance) required to limit the peak inrush current.

APPLICATION INFORMATION



(1) External capacitor.

Fig. 7 Because smoothing capacitor C2 is not always connected directly across the bridge (a suppression network may be sited between capacitor and bridge as shown), it is necessary to connect a capacitor of about  $1 \mu\text{F}$ , C1, between the + and - terminals of the bridge. This capacitor should be as close to the bridge as possible, to give optimum suppression of mains transients.

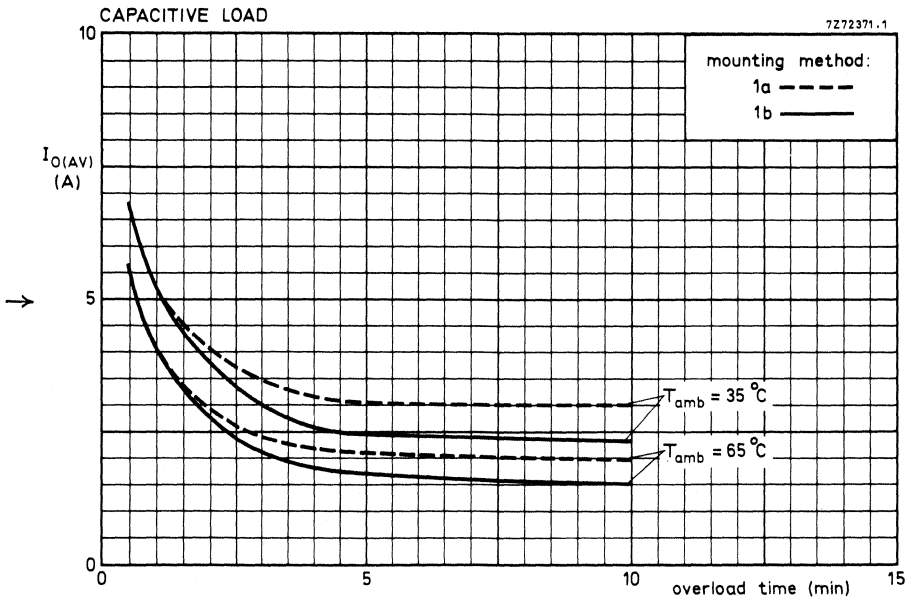


Fig.8



## SILICON BRIDGE RECTIFIERS

Ready-for-use full-wave bridge rectifiers in a plastic encapsulation. The bridges are intended for use in equipment supplied from a.c. with r.m.s. voltages up to 80 V and are capable of delivering output currents up to 4,8 A. They are also suitable for use in hi-fi audio equipments and low-voltage industrial power supplies. They may be used in free air or clipped to a heatsink.

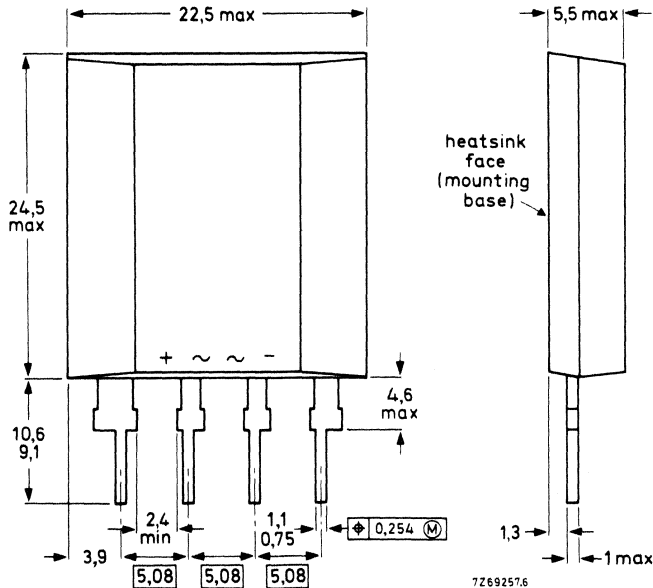
### QUICK REFERENCE DATA

Input	BY225-100		200
	R.M.S. voltage	$V_I(\text{RMS})$	max. 50
Repetitive peak voltage	$V_{IRM}$	max. 100	200 V
Non-repetitive peak current	$I_{ISM}$	max.	100 A
Peak inrush current	$I_{IIM}$	max.	200 A
<b>Output</b>			
Average current	$I_{O(AV)}$	max.	4,8 A

### MECHANICAL DATA

Dimensions in mm

Fig. 1 SOT-112.



Net mass: 6,8 g

Accessories supplied on request: 56366 (clip); for mounting instructions see data 56366.

The sealing of the plastic withstands the accelerated damp heat test of IEC recommendation 68-2 (test D, severity IV, 6 cycles).

# BY225 SERIES

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

Input	BY225-100		200
	max.	100	200 V
Non-repetitive peak voltage ( $t \leq 10$ ms)	$V_{ISM}$	max. 100	200 V
Repetitive peak voltage	$V_{IRM}$	max. 100	200 V
Crest working voltage	$V_{IWM}$	max. 70	112 V
R.M.S. voltage (sine-wave)	$V_{I(RMS)}$	max. 50	80 V
Non-repetitive peak current; half sine-wave; $t = 20$ ms; with reapplied $V_{IWMmax}$			
$T_j = 25$ °C prior to surge	$I_{ISM}$	max.	100 A
$T_j = 150$ °C prior to surge	$I_{ISM}$	max.	85 A
Peak inrush current (see Fig. 6)	$I_{IIM}$	max.	200 A
<b>Output</b>			
Average current (averaged over any 20 ms period; see Figs 2 and 3)			
heatsink operation up to $T_{mb} = 115$ °C	$I_{O(AV)}$	max.	4,8 A
heatsink operation at $T_{mb} = 125$ °C	$I_{O(AV)}$	max.	3,6 A
free-air operation at $T_{amb} = 45$ °C; (mounting method 1a)	$I_{O(AV)}$	max.	3,2 A
Repetitive peak current	$I_{ORM}$	max.	50 A
<b>Temperatures</b>			
Storage temperature	$T_{stg}$		-40 to +150 °C
Junction temperature	$T_j$	max.	150 °C

**THERMAL RESISTANCE**

From junction to mounting base  $R_{th\ j-mb} = 4,0\ ^\circ\text{C/W}$

**Influence of mounting method**

## 1. Free-air operation

The quoted values of  $R_{th\ j-a}$  should be used only when no leads of other dissipating components run to the same tie-point (see Fig. 2).

Thermal resistance from junction to ambient in free air

a. Mounted on a printed-circuit board with  $4\ \text{cm}^2$  of copper laminate to + and - leads  $R_{th\ j-a} = 19,5\ ^\circ\text{C/W}$

b. Mounted on a printed-circuit board with minimal copper laminate  $R_{th\ j-a} = 25\ ^\circ\text{C/W}$

## 2. Heatsink mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. With zinc-oxide heatsink compound  $R_{th\ mb-h} = 1,0\ ^\circ\text{C/W}$

b. Without heatsink compound  $R_{th\ mb-h} = 2,0\ ^\circ\text{C/W}$

**MOUNTING INSTRUCTIONS**

- Soldered joints must be at least 4 mm from the seal.
- The maximum permissible temperature of the soldering iron or bath is  $270\ ^\circ\text{C}$ ; contact with the joint must not exceed 3 seconds.
- Avoid hot spots due to handling or mounting; the body of the device must not come into contact with or be exposed to a temperature higher than  $150\ ^\circ\text{C}$ .
- Leads should not be bent less than 4 mm from the seal. Exert no axial pull when bending.
- Recommended force of clip on device is 120 N (12 kgf).
- The heatsink should be in contact with the entire mounting base of the device and heatsink compound should be used.

**CHARACTERISTICS**

Forward voltage (2 diodes in series)

$I_F = 10\ \text{A}; T_j = 25\ ^\circ\text{C}$   $V_F < 2,3\ \text{V}^*$

Reverse current (2 diodes in parallel)

$V_R = V_{IWM\text{max}}; T_j = 25\ ^\circ\text{C}$   $I_R < 200\ \mu\text{A}$

\* Measured under pulse conditions to avoid excessive dissipation.

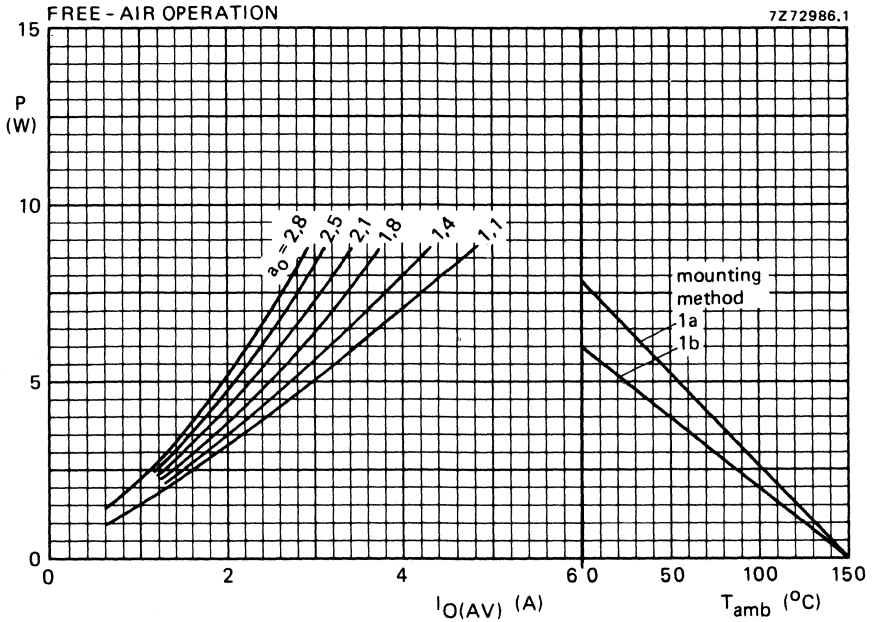


Fig. 2 The right-hand part shows the interrelationship between the power (derived from the left-hand graph) and the maximum permissible ambient temperature.

Output form factor  $a_0 = I_{O(RMS)}/I_{O(AV)} = 0,707 \times I_{F(RMS)}/I_{F(AV)}$  per diode.

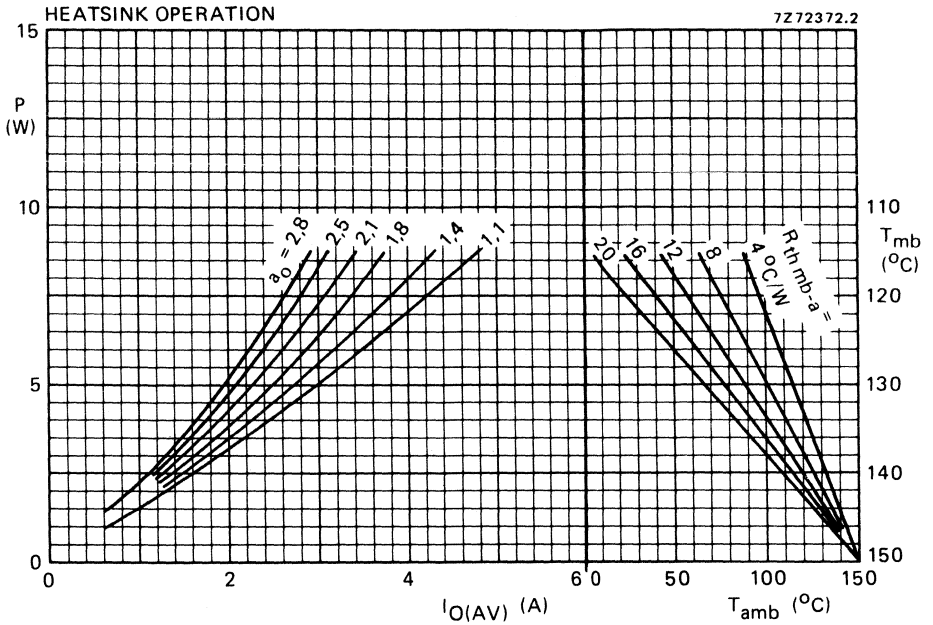


Fig. 3 The right-hand part shows the interrelationship between the power (derived from the left-hand graph) and the maximum permissible temperatures.

Output form factor  $a_o = I_{O(RMS)}/I_{O(AV)} = 0.707 \times I_{F(RMS)}/I_{F(AV)}$  per diode.

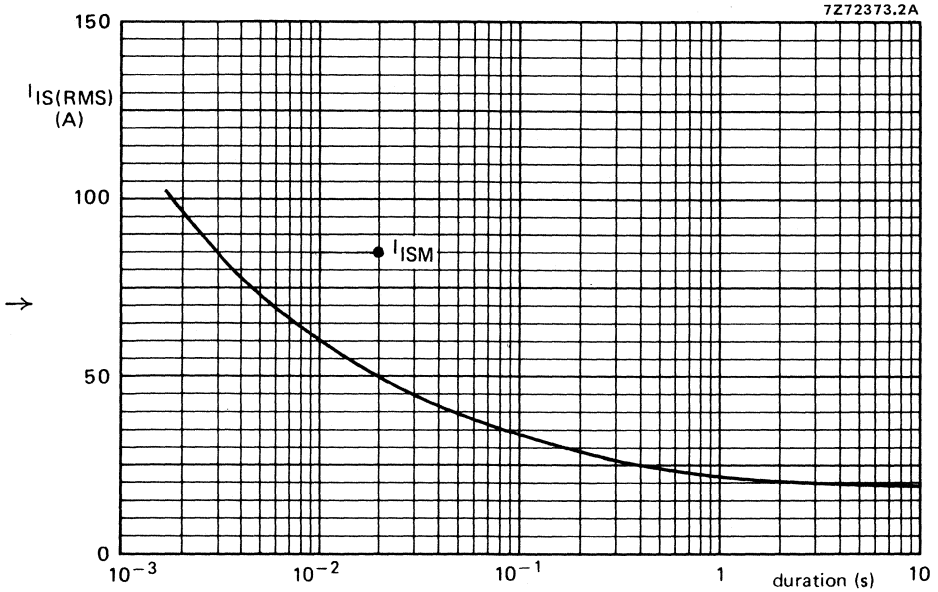


Fig. 4 Maximum permissible non-repetitive r.m.s. input current based on sinusoidal currents ( $f = 50$  Hz);  $T_j = 150^\circ\text{C}$  prior to surge; with reapplied  $V_{IWMmax}$ .

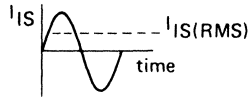
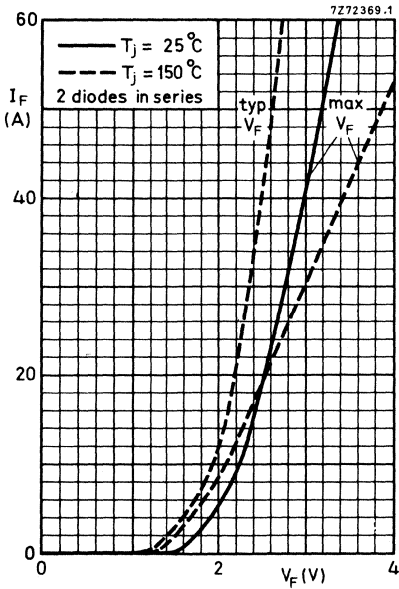
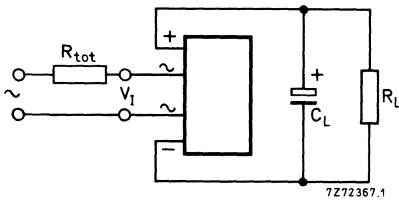
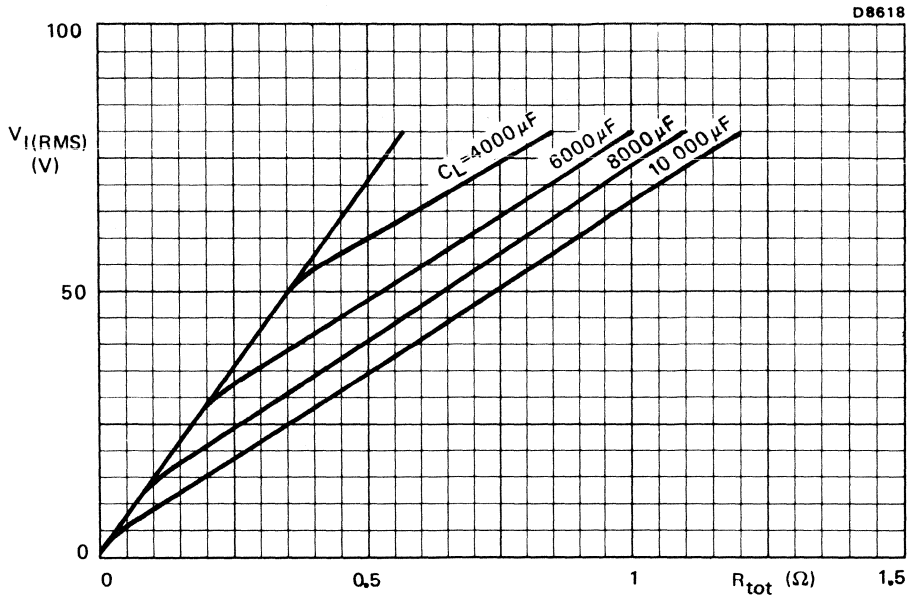


Fig. 5.



The graph takes the possibility of the following spreads into account:

- input voltage +10%
- capacitance +50%
- resistance -10%

Fig. 6 Minimum value of the total series resistance  $R_{tot}$  (including the transformer resistance) required to limit the peak inrush current.

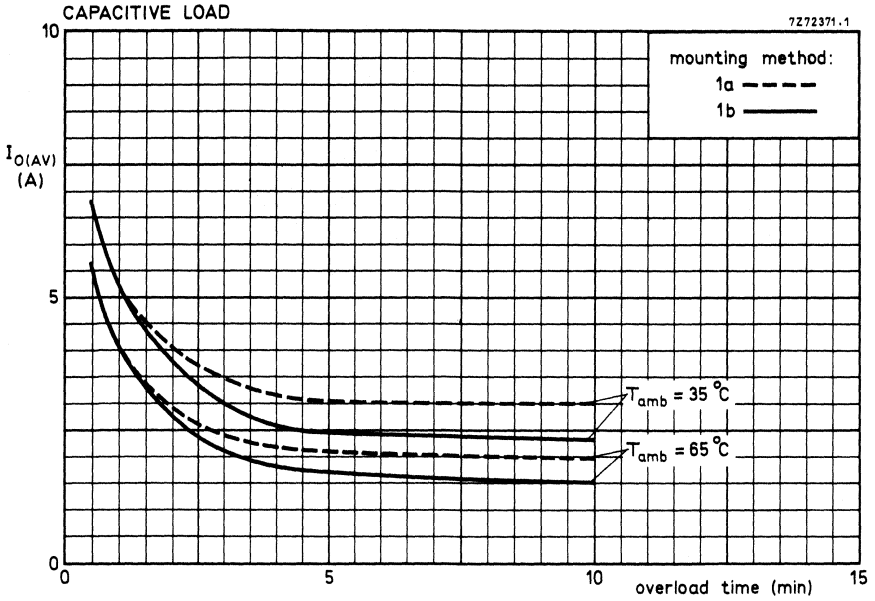


Fig. 7.



## FAST SOFT-RECOVERY RECTIFIER DIODES

Glass-passivated double-diffused rectifier diodes in plastic envelopes, featuring fast reverse recovery times and non-snap-off characteristics. They are intended for use in chopper applications as well as in switched-mode power supplies, as efficiency diodes and scan rectifiers in television receivers. The series consists of normal polarity (cathode to mounting base) types.

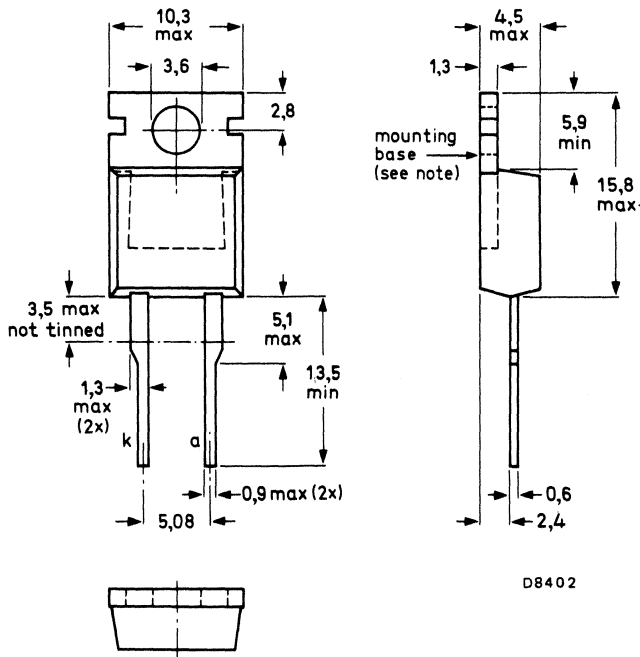
### QUICK REFERENCE DATA

		BY229-200	400	600	800	
Repetitive peak reverse voltage	$V_{RRM}$	max. 200	400	600	800	V
Average forward current	$I_F(AV)$	max. 7				A
Non-repetitive peak forward current	$I_{FSM}$	max. 60				A
Reverse recovery time	$t_{rr}$	< 450				ns

### MECHANICAL DATA

Dimensions in mm

Fig.1 SOD-59 (TO-220AC).



Note: The exposed metal mounting base is directly connected to the cathode. Accessories supplied on request: see data sheets Mounting instructions and accessories for TO-220 envelopes.

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

### Voltages\*

		BY229-200	400	600	800	
Non-repetitive peak reverse voltage	$V_{RSM}$	max. 200	400	600	800	V
Repetitive peak reverse voltage	$V_{RRM}$	max. 200	400	600	800	V
Crest working reverse voltage	$V_{RWM}$	max. 150	300	500	600	V
Continuous reverse voltage	$V_R$	max. 150	300	500	600	V

### Currents

Average forward current assuming zero switching losses

square-wave; $\delta = 0.5$ ; up to $T_{mb} = 100^\circ\text{C}$	$I_F(AV)$	max.	7			A
square-wave; $\delta = 0.5$ ; at $T_{mb} = 125^\circ\text{C}$	$I_F(AV)$	max.	4.1			A
sinusoidal; up to $T_{mb} = 101^\circ\text{C}$	$I_F(AV)$	max.	6.5			A
sinusoidal; at $T_{mb} = 125^\circ\text{C}$	$I_F(AV)$	max.	4			A

R.M.S. forward current	$I_F(RMS)$	max.	10			A
Repetitive peak forward current	$I_{FRM}$	max.	60			A
Repetitive peak forward current $t_p = 20 \mu\text{s}$ ; $\delta \leq 0.02$	$I_{FRM}$	max.	75			A

Non-repetitive peak forward current;  $t = 10 \text{ ms}$   
half sine-wave;  $T_j = 150^\circ\text{C}$  prior to surge;  
with reapplied  $V_{RWMmax}$

$I_{FSM}$	max.	60				A
-----------	------	----	--	--	--	---

### Temperatures

Storage temperature	$T_{stg}$		-40 to +150			$^\circ\text{C}$
Junction temperature	$T_j$	max.	150			$^\circ\text{C}$

\*To ensure thermal stability:  $R_{th j-a} \leq 15^\circ\text{C/W}$  for continuous reverse voltage.

**THERMAL RESISTANCE**

From junction to mounting base

$$R_{th\ j-mb} = 4.5\ ^\circ\text{C/W}$$

**Influence of mounting method**

1. Heatsink mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound

$$R_{th\ mb-h} = 0.3\ ^\circ\text{C/W}$$

b. with heatsink compound and 0.06 mm maximum mica insulator

$$R_{th\ mb-h} = 1.4\ ^\circ\text{C/W}$$

c. with heatsink compound and 0.1 mm maximum mica insulator (56369)

$$R_{th\ mb-h} = 2.2\ ^\circ\text{C/W}$$

d. with heatsink compound and 0.25 mm maximum alumina insulator (56367)

$$R_{th\ mb-h} = 0.8\ ^\circ\text{C/W}$$

e. without heatsink compound

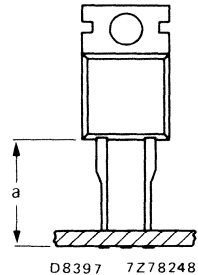
$$R_{th\ mb-h} = 1.4\ ^\circ\text{C/W}$$

2. Free-air operation

The quoted value of  $R_{th\ j-a}$  should be used only when no leads of other dissipating components run to the same tie-point. Thermal resistance from junction to ambient in free air: mounted on a printed-circuit board at  $a =$  any lead length.

$$R_{th\ j-a} = 60\ ^\circ\text{C/W}$$

Fig.2

**MOUNTING INSTRUCTIONS**

- The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; it must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
- The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending.
- It is recommended that the circuit connection be made to the cathode tag, rather than direct to the heatsink.
- Mounting by means of a spring clip is the best mounting method because it offers:
  - a good thermal contact under the crystal area and slightly lower  $R_{th\ mb-h}$  values than screw mounting;
  - safe isolation for mains operation.
 However, if a screw is used, it should be M3 cross-recess pan head. Care should be taken to avoid damage to the plastic body.
- For good thermal contact heatsink compound should be used between base-plate and heatsink. Values of  $R_{th\ mb-h}$  given for mounting with heatsink compound refer to the use of a metallic-oxide loaded compound. Ordinary silicone grease is not recommended.
- The device should not be pop-riveted to the heatsink. However, it is permissible to press-rivet providing that rivets of soft material are used, and the press forces are slowly and carefully controlled so as to avoid shock and deformation of either heatsink or mounting tab.

CHARACTERISTICS

Forward voltage

$I_F = 20 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_F < 1.85 \text{ V}^*$

Reverse current

$V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$

$I_R < 0.4 \text{ mA}$

Reverse recovery when switched from

$I_F = 2 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 20 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

Recovered charge

$Q_s < 0.7 \text{ } \mu\text{C}$

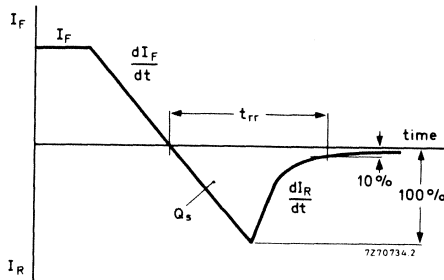
Recovery time

$t_{rr} < 450 \text{ ns}$

Maximum slope of the reverse recovery current

$I_F = 2 \text{ A}; -dI_F/dt = 20 \text{ A}/\mu\text{s}$

$|dI_R/dt| < 60 \text{ A}/\mu\text{s}$



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Fig. 3 Definition of  $t_{rr}$  and  $Q_s$

\*Measured under pulse conditions to avoid excessive dissipation.

SQUARE-WAVE OPERATION

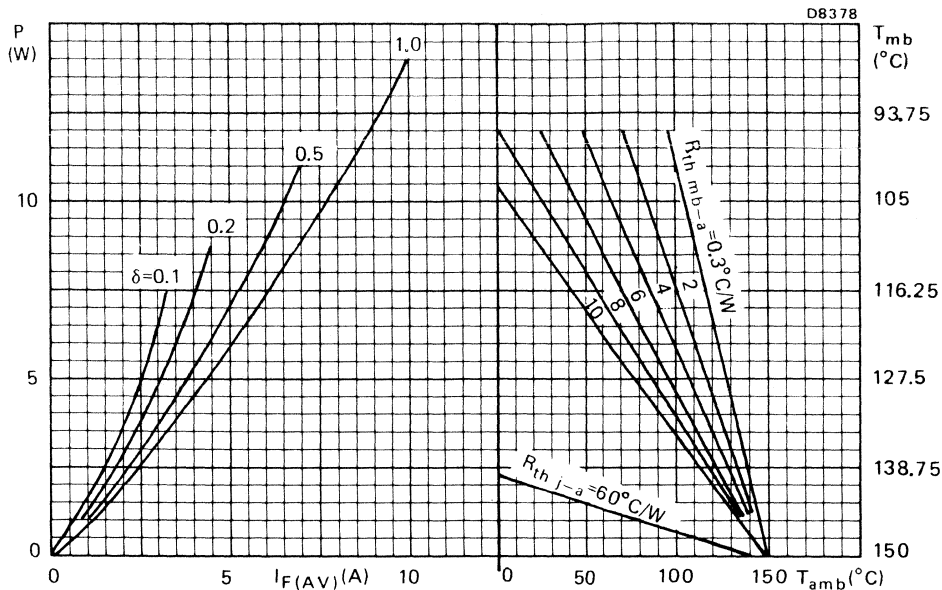
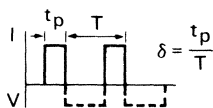


Fig. 4 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.  
 P = power including reverse current losses but excluding switching losses.



$$I_{F(AV)} = I_{F(RMS)} \times \sqrt{\delta}$$

SINUSOIDAL OPERATION

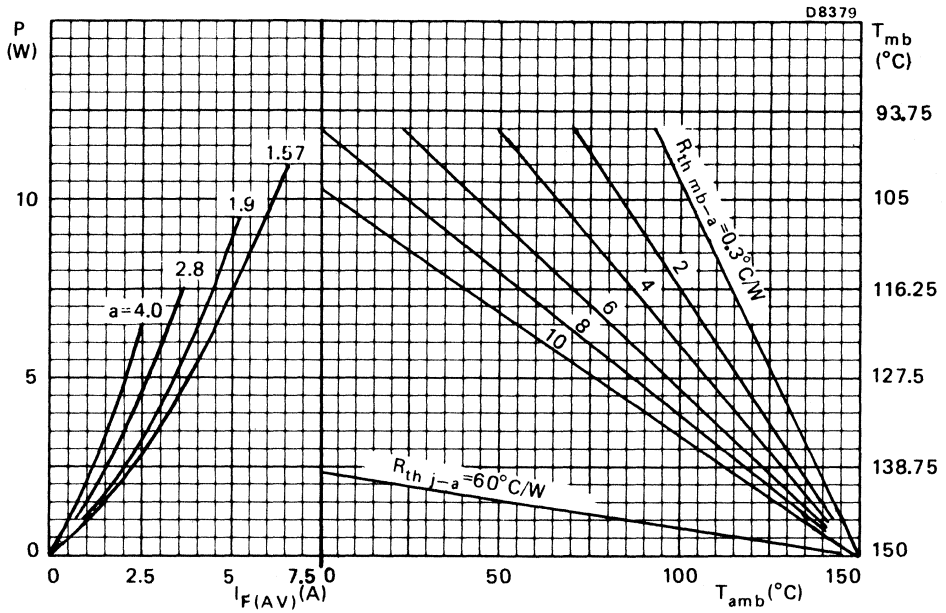


Fig. 5 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

P = power including reverse current losses but excluding switching losses.

a = form factor =  $I_F(\text{RMS})/I_F(\text{AV})$ .

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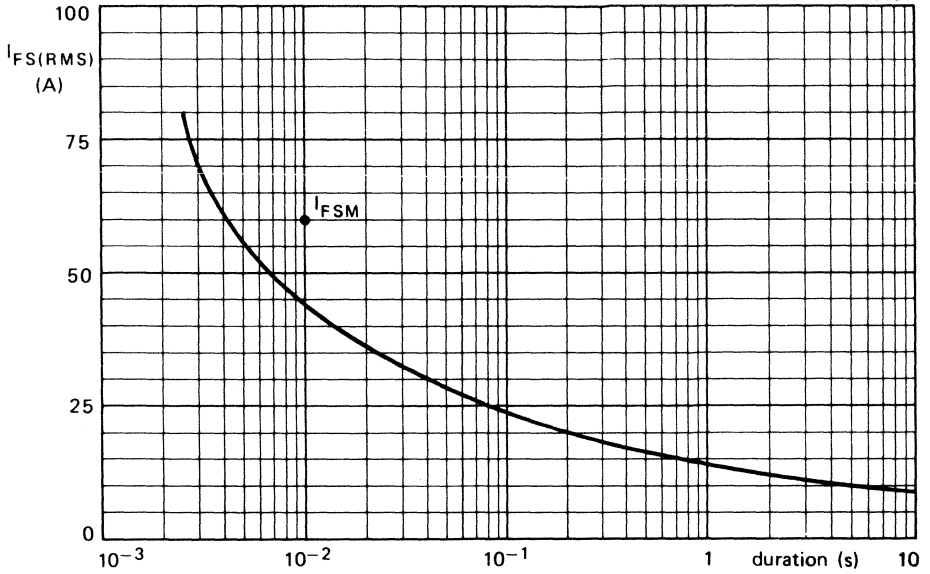


Fig. 6 Maximum permissible non-repetitive r.m.s. forward current based on sinusoidal currents ( $f = 50$  Hz);  $T_j = 150$  °C prior to surge; with reapplied  $V_{RWMmax}$ .

D8381

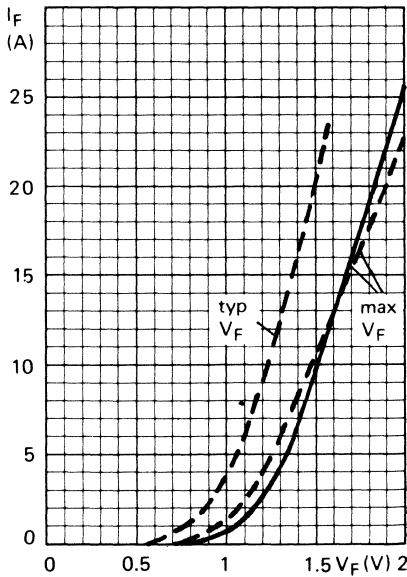


Fig. 7 —  $T_j = 25$  °C; - - -  $T_j = 125$  °C



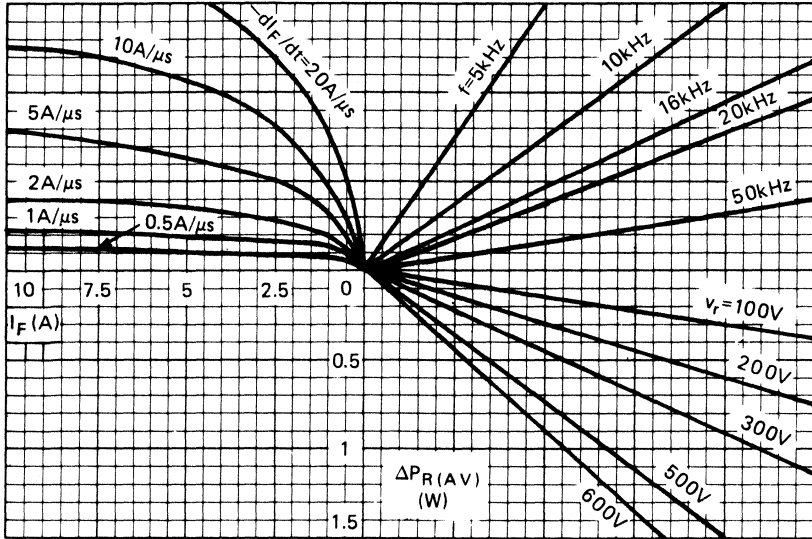
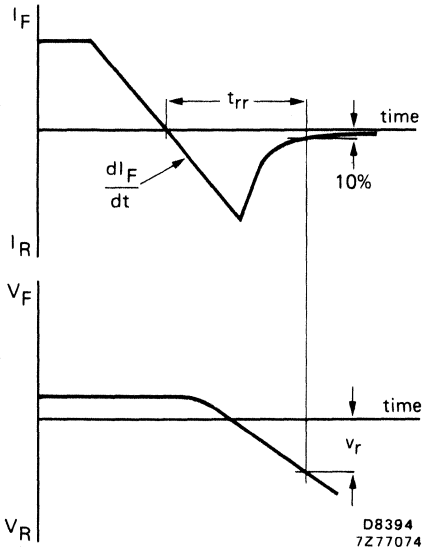


Fig. 8 NOMOGRAM

Power loss  $\Delta P_R(AV)$  due to switching only (to be added to steady state power losses).  
 $I_F$  = forward current just before switching off;  $T_j = 150\text{ }^\circ C$



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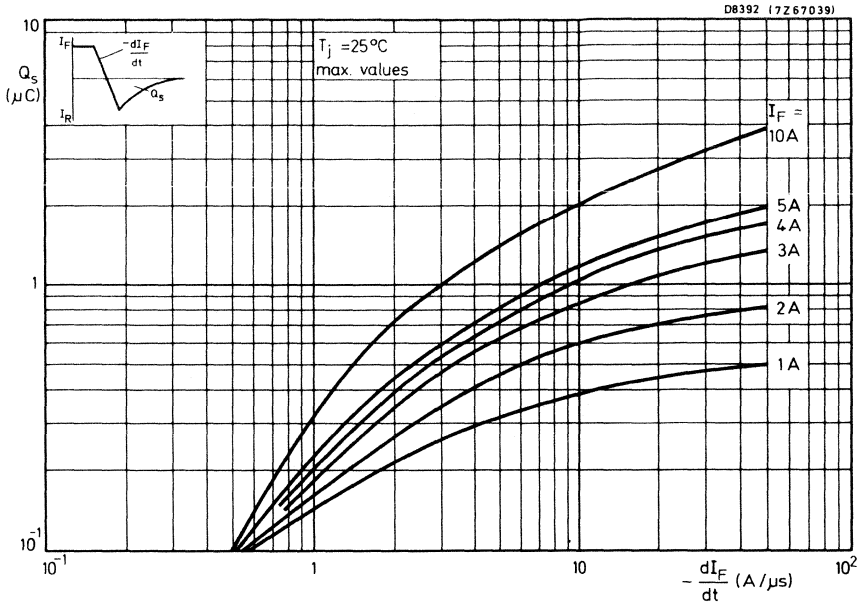


Fig.9

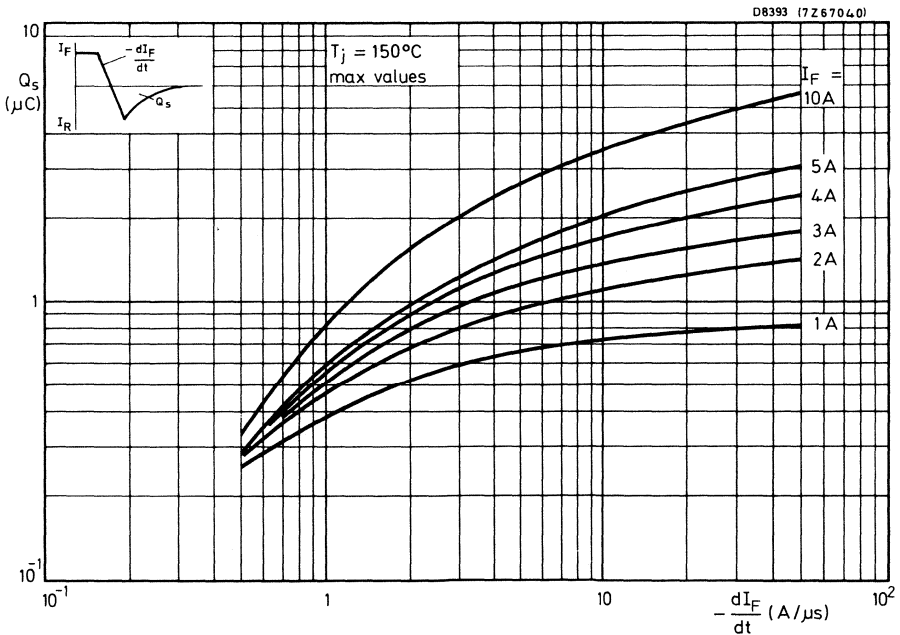


Fig.10

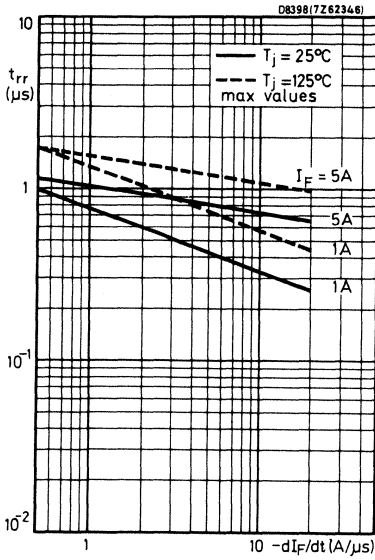


Fig. 11

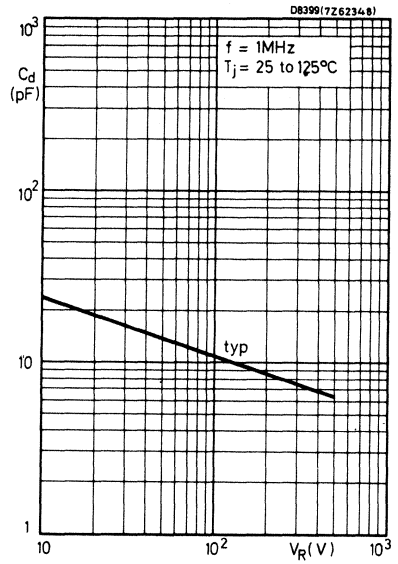


Fig. 12

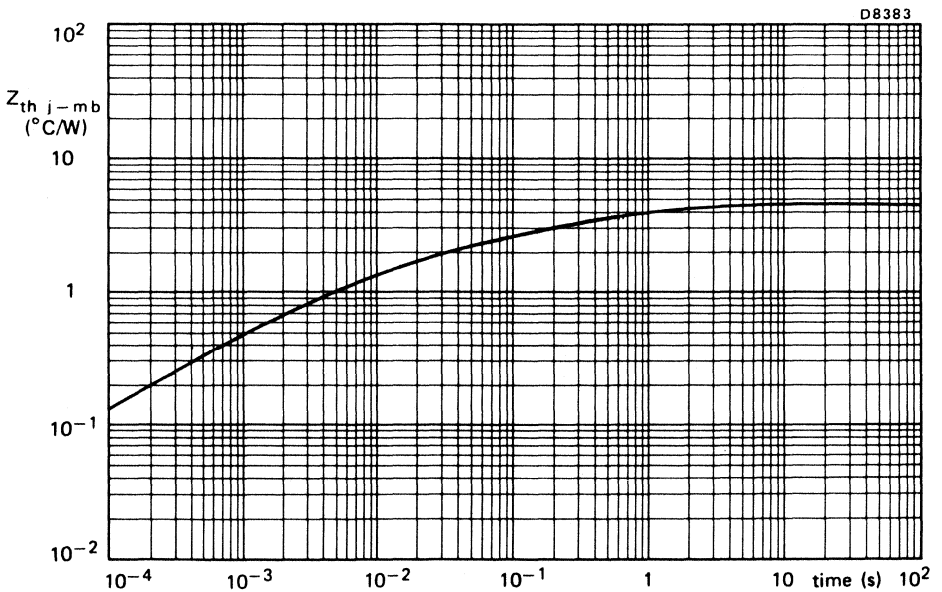
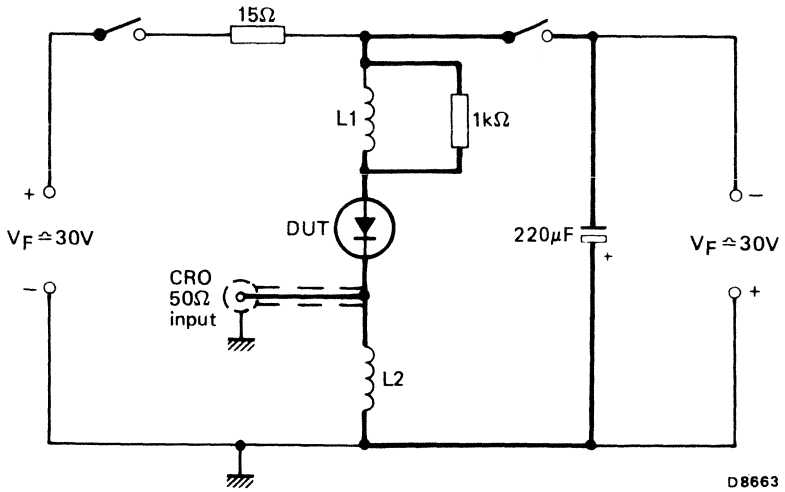


Fig. 13



D8663

Fig.14 Simplified circuit diagram of practical apparatus to test softness of recovery.

NOTES

1. Duty factor of forward current should be low,  $< 2\%$ .
2.  $dI_F/dt$  is set by  $L1$ ,  $1.5 \mu H$  gives  $20 A/\mu s$
3.  $dI_R/dt$  is measured across  $L2$ ,  $200 nH$  gives  $5A/\mu s/V$ .
4. Wiring shown in heavy should be kept as short as possible.



## SILICON BRIDGE RECTIFIER

Ready-for-use full-wave bridge rectifier in a plastic encapsulation. The bridge is intended for use in equipment supplied from a.c. with r.m.s. voltages up to 80 V and is capable of delivering output currents up to 1.5 A.

## QUICK REFERENCE DATA

## Input

R.M.S. voltage	$V_I(\text{RMS})$	max.	80 V
Repetitive peak voltage	$V_{IRM}$	max.	200 V
Non-repetitive peak current	$I_{ISM}$	max.	50 A

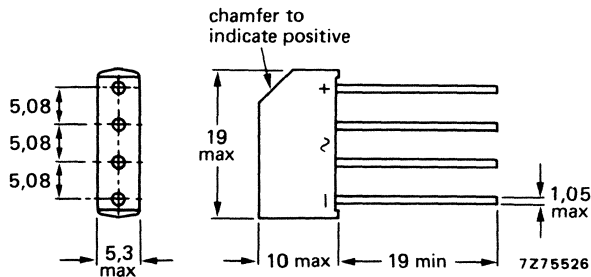
## Output

Average current	$I_O(\text{AV})$	max.	1.5 A
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## MECHANICAL DATA

Dimensions in mm

Fig.1 SOD-28



The sealing of the plastic envelope withstands the accelerated damp heat test of IEC recommendation 68-2 (test D, severity IV, 6 cycles).

**RATINGS**

Limiting values in accordance with the Absolute Maximum System (IEC 134)

**Input**

Non-repetitive peak voltage ( $t \leq 10$ ms)	$V_{ISM}$	max.	200 V
Repetitive peak voltage	$V_{IRM}$	max.	200 V
Crest working voltage	$V_{IWM}$	max.	112 V
R.M.S. voltage (sine-wave)	$V_{I(RMS)}$	max.	80 V
Non-repetitive peak current; half sine-wave; $t = 20$ ms; with reapplied $V_{IWMmax}$ $T_j = 150$ °C prior to surge	$I_{ISM}$	max.	50 A

**Output**

Average current (averaged over any 20 ms period); see Fig.3) free-air operation at $T_{amb} = 45$ °C; (mounting method a)	$I_{O(AV)}$	max.	1.5 A
Repetitive peak current	$I_{ORM}$	max.	10 A

**Temperatures**

Storage temperature	$T_{stg}$	-55 to +150 °C
Junction temperature	$T_j$	max. 150 °C

**THERMAL RESISTANCE****Influence of mounting method**

## 1. Free-air operation

The quoted values of  $R_{th\ j-a}$  should be used only when no leads of other dissipating components run to the same tie-point

Thermal resistance from junction to ambient in free air

- |  |               |   |         |
|--|---------------|---|---------|
| a. Mounted on a printed-circuit board with 4 cm <sup>2</sup> of copper laminate to + and – leads | $R_{th\ j-a}$ | = | 38 °C/W |
| b. Mounted on a printed-circuit board with minimal copper laminate; 1.5 mm lead length           | $R_{th\ j-a}$ | = | 52 °C/W |
| c. Mounted on a printed-circuit board with minimal copper laminate; maximum lead length          | $R_{th\ j-a}$ | = | 44 °C/W |

**MOUNTING INSTRUCTIONS**

1. The maximum permissible temperature of the soldering iron or bath is 270 °C; it must not be in contact with the joint for more than 3 seconds.
2. Avoid hot spots due to handling or mounting; the body of the device must not come into contact with or be exposed to a temperature higher than 150 °C
3. Exert no axial pull when bending.

**CHARACTERISTICS**

Forward voltage (2 diodes in series)

$I_F = 2\text{ A}; T_j = 25\text{ °C}$

$$V_F < 2.1\text{ V}^*$$

\*Measured under pulse conditions to avoid excessive dissipation.

**OPERATING NOTES**

The various components of junction temperature rise above ambient are illustrated below.

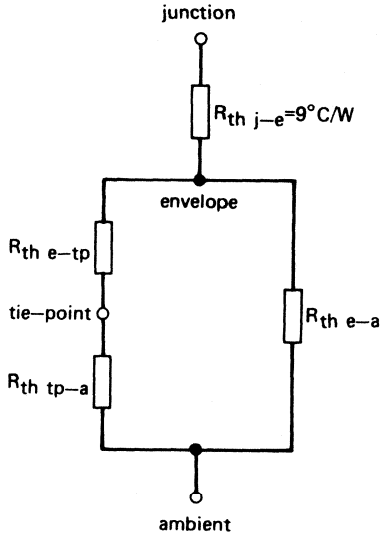


Fig.2

The thermal resistance between envelope and tie-point and between envelope and ambient depend on lead length:

lead length	1.5	5	10	15	max.	mm
$R_{th\ e-tp}$	1.2	4	8	12	15.2	$^\circ\text{C/W}$
$R_{th\ e-a}$	110	87	73	65	60	$^\circ\text{C/W}$

The thermal resistance between tie-point and ambient depends on the mounting method; for mounting on a 1.5 mm thick epoxy-glass printed-circuit board with a copper-thickness  $\geq 40\ \mu\text{m}$ , the following values apply:

1. Mounting with minimal copper laminate:  $R_{th\ tp-a} = 70\ ^\circ\text{C/W}$
2. Mounted on a printed-circuit board with a copper laminate to the + and - lead of:

1  $\text{cm}^2$  :  $R_{th\ tp-a} = 55\ ^\circ\text{C/W}$   
 2.25  $\text{cm}^2$  :  $R_{th\ tp-a} = 45\ ^\circ\text{C/W}$   
 4  $\text{cm}^2$  :  $R_{th\ tp-a} = 40\ ^\circ\text{C/W}$

Note: Any temperature can be calculated by using the dissipation graphs and the above thermal model.



FREE-AIR OPERATION

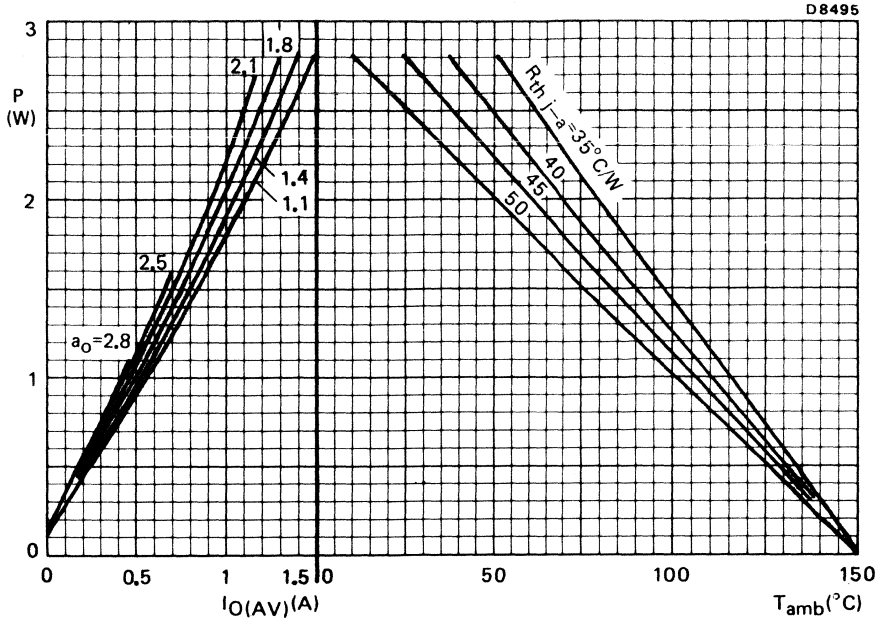


Fig.3 The right-hand part shows the interrelationship between the power (derived from the left-hand graph) and the maximum permissible ambient temperature.

Output form factor  $a_0 = I_{O(RMS)}/I_{O(AV)} = 0.707 \times I_{F(RMS)}/I_{F(AV)}$  per diode.

D8496

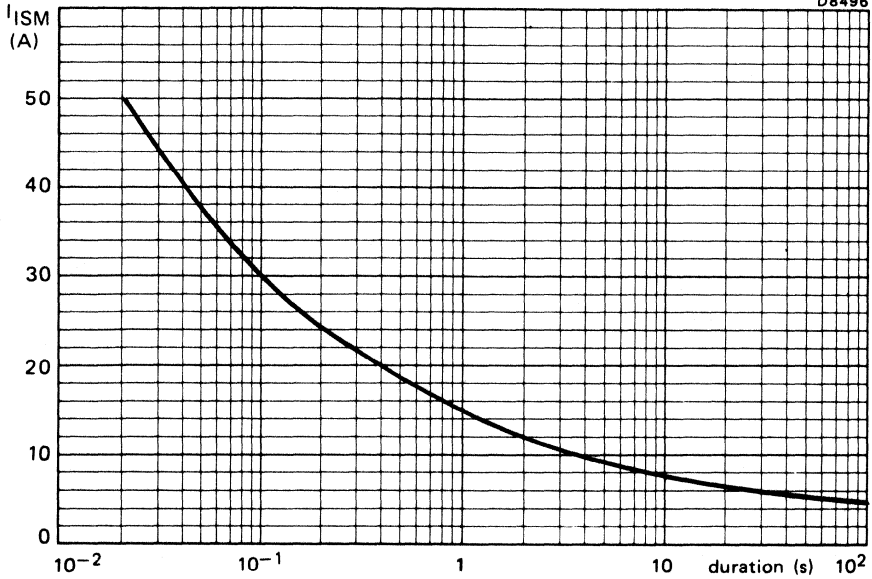


Fig.4 Maximum permissible non-repetitive peak input current based on sinusoidal currents ( $f = 50$  Hz);  $T_j = 150$  °C prior to surge; with reapplied  $V_{IWMmax}$ .

D8497

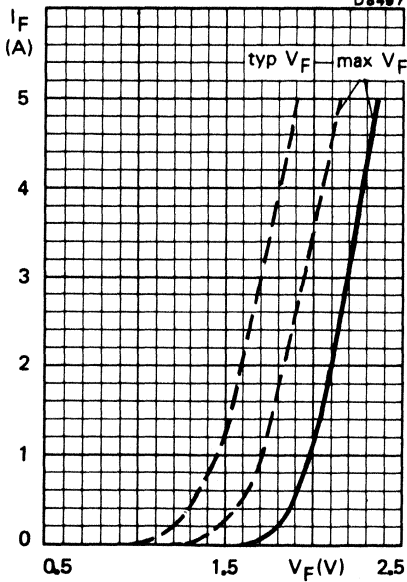
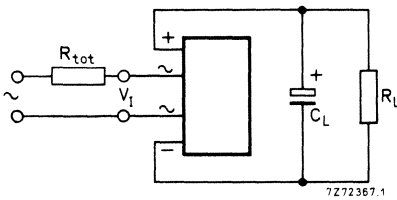
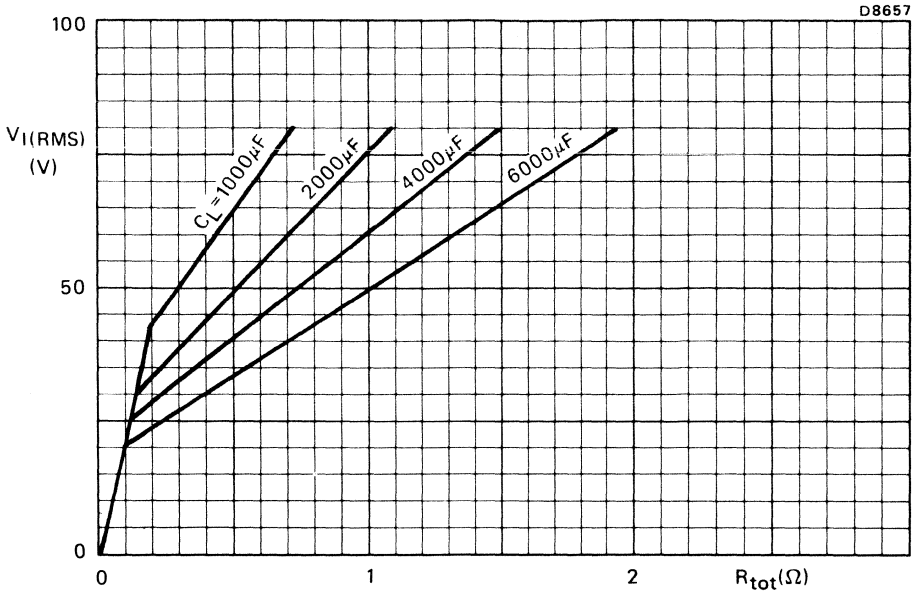


Fig.5 —  $T_j = 25$  °C; - - -  $T_j = 150$  °C; 2 diodes in series.



The graph takes the possibility of the following spreads into account:

- input voltage +10%
- capacitance +50%
- resistance -10%

Fig.6 Minimum value of the total series resistance  $R_{tot}$  (including the transformer resistance) required to limit the peak inrush current.



## SILICON BRIDGE RECTIFIER

Ready-for-use full-wave bridge rectifier in a plastic encapsulation. The bridge is intended for use in equipment supplied from mains with r.m.s. voltages up to 280 V and is capable of delivering output currents up to 1.5 A.

## QUICK REFERENCE DATA

**Input**

R.M.S. voltage	$V_{I(RMS)}$	max.	280 V
Repetitive peak voltage	$V_{IRM}$	max.	600 V
Non-repetitive peak current	$I_{ISM}$	max.	50 A

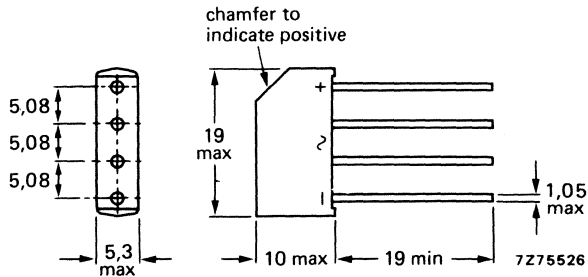
**Output**

Average current	$I_{OA(V)}$	max.	1.5 A
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## MECHANICAL DATA

Dimensions in mm

Fig. 1 SOD-28



The sealing of the plastic envelope withstands the accelerated damp heat test of IEC recommendation 68-2 (test D, severity IV, 6 cycles).

**RATINGS**

Limiting values in accordance with the Absolute Maximum System (IEC 134)

**Input**

Non-repetitive peak voltage ( $t \leq 10$ ms)	$V_{ISM}$	max.	600 V
Repetitive peak voltage	$V_{IRM}$	max.	600 V
Crest working voltage	$V_{IWM}$	max.	400 V
R.M.S. voltage (sine-wave)	$V_I(RMS)$	max.	280 V
Non-repetitive peak current;*			
half sine-wave; $t = 20$ ms; with reapplied $V_{IWMmax}$			
$T_j = 150$ °C prior to surge	$I_{ISM}$	max.	50 A

**Output**

Average current (averaged over any 20 ms period; see Fig.3)			
free-air operation at $T_{amb} = 45$ °C; (mounting method a)	$I_{O(AV)}$	max.	1.5 A
Repetitive peak current	$I_{ORM}$	max.	10 A

**Temperatures**

Storage temperature	$T_{stg}$	-55 to +150	°C
Junction temperature	$T_j$	max.	150 °C

**THERMAL RESISTANCE****Influence of mounting method**

## 1. Free-air operation

The quoted values of  $R_{th\ j-a}$  should be used only when no leads of other dissipating components run to the same tie-point.

Thermal resistance from junction to ambient in free air

- |  |               |   |         |
|--|---------------|---|---------|
| a. Mounted on a printed-circuit board with 4 cm <sup>2</sup> of copper laminate to + and - leads | $R_{th\ j-a}$ | = | 38 °C/W |
| b. Mounted on a printed-circuit board with minimal copper laminate; 1.5 mm lead length           | $R_{th\ j-a}$ | = | 52 °C/W |
| c. Mounted on a printed-circuit board with minimal copper laminate; maximum lead length          | $R_{th\ j-a}$ | = | 44 °C/W |

**MOUNTING INSTRUCTIONS**

1. The maximum permissible temperature of the soldering iron or bath is 270 °C; it must not be in contact with the joint for more than 3 seconds.
2. Avoid hot spots due to handling or mounting; the body of the device must not come into contact with or be exposed to a temperature higher than 150 °C.
3. Exert no axial pull when bending.

**CHARACTERISTICS**

Forward voltage (2 diodes in series)

$I_F = 2\text{ A}; T_j = 25\text{ °C}$	$V_F$	<	2.1 V*
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\*Measured under pulse conditions to avoid excessive dissipation.

**OPERATING NOTES**

The various components of junction temperature rise above ambient are illustrated below.

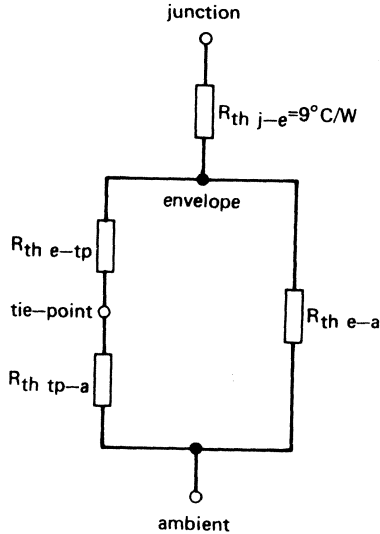


Fig.2

The thermal resistance between envelope and tie-point and between envelope and ambient depend on lead length:

lead length	1.5	5	10	15	max.	mm
$R_{th\ e-tp}$	1.2	4	8	12	15.2	$^\circ C/W$
$R_{th\ e-a}$	110	87	73	65	60	$^\circ C/W$

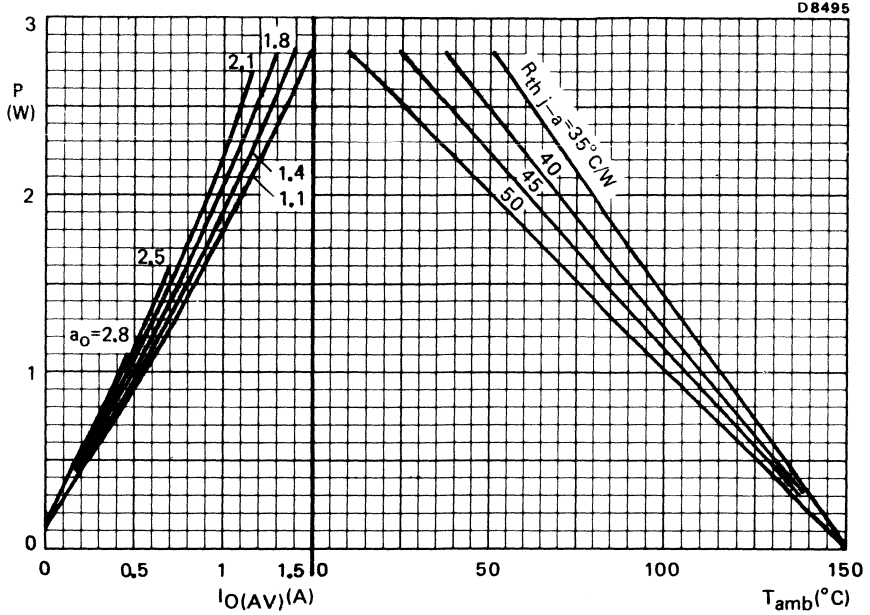
The thermal resistance between tie-point and ambient depends on the mounting method. For mounting on a 1.5 mm thick epoxy-glass printed-circuit board with a copper-thickness  $\geq 40\ \mu m$ , the following values apply:

1. Mounting with minimal copper laminate:  $R_{th\ tp-a} = 70\ ^\circ C/W$
2. Mounted on a printed-circuit board with a copper laminate to the + and - lead of:
  - 1  $cm^2$  :  $R_{th\ tp-a} = 55\ ^\circ C/W$
  - 2.25  $cm^2$  :  $R_{th\ tp-a} = 45\ ^\circ C/W$
  - 4  $cm^2$  :  $R_{th\ tp-a} = 40\ ^\circ C/W$

Note: Any temperature can be calculated by using the dissipation graphs and the above thermal model.



FREE-AIR OPERATION



D8495

Fig.3 The right-hand part shows the interrelationship between the power (derived from the left-hand graph) and the maximum permissible ambient temperature.

Output form factor  $a_o = I_O(RMS)/I_O(AV) = 0.707 \times I_F(RMS)/I_F(AV)$  per diode.

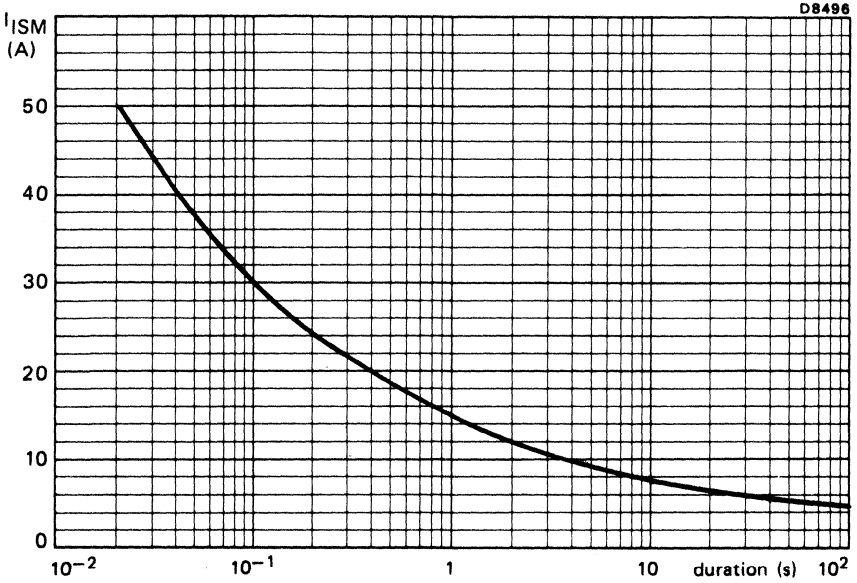


Fig.4 Maximum permissible non-repetitive peak input current based on sinusoidal currents ( $f = 50$  Hz);  $T_j = 150$  °C prior to surge; with reapplied  $V_{IWMmax}$ ;

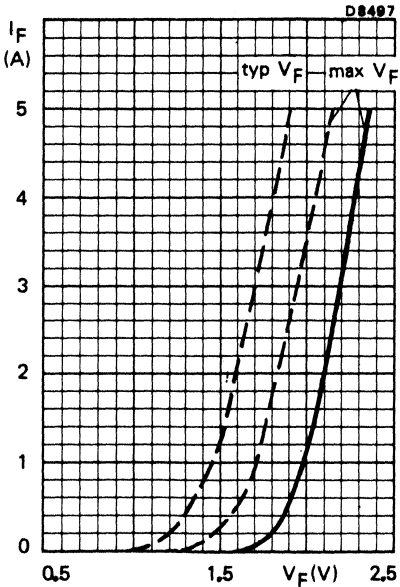
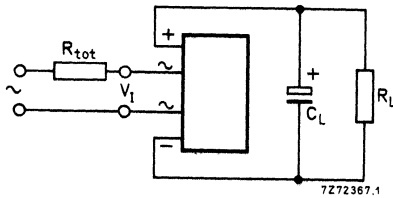
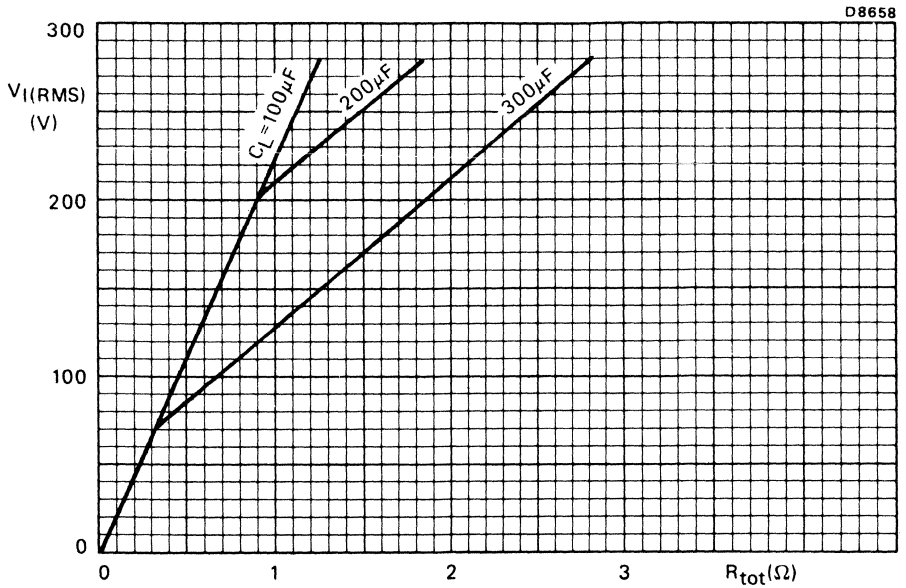


Fig.5 ———  $T_j = 25$  °C; - - -  $T_j = 150$  °C; 2 diodes in series



The graph takes the possibility of the following spreads into account:

- input voltage +10%
- capacitance +50%
- resistance -10%

Fig.6 Minimum value of the total series resistance  $R_{tot}$  (including the transformer resistance) required to limit the peak inrush current.



SILICON BRIDGE RECTIFIERS

Ready for use full-wave bridge rectifiers in a plastic encapsulation.

The bridges are intended for use in equipment supplied from a.c. with r.m.s. voltages up to 420 V and are capable of delivering output currents up to 12A. They are also suitable for use in hi-fi audio equipments and low-voltage industrial power supplies. They may be used in free air or on a heatsink.

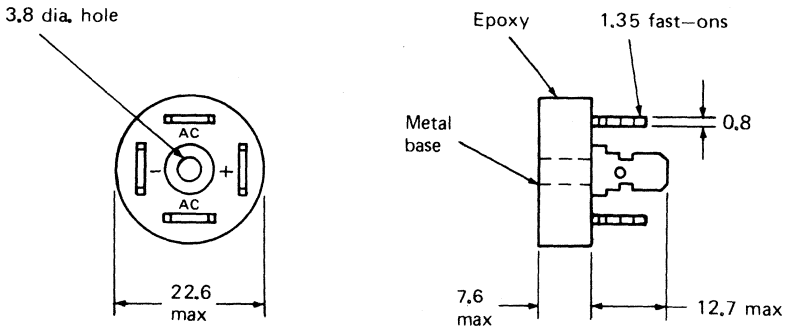
QUICK REFERENCE DATA

		BY260-200			400	600
<b>Input</b>						
R.M.S. voltage	$V_I(\text{RMS})$	max.	140	280	420	V
Repetitive peak voltage	$V_{IRM}$	max.	200	400	600	V
Non-repetitive peak current	$I_{ISM}$	max.		125		A
Peak inrush current	$I_{IIM}$	max.		250		A
<b>Output</b>						
Average current	$I_O(\text{AV})$	max.		12		A

MECHANICAL DATA

Dimensions in mm

Fig. 1.



D 8453

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC134).

Input		BY260-200	400	600	
Non-repetitive peak voltage ( $t \leq 10$ ms)	$V_{ISM}$	max. 200	400	600	V
Repetitive peak voltage	$V_{IRM}$	max. 200	400	600	V
Crest working voltage	$V_{IWM}$	max. 200	400	600	V
R.M.S. voltage (sine-wave)	$V_{I(RMS)}$	max. 140	280	420	V
Non-repetitive peak current half-sinewave; $t = 20$ ms; with reapplied $V_{IWMmax}$					
$T_j = 25$ °C prior to surge	$I_{ISM}$	max.	125		A
$T_j = 150$ °C prior to surge	$I_{ISM}$	max.	100		A
Peak inrush current (see Fig. 5)	$I_{IIM}$	max.	250		A
<b>Output</b>					
Average current (averaged over any 20 ms period)					
heatsink operation up to $T_{mb} = 60$ °C (R-load)	$I_{O(AV)}$	max.	12		A
heatsink operation up to $T_{mb} = 60$ °C (C-load)	$I_{O(AV)}$	max.	7.5		A
Repetitive peak current	$I_{ORM}$	max.	20		A
<b>Temperatures</b>					
Storage temperature	$T_{stg}$		-55 to +150		°C
Junction temperature	$T_j$	max.	150		°C
<b>THERMAL RESISTANCE</b>					
From junction to mounting base	$R_{th\ j-mb}$	=	4.5		°C/W
<b>CHARACTERISTICS</b>					
Forward voltage (2 diodes in series)					
$I_F = 7$ A; $T_j = 25$ °C	$V_F$	<	2.0		V*
Reverse current (2 diodes in parallel)					
$V_R = V_{IWMmax}$ ; $T_j = 100$ °C	$I_R$	<	150		μA

\*Measured under pulse conditions to avoid excessive dissipation.

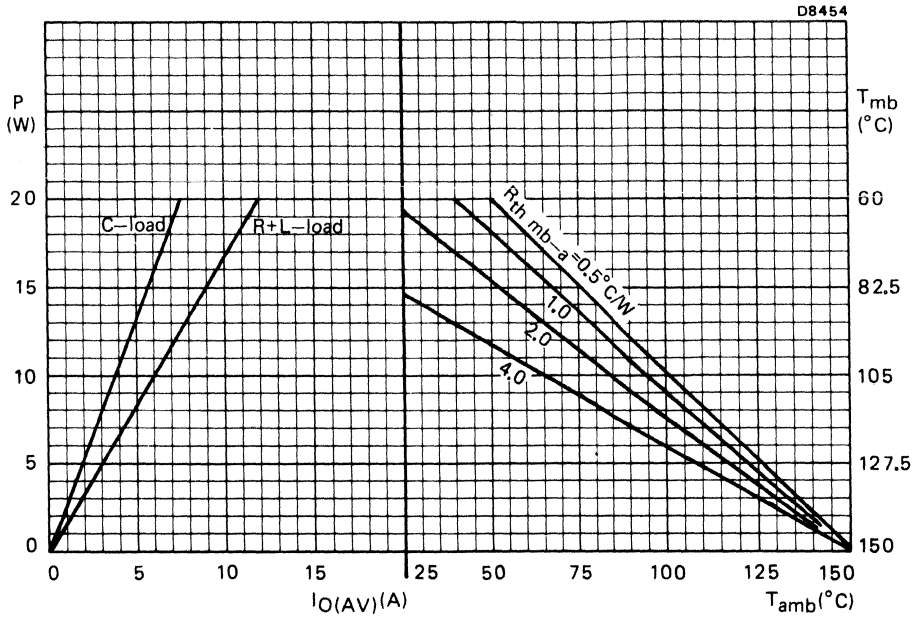


Fig.2 The right-hand part shows the interrelationship between the power (derived from the left-hand graph) and the maximum permissible temperatures.

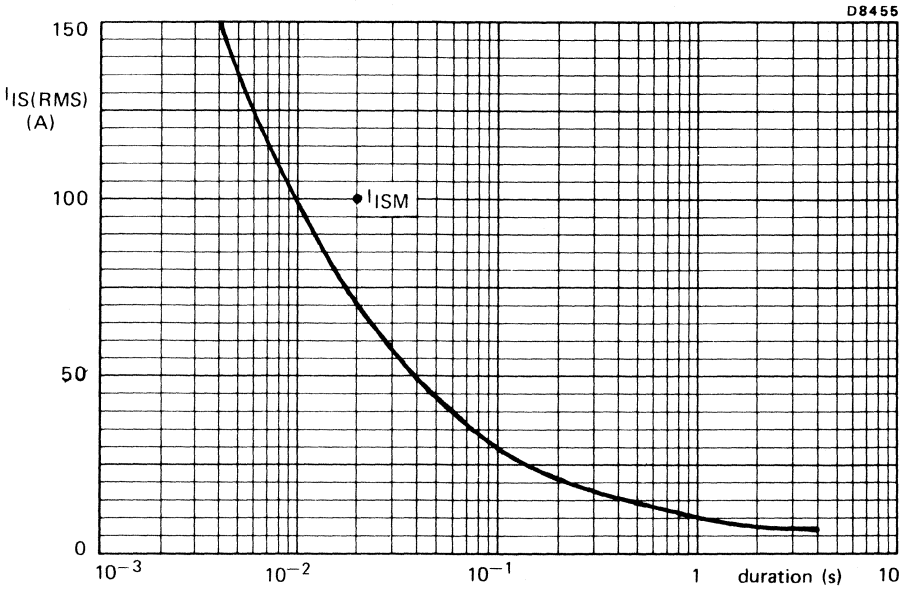


Fig.3 Maximum permissible non-repetitive r.m.s. input current based on sinusoidal currents ( $f = 50$  Hz);  $T_j = 150^\circ\text{C}$  prior to surge, with reapplied  $V_{IWMmax}$ .

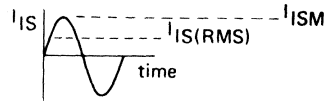
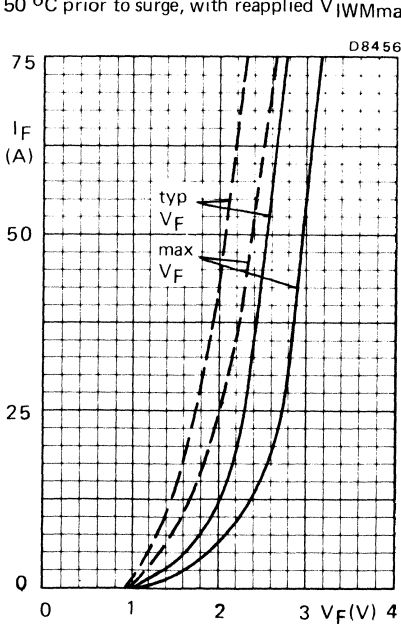
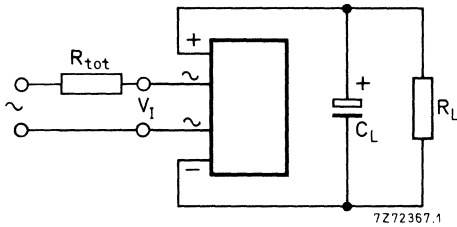
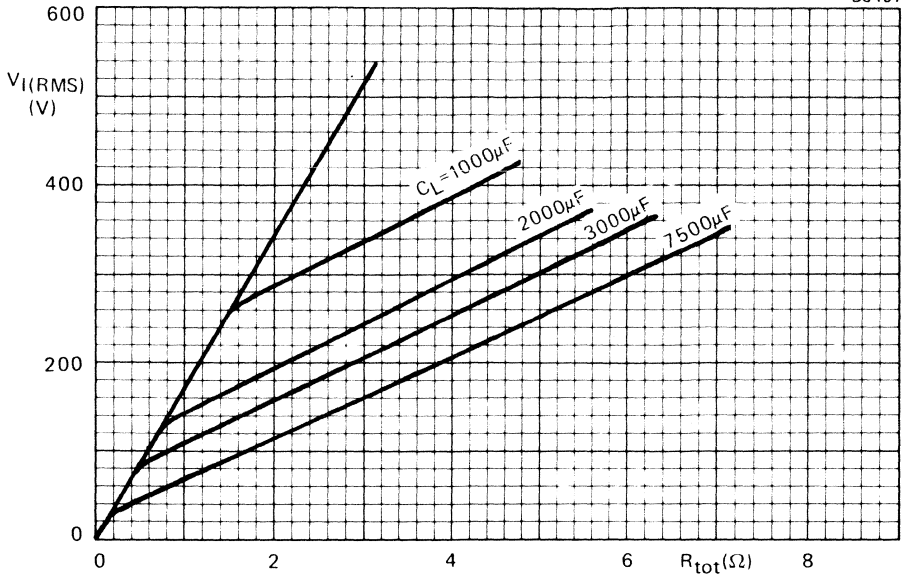


Fig.4 Two diodes in series;  
 —  $T_j = 25^\circ\text{C}$ ; - - -  $T_j = 150^\circ\text{C}$



D8457



The graph takes the possibility of the following spreads into account:

- mains voltage +10%
- capacitance +50%
- resistance -10%

Fig.5 Minimum value of the total series resistance  $R_{tot}$  (including the transformer resistance) required to limit the peak inrush current.



## SILICON BRIDGE RECTIFIERS

Ready for use full-wave bridge rectifiers in a plastic encapsulation.

The bridges are intended for use in equipment supplied from a.c. with r.m.s. voltages up to 420 V and are capable of delivering output currents up to 25A. They may be used in free air or on a heatsink.

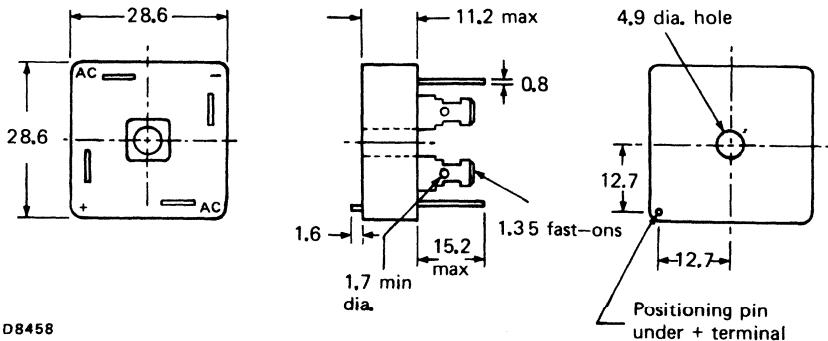
### QUICK REFERENCE DATA

Input		BY261-200	400	600	
R.M.S. voltage	$V_I(\text{RMS})$	max. 140	280	420	V
Repetitive peak voltage	$V_{IRM}$	max. 200	400	600	V
Non-repetitive peak current	$I_{ISM}$	max.	320		A
Peak inrush current	$I_{IIM}$	max.	640		A
Output					
Average current	$I_O(\text{AV})$	max.	25		A

### MECHANICAL DATA

Dimensions in mm

Fig. 1



D8458

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC134).

Input		BY261-200			400	600	
		max.	200	400			
Non-repetitive peak voltage ( $t \leq 10$ ms)	$V_{ISM}$	max.	200	400	600	V	
Repetitive peak voltage	$V_{IRM}$	max.	200	400	600	V	
Crest working voltage	$V_{IWM}$	max.	200	400	600	V	
R.M.S. voltage (sine-wave)	$V_I(RMS)$	max.	140	280	420	V	

Non-repetitive peak current  
half sinewave;  $t = 20$  ms; with reapplied  $V_{IWMmax}$

$T_j = 25$ °C prior to surge	$I_{ISM}$	max.	320	A
$T_j = 150$ °C prior to surge	$I_{ISM}$	max.	250	A
Peak inrush current (see Fig. 5)	$I_{IM}$	max.	640	A

## Output

Average current (averaged over any 20 ms period)  
heatsink operation; up to  $T_{mb} = 55$  °C (R-load)  
heatsink operation; up to  $T_{mb} = 55$  °C (C-load)

heatsink operation; up to $T_{mb} = 55$ °C (R-load)	$I_{O(AV)}$	max.	25	A
heatsink operation; up to $T_{mb} = 55$ °C (C-load)	$I_{O(AV)}$	max.	18	A
Repetitive peak current	$I_{ORM}$	max.	75	A

## Temperatures

Storage temperature	$T_{stg}$	-55 to +175	°C
Junction temperature	$T_j$	max. 175	°C

## THERMAL RESISTANCE

From junction to mounting base	$R_{th\ j-mb}$	=	2.5	°C/W
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## CHARACTERISTICS

Forward voltage (2 diodes in series)

$I_F = 12$ A; $T_j = 25$ °C	$V_F$	<	2.3	V*
-----------------------------	-------	---	-----	----

Reverse current (2 diodes in parallel)

$V_R = V_{IWMmax}$ ; $T_j = 100$ °C	$I_R$	<	200	$\mu$ A
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\*Measured under pulse conditions to avoid excessive dissipation.

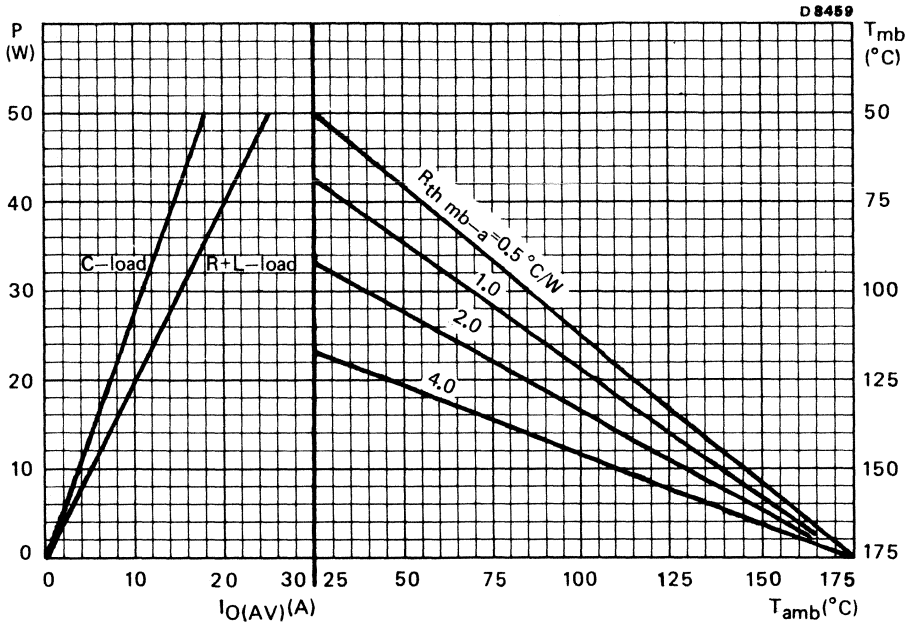


Fig. 2 The right-hand part shows the interrelationship between the power (derived from the left-hand graph) and the maximum permissible temperatures.

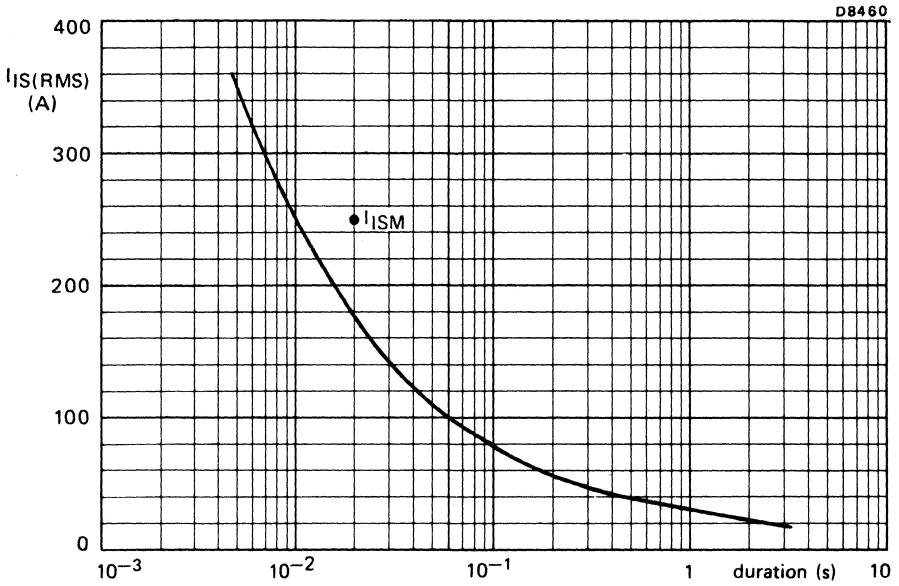


Fig.3 Maximum permissible non-repetitive r.m.s. input current based on sinusoidal currents ( $f = 50$  Hz);  $T_j = 150$  °C prior to surge; with reapplied  $V_{IWMmax}$ .

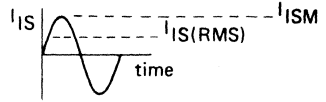
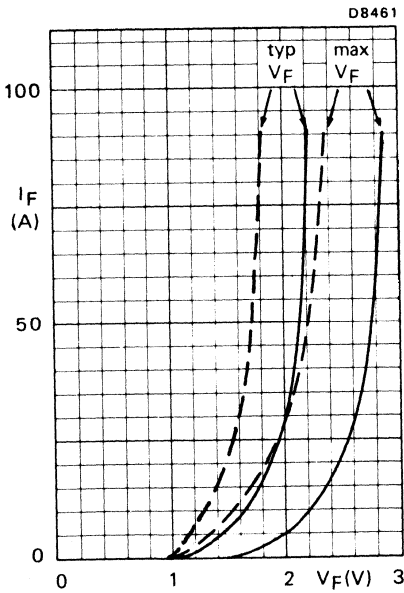
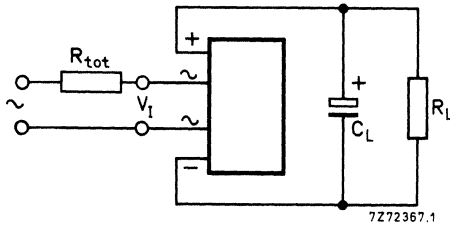
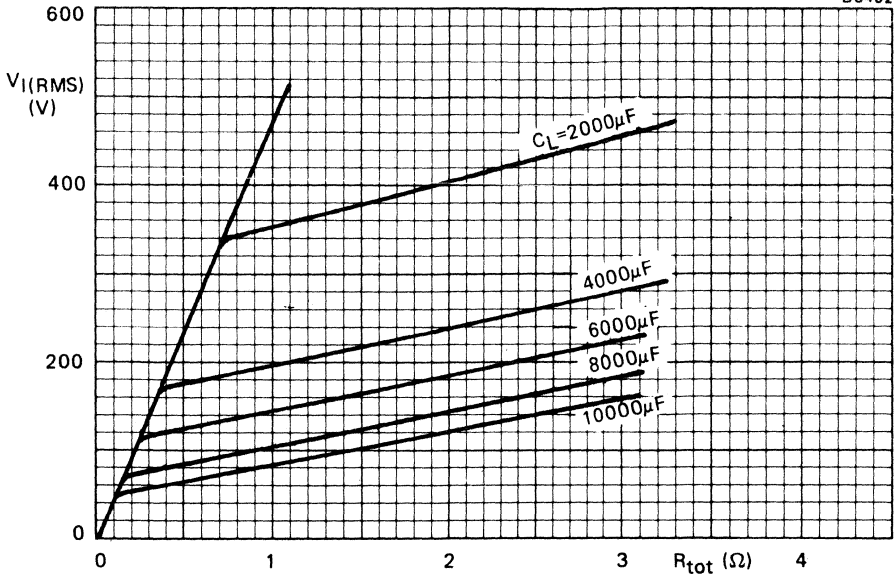


Fig.4 Two diodes in series;  
 —  $T_j = 25$  °C; - - -  $T_j = 150$  °C

D8462



The graph takes the possibility of the following spreads into account:

- input voltage +10%
- capacitance +50%
- resistance -10%

Fig. 5 Minimum value of the total series resistance  $R_{tot}$  (including the transformer resistance) required to limit the peak inrush current.





## PARALLEL EFFICIENCY DIODES

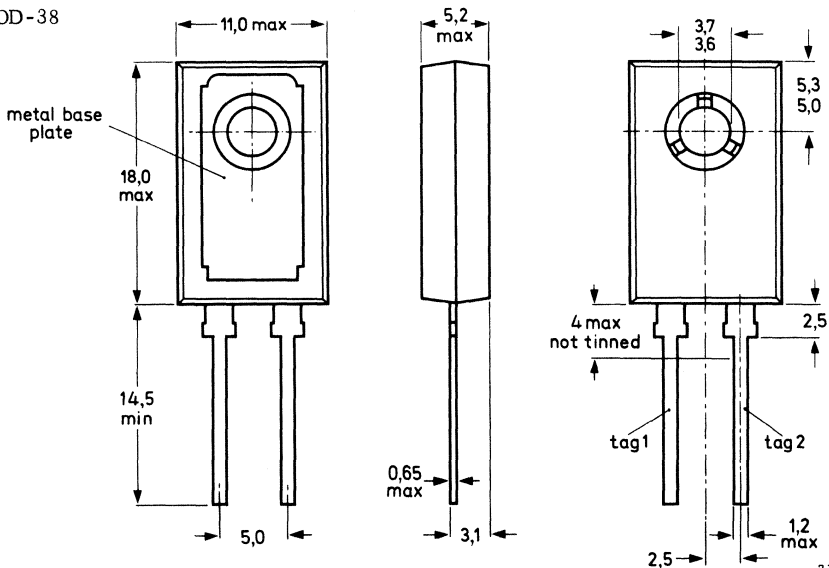
Silicon double-diffused rectifier diodes in plastic envelopes, intended for use as efficiency diode in thyristor horizontal deflection circuits of colour television receivers. The devices feature low forward recovery voltage and non-snap-off characteristics which makes them particularly suitable for this application.

QUICK REFERENCE DATA			
		BY277-600R	750R
Repetitive peak reverse voltage	$V_{RRM}$	max. 600	750 V
Working peak forward current	$I_{FWM}$	max.	10 A
Repetitive peak forward current	$I_{FRM}$	max.	20 A
Reverse recovery time	$t_{rr}$	<	400 ns

**MECHANICAL DATA** (see also page 2)

Dimensions in mm

SOD-38



7260001.5

Polarity of connections: tag 1 = anode, tag 2 = cathode.

The exposed metal base-plate is directly connected to tag 1.

**MECHANICAL DATA** (continued)

Net mass : 2,5 g

Recommended diameter of fixing screw : 3,5 mm

Torque on screw :

when using washer and heatsink compound : min. 0,95 Nm (9,5 kg cm)

max. 1,5 Nm (15 kg cm)

Accessories :

supplied with device : washer

available on request : 56316 (mica insulating washer)

**RATINGS** Limiting values in accordance with the Absolute Maximum System (IEC 134)

Voltages

		BY277-600R	750R	
Non-repetitive peak reverse voltage	$V_{RSM}$	max. 600	800	V
Repetitive peak reverse voltage ( $\delta \leq 0,01$ )	$V_{RRM}$	max. 600	750	V
Working reverse voltage <sup>1)</sup>	$V_{RW}$	max. 500	600	V

Currents

R. M. S. forward current	$I_{F(RMS)}$	max.	3	A
Working peak forward current up to $T_{mb} = 112$ °C	$I_{FWM}$	max.	10	A
Repetitive peak forward current	$I_{FRM}$	max.	20	A
Non-repetitive peak forward current	$I_{FSM}$	max.	50	A

Temperatures

Storage temperature	$T_{stg}$	-40 to +125	°C
Junction temperature	$T_j$	max. 125	°C

<sup>1)</sup> At  $t_p \leq 20$   $\mu$ s;  $\delta = t_p/T \leq 0,25$ ; see page 9.

**THERMAL RESISTANCE**

From junction to mounting base	$R_{th\ j-mb}$	=	4,5	°C/W
Transient thermal impedance ( $t = 1\ ms$ )	$Z_{th\ j-mb}$	=	0,3	°C/W

**Influence of mounting method**

1. Heatsink mounted

From mounting base to heatsink

a. with heatsink compound	$R_{th\ mb-h}$	=	1,5	°C/W
b. with heatsink compound and 56316 mica washer	$R_{th\ mb-h}$	=	2,7	°C/W
c. without heatsink compound	$R_{th\ mb-h}$	=	2,7	°C/W
d. without heatsink compound; with 56316 mica washer	$R_{th\ mb-h}$	=	5	°C/W

2. Free air operation

The quoted values of  $R_{th\ j-a}$  should be used only when no leads of other dissipating components run to the same tie-points.

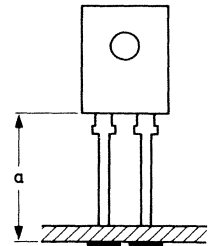
From junction to ambient in free air

mounted on a printed-circuit board

at  $a =$  maximum lead length

and with a copper laminate

a. $> 1\ cm^2$	$R_{th\ j-a} = 50\ °C/W$
b. $< 1\ cm^2$	$R_{th\ j-a} = 55\ °C/W$

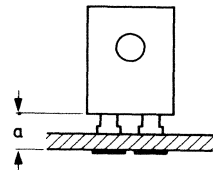


7Z62315.1

at a lead length  $a = 3\ mm$

and with a copper laminate

c. $> 1\ cm^2$	$R_{th\ j-a} = 55\ °C$
d. $< 1\ cm^2$	$R_{th\ j-a} = 60\ °C$



7Z62314

**CHARACTERISTICS**

Forward voltage

$I_F = 10 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$   $V_F < 1,4 \text{ V}^1)$

Reverse current

$V_R = V_{RWmax}; T_j = 100 \text{ }^\circ\text{C}$   $I_R < 0,2 \text{ mA}$

Reverse recovery when switched from

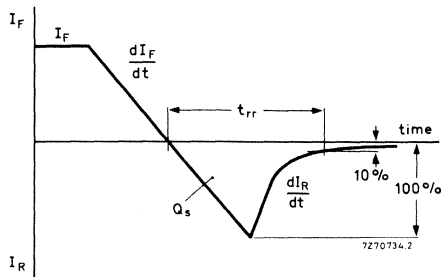
$I_F = 2 \text{ A to } V_R \geq 30 \text{ V};$   
 $-dI_F/dt = 20 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$   
 Recovery charge  $Q_s < 0,9 \text{ } \mu\text{C}$

$I_F = 1 \text{ A to } V_R \geq 30 \text{ V};$   
 $-dI_F/dt = 20 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$   
 Recovery time  $t_{rr} < 400 \text{ ns}$

Maximum slope of the reverse recovery current

(in horizontal deflection circuits)  
 when switched from

$I_F = 5 \text{ A to } V_R \geq 30 \text{ V};$  with  
 $-dI_F/dt = 1 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$   $|dI_R/dt| < 2 \text{ A}/\mu\text{s}$



<sup>1)</sup> Measured under pulse conditions to avoid excessive dissipation.

**CHARACTERISTICS** (continued)

Forward recovery when switched to

$I_F = 1 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

Recovery time

$t_{fr} < 0,3 \text{ } \mu\text{s}$

Recovery voltage

$V_{fr} < 13 \text{ V}$

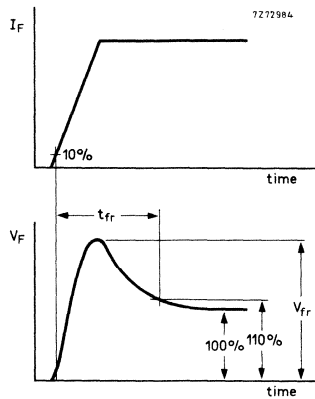
$I_F = 20 \text{ mA}; T_j = 25 \text{ }^\circ\text{C}$

Recovery time

$t_{fr} < 0,3 \text{ } \mu\text{s}$

Recovery voltage

$V_{fr} < 5 \text{ V}$



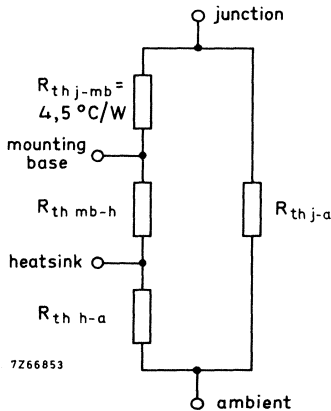
**MOUNTING INSTRUCTIONS**

1. Soldered joints must be at least 2,5 mm from the seal.
2. The maximum permissible temperature of the soldering iron or bath is 270 °C; contact with the joint must not exceed 3 seconds.
3. The devices should not be immersed in oil, and few potting resins are suitable for re-encapsulation. Advice on these materials is available on request.
4. Leads should not be bent less than 2,5 mm from the seal. Exert no axial pull when bending.
5. For good thermal contact heatsink compound should be used between base-plate and heatsink.

**OPERATING NOTES**

Dissipation and heatsink considerations :

- a. The various components of junction temperature rise above ambient are illustrated below :

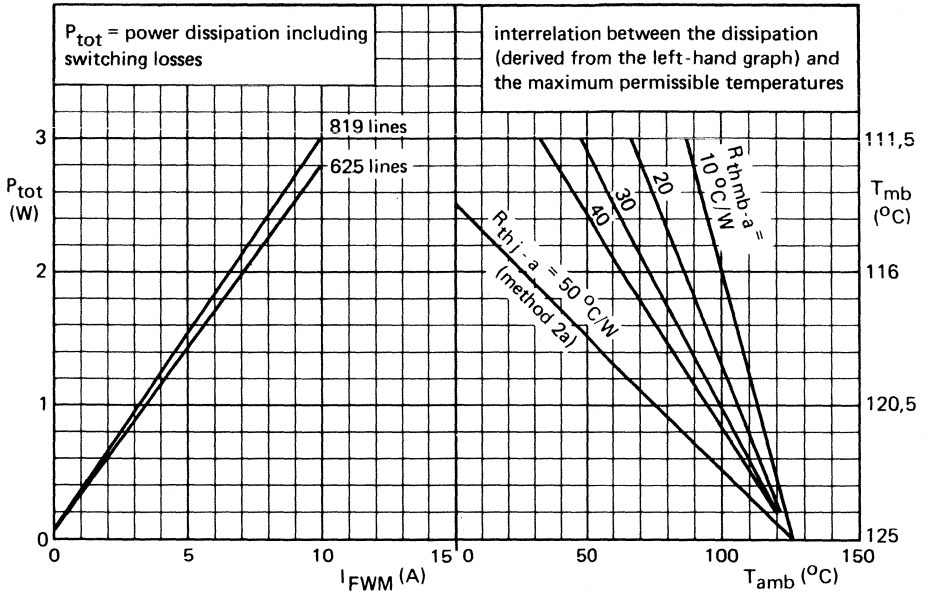


- b. The method of using the graph on page 7 is as follows :  
Starting with the required current on the  $I_{FWM}$  axis, trace upwards to meet the appropriate 625/819-curve. Trace right horizontally and upwards from the appropriate value on the  $T_{amb}$  scale. The intersection determines the  $R_{th\ mb-a}$ .  
The heatsink thermal resistance value ( $R_{th\ h-a}$ ) can now be calculated from :

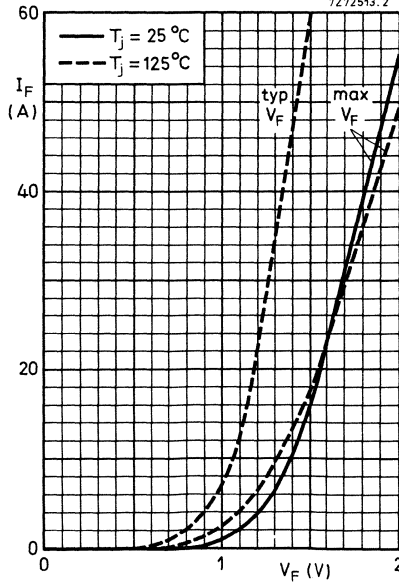
$$R_{th\ h-a} = R_{th\ mb-a} - R_{th\ mb-h}.$$

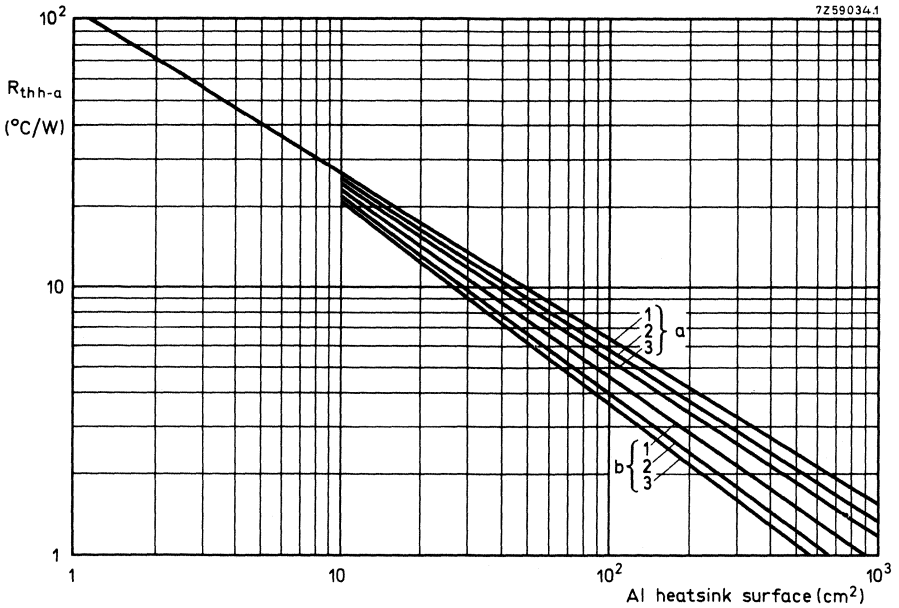
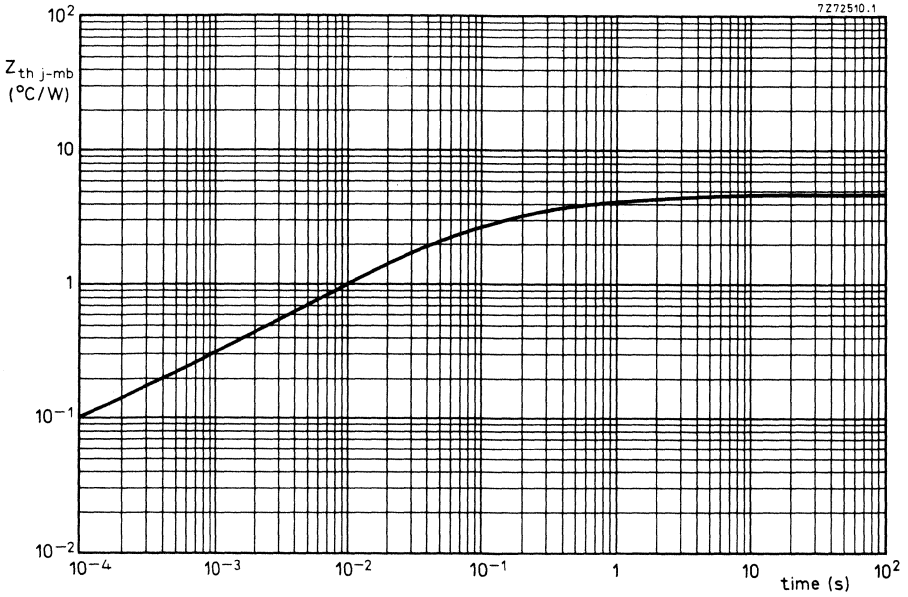
Any measurement of heatsink temperature should be made immediately adjacent to the device.

7Z72514.2



7Z72514.2

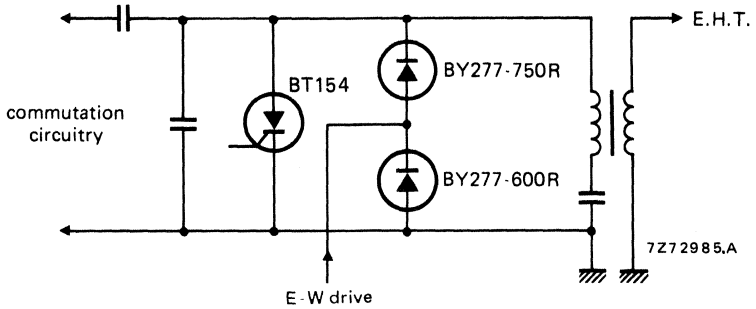
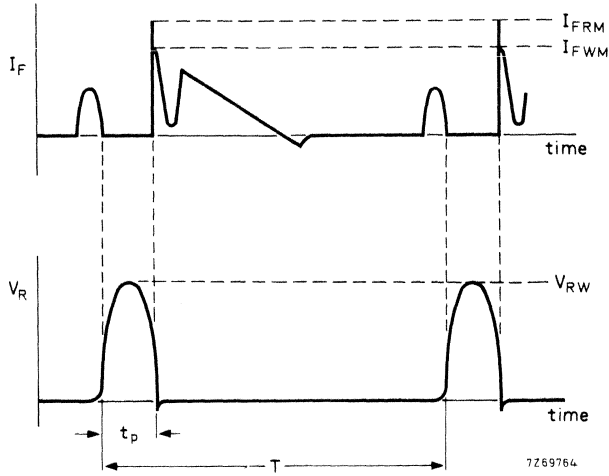




Thermal resistance  $R_{th\ h-a}$  from aluminium heatsink to ambient (free air) versus heat-sink surface (one side). 1, 2 and 3 are thicknesses in mm, a is for a bright surface, b is for a black surface.



APPLICATION INFORMATION



Basic circuit and waveforms



## SCHOTTKY-BARRIER RECTIFIER DIODES

High-efficiency rectifier diodes in DO-4 metal envelopes, featuring low forward voltage drop, low capacitance, absence of stored charge and high temperature stability. They are intended for use in low output voltage switched-mode power supplies and high-frequency circuits in general, where low conduction and switching losses are important.

The series consists of normal polarity (cathode to stud) types: BYV21-30, BYV21-35, BYV21-40 and BYV21-45.

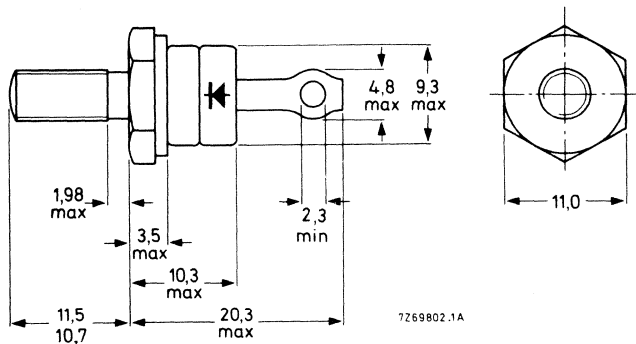
### QUICK REFERENCE DATA

		BYV21-30				35	40	45		
Repetitive peak reverse voltage	$V_{RRM}$	max.	30	35	40	45			V	
Average forward current	$I_F(AV)$	max.				28			A	
Forward voltage	$V_F$	<				0.55			V	

### MECHANICAL DATA

Dimensions in mm

Fig.1 DO-4 with 10-32 UNF stud ( $\phi 4.83$  mm) as standard.  
Metric M5 stud ( $\phi 5$  mm) is available on request.



Net mass: 7 g

Diameter of clearance hole: 5.2 mm

Accessories supplied on request: 56295  
(PTFE bush, 2 mica washers, plain washer, tag).

Supplied with device: 1 nut, 1 lock washer.

Nut dimensions across the flats: M5, 8.0 mm  
10-32 UNF, 9.5 mm

Torque on nut:  
min. 0.9 (9 kg cm),  
max. 1.7 (17 kg cm).

# BYV21 SERIES

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC134).

### Voltages

			BYV21-30	35	40	45	
Non-repetitive peak reverse voltage	$V_{RSM}$	max.	36	42	48	54	V
Repetitive peak reverse voltage*	$V_{RRM}$	max.	30	35	40	45	V
Crest working reverse voltage	$V_{RWM}$	max.	30	35	40	45	V
Continuous reverse voltage**	$V_R$	max.	30	35	40	45	V

### Currents

Average forward current; switching losses negligible

sinusoidal; up to  $T_{mb} = 100\text{ }^\circ\text{C}$

$I_F(AV)$  max. 25 A

square-wave; up to  $T_{mb} = 100\text{ }^\circ\text{C}$ ;  $\delta = 0.5$

$I_F(AV)$  max. 28 A

R.M.S. forward current

$I_F(RMS)$  max. 40 A

Non-repetitive peak forward current

$t = 10\text{ ms}$ ; half sine-wave;

$T_j = 125\text{ }^\circ\text{C}$  prior to surge;

with reapplied  $V_{RWMmax}$

$I_{FSM}$  max. 600 A

$I^2 t$  for fusing

$I^2 t$  max. 1800  $A^2 s$

### Temperatures

Storage temperature

$T_{stg}$  -55 to +150  $^\circ\text{C}$

Junction temperature; with full applied continuous reverse voltage  $V_{Rmax}$

$T_j$  max. 125  $^\circ\text{C}$

### THERMAL RESISTANCE

From junction to mounting base

$R_{th\ j-mb}$  < 1  $^\circ\text{C/W}$

From mounting base to heatsink

with heatsink compound

$R_{th\ mb-h}$  = 0.3  $^\circ\text{C/W}$

without heatsink compound

$R_{th\ mb-h}$  = 0.5  $^\circ\text{C/W}$

Transient thermal impedance;  $t = 1\text{ ms}$

$Z_{th\ j-mb}$  = 0.15  $^\circ\text{C/W}$

### MOUNTING INSTRUCTIONS

The top connector should be neither bent nor twisted; it should be soldered into the circuit so that there is no strain on it.

During soldering the heat conduction to the junction should be kept to a minimum.

\* For  $t_p = 200\text{ ns}$  a 20% increase in  $V_{RRM}$  is allowed.

\*\* To ensure thermal stability:  $R_{th\ j-a} < 2\text{ }^\circ\text{C/W}$

## CHARACTERISTICS

## Forward voltage

$$I_F = 30 \text{ A}; T_j = 100 \text{ }^\circ\text{C}$$

$$V_F < 0.55 \text{ V}^*$$

$$I_F = 80 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$$

$$V_F < 0.88 \text{ V}^*$$

## Rate of rise of reverse voltage

$$V_R = V_{RWMmax}$$

$$\frac{dV_R}{dt} < 1500 \text{ V}/\mu\text{s}$$

## Reverse current

$$V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$$

$$I_R < 150 \text{ mA}$$

Capacitance at  $f = 1 \text{ MHz}$ 

$$V_R = 5 \text{ V}; T_j = 25 \text{ to } 125 \text{ }^\circ\text{C}$$

$$C_d \text{ typ. } 900 \text{ pF}$$

\*Measured under pulse conditions to avoid excessive dissipation.

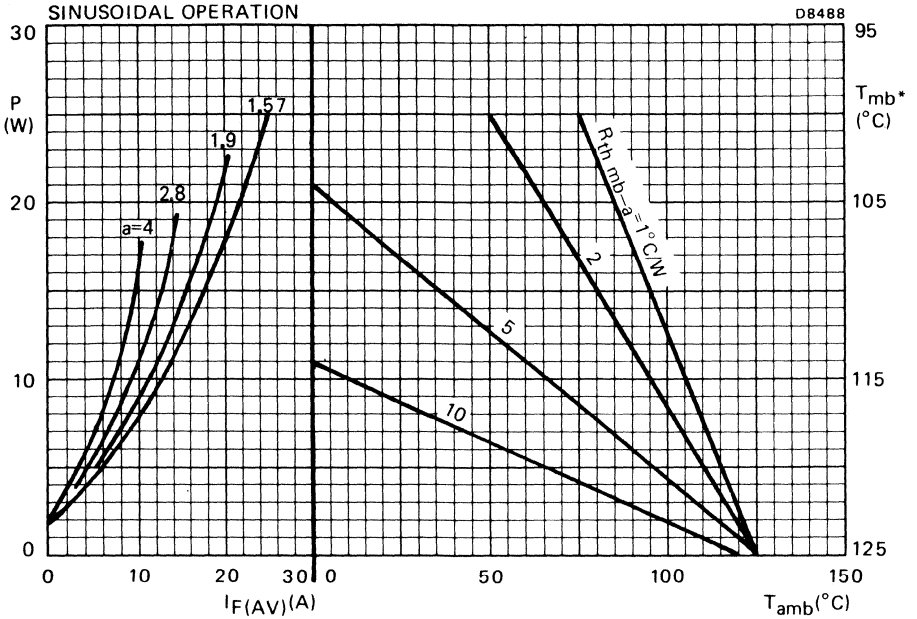


Fig.2 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

$a$  = form factor =  $I_F(RMS)/I_F(AV)$ .

\* $T_{mb}$  scale is for comparison purpose and is correct only for  $R_{th\ mb-a} < 6.4$   $^{\circ}C/W$ .

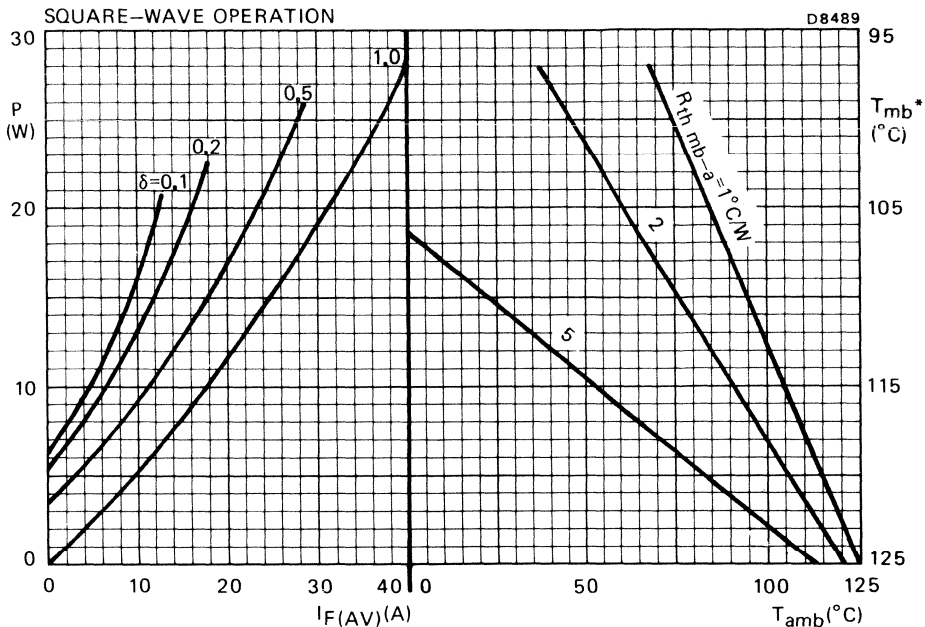
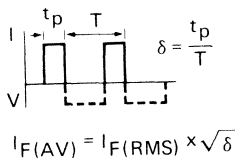


Fig.3 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.



\* $T_{mb}$  scale is for comparison purpose and is correct only for  $R_{th\ mb-a} < 6.4^\circ C/W$ .

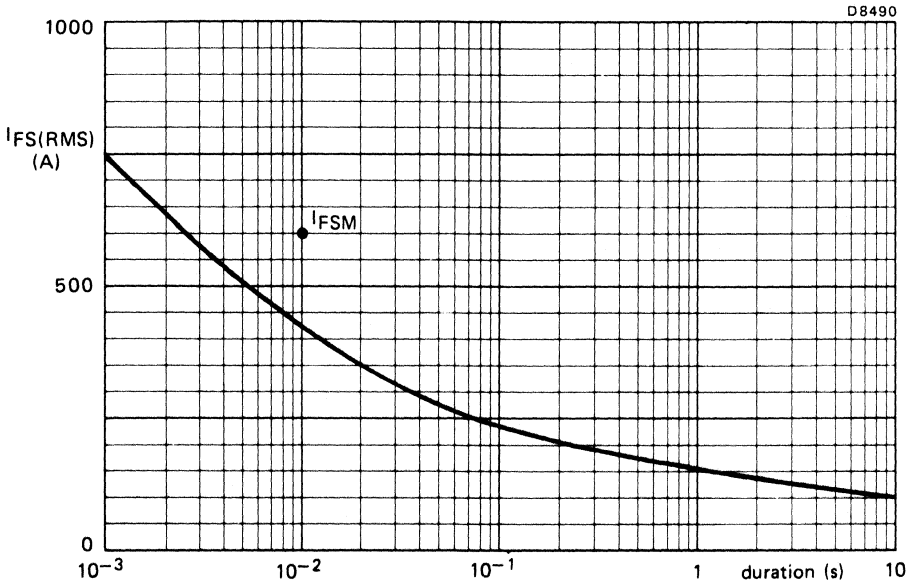


Fig.4 Maximum permissible non-repetitive r.m.s. forward current based on sinusoidal currents ( $f = 50$  Hz);  $T_j = 125$  °C prior to surge; with reapplied  $V_{RWMmax}$ .

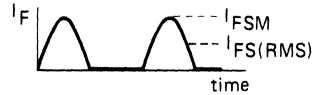
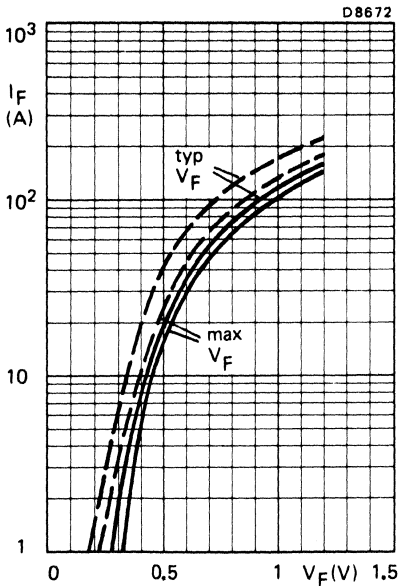


Fig. 5 ———  $T_j = 25$  °C; - - -  $T_j = 100$  °C.



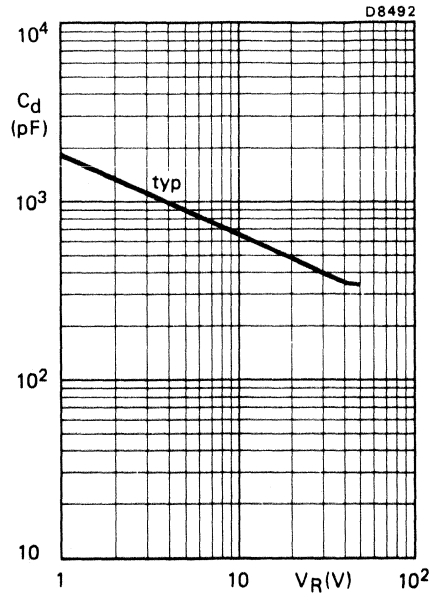


Fig.6  $f = 1$  MHz;  $T_j = 25$  to  $125$  °C

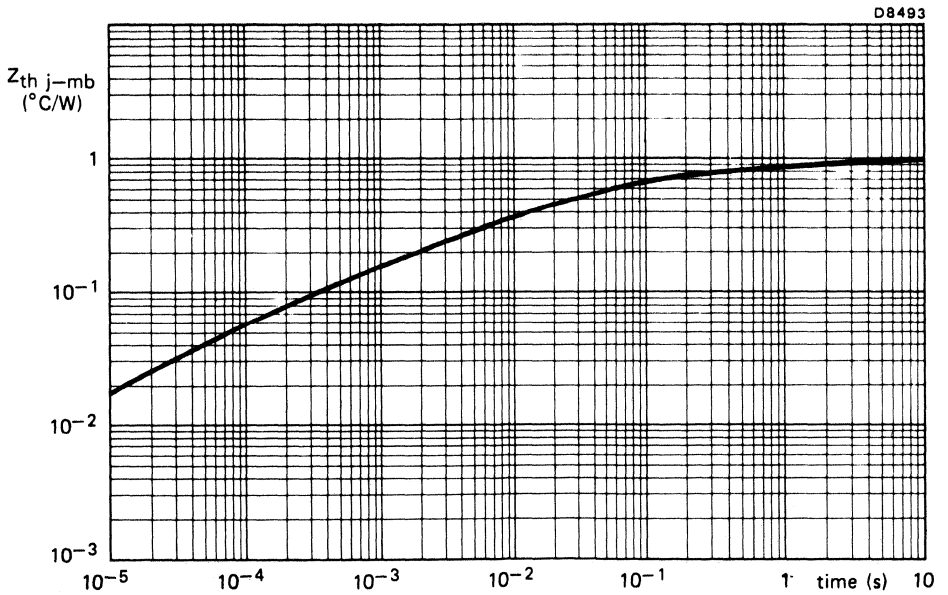


Fig.7



## VERY FAST SOFT-RECOVERY RECTIFIER DIODES

High-efficiency rectifier diodes in DO-4 metal envelopes, featuring low forward voltage drop, high reverse voltage capability, very fast reverse recovery times and non-snap-off characteristics. They are intended for use in switched-mode power supplies and high-frequency inverter circuits, in general, where high output voltages and low conduction and switching losses are essential.

The series consists of the following types:

Normal polarity (cathode to stud): BYV30-200, BYV30-300 and BYV30-400.

Reverse polarity (anode to stud): BYV30-200R, BYV30-300R, and BYV30-400R.

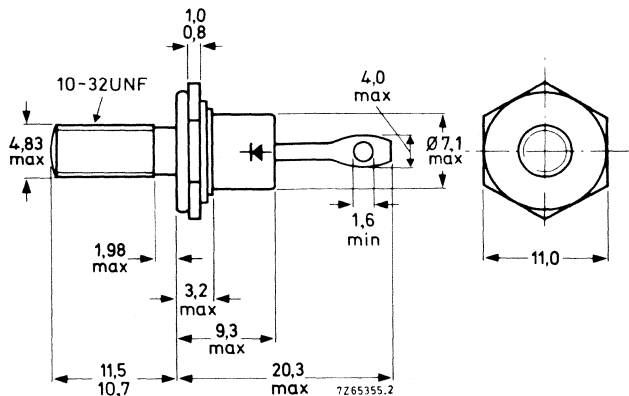
### QUICK REFERENCE DATA

		BYV30-200(R)	300(R)	400(R)	
Repetitive peak reverse voltage	$V_{RRM}$	max. 200	300	400	V
Average forward current	$I_{F(AV)}$	max.	12		A
Forward voltage	$V_F$	<	1.05		V
Reverse recovery time	$t_{rr}$	<	100		ns

### MECHANICAL DATA

Dimensions in mm

Fig.1 DO-4



Net mass: 6 g

Diameter of clearance hole: max. 5.2 mm

Accessories supplied on request:

56295 (PTFE bush, 2 mica washers, plain washer, tag).

Supplied with device: 1 nut, 1 lock washer.

Nut dimensions across the flats: 9.5 mm

The mark shown applies to the normal polarity types.

Torque on nut:

min. 0.9 Nm (9 kg cm),

max. 1.7 Nm (17 kg cm)

# BYV30 SERIES

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC134)

### Voltages

		BYV30-200(R)	300(R)	400(R)	
Non-repetitive peak reverse voltage ( $t \leq 10$ ms)	$V_{RSM}$	max. 250	350	450	V
Repetitive peak reverse voltage	$V_{RRM}$	max. 200	300	400	V
Crest working reverse voltage	$V_{RWM}$	max. 200	300	400	V

### Currents

Average forward current assuming zero switching losses (averaged over any 20 ms period)

up to  $T_{mb} = 100$  °C

at  $T_{mb} = 125$  °C

$I_{F(AV)}$	max.	12	A
$I_{F(AV)}$	max.	7	A

R.M.S. forward current

$I_{F(RMS)}$	max.	20	A
--------------	------	----	---

Repetitive peak forward current

$I_{FRM}$	max.	140	A
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Non-repetitive peak forward current

$T_j = 150$  °C prior to surge;

half sine-wave with reapplied  $V_{RWMmax}$ ;

$t = 10$  ms

$t = 8.3$  ms

$I_{FSM}$	max.	140	A
$I_{FSM}$	max.	150	A

$I^2 t$  for fusing ( $t = 10$  ms)

$I^2 t$	max.	100	A <sup>2</sup> s
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### Temperatures

Storage temperature

$T_{stg}$		-65 to +175	°C
-----------	--	-------------	----

Operating junction temperature

$T_j$	max.	150	°C
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### THERMAL RESISTANCE

From junction to ambient in free air

$R_{th j-a}$	=	50	°C/W
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From junction to mounting base

$R_{th j-mb}$	=	2.2	°C/W
---------------	---	-----	------

From mounting base to heatsink

$R_{th mb-h}$	=	0.5	°C/W
---------------	---	-----	------

Transient thermal impedance;  $t = 1$  ms

$Z_{th j-mb}$	=	0.8	°C/W
---------------	---	-----	------

CHARACTERISTICS

Forward voltage

$I_F = 10 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_F < 1.35 \text{ V}^*$

$I_F = 10 \text{ A}; T_j = 150 \text{ }^\circ\text{C}$

$V_F < 1.05 \text{ V}^*$

Reverse current

$V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$

$I_R < 3 \text{ mA}$

Reverse recovery when switched from

$I_F = 1 \text{ A to } V_R = 30 \text{ V};$

$-dI_F/dt = 35 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

Recovery time

$t_{rr} < 100 \text{ ns}$

$I_F = 2 \text{ A to } V_R = 30 \text{ V};$

$-dI_F/dt = 20 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

Recovery charge

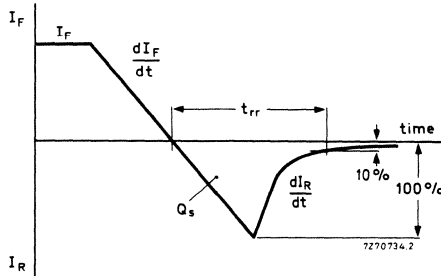
$Q_s < 125 \text{ nC}$

$I_F = 1 \text{ A to } V_R = 30 \text{ V};$

$-dI_F/dt = 2 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

Max. slope of the reverse recovery current

$|dI_R/dt| < 5 \text{ A}/\mu\text{s}$



D8403

Fig. 2 Definition of  $t_{rr}$  and  $Q_s$ .

\*Measured under pulse conditions to avoid excessive dissipation.

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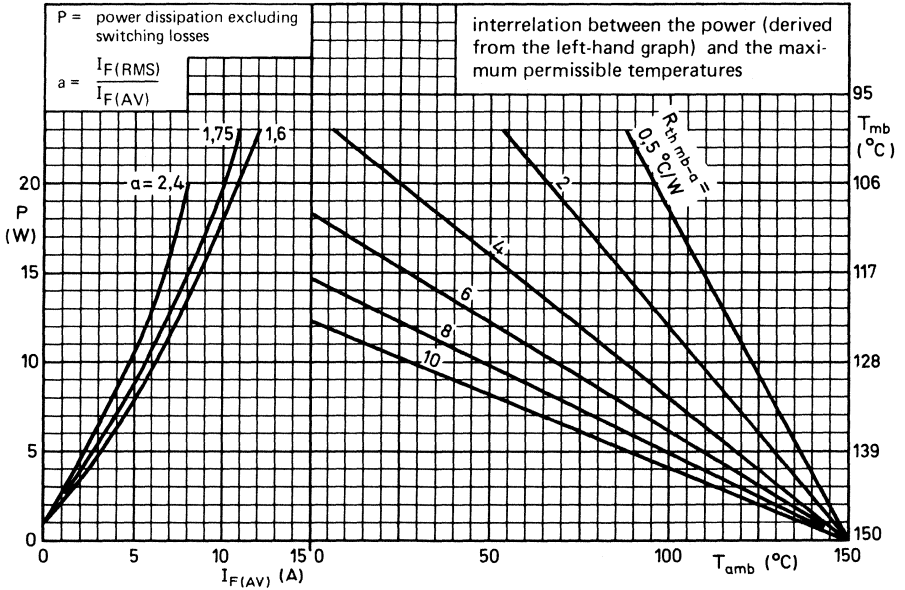


Fig. 3

7272611.1

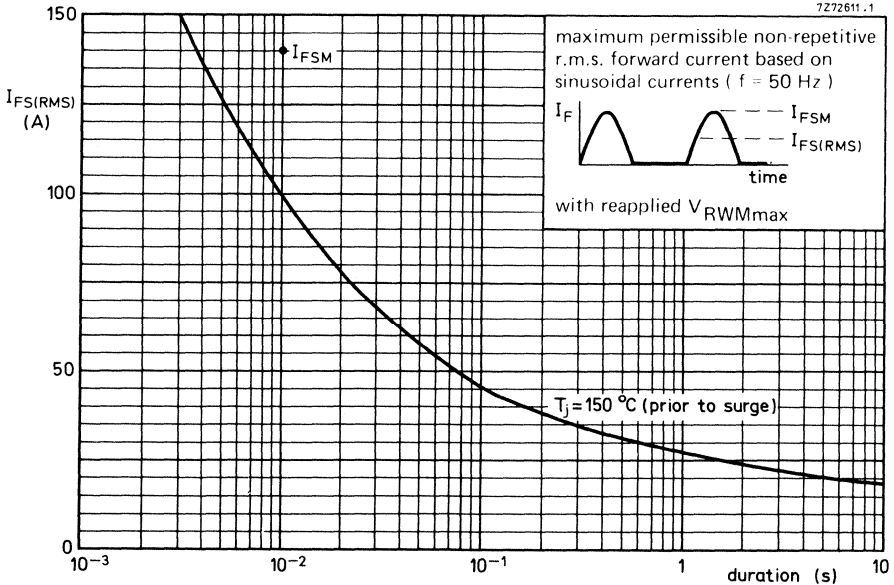


Fig. 4

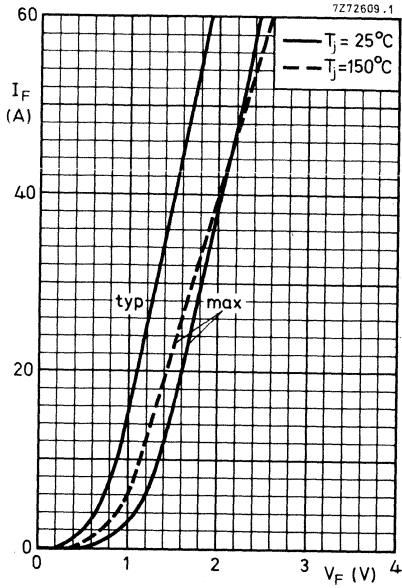


Fig. 5

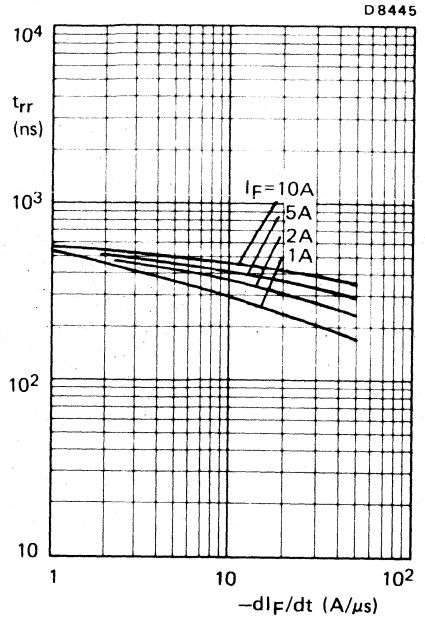


Fig. 6 Maximum values;  $T_j = 150\text{ }^\circ\text{C}$ .

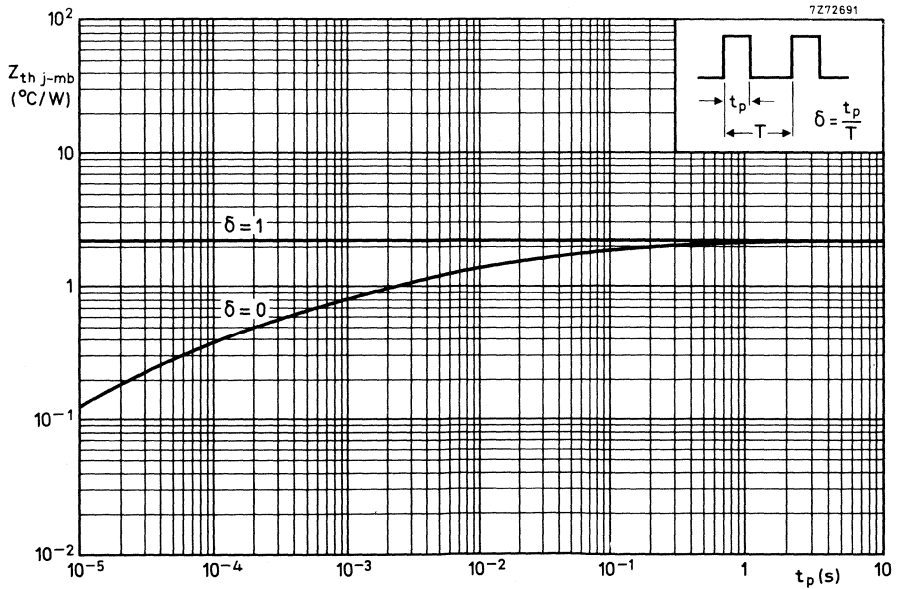


Fig. 7





VERY FAST SOFT-RECOVERY DIODES

High-efficiency rectifier diodes in DO-5 metal envelopes, featuring low forward voltage drop, high reverse voltage capability, very fast reverse recovery times and non-snap-off characteristics. They are intended for use in switched-mode power supplies and high-frequency inverter circuits, in general, where high output voltages and low conduction and switching losses are essential. The series consists of the following types:  
 Normal polarity (cathode to stud): BYV92-200, BYV92-300 and BYV92-400.  
 Reverse polarity (anode to stud): BYV92-200R, BYV92-300R and BYV92-400R.



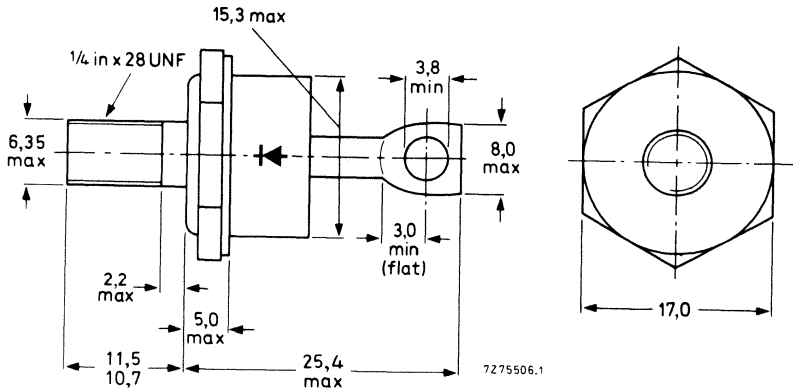
QUICK REFERENCE DATA

			BYV92-200(R)	300(R)	400(R)	
Repetitive peak reverse voltage	$V_{RRM}$	max.	200	300	400	V
Average forward current	$I_{F(AV)}$	max.	35			A
Forward voltage	$V_F$	<	1.05			V
Reverse recovery time	$t_{rr}$	<	100			ns

MECHANICAL DATA

Dimensions in mm

Fig.1 DO-5; Supplied with device: 1 nut, 1 lock-washer  
 Nut dimensions across the flats: 11.1 mm



Net mass: 22 g  
 Diameter of clearance hole: max. 6.5 mm  
 Accessories supplied on request:  
 56264A (mica washer, insulating ring, tag)

Torque on nut:  
 min. 1.7 Nm (17 kg cm)  
 max. 2.5 Nm (25 kg cm)

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

### Voltages\*

			BYV92-200(R)	300(R)	400(R)	
Non-repetitive peak reverse voltage	$V_{RSM}$	max.	200	300	400	V
Repetitive peak reverse voltage	$V_{RRM}$	max.	200	300	400	V
Crest working reverse voltage	$V_{RWM}$	max.	200	300	400	V
Continuous reverse voltage	$V_R$	max.	200	300	400	V

### Currents

Average forward current assuming zero switching losses;

sinusoidal; up to $T_{mb} = 100\text{ }^\circ\text{C}$	$I_F(AV)$	max.	35	A
sinusoidal; at $T_{mb} = 125\text{ }^\circ\text{C}$	$I_F(AV)$	max.	20	A
square wave; $\delta = 0.5$ ; up to $T_{mb} = 95\text{ }^\circ\text{C}$	$I_F(AV)$	max.	40	A
square wave; $\delta = 0.5$ ; at $T_{mb} = 125\text{ }^\circ\text{C}$	$I_F(AV)$	max.	19	A
R.M.S. forward current	$I_F(RMS)$	max.	55	A
Repetitive peak forward current	$I_{FRM}$	max.	500	A
Non-repetitive peak forward current				
$t = 10\text{ ms}$ ; half sine-wave;				
$T_j = 150\text{ }^\circ\text{C}$ prior to surge; with re-applied				
$V_{RWMmax}$	$I_{FSM}$	max.	500	A
$I^2 t$ for fusing ( $t = 10\text{ ms}$ )	$I^2 t$	max.	1250	$A^2 s$

### Temperatures

Storage temperatures	$T_{stg}$	-55 to +150	$^\circ\text{C}$
Junction temperature	$T_j$	max. 150	$^\circ\text{C}$

### THERMAL RESISTANCE

From junction to mounting base	$R_{th\ j-mb}$	=	1.0	$^\circ\text{C/W}$
From mounting base to heatsink				
with heatsink compound	$R_{th\ mb-h}$	=	0.3	$^\circ\text{C/W}$
without heatsink compound	$R_{th\ mb-h}$	=	0.5	$^\circ\text{C/W}$
Transient thermal impedance; $t = 1\text{ ms}$	$Z_{th\ j-mb}$	=	0.2	$^\circ\text{C/W}$

### MOUNTING INSTRUCTIONS

The top connector should neither be bent nor twisted; it should be soldered into the circuit so that there is no strain on it.

During soldering the heat conduction to the junction should be kept to a minimum.

\*To ensure thermal stability:  $R_{th\ j-a} \leq 6\text{ }^\circ\text{C/W}$  (continuous reverse voltage) up to  $T_{amb} = 110\text{ }^\circ\text{C}$

CHARACTERISTICS

Forward voltage

$I_F = 100 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_F < 1.4 \text{ V}^*$

$I_F = 35 \text{ A}; T_j = 100 \text{ }^\circ\text{C}$

$V_F < 1.05 \text{ V}^*$

Reverse current

$V_R = V_{RWMmax}; T_j = 100 \text{ }^\circ\text{C}$

$I_R < 1.5 \text{ mA}$

Reverse recovery when switched from

$I_F = 1 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 50 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

Recovery time

$t_{rr} < 100 \text{ ns}$

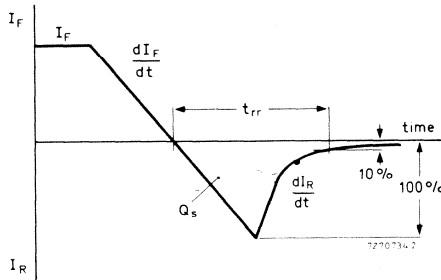
$I_F = 2 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 20 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

Recovered charge

$Q_s < 100 \text{ nC}$

Maximum slope of the reverse recovery current when switched from  $I_F = 1 \text{ A to } V_R \geq 30 \text{ V};$  with  $-dI_F/dt = 2 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

$|dI_R/dt| < 5 \text{ A}/\mu\text{s}$



D8403

Fig. 2 Definitions of  $t_{rr}$  and  $Q_s$ .

\*Measured under pulse conditions to avoid excessive dissipation.

SQUARE-WAVE OPERATION

D8420

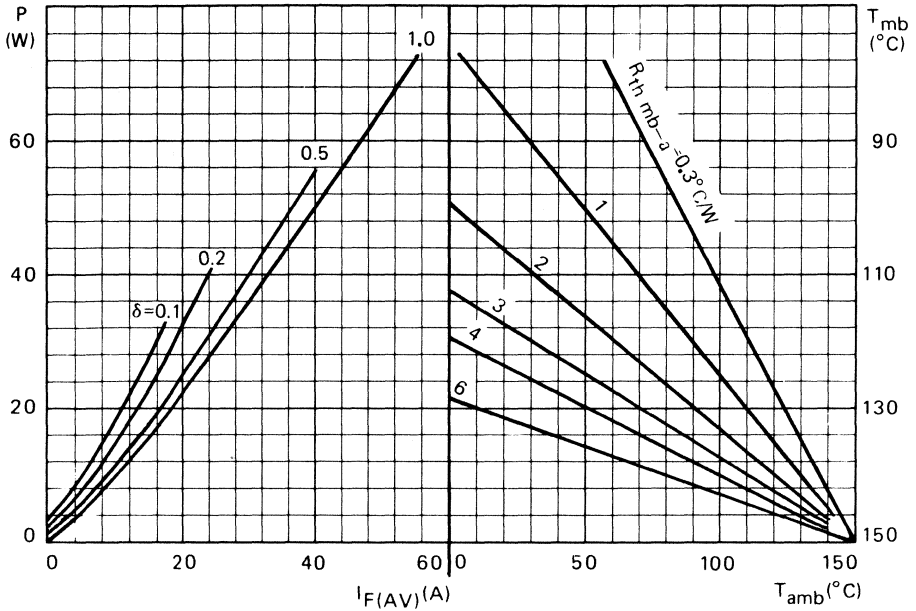
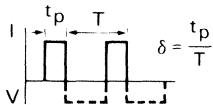


Fig.3 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

P = power including reverse current losses but excluding switching losses.



$$I_{F(AV)} = I_{F(RMS)} \times \sqrt{\delta}$$

SINUSOIDAL OPERATION

D8419

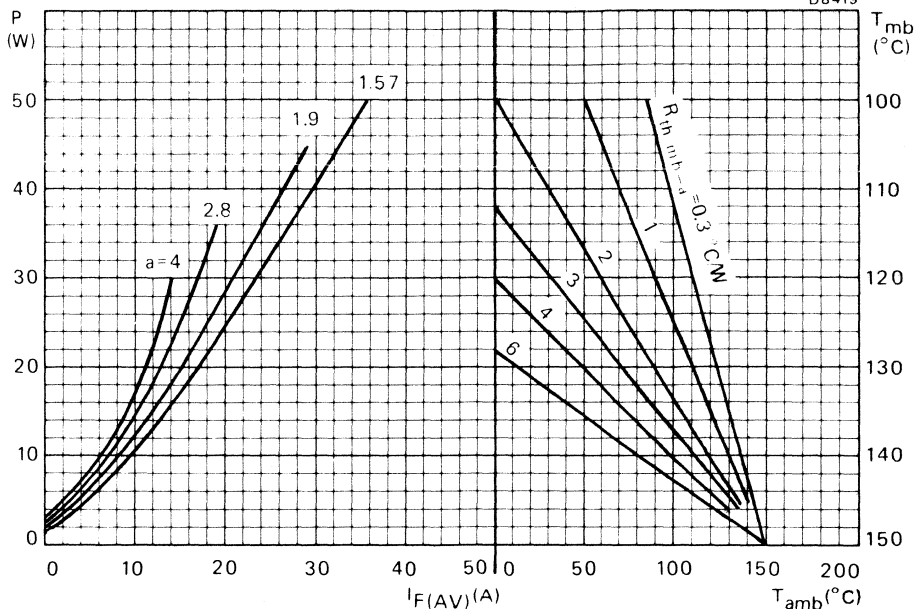


Fig.4 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

$P$  = power including reverse current losses but excluding switching losses.

$a$  = form factor =  $I_{F(RMS)}/I_{F(AV)}$ .

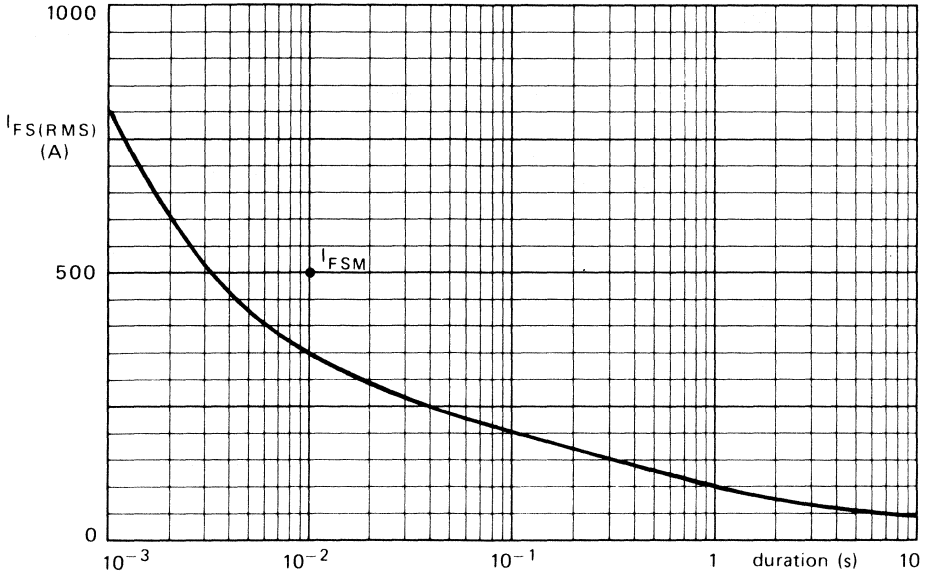


Fig.5 Maximum permissible non-repetitive r.m.s. forward current based on sinusoidal currents ( $f = 50$  Hz);  $T_j = 150$  °C prior to surge; with reapplied  $V_{RWMmax}$ .



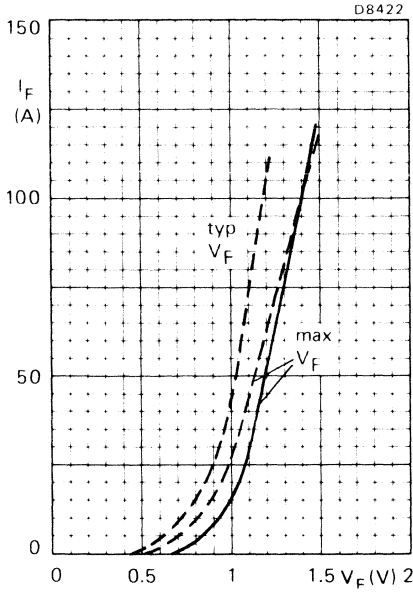


Fig. 6 —  $T_j = 25\text{ }^\circ\text{C}$ ; - - -  $T_j = 100\text{ }^\circ\text{C}$

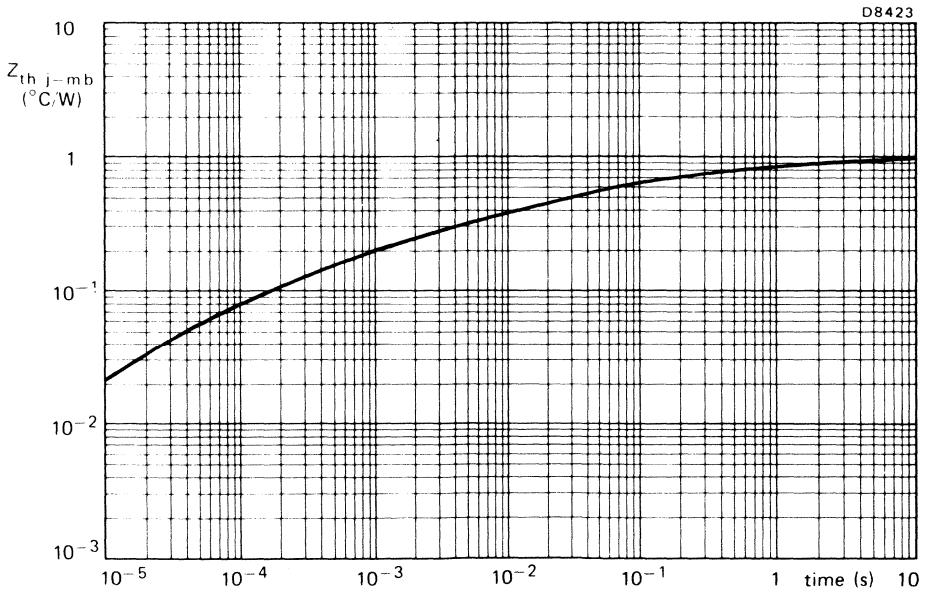


Fig. 7





## FAST SOFT-RECOVERY RECTIFIER DIODES

Silicon double-diffused rectifier diodes in plastic envelopes. They are intended for use as clamp diode, dV/dt limiter and output rectifier diodes in professional and consumer switched-mode power supply applications and as scan rectifier diodes in television receivers. The devices feature non-snap-off characteristics and a very fast turn-on behaviour, which makes them extremely suitable for clamp and dV/dt limiting applications.

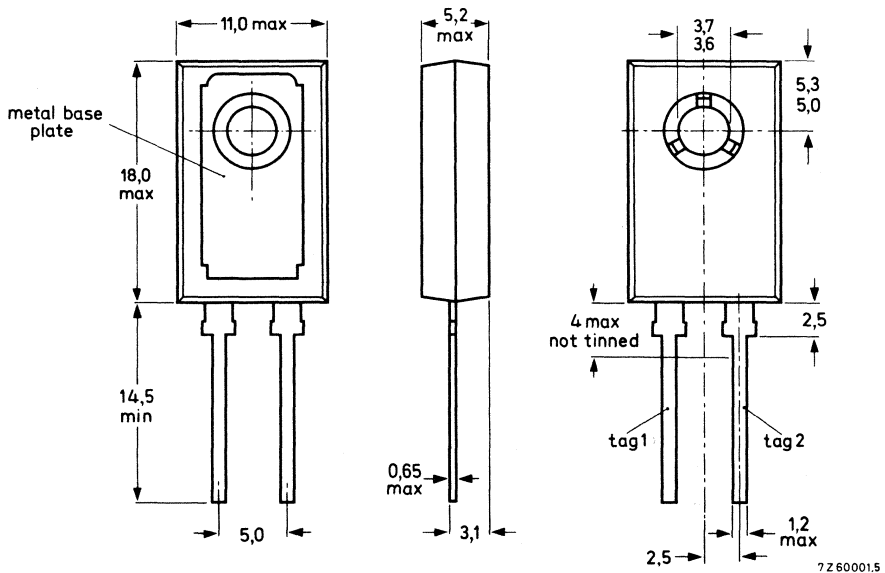
### QUICK REFERENCE DATA

		BYW19-800(R)		1000(R)	
		max	800	1000	
Repetitive peak reverse voltage	$V_{RRM}$	max	800	1000	V
Average forward current	$I_{F(AV)}$	max	7		A
Non-repetitive peak forward current	$I_{FSM}$	max	40		A
Reverse recovery time	$t_{rr}$	<	450		ns

### MECHANICAL DATA (see also page 2)

Dimensions in mm

SOD-38



The exposed metal base-plate is directly connected to tag 1.

## MECHANICAL DATA (continued)

Net mass: 2,5 g

Recommended diameter of fixing screw: 3,5 mm

Torque on screw

when using washer and heatsink compound: min 0,95 Nm (9,5 kg cm)  
max 1,5 Nm (15 kg cm)

Accessories:

supplied with device: washer

available on request : 56316 (mica insulating washer)

## POLARITY OF CONNECTIONS

	BYW19-800 and BYW19-1000	BYW19-800R and BYW19-1000R
Base-plate	cathode	anode
Tag 1	cathode	anode
Tag 2	anode	cathode

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

### Voltages

		BYW19-800(R)	1000(R)	
→ Non-repetitive peak reverse voltage	$V_{RSM}$	max 1000	1000	V
Repetitive peak reverse voltage	$V_{RRM}$	max 800	1000	V
Working reverse voltage	$V_{RW}$	max 800	800	V
Continuous reverse voltage	$V_R$	max 800	800	V

### Currents

Average forward current assuming zero switching

losses (averaged over any 20 ms period; see page 7)

square-wave;  $\delta = 0,5$ ; up to  $T_{mb} = 98^\circ\text{C}$

square-wave;  $\delta = 0,5$ ; at  $T_{mb} = 125^\circ\text{C}$

sinusoidal; up to  $T_{mb} = 98^\circ\text{C}$

sinusoidal; at  $T_{mb} = 125^\circ\text{C}$

$I_{F(AV)}$	max	7	A
$I_{F(AV)}$	max	4	A
$I_{F(AV)}$	max	7	A
$I_{F(AV)}$	max	4	A

Repetitive peak forward current;  $t_p = 20 \mu\text{s}$ ;  $\delta \leq 0,02$

$I_{FRM}$	max	75	A
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Non-repetitive peak forward current

square-wave;  $t = 10 \text{ ms}$ ;  $T_j = 150^\circ\text{C}$  prior

to surge; with reapplied  $V_{RWmax}$

$I_{FSM}$	max	40	A
-----------	-----	----	---

### Temperatures

Storage temperature

$T_{stg}$	-40 to +125	$^\circ\text{C}$
-----------	-------------	------------------

Junction temperature

$T_j$	max 150	$^\circ\text{C}$
-------	---------	------------------

**THERMAL RESISTANCE**

From junction to mounting base

$$R_{th\ j-mb} = 4,5\ ^\circ C/W$$

Transient thermal impedance ( $t = 1\ ms$ )

$$Z_{th\ j-mb} = 0,3\ ^\circ C/W$$

**Influence of mounting method**

1. Heatsink mounted

Thermal resistance from mounting base to heatsink

a. with heatsink compound

$$R_{th\ mb-h} = 1,5\ ^\circ C/W$$

b. with heatsink compound and 56316 mica washer

$$R_{th\ mb-h} = 2,7\ ^\circ C/W$$

c. without heatsink compound

$$R_{th\ mb-h} = 2,7\ ^\circ C/W$$

d. without heatsink compound with 56316 mica washer

$$R_{th\ mb-h} = 5\ ^\circ C/W$$

2. Free air operation

The quoted values of  $R_{th\ j-a}$  should be used only when no leads of other dissipating components run to the same tie-points.

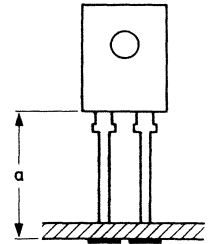
Thermal resistance from junction to ambient in free air: mounted on a printed-circuit board at  $a =$  maximum lead length and with a copper laminate

a.  $> 1\ cm^2$

$$R_{th\ j-a} = 50\ ^\circ C/W$$

b.  $< 1\ cm^2$

$$R_{th\ j-a} = 55\ ^\circ C/W$$



7Z62315.1

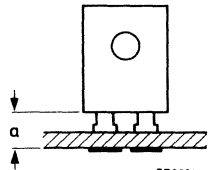
mounted on a printed-circuit board at a lead length  $a = 3\ mm$  and with a copper laminate

c.  $> 1\ cm^2$

$$R_{th\ j-a} = 55\ ^\circ C/W$$

d.  $< 1\ cm^2$

$$R_{th\ j-a} = 60\ ^\circ C/W$$



7Z62314

# BYW19 SERIES

## CHARACTERISTICS

### Forward voltage

$$I_F = 20 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$$

$$V_F < 2,3 \text{ V}^*$$

### Reverse current

$$V_R = V_{RW\max}; T_j = 125 \text{ }^\circ\text{C}$$

$$I_R < 0,6 \text{ mA}$$

### Reverse recovery when switched from

$$I_F = 2 \text{ A to } V_R \geq 30 \text{ V}; -dI_F/dt = 20 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$$

Recovered charge

$$Q_s < 0,7 \text{ } \mu\text{C}$$

Recovery time

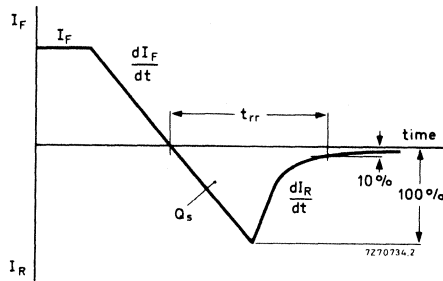
$$t_{rr} < 450 \text{ ns}$$

### Maximum slope of the reverse recovery current

when switched from  $I_F = 2 \text{ A}$  to  $V_R \geq 30 \text{ V}$ ;

with  $-dI_F/dt = 2 \text{ A}/\mu\text{s}$ ;  $T_j = 25 \text{ }^\circ\text{C}$

$$\left| dI_R/dt \right| < 5 \text{ A}/\mu\text{s}$$



\* Measured under pulse conditions to avoid excessive dissipation.

CHARACTERISTICS (continued)

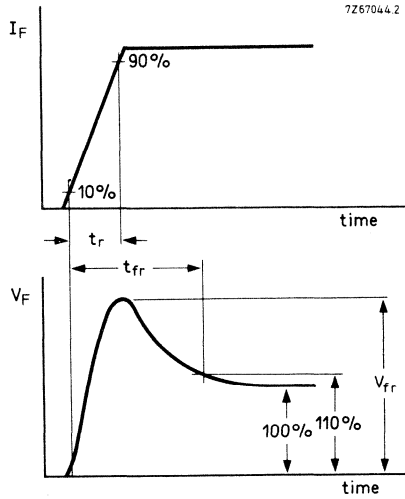
Forward recovery when switched to

$I_F = 10 \text{ A}$  with  $t_r = 1 \mu\text{s}$  at  $T_j = 25 \text{ }^\circ\text{C}$

Recovery time

Recovery voltage

$t_{fr} < 1 \mu\text{s}$   
 $V_{fr} < 15 \text{ V}$



Forward output waveform

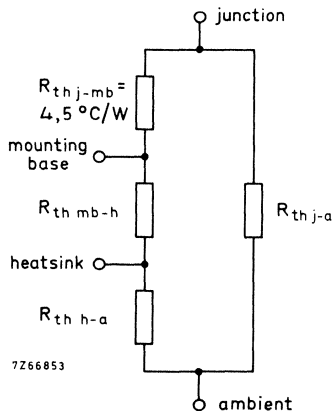
## MOUNTING INSTRUCTIONS

1. Soldered joints must be at least 2,5 mm from the seal.
2. The maximum permissible temperature of the soldering iron or bath is 270 °C; contact with the joint must not exceed 3 seconds.
3. The devices should not be immersed in oil, and few potting resins are suitable for re-encapsulation. Advice on these materials is available on request.
4. Leads should not be bent less than 2,5 mm from the seal. Exert no axial pull when bending.
5. For good thermal contact heatsink compound should be used between base-plate and heatsink.

## OPERATING NOTES

Dissipation and heatsink considerations:

- a. The various components of junction temperature rise above ambient are illustrated below:



- b. The method of using the graphs on page 7 is as follows:

Starting with the required current on the  $I_F(AV)$  axis, trace upwards to meet the appropriate form factor curve. Trace right horizontally and upwards from the appropriate value on the  $T_{amb}$  scale. The intersection determines the  $R_{th\ mb-a}$ . The heatsink thermal resistance value ( $R_{th\ h-a}$ ) can now be calculated from:

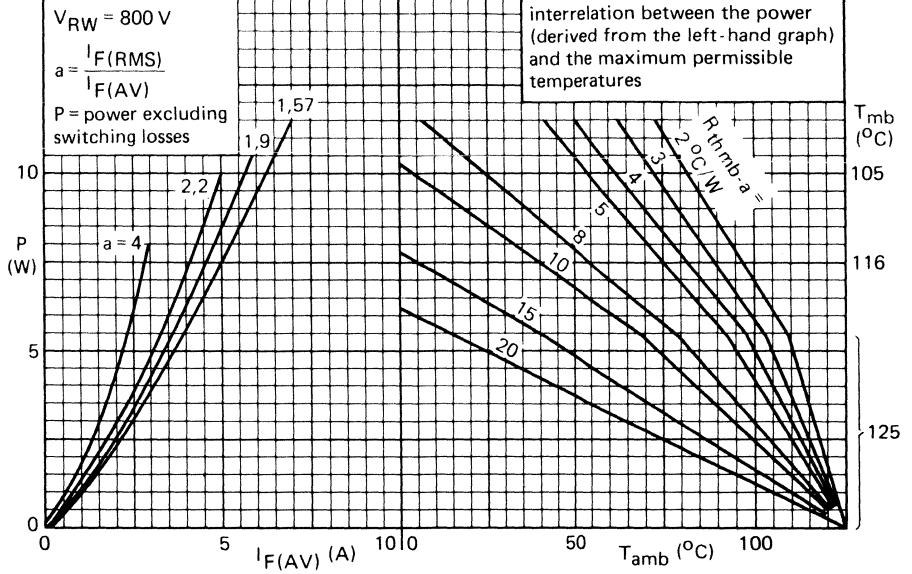
$$R_{th\ h-a} = R_{th\ mb-a} - R_{th\ mb-h}$$

Any measurement of heatsink temperature should be made immediately adjacent to the device.

- c. The heatsink curves are optimized to allow the junction temperature to run up to a maximum of 150 °C ( $T_{j\ max}$ ) whilst limiting  $T_{mb}$  to 125 °C (or less).

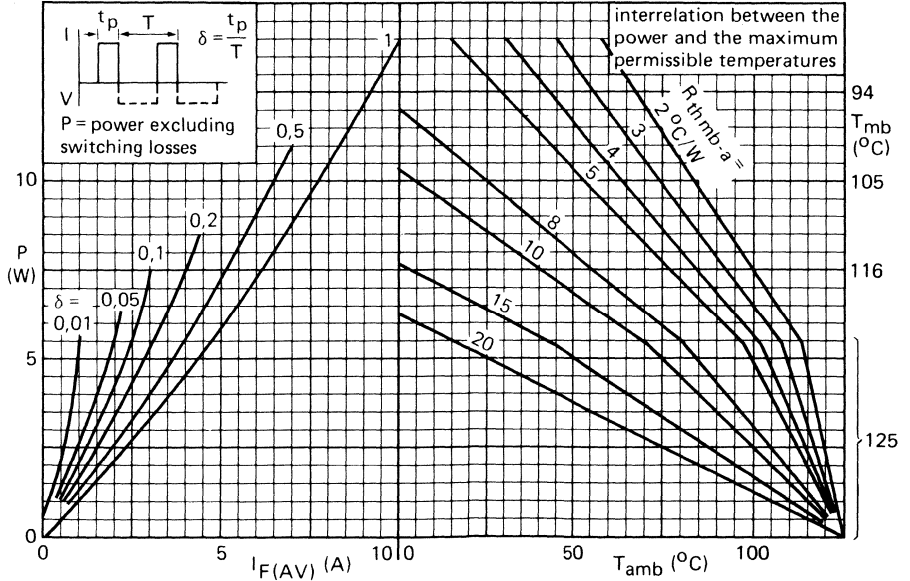
SINUSOIDAL OPERATION

7Z77081

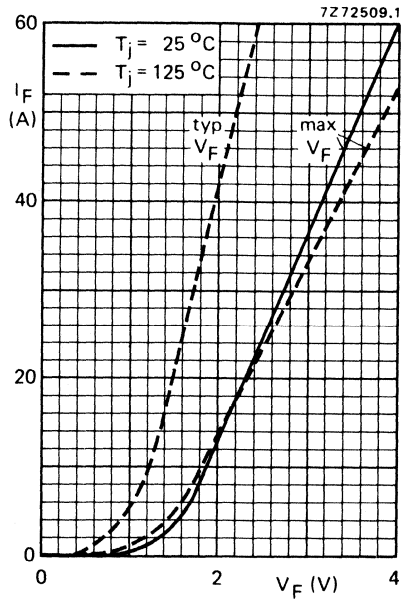
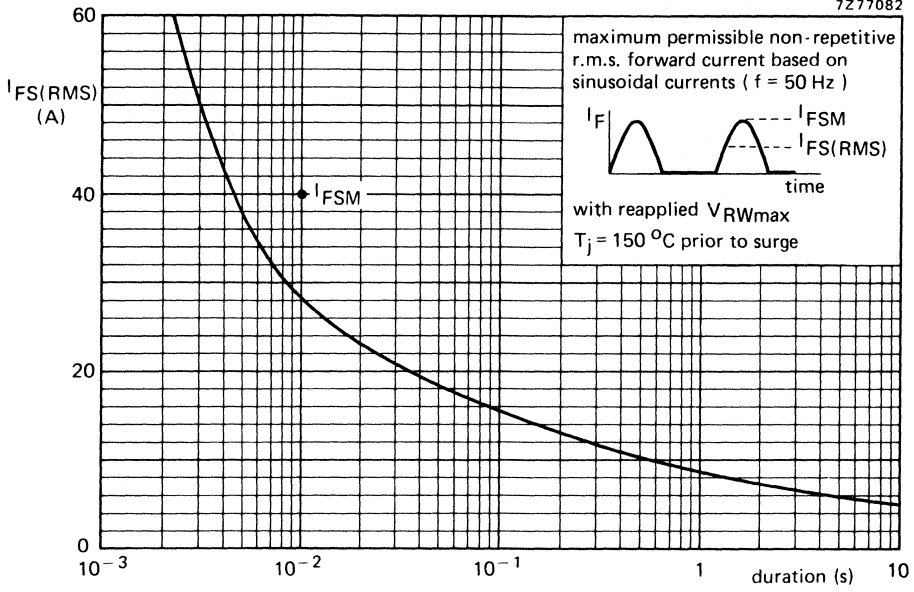


SQUARE-WAVE OPERATION

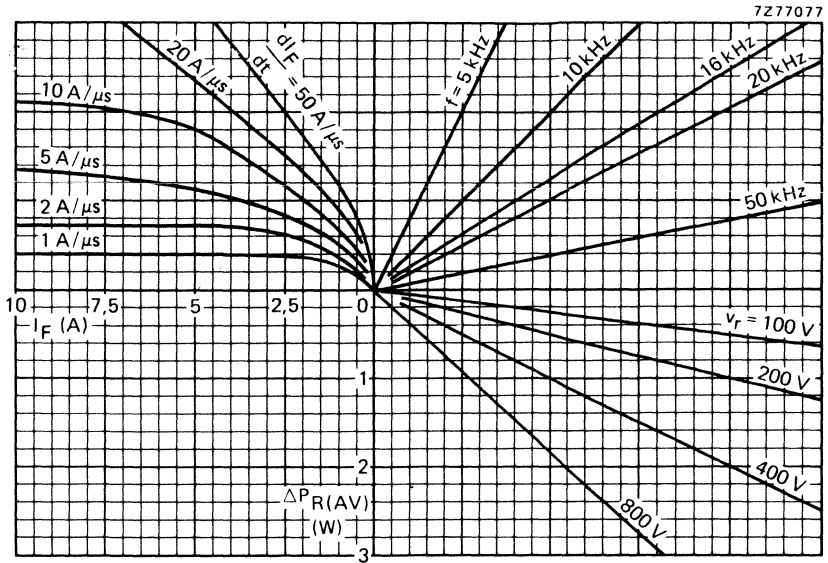
7Z77080



# BYW19 SERIES



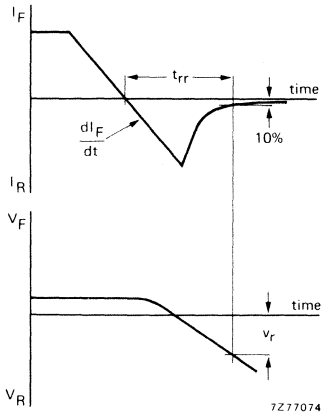




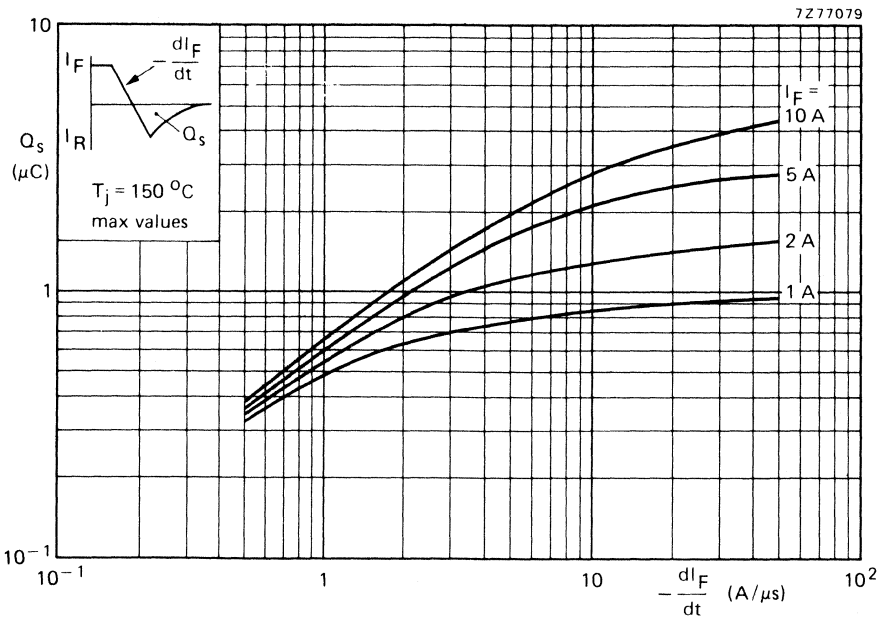
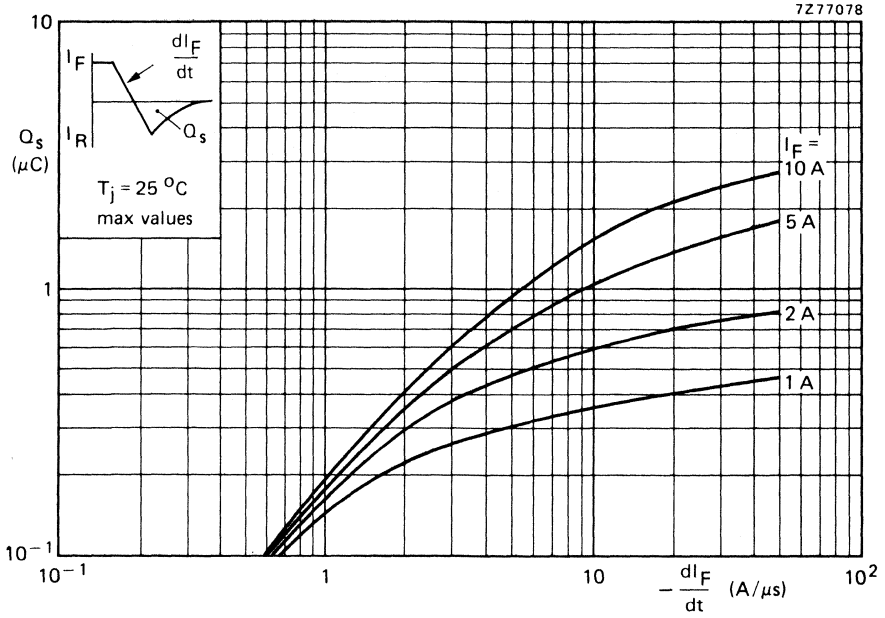
**NOMOGRAM**

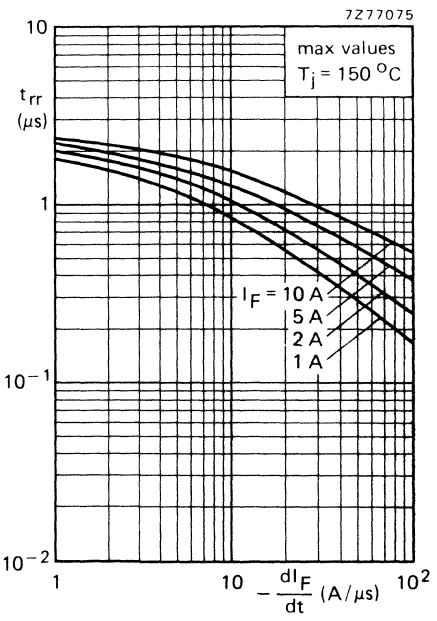
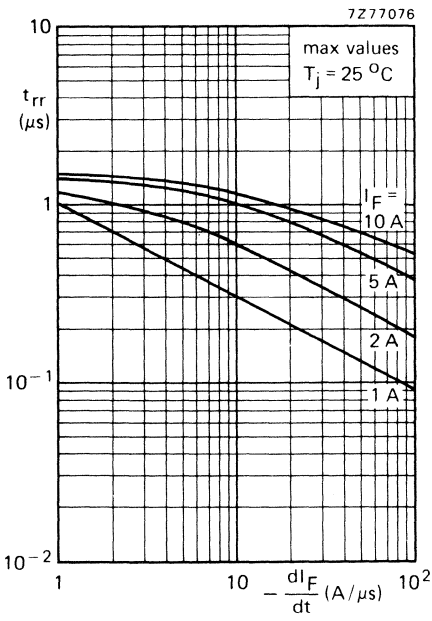
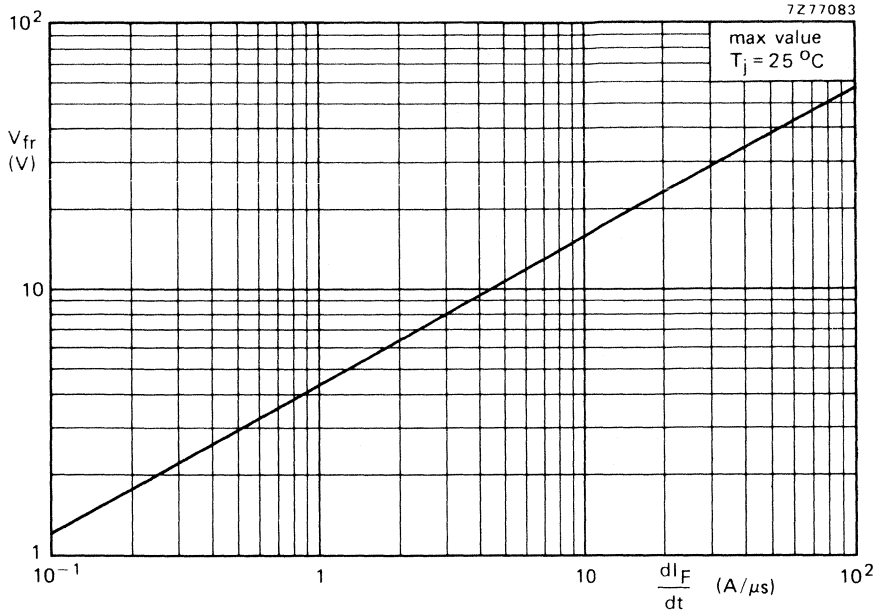
Power loss  $\Delta P_{R(AV)}$  due to switching only (to be added to steady state power losses).

$I_F$  = forward current just before switching off;  $T_j = 150\text{ }^\circ\text{C}$

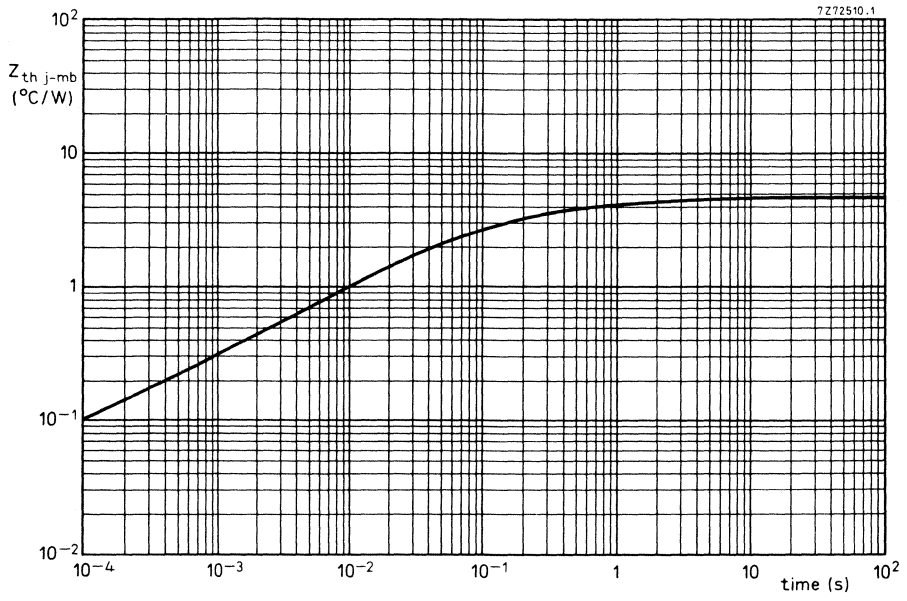


BYW19 SERIES





# BYW19 SERIES



## FAST SOFT-RECOVERY RECTIFIER DIODE

The BYW25 is a fast soft-recovery rectifier diode in a DO-5 metal envelope especially suitable for operation as main and commutating diode in 3-phase a.c. motor speed control inverters and in high frequency power supplies in general.

Two polarity versions are available:

Normal polarity (cathode to stud); BYW25.

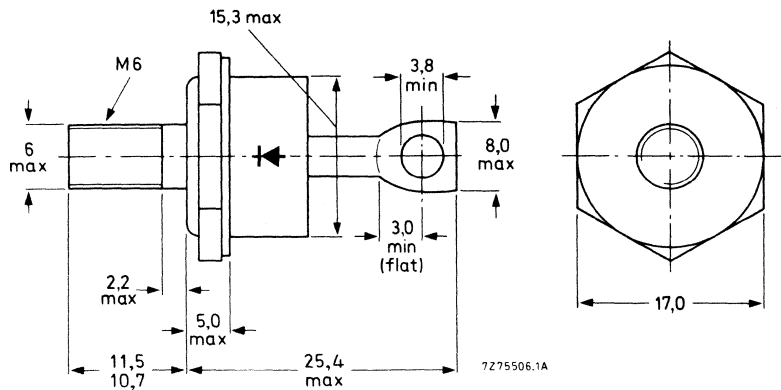
Reverse polarity (anode to stud); BYW25R.

### QUICK REFERENCE DATA

Repetitive peak reverse voltage	$V_{RRM}$	max.	800 V
Average forward current	$I_{F(AV)}$	max.	40 A
Repetitive peak forward current	$I_{FRM}$	max.	600 A
Reverse recovery time	$t_{rr}$	<	450 ns

### MECHANICAL DATA

Fig. 1 DO-5: with metric M6 stud ( $\phi 6$  mm)



Net mass: 22 g

Diameter of clearance hole: max. 6,5 mm

Torque on nut: min. 1,7 Nm (17 kg cm)

max. 3,5 Nm (35 kg cm)

Supplied with device: 1 nut, 1 lock washer

Nut dimensions across the flats: 10 mm

Supplied on request: accessories 56264A

(mica washer, insulating ring, tag)

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

### Voltages \*

Non-repetitive peak reverse voltage	$V_{RSM}$	max.	1000 V
Repetitive peak reverse voltage	$V_{RRM}$	max.	800 V
Continuous reverse voltage	$V_R$	max.	650 V

### Currents

Average forward current; switching losses negligible up to 20 kHz			
sinusoidal; up to $T_{mb} = 100\text{ }^\circ\text{C}$	$I_F(AV)$	max.	40 A
sinusoidal; at $T_{mb} = 125\text{ }^\circ\text{C}$	$I_F(AV)$	max.	23 A
R.M.S. forward current	$I_F(RMS)$	max.	60 A
Repetitive peak forward current	$I_{FRM}$	max.	600 A
Non-repetitive peak forward current; t = 10 ms; half sine-wave;			
$T_j = 150\text{ }^\circ\text{C}$ prior to surge	$I_{FSM}$	max.	550 A
$I^2t$ for fusing (t = 10 ms)	$I^2t$	max.	1500 A <sup>2</sup> s

### Temperatures

Storage temperature	$T_{stg}$	-55 to + 150 °C
Junction temperature	$T_j$	max. 150 °C

### THERMAL RESISTANCE

From junction to mounting base	$R_{th\ j-mb}$	=	0,6 °C/W
From mounting base to heatsink with heatsink compound	$R_{th\ mb-h}$	=	0,3 °C/W
without heatsink compound	$R_{th\ mb-h}$	=	0,5 °C/W

\* To ensure thermal stability:  $R_{th\ j-a} \leq 1\text{ }^\circ\text{C/W}$  (continuous reverse voltage).

**CHARACTERISTICS**

Forward voltage

$I_F = 35 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$I_F = 150 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_F < 1,55 \text{ V}^*$

$V_F < 2,25 \text{ V}^*$

Reverse current

$V_R = 650 \text{ V}; T_j = 125 \text{ }^\circ\text{C}$

$I_R < 7 \text{ mA}$

Reverse recovery when switched from

$I_F = 10 \text{ A to } V_R = 30 \text{ V with } -dI_F/dt = 50 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

Recovery time

$t_{rr} < 450 \text{ ns}$

$I_F = 600 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 70 \text{ A}/\mu\text{s}; T_{mb} = 85 \text{ }^\circ\text{C}$

Recovery time

$t_{rr} < 1 \mu\text{s}$

Maximum slope of the reverse recovery current

when switched from  $I_F = 600 \text{ A to } V_R \geq 30 \text{ V};$

with  $-dI_F/dt = 35 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

$|dI_R/dt| < 100 \text{ A}/\mu\text{s}$

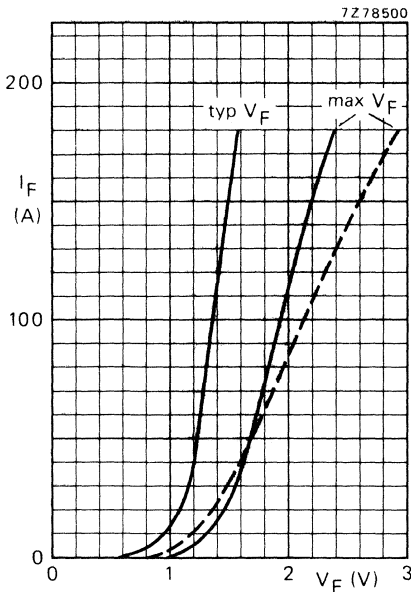


Fig. 3 —  $T_j = 25 \text{ }^\circ\text{C};$  - - -  $T_j = 150 \text{ }^\circ\text{C}.$

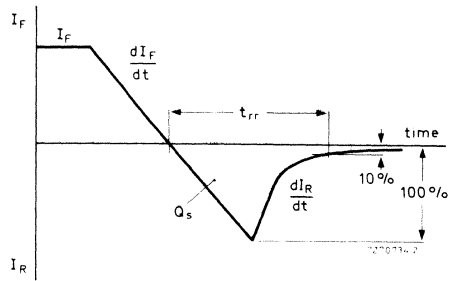


Fig. 2 Definitions of  $Q_s,$   $t_{rr}$  and  $dI_R/dt.$

\* Measured under pulse conditions to avoid excessive dissipation.

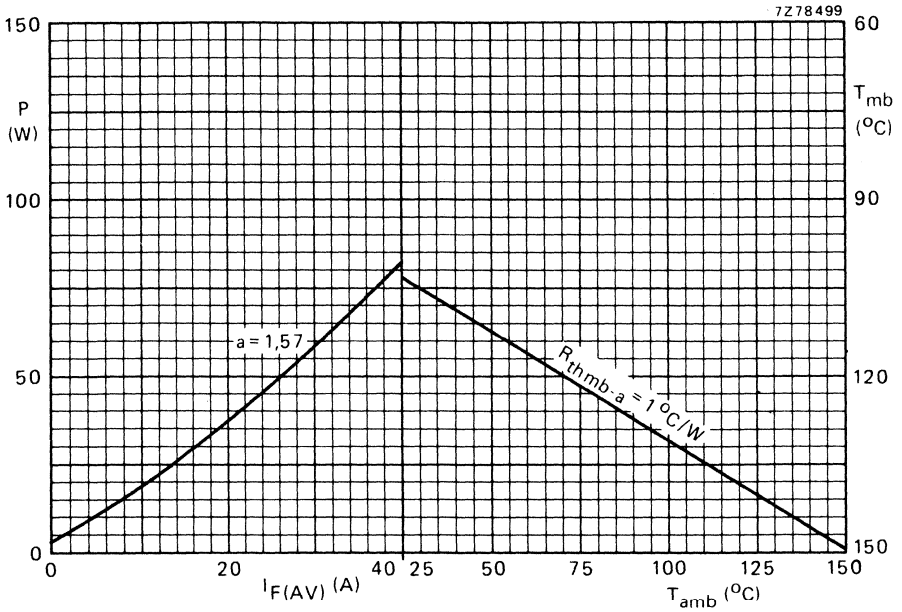


Fig. 4 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

$P$  = power including reverse current losses and switching losses up to  $f = 20$  kHz.

$a = I_{F(RMS)}/I_{F(AV)}$ .



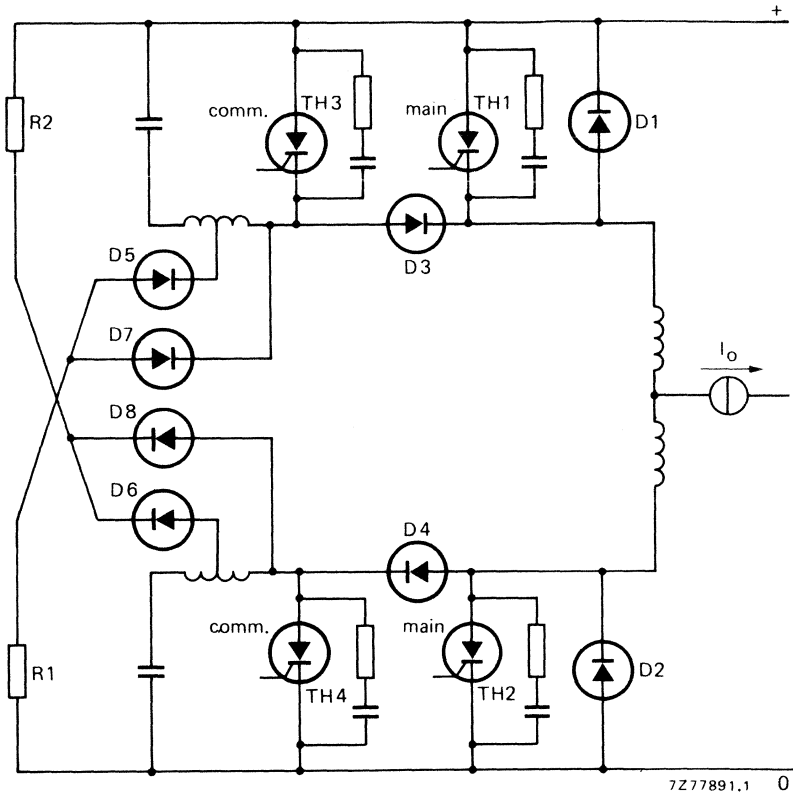


Fig. 5 One phase of a three-phase inverter for a.c. motor speed control. D1 to D4 are BYW25 types.





VERY FAST RECOVERY RECTIFIER DIODES

Glass-passivated, high-efficiency, eutectically-bonded rectifier diodes in plastic envelopes, featuring low forward voltage drop, very fast reverse recovery times, very low stored charge and non-snap-off. They are intended for use in switched-mode power supplies, and high-frequency circuits in general, where low conduction and switching losses are essential. The series consists of normal polarity (cathode to mounting base) types.

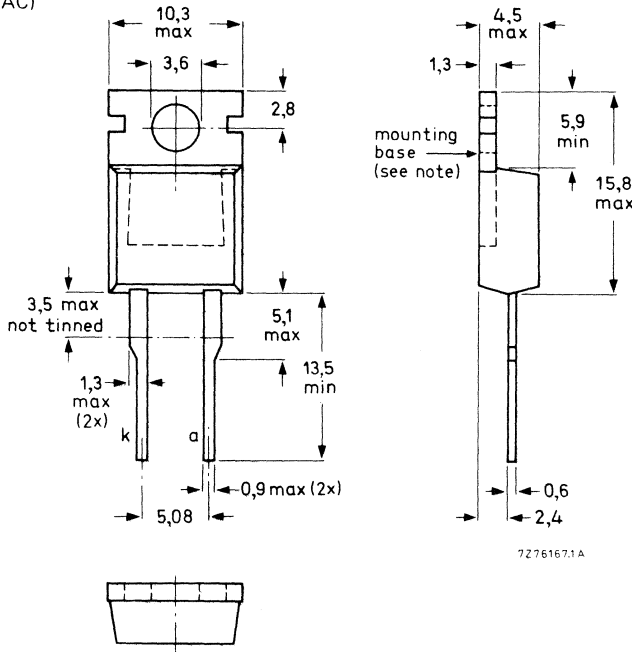
QUICK REFERENCE DATA

		BYW29-50	100	150
Repetitive peak reverse voltage	$V_{RRM}$	max. 50	100	150 V
Average forward current	$I_{F(AV)}$	max.	7	A
Forward voltage	$V_F$	<	0,85	V
Reverse recovery time	$t_{rr}$	<	35	ns

MECHANICAL DATA

Dimensions in mm

Fig.1 SOD-59  
(TO-220AC)



7276167:1 A

Note: The exposed metal mounting base is directly connected to the cathode.

Accessories supplied on request: see data sheets Mounting instructions and accessories for TO-220 envelopes.

Products approved to CECC 50 009-014, available on request.

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

### Voltages\*

		BYW29-50	100	150
Non-repetitive peak reverse voltage	$V_{RSM}$	max. 50	100	150 V
Repetitive peak reverse voltage	$V_{RRM}$	max. 50	100	150 V
Crest working reverse voltage	$V_{RWM}$	max. 50	100	150 V
Continuous reverse voltage	$V_R$	max. 50	100	150 V

### Currents

Average forward current; switching losses

negligible up to 500 kHz

sinusoidal; up to  $T_{mb} = 125\text{ }^\circ\text{C}$

square-wave;  $\delta = 0,5$ ; up to  $T_{mb} = 125\text{ }^\circ\text{C}$

$I_{F(AV)}$  max. 7 A

$I_{F(AV)}$  max. 7,6 A

R.M.S. forward current

$I_{F(RMS)}$  max. 12 A

Repetitive peak forward current

$I_{FRM}$  max. 80 A

Non-repetitive peak forward current;  $t = 10\text{ ms}$ ;

half sine-wave;  $T_j = 150\text{ }^\circ\text{C}$  prior to surge;

with reapplied  $V_{RWMmax}$

$I_{FSM}$  max. 80 A

$I^2 t$  for fusing ( $t = 10\text{ ms}$ )

$I^2 t$  max. 32  $\text{A}^2\text{s}$

### Temperatures

Storage temperature

$T_{stg}$  -40 to +150  $^\circ\text{C}$

Junction temperature

$T_j$  max. 150  $^\circ\text{C}$

\* To ensure thermal stability:  $R_{thj-a} \leq 16\text{ }^\circ\text{C/W}$  (continuous reverse voltage).

**THERMAL RESISTANCE**

From junction to mounting base

$$R_{th\ j-mb} = 2,7\ ^\circ C/W$$

Transient thermal impedance;  $t = 1\ ms$

$$Z_{th\ j-mb} = 0,26\ ^\circ C/W$$

**Influence of mounting method**

1. Heatsink mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound

$$R_{th\ mb-h} = 0,3\ ^\circ C/W$$

b. with heatsink compound and 0,06 mm maximum mica insulator

$$R_{th\ mb-h} = 1,4\ ^\circ C/W$$

c. with heatsink compound and 0,1 mm maximum mica insulator (56369)

$$R_{th\ mb-h} = 2,2\ ^\circ C/W$$

d. with heatsink compound and 0,25 mm maximum alumina insulator (56367)

$$R_{th\ mb-h} = 0,8\ ^\circ C/W$$

e. without heatsink compound

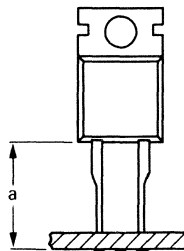
$$R_{th\ mb-h} = 1,4\ ^\circ C/W$$

2. Free-air operation

The quoted values of  $R_{th\ j-a}$  should be used only when no leads of other dissipating components run to the same tie-point.

Thermal resistance from junction to ambient in free air:  
mounted on a printed-circuit board at  $a =$  any lead length and with copper laminate

$$R_{th\ j-a} = 60\ ^\circ C/W$$



7278248

Fig. 2.

CHARACTERISTICS

Forward voltage

$I_F = 5 \text{ A}; T_j = 100 \text{ }^\circ\text{C}$

$V_F < 0,85 \text{ V}^*$

$I_F = 20 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_F < 1,3 \text{ V}^*$

Reverse current

$V_R = V_{RWMmax}; T_j = 100 \text{ }^\circ\text{C}$

$I_R < 0,6 \text{ mA}$

Reverse recovery when switched from

$I_F = 1 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 50 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

Recovery time

$t_{rr} < 35 \text{ ns}$

$I_F = 2 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 20 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

Recovered charge

$Q_s < 15 \text{ nC}$

Recovery time

$t_{rr} < 50 \text{ ns}$

Forward recovery when switched to  $I_F = 1 \text{ A}$

with  $dI_F/dt = 10 \text{ A}/\mu\text{s}$

Recovery voltage

$V_{fr} \text{ typ. } 1,0 \text{ V}$

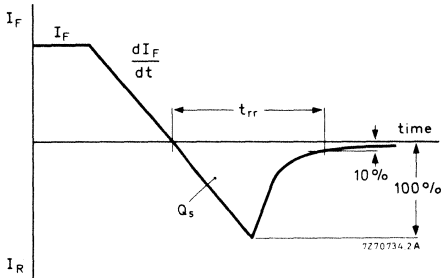


Fig. 3 Definitions of  $t_{rr}$  and  $Q_s$ .

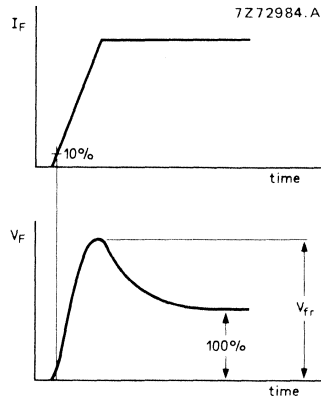


Fig. 4 Definition of  $V_{fr}$ .

\* Measured under pulse conditions to avoid excessive dissipation.

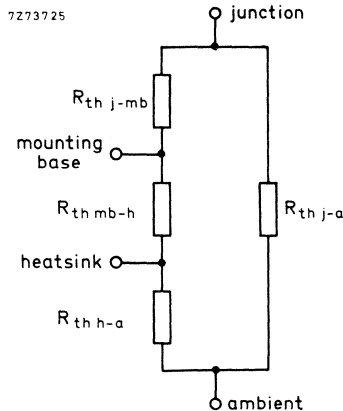
**MOUNTING INSTRUCTIONS**

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; it must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4,7 mm from the seal.
2. The leads should not be bent less than 2,4 mm from the seal, and should be supported during bending.
3. It is recommended that the circuit connection be made to the cathode tag, rather than direct to the heatsink.
4. Mounting by means of a spring clip is the best mounting method because it offers:
  - a. a good thermal contact under the crystal area and slightly lower  $R_{th\ mb-h}$  values than screw mounting.
  - b. safe isolation for mains operation.
 However, if a screw is used, it should be M3 cross-recess pan head. Care should be taken to avoid damage to the plastic body.
5. For good thermal contact heatsink compound should be used between base-plate and heatsink. Values of  $R_{th\ mb-h}$  given for mounting with heatsink compound refer to the use of a metallic-oxide loaded compound. Ordinary silicone grease is not recommended.
6. The device should not be pop-riveted to the heatsink. However, it is permissible to press-rivet providing that rivets of soft material are used, and the press forces are slowly and carefully controlled so as to avoid shock and deformation of either heatsink or mounting tab.

**OPERATING NOTES**

Dissipation and heatsink considerations:

- a. The various components of junction temperature rise above ambient are illustrated below:



- b. The method of using Figs 5 and 6 is as follows:  
 Starting with the required current on the  $I_F(AV)$  axis, trace upwards to meet the appropriate form factor or duty factor curve. Trace right horizontally and upwards from the appropriate value on the  $T_{amb}$  scale. The intersection determines the  $R_{th\ mb-a}$ . The heatsink thermal resistance value ( $R_{th\ h-a}$ ) can now be calculated from:
 
$$R_{th\ h-a} = R_{th\ mb-a} - R_{th\ mb-h}$$

- c. Any measurement of heatsink temperature should be made immediately adjacent to the device.

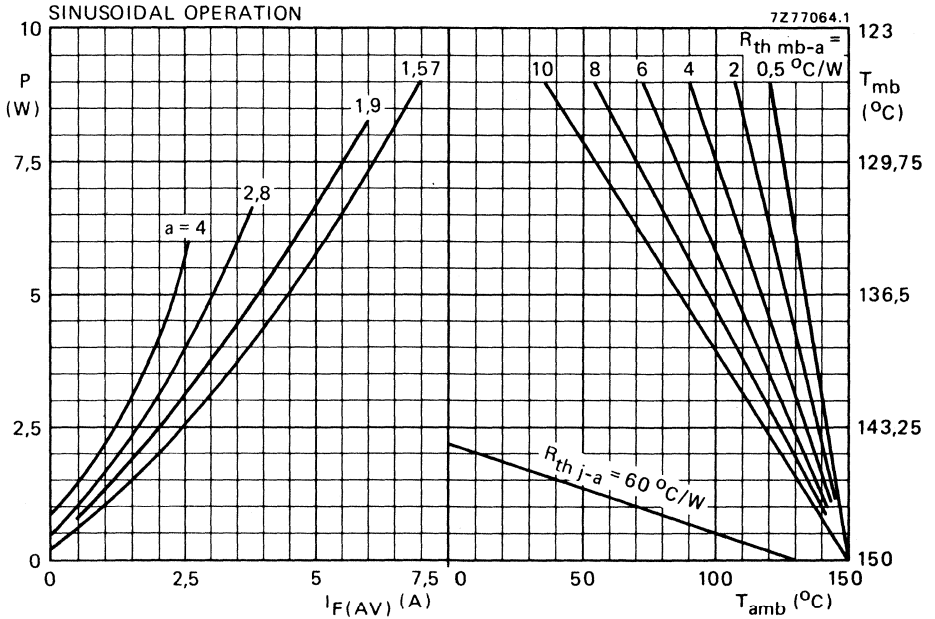


Fig. 5 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

$P$  = power including reverse current losses and switching losses up to  $f = 500\text{ kHz}$ .

$a$  = form factor =  $I_{F(RMS)}/I_{F(AV)}$ .



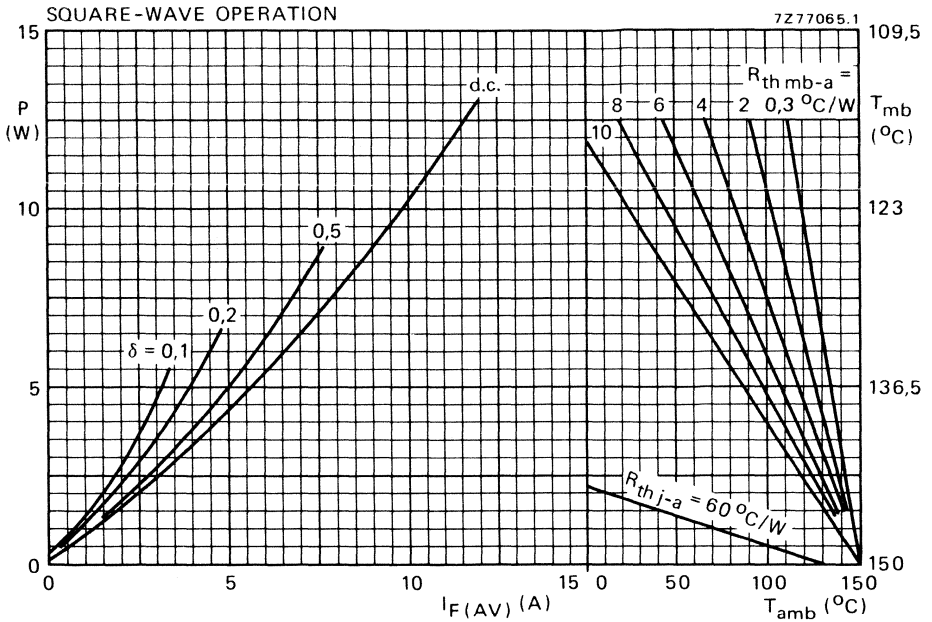
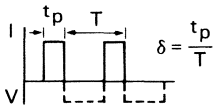


Fig. 6 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

P = power including reverse current losses and switching losses up to  $f = 500$  kHz.



$$I_F(AV) = I_F(RMS) \times \sqrt{\delta}$$

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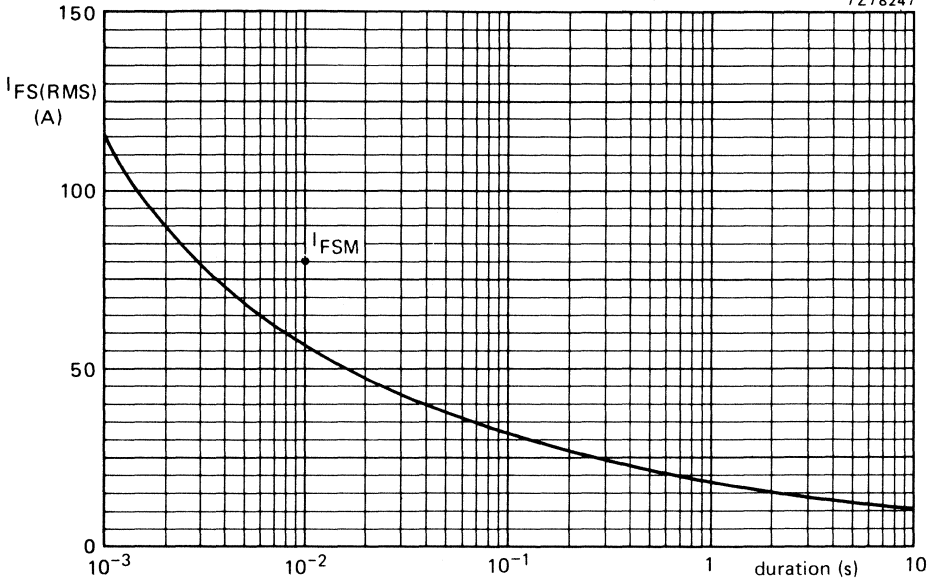


Fig. 7 Maximum permissible non-repetitive r.m.s. forward current based on sinusoidal currents ( $f = 50$  Hz);  $T_j = 150$  °C prior to surge; with reapplied  $V_{RWMmax}$ .

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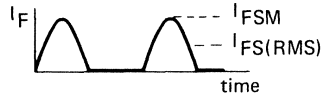
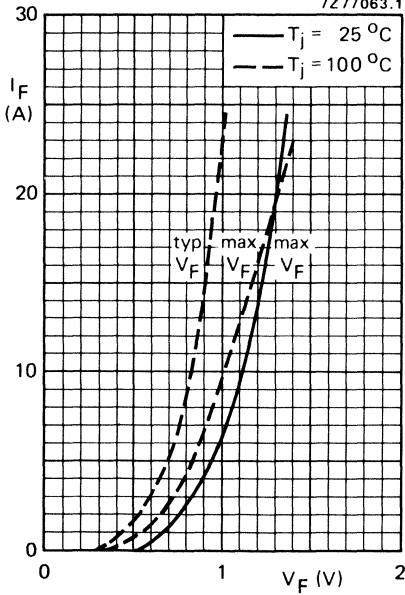


Fig. 8.

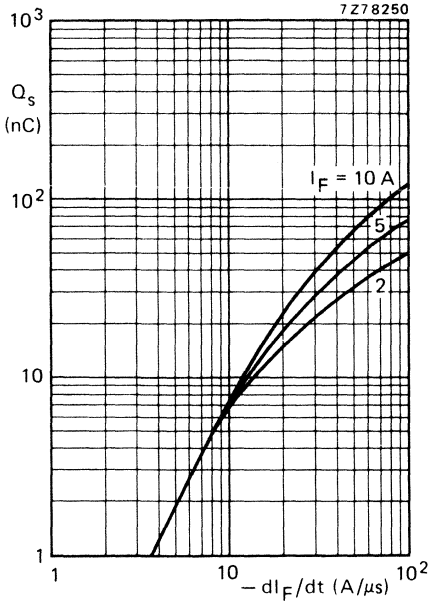


Fig. 9  $T_j = 25\text{ }^\circ\text{C}$ ; maximum values.

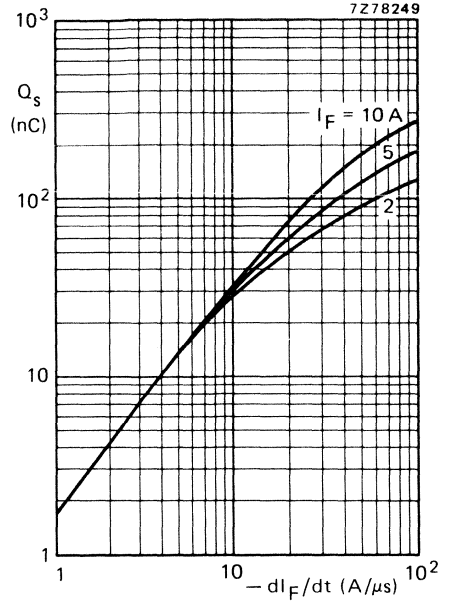


Fig. 10  $T_j = 100\text{ }^\circ\text{C}$ ; maximum values.

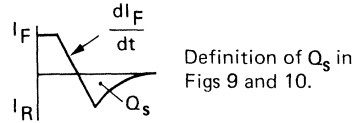
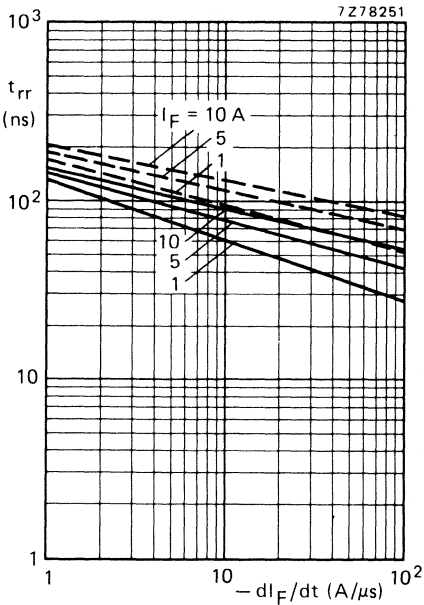
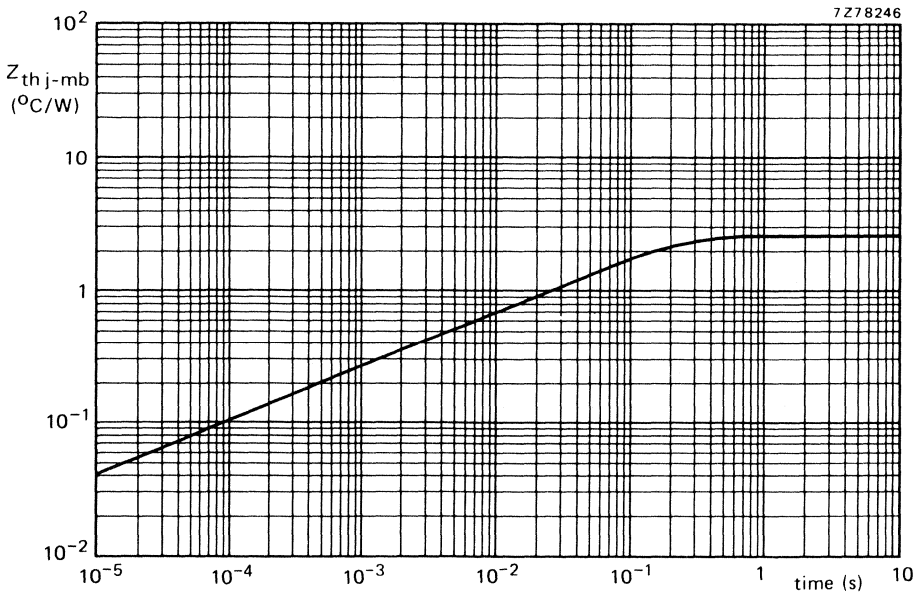
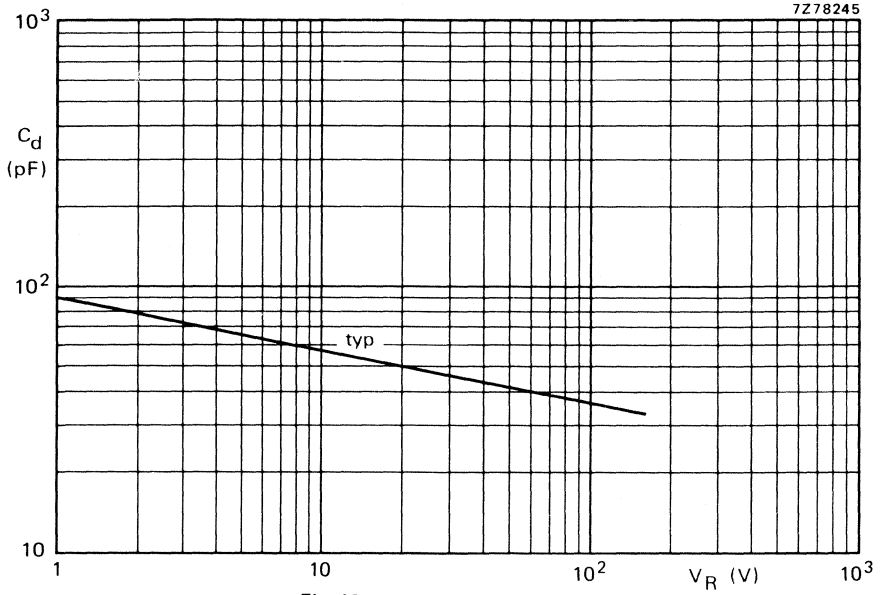


Fig. 11 Maximum values; —  $T_j = 25\text{ }^\circ\text{C}$ ; - - -  $T_j = 100\text{ }^\circ\text{C}$ .



VERY FAST RECOVERY RECTIFIER DIODES



Glass-passivated, high-efficiency rectifier diodes in DO-4 metal envelopes, featuring low forward voltage drop, very fast reverse recovery times, very low stored charge and non-snap-off. They are intended for use in switched-mode power supplies, and high-frequency circuits in general, where low conduction and switching losses are essential. The series consists of normal polarity (cathode to stud) types.

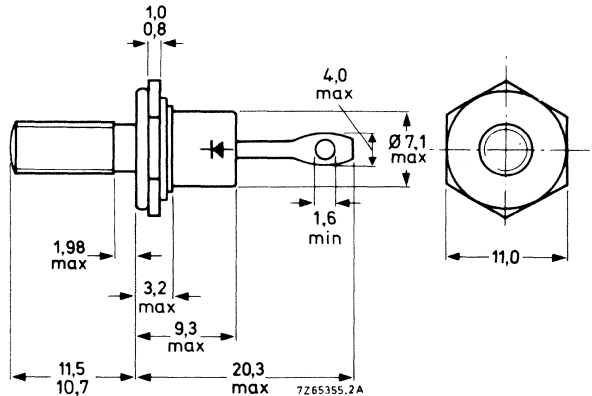
QUICK REFERENCE DATA

		BYW30-50		
		100	150	
Repetitive peak reverse voltage	$V_{RRM}$ max.	50	100	150 V
Average forward current	$I_F(AV)$ max.	12		A
Forward voltage	$V_F$	0,85		V
Reverse recovery time	$t_{rr}$	35		ns

MECHANICAL DATA

Dimensions in mm

Fig. 1 DO-4: with metric M5 stud ( $\phi 5$  mm); e.g. BYW30-50.  
with 10-32 UNF stud ( $\phi 4,83$  mm); e.g. BYW30-50U.



Net mass: 6 g

Diameter of clearance hole: max. 5,2 mm

Accessories supplied on request: 56295  
(PTFE bush, 2 mica washers, plain washer, tag)

Supplied with device: 1 nut, 1 lock washer  
Nut dimensions across the flats; M5: 8,0 mm  
10-32 UNF: 9,5 mm

Torque on nut: min. 0,9 Nm (9 kg cm)  
max. 1,7 Nm (17 kg cm)

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

### Voltages\*

		BYW30-50	100	150
Non-repetitive peak reverse voltage	$V_{RSM}$	max. 50	100	150 V
Repetitive peak reverse voltage	$V_{RRM}$	max. 50	100	150 V
Crest working reverse voltage	$V_{RWM}$	max. 50	100	150 V
Continuous reverse voltage	$V_R$	max. 50	100	150 V

### Currents

Average forward current; switching losses negligible up to 500 kHz

sinusoidal; up to $T_{mb} = 120\text{ }^{\circ}\text{C}$	$I_F(AV)$	max. 12 A
sinusoidal; at $T_{mb} = 125\text{ }^{\circ}\text{C}$	$I_F(AV)$	max. 10 A
square-wave; $\delta = 0,5$ ; up to $T_{mb} = 114\text{ }^{\circ}\text{C}$	$I_F(AV)$	max. 14 A
square-wave; $\delta = 0,5$ ; at $T_{mb} = 125\text{ }^{\circ}\text{C}$	$I_F(AV)$	max. 10 A

R.M.S. forward current  $I_F(RMS)$  max. 20 A

Repetitive peak forward current  $I_{FRM}$  max. 200 A

Non-repetitive peak forward current

$t = 10\text{ ms}$ ; half sine-wave;  $T_j = 150\text{ }^{\circ}\text{C}$  prior to surge with reapplied  $V_{RWMmax}$

$I_{FSM}$  max. 200 A

$I^2 t$  for fusing ( $t = 10\text{ ms}$ )  $I^2 t$  max. 200  $\text{A}^2\text{ s}$

### Temperatures

Storage temperature  $T_{stg}$   $-55\text{ to }+150\text{ }^{\circ}\text{C}$

Junction temperature  $T_j$  max. 150  $^{\circ}\text{C}$

## THERMAL RESISTANCE

From junction to mounting base  $R_{th\ j-mb} = 2,2\text{ }^{\circ}\text{C/W}$

From mounting base to heatsink

a. with heatsink compound  $R_{th\ mb-h} = 0,5\text{ }^{\circ}\text{C/W}$

b. without heatsink compound  $R_{th\ mb-h} = 0,6\text{ }^{\circ}\text{C/W}$

Transient thermal impedance;  $t = 1\text{ ms}$   $Z_{th\ j-mb} = 0,3\text{ }^{\circ}\text{C/W}$

## MOUNTING INSTRUCTIONS

The top connector should neither be bent nor twisted; it should be soldered into the circuit so that there is no strain on it.

During soldering the heat conduction to the junction should be kept to a minimum.

\* To ensure thermal stability:  $R_{th\ j-a} \leq 8,2\text{ }^{\circ}\text{C/W}$  (continuous reverse voltage).

CHARACTERISTICS

Forward voltage

$I_F = 10 \text{ A}; T_j = 100 \text{ }^\circ\text{C}$

$I_F = 50 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_F < 0,85 \text{ V}^*$

$V_F < 1,3 \text{ V}^*$

Reverse current

$V_R = V_{RWMmax}; T_j = 100 \text{ }^\circ\text{C}$

$I_R < 1,3 \text{ mA}$

Reverse recovery when switched from

$I_F = 1 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 20 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

Recovery time

$t_{rr} < 35 \text{ ns}$

$I_F = 2 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 20 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

Recovery charge

$Q_s < 15 \text{ nC}$

Recovery time

$t_{rr} < 50 \text{ ns}$

Forward recovery when switched to  $I_F = 10 \text{ A}$   
with  $dI_F/dt = 10 \text{ A}/\mu\text{s}$

$V_{fr} \text{ typ. } 1,0 \text{ V}$

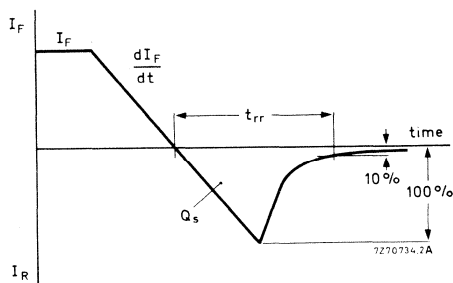


Fig. 2 Definitions of  $t_{rr}$  and  $Q_s$ .

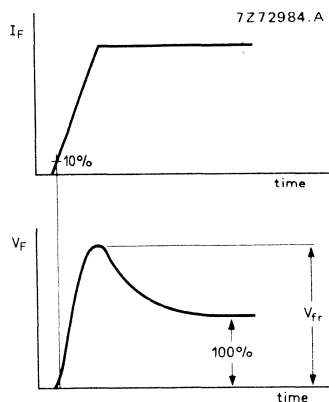


Fig. 3 Definition of  $V_{fr}$ .

\* Measured under pulse conditions to avoid excessive dissipation.

SINUSOIDAL OPERATION

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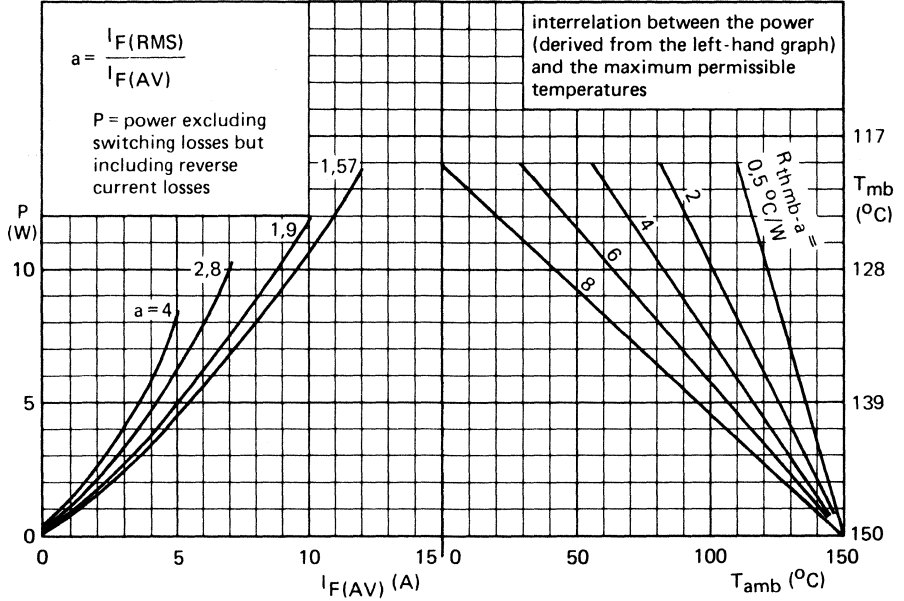


Fig. 4.



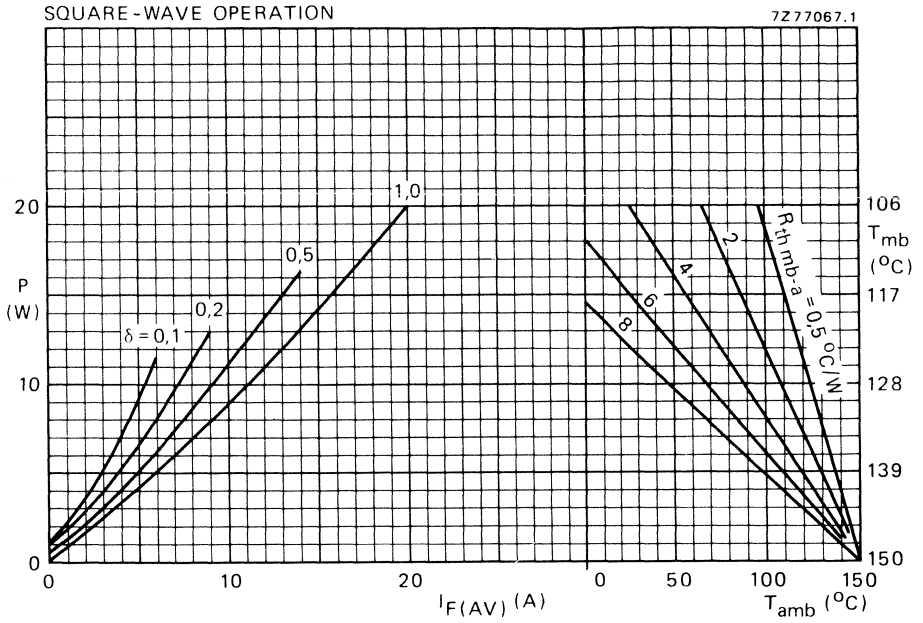
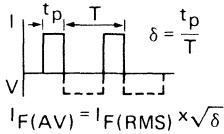


Fig. 5 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.  
 P = power including reverse current losses and switching losses up to  $f = 500$  kHz.



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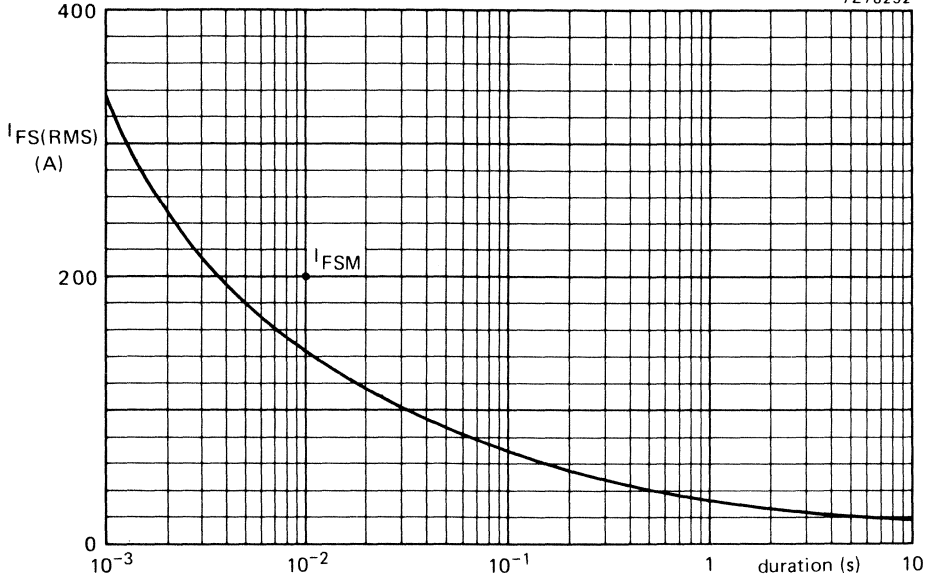


Fig. 6 Maximum permissible non-repetitive r.m.s. forward current based on sinusoidal currents ( $f = 50$  Hz);  $T_j = 150$  °C prior to surge; with reapplied  $V_{RWMmax}$ .

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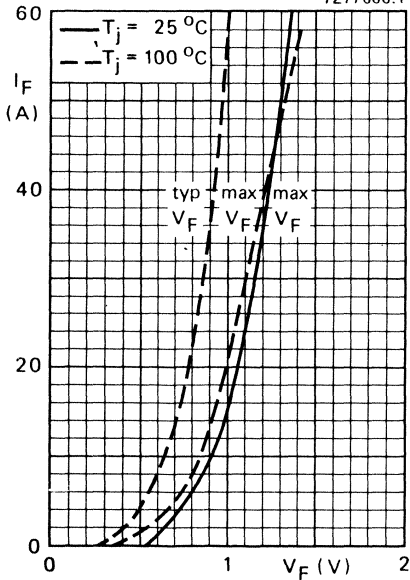


Fig. 7.

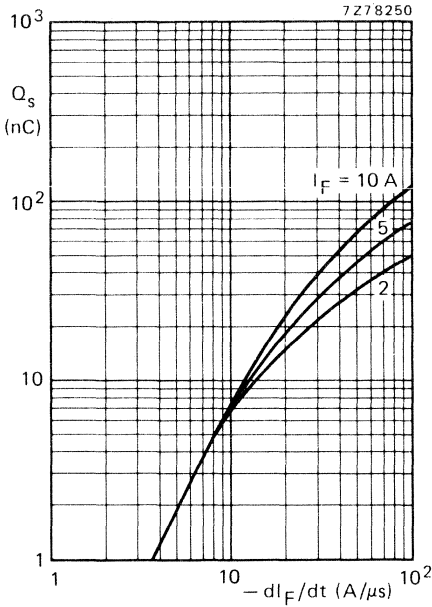


Fig. 8  $T_j = 25\text{ }^\circ\text{C}$ ; maximum values.

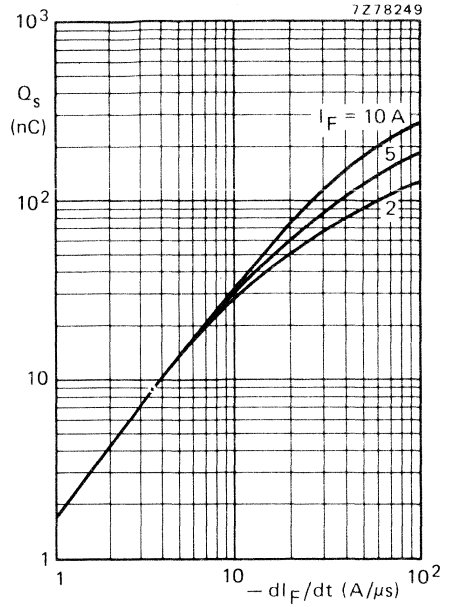
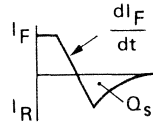
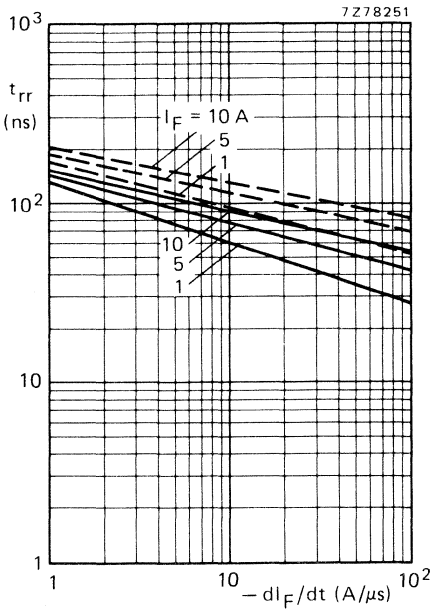


Fig. 9  $T_j = 100\text{ }^\circ\text{C}$ ; maximum values.



Definition of  $Q_s$  in Figs 8 and 9.

Fig. 10 Maximum values; —  $T_j = 25\text{ }^\circ\text{C}$ ; ---  $T_j = 100\text{ }^\circ\text{C}$ .

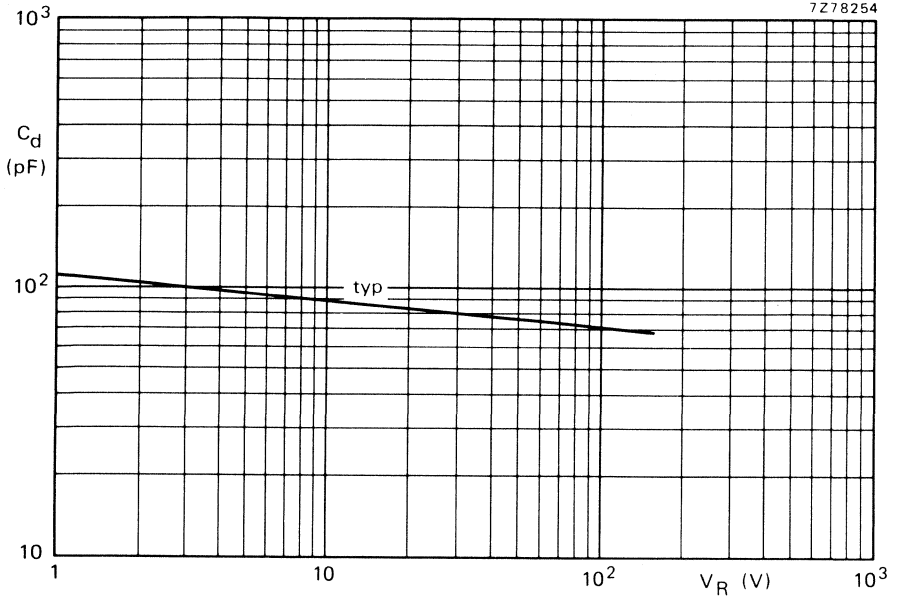


Fig. 11  $f = 1$  MHz;  $T_j = 25$  °C.

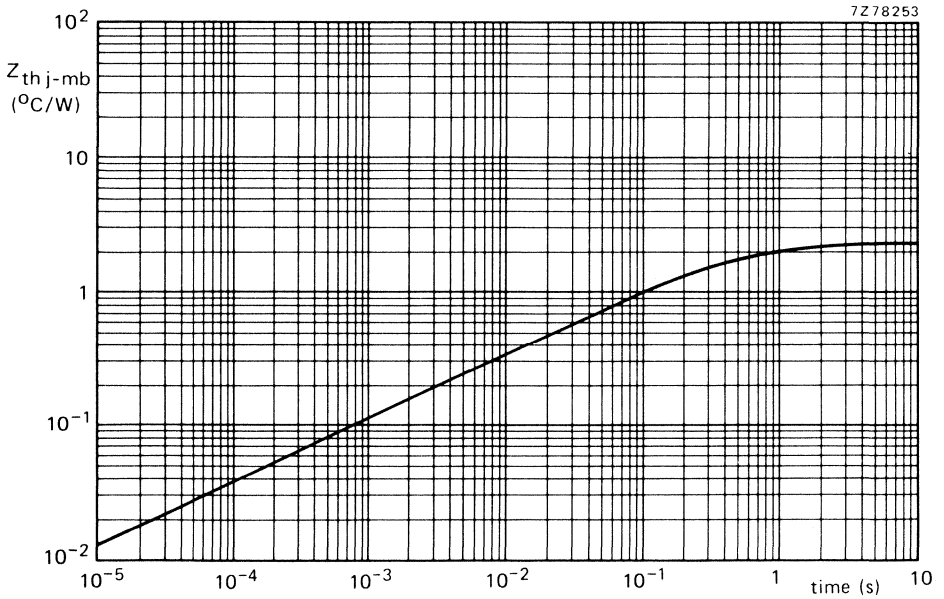


Fig. 12.

VERY FAST RECOVERY RECTIFIER DIODES



Glass-passivated, high-efficiency rectifier diodes in DO-4 metal envelopes, featuring low forward voltage drop, very fast reverse recovery times, very low stored charge and non-snap-off. They are intended for use in switched-mode power supplies, and high frequency circuits in general, where low conduction and switching losses are essential. The series consists of normal polarity (cathode to stud) types.

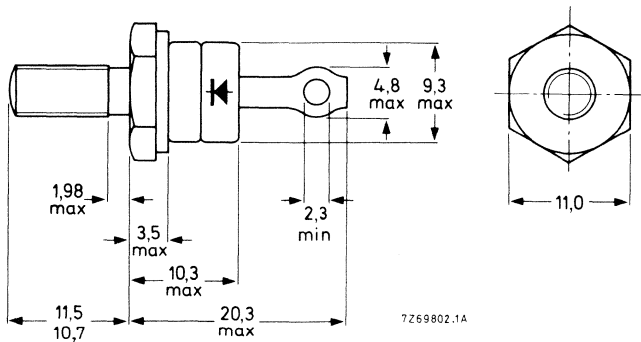
QUICK REFERENCE DATA

		BYW31-50	100	150
Repetitive peak reverse voltage	$V_{RRM}$	max. 50	100	150 V
Average forward current	$I_{F(AV)}$	max.	25	A
Forward voltage	$V_F$	<	0,85	V
Reverse recovery time	$t_{rr}$	<	50	ns

MECHANICAL DATA

Dimensions in mm

Fig. 1 DO-4: with metric M5 stud ( $\phi 5$  mm); e.g. BYW31-50.  
with 10-32 UNF stud ( $\phi 4,83$  mm); e.g. BYW31-50U.



Net mass: 7 g

Diameter of clearance hole: max. 5,2 mm

Accessories supplied on request: 56295  
(PTFE bush, 2 mica washers, plain washer, tag)

Supplied with device: 1 nut, 1 lock washer  
Nut dimensions across the flats; M5: 8,0 mm

10-32 UNF: 9,5 mm

Torque on nut: min. 0,9 (9 kg cm)  
max. 1,7 (17 kg cm)

Products available to CECC 50 009-002, available on request.

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

### Voltages \*

		BYW31-50	100	150
Non-repetitive peak reverse voltage	$V_{RSM}$	max. 50	100	150 V
Repetitive peak reverse voltage	$V_{RRM}$	max. 50	100	150 V
Crest working reverse voltage	$V_{RWM}$	max. 50	100	150 V
Continuous reverse voltage	$V_R$	max. 50	100	150 V

### Currents

Average forward current; switching losses

negligible up to 500 kHz

sinusoidal; up to  $T_{mb} = 120\text{ }^{\circ}\text{C}$

sinusoidal; at  $T_{mb} = 125\text{ }^{\circ}\text{C}$

square-wave;  $\delta = 0,5$ ; up to  $T_{mb} = 119\text{ }^{\circ}\text{C}$

square-wave;  $\delta = 0,5$ ; at  $T_{mb} = 125\text{ }^{\circ}\text{C}$

$I_{F(AV)}$	max.	25	A
$I_{F(AV)}$	max.	23	A
$I_{F(AV)}$	max.	28	A
$I_{F(AV)}$	max.	23	A

R.M.S. forward current

$I_{F(RMS)}$	max.	40	A
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Repetitive peak forward current

$I_{FRM}$	max.	320	A
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Non-repetitive peak forward current

$t = 10\text{ ms}$ ; half sine-wave;  $T_j = 150\text{ }^{\circ}\text{C}$  prior to surge;

with reapplied  $V_{RWMmax}$

$I_{FSM}$	max.	320	A
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$I^2t$  for fusing ( $t = 10\text{ ms}$ )

$I^2t$	max.	500	$\text{A}^2\text{s}$
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### Temperatures

Storage temperature

$T_{stg}$		-55 to +150	$^{\circ}\text{C}$
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Junction temperature

$T_j$	max.	150	$^{\circ}\text{C}$
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### THERMAL RESISTANCE

From junction to mounting base

$R_{th\ j-mb}$	=	1,0	$^{\circ}\text{C/W}$
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From mounting base to heatsink

a. with heatsink compound

$R_{th\ mb-h}$	=	0,3	$^{\circ}\text{C/W}$
----------------	---	-----	----------------------

b. without heatsink compound

$R_{th\ mb-h}$	=	0,5	$^{\circ}\text{C/W}$
----------------	---	-----	----------------------

Transient thermal impedance:  $t = 1\text{ ms}$

$Z_{th\ j-mb}$	=	0,2	$^{\circ}\text{C/W}$
----------------	---	-----	----------------------

### MOUNTING INSTRUCTIONS

The top connector should neither be bent nor twisted; it should be soldered into the circuit so that there is no strain on it.

During soldering the heat conduction to the junction should be kept to a minimum.

\* To ensure thermal stability:  $R_{th\ j-a} \leq 6\text{ }^{\circ}\text{C/W}$  (continuous reverse voltage).

CHARACTERISTICS

Forward voltage

$I_F = 20 \text{ A}; T_j = 100 \text{ }^\circ\text{C}$

$V_F < 0,85 \text{ V}^*$

$I_F = 100 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_F < 1,3 \text{ V}^*$

Reverse current

$V_R = V_{RWMmax}; T_j = 100 \text{ }^\circ\text{C}$

$I_R < 1,5 \text{ mA}$

Reverse recovery when switched from

$I_F = 1 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 50 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

$t_{rr} < 50 \text{ ns}$

Recovery time

$I_F = 2 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 20 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

$Q_s < 20 \text{ nC}$

Recovered charge

Forward recovery when switched to  $I_F = 10 \text{ A}$   
with  $dI_F/dt = 10 \text{ A}/\mu\text{s}$

$V_{fr} \text{ typ. } 1,0 \text{ V}$

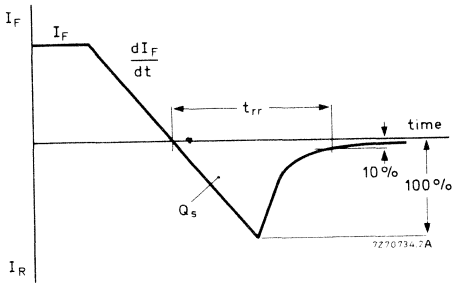


Fig. 2 Definitions of  $t_{rr}$  and  $Q_s$ .

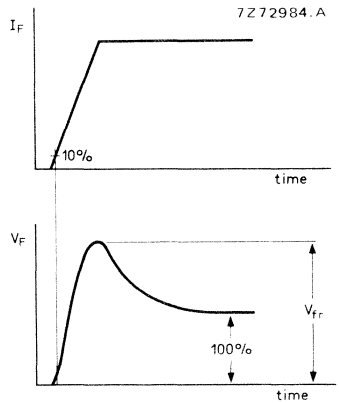


Fig. 3 Definition of  $V_{fr}$ .

\* Measured under pulse conditions to avoid excessive dissipation.

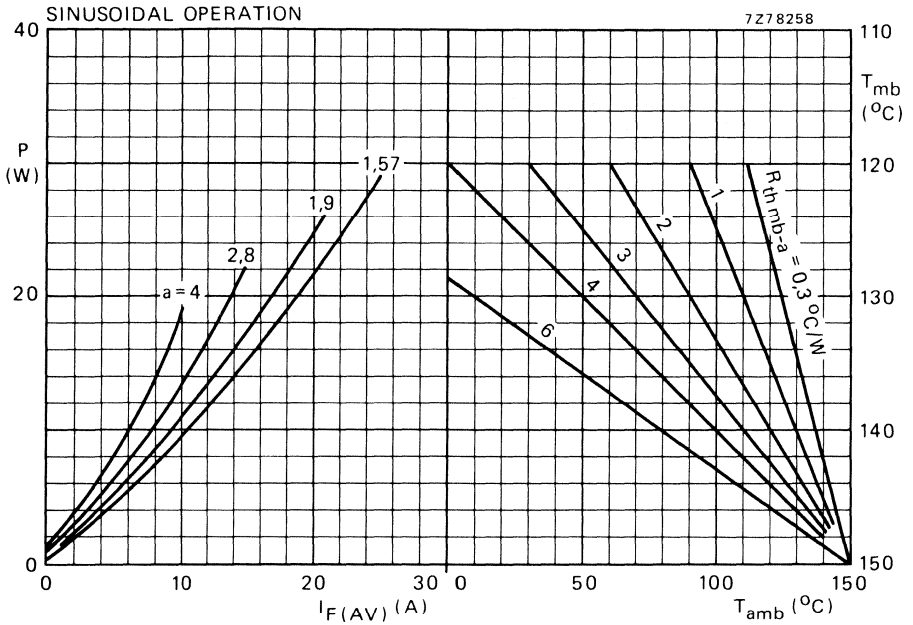


Fig. 4 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.  
 $P$  = power including reverse current losses and switching losses up to  $f = 500$  kHz.  
 $a$  = form factor =  $I_{F(RMS)}/I_F(AV)$ .



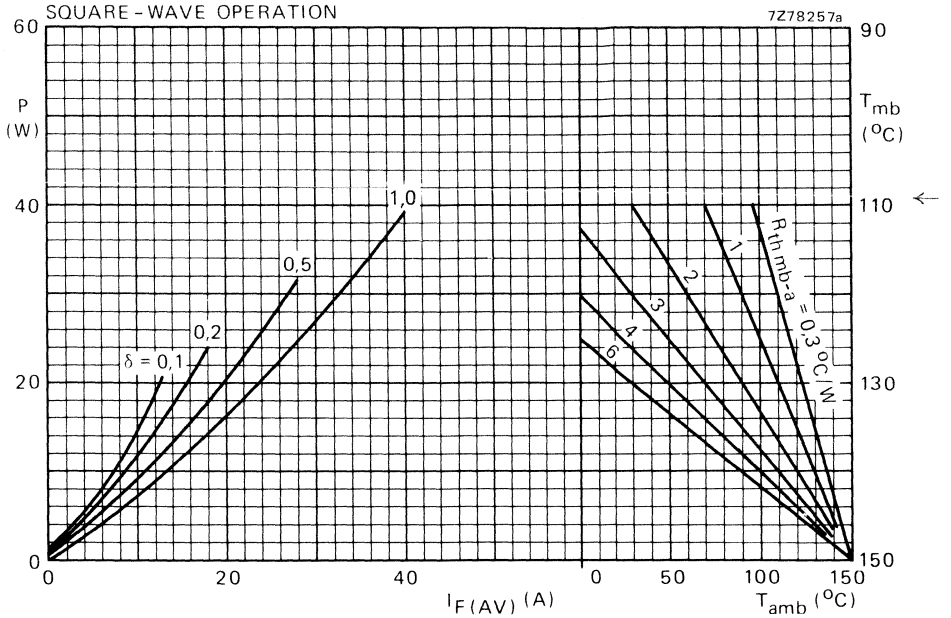
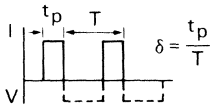


Fig. 5 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

P = power including reverse current losses and switching losses up to  $f = 500$  kHz.



$$I_F(AV) = I_F(RMS) \times \sqrt{\delta}$$

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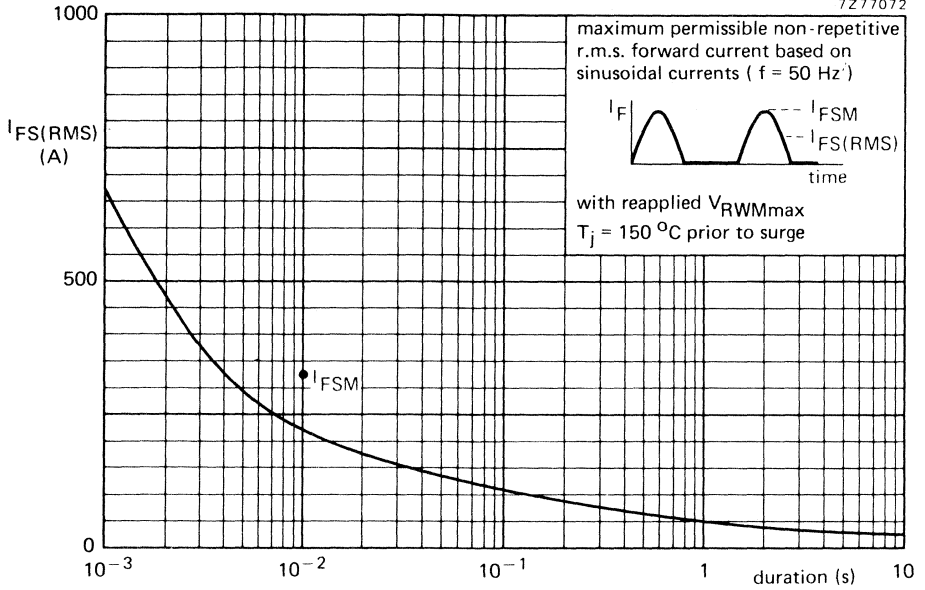


Fig. 6.

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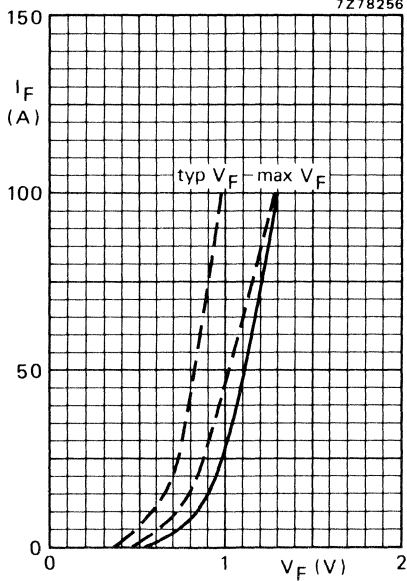


Fig. 7 ———  $T_j = 25^\circ\text{C}$ ; - - -  $T_j = 100^\circ\text{C}$ .

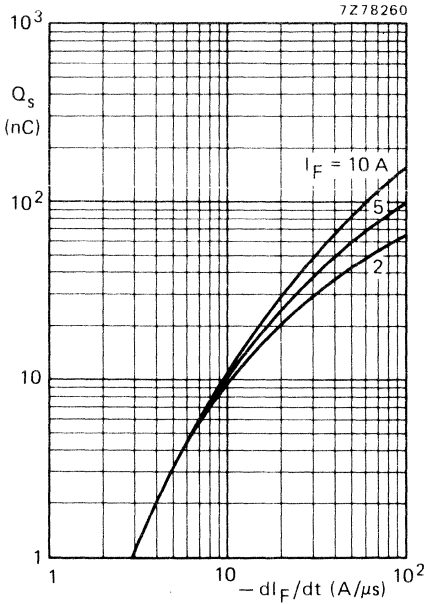


Fig. 8  $T_j = 25\text{ }^\circ\text{C}$ ; maximum values.

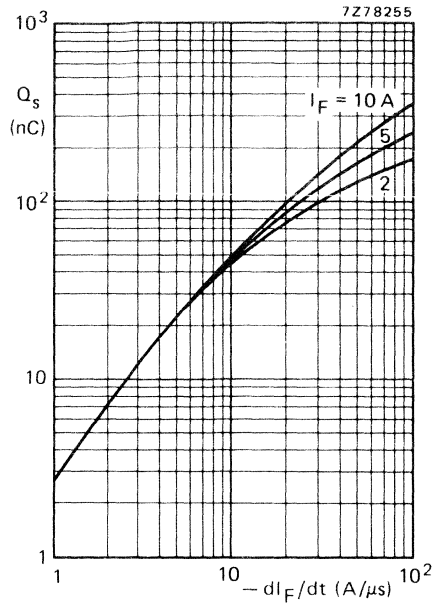


Fig. 9  $T_j = 100\text{ }^\circ\text{C}$ ; maximum values.

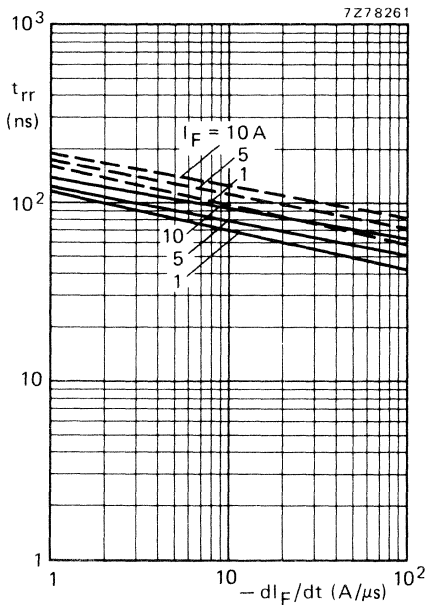
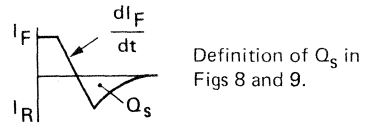


Fig. 10 Maximum values; —  $T_j = 25\text{ }^\circ\text{C}$ ;  
 ---  $T_j = 100\text{ }^\circ\text{C}$ .



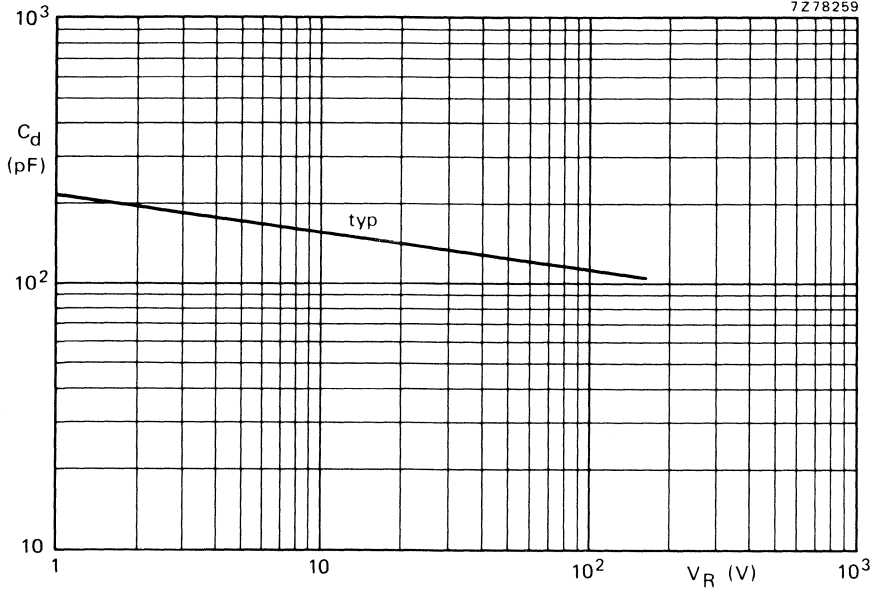


Fig. 11  $f = 1 \text{ MHz}$ ;  $T_j = 25 \text{ }^\circ\text{C}$ .

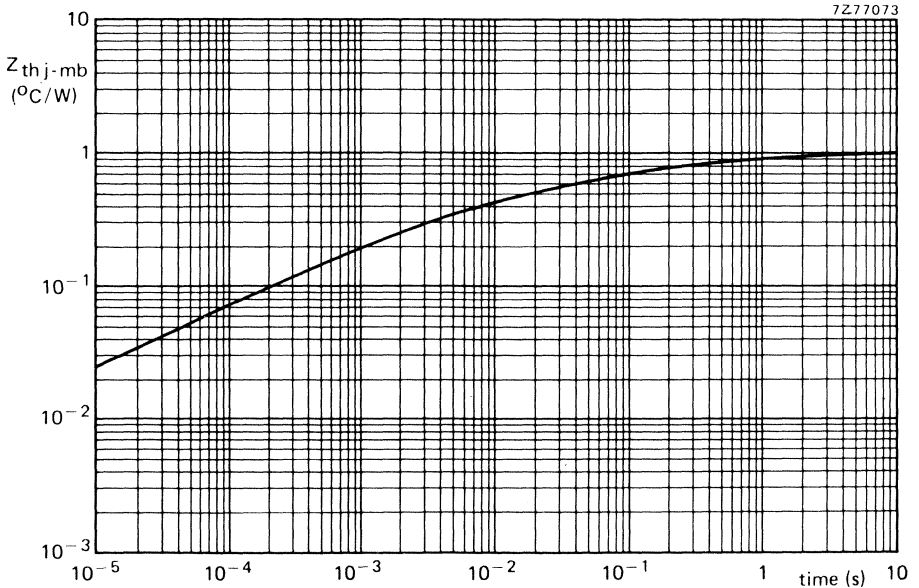


Fig. 12.

VERY FAST RECOVERY RECTIFIER DIODES



Glass-passivated, high-efficiency rectifier diodes in DO-5 metal envelopes, featuring low forward voltage drop, very fast reverse recovery times, very low stored charge and non-snap-off. They are intended for use in switched-mode power supplies and high-frequency inverter circuits in general, where low conduction and switching losses are essential. The series consists of normal polarity (cathode-to-stud) types.

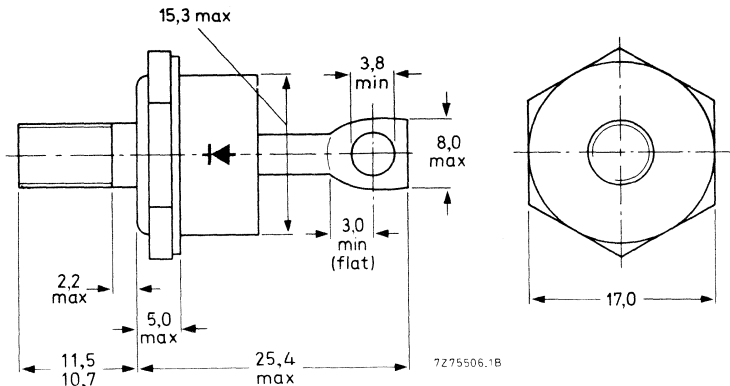
QUICK REFERENCE DATA

		BYW92-50   100   150			
Repetitive peak reverse voltage	$V_{RRM}$	max.	50   100   150	V	
Average forward current	$I_{F(AV)}$	max.	35	A	
Forward voltage	$V_F$	<	0,95	V	
Reverse recovery time	$t_{rr}$	<	50	ns	

MECHANICAL DATA

Dimensions in mm

Fig. 1 DO-5: with metric M6 stud ( $\phi$  6 mm); e.g. BYW92-50.  
with  $\frac{1}{4}$  in x 28UNF stud ( $\phi$  6,35mm); e.g. BYW92-50U.



Net mass: 22 g  
Diameter of clearance hole: max. 6,5 mm  
Torque on nut: min. 1,7 Nm (17 kg cm)  
max. 3,5 Nm (35 kg cm)

Supplied with device: 1 nut, 1 lock washer  
Nut dimensions across the flats;  
M6: 10 mm  
 $\frac{1}{4}$  in x 28UNF: 11,1 mm  
Supplied on request: accessories 56264A  
(mica washer, insulating ring, tag)

# BYW92 SERIES

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

### Voltages\*

		BYW92-50	100	150
Non-repetitive peak reverse voltage	$V_{RSM}$	max. 50	100	150 V
Repetitive peak reverse voltage	$V_{RRM}$	max. 50	100	150 V
Crest working reverse voltage	$V_{RWM}$	max. 50	100	150 V
Continuous reverse voltage	$V_R$	max. 50	100	150 V

### Currents

Average forward current; switching losses negligible up to 500 kHz

sinusoidal; up to  $T_{mb} = 105\text{ }^\circ\text{C}$

$I_{F(AV)}$  max. 35 A

sinusoidal; at  $T_{mb} = 125\text{ }^\circ\text{C}$

$I_{F(AV)}$  max. 23 A

square wave;  $\delta = 0,5$ ; up to  $T_{mb} = 102\text{ }^\circ\text{C}$

$I_{F(AV)}$  max. 40 A

square wave;  $\delta = 0,5$ ; at  $T_{mb} = 125\text{ }^\circ\text{C}$

$I_{F(AV)}$  max. 23 A

R.M.S. forward current

$I_{F(RMS)}$  max. 55 A

Repetitive peak forward current

$I_{FRM}$  max. 500 A

Non-repetitive peak forward current;  $t = 10\text{ ms}$ ; half sine-wave;

$T_j = 150\text{ }^\circ\text{C}$  prior to surge; with re-applied  $V_{RWMmax}$

$I_{FSM}$  max. 500 A

$I^2 t$  for fusing ( $t = 10\text{ ms}$ )

$I^2 t$  max. 1250  $\text{A}^2\text{ s}$

Temperatures

Storage temperature

$T_{stg}$   $-55$  to  $+150\text{ }^\circ\text{C}$

Junction temperature

$T_j$  max. 150  $^\circ\text{C}$

## THERMAL RESISTANCE

From junction to mounting base

$R_{th\ j-mb} = 1,0\text{ }^\circ\text{C/W}$

From mounting base to heatsink

a. with heatsink compound

$R_{th\ mb-h} = 0,3\text{ }^\circ\text{C/W}$

b. without heatsink compound

$R_{th\ mb-h} = 0,5\text{ }^\circ\text{C/W}$

Transient thermal impedance;  $t = 1\text{ ms}$

$Z_{th\ j-mb} = 0,2\text{ }^\circ\text{C/W}$

## MOUNTING INSTRUCTIONS

The top connector should neither be bent nor twisted; it should be soldered into the circuit so that there is no strain on it.

During soldering the heat conduction to the junction should be kept to a minimum.

\* To ensure thermal stability:  $R_{th\ j-a} \leq 6\text{ }^\circ\text{C/W}$  (continuous reverse voltage).

**CHARACTERISTICS**

Forward voltage

$I_F = 35 \text{ A}; T_j = 100 \text{ }^\circ\text{C}$   
 $I_F = 100 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_F < 0,95 \text{ V}^*$   
 $V_F < 1,3 \text{ V}^*$

Reverse current

$V_R = V_{RWMmax}; T_j = 100 \text{ }^\circ\text{C}$

$I_R < 2,5 \text{ mA}$

Reverse recovery when switched from

$I_F = 1 \text{ A}$  to  $V_R \geq 30 \text{ V}$  with  $-dI_F/dt = 50 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$   
 Recovery time

$t_{rr} < 50 \text{ ns}$

$I_F = 2 \text{ A}$  to  $V_R \geq 30 \text{ V}$  with  $-dI_F/dt = 20 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$   
 Recovered charge

$Q_s < 20 \text{ nC}$

Forward recovery when switched to  $I_F = 10 \text{ A}$   
 with  $dI_F/dt = 10 \text{ A}/\mu\text{s}$

$V_{fr} \text{ typ. } 1,0 \text{ V}$

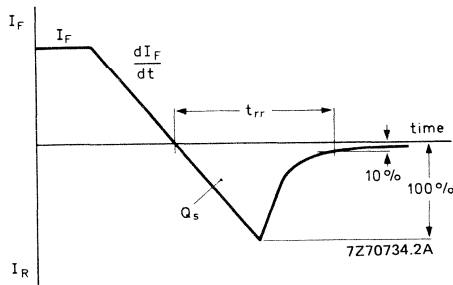


Fig. 2 Definitions of  $t_{rr}$  and  $Q_s$ .

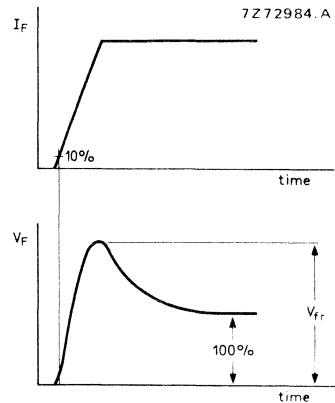


Fig. 3 Definition of  $V_{fr}$ .

\* Measured under pulse conditions to avoid excessive dissipation.

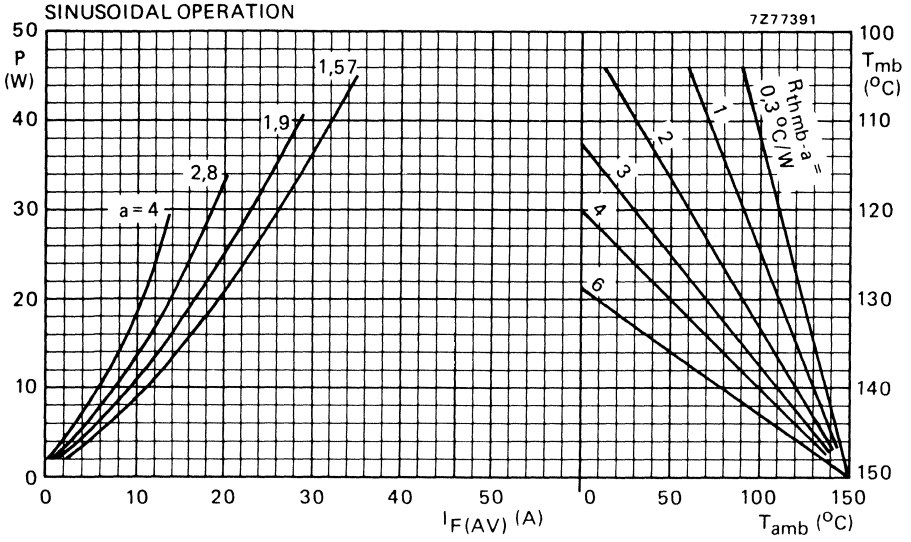


Fig. 4  $P$  = power including reverse current losses and switching losses up to  $f = 500$  kHz.  
 $a$  = form factor =  $I_{F(RMS)}/I_{F(AV)}$ .



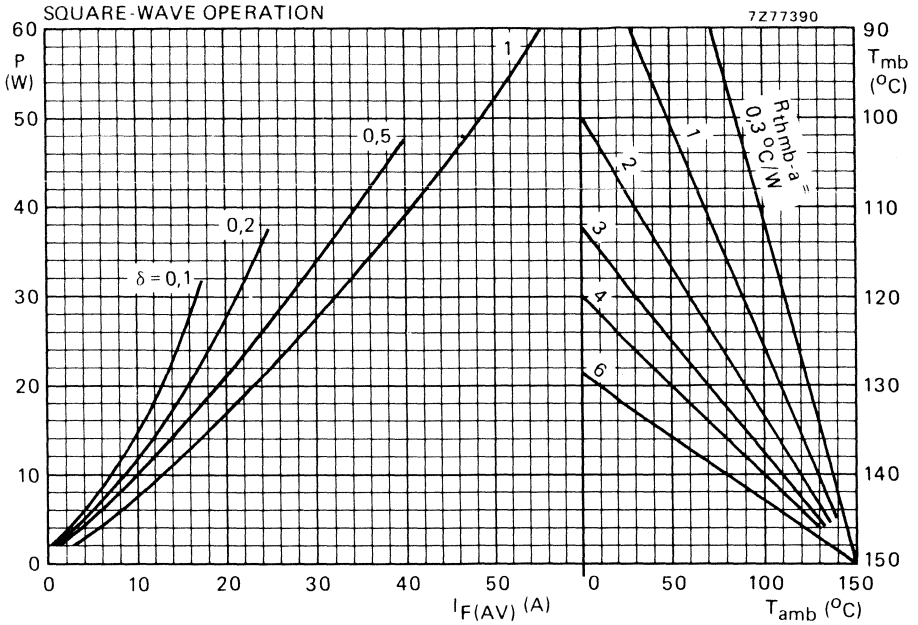


Fig. 5 P = power including reverse current losses and switching losses up to  $f = 500 \text{ kHz}$ .

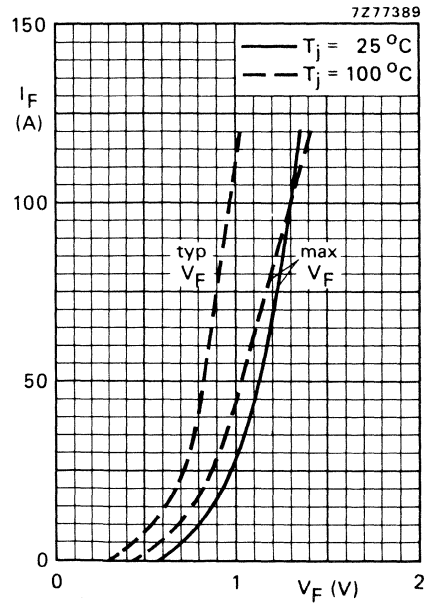
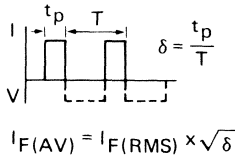


Fig. 6.

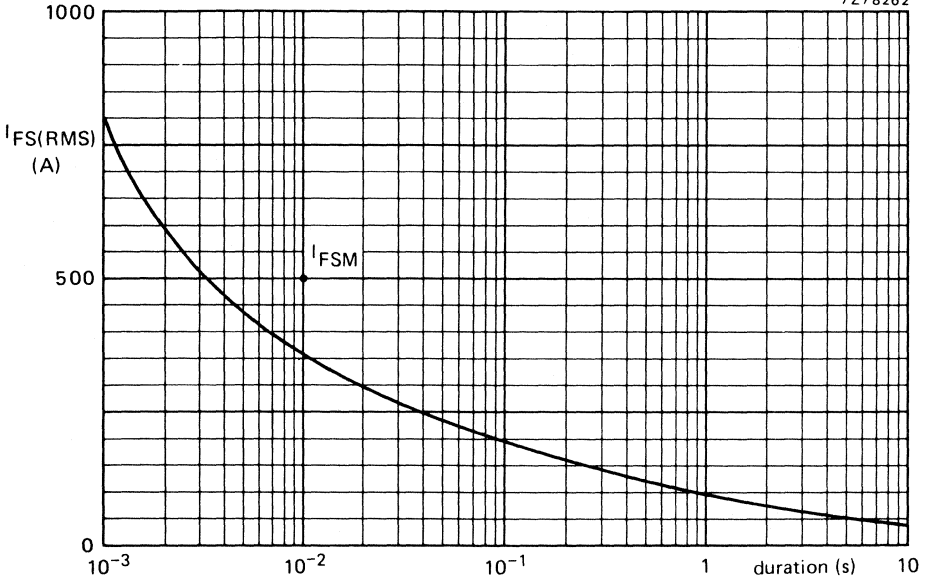
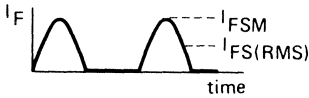


Fig. 7 Maximum permissible non-repetitive r.m.s. forward current based on sinusoidal currents ( $f = 50$  Hz);  $T_j = 150$  °C prior to surge; with reapplied  $V_{RWMmax}$ .



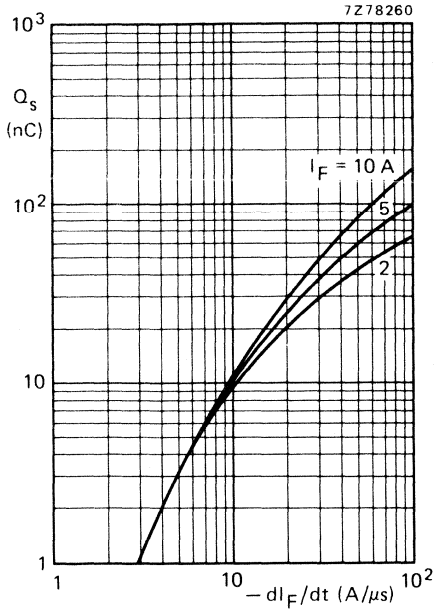


Fig. 8  $T_j = 25 \text{ }^\circ\text{C}$ ; maximum values.

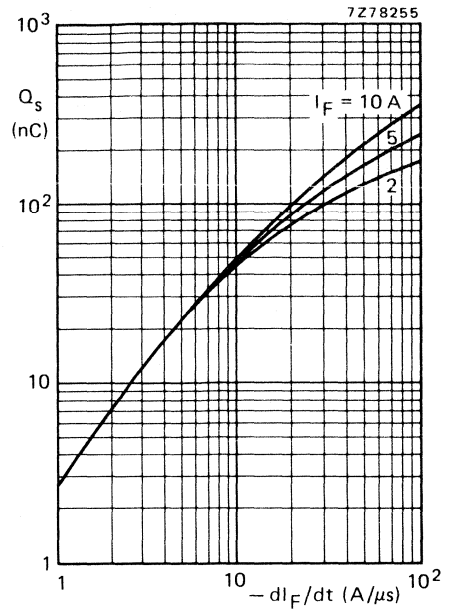


Fig. 9  $T_j = 100 \text{ }^\circ\text{C}$ ; maximum values.

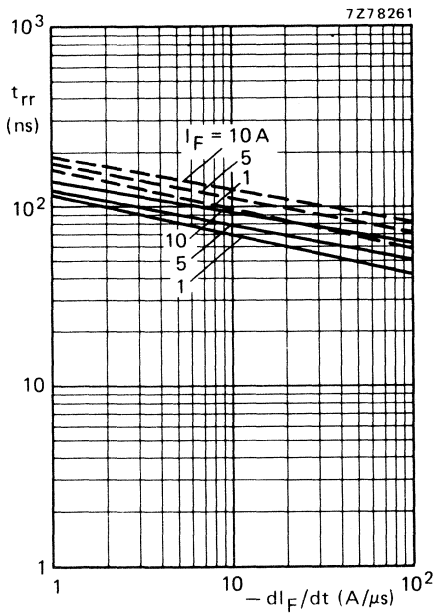
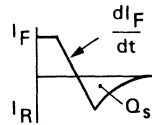


Fig. 10 Maximum values; —  $T_j = 25 \text{ }^\circ\text{C}$ ;  
 - - -  $T_j = 100 \text{ }^\circ\text{C}$ .



Definition of  $Q_s$  in  
 Figs 8 and 9.

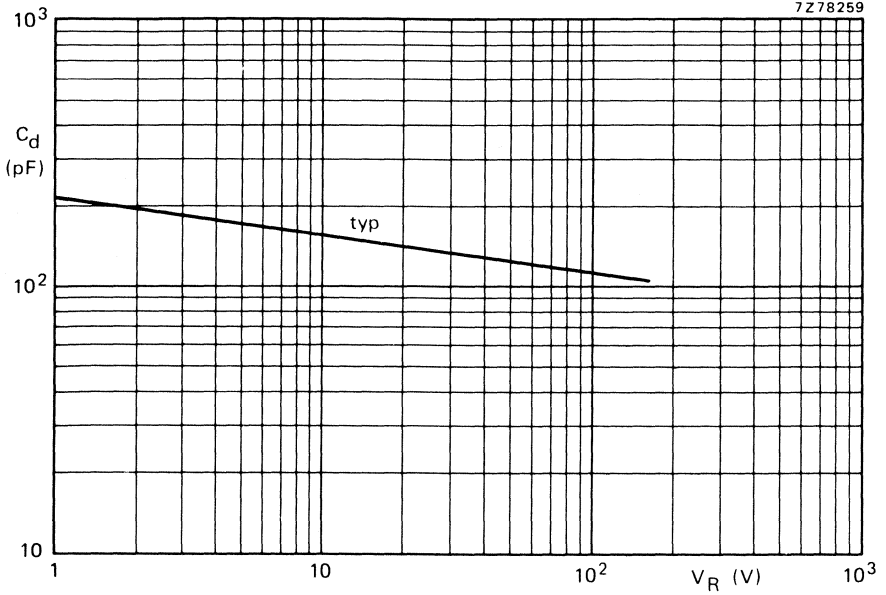


Fig. 11  $f = 1$  MHz;  $T_j = 25$  °C.

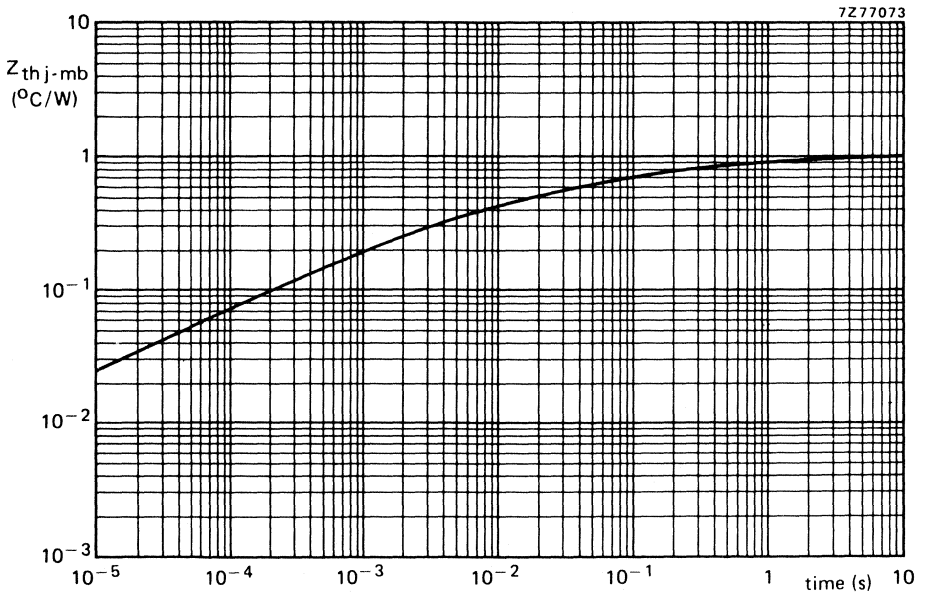


Fig. 12.

SILICON RECTIFIER DIODES

Also available to BS9331-F131

The BYX22-600 and BYX22-1200 are silicon diodes in a metal DO-1 envelope, intended for power rectifier applications up to 1.4 A.

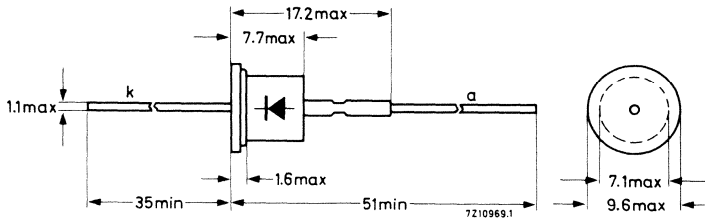
QUICK REFERENCE DATA

		BYX22-600		1200	
Crest working reverse voltage	$V_{RWM}$	max.	400	800	V
Repetitive peak reverse voltage	$V_{RRM}$	max.	600	1200	V
Average forward current	$I_F(AV)$	max.	1.4		A
Non-repetitive peak forward current	$I_{FSM}$	max.	40		A

MECHANICAL DATA

Dimensions in mm

DO-1



MOUNTING METHODS see page 3

# BYX22 SERIES

**RATINGS** Limiting values in accordance with the Absolute Maximum System (IEC 134)

All information applies to frequencies up to 400Hz

## Voltages

		BYX22-600	1200
Crest working reverse voltage	$V_{RWM}$	max. 400	800 V
Repetitive peak reverse voltage ( $d \leq 1\%$ )	$V_{RRM}$	max. 600	1200 V
Non repetitive peak reverse voltage ( $t \leq 10$ ms)	$V_{RSM}$	max. 600	1200 V

## Currents

Average forward current (averaged over any 20 ms period) for R-load up to $T_{amb} = 30^\circ\text{C}$	$I_{FAV}$	max.	1.4 A
Forward current (d. c.) up to $T_{amb} = 30^\circ\text{C}$	$I_F$	max.	1.6 A
Repetitive peak forward current	$I_{FRM}$	max.	15 A
Non repetitive peak forward current $t = 10$ ms; $T_j = 150^\circ\text{C}$ (see page 6)	$I_{FSM}$	max.	40 A

## Temperatures

Storage temperature	$T_{stg}$	-65 to +150	$^\circ\text{C}$
Ambient temperature	$T_{amb}$	max. 150	$^\circ\text{C}$

## **THERMAL RESISTANCE**

From junction to ambient	$R_{th\ j-a}$	See page 3
--------------------------	---------------	------------

## **CHARACTERISTICS**

Forward voltage at $I_F = 5\text{A}$ ; $T_{amb} = 25^\circ\text{C}$	$V_F$	<	1.5 V <sup>1)</sup>
Reverse current at $V_R = V_{RWMmax}$ ; $T_{amb} = 125^\circ\text{C}$	$I_R$	<	120 $\mu\text{A}$

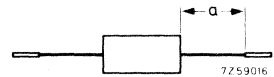
<sup>1)</sup> Measured under pulsed conditions to avoid excessive dissipation.

**THERMAL RESISTANCE**

Effect of mounting on thermal resistance  $R_{th\ j-a}$

The quoted values apply when no other leads run to the tie-points. If leads of other dissipating components share the same tie-points, the thermal resistance will be higher than that quoted.

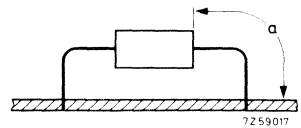
1. Mounted to solder tags at a lead-length  $a = 10$  mm.  $R_{th\ j-a} = 60$  °C/W



2. Mounted to solder tags at  $a =$  maximum lead-length.  $R_{th\ j-a} = 70$  °C/W

3. Mounted on printed-wiring board at  $a =$  maximum lead-length.  $R_{th\ j-a} = 80$  °C/W

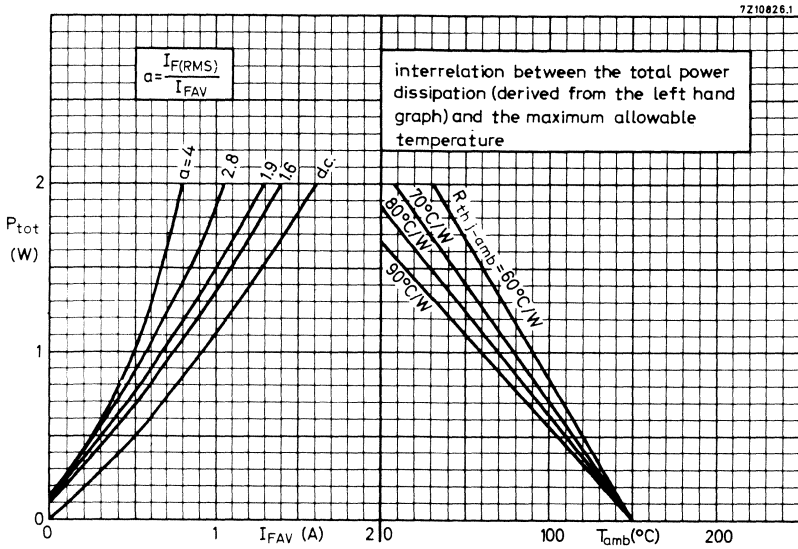
4. Mounted on printed-wiring board at a lead-length  $a = 10$  mm.  $R_{th\ j-a} = 90$  °C/W



**SOLDERING AND MOUNTING NOTES**

1. At a soldering iron or bath temperature of up to 245 °C, the maximum permissible soldering time is 10 s if the joint is 5 mm from the seal, 3 s if it is 1.5 mm from the seal.
2. At a temperature between 245 °C and 400 °C (max.), the joint must be more than 5 mm from the seal and soldering time must not exceed 5 s.
3. Leads should not be bent less than 1.5 mm from the seal; exert no axial pull when bending.

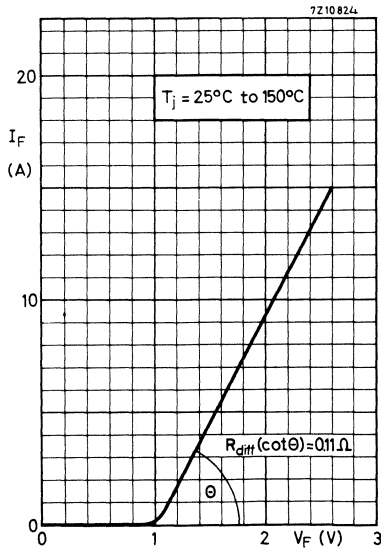
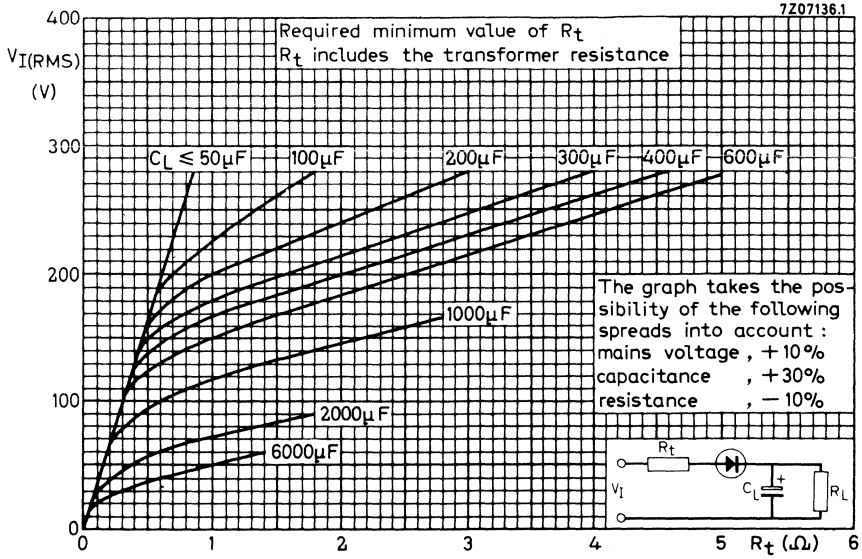
# BYX22 SERIES



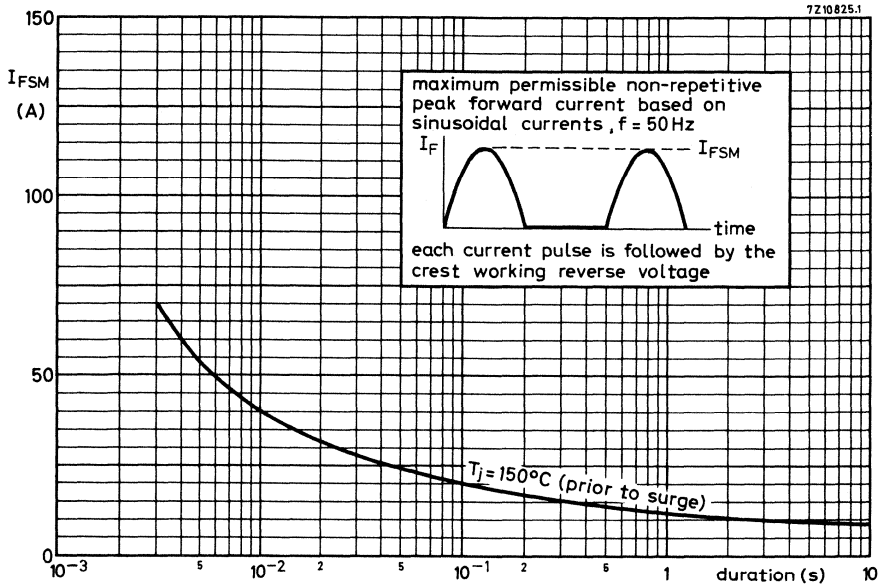
The form factor  $a = \frac{I_{F(RMS)} \text{ per diode}}{I_{FAV} \text{ per diode}}$  depends on  $n\omega R_L C_L$  and  $\frac{R_t + R_{diff}}{nR_L}$  and can be found from existing graphs.

See Application Book: RECTIFIER DIODES.





# BYX22 SERIES



CONTROLLED AVALANCHE RECTIFIER DIODES

Also available to BS9333-F003

Diffused silicon diodes in DO-4 metal envelopes, capable of absorbing transients and intended for power rectifier applications. The series consists of the following types:  
 Normal polarity (cathode to stud): BYX25-600 to BYX25-1400.  
 Reverse polarity (anode to stud): BYX25-600R to BYX25-1400R.



QUICK REFERENCE DATA

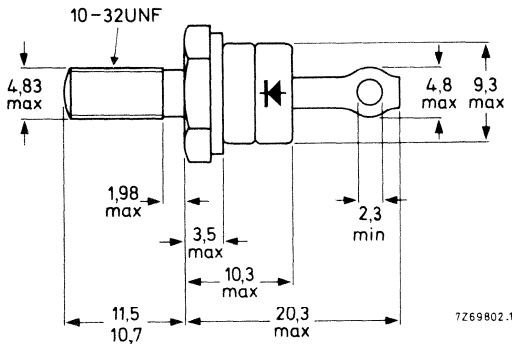
		BYX25-600(R)	800(R)	1000(R)	1200(R)	1400(R)	
Crest working reverse voltage	$V_{RWM}$	max. 600	800	1000	1200	1400	V
Reverse avalanche breakdown voltage	$V_{(BR)R}$	> 750	1000	1250	1450	1650	V
Average forward current	$I_{F(AV)}$	max. 20					A
Non-repetitive peak forward current	$I_{FSM}$	max. 360					A
Non-repetitive peak reverse power	$P_{RSM}$	max. 18					kW



MECHANICAL DATA

Dimensions in mm

Fig. 1 DO-4.



Net mass: 7 g.

Diameter of clearance hole: max. 5.2 mm.

Accessories supplied on request:

56295 (PTFE bush, 2 mica washers, plain washer, tag).

56262A (mica washer, insulating ring, plain washer).

Supplied with device: 1 nut, 1 lock washer.

Nut dimensions across the flats: 9.5 mm

The mark shown applies to the normal polarity types.

Torque on nut:  
 min. 0.9 Nm (9 kg cm),  
 max. 1.7 Nm (17 kg cm).

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC134)

→ Voltages*		BYX25-600(R)	800(R)	1000(R)	1200(R)	1400(R)	
Crest working reverse voltage	$V_{RWM}$	max. 600	800	1000	1200	1400	V
Continuous reverse voltage	$V_R$	max. 600	800	1000	1200	1400	V

## Currents

Average forward current (averaged over any 20 ms period)	$I_{F(AV)}$	max.	20	A
Repetitive peak forward current	$I_{FRM}$	max.	440	A
Non-repetitive peak forward current t = 10 ms (half sine-wave); $T_j = 175\text{ }^\circ\text{C}$ prior to surge; with reapplied $V_{RWMmax}$	$I_{FSM}$	max.	360	A
$I^2 t$ for fusing	$I^2 t$	max.	650	$\text{A}^2\text{s}$

## Reverse power dissipation

Average reverse power dissipation (averaged over any 20 ms period); $T_j = 175\text{ }^\circ\text{C}$	$P_R(AV)$	max.	38	W
Repetitive peak reverse power dissipation t = 10 $\mu\text{s}$ (square-wave; f = 50 Hz); $T_j = 175\text{ }^\circ\text{C}$	$P_{RRM}$	max.	3	kW
Non-repetitive peak reverse power dissipation t = 10 $\mu\text{s}$ (square-wave) $T_j = 25\text{ }^\circ\text{C}$ prior to surge	$P_{RSM}$	max.	18	kW
$T_j = 175\text{ }^\circ\text{C}$ prior to surge	$P_{RSM}$	max.	3	kW

## Temperatures

Storage temperature	$T_{stg}$		-55 to +175	$^\circ\text{C}$
Junction temperature	$T_j$	max.	175	$^\circ\text{C}$

\*To ensure thermal stability:  $R_{th\ j-a} < 5\text{ }^\circ\text{C/W}$  (a.c.)

**THERMAL RESISTANCE**

From junction to ambient in free air	$R_{th\ j-a}$	=	50	°C/W
From junction to mounting base	$R_{th\ j-mb}$	=	1.3	°C/W
From mounting base to heatsink	$R_{th\ mb-h}$	=	0.5	°C/W

**CHARACTERISTICS**

		BYX25-600(R)	800(R)	1000(R)	1200(R)	1400(R)	←
Forward voltage							
$I_F = 50\text{ A}; T_j = 25\text{ °C}$	$V_F$	< 1.8	1.8	1.8	1.8	1.8	V*
Reverse avalanche breakdown voltage							
$I_R = 5\text{ mA}; T_j = 25\text{ °C}$	$V_{(BR)R}$	> 750	1000	1250	1450	1650	V
		< 2000	2000	2000	2200	2400	V
Peak reverse current							
$V_R = V_{RWMmax}; T_j = 125\text{ °C}$	$I_R$	< 1.0	0.8	0.6	0.5	0.5	mA

\*Measured under pulse conditions to avoid excessive dissipation.

## OPERATING NOTES

### 1. Voltage sharing of series connected controlled avalanche diodes.

If diodes with avalanche characteristics are connected in series, the usual R and C elements for voltage sharing can be omitted.

### 2. The top connector should not be bent; it should be soldered into the circuit so that there is no strain on it.

During soldering the heat conduction to the junction should be kept to a minimum by using a thermal shunt.

### Determination of the heatsink thermal resistance

Example:

Assume a diode, used in a three phase rectifier circuit.

frequency	$f = 50 \text{ Hz}$
average forward current	$I_{FAV} = 10 \text{ A (per diode)}$
ambient temperature	$T_{amb} = 40 \text{ }^\circ\text{C}$
repetitive peak reverse power dissipation in the avalanche region	$P_{RRM} = 2 \text{ kW (per diode)}$
duration of $P_{RRM}$	$t = 40 \text{ } \mu\text{s}$

From the left hand part of the upper graph on page 5 it follows that at  $I_{FAV} = 10 \text{ A}$  in a three phase rectifier circuit the average forward power + average leakage power =  $19.5 \text{ W}$  per diode (point A). The average reverse power in the avalanche region, averaged over any cycle, follows from:

$$P_{RAV} = \delta \times P_{RRM}, \text{ where the duty cycle } \delta = \frac{40 \text{ } \mu\text{s}}{20 \text{ ms}} = 0.002$$

Thus:  $P_{RAV} = 0.002 \times 2 \text{ kW} = 4 \text{ W}$

Therefore the total device power dissipation  $P_{tot} = (19.5 + 4) \text{ W} = 23.5 \text{ W}$  (point B).

In order to avoid excessive peak junction temperatures resulting from the pulse character of the repetitive peak reverse power in the avalanche region, the value of the maximum junction temperature should be reduced. If the repetitive peak reverse power in the avalanche region is  $2 \text{ kW}$ ;  $t = 40 \text{ } \mu\text{s}$ ;  $f = 50 \text{ Hz}$ , the maximum allowable junction temperature should be  $163 \text{ }^\circ\text{C}$  instead of  $175 \text{ }^\circ\text{C}$ , thus  $12 \text{ }^\circ\text{C}$  lower (see the lower graph on page 5).

Allowance can be made for this by assuming an ambient temperature  $12 \text{ }^\circ\text{C}$  higher than before, in this case  $52 \text{ }^\circ\text{C}$  instead of  $40 \text{ }^\circ\text{C}$ .

Using this in the curve leads to a thermal resistance

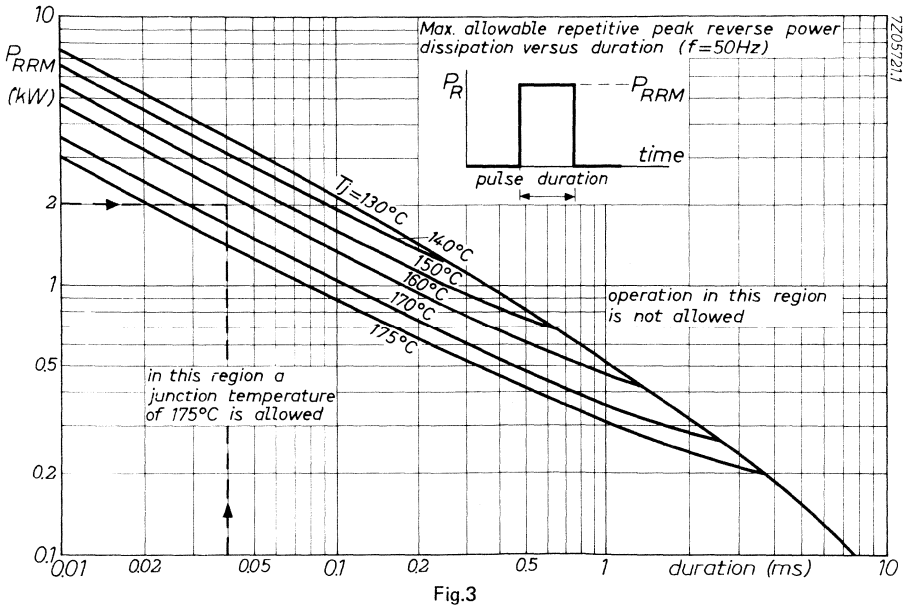
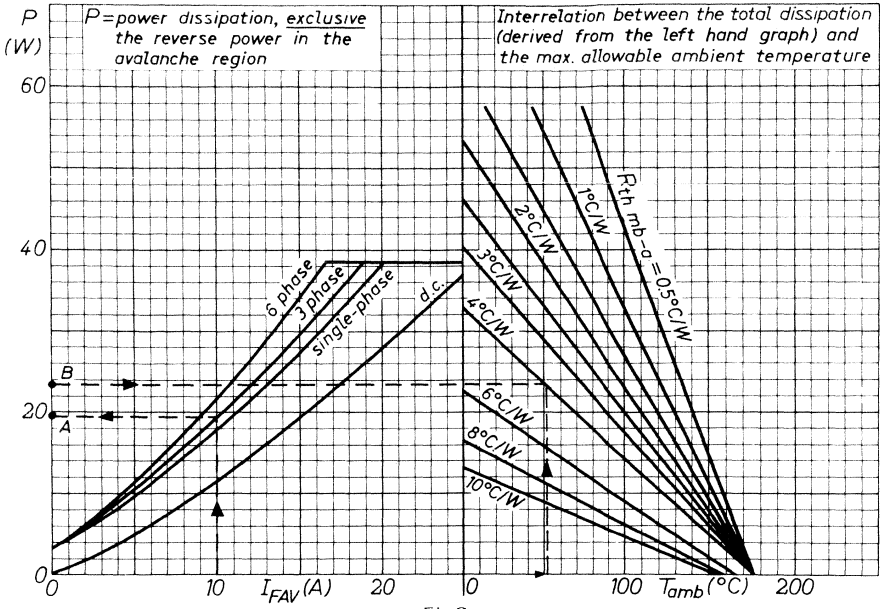
$$R_{th \text{ mb-a}} \approx 4 \text{ }^\circ\text{C/W}$$

The contact thermal resistance  $R_{th \text{ mb-h}} = 0.5 \text{ }^\circ\text{C/W}$

Hence the heatsink thermal resistance should be:

$$R_{th \text{ h-a}} = R_{th \text{ mb-a}} - R_{th \text{ mb-h}} = (4 - 0.5) \text{ }^\circ\text{C/W} = 3.5 \text{ }^\circ\text{C/W}$$

7205733.2



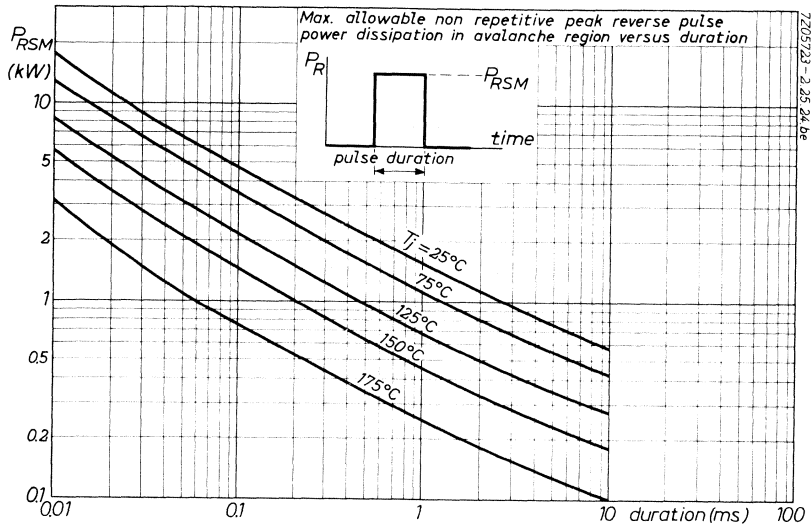


Fig.4

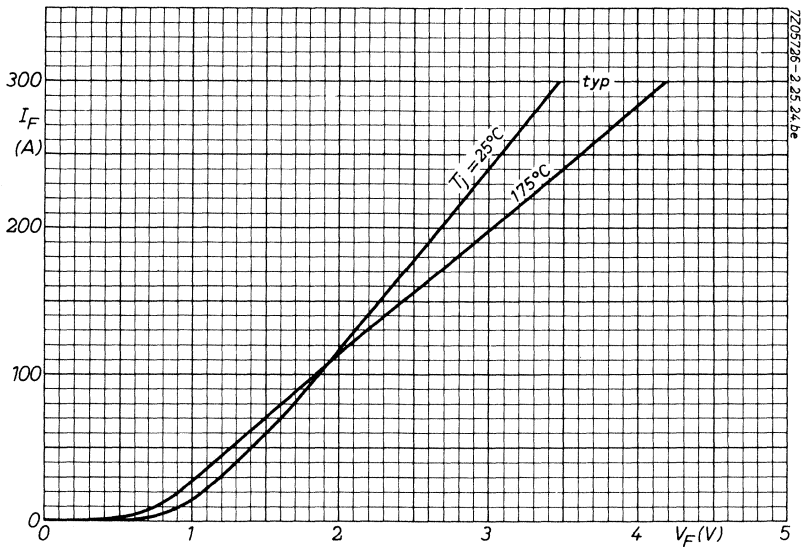


Fig.5



7272545.1

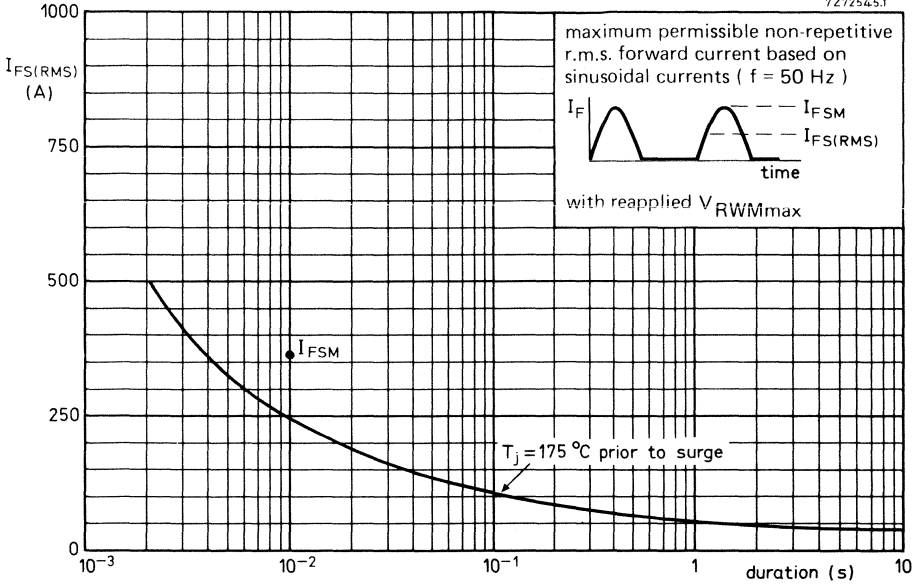


Fig.6



FAST SOFT-RECOVERY RECTIFIER DIODES

- With controlled avalanche

Also available to BS9333-F002

Diffused silicon diodes in DO-4 metal envelopes, capable of absorbing transients. They are primarily intended for use in high-frequency power supplies, thyristor inverters and multi-phase power rectifier applications.

The series consists of the following types :

Normal polarity (cathode to stud): BYX30-200 to BYX30-600

Reverse polarity (anode to stud): BYX30-200R to BYX30-600R.

QUICK REFERENCE DATA

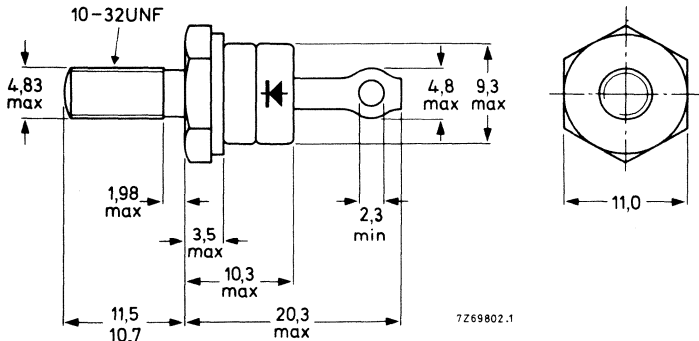
	BYX30-200(R)	300(R)	400(R)	500(R)	600(R)
Crest working reverse voltage $V_{RWM}$	max. 200	300	400	500	600 V
Reverse avalanche breakdown voltage $V_{(BR)R}$	> 250	375	500	625	750 V
Average forward current $I_{F(AV)}$		max.	14		A
Non-repetitive peak forward current $I_{FSM}$		max.	250		A
Non-repetitive peak reverse power $P_{RSM}$		max.	18		kW
Reverse recovery time $t_{rr}$		<	200		ns

MECHANICAL DATA

Dimensions in mm

DO-4; Supplied with device: 1 nut, 1 lock-washer

Nut dimensions across the flats: 9.5 mm



Net mass : 7g

Diameter of clearance hole : max. 5.2 mm

Accessories supplied on request :

56295 (PTFE bush, 2 mica washers, plain washer, tag)

Torque on nut : min. 0.9 Nm  
(9 kg cm)

max. 1.7 Nm  
(17 kg cm)

The mark shown applies to the normal polarity types.

# BYX30 SERIES

**RATINGS** Limiting values in accordance with the Absolute Maximum System (IEC134)

Voltages <sup>1)</sup>		BYX30-200(R)	300(R)	400(R)	500(R)	600(R)
Crest working reverse voltage	$V_{RWM}$	max. 200	300	400	500	600
Continuous reverse voltage	$V_R$	max. 200	300	400	500	600

## Currents

Average forward current (averaged over any 20 ms period) up to $T_{mb} = 100\text{ }^\circ\text{C}$ at $T_{mb} = 125\text{ }^\circ\text{C}$	$I_F(AV)$	max.	14	A
	$I_F(AV)$	max.	7.5	A
R. M. S. forward current	$I_F(RMS)$	max.	22	A
Repetitive peak forward current	$I_{FRM}$	max.	310	A
Non-repetitive peak forward current ( $t = 10\text{ ms}$ ; half-sinewave) $T_j = 150\text{ }^\circ\text{C}$ prior to surge; with reapplied $V_{RWM}$ max.	$I_{FSM}$	max.	250	A
$I^2t$ for fusing ( $t = 10\text{ ms}$ )	$I^2t$	max.	312	$A^2s$

## Reverse power dissipation

Repetitive peak reverse power dissipation $t = 10\text{ }\mu\text{s}$ (square wave; $f = 50\text{ Hz}$ ) $T_j = 150\text{ }^\circ\text{C}$	$P_{RRM}$	max.	5.5	kW
Non-repetitive peak reverse power dissipation $t = 10\text{ }\mu\text{s}$ (square wave) $T_j = 25\text{ }^\circ\text{C}$ prior to surge $T_j = 150\text{ }^\circ\text{C}$ prior to surge	$P_{RSM}$ $P_{RSM}$	max.	18	kW
		max.	5.5	kW

## Temperatures

Storage temperature	$T_{stg}$	-55 to +150	$^\circ\text{C}$
Junction temperature	$T_j$	max. 150	$^\circ\text{C}$

## THERMAL RESISTANCE

From junction to ambient in free air	$R_{th\ j-a}$	=	50	$^\circ\text{C/W}$
From junction to mounting base	$R_{th\ j-mb}$	=	1.3	$^\circ\text{C/W}$
From mounting base to heatsink	$R_{th\ mb-h}$	=	0.5	$^\circ\text{C/W}$

<sup>1)</sup> To ensure thermal stability:  $R_{th\ j-a} < 2.5\text{ }^\circ\text{C/W}$  (continuous reverse voltage) or  $< 5\text{ }^\circ\text{C/W}$  (a. c.).

For smaller heatsinks  $T_j$  max should be derated. For a. c. see page 5.

For continuous reverse voltage: if  $R_{th\ j-a} = 5\text{ }^\circ\text{C/W}$ , then  $T_j$  max = 135  $^\circ\text{C}$ .

if  $R_{th\ j-a} = 10\text{ }^\circ\text{C/W}$ , then  $T_j$  max = 120  $^\circ\text{C}$ .

**CHARACTERISTICS**

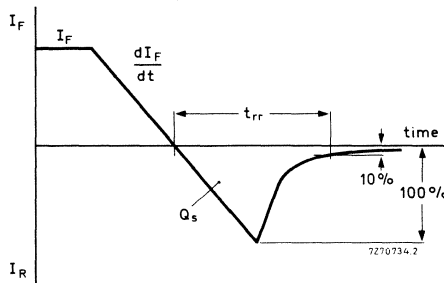
	BYX30-200(R)	300(R)	400(R)	500(R)	600(R)	
<u>Forward voltage</u>						
$I_F = 50 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$	$V_F < 3.2$	3.2	3.2	3.2	3.2	V <sup>1)</sup>
<u>Reverse breakdown voltage</u>						
$I_R = 5 \text{ mA}; T_j = 25 \text{ }^\circ\text{C}$	$V_{(BR)R} > 250$	375	500	625	750	V
	$< 1050$	1050	1050	1050	1050	V
<u>Reverse current</u>						
$V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$	$I_R < 4.0$	4.0	4.0	4.0	4.0	mA

Reverse recovery charge when switched from

$I_F = 2 \text{ A to } V_R \geq 30 \text{ V};$ with $-dI_F/dt = 100 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$	$Q_s < 0.70$	$\mu\text{C}$
--	--------------	---------------

Reverse recovery time when switched from

$I_F = 1 \text{ A to } V_R \geq 30 \text{ V};$ $-dI_F/dt = 50 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$	$t_{rr} < 200$	ns
--	----------------	----



**OPERATING NOTES**

1. Square-wave operation

When  $I_F$  has been flowing sufficiently long for the steady state to be established, there will be a charge due to minority carriers present. Before the device can block in the reverse direction this charge must be extracted. This extraction takes the form of a reverse transient (see figure above). The majority of the power dissipation due to the reverse transient occurs during fall time as the rectifier gradually becomes reverse biased, and the mean power will be proportional to the operating frequency. The mean value of this power loss can be derived from the graphs on page 10.

<sup>1)</sup> Measured under pulse conditions to avoid excessive dissipation.

**OPERATING NOTES** (continued)

2. Sine wave operation

Power loss in sine wave operation will be considerably less owing to the much slower rate of change of the applied voltage (and consequently lower values of  $I_{RRM}$ ), so that power loss due to reverse recovery may be safely ignored for frequencies up to 20 kHz.

3. Determination of the heatsink thermal resistance

Example:

Assume a diode, used in an inverter.

frequency	$f$	=	20	kHz
duty cycle	$\delta$	=	0.5	
ambient temperature	$T_{amb}$	=	45	°C
switched from	$I_F$	=	12	A
to	$V_R$	=	400	V
at a rate	$-\frac{dI}{dt}$	=	20	A/ $\mu$ s

At a duty cycle  $\delta = 0.5$  the average forward current  $I_{FAV} = 6$  A.

From the upper graph on page 5 it follows, that at  $I_{FAV} = 6$  A the average forward power + average leakage power = 15 W (point A).

The additional power losses due to switching-off can be read from the nomogram on page 10 (the example being based on optimum use, i.e.  $T_j = 150$  °C). Starting from  $I_F = 12$  A on the horizontal scale trace upwards until the appropriate line

$-\frac{dI}{dt} = 20$  A/ $\mu$ s. From the intersection trace horizontally to the right until the line for  $f = 20$  kHz. Then trace downwards to the line  $V_R = 400$  V and ultimately trace horizontally to the left and on the vertical axis read the additional average power dissipation  $P_{RAV} = 4$  W.

Therefore the total power dissipation  $P_{tot} = 15$  W + 4 W = 19 W (point B of the upper graph on page 5). From the right hand part follows the thermal resistance, required at  $T_{amb} = 45$  °C.

$$R_{th\ mb-a} \approx 4 \text{ °C/W}$$

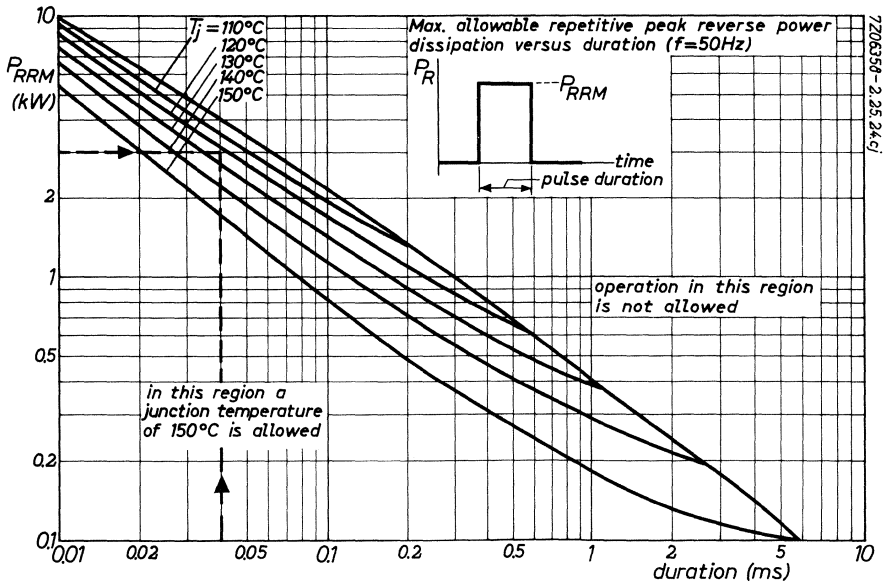
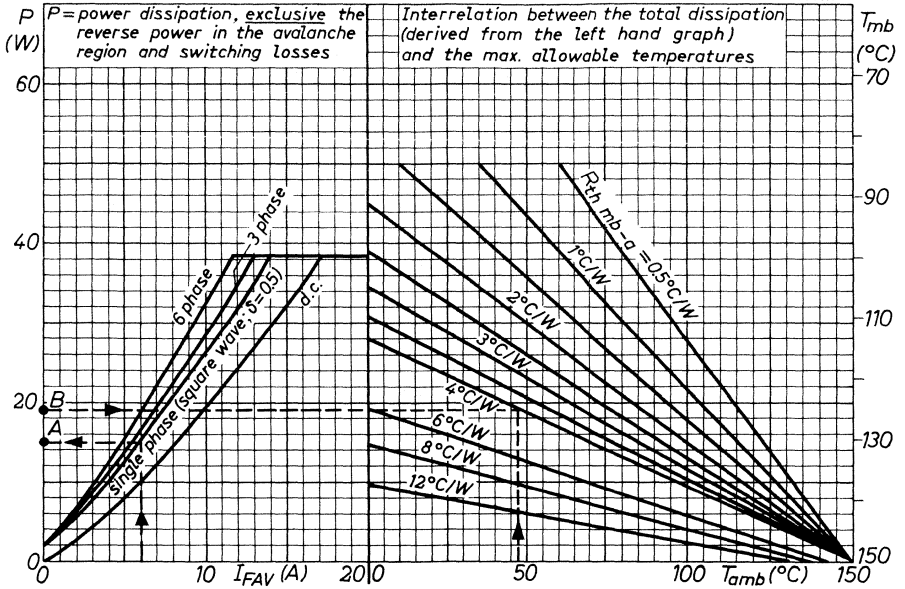
The contact thermal resistance  $R_{th\ mb-h} = 0.5$  °C/W.

Hence the heatsink thermal resistance should be:

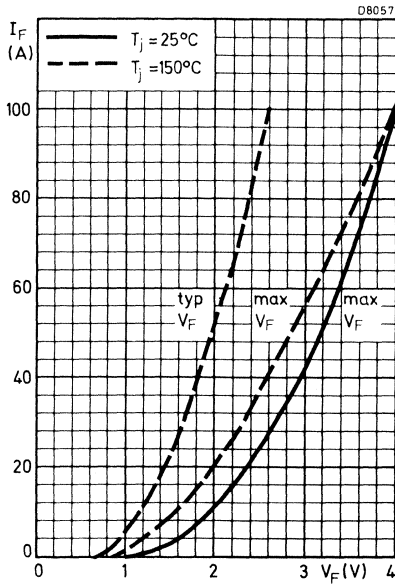
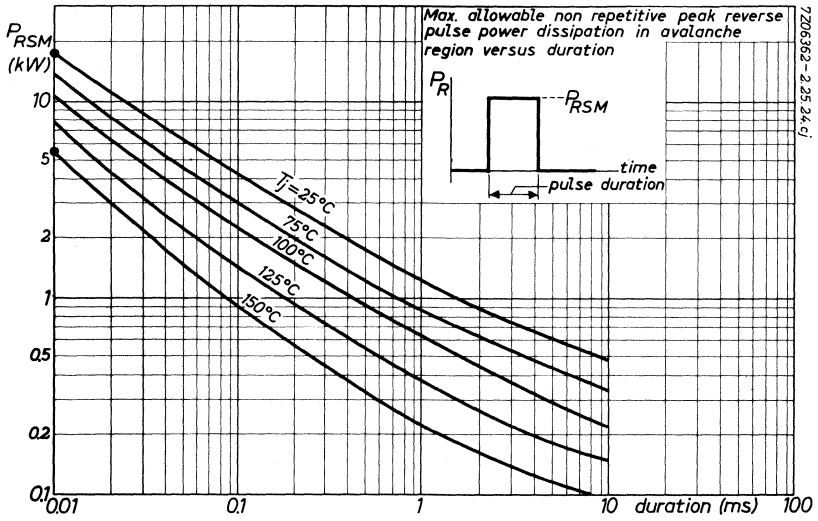
$$R_{th\ h-a} = R_{th\ mb-a} - R_{th\ mb-h} = (4 - 0.5) \text{ °C/W} = 3.5 \text{ °C/W.}$$

The applicable heatsink(s) may then be found in the Section HEATSINKS.

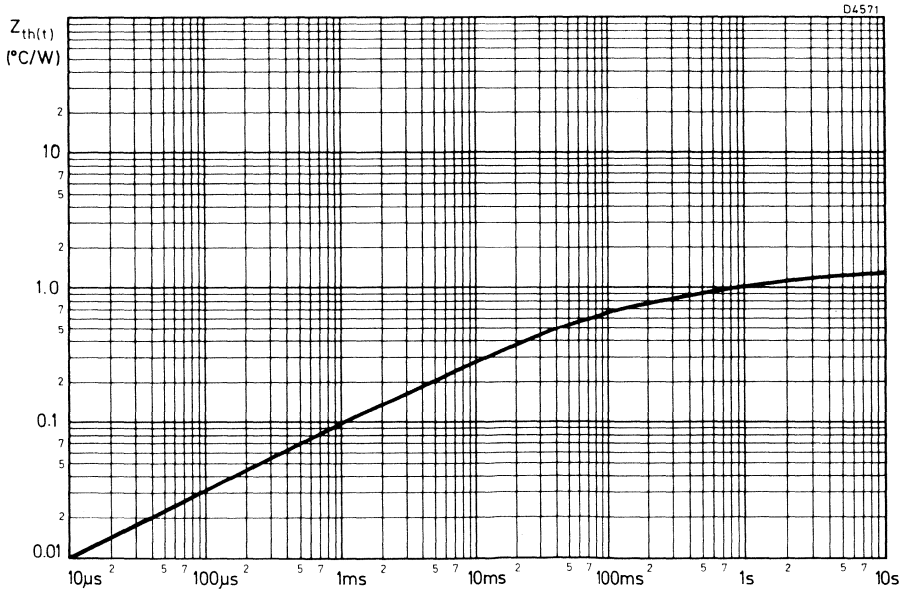
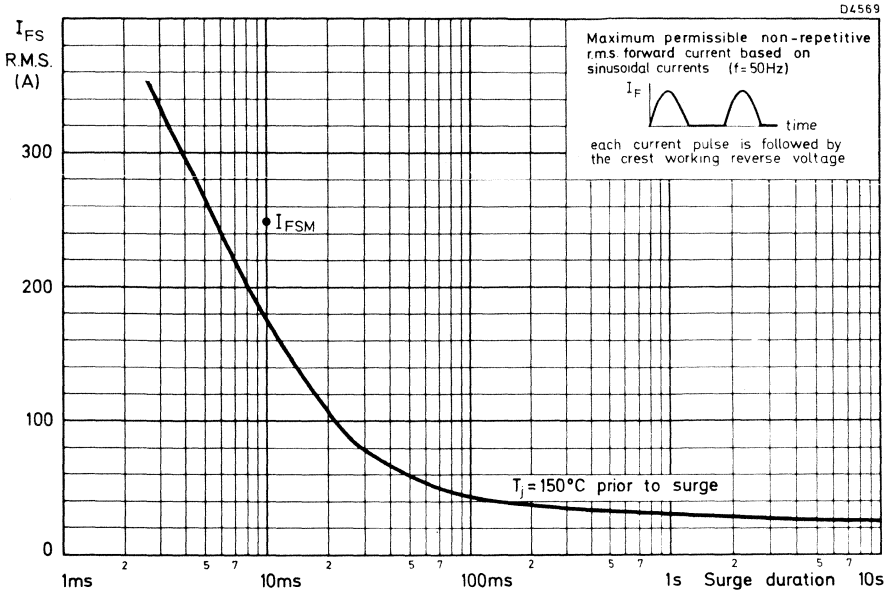
7206363.3



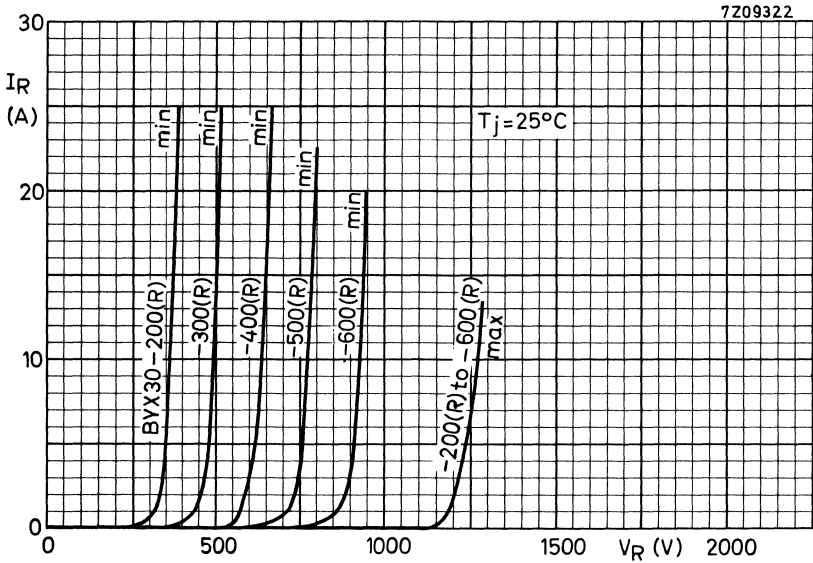
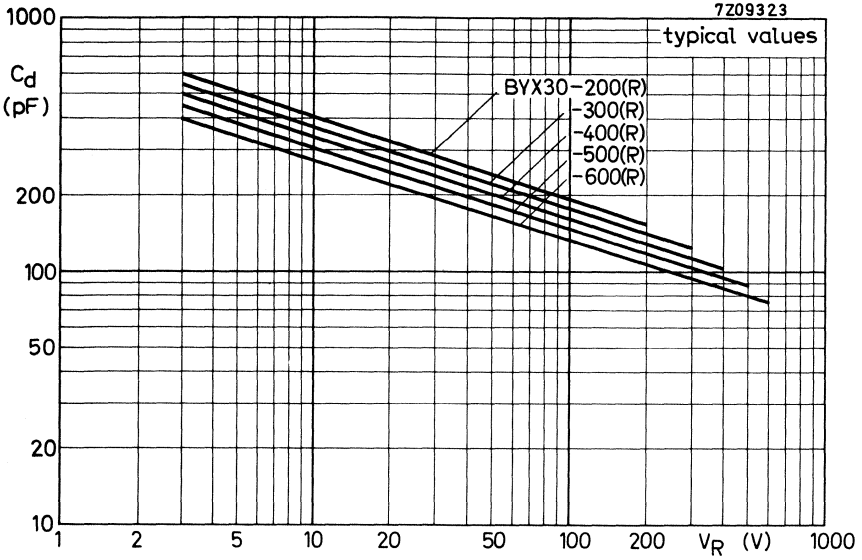
# BYX30 SERIES

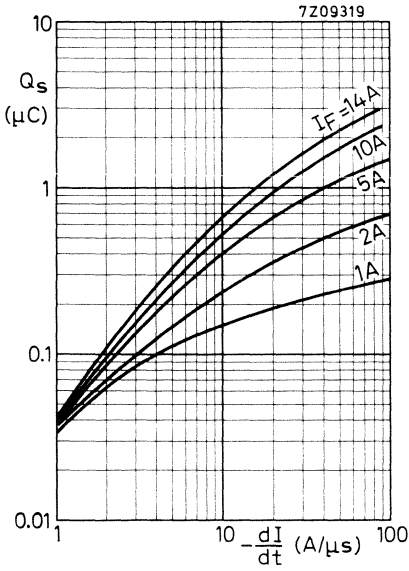




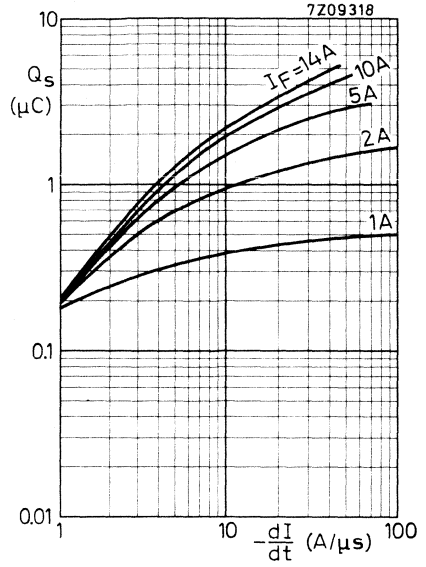


**BYX30  
SERIES**

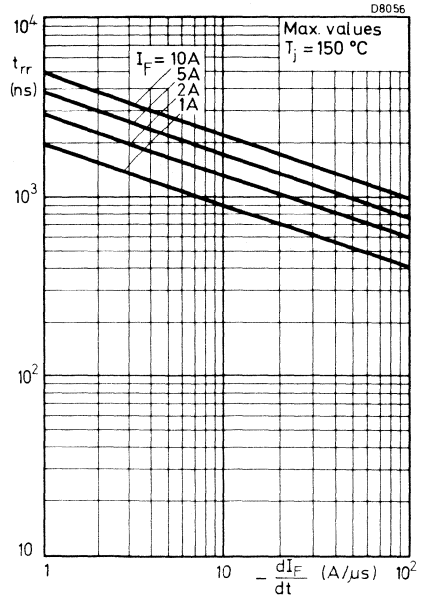
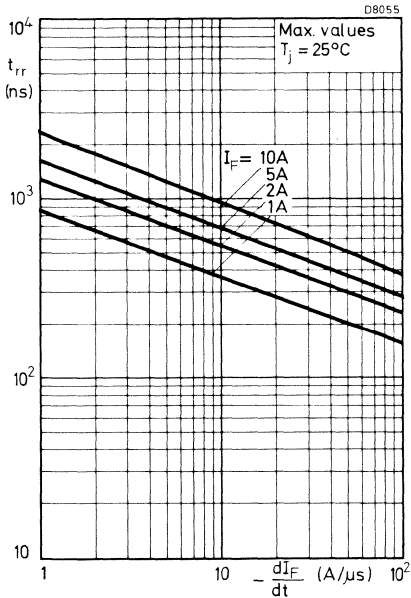




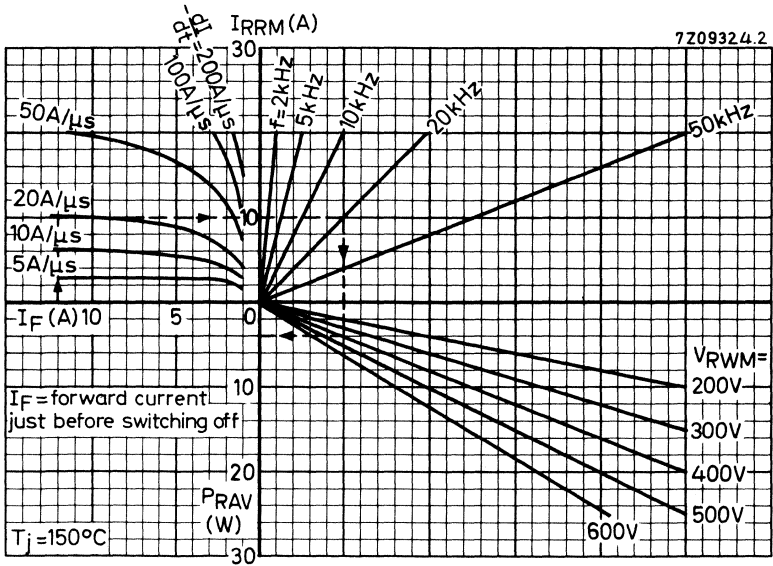
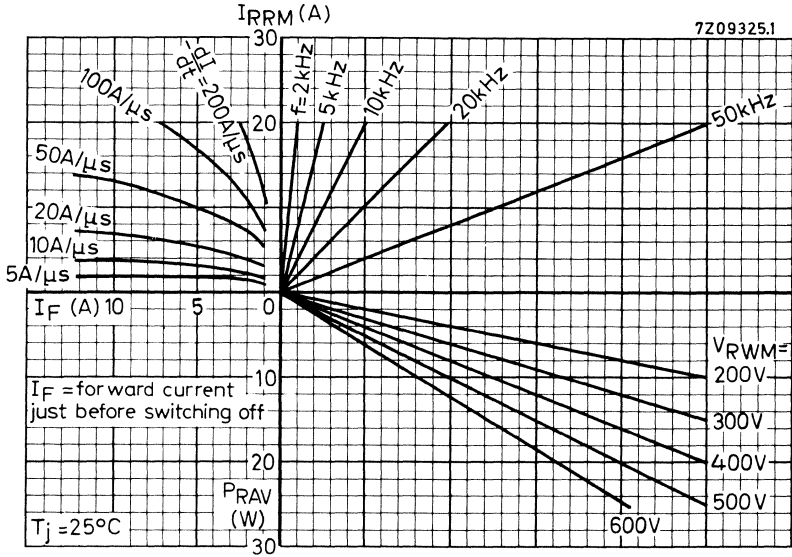
Maximum values;  $T_j = 25^\circ\text{C}$ ; switched from  $I_F$  to  $V_R \geq 30\text{ V}$ .



Maximum values;  $T_j = 150^\circ\text{C}$ ; switched from  $I_F$  to  $V_R \geq 30\text{ V}$ .



**BYX30  
SERIES**



Nomogram: Power loss  $P_{RAV}$  due to switching only (square wave operation)

SILICON RECTIFIER DIODES

Diffused silicon diodes in metal envelopes with ceramic insulation, intended for power rectifier application. The series consists of the following types:

Normal polarity (cathode to stud): BYX32-600 to BYX32-1600

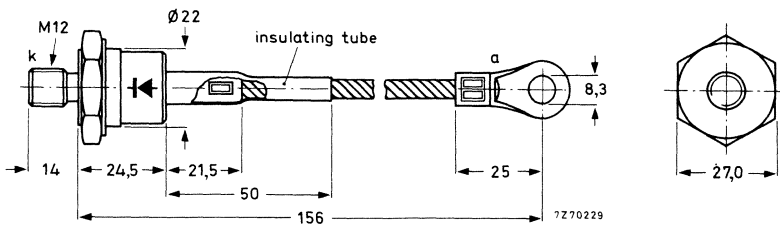
Reverse polarity (anode to stud): BYX32-600R to BYX32-1600R

QUICK REFERENCE DATA

		BYX32-600 600R	800 800R	1000 1000R	1200 1200R	1600 1600R	
Crest working reverse voltage	$V_{RWM}$ max.	600	800	1000	1200	1200	V
Repetitive peak reverse voltage	$V_{RRM}$ max.	600	800	1000	1200	1600	V
Average forward current	$I_F(AV)$			max.	150		A
Non-repetitive peak forward current	$I_{FSM}$			max.	1600		A

MECHANICAL DATA

Dimensions in mm



Normal polarity (⚡): blue cable. Reverse polarity (⚡): red cable.

Net mass: 115 g

Diameter of clearance hole: max. 13.0 mm

Torque on nut: min. 10 Nm  
(100 kg cm)  
max. 25 Nm  
(250 kg cm)

# BYX32 SERIES

All information applies to frequencies up to 400 Hz.

**RATINGS** Limiting values in accordance with the Absolute Maximum System (IEC 134)

Voltages <sup>1)</sup>			BYX32-				
			600 600R	800 800R	1000 1000R	1200 1200R	1600 1600R
Continuous reverse voltage	$V_R$	max.	600	800	1000	1200	1200 V
Crest working reverse voltage	$V_{RWM}$	max.	600	800	1000	1200	1200 V
Repetitive peak reverse voltage	$V_{RRM}$	max.	600	800	1000	1200	1600 V
Non-repetitive peak reverse voltage ( $t \leq 10$ ms)	$V_{RSM}$	max.	650	900	1100	1300	1600 V

## Currents

Average forward current (averaged over any 20 ms period) up to $T_{mb} = 100$ °C at $T_{mb} = 125$ °C	$I_{F(AV)}$	max.	150 A
	$I_{F(AV)}$	max.	115 A
Forward current (d. c.)	$I_F$	max.	240 A
R. M. S. forward current	$I_{F(RMS)}$	max.	240 A
Repetitive peak forward current	$I_{FRM}$	max.	750 A
Non-repetitive peak forward current ( $t = 10$ ms; half sine wave) $T_j = 190$ °C prior to surge	$I_{FSM}$	max.	1600 A
I squared t for fusing ( $t = 10$ ms)	$I^2t$	max.	12800 A <sup>2</sup> s

## Temperatures

Storage temperature	$T_{stg}$	-55 to +200 °C
Operating junction temperature	$T_j$	max. 190 °C

## THERMAL RESISTANCE

From junction to mounting base	$R_{th j-mb}$	= 0.4 °C/W
From mounting base to heatsink without heatsink compound	$R_{th mb-h}$	= 0.1 °C/W
From mounting base to heatsink with heatsink compound (Dow Corning 340)	$R_{th mb-h}$	= 0.04 °C/W
Transient thermal impedance; $t = 1$ ms	$Z_{th j-mb}$	= 0.025 °C/W

<sup>1)</sup> To ensure thermal stability:  $R_{th j-a} < 0.75$  °C/W (continuous reverse voltage) or  $< 1.5$  °C/W (a. c.)

For smaller heatsinks  $T_j$  should be derated. For a. c. see graph on page 3.

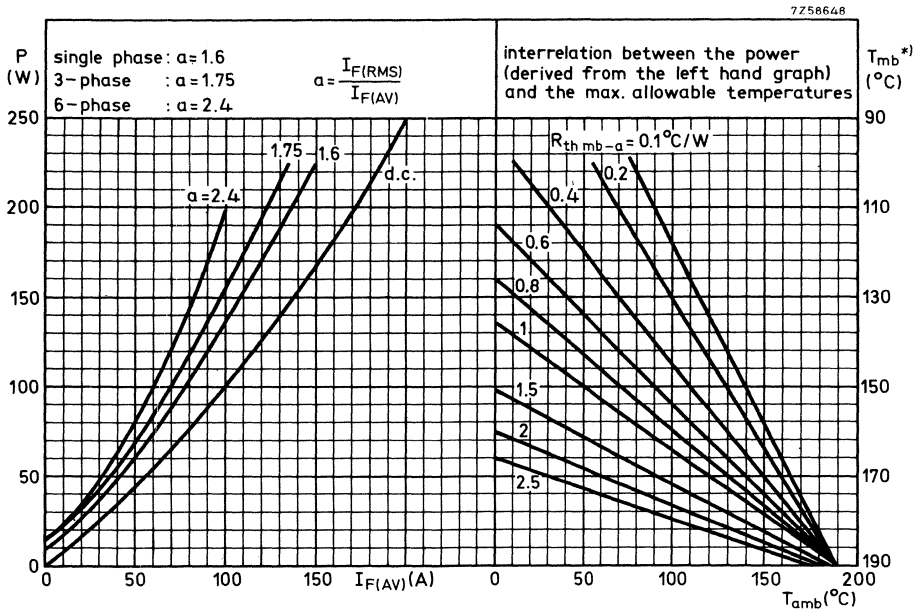
For continuous reverse voltage:  $R_{th j-a} = 1$  °C/W, then  $T_{jmax} = 184$  °C

$R_{th j-a} = 1.2$  °C/W, then  $T_{jmax} = 180$  °C

$R_{th j-a} = 1.5$  °C/W, then  $T_{jmax} = 175$  °C

**CHARACTERISTICS**

	BYX32- 600(R)	800(R)	1000(R)	1200(R)	1600(R)
Forward voltage $I_F = 500 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$	$V_F < 1,6$	1,6	1,6	1,6	1,6 V <sup>1)</sup>
Peak reverse current $V_{RM} = V_{RWMmax}$ $T_j = 175 \text{ }^\circ\text{C}$	$I_{RM} < 24$	18	15	12	12 mA



\* )  $T_{mb}$ -scale is for comparison purposes only and is correct only for  $R_{th\ mb-a} \leq 1.1 \text{ }^\circ\text{C/W}$

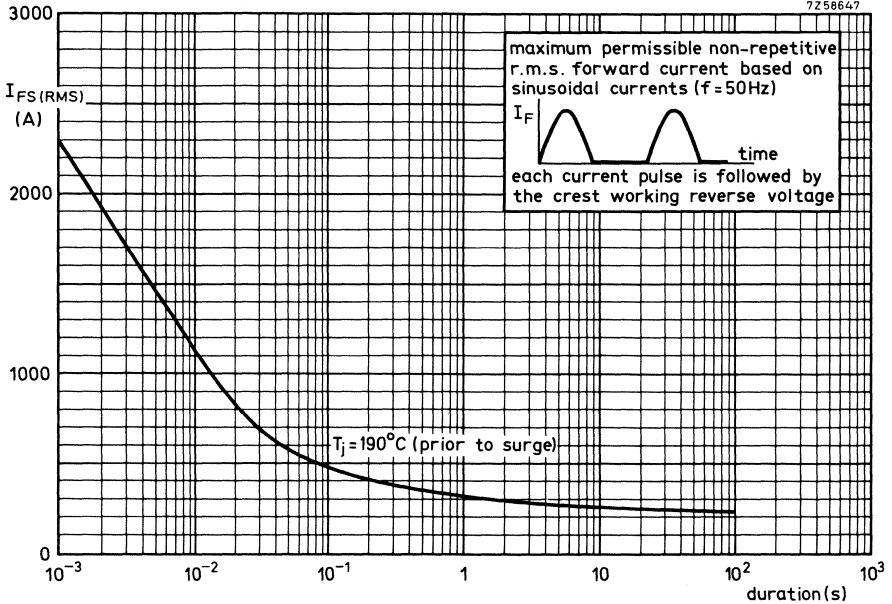
**APPLICATION INFORMATION AND OPERATING NOTES**

See general pages at the beginning of this section.

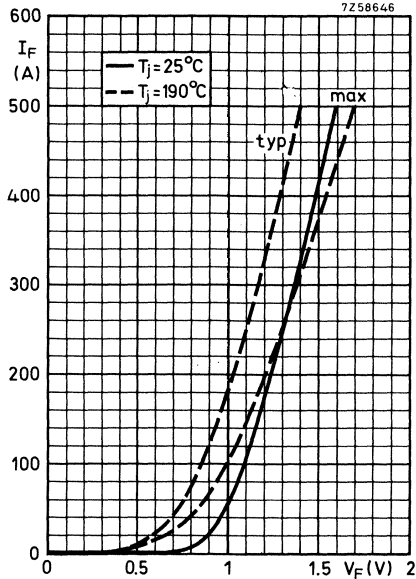
<sup>1)</sup> Measured under pulse conditions to avoid excessive dissipation.

# BYX32 SERIES

7258647

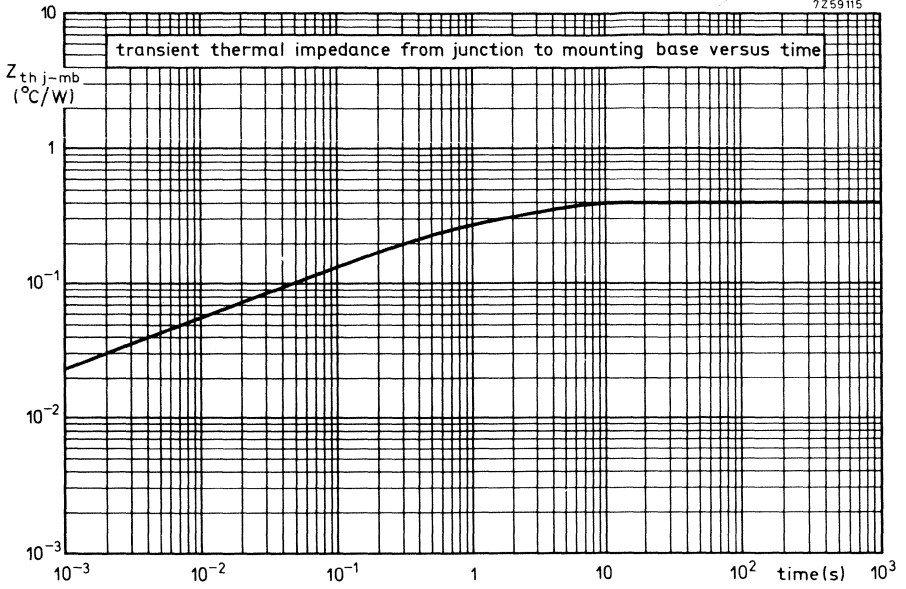


7258646





7259115





SILICON RECTIFIER DIODES

Also available to BS9331-F127

Silicon rectifier diodes in DO-4 metal envelopes, intended for use in power rectifier applications. The series consists of the following types:

Normal polarity (cathode to stud): BYX38-300 to 1200.

Reverse polarity (anode to stud): BYX38-300R to 1200R.

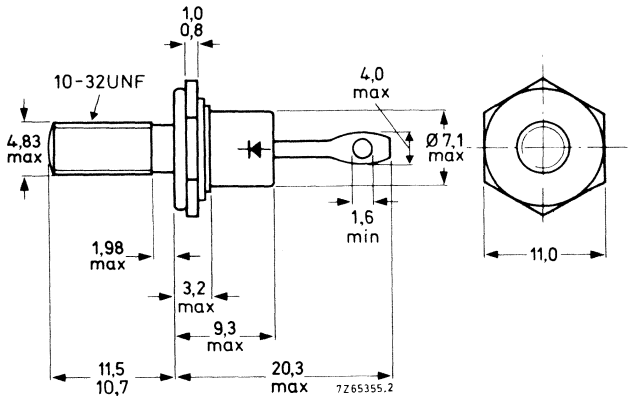
QUICK REFERENCE DATA

		BYX38-300(R)	600(R)	1200(R)
Repetitive peak reverse voltage	$V_{RRM}$	max. 300	600	1200 V
Average forward current	$I_{F(AV)}$	max.	6	A
Non-repetitive peak forward current	$I_{FSM}$	max.	50	A

MECHANICAL DATA

Dimensions in mm

DO-4



Net mass: 6 g

Diameter of clearance hole: max. 5,2 mm

Accessories supplied on request:

56295 (PTFE bush, 2 mica washers, plain washer, tag)

56262A (mica washer, insulating ring, plain washer)

Supplied with device: 1 nut, 1 lock washer

Nut dimensions across the flats: 9,5 mm

The mark shown applies to normal polarity types.

Torque on nut: min. 0,9 Nm

(9 kg cm)

max. 1,7 Nm

(17 kg cm)

# BYX38 SERIES

**RATINGS** Limiting values in accordance with the Absolute Maximum System (IEC 134)

Voltages		BYX38-300(R)	600(R)	1200(R)	
Non-repetitive peak reverse voltage ( $t \leq 10$ ms)	$V_{RSM}$	max. 300	600	1200	V
Repetitive peak reverse voltage ( $\delta \leq 0,01$ )	$V_{RRM}$	max. 300	600	1200	V
Crest working reverse voltage	$V_{RWM}$	max. 200	400	800	V
Continuous reverse voltage	$V_R$	max. 200	400	800	V

## Currents

Average forward current (averaged over any 20 ms period) up to $T_{mb} = 110$ °C at $T_{mb} = 125$ °C	$I_F(AV)$	max.	6	A
	$I_F(AV)$	max.	4	A
R. M. S. forward current	$I_F(RMS)$	max.	10	A
Repetitive peak forward current	$I_{FRM}$	max.	50	A
Non-repetitive peak forward current ( $t = 10$ ms; half sine-wave) $T_j = 150$ °C prior to surge; with reapplied $V_{RWMmax}$	$I_{FSM}$	max.	50	A
$I^2t$ for fusing ( $t = 10$ ms)	$I^2t$	max.	13	A <sup>2</sup> s

## Temperatures

Storage temperature	$T_{stg}$	-55 to +150	°C
Junction temperature	$T_j$	max. 150	°C

## THERMAL RESISTANCE

From junction to ambient in free air	$R_{th j-a}$	=	50	°C/W
From junction to mounting base	$R_{th j-mb}$	=	4	°C/W
From mounting base to heatsink with heatsink compound	$R_{th mb-h}$	=	0,5	°C/W
without heatsink compound	$R_{th mb-h}$	=	0,6	°C/W
Transient thermal impedance; $t = 1$ ms	$Z_{th j-mb}$	=	0,3	°C/W

**CHARACTERISTICS**Forward voltage

$$I_F = 20 \text{ A}; T_j = 25 \text{ }^\circ\text{C} \quad V_F < 1,7 \text{ V } ^1)$$

Reverse current

$$V_R = V_{RWM\max}; T_j = 125 \text{ }^\circ\text{C} \quad I_R < 200 \text{ } \mu\text{A}$$

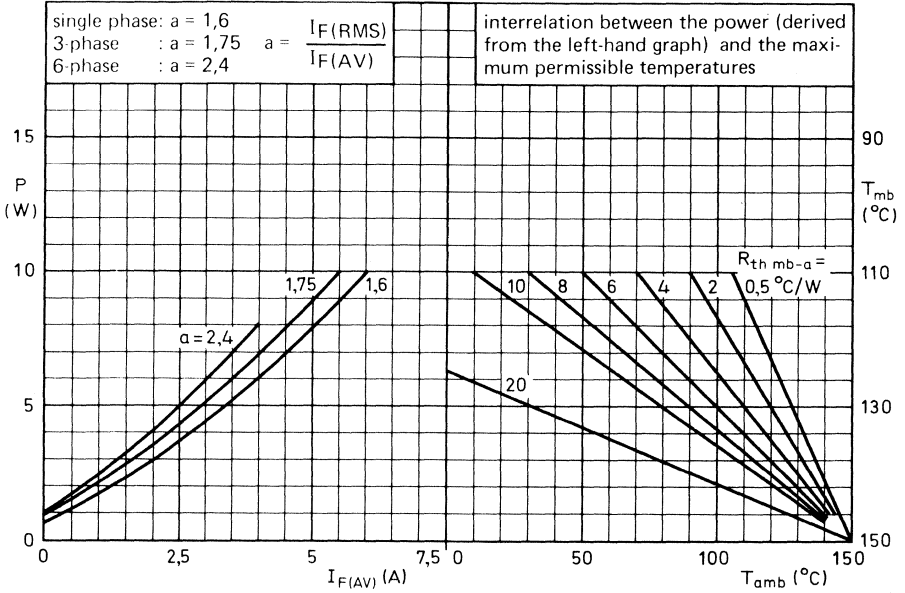
**OPERATING NOTES**

1. The top connector should neither be bent nor twisted; it should be soldered into the circuit so that there is no strain on it.  
During soldering the heat conduction to the junction should be kept to a minimum.
2. Where there is a possibility that transients, due to the energy stored in the transformer, will exceed the maximum permissible non-repetitive peak reverse voltage, see General Section for information on damping circuits in Data Handbook Part SC 1a.

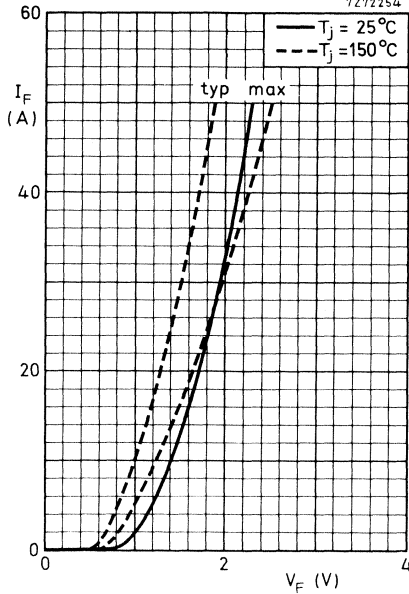
<sup>1)</sup> Measured under pulse conduction to avoid excessive dissipation.

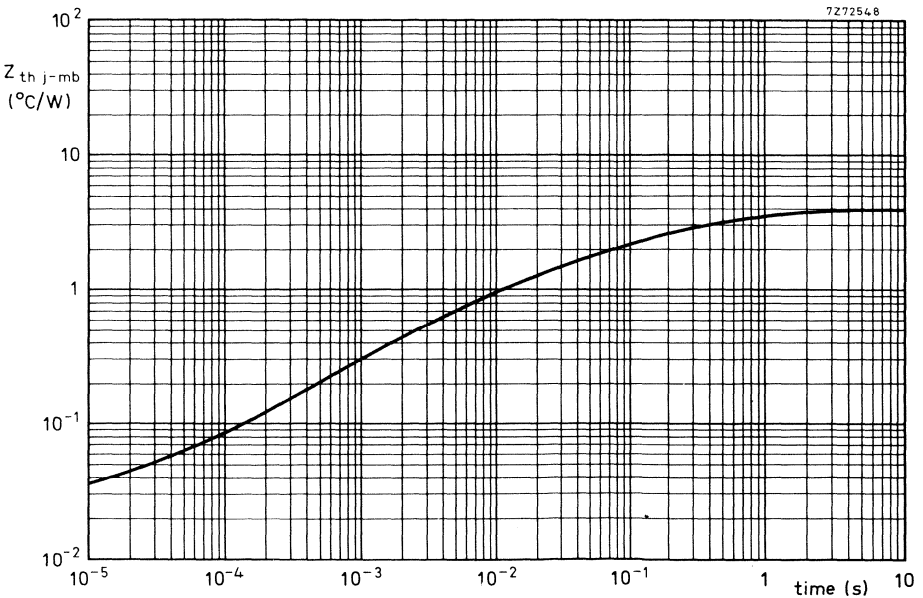
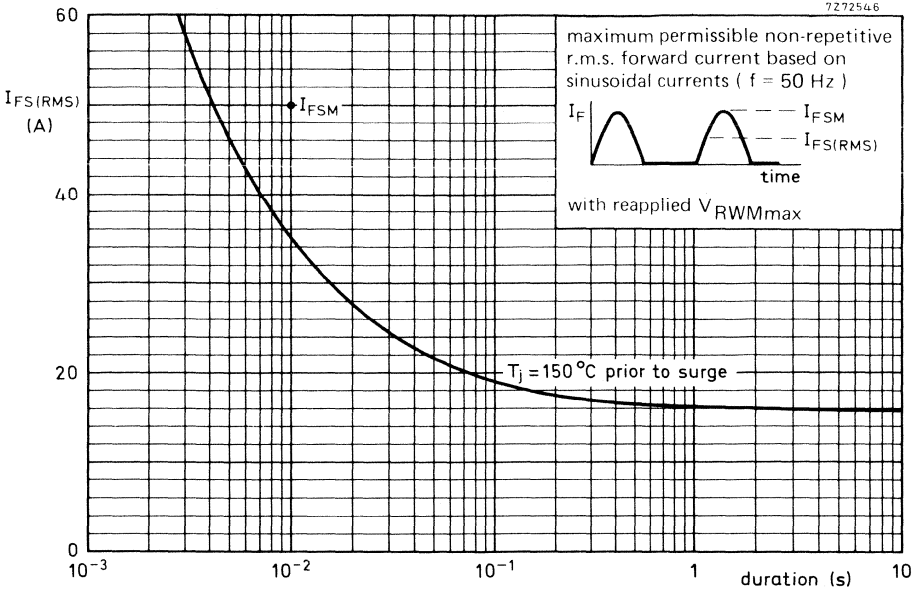
# BYX38 SERIES

7272547



727254









CONTROLLED AVALANCHE RECTIFIER DIODES

Also available to BS9333-F005

Silicon diodes in a DO-4 metal envelope, capable of absorbing transients and intended for use in power rectifier application.

The series consists of the following types:

Normal polarity (cathode to stud): BYX39-600 to BYX39-1400.

Reverse polarity (anode to stud): BYX39-600R to BYX39-1400R.

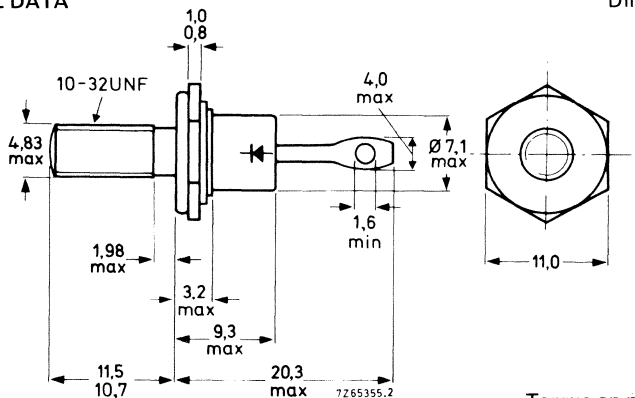
QUICK REFERENCE DATA

		BYX39-600(R)	800(R)	1000(R)	1200(R)	1400(R)	
Crest working reverse voltage	$V_{RWM}$	max.	600	800	1000	1200	1400 V
Reverse avalanche breakdown voltage	$V_{(BR)R}$	>	750	1000	1250	1450	1650 V
Average forward current			$I_{F(AV)}$	max.	9.5		A
Non-repetitive peak forward current			$I_{FSM}$	max.	125		A
Non-repetitive peak reverse power dissipation			$P_{RSM}$	max.	4		kW

MECHANICAL DATA

Dimensions in mm

Fig. 1 DO-4



Net mass: 6 g

Diameter of clearance hole: max. 5.2 mm

Accessories supplied on request:

56295 (PTFE bush, 2 mica washers, plain washer, tag).

Supplied with device: 1 nut, 1 lock-washer.

Nut dimensions across the flats: 9.5 mm.

The mark shown applies to normal polarity types.

Torque on nut:  
min. 0.9 Nm (9 kg cm),  
max. 1.7 Nm (17 kg cm).

# BYX39 SERIES

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC134)

→ Voltages*		BYX39-600(R)	800(R)	1000(R)	1200(R)	1400(R)	
Continuous reverse voltage	$V_R$	max. 600	800	1000	1200	1400	V
Crest working reverse voltage	$V_{RWM}$	max. 600	800	1000	1200	1400	V

## Currents

Average forward current (averaged over any 20 ms period) up to  $T_{mb} = 85\text{ }^\circ\text{C}$   
at  $T_{mb} = 125\text{ }^\circ\text{C}$

$I_{F(AV)}$	max.	9.5	A
$I_{F(AV)}$	max.	6.0	A

R.M.S. forward current

$I_{F(RMS)}$	max.	15	A
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Repetitive peak forward current

$I_{FRM}$	max.	100	A
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Non-repetitive peak forward current

$t = 10\text{ ms}$  (half sine-wave);  $T_j = 175\text{ }^\circ\text{C}$  prior to surge;  
with reapplied  $V_{RWMmax}$

$I_{FSM}$	max.	125	A
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$I^2 t$  for fusing ( $t = 10\text{ ms}$ )

$I^2 t$	max.	78	$\text{A}^2\text{s}$
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## Reverse power dissipation

Average reverse power dissipation  
(averaged over any 20 ms period);  $T_j = 125\text{ }^\circ\text{C}$

$P_{R(AV)}$	max.	10	W
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Repetitive peak reverse power dissipation  
 $t = 10\text{ }\mu\text{s}$  (square-wave;  $f = 50\text{ Hz}$ );  $T_j = 125\text{ }^\circ\text{C}$

$P_{RRM}$	max.	2	kW
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Non-repetitive peak reverse power dissipation  
 $t = 10\text{ }\mu\text{s}$  (square-wave)

$T_j = 25\text{ }^\circ\text{C}$  prior to surge  
 $T_j = 175\text{ }^\circ\text{C}$  prior to surge

$P_{RSM}$	max.	4	kW
$P_{RSM}$	max.	0.8	kW

## Temperatures

Storage temperature

$T_{stg}$		-55 to +175	$^\circ\text{C}$
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Junction temperature

$T_j$	max.	175	$^\circ\text{C}$
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\*To ensure thermal stability:  $R_{th\ j-a} \leq 5\text{ }^\circ\text{C/W}$  (continuous reverse voltage) or  $\leq 20\text{ }^\circ\text{C/W}$  (a.c.)

## THERMAL RESISTANCE

From junction to ambient in free air	$R_{th\ j-a}$	=	50	$^{\circ}C/W$
From junction to mounting base	$R_{th\ j-mb}$	=	4.5	$^{\circ}C/W$
From mounting base to heatsink without heatsink compound	$R_{th\ mb-h}$	=	1.0	$^{\circ}C/W$
with heatsink compound	$R_{th\ mb-h}$	=	0.5	$^{\circ}C/W$
with mica washer	$R_{th\ mb-h}$	=	2.0	$^{\circ}C/W$
Transient thermal impedance; $t = 1\ ms$	$Z_{th\ j-mb}$	=	0.35	$^{\circ}C/W$

## CHARACTERISTICS

		BYX39-600(R)	800(R)	1000(R)	1200(R)	1400(R)	
Forward voltage							
$I_F = 20\ A; T_j = 25\ ^{\circ}C$	$V_F$	< 1.7	1.7	1.7	1.7	1.7	$V^*$
Reverse avalanche breakdown voltage							
$I_R = 5\ mA; T_j = 25\ ^{\circ}C$	$V_{(BR)R}$	> 750	1000	1250	1450	1650	$V$
		< 2000	2000	2000	2200	2400	$V$
Reverse current							
$V_R = V_{RWMmax};$ $T_j = 125\ ^{\circ}C$	$I_R$	< 200	200	200	200	200	$\mu A$

## OPERATING NOTES

The top connector should neither be bent nor twisted; it should be soldered into the circuit so that there is no strain on it.

During soldering the heat conduction to the junction should be kept to a minimum.

\*Measured under pulse conditions to avoid excessive dissipation.

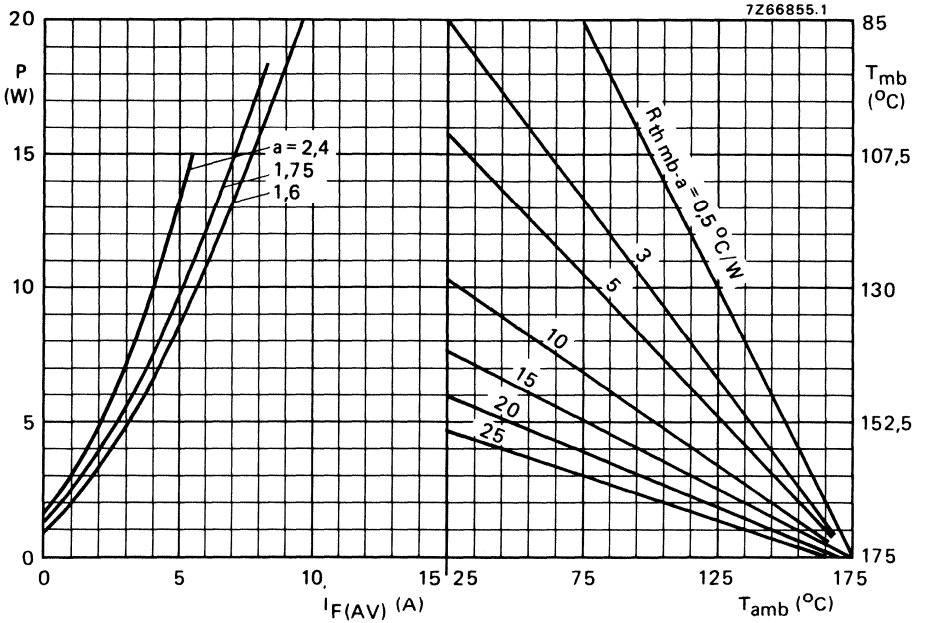
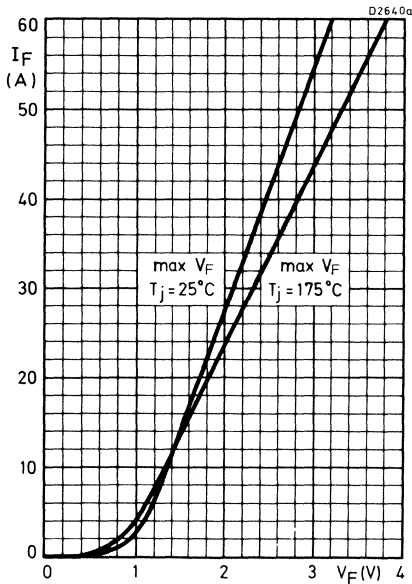


Fig.2



The right-hand part shows the inter-relationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

P = dissipation excluding power in the avalanche region.

- single phase:  $a = 1.6$
- 3-phase :  $a = 1.75$
- 6-phase :  $a = 2.4$

$$a = I_F(\text{RMS})/I_F(\text{AV})$$

Fig.3

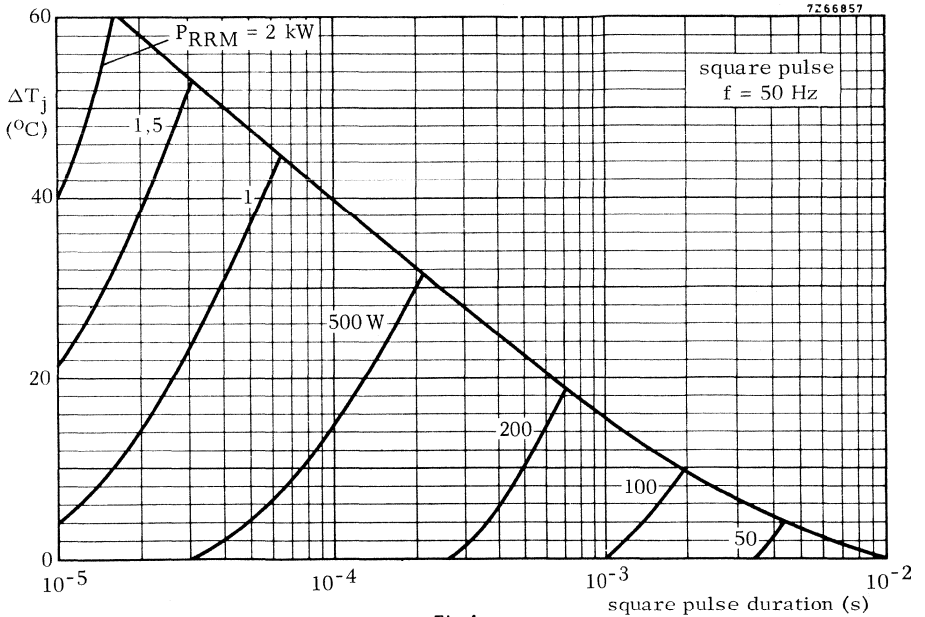


Fig.4

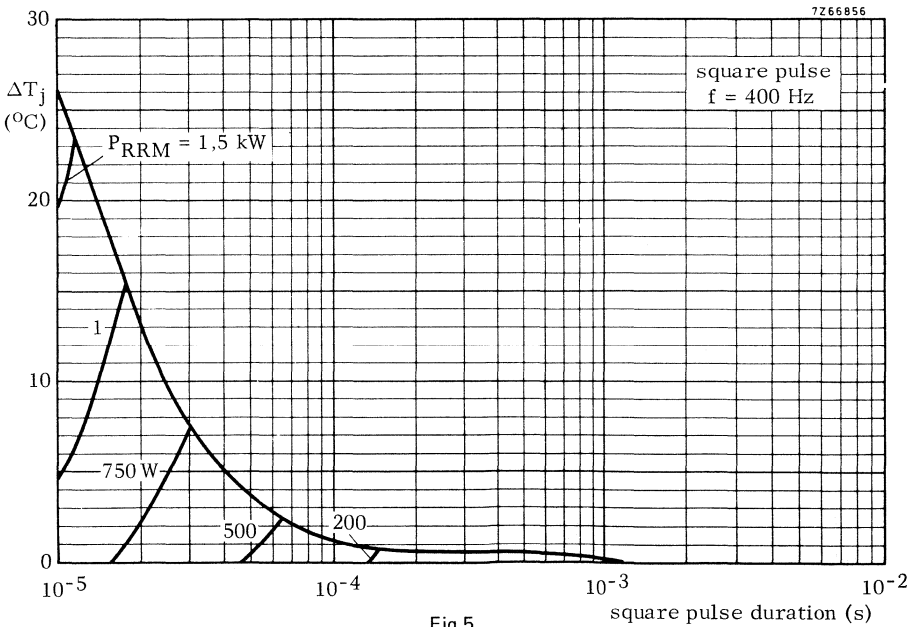


Fig.5

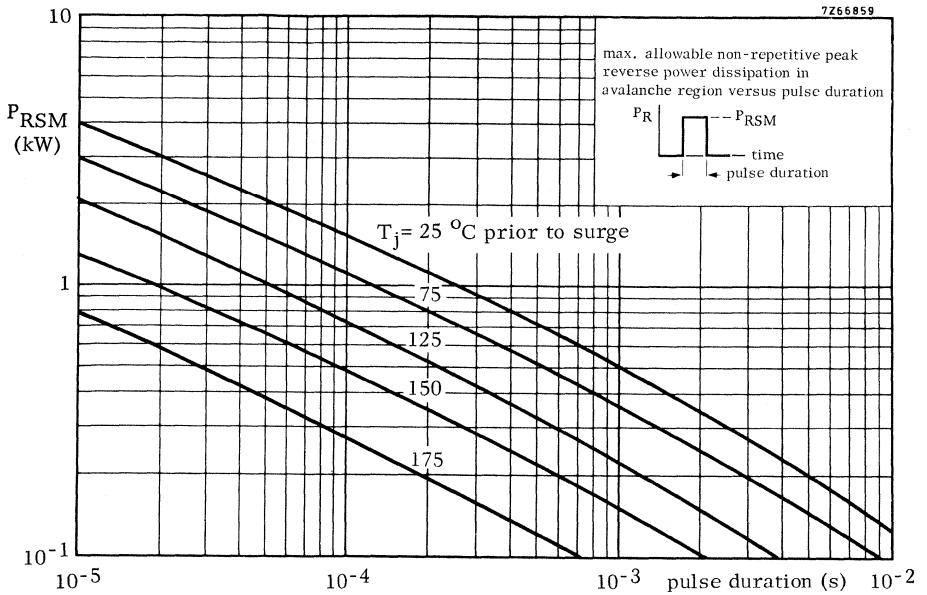


Fig.6

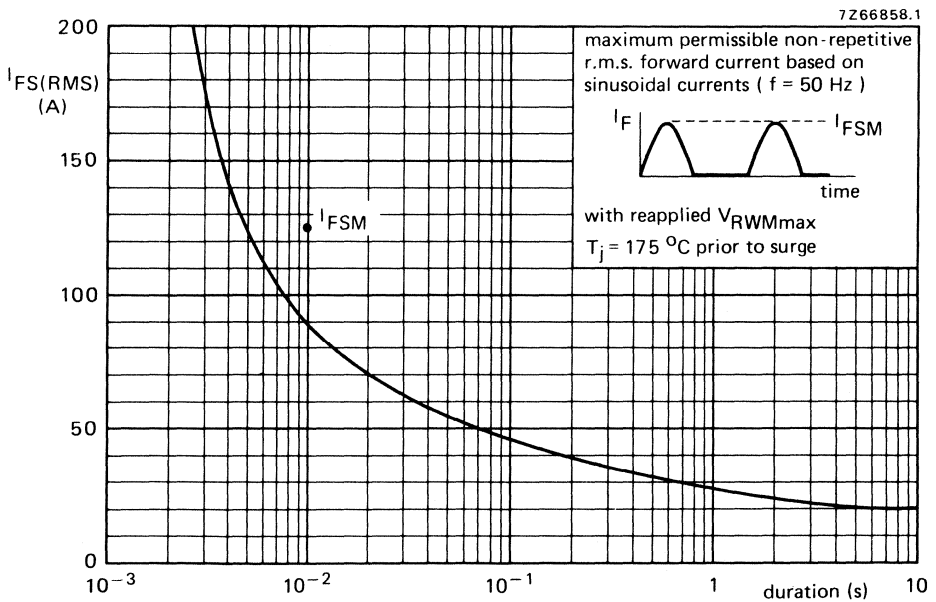


Fig.7

SILICON RECTIFIER DIODES

Also available to BS9331-F128

Diffused silicon rectifier diodes in DO-4 metal envelopes, intended for power rectifier applications.

The series consists of the following types:

Normal polarity (cathode to stud): BYX42-300 to 1200.

Reserve polarity (anode to stud): BYX42-300R to 1200R.

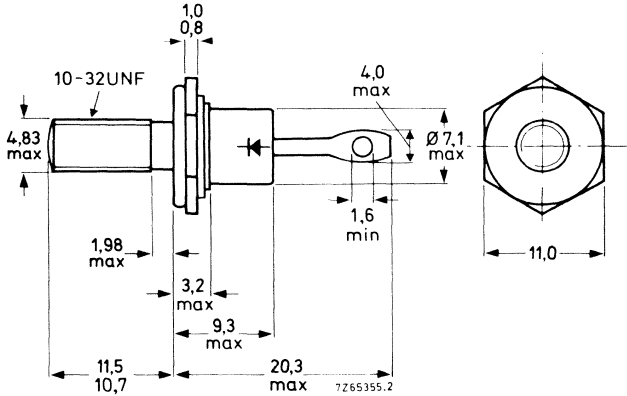
QUICK REFERENCE DATA

		BYX42-300(R)	600(R)	1200(R)
Repetitive peak reverse voltage	$V_{RRM}$	max. 300	600	1200 V
Average forward current	$I_{F(AV)}$	max.	12	A
Non-repetitive peak forward current	$I_{FSM}$	max.	125	A

MECHANICAL DATA

Dimensions in mm

DO-4



Net mass: 6 g

Diameter of clearance hole: 5,2 mm

Accessories supplied on request:

56295 (PTFE bush, 2 mica washers, plain washer, tag)

56262A (mica washer, insulating ring, plain washer)

Supplied with device: 1 nut, 1 lock washer

Nut dimensions across the flats: 9,5 mm

The mark shown applies to normal polarity types.

Torque on nut: min. 0,9 Nm

(9 kg cm)

max. 1,7 Nm

(17 kg cm)

# BYX42 SERIES

**RATINGS** Limiting values in accordance with the Absolute Maximum System (IEC 134)

<u>Voltages</u>		BYX42-300(R)	600(R)	1200(R)	
Non-repetitive peak reverse voltage ( $t \leq 10$ ms)	$V_{RSM}$	max. 300	600	1200	V
Repetitive peak reverse voltage ( $\delta \leq 0,01$ )	$V_{RRM}$	max. 300	600	1200	V
Crest working reverse voltage	$V_{RWM}$	max. 200	400	800	V
Continuous reverse voltage	$V_R$	max. 200	400	800	V

## Currents

Average forward current (averaged over any 20 ms period) up to $T_{mb} = 115$ °C		$I_{F(AV)}$	max.	12	A
	at $T_{mb} = 125$ °C	$I_{F(AV)}$	max.	10	A
R. M. S. forward current		$I_{F(RMS)}$	max.	20	A
Repetitive peak forward current		$I_{FRM}$	max.	60	A
Non-repetitive peak forward current ( $t = 10$ ms; half sine-wave) $T_j = 175$ °C prior to surge; with reapplied $V_{RWMmax}$		$I_{FSM}$	max.	125	A

## Temperatures

Storage temperature	$T_{stg}$	-55 to +175	°C
Junction temperature	$T_j$	max. 175	°C

## **THERMAL RESISTANCE**

From junction to ambient in free air	$R_{th j-a}$	=	50	°C/W
From junction to mounting base	$R_{th j-mb}$	=	3	°C/W
From mounting base to heatsink	$R_{th mb-h}$	=	0,5	°C/W

## **CHARACTERISTICS**

<u>Forward voltage</u> at $I_F = 15$ A; $T_j = 25$ °C	$V_F$	<	1,4	V <sup>1)</sup>
<u>Reverse current</u> at $V_R = V_{RWMmax}$ ; $T_j = 125$ °C	$I_R$	<	200	µA

## **MOUNTING INSTRUCTIONS**

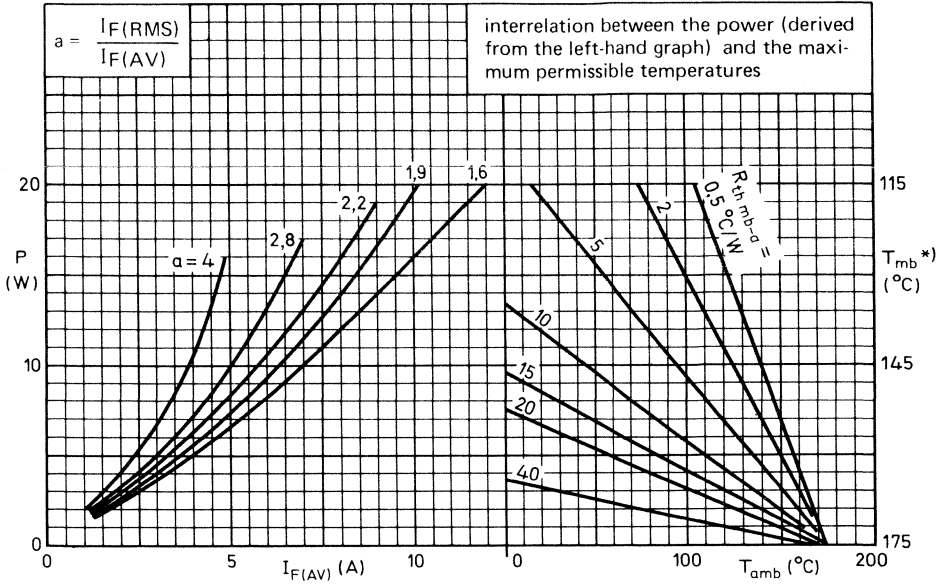
The top connector should neither be bent nor twisted; it should be soldered into the circuit so that there is no strain on it.

During soldering the heat conduction to the junction should be kept to a minimum.

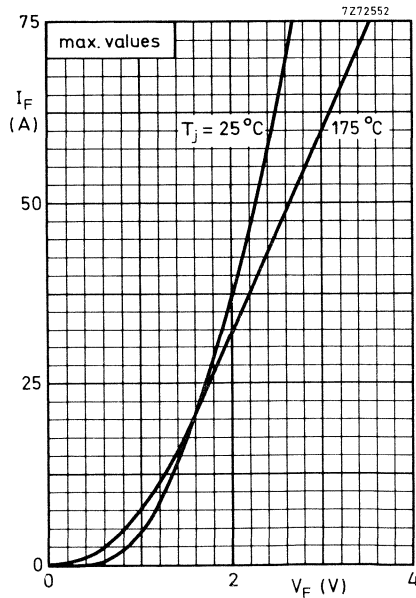
<sup>1)</sup> Measured under pulse conditions to avoid excessive dissipation.



7272553

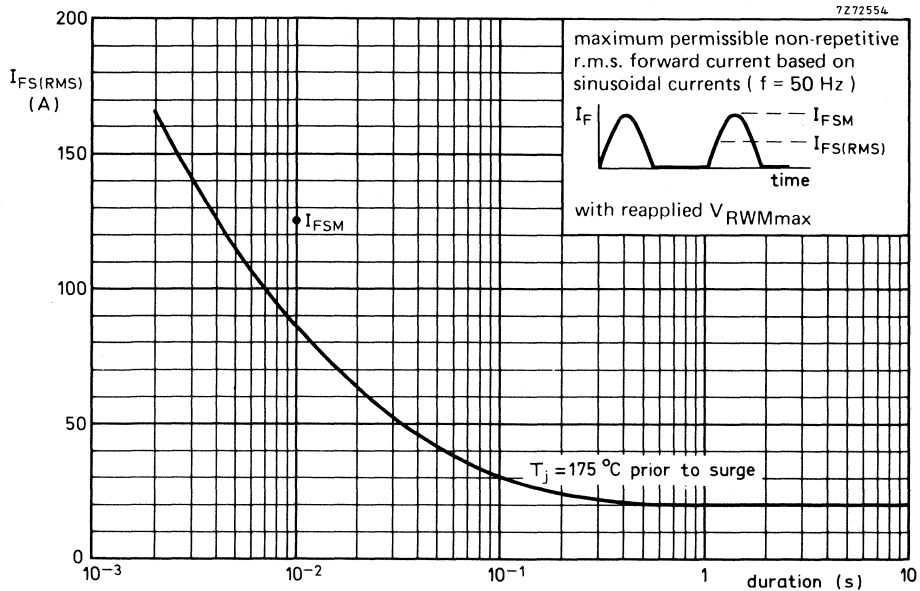


\*)  $T_{mb}$ -scale is for comparison purposes only and is correct only for  $R_{th\ mb-a} \leq 22\text{ }^{\circ}\text{C/W}$



# BYX42 SERIES

7272554



CONTROLLED AVALANCHE RECTIFIER DIODES

Also available to BS9333-F004

Diffused silicon diodes in a DO-1 metal envelope, capable of absorbing transients. They are intended for rectifier applications and particularly suited for series operation.

The series consists of the following reverse polarity types (anode to case):

BYX45-600R, BYX45-800R, BYX45-1000R, BYX45-1200R and BYX45-1400R.

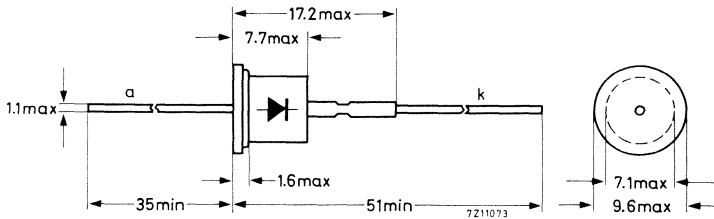
QUICK REFERENCE DATA

			BYX45-600R	800R	1000R	1200R	1400R	
Crest working reverse voltage	$V_{RWM}$	max.	600	800	1000	1200	1400	V
Reverse breakdown voltage	$V_{(BR)R}$	>	750	1000	1250	1450	1650	V
Average forward current	$I_{F(AV)}$	max.	1.5					A
Non repetitive peak forward current	$I_{FSM}$	max.	40					A
Non repetitive peak reverse power	$P_{RSM}$	max.	2.5					kW

MECHANICAL DATA

Dimensions in mm

Fig. 1 DO-1



# BYX45 SERIES

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC134)

### → Voltages

		BYX45-600R	800R	1000R	1200R	1400R	
Crest working reverse voltage	$V_{RWM}$	max. 600	800	1000	1200	1400	V
Continuous reverse voltage	$V_R$	max. 600	800	1000	1200	1400	V

### Currents

Average forward current  
(averaged over any 20 ms period)

$I_F(AV)$  max. 1.5 A

R.M.S. forward current

$I_F(RMS)$  max. 2.4 A

Repetitive peak forward current

$I_{FRM}$  max. 15 A

Non-repetitive peak forward current

$t = 10$  ms (half sine-wave);  $T_j = 150$  °C prior to surge;  
with reapplied  $V_{RWMmax}$ .

$I_{FSM}$  max. 40 A

$I^2 t$  for fusing ( $t = 10$  ms)

$I^2 t$  max. 8 A<sup>2</sup>s

### Reverse power dissipation

Repetitive peak reverse power dissipation

$t = 10$   $\mu$ s (square-wave;  $f = 50$  Hz);  $T_j = 125$  °C

$P_{RRM}$  max. 800 W

Non-repetitive peak reverse power dissipation

$t = 10$   $\mu$ s (square-wave)

$T_j = 25$  °C prior to surge

$T_j = 150$  °C prior to surge

$P_{RSM}$  max. 2.5 kW

$P_{RSM}$  max. 800 W

### Temperatures

Storage temperature

$T_{stg}$  -55 to +150 °C

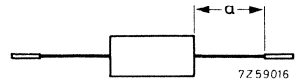
Junction temperature

$T_j$  max. 150 °C

**THERMAL RESISTANCE****Effect of mounting on thermal resistance  $R_{th\ j-a}$** 

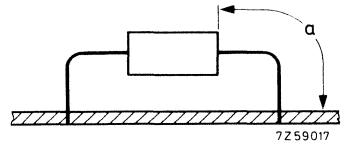
The quoted values apply when no other leads run to the tie-points. If leads of other dissipating components share the same tie-points, the thermal resistance will be higher than that quoted.

1. Mounted on solder tags at a lead-length  $a = 10$  mm.  $R_{th\ j-a} = 60$  °C/W



2. Mounted on solder tags at  $a =$  maximum lead-length.  $R_{th\ j-a} = 70$  °C/W

3. Mounted on printed-wiring board at  $a =$  maximum lead-length.  $R_{th\ j-a} = 80$  °C/W



4. Mounted on printed-wiring board at a lead-length  $a = 10$  mm.  $R_{th\ j-a} = 90$  °C/W

**SOLDERING AND MOUNTING NOTES**

1. At a soldering iron or bath temperature of up to 245 °C, the maximum permissible soldering time is 10 s if the joint is 5 mm from the seal, 3 s if it is 1.5 mm from the seal.
2. At a temperature between 245 °C and 400 °C (max.), the joint must be more than 5 mm from the seal and soldering time must not exceed 5 s.
3. Leads should not be bent less than 1.5 mm from the seal; exert no axial pull when bending.

# BYX45 SERIES

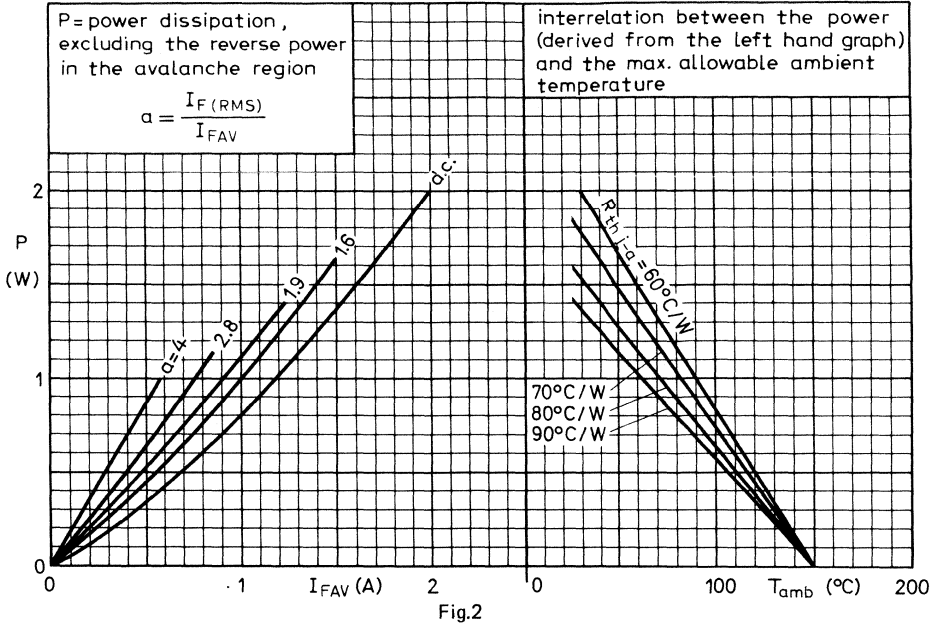
## CHARACTERISTICS

→

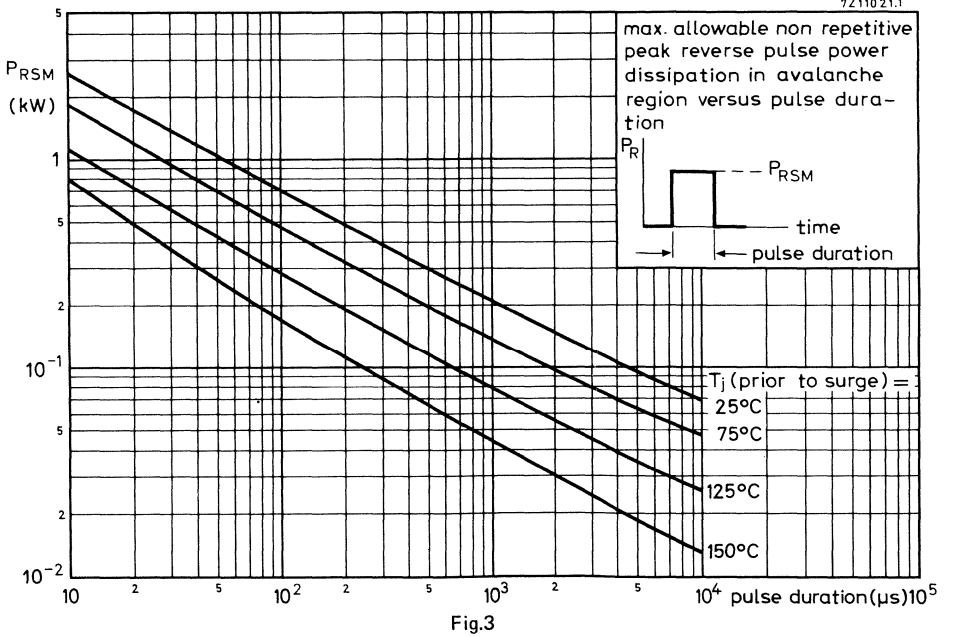
			BYX45-600R	800R	1000R	1200R	1400R	
Forward voltage	$V_F$	<	1.45	1.45	1.45	1.45	1.45	V*
$I_F = 5 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$								
Reverse avalanche breakdown voltage	$V_{(BR)R}$	>	750	1000	1250	1450	1650	V
$I_R = 1 \text{ mA}; T_j = 25 \text{ }^\circ\text{C}$								
Reverse current	$I_R$	<	100	100	100	100	100	$\mu\text{A}$
$V_R = V_{RWM\text{max}}; T_j = 125 \text{ }^\circ\text{C}$								

\*Measured under pulse conditions to avoid excessive dissipation.

7Z11022.2



7Z11021.1



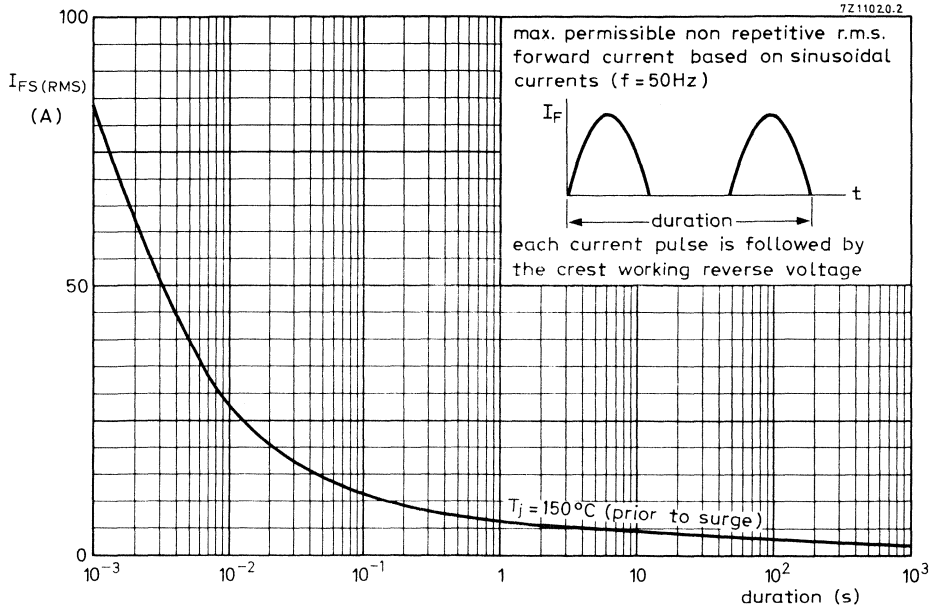


Fig.4

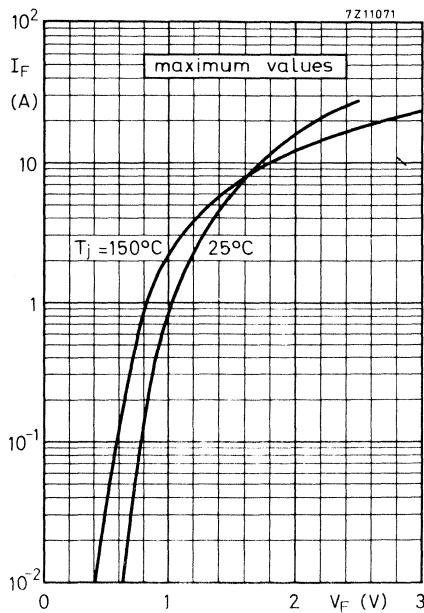


Fig.5



FAST SOFT-RECOVERY RECTIFIER DIODES

- With controlled avalanche

Diffused silicon diodes in DO-4 metal envelopes, capable of absorbing transients. They are primarily intended for use in high-frequency power supplies, thyristor inverters and multi-phase power rectifier applications.

The series consists of the following types:

Normal polarity (cathode to stud): BYX46-200 to BYX46-600.

Reverse polarity (anode to stud): BYX46-200R to BYX46-600R

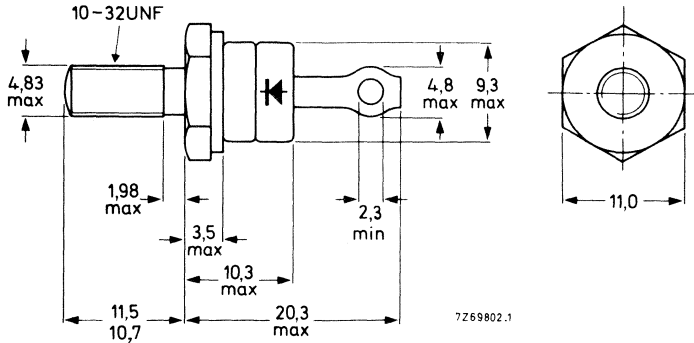
QUICK REFERENCE DATA

		BYX46-200(R)	300(R)	400(R)	500(R)	600(R)	
Crest working reverse voltage	$V_{RWM}$	max. 200	300	400	500	600	V
Reverse avalanche breakdown voltage	$V_{(BR)R}$	> 250	375	500	625	750	V
Average forward current	$I_{F(AV)}$	max. 22					A
Non-repetitive peak forward current	$I_{FSM}$	max. 300					A
Non-repetitive peak reverse power	$P_{RSM}$	max. 18					kW
Reverse recovery time	$t_{rr}$	< 200					ns

MECHANICAL DATA

Dimensions in mm

DO-4 Supplied with device: 1 nut, 1 lock-washer  
Nut dimensions across the flats: 9,5 mm



Net mass: 7 g  
Diameter of clearance hole: max. 5,2 mm  
Accessories supplied on request: 56295  
(PTFE bush, 2 mica washers, plain washer, tag)

Torque on nut: min. 0,9 Nm (9 kg cm)  
max. 1,7 Nm (17 kg cm)

The mark shown applies to the normal polarity types.

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

Voltages *		BYX46-200(R)	300(R)	400(R)	500(R)	600(R)
Crest working reverse voltage	$V_{RWM}$ max.	200	300	400	500	600 V
Continuous reverse voltage	$V_R$ max.	200	300	400	500	600 V

## Currents

Average forward current (averaged over any 20 ms period)

up to $T_{mb} = 100\text{ }^\circ\text{C}$	$I_F(AV)$ max.			22		A
at $T_{mb} = 125\text{ }^\circ\text{C}$	$I_F(AV)$ max.			15		A

R.M.S. forward current	$I_F(RMS)$ max.			35		A
------------------------	-----------------	--	--	----	--	---

Repetitive peak forward current	$I_{FRM}$ max.			400		A
---------------------------------	----------------	--	--	-----	--	---

Non-repetitive peak forward current  
( $t = 10\text{ ms}$ ; half-sinewave)  $T_j = 165\text{ }^\circ\text{C}$   
prior to surge; with reapplied

$V_{RWMmax}$	$I_{FSM}$ max.			300		A
--------------	----------------	--	--	-----	--	---

$I^2t$ for fusing ( $t = 10\text{ ms}$ )	$I^2t$ max.			450		$A^2s$
--	-------------	--	--	-----	--	--------

## Reverse power dissipation

Repetitive peak reverse power dissipation  
 $t = 10\text{ } \mu\text{s}$  (square wave;  $f = 50\text{ Hz}$ )  
 $T_j = 100\text{ }^\circ\text{C}$

$P_{RRM}$ max.		9,5		kW
----------------	--	-----	--	----

Non-repetitive peak reverse power  
dissipation  $t = 10\text{ } \mu\text{s}$  (square wave)  
 $T_j = 25\text{ }^\circ\text{C}$  prior to surge  
 $T_j = 165\text{ }^\circ\text{C}$  prior to surge

$P_{RSM}$ max.		18		kW
$P_{RSM}$ max.		4		kW

## Temperatures

Storage temperature	$T_{stg}$		-55 to +165	$^\circ\text{C}$
---------------------	-----------	--	-------------	------------------

Junction temperature	$T_j$ max.		165	$^\circ\text{C}$
----------------------	------------	--	-----	------------------

## THERMAL RESISTANCE

From junction to ambient in free air	$R_{th\ j-a}$ =		50	$^\circ\text{C/W}$
--------------------------------------	-----------------	--	----	--------------------

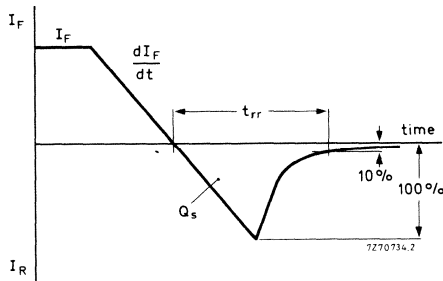
From junction to mounting base	$R_{th\ j-mb}$ =		1,3	$^\circ\text{C/W}$
--------------------------------	------------------	--	-----	--------------------

From mounting base to heatsink	$R_{th\ mb-h}$ =		0,5	$^\circ\text{C/W}$
--------------------------------	------------------	--	-----	--------------------

\* To ensure thermal stability:  $R_{th\ j-a} < 2,5\text{ }^\circ\text{C/W}$  (continuous reverse voltage) or  $< 5\text{ }^\circ\text{C/W}$  (a.c.). For smaller heatsinks  $T_{j\ max}$  should be derated. For a.c. see page 5. For continuous reverse voltage: if  $R_{th\ j-a} = 5\text{ }^\circ\text{C/W}$ , then  $T_{j\ max} = 135\text{ }^\circ\text{C}$ ; if  $R_{th\ j-a} = 10\text{ }^\circ\text{C/W}$ , then  $T_{j\ max} = 125\text{ }^\circ\text{C}$ .

**CHARACTERISTICS**

		BYX46-200(R)	300(R)	400(R)	500(R)	600(R)
Forward voltage $I_F = 50 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$	$V_F$	<	2,0	2,0	2,0	2,0 V *
Reverse breakdown voltage $I_R = 5 \text{ mA}; T_j = 25 \text{ }^\circ\text{C}$	$V_{(BR)R}$	>	250	375	500	625 750 V
		<	1050	1050	1050	1050 V
Reverse current $V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$	$I_R$	<	4,0	4,0	4,0	4,0 mA
Reverse recovery charge when switched from $I_F = 2 \text{ A to } V_R \geq 30 \text{ V};$ $-dI_F/dt = 100 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$	$Q_s$	<		0,70		$\mu\text{C}$
Reverse recovery time when switched from $I_F = 1 \text{ A to } V_R \geq 30 \text{ V};$ $-dI_F/dt = 50 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$	$t_{rr}$	<		200		ns



**OPERATING NOTES**

1. Square-wave operation

When  $I_F$  has been flowing sufficiently long for the steady state to be established, there will be a charge due to minority carriers present. Before the device can block in the reverse direction this charge must be extracted. This extraction takes the form of a reverse transient (see figure above). The majority of the power dissipation due to the reverse transient occurs during fall time as the rectifier gradually becomes reverse biased, and the mean power will be proportional to the operating frequency. The mean value of this power loss can be derived from the graphs on page 10.

\* Measured under pulse conditions to avoid excessive dissipation.

**OPERATING NOTES** (continued)

2. Sine wave operation

Power loss in sine wave operation will be considerably less owing to the much slower rate of change of the applied voltage (and consequently lower values of  $I_{RRM}$ ), so that power loss due to reverse recovery may be safely ignored for frequencies up to 50 kHz.

3. Determination of the heatsink thermal resistance

Example:

Assume a diode, used in an inverter.

frequency	$f$	=	20	kHz
duty cycle	$\delta$	=	0.5	
ambient temperature	$T_{amb}$	=	40	°C
switched from	$I_F$	=	12	A
to	$V_R$	=	300	V
at a rate	$-\frac{dI}{dt}$	=	50	A/ $\mu$ s

At a duty cycle  $\delta = 0.5$  the average forward current  $I_{FAV} = 6$  A.

From the upper graph on page 5 it follows, that at  $I_{FAV} = 6$  A the average forward power + average leakage power = 13 W (point A).

The additional power losses due to switching-off can be read from the nomogram on page 10 (the example being based on optimum use, i.e.  $T_j = 165$  °C). Starting from  $I_F = 12$  A on the horizontal scale trace upwards until the appropriate line

$-\frac{dI}{dt} = 50$  A/ $\mu$ s. From the intersection trace horizontally to the right until the line for  $f = 20$  kHz. Then trace downwards to the line  $V_R = 300$  V and ultimately trace horizontally to the left and on the vertical axis read the additional average power dissipation  $P_{RAV} = 6$  W.

Therefore the total power dissipation  $P_{tot} = 13$  W + 6 W = 19 W (point B of the upper graph on page 5).

From the right hand part of the upper graph on page 5 follows the thermal resistance, required at  $T_{amb} = 40$  °C.

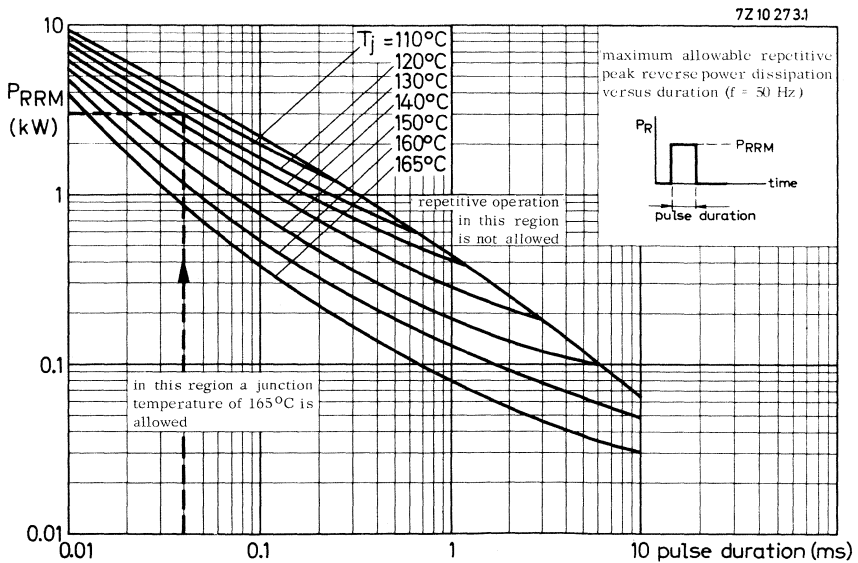
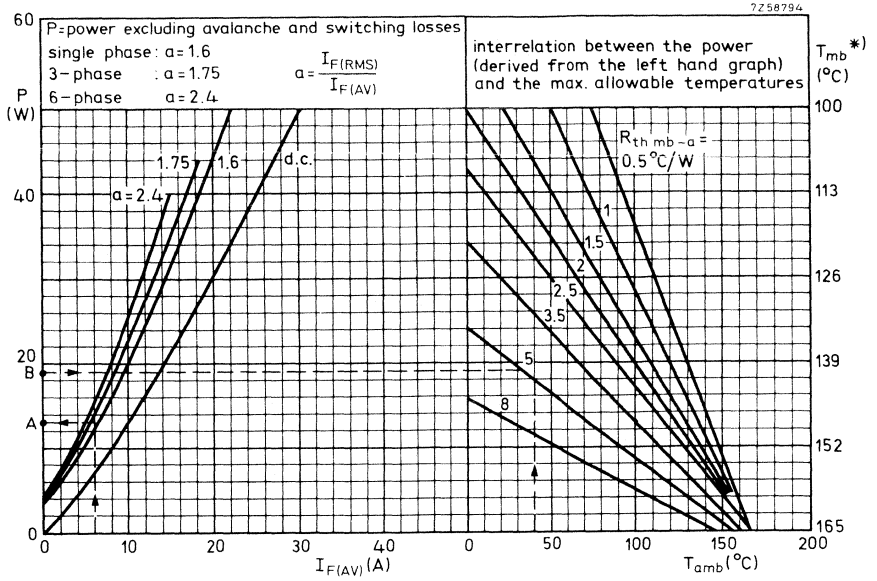
$$R_{th\ mb-a} \approx 5\text{ °C/W}$$

The contact thermal resistance  $R_{th\ mb-h} = 0.5$  °C/W.

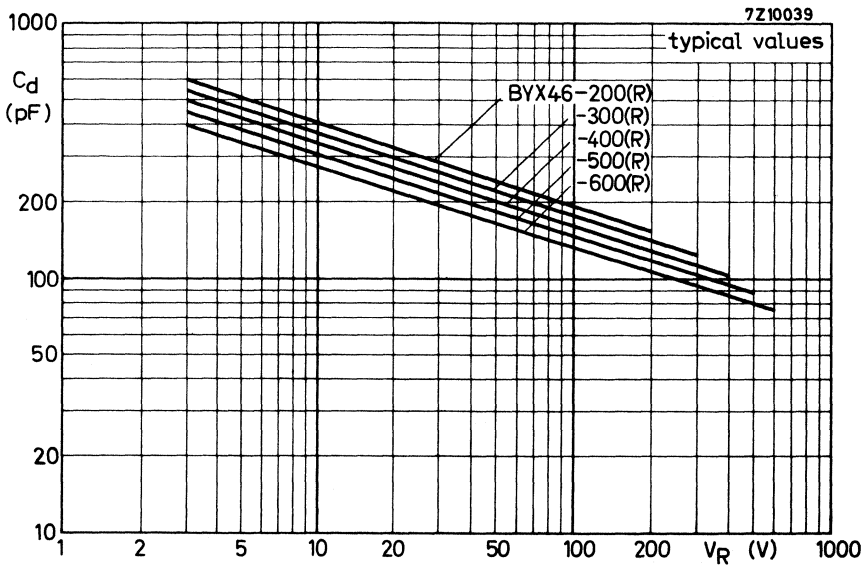
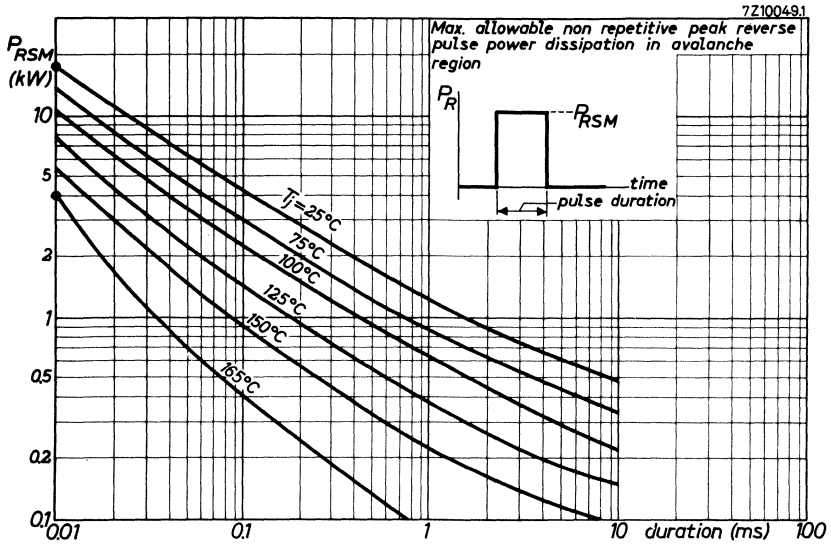
Hence the heatsink thermal resistance should be:

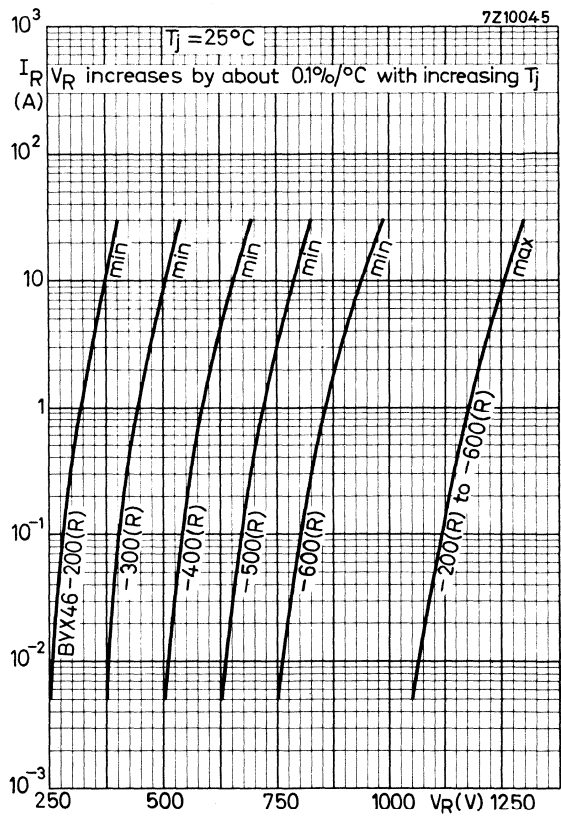
$$R_{th\ h-a} = R_{th\ mb-a} - R_{th\ mb-h} = (5 - 0.5)\text{ °C/W} = 4.5\text{ °C/W.}$$

The applicable heatsink(s) may then be found in the Section HEATSINKS.

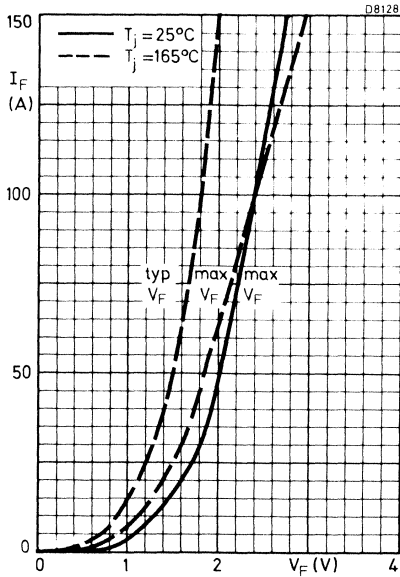
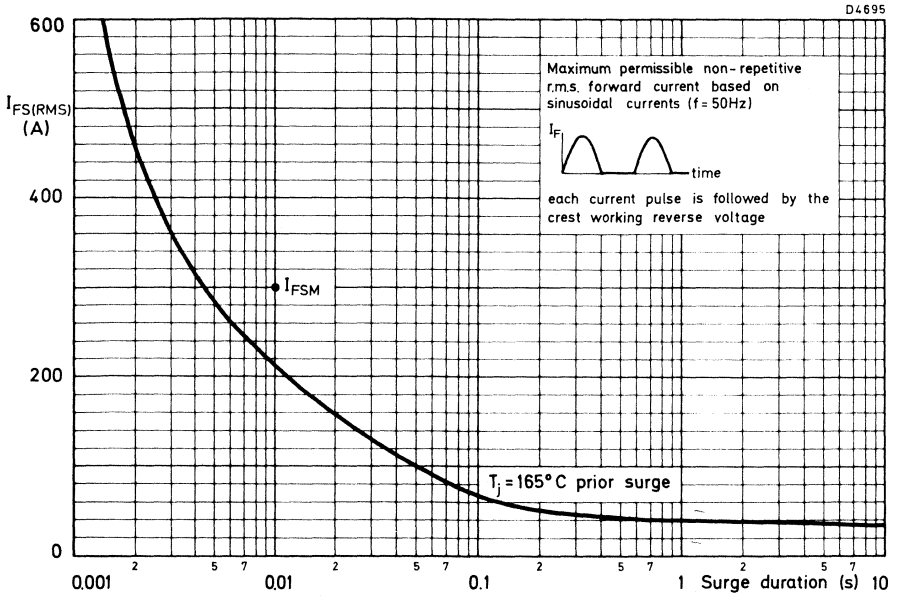


# BYX46 SERIES

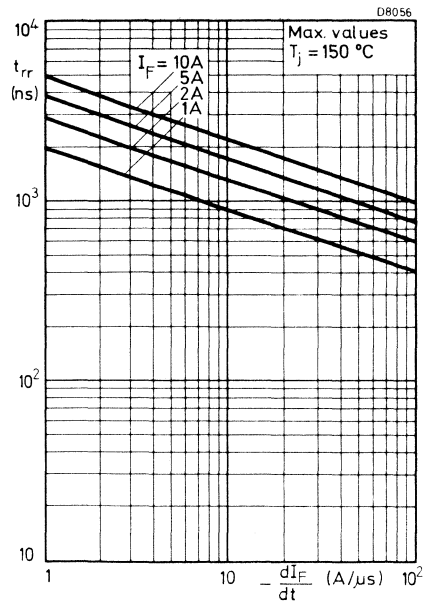
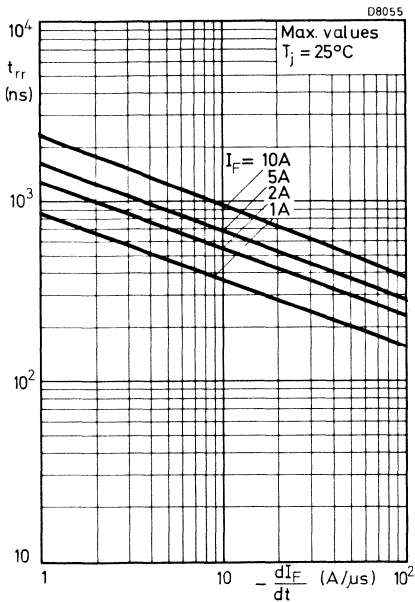
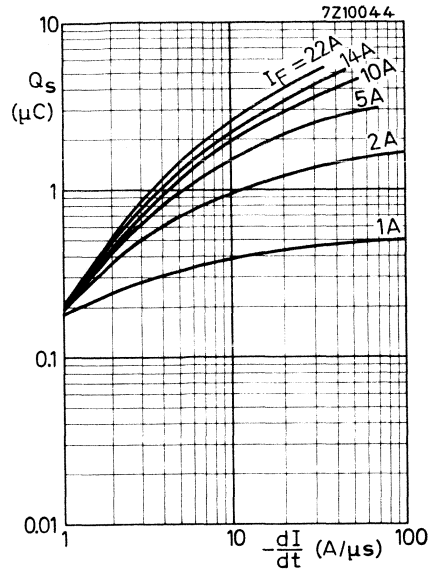
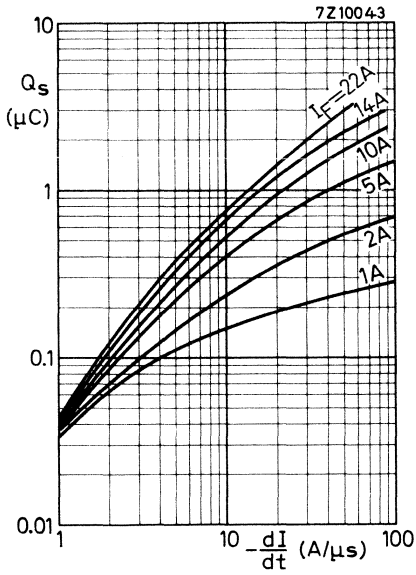




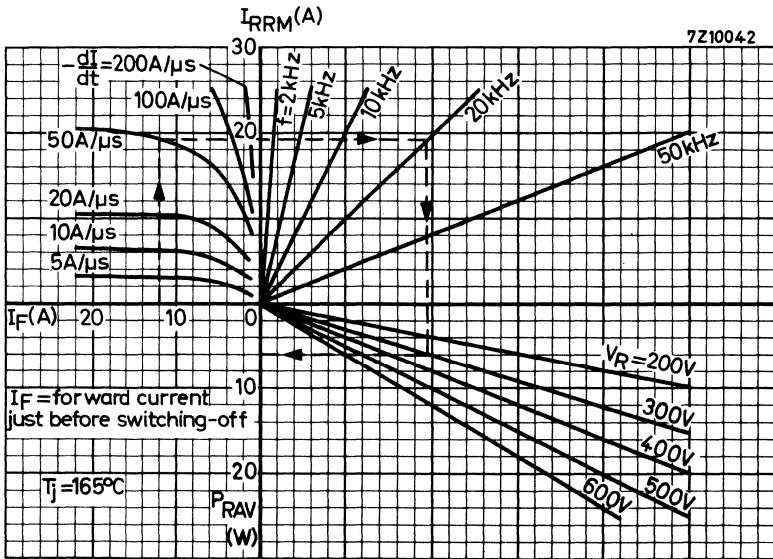
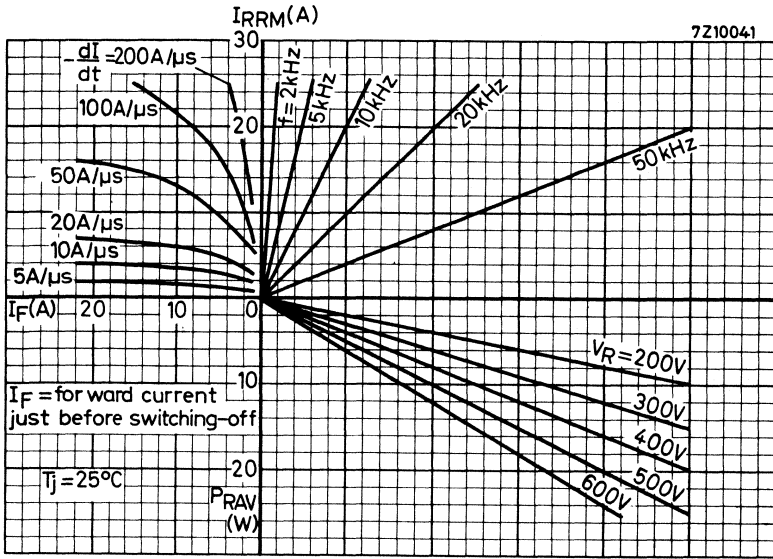
# BYX46 SERIES





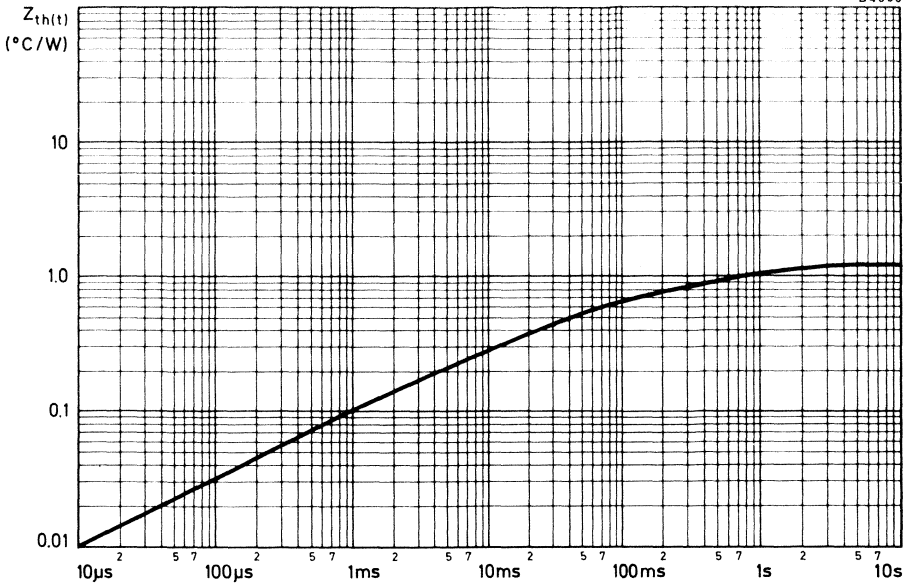


**BYX46  
SERIES**



Nomogram: Power loss  $P_{RAV}$  due to switching only (square wave operation)

D4696





**SILICON RECTIFIER DIODES**



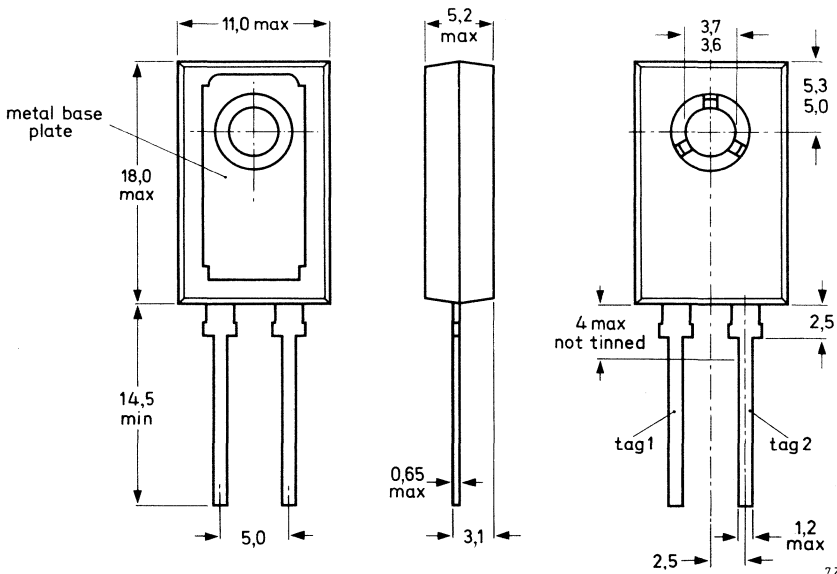
Plastic-encapsulated rectifier diodes intended for power rectifier applications.  
Normal and reverse polarity types are available.

QUICK REFERENCE DATA						
		BYX49-300(R)	600(R)	1200(R)		
Repetitive peak reverse voltage	$V_{RRM}$	max. 300	600	1200	V	
Average forward current	$I_{F(AV)}$		max. 6		A	
Non-repetitive peak forward current	$I_{FSM}$		max. 40		A	

**MECHANICAL DATA** (see also page 2)

Dimensions in mm

SOD-38



The exposed metal base-plate is directly connected to tag 1.



Products approved to CECC 50 009-011, available on request

**BYX49**  
**SERIES**

**MECHANICAL DATA** (continued)

Net mass : 2,5 g

Recommended diameter of fixing screw : 3,5 mm

Torque on screw

when using washer and heatsink compound : min. 0,95 Nm (9,5 kg cm)  
max. 1,5 Nm (15 kg cm)

Accessories :

supplied with device : washer

available on request : 56316 (mica insulating washer)

**POLARITY OF CONNECTIONS**

	BYX 49-300 to BYX 49-1200	BYX 49-300R to BYX 49-1200R
Base-plate :	cathode	anode
Tag 1 :	cathode	anode
Tag 2 :	anode	cathode

All information applies to frequencies up to 400 Hz.

**RATINGS** Limiting values in accordance with the Absolute Maximum System (IEC134)

<u>Voltages</u>		BYX49-300(R)	600(R)	1200(R)	
Continuous reverse voltage	$V_R$	max. 200	400	800	V
Crest working reverse voltage	$V_{RWM}$	max. 200	400	800	V
Repetitive peak reverse voltage ( $\delta = 0,01$ )	$V_{RRM}$	max. 300	600	1200	V
Non-repetitive peak reverse voltage ( $t \leq 10$ ms)	$V_{RSM}$	max. 300	600	1200	V

Currents

Average forward current (averaged over any 20 ms period) up to $T_{mb} = 85$ °C	$I_{F(AV)}$	max. 6,0	A
at $T_{mb} = 120$ °C	$I_{F(AV)}$	max. 3,0	A
without heatsink; at $T_{amb} = 50$ °C	$I_{F(AV)}$	max. 1,1	A
Forward current (d.c.)	$I_F$	max. 9,5	A
R. M. S. forward current	$I_{F(RMS)}$	max. 9,5	A
Repetitive peak forward current	$I_{FRM}$	max. 20	A
Non-repetitive peak forward current ( $t = 10$ ms; half sine wave) $T_j = 150$ °C prior to surge	$I_{FSM}$	max. 40	A
$I^2t$ for fusing ( $t = 10$ ms)	$I^2t$	max. 8,0	$A^2s$

Temperatures

Storage temperature	$T_{stg}$	-55 to +125	°C
Junction temperature	$T_j$	max. 150	°C

**THERMAL RESISTANCE**

From junction to mounting base

$$R_{th\ j-mb} = 4,5\ ^\circ C/W$$

Transient thermal impedance;  $t = 1\ ms$

$$Z_{th\ j-mb} = 0,3\ ^\circ C/W$$

**Influence of mounting method :**

1. Heatsink mounted

From mounting base to heatsink

- a. with heatsink compound
- b. with heatsink compound and 56316 mica washer
- c. without heatsink compound
- d. without heatsink compound; with 56316 mica washer

$$R_{th\ mb-h} = 1,5\ ^\circ C/W$$

$$R_{th\ mb-h} = 2,7\ ^\circ C/W$$

$$R_{th\ mb-h} = 2,7\ ^\circ C/W$$

$$R_{th\ mb-h} = 5\ ^\circ C/W$$

2. Free air operation

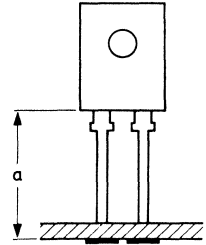
The quoted values of  $R_{th\ j-a}$  should be used only when no other leads run to the tie-points.

From junction to ambient in free air mounted on a printed circuit board at  $a =$  maximum lead length and with a copper laminate

- a.  $> 1\ cm^2$
- b.  $< 1\ cm^2$

$$R_{th\ j-a} = 50\ ^\circ C/W$$

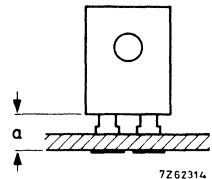
$$R_{th\ j-a} = 55\ ^\circ C/W$$



- at a lead-length  $a = 3\ mm$  and with a copper laminate
- c.  $> 1\ cm^2$
  - d.  $< 1\ cm^2$

$$R_{th\ j-a} = 55\ ^\circ C/W$$

$$R_{th\ j-a} = 60\ ^\circ C/W$$





**CHARACTERISTICS**Forward voltage

$$I_F = 20 \text{ A}; T_j = 25 \text{ }^\circ\text{C} \qquad V_F < 2,3 \text{ V } ^1)$$

Reverse current

$$V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C} \qquad I_R < 200 \text{ } \mu\text{A}$$

**SOLDERING AND MOUNTING NOTES**

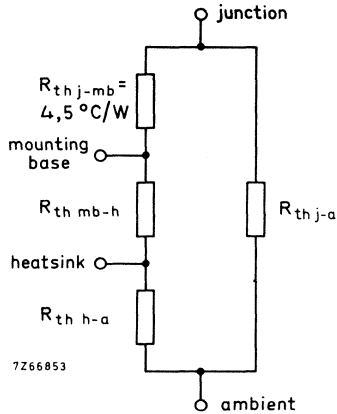
1. Soldered joints must be at least 2,5 mm from the seal.
2. The maximum permissible temperature of the soldering iron or bath is 270 °C; contact with the joint must not exceed 3 seconds.
3. The devices should not be immersed in oil, and few potting resins are suitable for re-encapsulation. Advice on these materials is available on request.
4. Leads should not be bent less than 2,5 mm from the seal; exert no axial pull when bending.
5. For good thermal contact heatsink compound should be used between base-plate and heatsink.

<sup>1)</sup> Measured under pulse conditions to avoid excessive dissipation.

**OPERATING NOTES**

Dissipation and heatsink considerations:

- a. The various components of junction temperature rise above ambient are illustrated below:



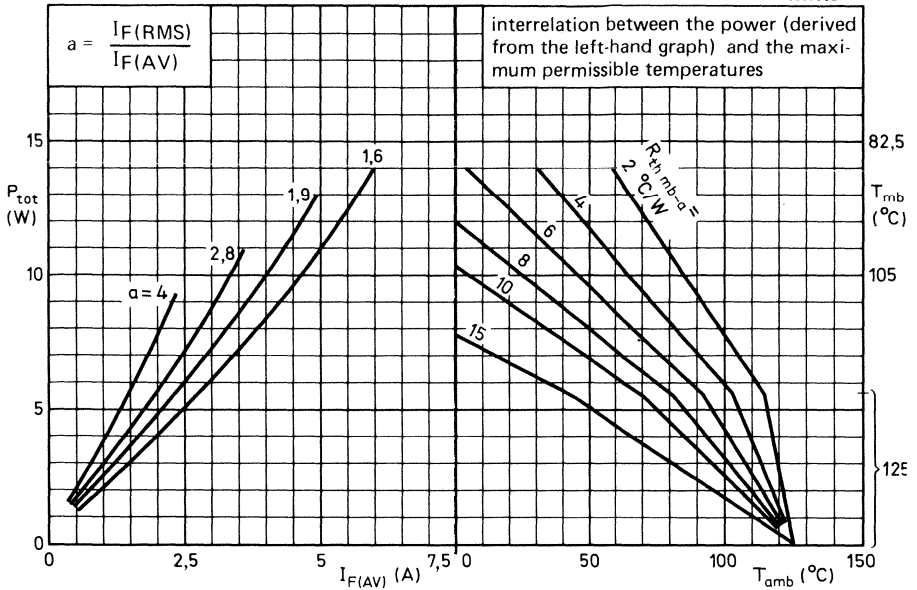
- b. The method of using the graph on page 7 is as follows:  
 Starting with the curve of maximum dissipation as a function of  $I_{F(AV)}$ , for a particular current value trace upwards to meet the appropriate form factor curve. Trace horizontally until the  $R_{th\ mb-a}$  curve is reached. Finally trace upwards from the  $T_{amb}$  scale. The intersection determines the  $R_{th\ mb-a}$  required.  
 The heatsink thermal resistance value ( $R_{th\ h-a}$ ) can now be calculated from:

$$R_{th\ h-a} = R_{th\ mb-a} - R_{th\ mb-h}$$

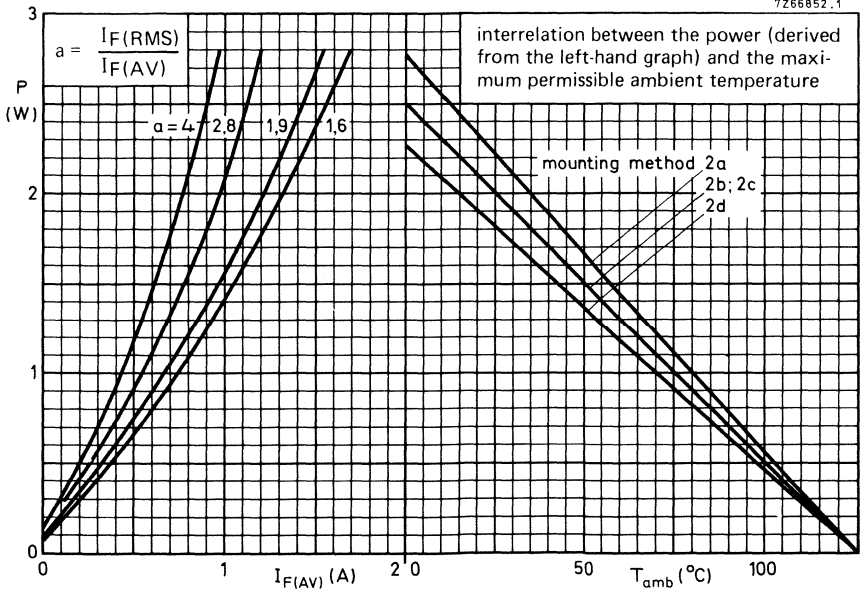
Any measurement of heatsink temperature should be made immediately adjacent to the device.

- c. The heatsink curves are optimised to allow the junction temperature to run up to  $150\ ^\circ\text{C}$  ( $T_{j\ max}$ ) whilst limiting  $T_{mb}$  to  $125\ ^\circ\text{C}$  (or less).

7Z59990.2

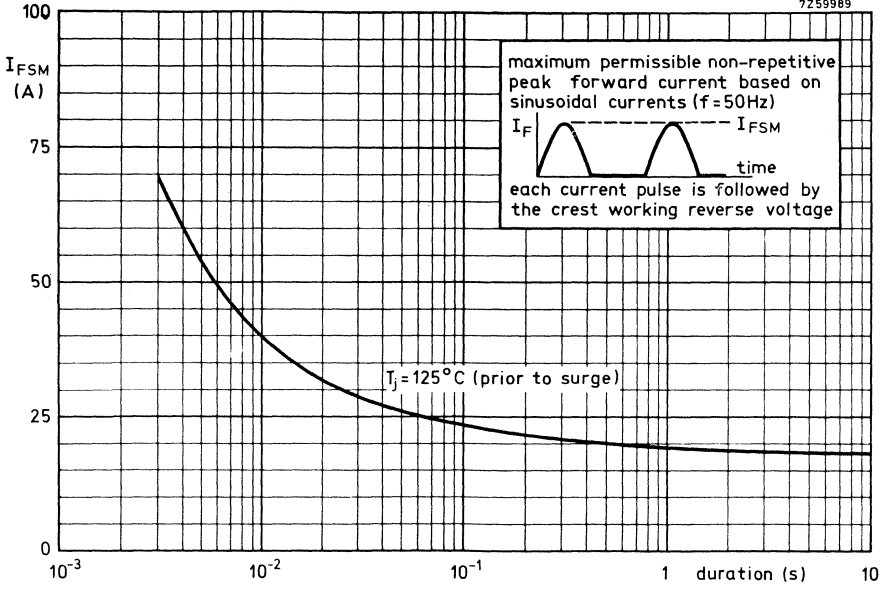


7Z66852.1

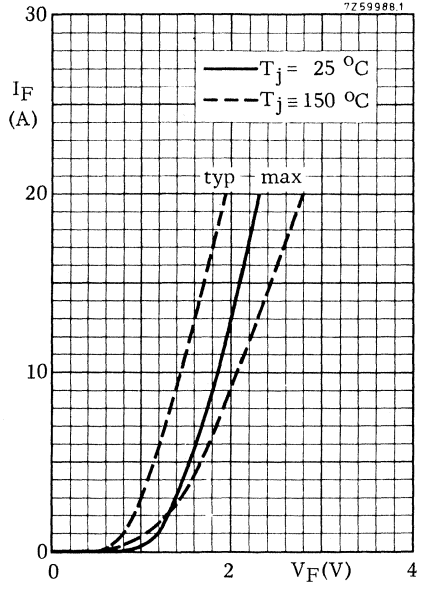


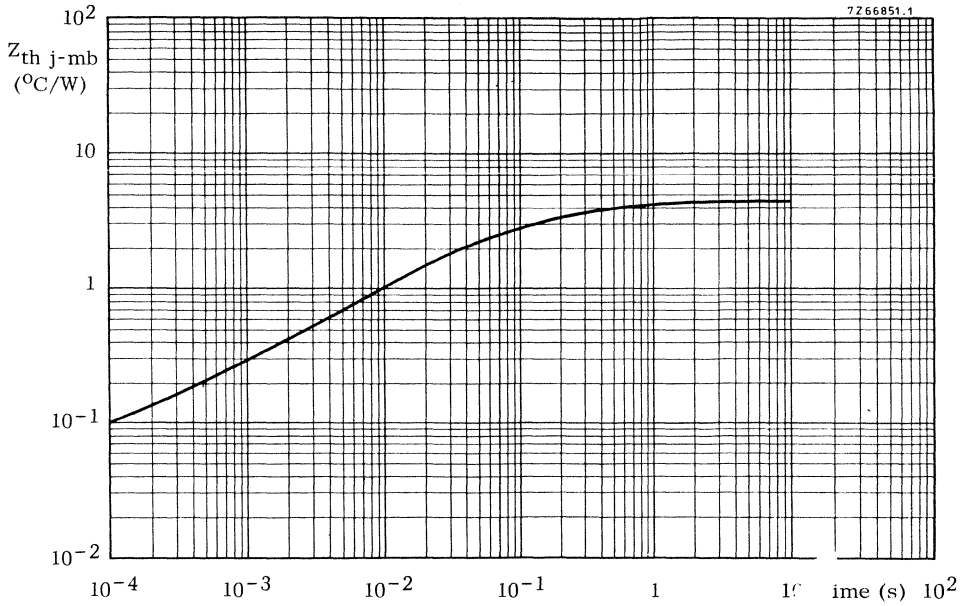
**BYX49  
SERIES**

7259989



72599881







FAST SOFT-RECOVERY RECTIFIER DIODES

Also available to BS9331-F028

Silicon diodes in DO-4 metal envelopes, intended for use in high-frequency power supplies, thyristor inverters and multi-phase power rectifier applications. The series consists of the following types:

Normal polarity (cathode to stud): BYX50-200, 300

Reverse polarity (anode to stud): BYX50-200R, 300R

These devices feature non-snap-off characteristics.

QUICK REFERENCE DATA

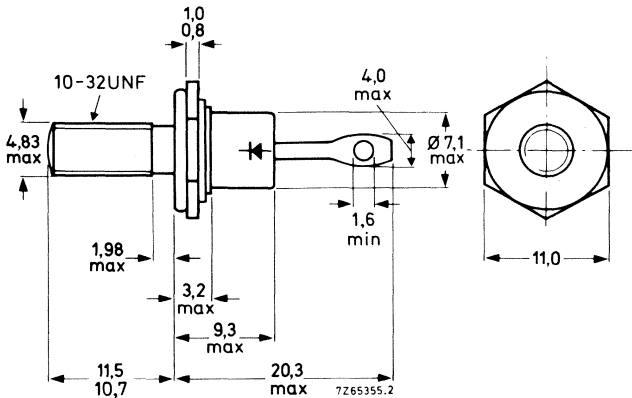
		BYX50-200(R)		300(R)	
Repetitive peak reverse voltage	$V_{RRM}$	max. 200	300	V	
Average forward current	$I_{F(AV)}$	max. 7		A	
Non-repetitive peak forward current	$I_{FSM}$	max. 80		A	
Reverse recovery time	$t_{rr}$	<	100	ns	

MECHANICAL DATA

Dimensions in mm

DO-4, Supplied with device: 1 nut, 1 lock washer

Nut dimensions across the flats: 9.5 mm



Net mass: 6 g

Diameter of clearance hole: max. 5.2 mm

Accessories supplied on request:

56295 (PTFE bush, 2 mica washers, plain washer, tag)

Torque on nut: min. 0.9 Nm  
(9 kg cm)

max. 1.7 Nm  
(17 kg cm)

The mark shown applies to the normal polarity types.

# BYX50 SERIES

**RATINGS** Limiting values in accordance with the Absolute Maximum System (IEC 134)

## Voltages

		BYX50-200(R)	300(R)	
Non-repetitive peak reverse voltage; $t \leq 10$ ms	$V_{RSM}$	max. 250	350	V
Repetitive peak reverse voltage	$V_{RRM}$	max. 200	300	V
Crest working reverse voltage	$V_{RWM}$	max. 200	300	V
Continuous reverse voltage	$V_R$	max. 200	300	V

## Currents

Average on-state current assuming zero switching losses (averaged over any 20 ms period)				
up to $T_{mb} = 103$ °C	$I_F(AV)$	max.	7	A
at $T_{mb} = 125$ °C	$I_F(AV)$	max.	4	A
R. M. S. forward current	$I_F(RMS)$	max.	11	A
Repetitive peak forward current	$I_{FRM}$	max.	80	A
Non-repetitive peak forward current $t = 10$ ms; $T_j = 150$ °C prior to surge with reapplied $V_{RWMmax}$	$I_{FSM}$	max.	80	A
$I^2t$ for fusing ( $t = 10$ ms)	$I^2t$	max.	32	A <sup>2</sup> s
Rate of change of commutation current				See nomogram on page 5

## Temperatures

Storage temperature	$T_{stg}$	-55 to +150	°C
Junction temperature	$T_j$	max. 150	°C

## **THERMAL RESISTANCE**

From junction to ambient in free air	$R_{th j-a}$	=	50	°C/W
From junction to mounting base	$R_{th j-mb}$	=	3,5	°C/W
From mounting base to heatsink	$R_{th mb-h}$	=	0,5	°C/W
Transient thermal impedance; $t = 1$ ms	$Z_{th j-mb}$	=	1	°C/W



**CHARACTERISTICS**

Forward voltage

$I_F = 20 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$   $V_F < 1,95 \text{ V}^1)$

Reverse current

$V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$   $I_R < 3 \text{ mA}$

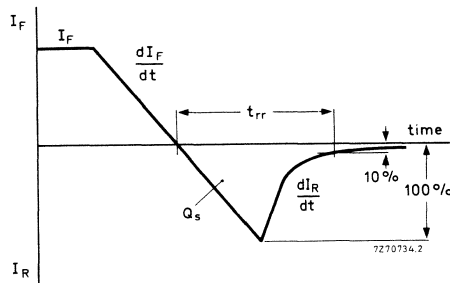
Reverse recovery when switched from

$I_F = 1 \text{ A to } V_R = 30 \text{ V};$   
 $-dI_F/dt = 100 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$   
 Recovery time  $t_{rr} < 100 \text{ ns}$

$I_F = 1 \text{ A to } V_R = 30 \text{ V};$   
 $-dI_F/dt = 35 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$   
 Recovery time  $t_{rr} < 150 \text{ ns}$

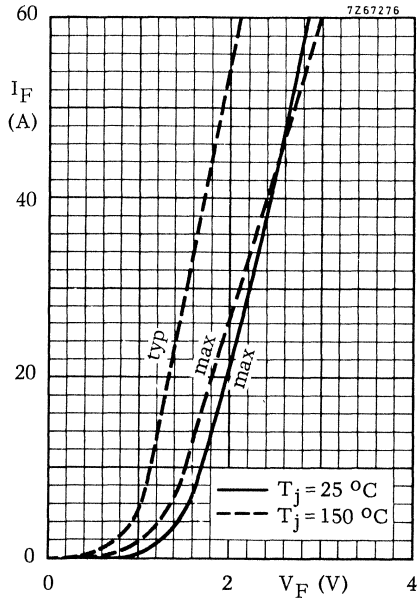
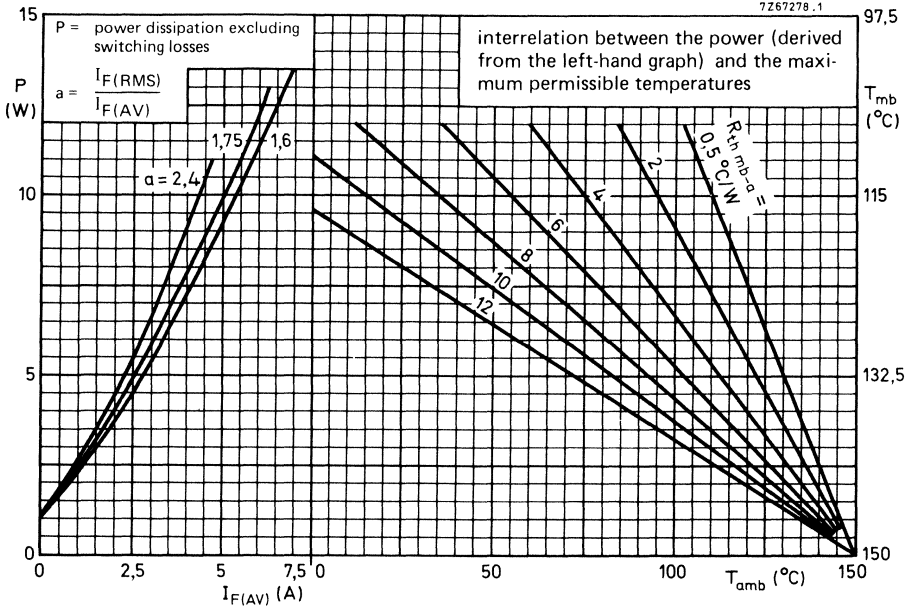
$I_F = 2 \text{ A to } V_R = 30 \text{ V};$   
 $-dI_F/dt = 20 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$   
 Recovered charge  $Q_s < 250 \text{ nC}$

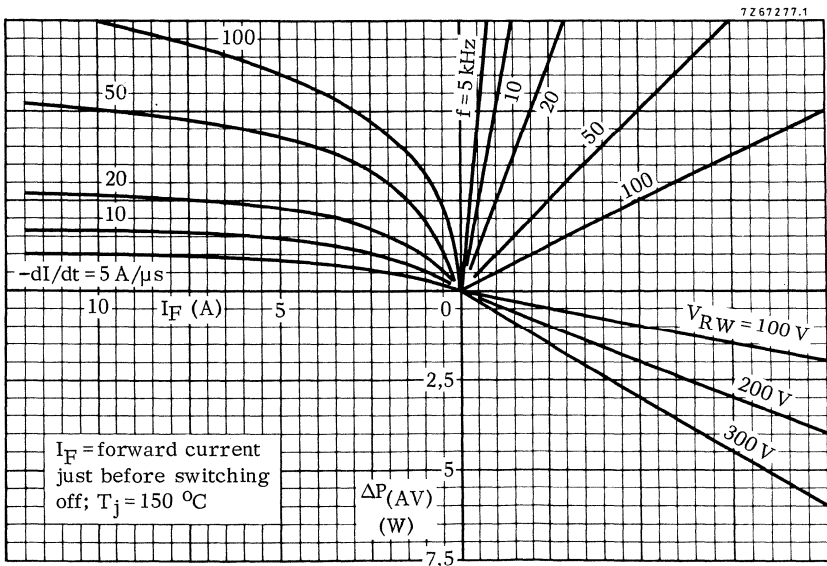
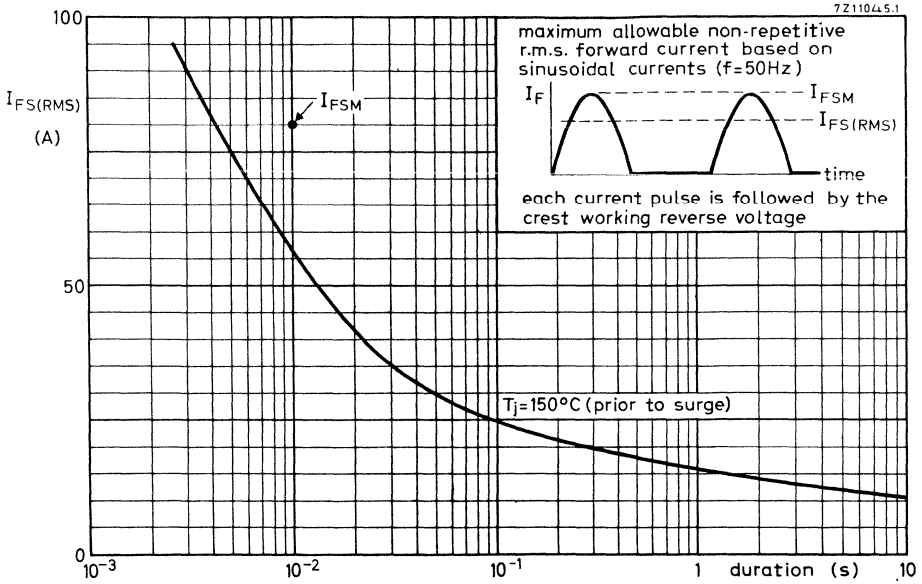
$I_F = 2 \text{ A to } V_R = 50 \text{ V};$   
 $-dI_F/dt = 2 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$   
 Max. slope of the reverse recovery current  $|dI_R/dt| < 5 \text{ A}/\mu\text{s}$



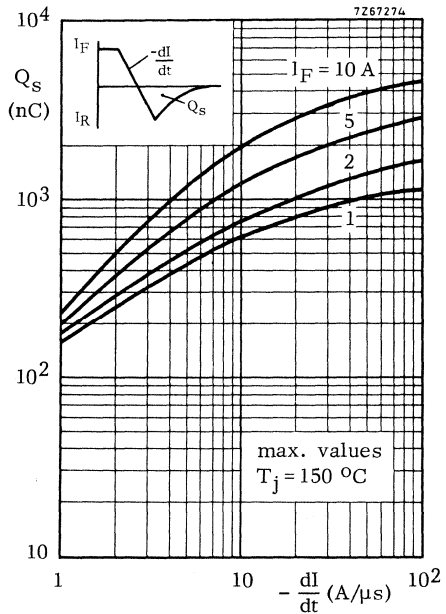
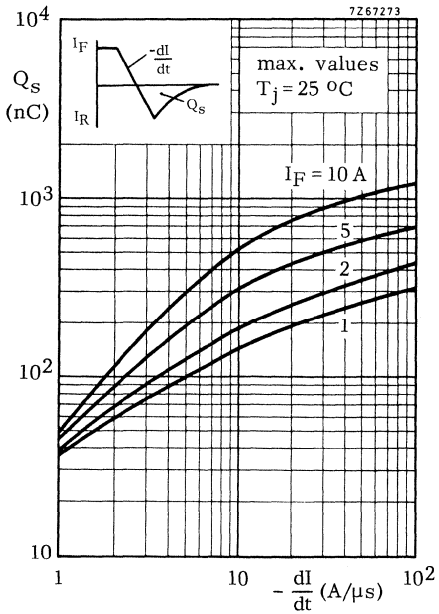
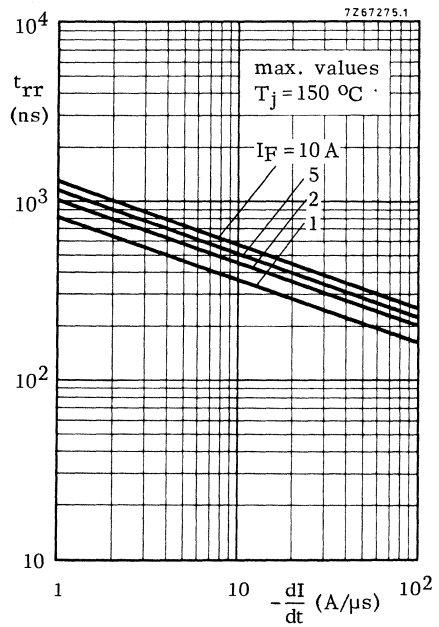
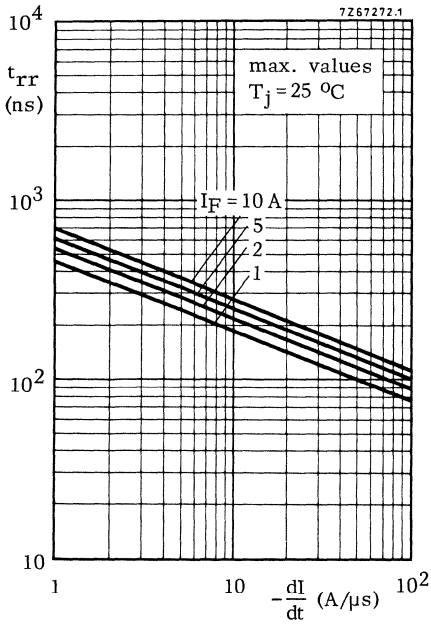
<sup>1)</sup> Measured under pulse conditions to avoid excessive dissipation.

# BYX50 SERIES

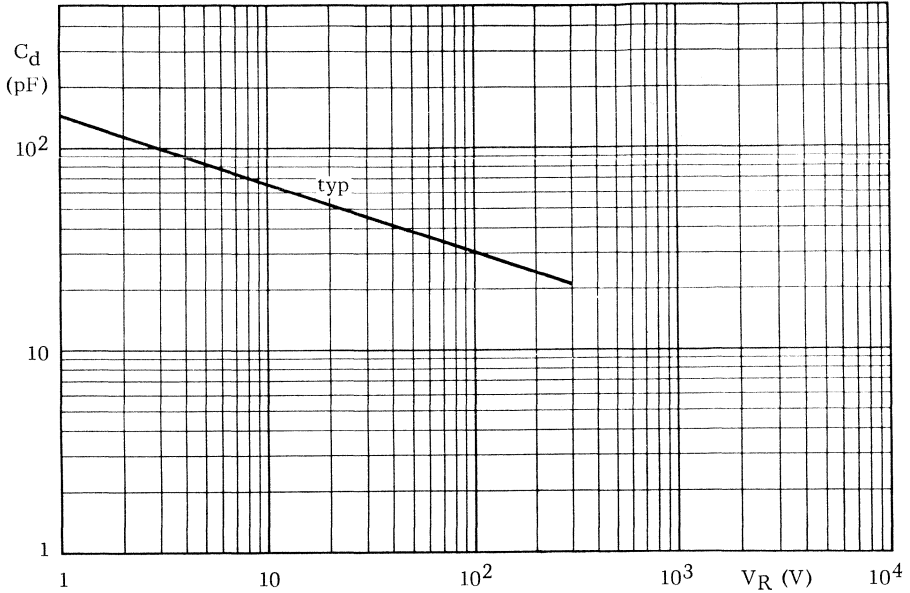




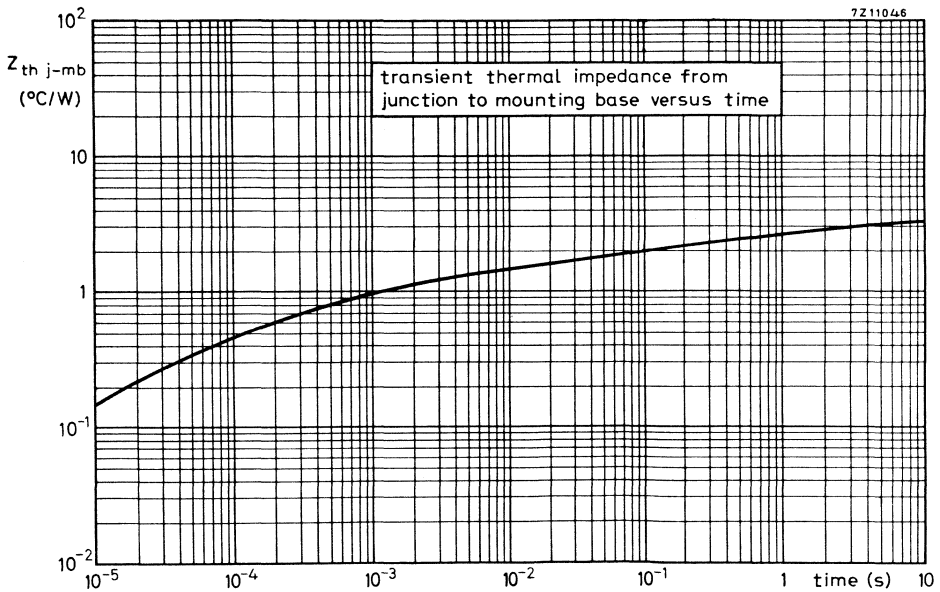
**BYX50  
SERIES**



7Z67279



7Z11046





RECTIFIER DIODES

Also available to BS9331-F026

Silicon rectifier diodes in DO-5 metal envelopes, intended for use in power rectifier applications.

The series consists of the following types:

Normal polarity (cathode to stud): BYX52-300, BYX52-600, BYX52-1200.

Reverse polarity (anode to stud): BYX52-300R, BYX52-600R, BYX52-1200R.

QUICK REFERENCE DATA

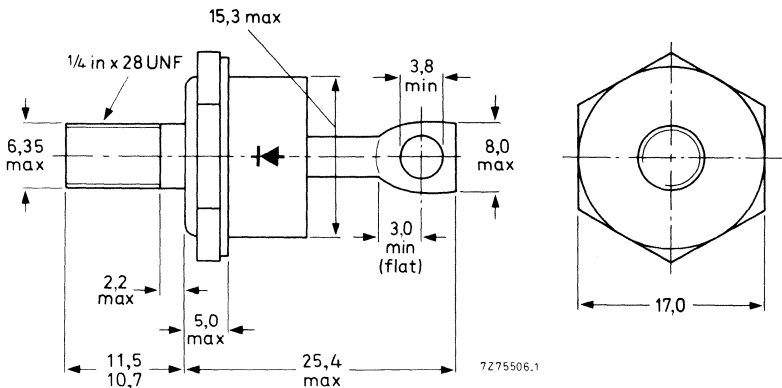
		BYX52-300(R)	600(R)	1200(R)	
Repetitive peak reverse voltage	$V_{RRM}$	max. 300	600	1200	V
Average forward current	$I_{F(AV)}$	max. 48		A	
Non-repetitive peak forward current	$I_{FSM}$	max. 800		A	

MECHANICAL DATA

Dimensions in mm

DO-5: Supplied with device: 1 nut, 1 lock-washer

Nut dimensions across the flats: 11,1 mm



Net mass: 22 g

Diameter of clearance hole: max. 6,5 mm

Accessories supplied on request:

56264A (mica washer, insulating ring, tag)

Torque on nut: min. 1,7 Nm

(17 kg cm)

max. 3,5 Nm

(35 kg cm)

The mark shown applies to the normal polarity types.

**RATINGS** Limiting values in accordance with the Absolute Maximum System (IEC 134)

### Voltages

		BYX52-300(R)	600(R)	1200(R)	
Non-repetitive peak reverse voltage ( $t \leq 10$ ms)	$V_{RSM}$	max. 300	600	1200	V
Repetitive peak reverse voltage ( $\delta = 0.01$ )	$V_{RRM}$	max. 300	600	1200	V
Crest working reverse voltage	$V_{RWM}$	max. 200	400	800	V

### Currents

Average forward current (averaged over any 20 ms period) up to $T_{mb} = 112$ °C	$I_{F(AV)}$	max.	48	A
at $T_{mb} = 125$ °C	$I_{F(AV)}$	max.	40	A
R. M. S. forward current	$I_{F(RMS)}$	max.	75	A
Repetitive peak forward current	$I_{FRM}$	max.	450	A
Non-repetitive peak forward current ( $t = 10$ ms; half-sinewave) $T_j = 175$ °C prior to surge	$I_{FSM}$	max.	800	A
$I^2t$ for fusing ( $t = 10$ ms)	$I^2t$	max.	3200	A <sup>2</sup> s

### Temperatures

Storage temperature	$T_{stg}$	-55 to +175	°C
Junction temperature	$T_j$	max. 175	°C

### THERMAL RESISTANCE

From junction to mounting base	$R_{th\ j-mb}$	=	0.8	°C/W
From mounting base to heatsink	$R_{th\ mb-h}$	=	0.2	°C/W

### CHARACTERISTICS

#### Forward voltage

$$I_F = 150 \text{ A}; T_j = 25 \text{ °C} \quad V_F < 1.8 \text{ V } ^1)$$

#### Reverse current

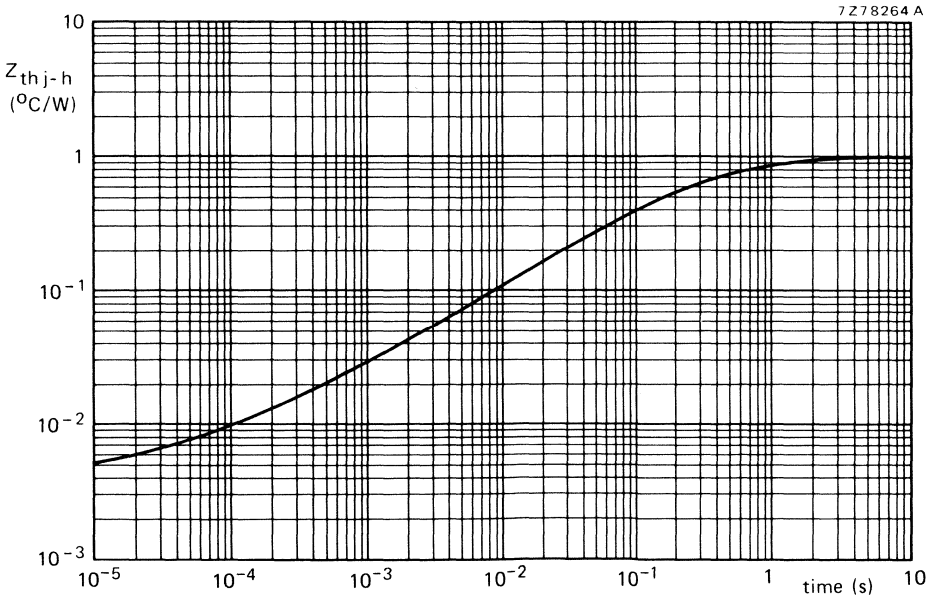
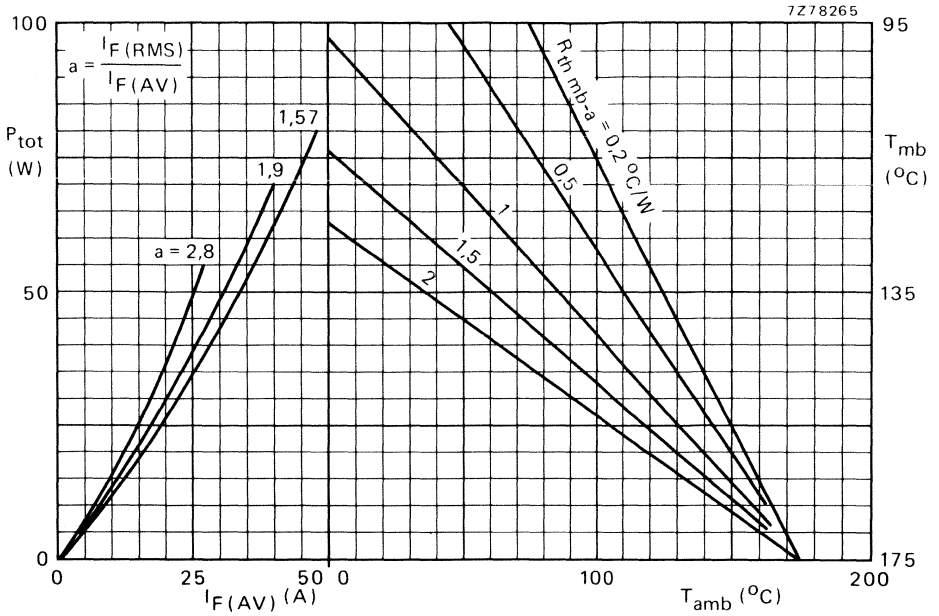
$$V_R = V_{RWM} \text{ max}; T_j = 125 \text{ °C} \quad I_R < 1.6 \text{ mA}$$

### OPERATING NOTES

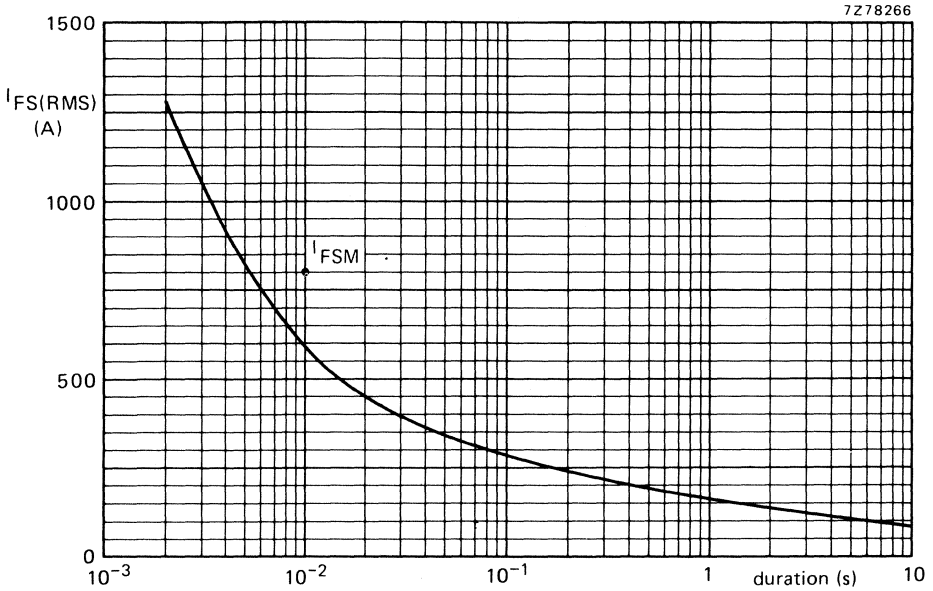
The top connector should neither be bent nor twisted; it should be soldered into the circuit so there is no strain on it.

<sup>1)</sup> Measured under pulse conditions to avoid excessive dissipation.

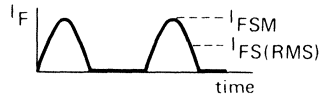
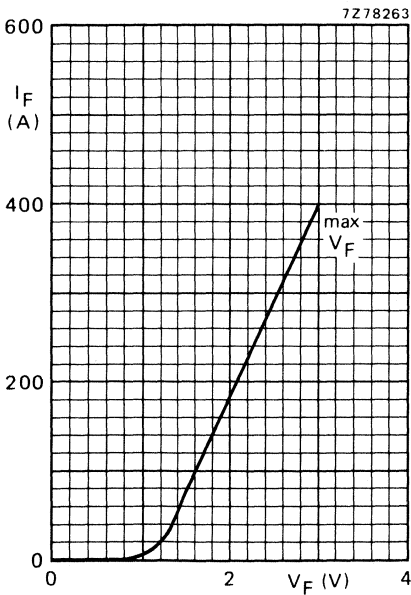




# BYX52 SERIES



Maximum permissible non-repetitive r.m.s. forward current based on sinusoidal currents ( $f = 50$  Hz);  $T_j = 175$  °C prior to surge; with reapplied  $V_{RWMmax}$ .



## CONTROLLED AVALANCHE RECTIFIER DIODES

Silicon diodes in a DO-5 metal envelope, capable of absorbing transients and intended for power rectifier applications.

The series consists of the following types:

Normal polarity (cathode to stud): BYX56-600 to BYX56-1400.

Reverse polarity (anode to stud): BYX56-600R to BYX56-1400R.

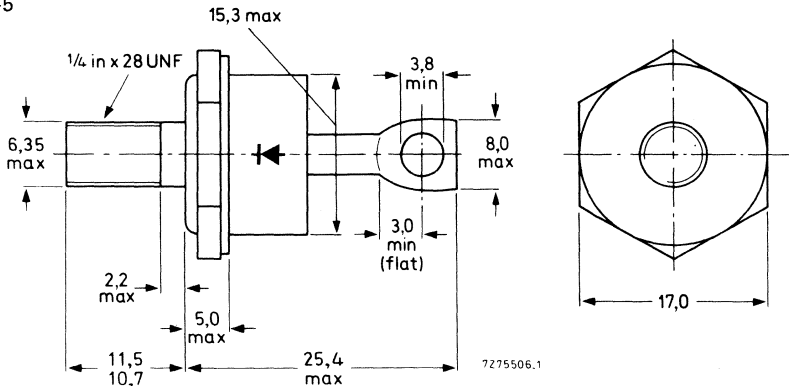
### QUICK REFERENCE DATA

		BYX56-600(R)   800(R)   1000(R)   1200(R)   1400(R)						
Crest working reverse voltage	$V_{RWM}$	max.	600	800	1000	1200	1400	V
Reverse avalanche breakdown voltage	$V_{(BR)R}$	>	750	1000	1250	1450	1650	V
Average forward current	$I_{F(AV)}$	max.	48			A		
Non-repetitive peak forward current	$I_{FSM}$	max.	800			A		
Non-repetitive peak reverse power dissipation	$P_{RSM}$	max.	40			kW		

### MECHANICAL DATA

Dimensions in mm

Fig. 1 DO-5



Net mass: 22 g

Diameter of clearance hole: max. 6.5 mm

Accessories supplied on request:

56264A (mica washer, insulating ring, tag).

Supplied with device: 1 nut, 1 lock washer.

Nut dimensions across the flats: 11.1 mm.

The mark shown applies to normal polarity types.

Torque on nut:

min. 1.7 Nm (17 kg cm),

max. 2.5 Nm (25 kg cm).

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC134)

→ Voltages*		BYX56-600(R)	800(R)	1000(R)	1200(R)	1400(R)	
Crest working reverse voltage	$V_{RWM}$	max. 600	800	1000	1200	1400	V
Continuous reverse voltage	$V_R$	max. 600	800	1000	1200	1400	V

## Currents

Average forward current

(averaged over any 20 ms period)

up to  $T_{mb} = 112\text{ }^\circ\text{C}$

at  $T_{mb} = 125\text{ }^\circ\text{C}$

$I_F(AV)$	max.	48	A
$I_F(AV)$	max.	40	A

R.M.S. forward current

$I_F(RMS)$	max.	75	A
------------	------	----	---

Repetitive peak forward current

$I_{FRM}$	max.	450	A
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Non-repetitive peak forward current

$t = 10\text{ ms}$  (half sine-wave);

$T_j = 175\text{ }^\circ\text{C}$  prior to surge;

with reapplied  $V_{RWMmax}$

$I_{FSM}$	max.	800	A
-----------	------	-----	---

$I^2 t$  for fusing ( $t \leq 10\text{ ms}$ )

$I^2 t$	max.	3200	$A^2 s$
---------	------	------	---------

## Reverse power dissipation

Repetitive peak reverse power dissipation

$t = 10\text{ }\mu\text{s}$  (square-wave;  $f = 50\text{ Hz}$ );

$T_j = 175\text{ }^\circ\text{C}$

$P_{RRM}$	max.	6.5	kW
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Non-repetitive peak reverse power dissipation

$t = 10\text{ }\mu\text{s}$  (square-wave)

$T_j = 25\text{ }^\circ\text{C}$  prior to surge

$T_j = 175\text{ }^\circ\text{C}$  prior to surge

$P_{RSM}$	max.	40	kW
$P_{RSM}$	max.	6.5	kW

## Temperatures

Storage temperature

$T_{stg}$		-55 to +175	$^\circ\text{C}$
-----------	--	-------------	------------------

Junction temperature

$T_j$	max.	175	$^\circ\text{C}$
-------	------	-----	------------------

## THERMAL RESISTANCE

From junction to mounting base

$R_{th\ j-mb}$	=	0.8	$^\circ\text{C/W}$
----------------	---	-----	--------------------

From mounting base to heatsink

$R_{th\ mb-h}$	=	0.2	$^\circ\text{C/W}$
----------------	---	-----	--------------------

Transient thermal impedance;  $t = 1\text{ ms}$

$Z_{th\ j-h}$	=	0.03	$^\circ\text{C/W}$
---------------	---	------	--------------------

\*To ensure thermal stability:  $R_{th\ j-a} < 2.2\text{ }^\circ\text{C/W}$  (a.c.)

**CHARACTERISTICS**

		BYX56-600(R)	800(R)	1000(R)	1200(R)	1400(R)	←
Forward voltage							
$I_F = 150 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$	$V_F$	< 1.8	1.8	1.8	1.8	1.8	V*
Reverse avalanche breakdown voltage							
$I_R = 5 \text{ mA}; T_j = 25 \text{ }^\circ\text{C}$	$V_{(BR)R}$	> 750	1000	1250	1450	1650	V
		< 2000	2000	2000	2200	2400	V
Reverse current							
$V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$	$I_R$	< 1.6	1.6	1.6	1.6	1.6	mA

**OPERATING NOTES**

The top connector should neither be bent nor twisted; it should be soldered into the circuit so that there is no strain on it.  
 During soldering the heat conduction to the junction should be kept to a minimum by using a thermal shunt.

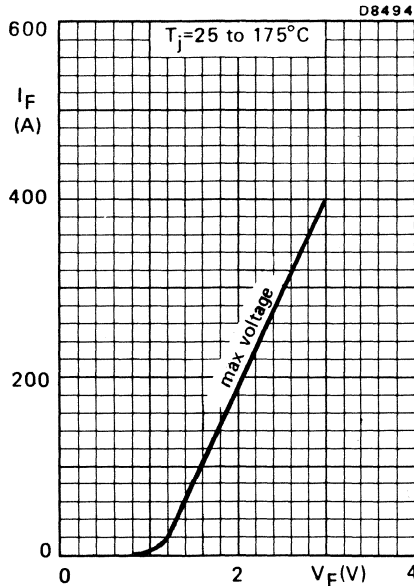


Fig.2

\*Measured under pulsed conditions to avoid excessive dissipation.

7259128

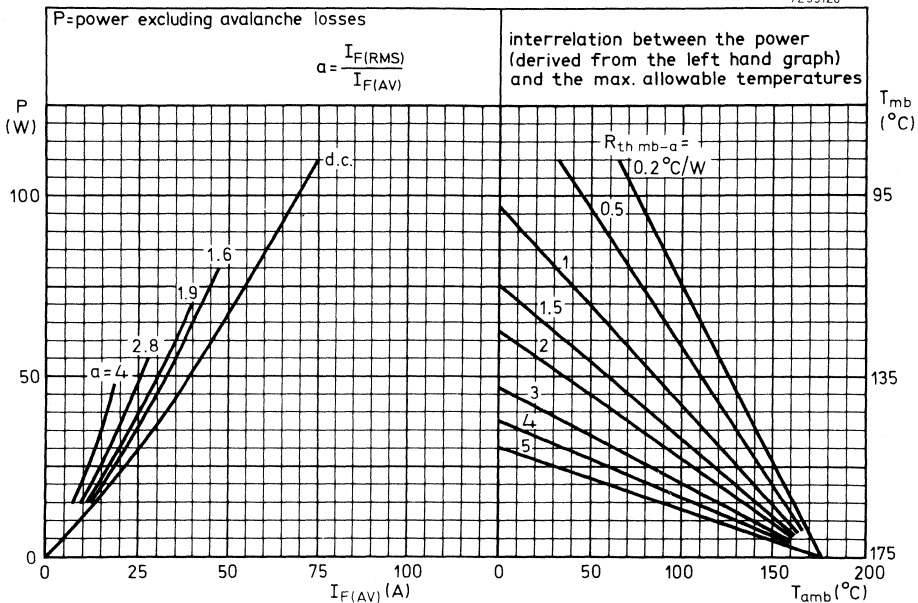


Fig.3

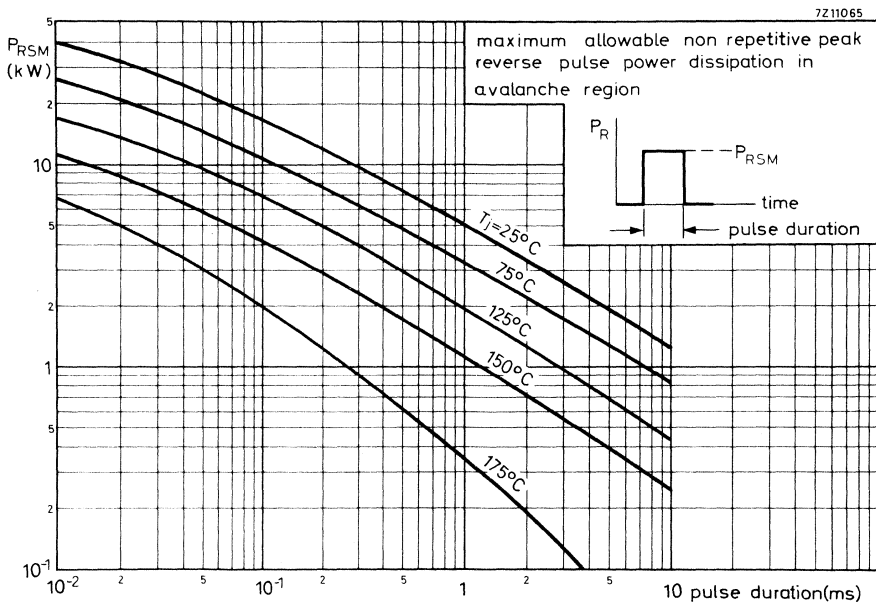


Fig.4

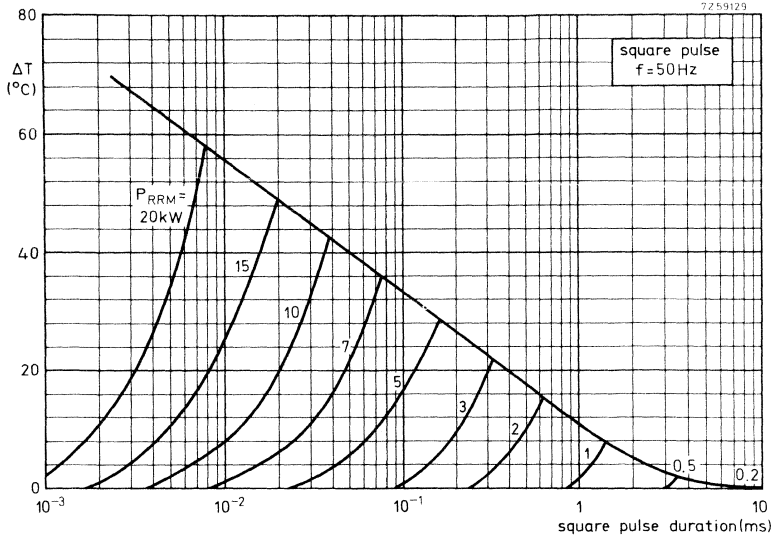


Fig.5

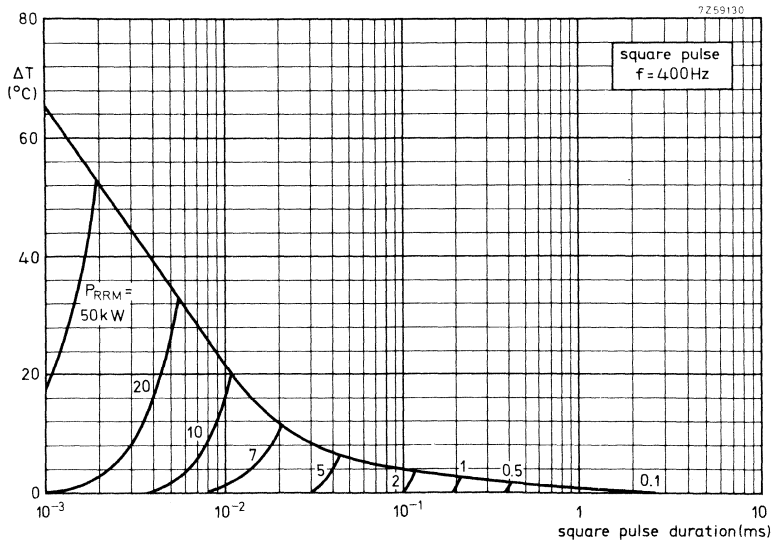


Fig.6

$\Delta T$  = necessary derating of  $T_{jmax}$  to accommodate repetitive transients in the reverse direction. Allowance can be made for this by assuming the ambient temperature  $\Delta T$  higher.

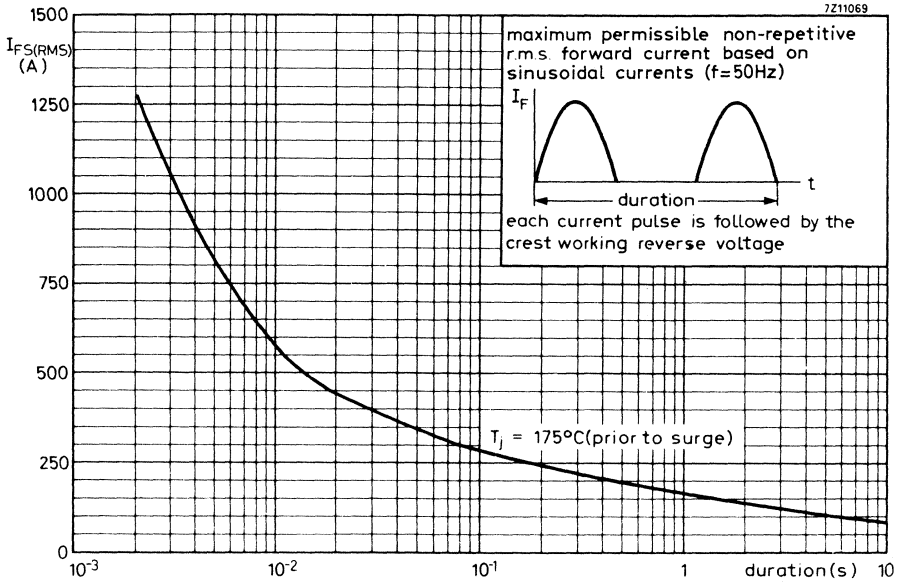


Fig.7

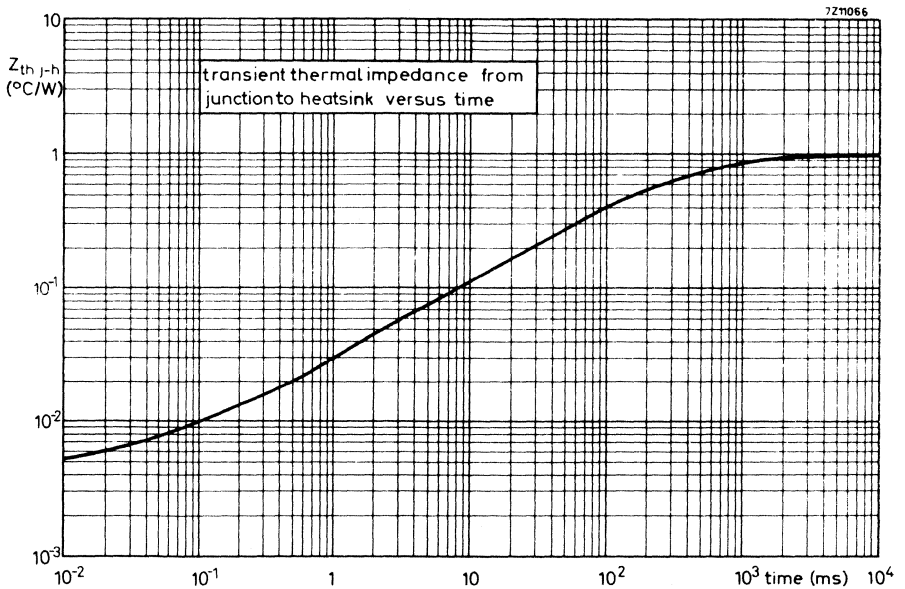


Fig.8



## FAST SOFT-RECOVERY RECTIFIER DIODES

Silicon double-diffused rectifier diodes in plastic envelopes. They are intended for use in chopper applications as well as in switched-mode power supplies, as efficiency diodes and scan rectifiers in television receivers. The devices feature non-snap-off characteristics. Normal and reverse polarity types are available.

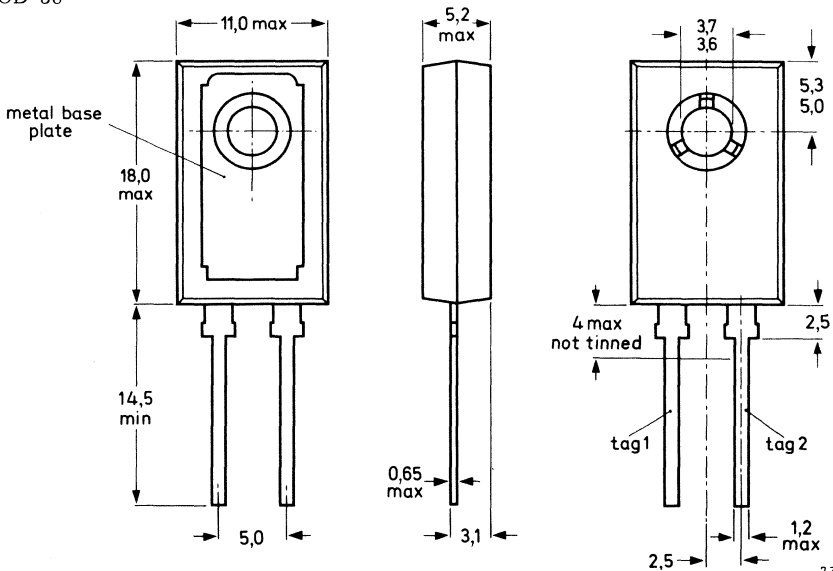
### QUICK REFERENCE DATA

		BYX71-350(R)		600(R)	V
		max.		600	
Repetitive peak reverse voltage	$V_{RRM}$	350		600	
Average forward current	$I_{F(AV)}$	max.	7		A
Non-repetitive peak forward current	$I_{FSM}$	max.	60		A
Reverse recovery time	$t_{rr}$	<	450		ns

### MECHANICAL DATA (see also page 2)

Dimensions in mm

SOD-38



7260001.5

The exposed metal base-plate is directly connected to tag 1.

# BYX71 SERIES

## MECHANICAL DATA (continued)

Net mass : 2,5 g

Recommended diameter of fixing screw : 3,5 mm

Torque on screw

when using washer and heatsink compound : min. 0,95 Nm (9,5 kg cm)  
max. 1,5 Nm (15 kg cm)

Accessories :

supplied with the device : 56355 (washer)

available on request : 56316 (mica insulating washer)

## POLARITY OF CONNECTIONS

	BYX71-350 and BYX71-600	BYX71-350R and BYX71-600R
Base-plate :	cathode	anode
Tag 1 :	cathode	anode
Tag 2 :	anode	cathode

**RATINGS** Limiting values in accordance with the Absolute Maximum System (IEC134)

<u>Voltages</u>		BYX71 -350(R)	600(R)	
Continuous reverse voltage	$V_R$	max. 300	500	V
Working reverse voltage	$V_{RW}$	max. 300	500	V
Repetitive peak reverse voltage ( $\delta \leq 0,01$ )	$V_{RRM}$	max. 350	600	V
Non-repetitive peak reverse voltage ( $t \leq 10$ ms)	$V_{RSM}$	max. 350	600	V
 <u>Currents</u>				
Average on-state current assuming zero switching losses (averaged over any 20 ms period)				
square wave; $\delta = 0,5$ ; up to $T_{mb} = 85$ °C	$I_{F(AV)}$	max.	7	A
without heatsink at $T_{amb} = 50$ °C	$I_{F(AV)}$	max.	1,4	A
sinusoidal: at $T_{mb} = 85$ °C	$I_{F(AV)}$	max.	6,5	A
R. M. S. forward current	$I_{F(RMS)}$	max.	10	A
Repetitive peak forward current	$I_{FRM}$	max.	25	A
Non-repetitive peak forward current				
half sine wave; $t = 10$ ms; $T_j = 150$ °C prior to surge	$I_{FSM}$	max.	60	A
square pulse; $t = 5$ ms; $T_j = 150$ °C prior to surge	$I_{FSM}$	max.	60	A
Rate of change of commutation current	$-\frac{di}{dt}$	max.	50	A/ $\mu$ s
 <u>Temperatures</u>				
Storage temperature	$T_{stg}$		-55 to +125	°C
Junction temperature	$T_j$	max.	150	°C

**THERMAL RESISTANCE**

From junction to mounting base

$$R_{th\ j-mb} = 6,5\ ^\circ C/W$$

Transient thermal impedance;  $t = 1\ ms$

$$Z_{th\ j-mb} = 0,3\ ^\circ C/W$$

**Influence of mounting method**

1. Heatsink mounted

From mounting base to heatsink

- a. with heatsink compound
- b. with heatsink compound and 56316 mica washer
- c. without heatsink compound
- d. without heatsink compound; with 56316 mica washer

$$R_{th\ mb-h} = 1,5\ ^\circ C/W$$

$$R_{th\ mb-h} = 2,7\ ^\circ C/W$$

$$R_{th\ mb-h} = 2,7\ ^\circ C/W$$

$$R_{th\ mb-h} = 5\ ^\circ C/W$$

2. Free air operation

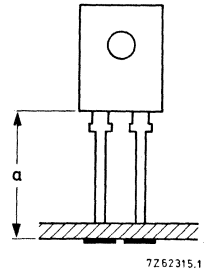
The quoted values of  $R_{th\ j-a}$  should be used only when no other leads run to the tie-points.

From junction to ambient in free air mounted on a printed circuit board at  $a =$  maximum lead length and with a copper laminate

- a.  $> 1\ cm^2$
- b.  $< 1\ cm^2$

$$R_{th\ j-a} = 50\ ^\circ C/W$$

$$R_{th\ j-a} = 55\ ^\circ C/W$$

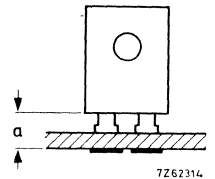


at a lead-length  $a = 3\ mm$  and with a copper laminate

- c.  $> 1\ cm^2$
- d.  $< 1\ cm^2$

$$R_{th\ j-a} = 55\ ^\circ C/W$$

$$R_{th\ j-a} = 60\ ^\circ C/W$$



**SOLDERING AND MOUNTING NOTES**

1. Soldered joints must be at least 2,5 mm from the seal.
2. The maximum permissible temperature of the soldering iron or bath is 270 °C; contact with the joint must not exceed 3 seconds.
3. The device should not be immersed in oil, and few potting resins are suitable for re-encapsulation. Advice on these materials is available on request.
4. Leads should not be bent less than 2,5 mm from the seal; exert no axial pull when bending.
5. For good thermal contact heatsink compound should be used between base-plate and heatsink.

**CHARACTERISTICS**

Forward voltage

$$I_F = 5 \text{ A}; T_j = 25 \text{ }^\circ\text{C} \qquad V_F < 1,25 \text{ V } ^1)$$

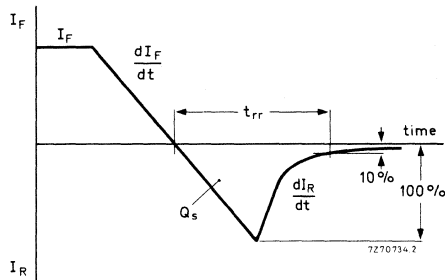
Reverse current

$$V_R = V_{RW_{max}}; T_j = 125 \text{ }^\circ\text{C} \qquad I_R < 0,4 \text{ mA}$$

Reverse recovery when switched from

$$I_F = 2 \text{ A to } V_R = 30 \text{ V with } -dI_F/dt = 20 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$$

Recovery charge	$Q_S$	$<$	700 nC
Recovery time	$t_{RR}$	$<$	450 ns
Max. slope of the reverse recovery current with $-dI_F/dt = 2 \text{ A}/\mu\text{s}$	$ dI_R/dt $	$<$	5 A/ $\mu\text{s}$



<sup>1)</sup> Measured under pulse conditions to avoid excessive dissipation.

**CHARACTERISTICS** (continued)

Forward recovery when switched to

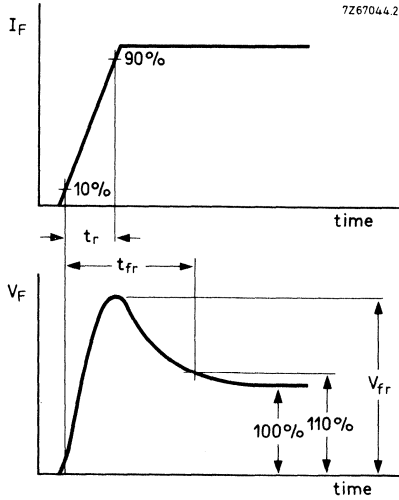
$I_F = 25 \text{ A}$  with  $t_r = 0,5 \mu\text{s}$  at  $T_j = 25 \text{ }^\circ\text{C}$

Recovery time

$t_{fr} < 0,8 \mu\text{s}$

Recovery voltage

$V_{fr} < 3,5 \text{ V}$

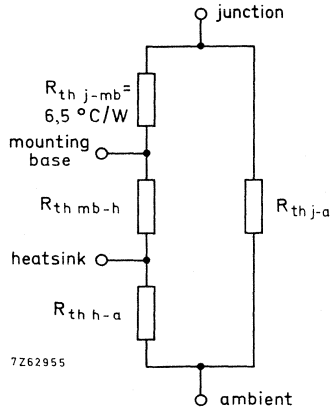


Forward output waveform

**OPERATING NOTES**

Dissipation and heatsink considerations:

- a. The various components of junction temperature rise above ambient are illustrated below:



- b. The method of using the graph on page 8 is as follows:  
Starting with the curve of maximum dissipation as a function of  $I_F(AV)$ , for a particular current trace horizontally to meet the appropriate form factor; upwards to the operating duty cycle ( $\delta$ ) line; horizontally until the  $R_{th\ mb-a}$  curve is reached. Finally trace upwards from the  $T_{amb}$  scale. The intersection determines the  $R_{th\ mb-a}$  required.  
The heatsink thermal resistance value ( $R_{th\ h-a}$ ) can now be calculated from:

$$R_{th\ h-a} = R_{th\ mb-a} - R_{th\ mb-h}$$

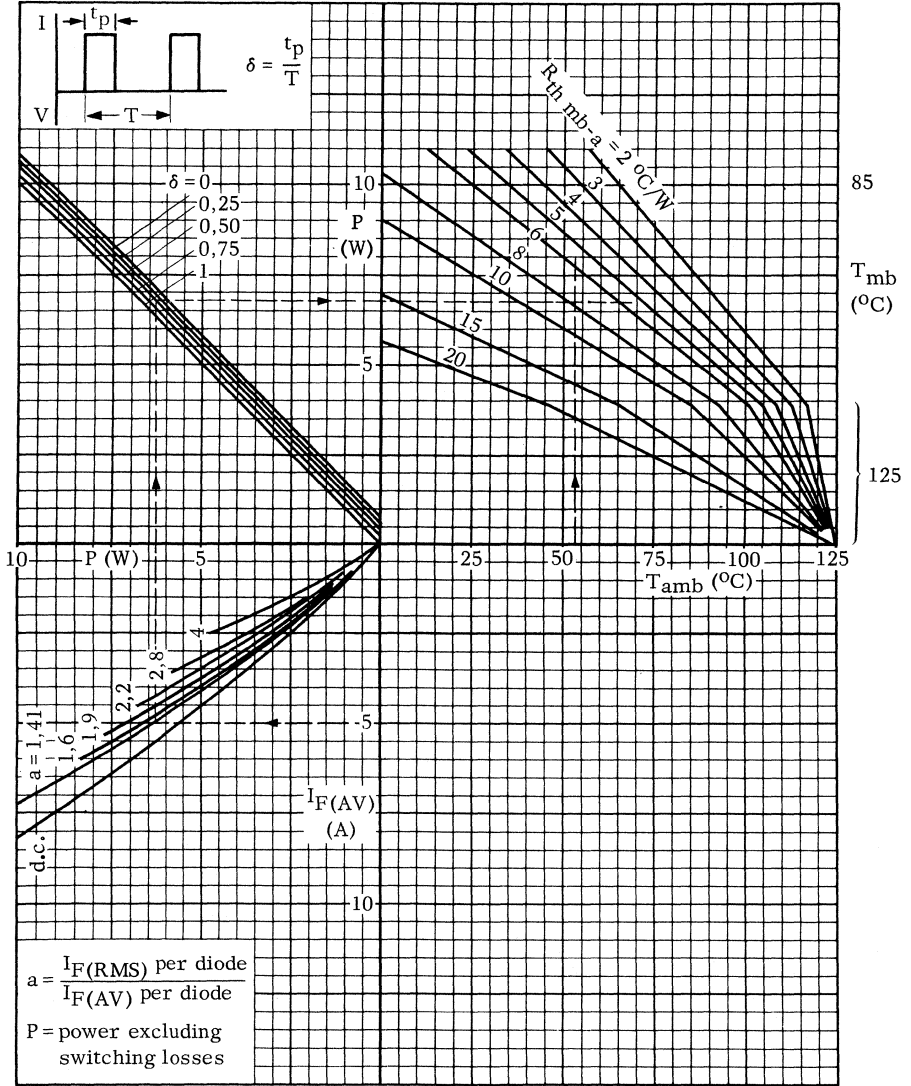
Any measurement of heatsink temperature should be made immediately adjacent to the device.

- c. The heatsink curves are optimised to allow the junction temperature to run up to 150 °C ( $T_{j\ max}$ ) whilst limiting  $T_{mb}$  to 125 °C (or less).

# BYX71 SERIES

## CHOPPER APPLICATIONS

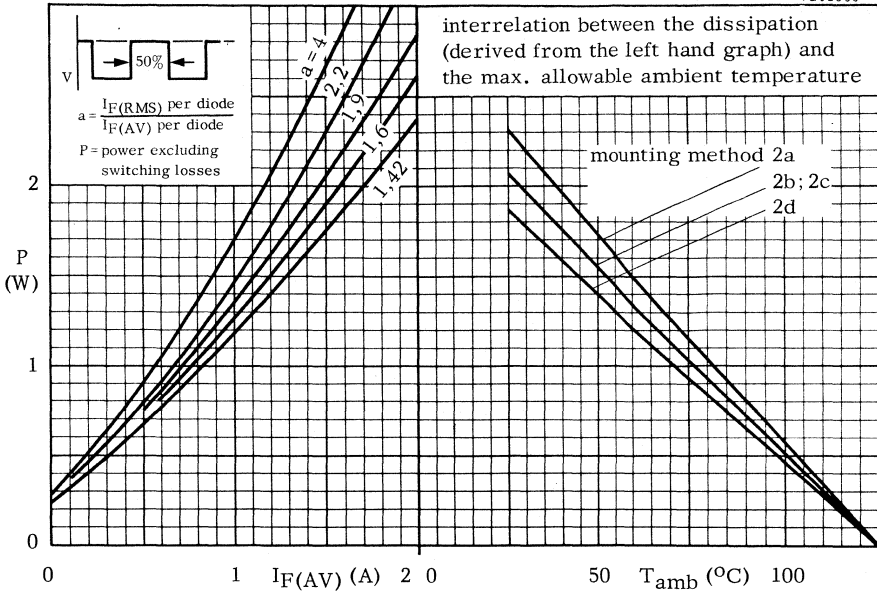
7Z67042





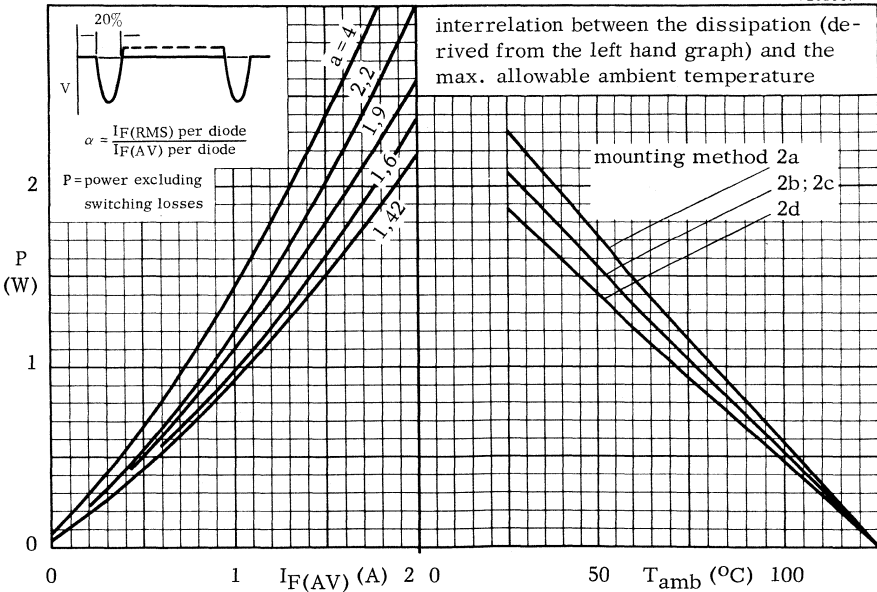
**SWITCHED-MODE APPLICATION**

7Z62958

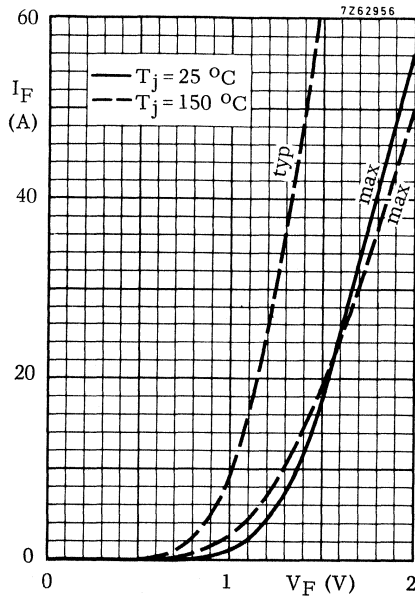
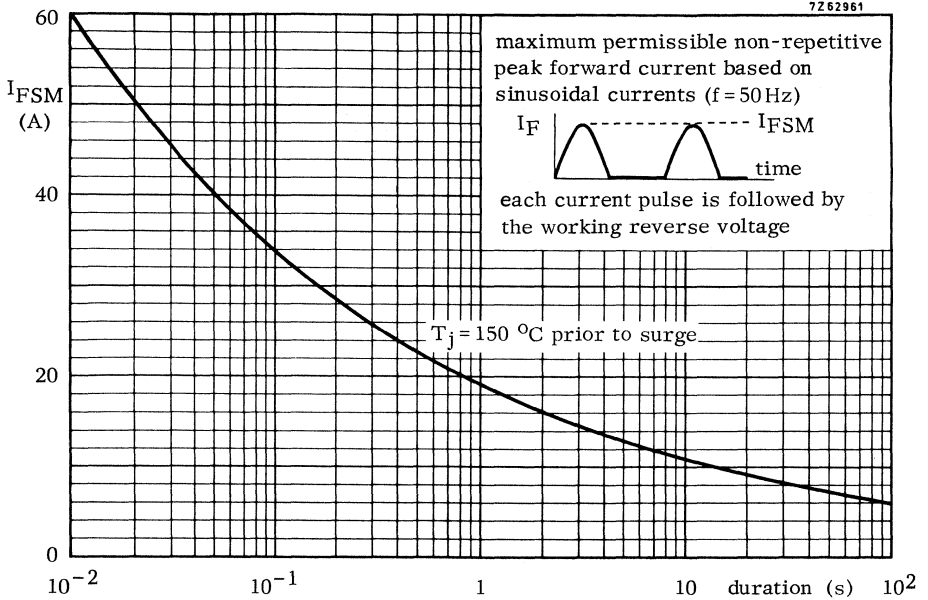


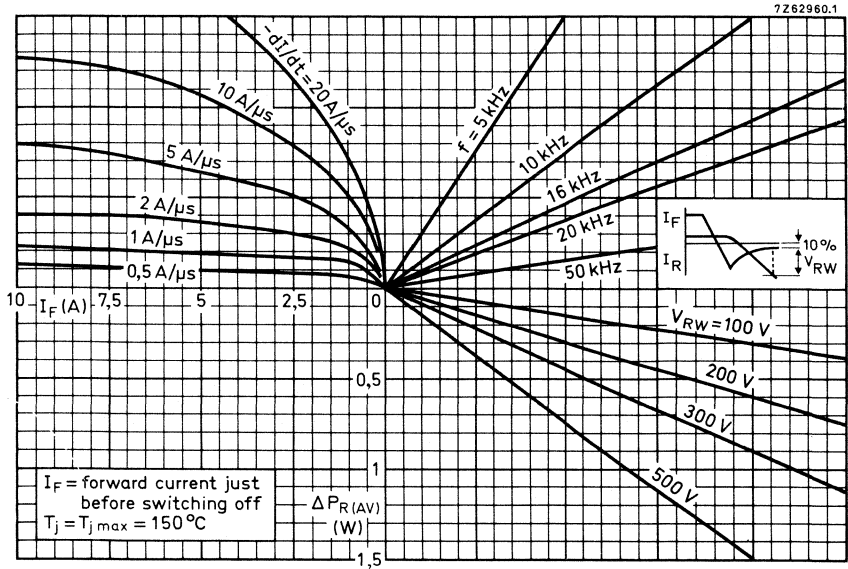
**SCAN RECTIFICATION**

7Z62957

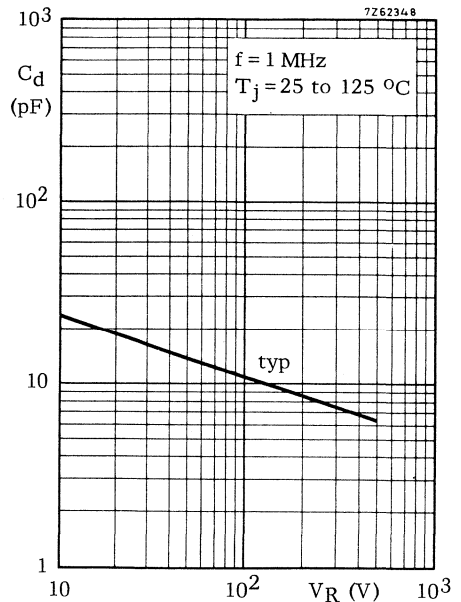
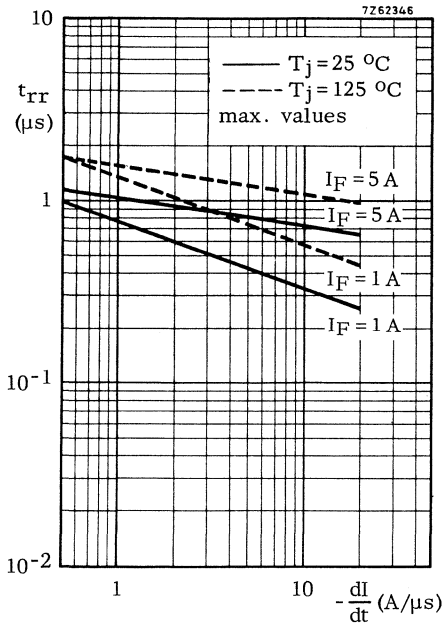


**BYX71  
SERIES**

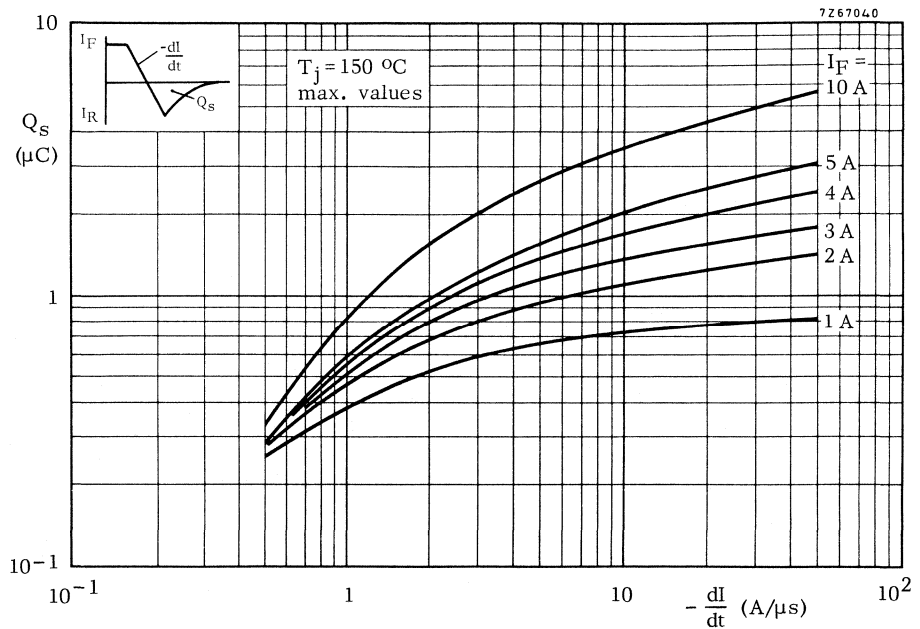
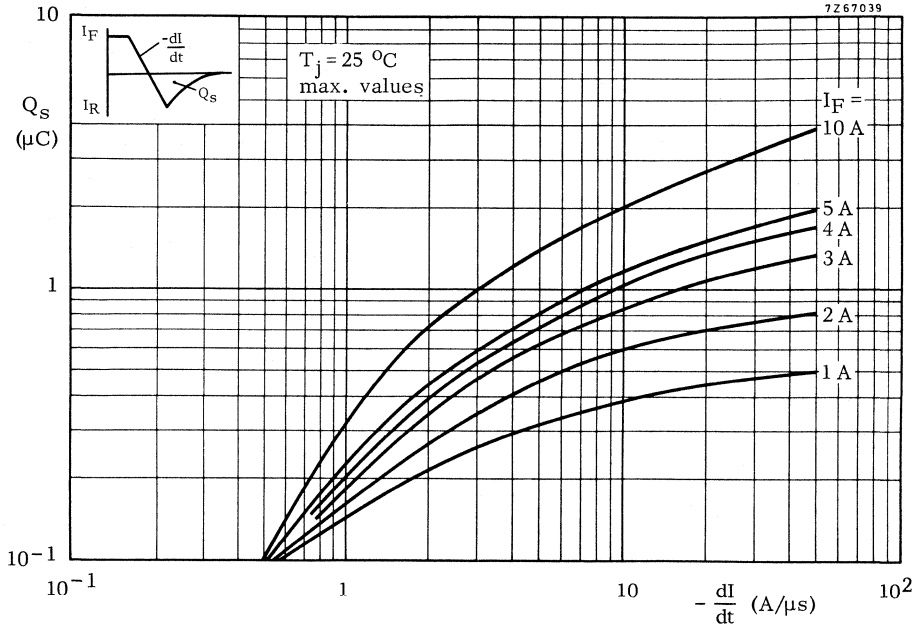


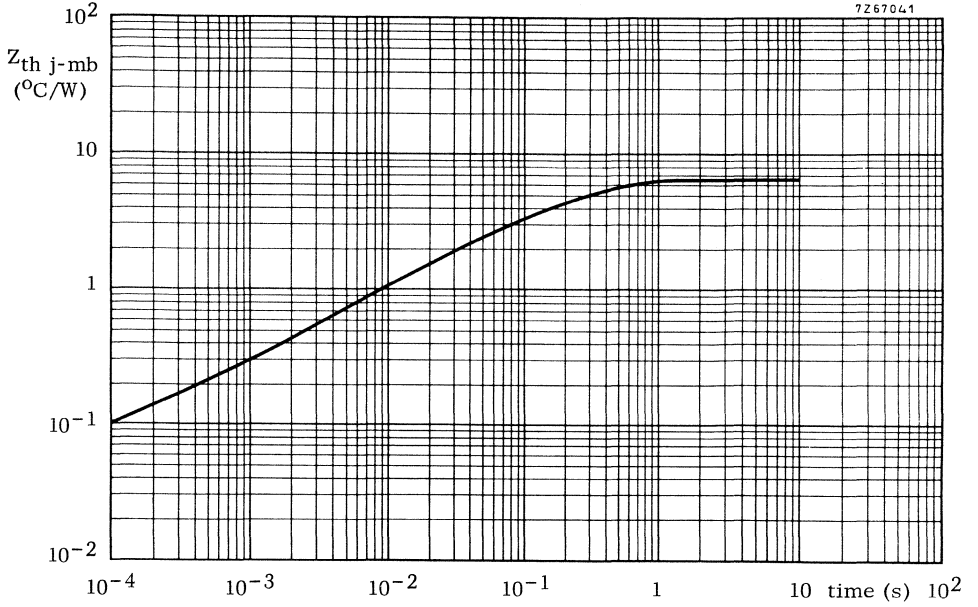


Nomogram; power loss  $\Delta P_R(\text{AV})$  due to switching only (to be added to forward and reverse power losses).



# BYX71 SERIES







RECTIFIER DIODES

Also available to BS9331-F129

Silicon rectifier diodes in metal envelopes similar to DO-4, intended for use in power rectifier applications.

The series consists of the following types :

Normal polarity (cathode to stud): BYX96-300 to 1600.

Reverse polarity (anode to stud): BYX96-300R to 1600R.

QUICK REFERENCE DATA

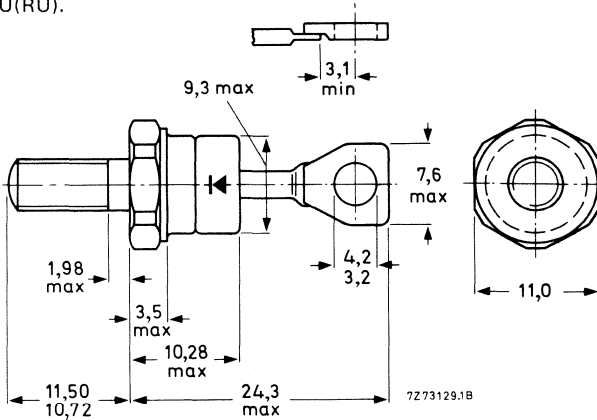
		BYX96-300	600	1200	1600	
		BYX96-300R	600R	1200R	1600R	
Repetitive peak reverse voltage	$V_{RRM}$	max. 300	600	1200	1600	V
Average forward current	$I_{F(AV)}$			max. 30		A
Non-repetitive peak forward current	$I_{FSM}$			max. 400		A

MECHANICAL DATA

Dimensions in mm

Fig. 1 DO-4: with metric M5 stud ( $\phi$  5 mm); e.g. BYX96-300(R).

Types with 10-32 UNF stud ( $\phi$  4,83 mm) are available on request. These are indicated by the suffix U; e.g. BYX96-300U(RU).



Supplied with device: 1 nut, 1 lock-washer

Nut dimensions across the flats, M5 thread: 8 mm, 10-32 UNF thread: 9.5 mm

Net mass : 7 g

Diameter of clearance hole : max. 5.2 mm

Supplied on request : accessories 56295

(PTFE bush, 2 mica washers, plain washer, tag)

a version with insulated flying leads

The mark shown applies to normal polarity types

Torque on nut : min. 0.9 Nm

(9 kg cm)

max. 1.7 Nm

(17 kg cm)

**RATINGS** Limiting values in accordance with the Absolute Maximum System (IEC 134)

Voltages <sup>1)</sup>		BYX96-300(R)	600(R)	1200(R)	1600(R)	
Non-repetitive peak reverse voltage ( $t \leq 10$ ms)	$V_{RSM}$	max. 300	600	1200	1600	V
Repetitive peak reverse voltage ( $\delta \leq 0,01$ )	$V_{RRM}$	max. 300	600	1200	1600	V
Crest working reverse voltage	$V_{RWM}$	max. 200	400	800	800	V
Continuous reverse voltage	$V_R$	max. 200	400	800	800	V

Currents

Average forward current (averaged over any 20 ms period) up to $T_{mb} = 125$ °C	$I_{F(AV)}$	max.	30	A
R. M. S. forward current	$I_{F(RMS)}$	max.	48	A
Repetitive peak forward current	$I_{FRM}$	max.	400	A
Non-repetitive peak forward current ( $t = 10$ ms; half sine-wave) $T_j = 175$ °C prior to surge; with reapplied $V_{RWMmax}$	$I_{FSM}$	max.	400	A
$I^2t$ for fusing ( $t = 10$ ms)	$I^2t$	max.	800	$A^2s$

Temperatures

Storage temperature	$T_{stg}$	-55 to +175	°C
Junction temperature	$T_j$	max. 175	°C

**THERMAL RESISTANCE**

From junction to mounting base	$R_{th\ j-mb}$	=	1,0	°C/W
From mounting base to heatsink without heatsink compound	$R_{th\ mb-h}$	=	0,5	°C/W
with heatsink compound	$R_{th\ mb-h}$	=	0,3	°C/W
Transient thermal impedance; $t = 1$ ms	$Z_{th\ j-mb}$	=	0,2	°C/W

<sup>1)</sup> To ensure thermal stability:  $R_{th\ j-a} \leq 2$  °C/W (continuous reverse voltage) or  $\leq 8$  °C/W (a. c.)

For smaller heatsinks  $T_{j\ max}$  should be derated. For a. c. see page 4.

For continuous reverse voltage: if  $R_{th\ j-a} = 4$  °C/W, then  $T_{j\ max} = 138$  °C,

if  $R_{th\ j-a} = 6$  °C/W, then  $T_{j\ max} = 125$  °C.



**CHARACTERISTICS**Forward voltage

$$I_F = 100 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$$

$$V_F < 1,7 \text{ V } ^1)$$

Reverse current

$$V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$$

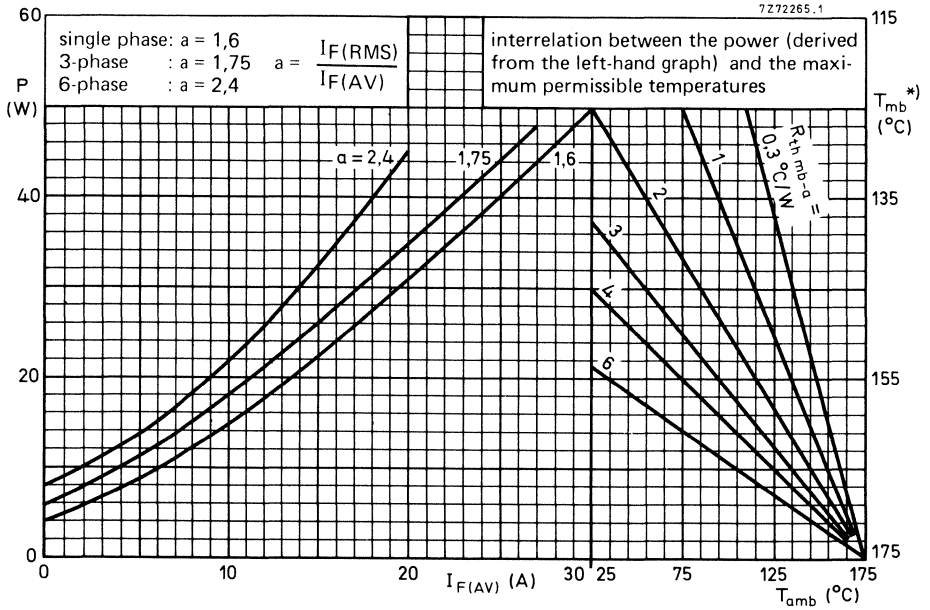
$$I_R < 1 \text{ mA}$$

**OPERATING NOTES**

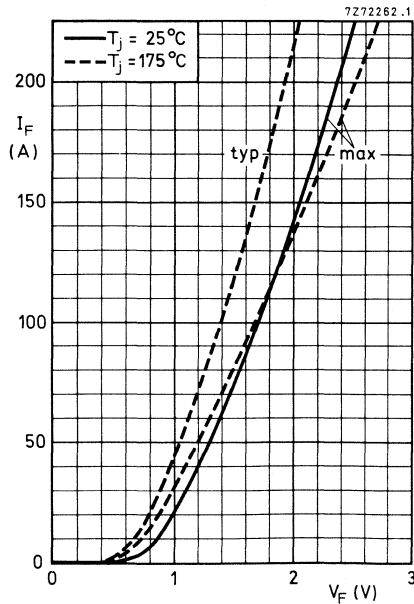
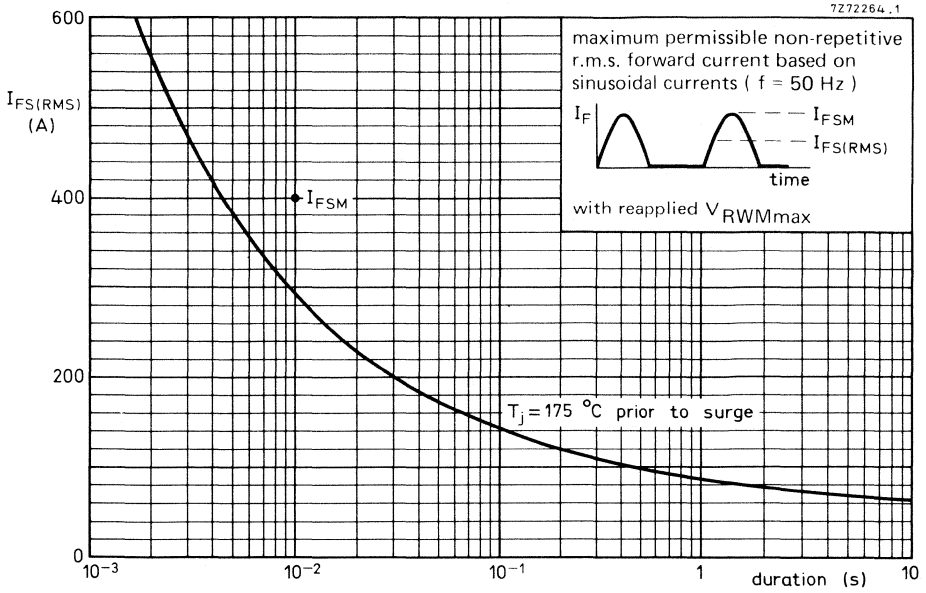
1. The top connector should neither be bent nor twisted; it should be soldered into the circuit so that there is no strain on it.  
During soldering the heat conduction to the junction should be kept to a minimum.
2. Where there is a possibility that transients, due to the energy stored in the transformer, will exceed the maximum permissible non-repetitive peak reverse voltage, see General Section for information on damping circuits in Data Handbook Part SC1a.

<sup>1)</sup> Measured under pulse conditions to avoid excessive dissipation.

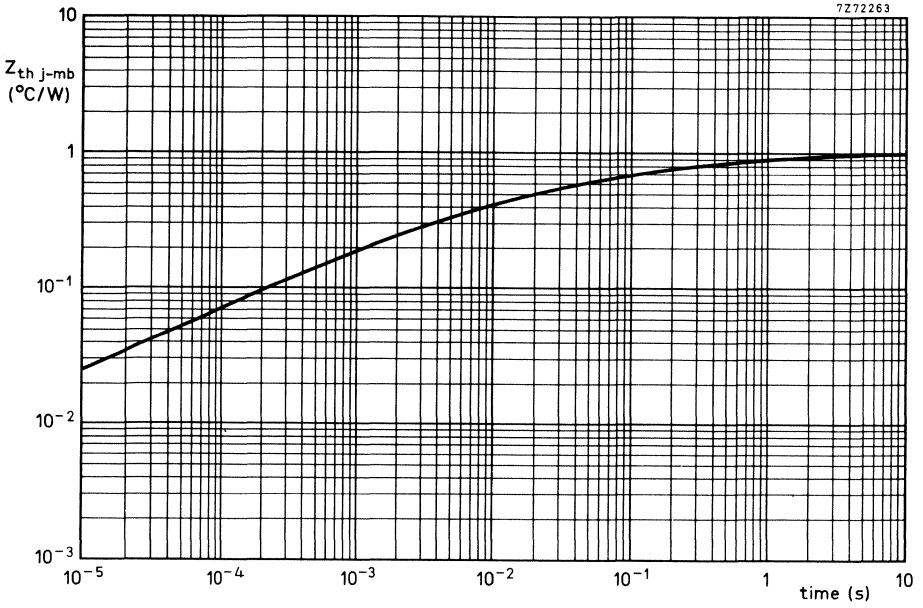
**BYX96**  
**SERIES**



\*)  $T_{mb}$ -scale is for comparison purposes only and is correct only for  $R_{th\ mb-a} \leq 6,5\ ^\circ\text{C}/\text{W}$



**BYX96**  
**SERIES**



RECTIFIER DIODES

Also available to BS9331-F130

Silicon rectifier diodes in metal envelopes similar to DO-5, intended for use in power rectifier applications.

The series consists of the following types:

Normal polarity (cathode to stud): BYX97-300 to 1600.

Reverse polarity (anode to stud): BYX97-300R to 1600R.

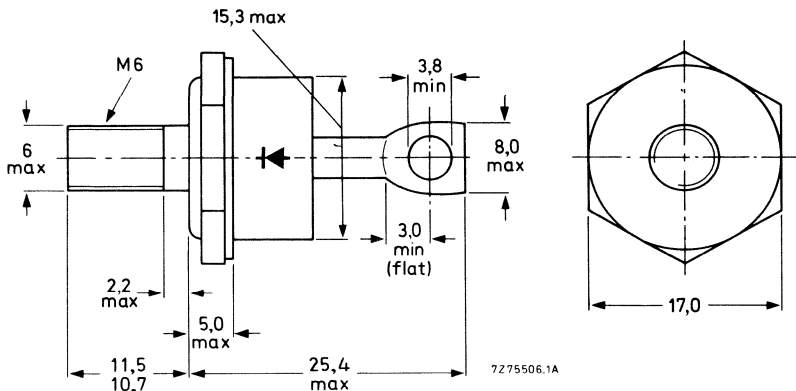
QUICK REFERENCE DATA

	BYX97-300 BYX97-300R	600 600R	1200 1200R	1600 1600R	
Repetitive peak reverse voltage $V_{RRM}$	max. 300 600 1200 1600				V
Average forward current	$I_{F(AV)}$		max. 47		A
Non-repetitive peak forward current	$I_{FSM}$		max. 800		A

MECHANICAL DATA

Dimensions in mm

DO-5 (except for M6 stud); Supplied with device: 1 nut, 1 lock-washer  
Nut dimensions across the flats: 10 mm



Net mass: 22 g

Diameter of clearance hole: max. 6.5 mm

Supplied on request: accessories 56264A

(mica washer, insulating ring, tag)

a version with insulated flying leads

The mark shown applies to normal polarity types

Torque on nut: min. 1.7 Nm

(17 kg cm)

max. 3.5 Nm

(35 kg cm)

# BYX97 SERIES

**RATINGS** Limiting values in accordance with the Absolute Maximum System (IEC 134)

Voltages <sup>1)</sup>		BYX97-300(R)	600(R)	1200(R)	1600(R)	
Non-repetitive peak reverse voltage ( $t \leq 10$ ms)	$V_{RSM}$	max. 300	600	1200	1600	V
Repetitive peak reverse voltage ( $\delta \leq 0,01$ )	$V_{RRM}$	max. 300	600	1200	1600	V
Crest working reverse voltage	$V_{RWM}$	max. 200	400	800	800	V
Continuous reverse voltage	$V_R$	max. 200	400	800	800	V

## Currents

Average forward current (averaged over any 20 ms period) up to $T_{mb} = 120$ °C at $T_{mb} = 125$ °C	$I_F(AV)$	max.	47	A
	$I_F(AV)$	max.	40	A
R. M. S. forward current	$I_F(RMS)$	max.	75	A
Repetitive peak forward current	$I_{FRM}$	max.	550	A
Non-repetitive peak forward current ( $t = 10$ ms; half sine-wave) $T_j = 150$ °C prior to surge; with reapplied $V_{RWMmax}$	$I_{FSM}$	max.	800	A
$I^2t$ for fusing ( $t = 10$ ms)	$I^2t$	max.	3200	A <sup>2</sup> s

## Temperatures

Storage temperature	$T_{stg}$	-55 to +150	°C
Junction temperature	$T_j$	max. 150	°C

## THERMAL RESISTANCE

From junction to mounting base	$R_{th\ j-mb}$	=	0,6	°C/W
From mounting base to heatsink without heatsink compound	$R_{th\ mb-h}$	=	0,3	°C/W
with heatsink compound	$R_{th\ mb-h}$	=	0,2	°C/W
Transient thermal impedance; $t = 1$ ms	$Z_{th\ j-mb}$	=	0,1	°C/W

<sup>1)</sup> To ensure thermal stability:  $R_{th\ j-a} \leq 1$  °C/W (continuous reverse voltage) or  $\leq 4$  °C/W (a. c.)

For smaller heatsinks  $T_{j\ max}$  should be derated. For a. c. see page 4.

For continuous reverse voltage: if  $R_{th\ j-a} = 2$  °C/W, then  $T_{j\ max} = 138$  °C,

if  $R_{th\ j-a} = 3$  °C/W, then  $T_{j\ max} = 125$  °C.

**CHARACTERISTICS**Forward voltage

$$I_F = 150 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$$

$$V_F < 1,45 \text{ V } ^1)$$

Reverse current

$$V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$$

$$I_R < 4 \text{ mA}$$

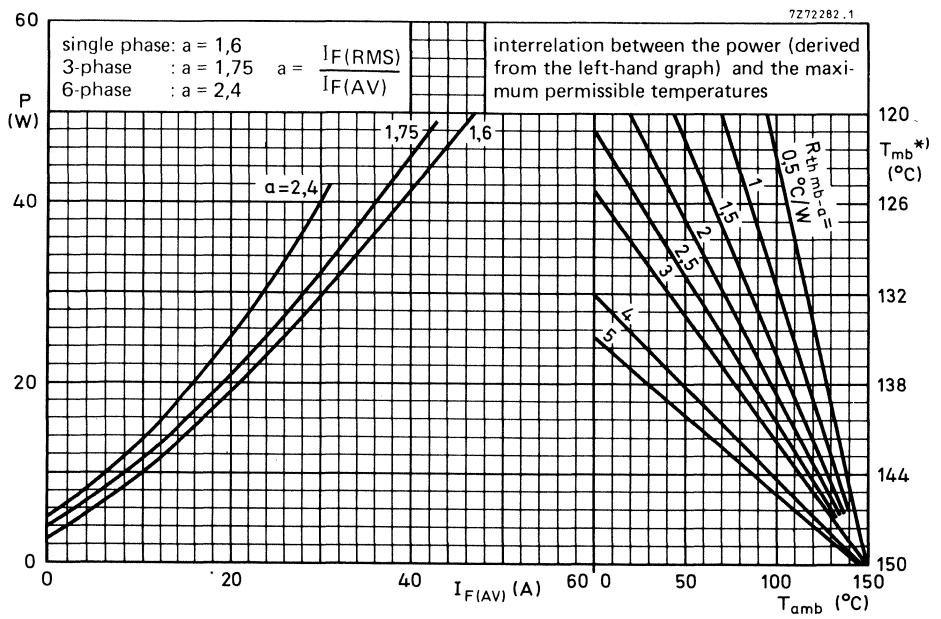
**OPERATING NOTES**

1. The top connector should neither be bent nor twisted; it should be soldered into the circuit so that there is no strain on it.  
During soldering the heat conduction to the junction should be kept to a minimum.
2. Where there is a possibility that transients, due to the energy stored in the transformer, will exceed the maximum permissible non-repetitive peak reverse voltage, see General Section for information on damping circuits in Data Handbook Part SC1a.

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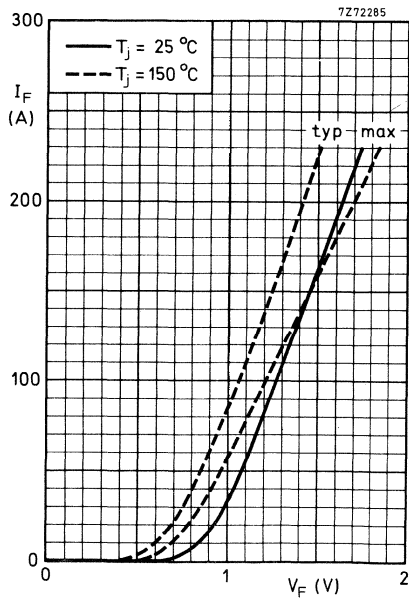
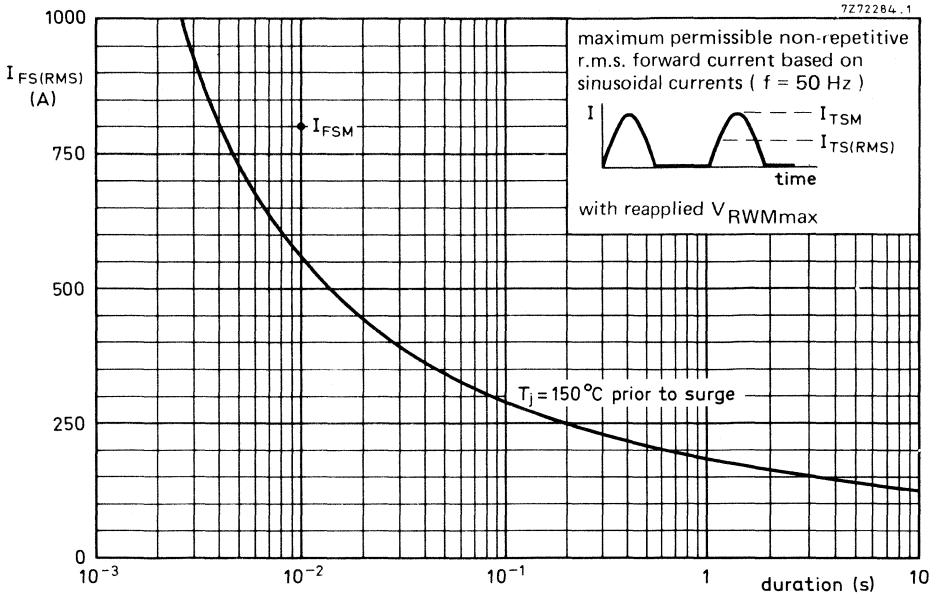
<sup>1)</sup> Measured under pulse conditions to avoid excessive dissipation.

**BYX97  
SERIES**

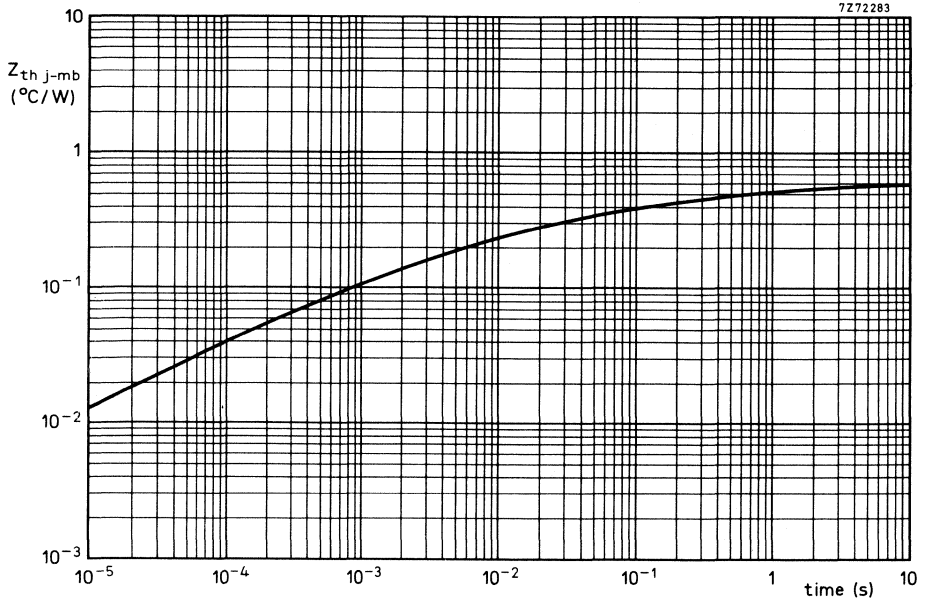


\*)  $T_{mb}$ -scale is for comparison purposes only and is correct only for  $R_{th\ mb-a} \leq 3,4\ ^\circ\text{C}/\text{W}$





**BYX97**  
**SERIES**



RECTIFIER DIODES



Silicon rectifier diodes in DO-4 metal envelopes, intended for use in power rectifier applications.

The series consists of the following types:

Normal polarity (cathode to stud): BYX98-300 to 1200.

Reverse polarity (anode to stud): BYX98-300R to 1200R.

QUICK REFERENCE DATA

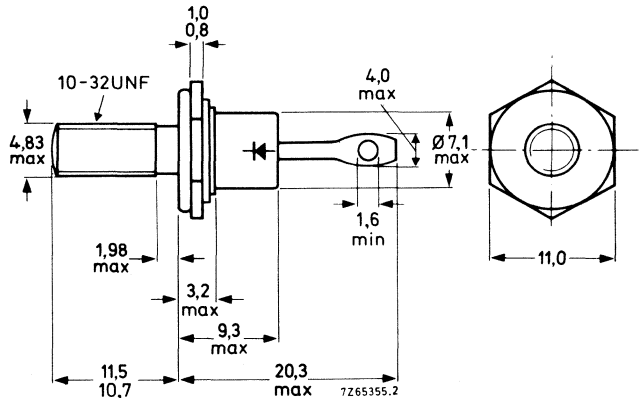
	BYX98-300	600	1200			
	BYX98-300R	600R	1200R			
Repetitive peak reverse voltage	$V_{RRM}$	max.	300	600	1200	V
Average forward current	$I_{F(AV)}$	max.	10			A
Non-repetitive peak forward current	$I_{FSM}$	max.	75			A

MECHANICAL DATA

Dimensions in mm

DO-4: Supplied with device: 1 nut, 1 lock-washer

Nut dimensions across the flats: 9.5 mm



Net mass: 6 g

Diameter of clearance hole: max. 5.2 mm

Accessories supplied on request:

56295 (PTFE bush, 2 mica washers, plain washer, tag)

The mark shown applies to the normal polarity types.

Torque on nut: min. 0.9 Nm  
(9 kg cm)

max. 1.7 Nm  
(17 kg cm)

Products approved to CECC 50 009-004, available on request

# BYX98 SERIES

**RATINGS** Limiting values in accordance with the Absolute Maximum System (IEC 134)

<u>Voltages</u>		BYX98-300(R)	600(R)	1200(R)	
Non-repetitive peak reverse voltage ( $t \leq 10$ ms)	$V_{RSM}$	max. 300	600	1200	V
Repetitive peak reverse voltage ( $\delta \leq 0.01$ )	$V_{RRM}$	max. 300	600	1200	V
Crest working reverse voltage	$V_{RWM}$	max. 200	400	800	V
Continuous reverse voltage	$V_R$	max. 200	400	800	V

## Currents

Average forward current (averaged over any 20 ms period) up to $T_{mb} = 97$ °C at $T_{mb} = 125$ °C	$I_F(AV)$	max.	10	A
	$I_F(AV)$	max.	6	A
R. M. S. forward current	$I_F(RMS)$	max.	16	A
Repetitive peak forward current	$I_{FRM}$	max.	75	A
Non-repetitive peak forward current ( $t = 10$ ms; half sine-wave) $T_j = 150$ °C prior to surge; with reapplied $V_{RWMmax}$	$I_{FSM}$	max.	75	A
$I^2t$ for fusing ( $t = 10$ ms)	$I^2t$	max.	28	A <sup>2</sup> s

## Temperatures

Storage temperature	$T_{stg}$	-55 to +150	°C
Junction temperature	$T_j$	max. 150	°C

## **THERMAL RESISTANCE**

From junction to ambient in free air	$R_{th j-a}$	=	50	°C/W
From junction to mounting base	$R_{th j-mb}$	=	3	°C/W
From mounting base to heatsink with heatsink compound	$R_{th mb-h}$	=	0,5	°C/W
without heatsink compound	$R_{th mb-h}$	=	0,6	°C/W
Transient thermal impedance; $t = 1$ ms	$Z_{th j-mb}$	=	0,3	°C/W

**CHARACTERISTICS**

Forward voltage

$I_F = 20 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_F < 1,7 \text{ V } I_1)$

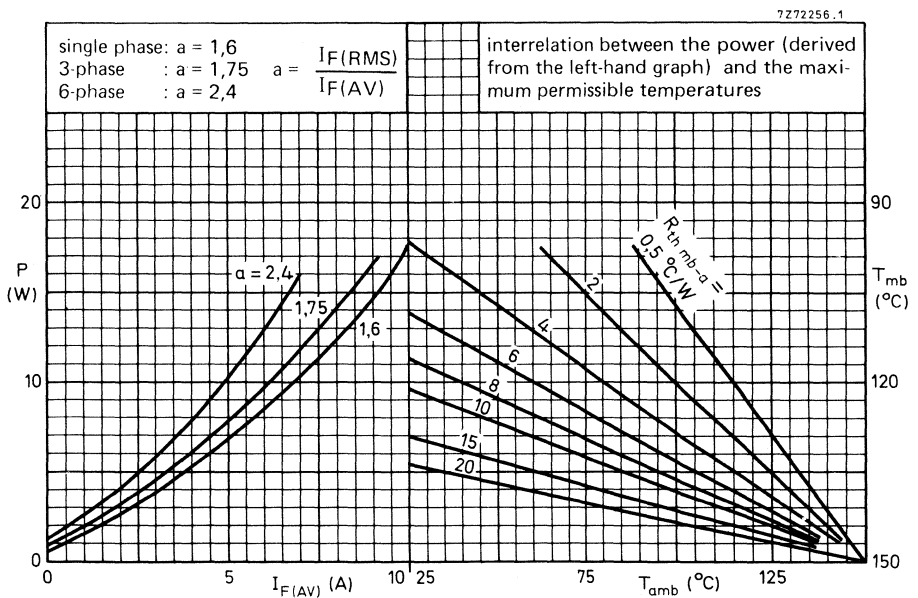
Reverse current

$V_R = V_{RWM\max}; T_j = 125 \text{ }^\circ\text{C}$

$I_R < 200 \text{ } \mu\text{A}$

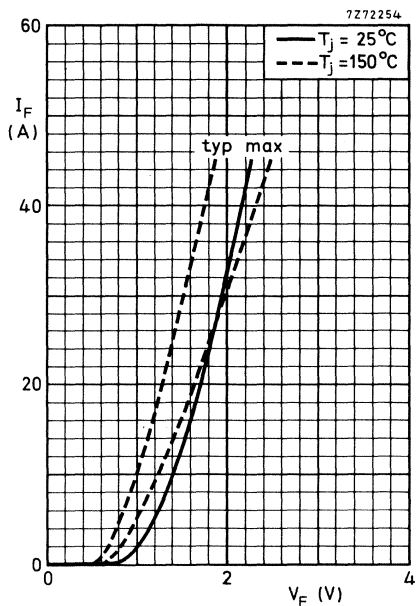
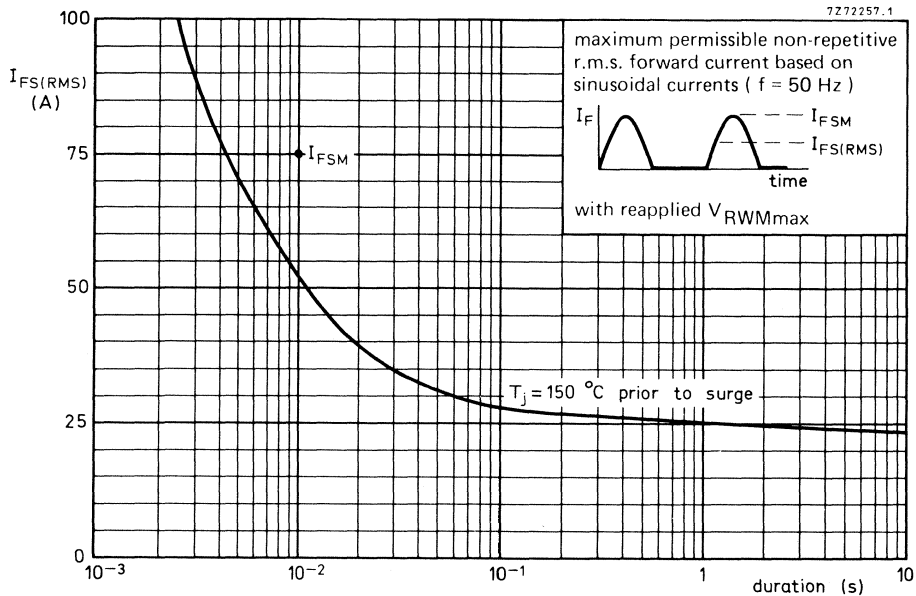
**OPERATING NOTES**

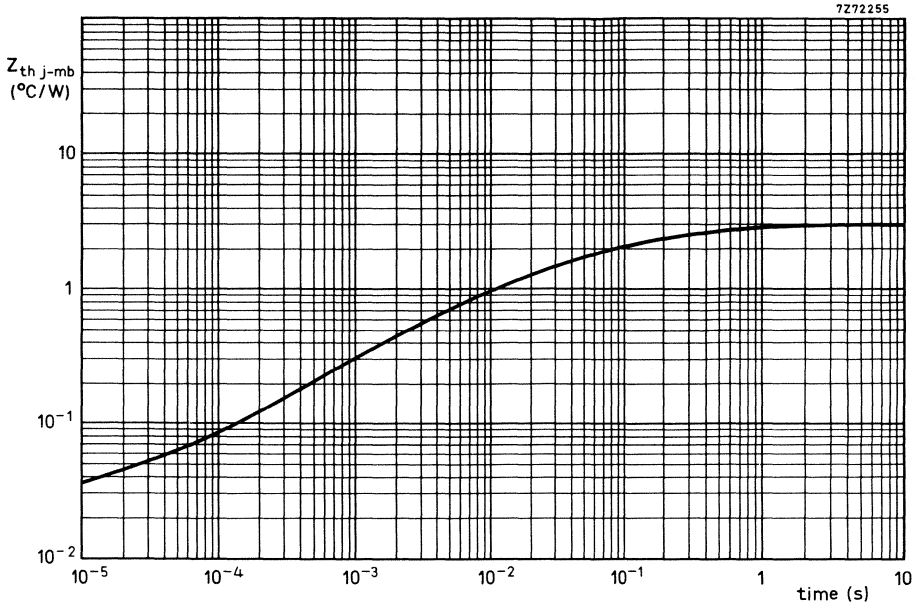
1. The top connector should neither be bent nor twisted; it should be soldered into the circuit so that there is no strain on it.  
During soldering the heat conduction to the junction should be kept to a minimum.
2. Where there is a possibility that transients, due to the energy stored in the transformer, will exceed the maximum permissible non-repetitive peak reverse voltage, see General Section for information on damping circuits in Data Handbook Part SC1a.



1) Measured under pulse conditions to avoid excessive dissipation.

**BYX98  
SERIES**









RECTIFIER DIODES



Silicon rectifier diodes in DO-4 metal envelopes, intended for use in power rectifier applications.

The series consists of the following types:

Normal polarity (cathode to stud): BYX99-300 to 1200.

Reverse polarity (anode to stud): BYX99-300R to 1200R.

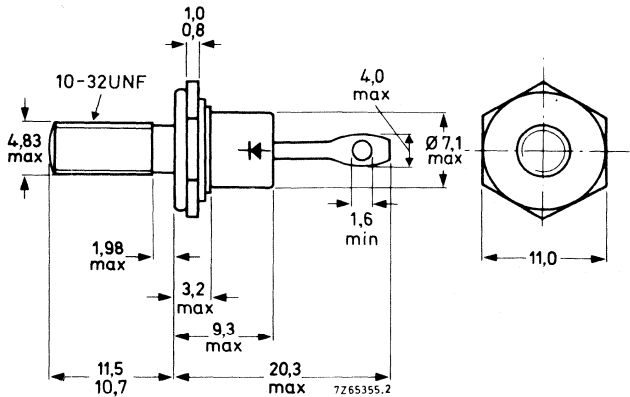
QUICK REFERENCE DATA

	BYX99-300 BYX99-300R	600 600R	1200 1200R	
Repetitive peak reverse voltage $V_{RRM}$ max.	300	600	1200	V
Average forward current $I_{F(AV)}$	max.	15		A
Non-repetitive peak forward current $I_{FSM}$	max.	180		A

MECHANICAL DATA

Dimensions in mm

DO-4; Supplied with device: 1 nut, 1 lock-washer  
Nut dimensions across the flats: 9.5 mm



Net mass: 6 g

Diameter of clearance hole: 5.2 mm

Accessories supplied on request:

56295 (PTFE bush, 2 mica washers, plain washer, tag)

Torque on nut: min. 0.9 Nm  
(9 kg cm)  
max. 1.7 Nm  
(17 kg cm)

The mark shown applies to the normal polarity types

Products approved to CECC 50 009-005, available on request

# BYX99 SERIES

**RATINGS** Limiting values in accordance with the Absolute Maximum System (IEC 134)

<u>Voltages</u>		BYX99-300(R)	600(R)	1200(R)	
Non-repetitive peak reverse voltage ( $t \leq 10$ ms)	$V_{RSM}$	max. 300	600	1200	V
Repetitive peak reverse voltage ( $\delta \leq 0,01$ )	$V_{RRM}$	max. 300	600	1200	V
Crest working reverse voltage	$V_{RWM}$	max. 200	400	800	V
Continuous reverse voltage	$V_R$	max. 200	400	800	V

## Currents

Average forward current (averaged over any 20 ms period) up to $T_{mb} = 129$ °C	$I_{F(AV)}$	max.	15	A
R. M. S. forward current	$I_{F(RMS)}$	max.	24	A
Repetitive peak forward current	$I_{FRM}$	max.	180	A
Non-repetitive peak forward current ( $t = 10$ ms; half sine-wave) $T_j = 175$ °C prior to surge; with reapplied $V_{RWMmax}$	$I_{FSM}$	max.	180	A
$i^2t$ for fusing ( $t = 10$ ms)	$I^2t$	max.	162	A <sup>2</sup> s

## Temperatures

Storage temperature	$T_{stg}$	-55 to +175	°C
Junction temperature	$T_j$	max. 175	°C

## **THERMAL RESISTANCE**

From junction to ambient in free air	$R_{th j-a}$	=	50	°C/W
From junction to mounting base	$R_{th j-mb}$	=	2,3	°C/W
From mounting base to heatsink with heatsink compound	$R_{th mb-h}$	=	0,5	°C/W
without heatsink compound	$R_{th mb-h}$	=	0,6	°C/W
Transient thermal impedance; $t = 1$ ms	$Z_{th j-mb}$	=	0,13	°C/W

**CHARACTERISTICS**Forward voltage

$$I_F = 50 \text{ A}; T_j = 25 \text{ }^\circ\text{C} \qquad V_F < 1,55 \text{ V } ^1)$$

Reverse current

$$V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C} \qquad I_R < 200 \text{ } \mu\text{A}$$

**OPERATING NOTES**

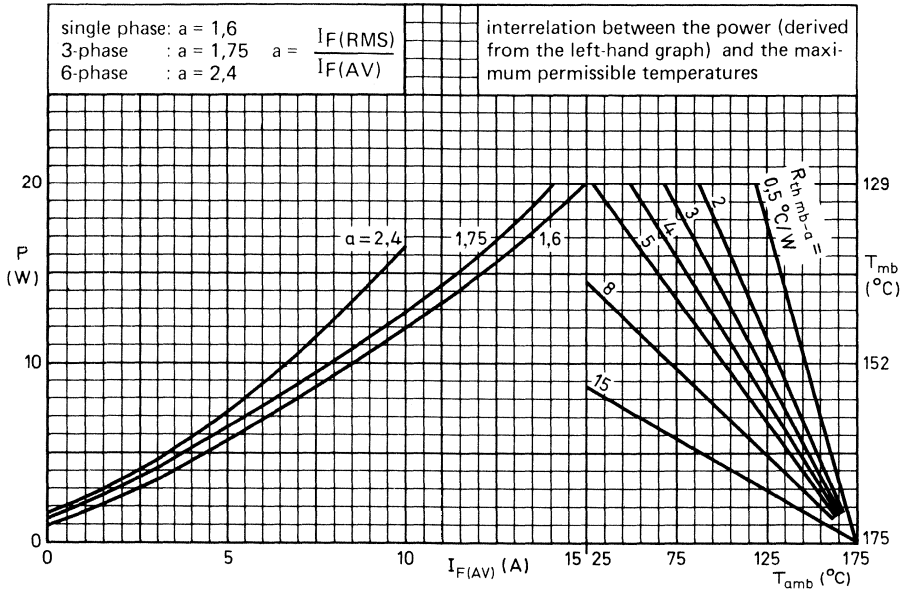
1. The top connector should neither be bent nor twisted; it should be soldered into the circuit so that there is no strain on it.  
During soldering the heat conduction to the junction should be kept to a minimum.
2. Where there is a possibility that transients, due to the energy stored in the transformer, will exceed the maximum permissible non-repetitive peak reverse voltage, see General Section for information on damping circuits in Data Handbook Part SC1a.

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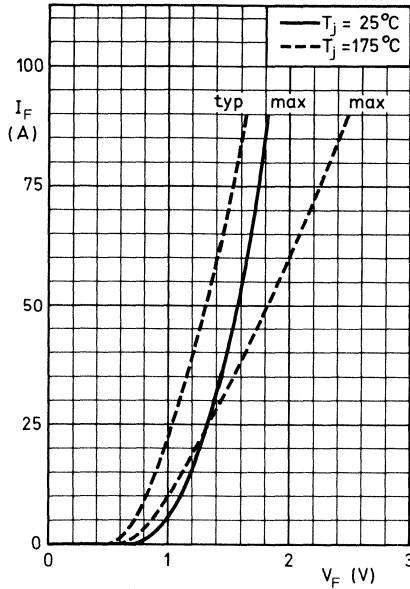
<sup>1)</sup> Measured under pulse conduction to avoid excessive dissipation.

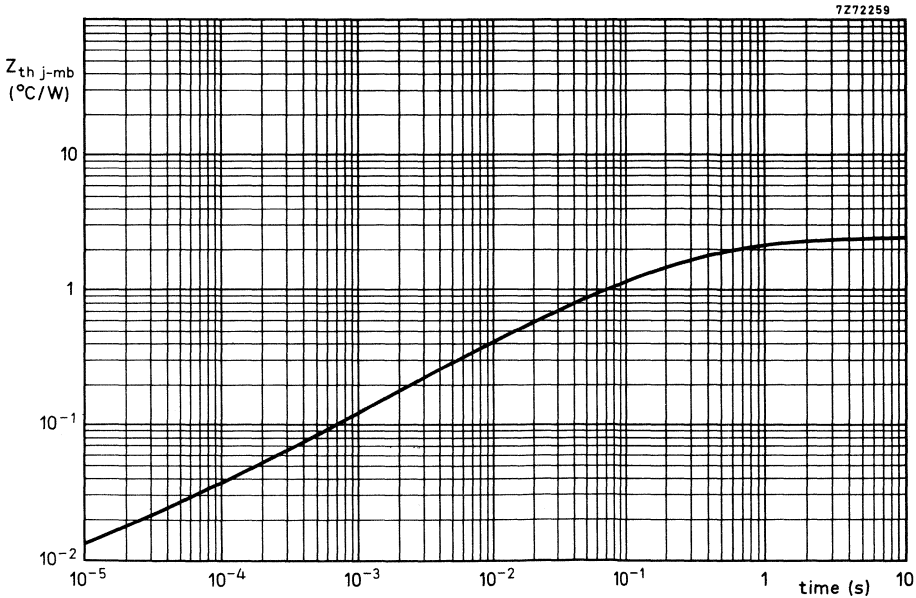
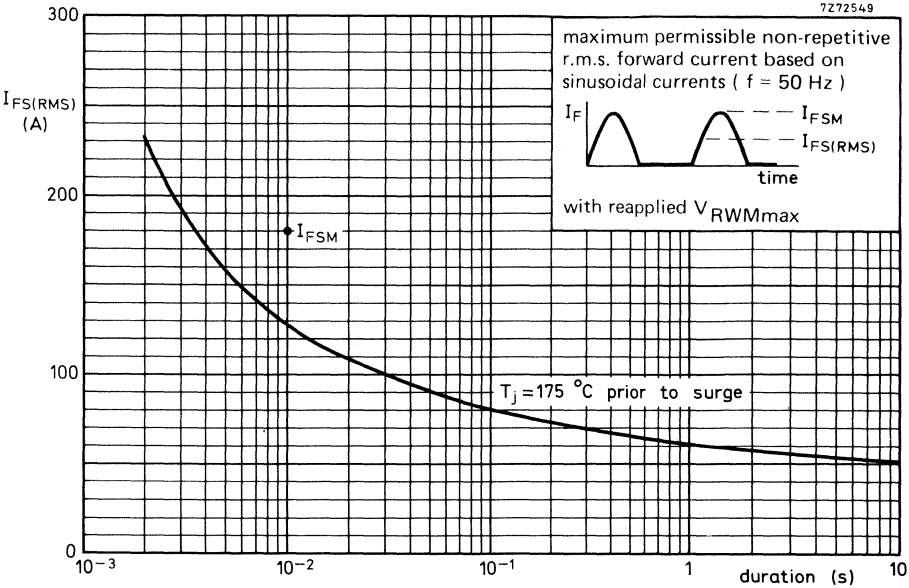
**BYX99  
SERIES**

7272261.1



7272258







## FAST SOFT-RECOVERY RECTIFIER DIODES



Silicon diodes, each in a DO-4 metal envelope, featuring non-snap-off characteristics, and intended for use in high-frequency power supplies, thyristor inverters and multi-phase power rectifier applications. The series consists of the following types:

Normal polarity (cathode to stud): 1N3879, 1N3880, 1N3881 and 1N3882.

Reverse polarity (anode to stud): 1N3879R, 1N3880R, 1N3881R and 1N3882R.

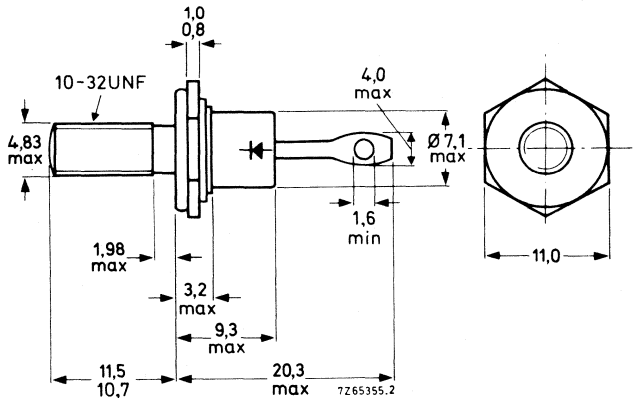
## QUICK REFERENCE DATA

		1N3879(R)	1N3880(R)	1N3881(R)	1N3882(R)
Repetitive peak reverse voltage	$V_{RRM}$	max. 50	100	200	300 V
Average forward current			$I_{F(AV)}$	max. 6	A
Non-repetitive peak forward current			$I_{FSM}$	max. 80	A
Reverse recovery time	$t_{rr}$			< 200	ns

## MECHANICAL DATA

Dimensions in mm

DO-4



Net mass: 6 g

Diameter of clearance hole: max. 5,2 mm

Accessories supplied on request:

56295 (PTFE bush, 2 mica washers, plain washer, tag)

Supplied with device: 1 nut, 1 lock washer

Nut dimensions across the flats: 9,5 mm

The mark shown applies to the normal polarity types.

Torque on nut: min. 0,9 Nm

(9 kg cm)

max. 1,7 Nm

(17 kg cm)

Products approved to CECC 50 009-006, available on request.

**RATINGS** Limiting values in accordance with the Absolute Maximum System (IEC 134)

Voltages

		1N3879(R)	1N3880(R)	1N3881(R)	1N3882(R)
Non-repetitive peak reverse voltage ( $t \leq 10$ ms)	$V_{RSM}$ max.	100	150	250	350 V
Repetitive peak reverse voltage ( $\delta \leq 0,01$ )	$V_{RRM}$ max.	50	100	200	300 V
Crest working reverse voltage	$V_{RWM}$ max.	50	100	200	300 V

Currents

Average on-state current assuming zero switching losses (averaged over any 20 ms period)

up to $T_{mb} = 100$ °C	$I_F(AV)$	max.	6	A
at $T_{mb} = 125$ °C	$I_F(AV)$	max.	3,5	A

R. M. S. forward current  $I_F(RMS)$  max. 10 A

Repetitive peak forward current  $I_{FRM}$  max. 75 A

Non-repetitive peak forward current

$T_j = 150$  °C prior to surge;

half sine-wave with reapplied  $V_{RWMmax}$ ;

$t = 10$  ms

$t = 8,3$  ms

$I_{FSM}$	max.	75	A
$I_{FSM}$	max.	80	A

$I^2t$  for fusing ( $t = 10$  ms)  $I^2t$  max. 28 A<sup>2</sup>s

Temperatures

Storage temperature  $T_{stg}$  -65 to +175 °C

Operating junction temperature  $T_j$  max. 150 °C

**THERMAL RESISTANCE**

From junction to ambient in free air  $R_{th j-a} = 50$  °C/W

From junction to mounting base  $R_{th j-mb} = 4,4$  °C/W

From mounting base to heatsink  $R_{th mb-h} = 0,5$  °C/W

Transient thermal impedance;  $t = 1$  ms;  $\delta = 0$   $Z_{th j-mb} = 1$  °C/W



**CHARACTERISTICS**Forward voltage <sup>1)</sup>

$$I_F = 6 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$$

$$V_F < 1,4 \text{ V}$$

Reverse current

$$V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$$

$$I_R < 3 \text{ mA}$$

Reverse recovery when switched from

$$I_F = 1 \text{ A to } V_R = 30 \text{ V};$$

$$-dI_F/dt = 35 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$$

Recovery time

$$t_{rr} < 200 \text{ ns}$$

$$I_F = 2 \text{ A to } V_R = 30 \text{ V};$$

$$-dI_F/dt = 20 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$$

Recovery charge

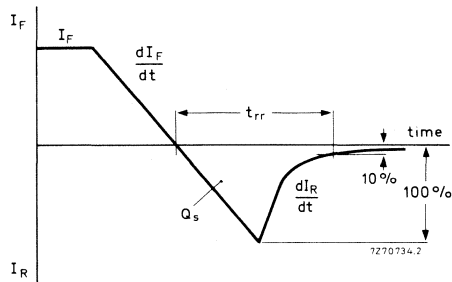
$$Q_s < 250 \text{ nC}$$

$$I_F = 1 \text{ A to } V_R = 30 \text{ V};$$

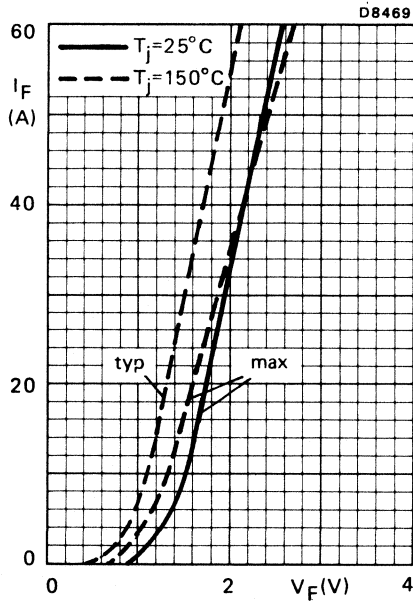
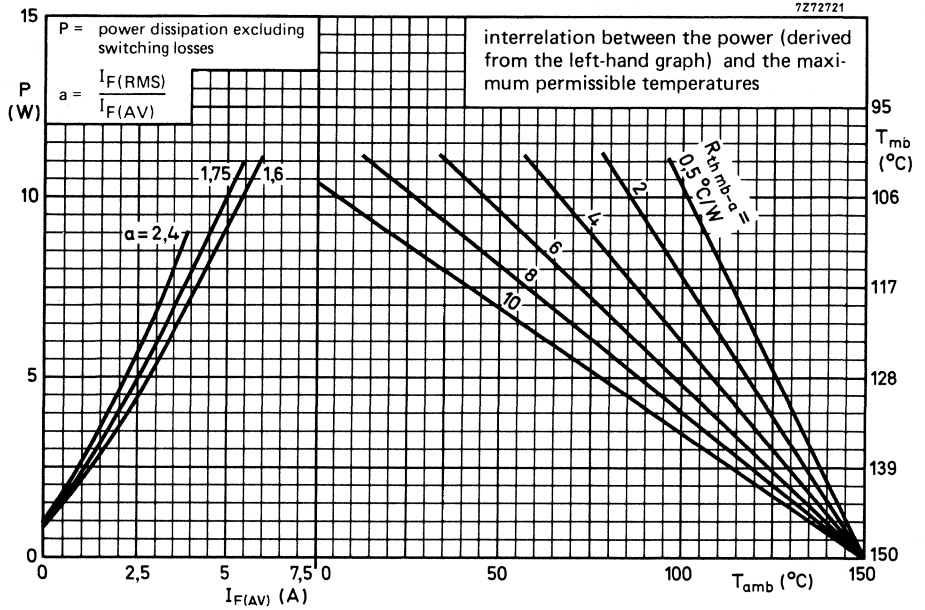
$$-dI_F/dt = 2 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$$

Max. slope of the reverse recovery current

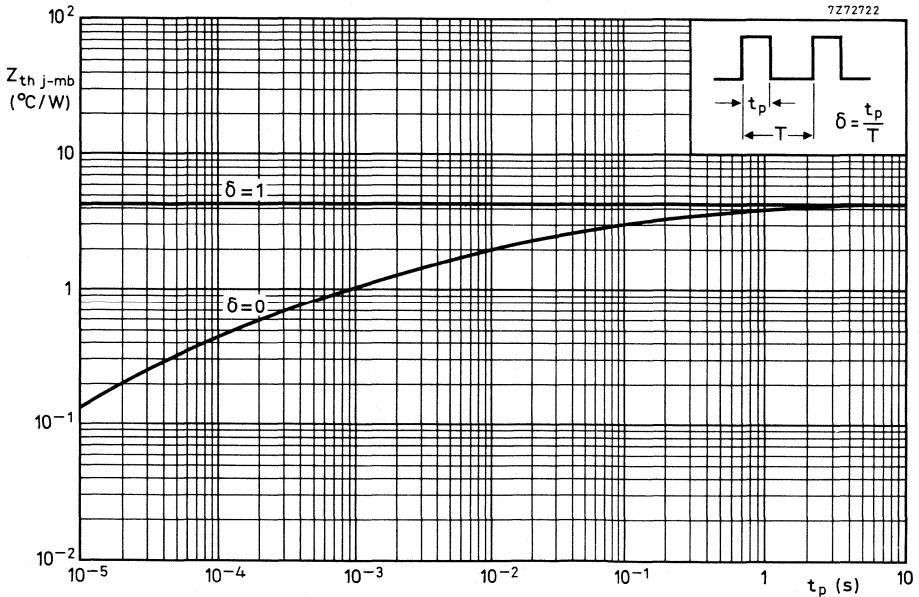
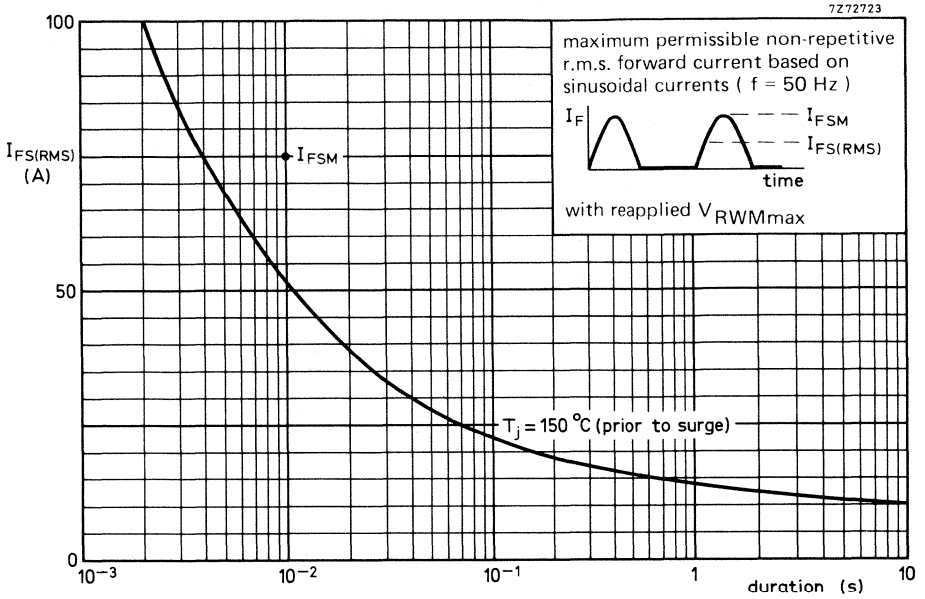
$$|dI_R/dt| < 5 \text{ A}/\mu\text{s}$$

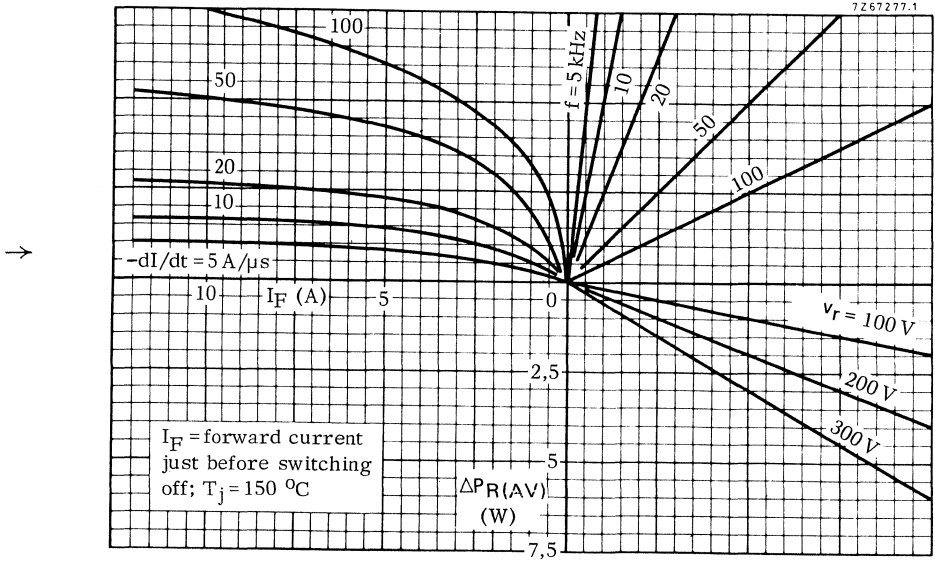


<sup>1)</sup> Measured under pulse conditions to avoid excessive dissipation.



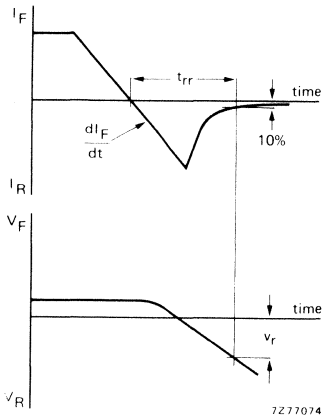
→





**NOMOGRAM**

Power loss  $\Delta P_R(\text{AV})$  due to switching only (to be added to steady state power losses).



## FAST SOFT-RECOVERY RECTIFIER DIODES



Silicon diodes, each in a DO-4 metal envelope, featuring non-snap-off characteristics, and intended for use in high-frequency power supplies, thyristor inverters and multi-phase power rectifier applications.

The series consists of the following types:

Normal polarity (cathode to stud): 1N3889, 1N3890, 1N3891 and 1N3892.

Reverse polarity (anode to stud): 1N3889R, 1N3890R, 1N3891R and 1N3892R.

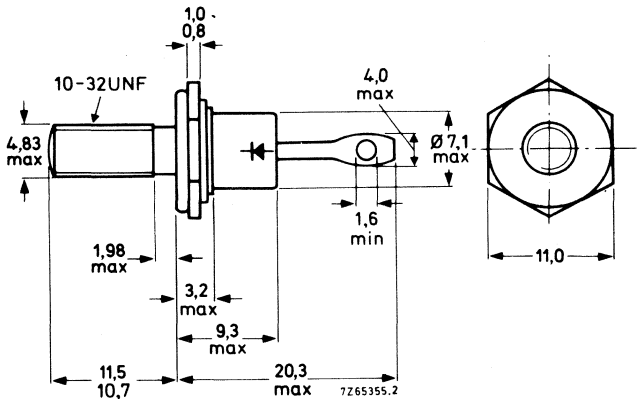
## QUICK REFERENCE DATA

		1N3889(R)	1N3890(R)	1N3891(R)	1N3892(R)
Repetitive peak reverse voltage	$V_{RRM}$	max. 50	100	200	300 V
Average forward current			$I_{F(AV)}$	max. 12	A
Non-repetitive peak forward current			$I_{FSM}$	max. 150	A
Reverse recovery time			$t_{rr}$	< 200	ns

## MECHANICAL DATA

Dimensions in mm

DO-4



Net mass: 6 g

Diameter of clearance hole: max. 5,2 mm

Accessories supplied on request:

56295 (PTFE bush, 2 mica washers, plain washer, tag)

Supplied with device: 1 nut, 1 lock washer

Nut dimensions across the flats: 9,5 mm

The mark shown applies to the normal polarity types.

Torque on nut: min. 0,9 Nm

(9 kg cm)

max. 1,7 Nm

(17 kg cm)

**RATINGS** Limiting values in accordance with the Absolute Maximum System (IEC134)

Voltages

		1N3889(R)	1N3890(R)	1N3891(R)	1N3892(R)
Non-repetitive peak reverse voltage ( $t \leq 10$ ms)	$V_{RSM}$ max.	100	150	250	350 V
Repetitive peak reverse voltage ( $\delta \leq 0,01$ )	$V_{RRM}$ max.	50	100	200	300 V
Crest working reverse voltage	$V_{RWM}$ max.	50	100	200	300 V

Currents

Average on-state current assuming zero

switching losses (averaged over any 20 ms period)

up to  $T_{mb} = 100$  °C

$I_F(AV)$  max. 12 A

at  $T_{mb} = 125$  °C

$I_F(AV)$  max. 7 A

R. M. S. forward current

$I_F(RMS)$  max. 20 A

Repetitive peak forward current

$I_{FRM}$  max. 140 A

Non-repetitive peak forward current

$T_j = 150$  °C prior to surge;

half sine-wave with reapplied  $V_{RWMmax}$ ;

$t = 10$  ms

$I_{FSM}$  max. 140 A

$t = 8,3$  ms

$I_{FSM}$  max. 150 A

$I^2t$  for fusing ( $t = 10$  ms)

$I^2t$  max. 100 A<sup>2</sup>s

Temperatures

Storage temperature

$T_{stg}$  -65 to +175 °C

Operating junction temperature

$T_j$  max. 150 °C

**THERMAL RESISTANCE**

From junction to ambient in free air

$R_{th j-a}$  = 50 °C/W

From junction to mounting base

$R_{th j-mb}$  = 2,2 °C/W

From mounting base to heatsink

$R_{th mb-h}$  = 0,5 °C/W

Transient thermal impedance;  $t = 1$  ms;  $\delta = 0$

$Z_{th j-mb}$  = 0,8 °C/W

**CHARACTERISTICS**

Forward voltage <sup>1)</sup>

$I_F = 12 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$   $V_F < 1,4 \text{ V}$

Reverse current

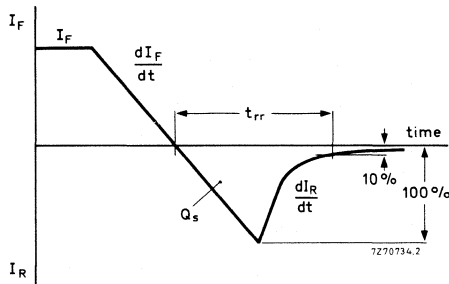
$V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$   $I_R < 3 \text{ mA}$

Reverse recovery when switched from

$I_F = 1 \text{ A to } V_R = 30 \text{ V};$   
 $-dI_F/dt = 35 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$   
 Recovery time  $t_{rr} < 200 \text{ ns}$

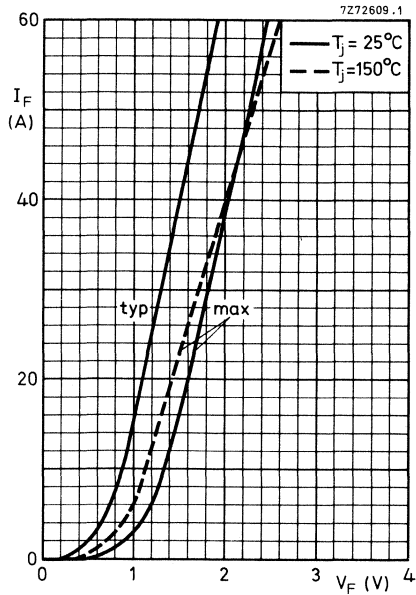
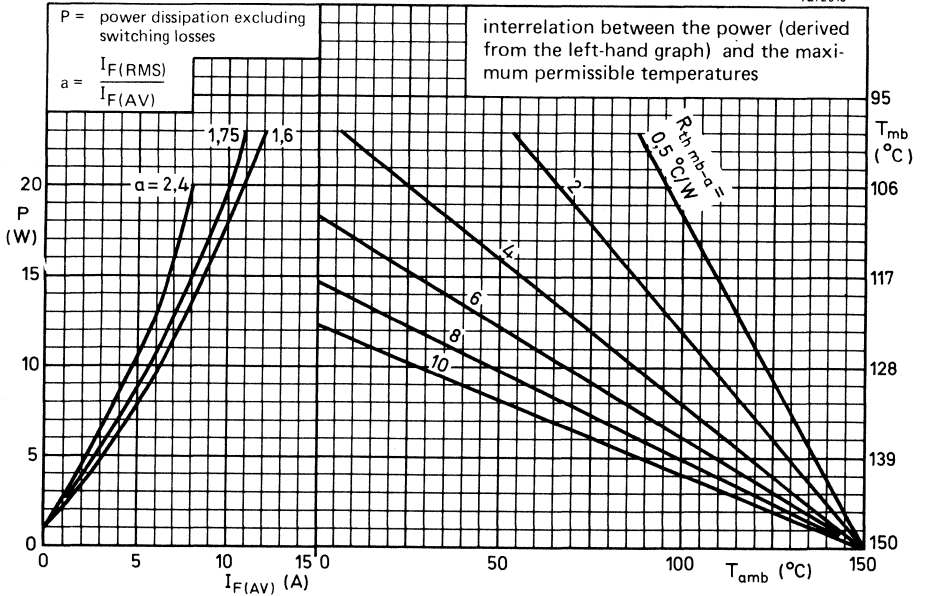
$I_F = 2 \text{ A to } V_R = 30 \text{ V};$   
 $-dI_F/dt = 20 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$   
 Recovery charge  $Q_s < 250 \text{ nC}$

$I_F = 1 \text{ A to } V_R = 30 \text{ V};$   
 $-dI_F/dt = 2 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$   
 Max. slope of the reverse recovery current  $|dI_R/dt| < 5 \text{ A}/\mu$

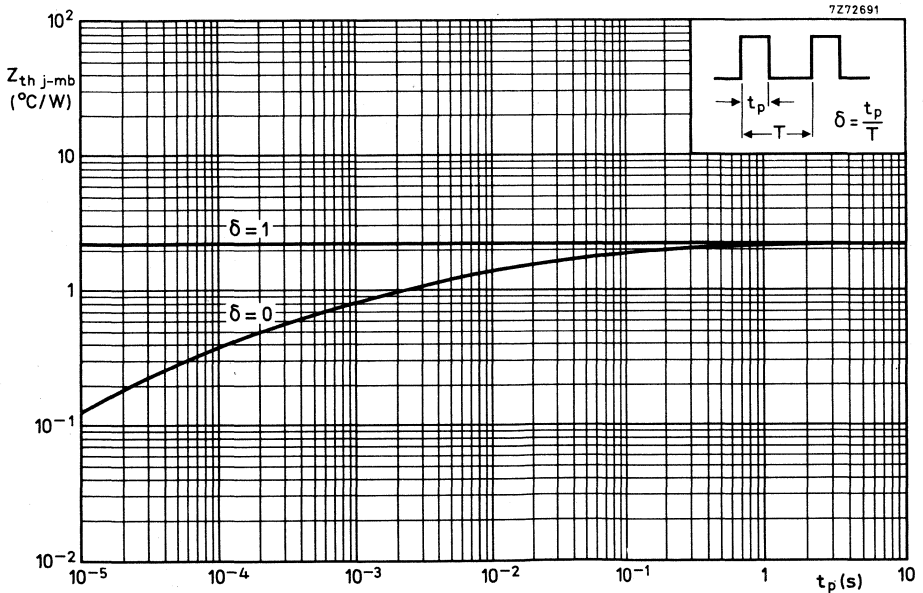
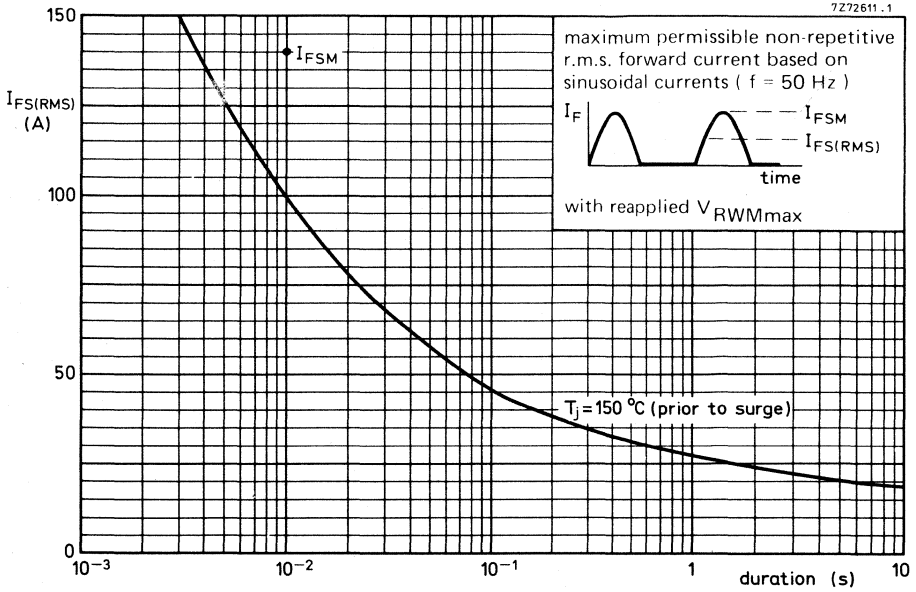


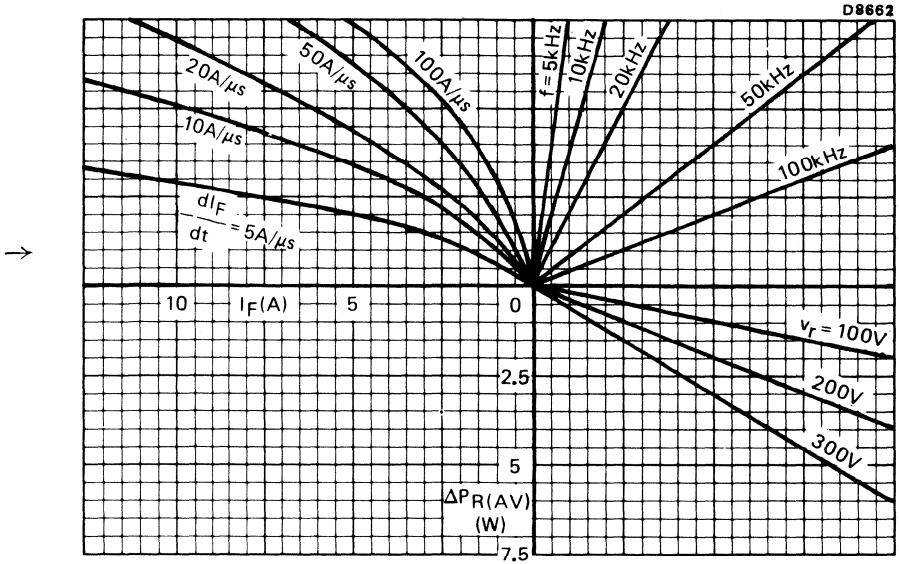
<sup>1)</sup> Measured under pulse conditions to avoid excessive dissipation.

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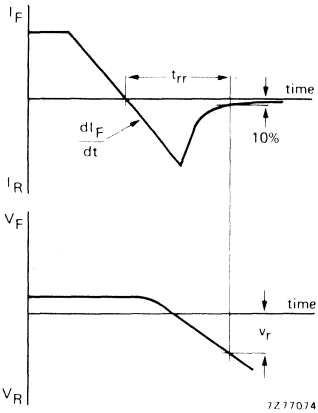




**NOMOGRAM**

Power loss  $\Delta P_R(AV)$  due to switching only (to be added to steady state power losses).

$I_F$  = forward current just before switching off;  $T_j = 150^\circ\text{C}$



## FAST SOFT-RECOVERY RECTIFIER DIODES

Silicon diodes in DO-5 metal envelopes, featuring non-snap-off characteristics. They are intended for use in high-frequency power supplies, thyristor inverters and multi-phase power rectifier applications.

The series consists of the following types:

Normal polarity (cathode to stud): 1N3899, 1N3900, 1N3901, 1N3902, 1N3903.

Reverse polarity (anode to stud), 1N3899R, 1N3900R, 1N3901R, 1N3902R, 1N3903R.

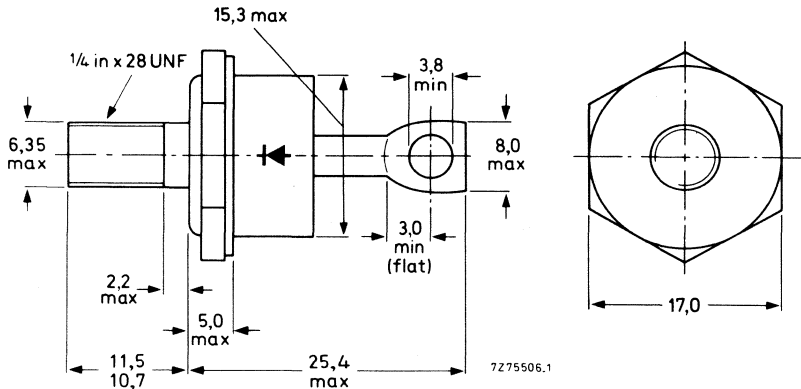
## QUICK REFERENCE DATA

			1N3899(R)	3900(R)	3901(R)	3902(R)	3903(R)	
Repetitive peak reverse voltage	$V_{RRM}$	max.	50	100	200	300	400	V
Average forward current	$I_{F(AV)}$	max.	20					A
Non-repetitive peak forward current	$I_{FSM}$	max.					225	A
Reverse recovery time	$t_{rr}$	<					200	ns

## MECHANICAL DATA

Dimensions in mm

Fig.1 DO-5; Supplied with device: 1 nut, 1 lock washer  
Nut dimensions across the flats: 11.1 mm



Net mass: 22 g

Diameter of clearance hole: max. 6.5 mm

Accessories supplied on request:

56264A (mica washer, insulating ring, tag)

The mark shown applies to normal polarity types.

Torque on nut:

min. 1.7 Nm (17 kg cm)

max. 2.5 Nm (25 kg cm)

**RATINGS**

Limiting values in accordance with the Absolute Maximum System (IEC 134)

**Voltages**

		1N3899(R)	3900(R)	3901(R)	3902(R)	3903(R)	
Non-repetitive peak reverse voltage ( $t \leq 10$ ms)	$V_{RSM}$ max.	75	200	300	400	500	V
Repetitive peak reverse voltage ( $\delta \leq 0.01$ )	$V_{RRM}$ max.	50	100	200	300	400	V
Crest working voltage	$V_{RWM}$ max.	50	100	200	300	400	V

**Currents**

Average on-state current assuming zero switching losses (averaged over any 20 ms period)  
 up to  $T_{mb} = 100$  °C  
 at  $T_{mb} = 125$  °C

$I_F(AV)$	max.	20	A
$I_F(AV)$	max.	10	A

R.M.S. forward current

$I_F(RMS)$	max.	30	A
------------	------	----	---

Repetitive peak forward current

$I_{FRM}$	max.	100	A
-----------	------	-----	---

Non-repetitive peak forward current

$T_j = 150$  °C prior to surge;  
 half sine-wave; with reapplied  $V_{RWMmax}$ ;  
 $t = 10$  ms  
 $t = 8.3$  ms

$I_{FSM}$	max.	200	A
$I_{FSM}$	max.	225	A

$I^2t$  for fusing ( $t = 10$  ms)

$I^2t$	max.	210	A <sup>2</sup> s
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**Temperatures**

Storage temperature

$T_{stg}$		-65 to 175	°C
-----------	--	------------	----

Operating junction temperature

$T_j$	max.	150	°C
-------	------	-----	----

**THERMAL RESISTANCE**

From junction to mounting base

$R_{th j-mb}$	=	1.5	°C/W
---------------	---	-----	------

From mounting base to heatsink with heatsink compound

$R_{th mb-h}$	=	0.3	°C/W
---------------	---	-----	------

Transient thermal impedance;  $t = 1$  ms

$Z_{th j-mb}$	=	0.3	°C/W
---------------	---	-----	------

**CHARACTERISTICS**

Forward voltage

$$I_F = 20 \text{ A}; T_j = 25 \text{ }^\circ\text{C} \qquad V_F < 1.4 \text{ V}^*$$

Reverse current

$$V_R = V_{RWMmax}; T_j = 100 \text{ }^\circ\text{C} \qquad I_R < 6 \text{ mA}$$

Reverse recovery when switched from

$$I_F = 1 \text{ A to } V_R \geq 30 \text{ V}; -dI_F/dt = 35 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$$

Recovery time  $t_{rr} < 200 \text{ ns}$

$$I_F = 2 \text{ A to } V_R \geq 30 \text{ V}; -dI_F/dt = 20 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$$

Recovered charge  $Q_s < 250 \text{ nC}$

Maximum slope of the reverse recovery current

when switched from  $I_F = 1 \text{ A to } V_R \geq 30 \text{ V};$

$$-dI_F/dt = 2 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C} \qquad |dI_R/dt| < 5 \text{ A}/\mu\text{s}$$

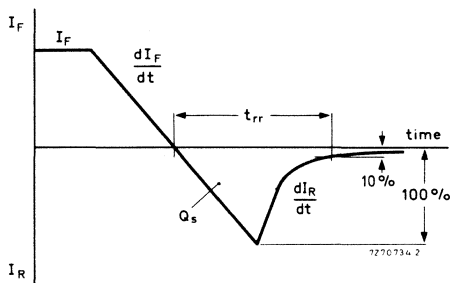


Fig.2 Definitions of  $t_{rr}$  and  $Q_s$ .

D8403

\*Measured under pulse conditions to avoid excessive dissipation.

SINUSOIDAL OPERATION

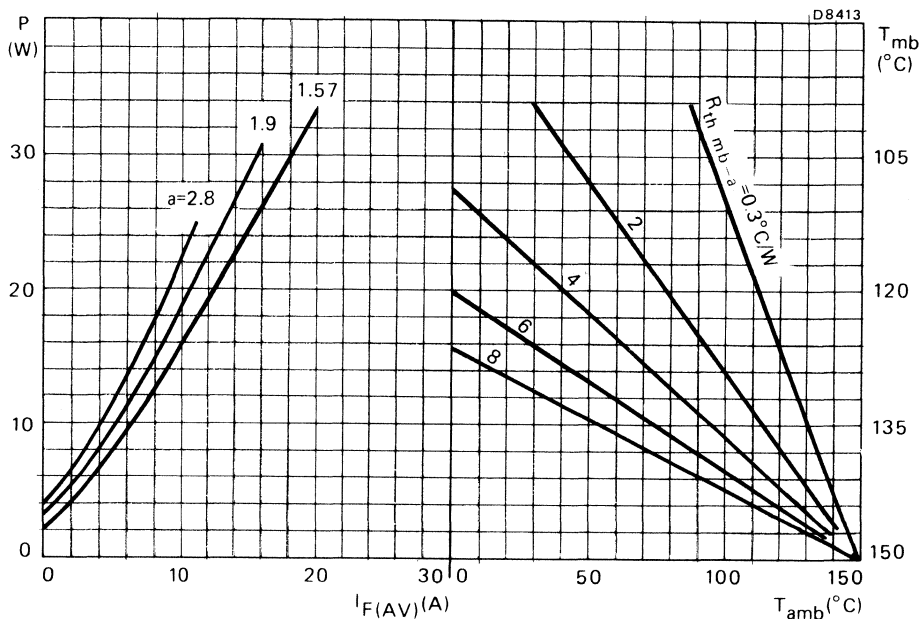


Fig.3 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.  
 P = power dissipation excluding switching losses.  
 a = form factor =  $I_{F(RMS)}/I_{F(AV)}$ .

SQUARE WAVE OPERATION

D8414

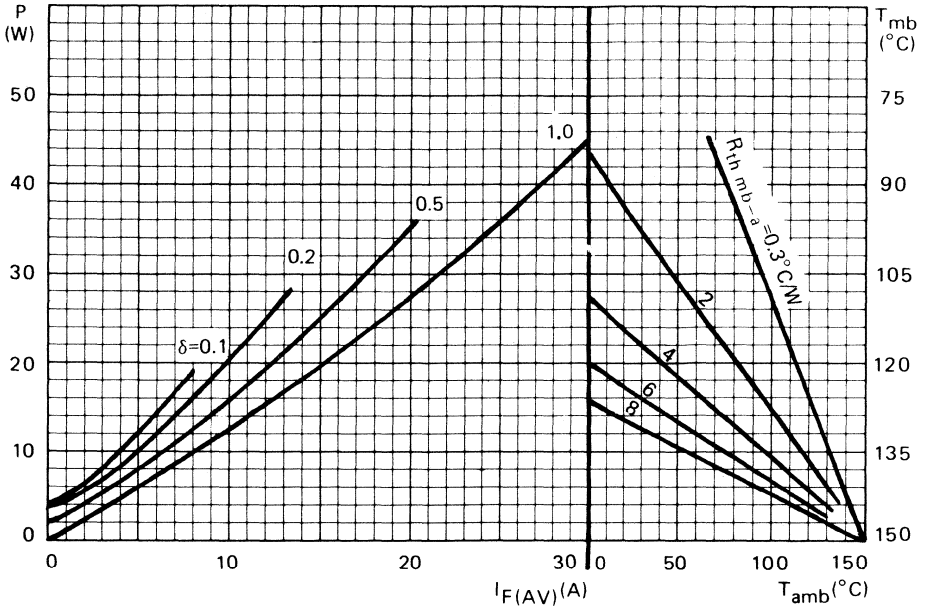
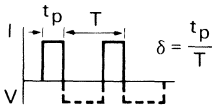


Fig.4 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.  
 P = power dissipation excluding switching losses.



$$I_{F(AV)} = I_{F(RMS)} \times \sqrt{\delta}$$

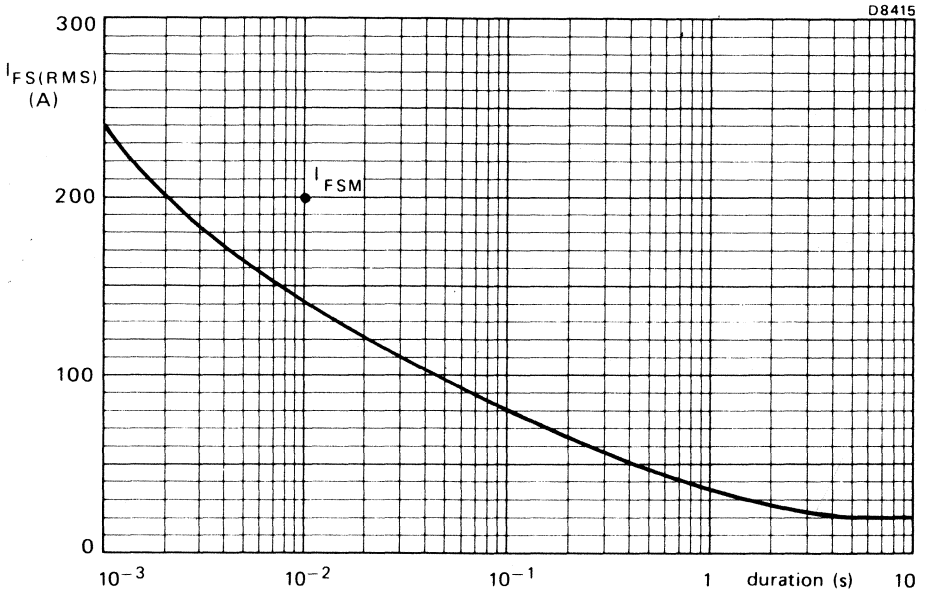
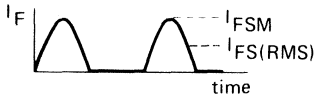


Fig.5 Maximum permissible non-repetitive r.m.s. forward current based on sinusoidal currents ( $f = 50$  Hz);  $T_j = 150$  °C prior to surge; with reapplied  $V_{RWMmax}$ .





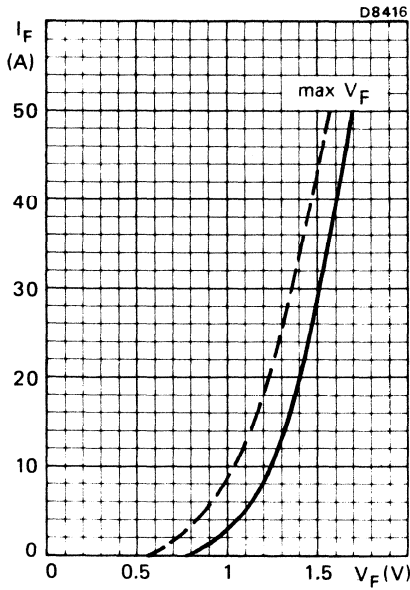


Fig.6 —  $T_j = 25\text{ }^\circ\text{C}$ ; ---  $T_j = 150\text{ }^\circ\text{C}$

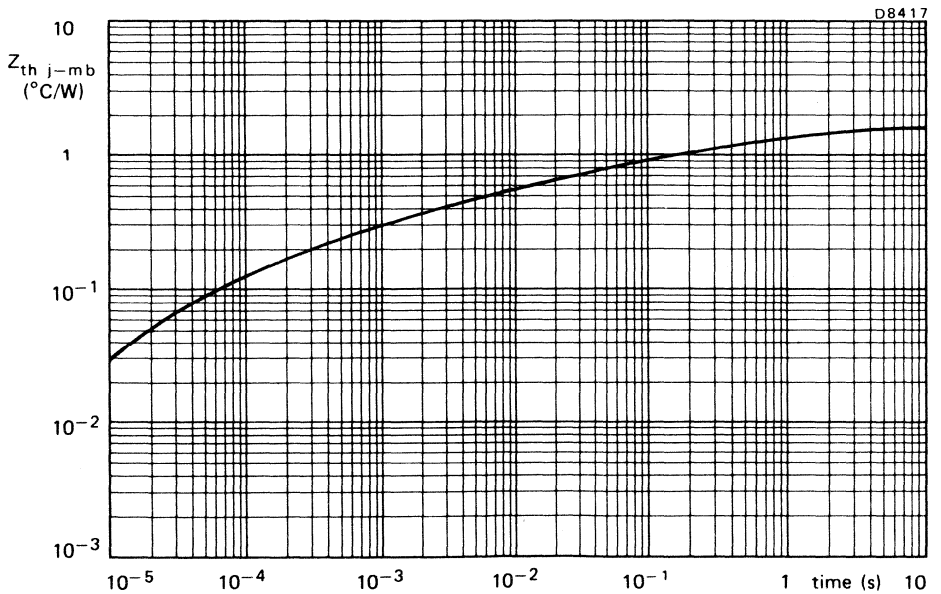


Fig.7



## FAST SOFT-RECOVERY RECTIFIER DIODES

Silicon diodes in DO-5 metal envelopes, featuring non-snap-off characteristics. They are intended for use in high-frequency power supplies, thyristor inverters and multi-phase power rectifier applications. The series consists of the following types:

Normal polarity (cathode to stud): 1N3909, 1N3910, 1N3911, 1N3912, 1N3913.

Reverse polarity (anode to stud): 1N3909R, 1N3910R, 1N3911R, 1N3912R, 1N3913R.

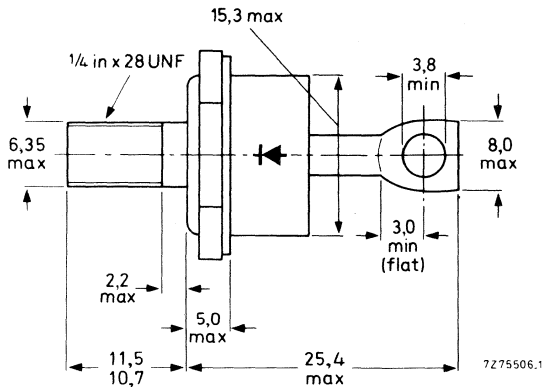
## QUICK REFERENCE DATA

		1N3909(R)	3910(R)	3911(R)	3912(R)	3913(R)	
Repetitive peak reverse voltage	$V_{RRM}$ max.	50	100	200	300	400	V
Average forward current	$I_{F(AV)}$ max.			30			A
Non-repetitive peak forward current	$I_{FSM}$ max.			300			A
Reverse recovery time	$t_{rr}$ <			200			ns

## MECHANICAL DATA

Dimensions in mm

Fig.1 DO-5; Supplied with device: 1 nut, 1 lock-washer  
Nut dimensions across the flats: 11.1 mm



Net mass: 22 g

Diameter of clearance hole: max. 6.5 mm

Accessories supplied on request:

56264A (mica washer, insulating ring, tag)

The mark shown applies to normal polarity types.

Torque on nut:

min. 1.7 Nm (17 kg cm)

max. 2.5 Nm (25 kg cm)

**RATINGS**

Limiting values in accordance with the Absolute Maximum System (IEC 134)

**Voltages**

			1N3909(R)	3910(R)	3911(R)	3912(R)	3913(R)	
Non-repetitive peak reverse voltage (t = 10 ms)	$V_{RSM}$	max.	75	200	300	400	500	V
Repetitive peak reverse voltage ( $\delta \leq 0.01$ )	$V_{RRM}$	max.	50	100	200	300	400	V
Crest working voltage	$V_{RWM}$	max.	50	100	200	300	400	V

**Currents**

Average on-state current assuming zero switching losses (averaged over any 20 ms period)

up to  $T_{mb} = 100\text{ }^\circ\text{C}$

at  $T_{mb} = 125\text{ }^\circ\text{C}$

$I_F(AV)$	max.	30	A
$I_F(AV)$	max.	15	A

R.M.S. forward current

$I_F(RMS)$	max.	45	A
------------	------	----	---

Repetitive peak forward current

$I_{FRM}$	max.	125	A
-----------	------	-----	---

Non-repetitive peak forward current

$T_j = 150\text{ }^\circ\text{C}$  prior to surge;

half sine-wave with reapplied  $V_{RWMmax}$ ;

t = 10 ms

t = 8.3 ms

$I_{FSM}$	max.	275	A
$I_{FSM}$	max.	300	A

$I^2t$  for fusing (t = 10 ms)

$I^2t$	max.	375	$A^2s$
--------	------	-----	--------

**Temperatures**

Storage temperature

$T_{stg}$		-65 to 175	$^\circ\text{C}$
-----------	--	------------	------------------

Operating junction temperature

$T_j$	max.	150	$^\circ\text{C}$
-------	------	-----	------------------

**THERMAL RESISTANCE**

From junction to mounting base

$R_{th\ j-mb}$	=	1.0	$^\circ\text{C/W}$
----------------	---	-----	--------------------

From mounting base to heatsink with heatsink compound

$R_{th\ mb-h}$	=	0.3	$^\circ\text{C/W}$
----------------	---	-----	--------------------

Transient thermal impedance; t = 1 ms

$Z_{th\ j-mb}$	=	0.2	$^\circ\text{C/W}$
----------------	---	-----	--------------------

**CHARACTERISTICS**

Forward voltage

$I_F = 30 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_F < 1.4 \text{ V}^*$

Reverse current

$V_R = V_{RWMmax}; T_j = 100 \text{ }^\circ\text{C}$

$I_R < 10 \text{ mA}$

Reverse recovery when switched from

$I_F = 1 \text{ A to } V_R \geq 30 \text{ V}; -dI_F/dt = 35 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

Recovery time

$t_{rr} < 200 \text{ ns}$

$I_F = 2 \text{ A to } V_R \geq 30 \text{ V}; -dI_F/dt = 20 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

Recovered charge

$Q_s < 250 \text{ nC}$

Maximum slope of the reverse recovery current

when switched from  $I_F = 1 \text{ A to } V_R \geq 30 \text{ V};$

$-dI_F/dt = 2 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

$|dI_R/dt| < 5 \text{ A}/\mu\text{s}$

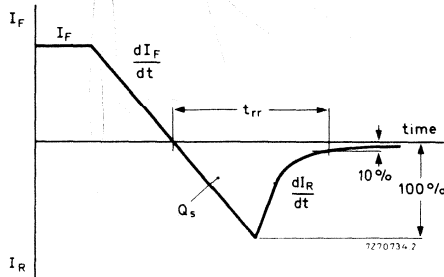


Fig. 2 Definitions of  $t_{rr}$  and  $Q_s$ .

D8403

\*Measured under pulse conditions to avoid excessive dissipation.

SINUSOIDAL OPERATION

D8408

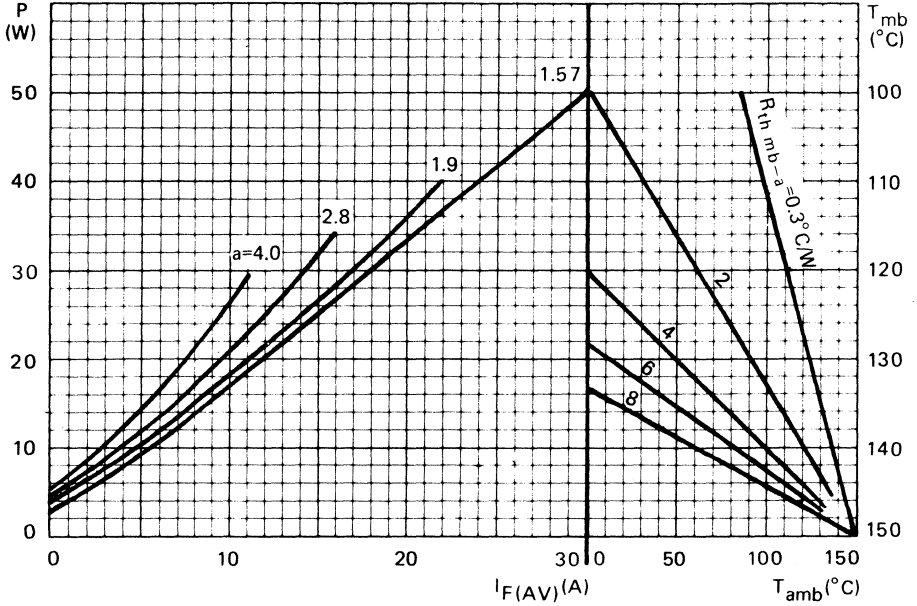


Fig. 3 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.  
 P = power dissipation excluding switching losses.  
 a = form factor =  $I_{F(RMS)}/I_{F(AV)}$ .

SQUARE-WAVE OPERATION

D 8409

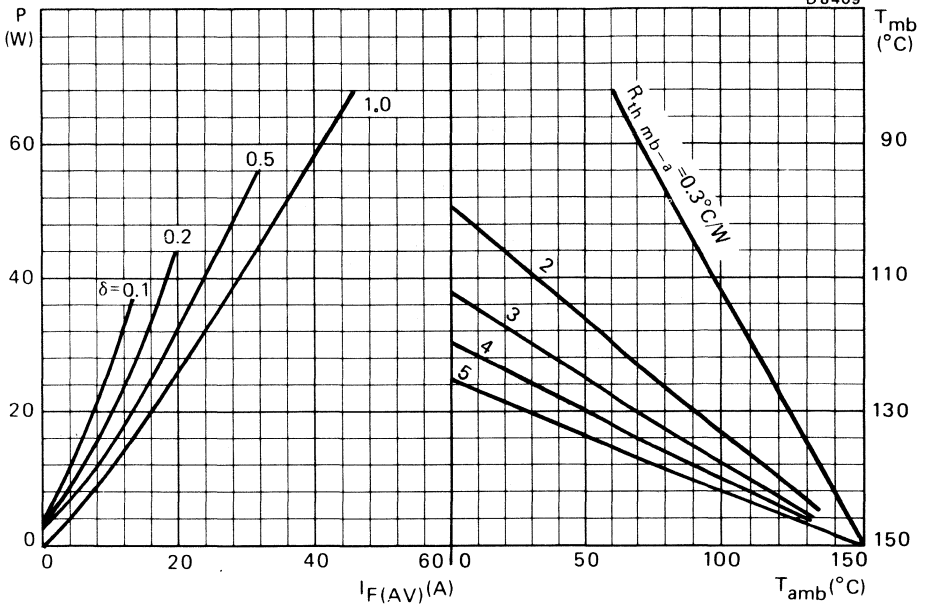
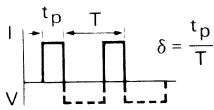


Fig. 4 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures. P = power dissipation excluding switching losses.



$$I_{F(AV)} = I_{F(RMS)} \times \sqrt{\delta}$$

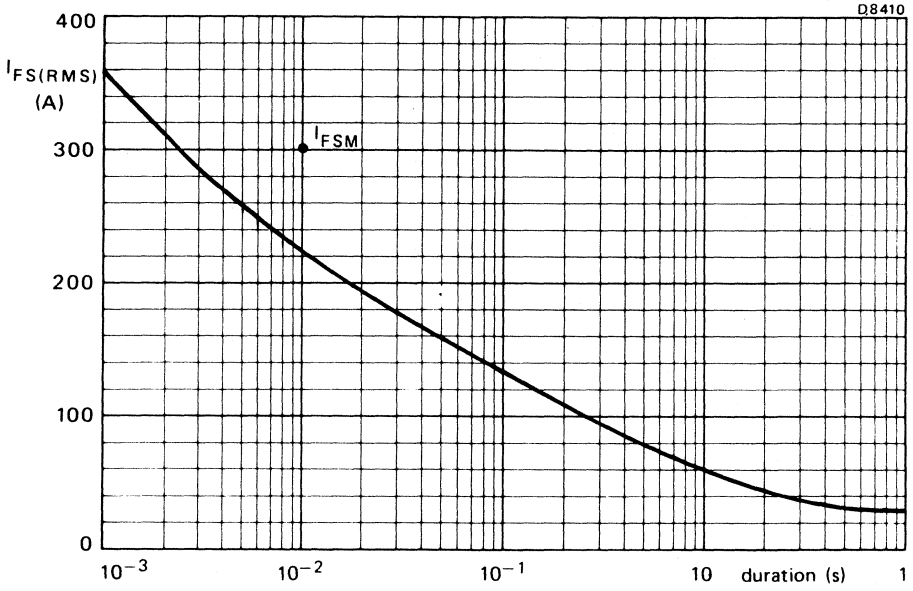


Fig.5 Maximum permissible non-repetitive r.m.s. forward current based on sinusoidal currents ( $f = 50$  Hz);  $T_j = 150$  °C prior to surge; with reapplied  $V_{RWMmax}$ .





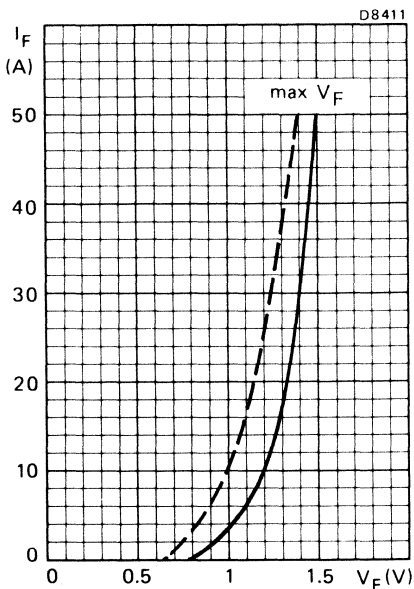


Fig. 6 —  $T_j = 25\text{ }^\circ\text{C}$ ; ---  $T_j = 150\text{ }^\circ\text{C}$

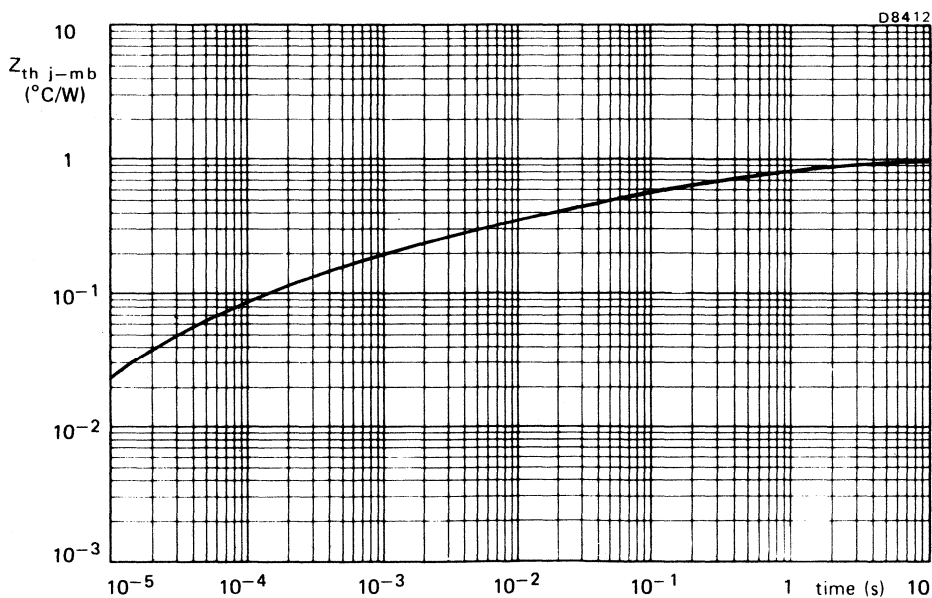


Fig. 7



# REGULATOR DIODES

**C**



**C**

## VOLTAGE REGULATOR DIODES

A range of voltage regulator diodes in plastic envelopes intended for use as voltage stabilizers in power supply circuits.

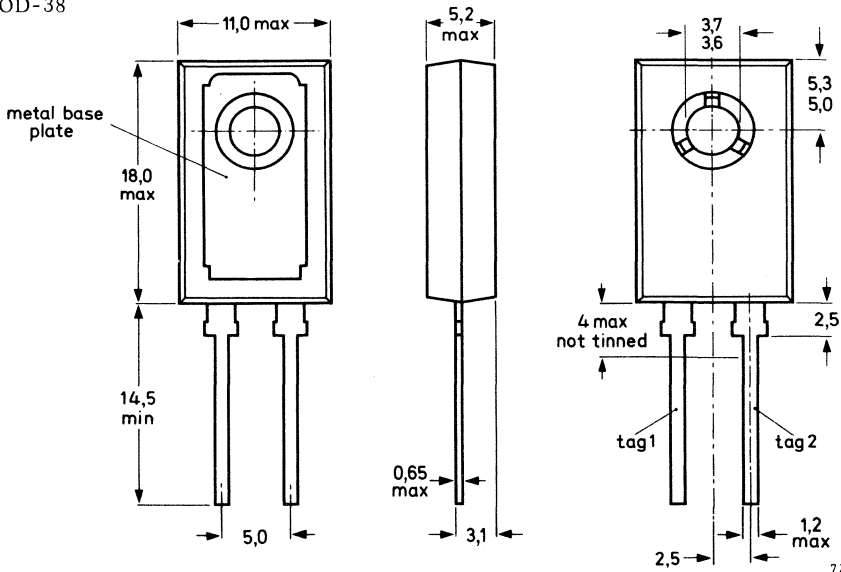
Normal and reverse polarity types are available: BZV15-C10(R) to C75(R).

QUICK REFERENCE DATA			
Working voltage range (5% range)	$V_Z$	nom.	10 to 75 V
Total power dissipation at $T_{amb} = 25\text{ }^\circ\text{C}$ at $T_{mb} = 82\text{ }^\circ\text{C}$	$P_{tot}$	max.	2,2 W
	$P_{tot}$	max.	15 W
Junction temperature	$T_j$	max.	150 $^\circ\text{C}$

### MECHANICAL DATA

Dimensions in mm

SOD-38



Net mass; 2,5 g

Accessories:

supplied with device : washer

available on request : 56316 (mica insulating washer)

Torque on screw : min. 0,95 Nm

(9,5 kg cm)

max. 1,5 Nm

(15 kg cm)

Tag 1 is connected to the metal base-plate, which should be mounted in contact with the heatsink used.

**POLARITY OF CONNECTIONS**

	BZV15-C10 to C75	BZV15-C10R to C75R
Base-plate :	cathode	anode
Tag 1 :	cathode	anode
Tag 2 :	anode	cathode

**RATINGS** Limiting values in accordance with the Absolute Maximum System (IEC 134)

Currents

Average forward current (averaged over any 20 ms period) at $T_{mb} = 82\text{ }^{\circ}\text{C}$	$I_{F(AV)}$	max.	7,5	A
Repetitive peak forward current	$I_{FRM}$	max.	50	A

Power dissipation

Total power dissipation at $T_{amb} = 25\text{ }^{\circ}\text{C}$ (method a) at $T_{mb} = 82\text{ }^{\circ}\text{C}$	$P_{tot}$	max.	2,2	W
	$P_{tot}$	max.	15	W
Non-repetitive peak reverse power dissipation $T_{amb} = 25\text{ }^{\circ}\text{C}$ ; $t = 1\text{ ms}$ (square pulse)	$P_{ZSM}$	max.	400	W

Temperatures

Storage temperature	$T_{stg}$	-55 to +125	$^{\circ}\text{C}$
Junction temperature	$T_j$	max.	150 $^{\circ}\text{C}$

**SOLDERING AND MOUNTING NOTES**

1. The devices may be soldered directly into the circuit.
2. The maximum permissible temperature of the soldering iron or bath is  $270\text{ }^{\circ}\text{C}$ ; contact with the joint must not exceed 3 seconds.
3. The devices should not be immersed in oil, and few potting resins are suitable for re-encapsulation. Advice on these materials is available on request.
4. Leads should not be bent less than 2,5 mm from the seal; exert no axial pull when bending.
5. Soldered joints must be at least 2,5 mm from the seal.
6. For good thermal contact heatsink compound should be used between base-plate and heatsink.

**THERMAL RESISTANCE**

From junction to mounting base

$$R_{th\ j-mb} = 4,5\ ^\circ C/W$$

Transient thermal impedance;  $t = 1\ ms$

$$Z_{th\ j-mb} = 0,3\ ^\circ C/W$$

**Influence of mounting method**

1. Heatsink operation

From mounting base to heatsink

a. With heatsink compound

$$R_{th\ mb-h} = 1,5\ ^\circ C/W$$

b. With heatsink compound and  
56316 mica washer

$$R_{th\ mb-h} = 2,7\ ^\circ C/W$$

c. Without heatsink compound

$$R_{th\ mb-h} = 2,7\ ^\circ C/W$$

d. Without heatsink compound  
with 56316 mica washer

$$R_{th\ mb-h} = 5\ ^\circ C/W$$

2. Free air operation

The quoted values of  $R_{th\ j-a}$  should be used only when no other leads run to the tie-points.

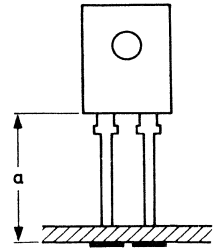
From junction to ambient in free air  
mounted on a printed circuit board

at  $a =$  maximum lead length  
and with a copper laminate

- a.  $> 1\ cm^2$
- b.  $< 1\ cm^2$

$$R_{th\ j-a} = 50\ ^\circ C/W$$

$$R_{th\ j-a} = 55\ ^\circ C/W$$



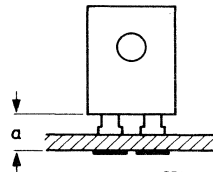
7Z62315.1

at a lead-length  $a = 3\ mm$   
and with a copper laminate

- c.  $> 1\ cm^2$
- d.  $< 1\ cm^2$

$$R_{th\ j-a} = 55\ ^\circ C/W$$

$$R_{th\ j-a} = 60\ ^\circ C/W$$



7Z62314

# BZV15 SERIES

## CHARACTERISTICS

$T_j = 25\text{ }^\circ\text{C}$  unless otherwise specified

Forward voltage at  $I_F = 10\text{ A}$

$V_F < 1,5\text{ V}$

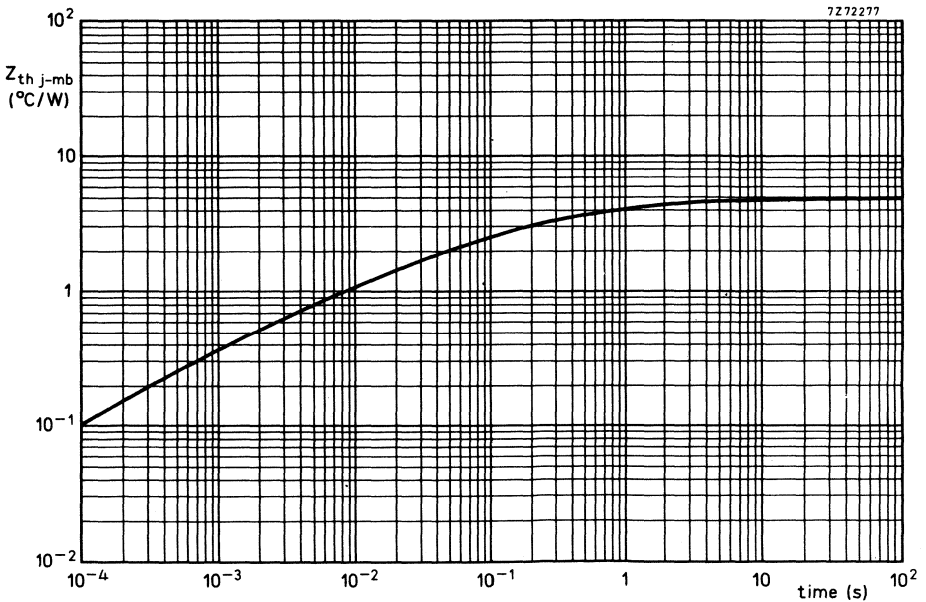
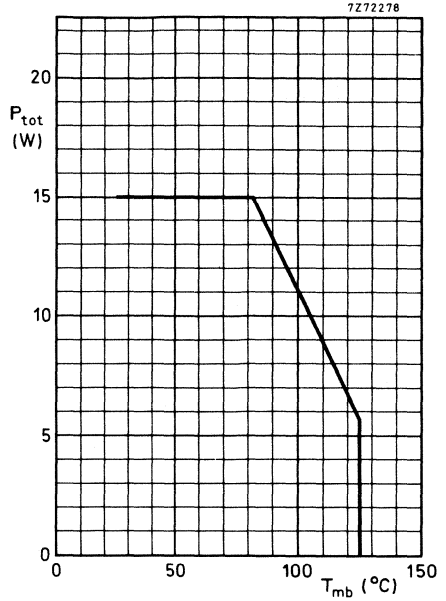
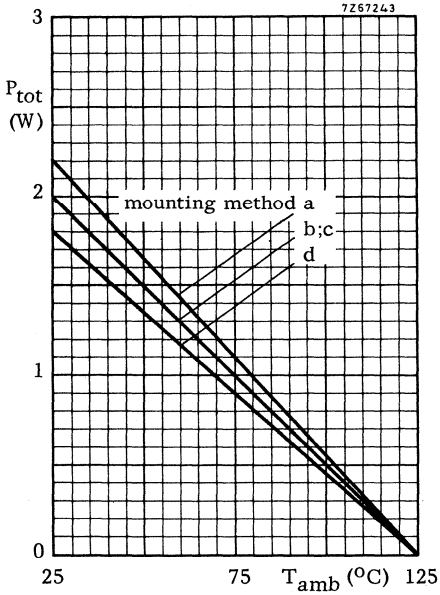
Reverse current at  $V_R = \frac{2}{3} V_{Znom}$

$I_R < 50\text{ }\mu\text{A}$

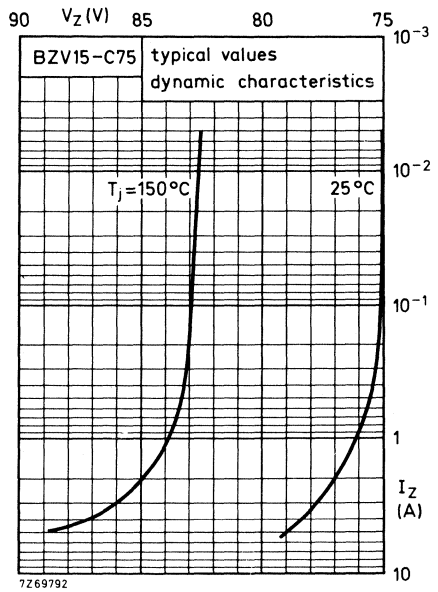
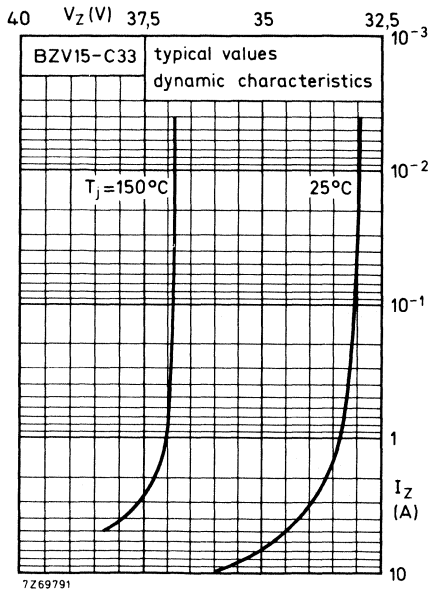
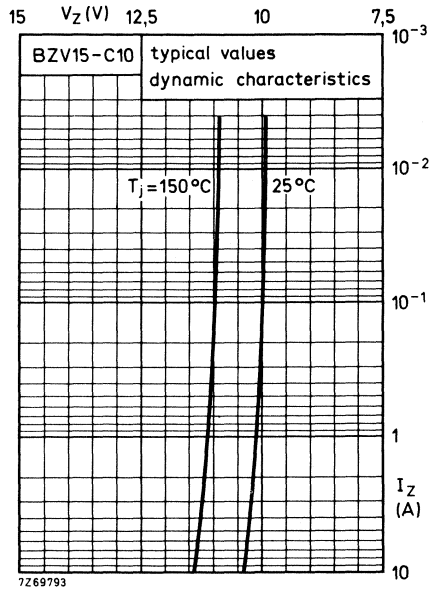
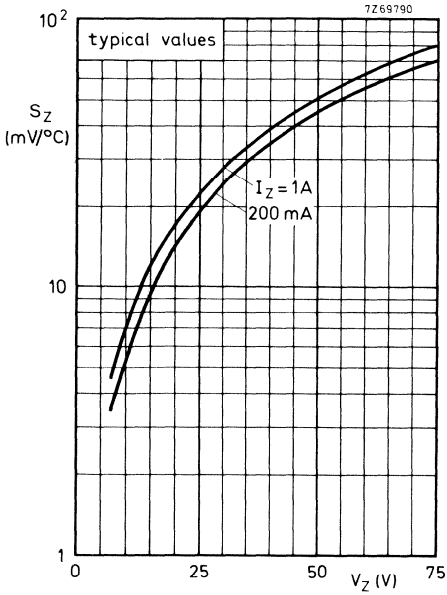
	Working voltage		Differential resistance $r_{diff}$ ( $\Omega$ ) <sup>1)</sup>	Temperature coefficient $SZ$ (mV/ $^\circ\text{C}$ ) <sup>1)</sup>
	$V_Z$ (V) 1)			
	at $I_Z = 1\text{ A}$		at $I_Z = 1\text{ A}$	at $I_Z = 1\text{ A}$
BZV15- . .	min.	max.	max.	typ.
C10(R)	9,4	10,6	0,5	9
C11(R)	10,4	11,6	1,0	9,9
C12(R)	11,4	12,7	1,0	10,8
C13(R)	12,4	14,1	1,0	11,7
C15(R)	13,8	15,6	1,2	13,5
	at $I_Z = 0,5\text{ A}$		at $I_Z = 0,5\text{ A}$	at $I_Z = 0,5\text{ A}$
C16(R)	15,3	17,1	1,2	14,4
C18(R)	16,8	19,1	1,5	16,2
C20(R)	18,8	21,2	1,5	15
C22(R)	20,8	23,3	1,8	16,5
C24(R)	22,7	25,9	2,0	19,2
C27(R)	25,1	28,9	2,0	22,1
C30(R)	28	32	2,5	25,5
C33(R)	31	35	3,0	29
	at $I_Z = 0,2\text{ A}$		at $I_Z = 0,2\text{ A}$	at $I_Z = 0,2\text{ A}$
C36(R)	34	38	4,0	32,4
C39(R)	37	41	5,0	35,1
C43(R)	40	46	6,5	39,6
C47(R)	44	50	7,0	43,7
C51(R)	48	54	7,5	47,4
C56(R)	52	60	8,0	52,6
C62(R)	58	66	9,0	58,3
C68(R)	64	72	10,0	63,9
C75(R)	70	79	10,5	71,3

1) Measured by a pulse method with  $t_p \leq 100\text{ }\mu\text{s}$ , duty cycle  $\delta \leq 0,001$  and  $T_j \approx 25\text{ }^\circ\text{C}$ .





# BZV15 SERIES



## TRANSIENT SUPPRESSOR BRIDGES

Plastic encapsulated bridge assembly comprising four silicon double diffused transient suppressor diodes. It is specifically intended for use as line polarity guard and transient protection element in telephony equipment, and as suppressor element in electrical and electronic equipment in general.

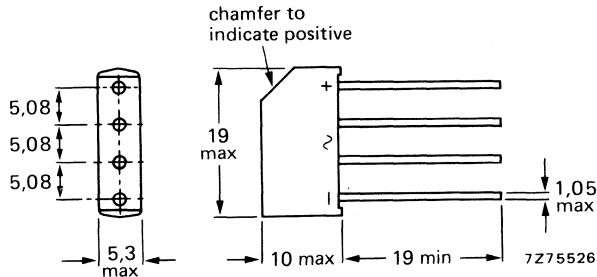
## QUICK REFERENCE DATA

			BZW10-12		15	
Input stand-off voltage	$V_I$	max.	12	15	V	
Output clamping voltage	$V_{O(CL)}$	<	30	34	V	
Non-repetitive peak clamping current	$I_{(CL)SM}$	max.	50	40	A	
Output voltage	$V_O$	>	10	13	V	

## MECHANICAL DATA

Dimensions in mm

Fig. 1 SOD-28



The sealing of the plastic envelope withstands the accelerated damp heat test of IEC recommendation 68-2 (test D, severity IV, 6 cycles).

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC134)

		BZW10-12		15	
Input stand-off voltage (note 1)	$V_I$	max.	12	15	V
Average output current (averaged over any 20 ms period)	$I_O(AV)$	max.	150	150	mA
Non-repetitive peak clamping current full load prior to surge (see note 2)	$I_{(CL)SM}$	max.	50	40	A
→ Storage temperature	$T_{stg}$		-55 to +150		°C
→ Operating ambient temperature	$T_{amb}$		-25 to +85		°C

## THERMAL RESISTANCE

From junction to ambient	$R_{th j-a}$	=	60	°C/W
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## CHARACTERISTICS

→  $T_{amb} = -25$  to  $+85$  °C

Output voltage $V_I = V_{I_{max}}$ ; $I_O = 10$ mA	$V_O$	>	10	13	V
Output clamping voltage at $I_{(CL)SM}$ at rated load conditions	$V_{O(CL)}$	<	30	34	V
Leakage current $V_I = V_{I_{max}}$ ; at rated load conditions	$I_R$	<	40	40	μA

## MOUNTING INSTRUCTIONS

1. The maximum permissible temperature of the soldering iron or bath is 270 °C; it must not be in contact with the joint for more than 3 seconds.
2. Avoid hot spots due to handling or mounting; the body of the device must not come into contact with or be exposed to a temperature higher than 150 °C.
3. Exert no axial pull when bending the leads.

## Notes

1. The stand-off voltage is the maximum bridge input voltage permitted for continuous operation.
2. In accordance with F.T.Z. requirement 10/700 with 2 kV test voltage: BZW10-12 and 1.6 kV: BZW10-15 (see also page 3).

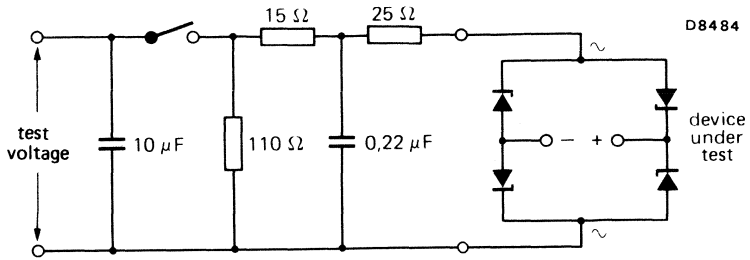


Fig. 2 Test set-up in accordance with F.T.Z. 10/700

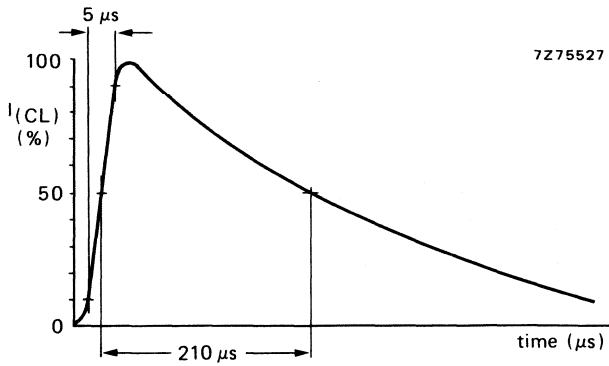


Fig. 3 Output clamping current as a function of time.



## TRANSIENT SUPPRESSOR DIODES

A range of diffused silicon diodes in a plastic envelope intended for use in the protection of electrical and electronic equipment against voltage transients.  
The series consists of the following types: BZW70-5V6 to BZW70-62.

### QUICK REFERENCE DATA

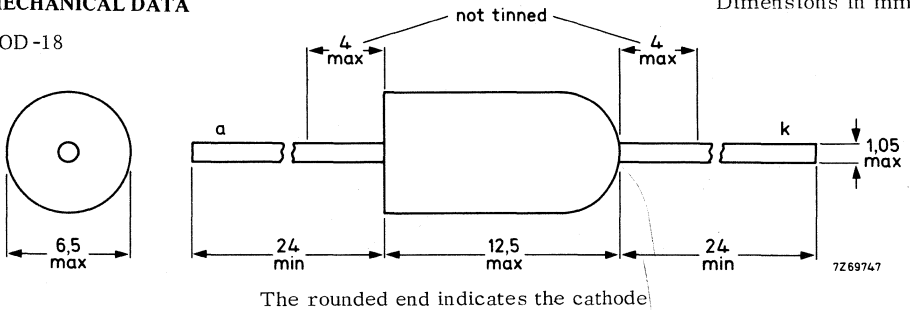
Stand-off voltage (15% range) *	$V_R$	5,6 to 62 V
Reverse breakdown voltage	$V_{(BR)R}$	6,4 to 70 V
Non-repetitive peak reverse power dissipation; exponential pulse	PRSM	max. 700 W

\* The stand-off voltage is the maximum reverse voltage recommended for continuous operation; at this value non-conduction is ensured.

### MECHANICAL DATA

SOD-18

Dimensions in mm



The sealing of the plastic envelope withstands the accelerated damp heat test of IEC recommendation 68-2 (test D, severity IV, 6 cycles).

CHARACTERISTICS – WHEN USED AS TRANSIENT SUPPRESSOR DIODES;  $T_{amb} = 25\text{ }^{\circ}\text{C}$ 

clamping voltage $t_p = 500\ \mu\text{s}$ exp. pulse $V_{(CL)R}$ V		at	non-repetitive peak reverse current  $I_{RSM}$ A	reverse current at recommended stand-off voltage  $I_R$ mA $V_R$ V		BZW70-...
typ.	max.			max.		
9	10		20	0.5	5.6	5V6
10	11.2		20	0.5	6.2	6V2
11	12.5		20	0.5	6.8	6V8
12	14		20	0.1	7.5	7V5
13.5	15.5		20	0.1	8.2	8V2
15	17.5		20	0.1	9.1	9V1
17	19		20	0.1	10	10
19	21		20	0.1	11	11
21	23		20	0.1	12	12
23	26		20	0.1	13	13
22	26		10	0.1	15	15
25	29		10	0.1	16	16
28	33		10	0.1	18	18
32	38		10	0.1	20	20
36	43		10	0.1	22	22
41	48		10	0.1	24	24
47	54		10	0.1	27	27
44	52		5	0.1	30	30
49	58		5	0.1	33	33
56	65		5	0.1	36	36
63	72		5	0.1	39	39
71	82		5	0.1	43	43
80	93		5	0.1	47	47
89	104		5	0.1	51	51
98	116		5	0.1	56	56
104	116		5	0.1	62	62



## TRANSIENT SUPPRESSOR DIODES

A range of diffused silicon diodes in a DO-30 metal envelope intended for use in the protection of the electrical and electronic equipment against voltage transients.

The series consists of the following types:

Normal polarity (cathode to stud): BZW86-7V5 to 56

Reverse polarity (anode to stud) : BZW86-7V5R to 56R

### QUICK REFERENCE DATA

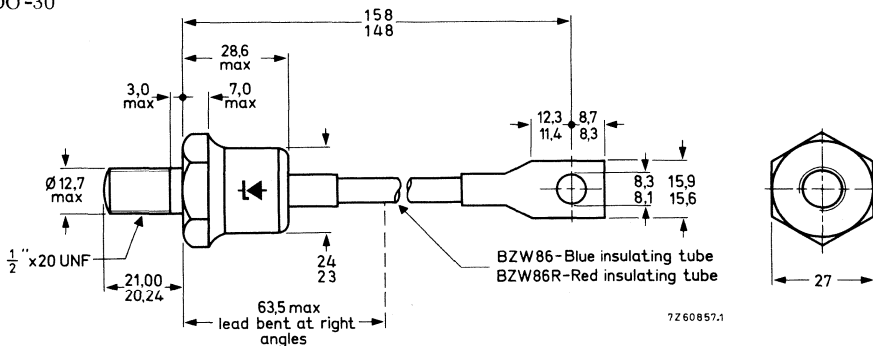
Stand-off voltage (15% range) *	$V_R$	7,5 to 56	V
Reverse breakdown voltage	$V_{(BR)R}$	9,4 to 64	V
Non-repetitive peak reverse power dissipation; exponential pulse	$P_{RSM}$ max.	25	kW

\* The stand-off voltage is the maximum reverse voltage recommended for continuous operation; at this value non-conduction is ensured.

### MECHANICAL DATA

Dimensions in mm

DO-30



Supplied with device: 1 nut, 1 lock washer

Nut dimensions across the flats: 19 mm

Diameter of clearance hole: max. 13 mm

Net weight: 123 g

The mark shown applies to the normal polarity types.

Torque on nut: min. 9 Nm

(90 kgcm)

max. 17,5 Nm

(175 kgcm)

# BZW86 SERIES

**RATINGS** Limiting values in accordance with the Absolute Maximum System (IEC134)

Stand-off voltage \*  $V_R$  equal to type number suffix

## Currents

Non-repetitive peak reverse current

$T_j = 25\text{ }^\circ\text{C}$  prior to surge

$t_p = 10\text{ }\mu\text{s}$ ; square pulse

BZW86-9V1(R)

$I_{RSM}$  max. 3700 A

BZW86-27(R)

$I_{RSM}$  max. 1200 A

BZW86-56(R)

$I_{RSM}$  max. 700 A

$t_p = 1\text{ ms}$ ; exponential pulse

BZW86-9V1(R)

$I_{RSM}$  max. 1200 A

BZW86-27(R)

$I_{RSM}$  max. 400 A

BZW86-56(R)

$I_{RSM}$  max. 250 A

## Power dissipation

Repetitive peak reverse power dissipation

$T_{mb} = 65\text{ }^\circ\text{C}$ ;  $f = 50\text{ Hz}$ ;  $t_p = 10\text{ }\mu\text{s}$  (square pulse; see also graphs on page 6)

$P_{RRM}$  max. 50 kW

Non-repetitive peak reverse power dissipation

$T_j = 25\text{ }^\circ\text{C}$  prior to surge; exponential pulse: see also graph on page 5

$t_p = 100\text{ }\mu\text{s}$

$P_{RSM}$  max. 60 kW

$t_p = 1\text{ ms}$

$P_{RSM}$  max. 25 kW

## Temperatures

Storage temperature

$T_{stg}$  -55 to +175  $^\circ\text{C}$

Junction temperature

$T_j$  max. 175  $^\circ\text{C}$

## **THERMAL RESISTANCE**

From junction to mounting base

$R_{th\ j-mb} = 0,3\text{ }^\circ\text{C/W}$

From mounting base to heatsink

$R_{th\ mb-h} = 0,1\text{ }^\circ\text{C/W}$

## **CHARACTERISTICS**

### Forward voltage

$I_F = 500\text{ A}$  at  $T_j = 25\text{ }^\circ\text{C}$

$V_F < 1,5\text{ V}^{**}$

\* The stand-off voltage is the maximum reverse voltage recommended for continuous operation; at this value non-conduction is ensured.

\*\* Measured under pulse condition.

**CHARACTERISTICS** (continued)

	Clamping voltages (exp. pulse) at $T_j = 25^\circ\text{C}$ prior to surge; $t_p = 500 \mu\text{s}$			Reverse breakdown voltage at $T_j = 25^\circ\text{C}$	
	typ.	max.		$V_{(BR)R}$ (V)	min.
BZW86 -7V5(R)	12	14	$I_R = 1000 \text{ A}$	8, 5	$I_R = 10 \text{ A}$
-8V2(R)	13	15, 5		9, 4	
-9V1(R)	14	17		10, 4	
-10(R)	15, 5	18, 5		11, 4	
-11(R)	17	20		12, 4	
-12(R)	18, 5	22		13, 8	
-13(R)	20	24		15, 3	
-15(R)	23	27		16, 8	
-16(R)	27	32		18, 8	
-18(R)	31	36		20, 8	
-20(R)	34	40	$I_R = 500 \text{ A}$	22, 8	$I_R = 5 \text{ A}$
-22(R)	37	43		25, 1	
-24(R)	40	47		28	
-27(R)	44	52		31	
-30(R)	47	55		34	
-33(R)	51	60		37	
-36(R)	55	65		40	
-39(R)	60	70		44	
-43(R)	66	77		48	
-47(R)	72	84		52	
-51(R)	78	92	$I_R = 250 \text{ A}$	58	$I_R = 2 \text{ A}$
-56(R)	85	102		64	

The maximum clamping voltage is the maximum reverse voltage which appear across the diode at the specified pulse duration and junction temperature.  
See curves on pages 8 and 9 for square pulses and pages 10 and 11 for exponential pulses.

**CHARACTERISTICS** (continued)

$T_j = 25\text{ }^\circ\text{C}$  unless otherwise specified

Peak reverse current

$V_{RM}$  = recommended stand-off voltage  $I_{RM} < 2\text{ mA}$

Temperature coefficient of clamping voltage S typ.  $+0,1\text{ } \%/^\circ\text{C}$

**OPERATING NOTES**

Heatsink considerations

- (a) For non-repetitive transients, the device may be used without a heatsink for pulses up to 10 ms in duration.
- (b) For repetitive transients which fall within the permitted operating range shown in the curves on page 6 the required heatsink is found as follows:

$$R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a} = \frac{T_{j\ max} - T_{amb}}{P_s + \delta \cdot P_{RRM}}$$

where  $T_{j\ max} = 175\text{ }^\circ\text{C}$

$T_{amb}$  = ambient temperature

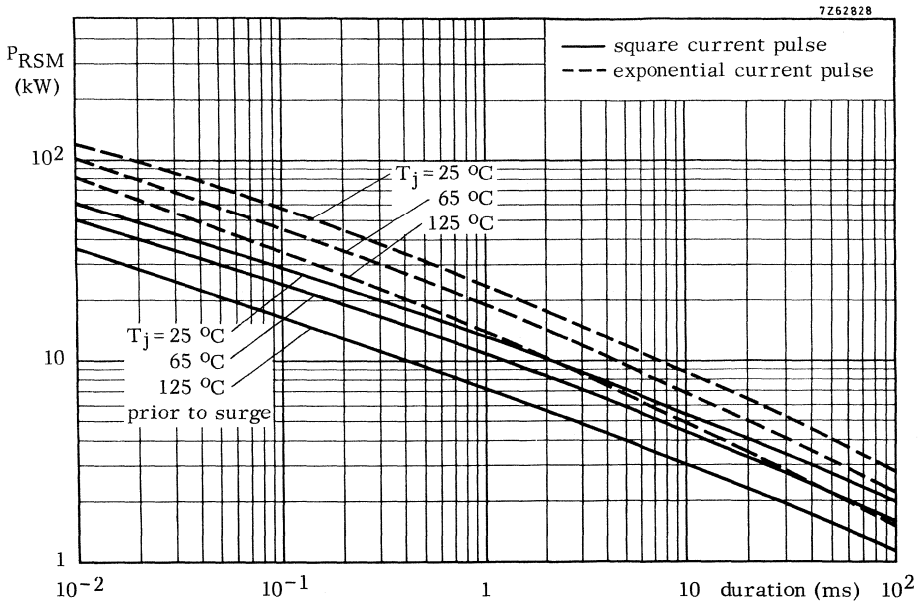
$P_s$  = any steady state dissipation excluding that in pulses

$\delta$  = duty factor ( $t_p/T$ )

$R_{th\ j-mb} = 0,3\text{ }^\circ\text{C/W}$

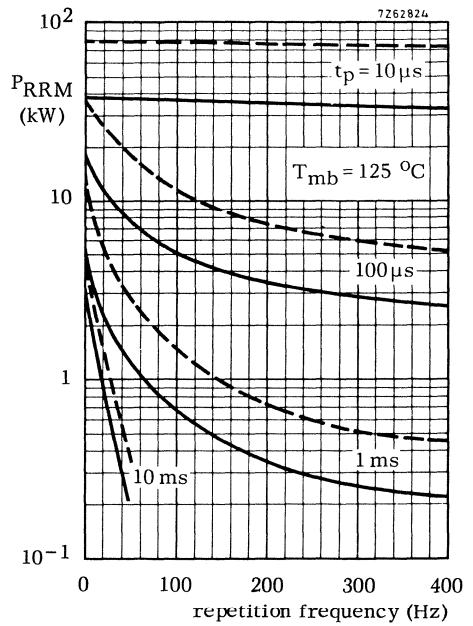
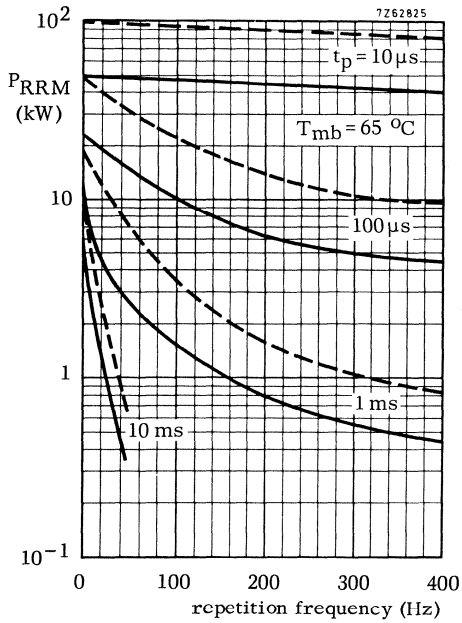
$R_{th\ mb-h} = 0,1\text{ }^\circ\text{C/W}$

thus  $R_{th\ h-a}$  can be found.

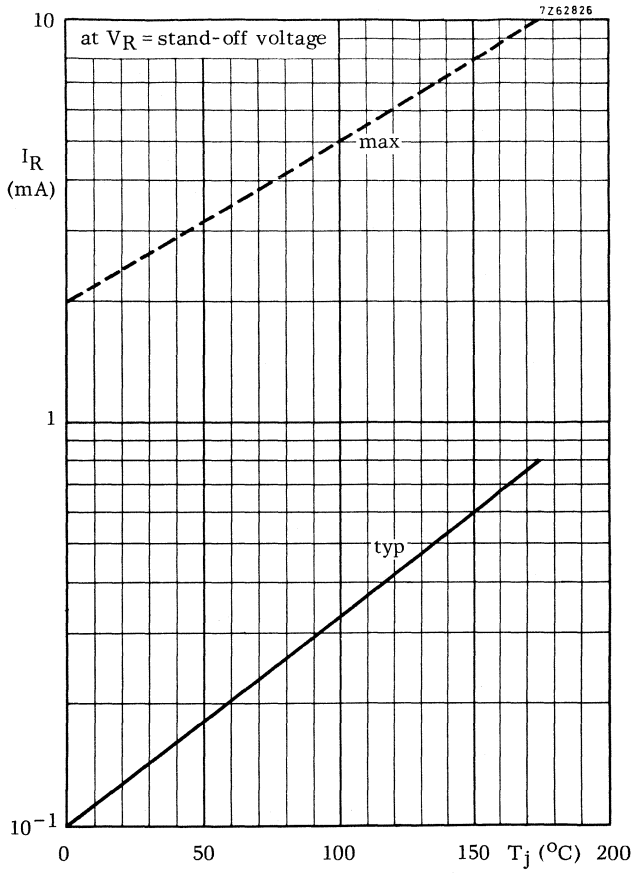


Duration of an exponential pulse is defined as the time taken for the pulse to fall to 37% of its initial value. It is assumed that the energy content does not continue beyond twice this time.

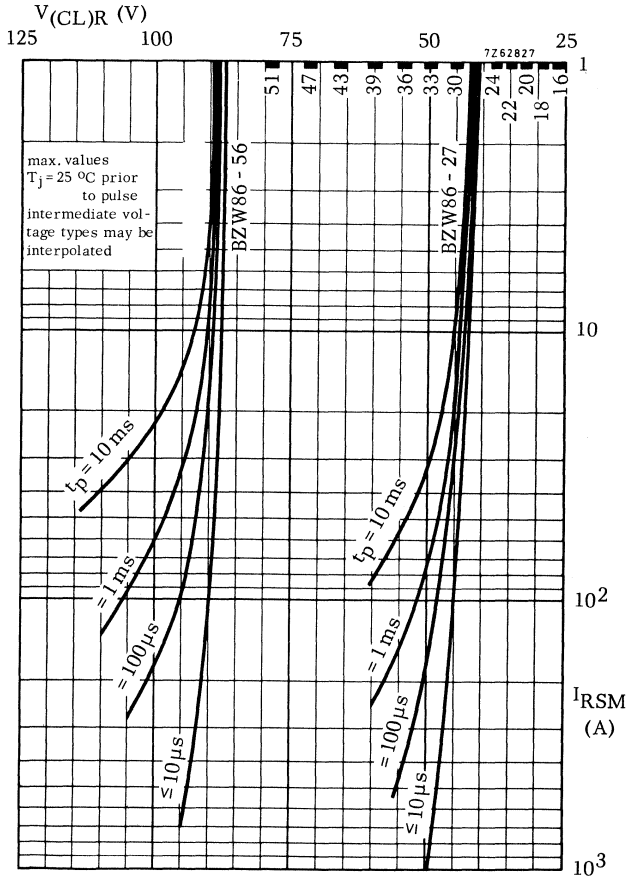
**BZW86**  
**SERIES**



- square current pulses
- - - exponential current pulses

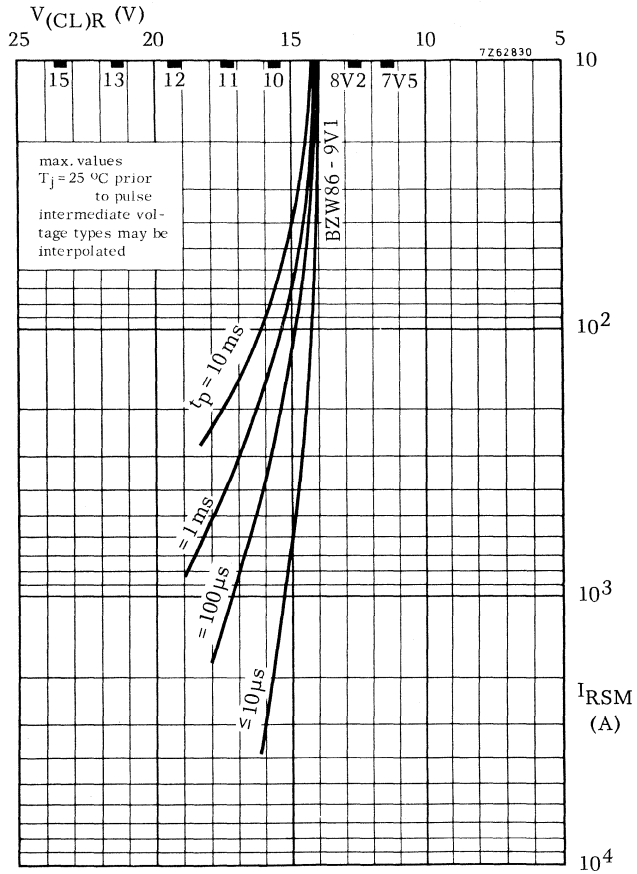


**BZW86**  
SERIES



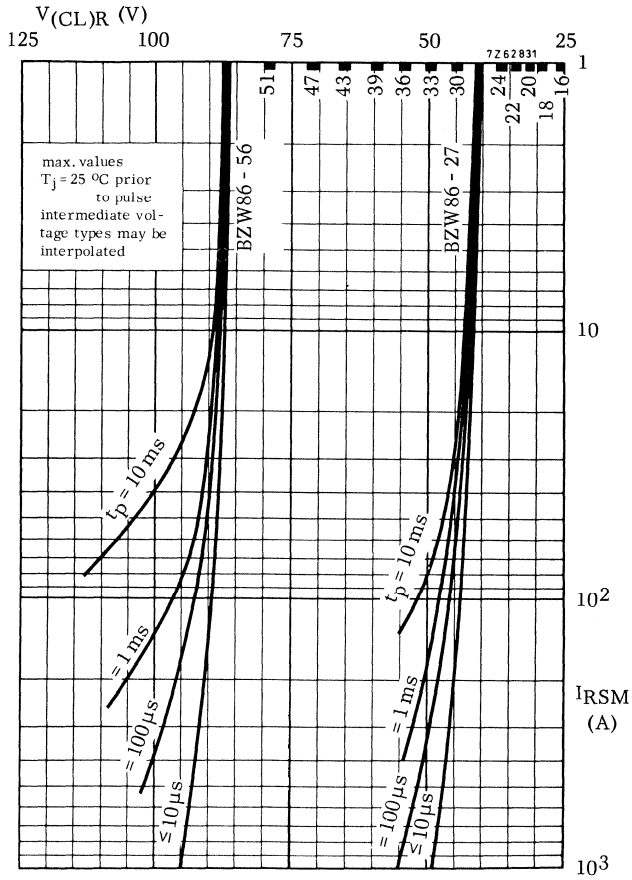
square pulses



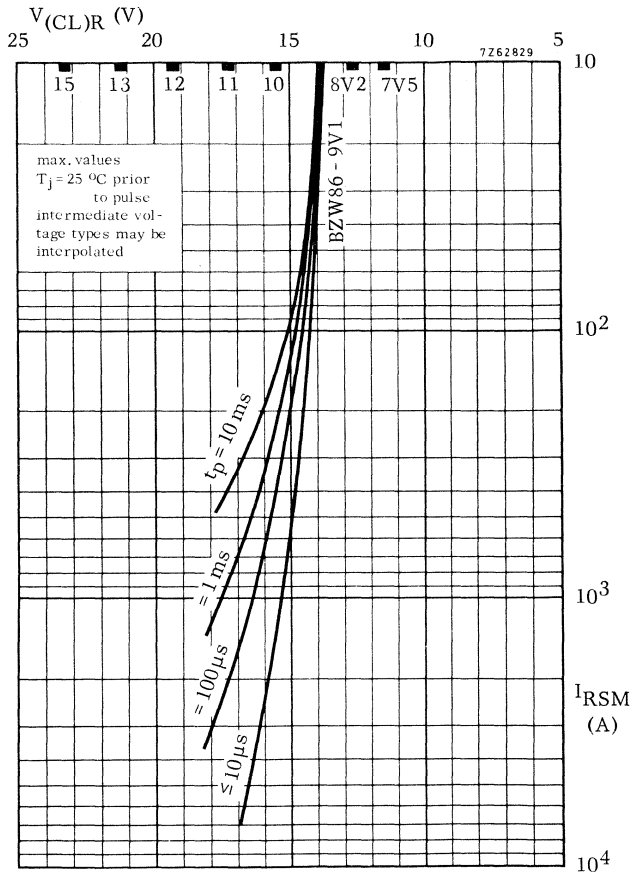


square pulses

**BZW86**  
SERIES



exponential pulses



exponential pulses



## TRANSIENT SUPPRESSOR DIODES

A range of diffused silicon diodes in a DO-5 metal envelope intended for use in the protection of the electrical and electronic equipment against voltage transients.

The series consists of the following types:

Normal polarity (cathode to stud): BZW91 - 6V2 to 62

Reverse polarity (anode to stud) : BZW91 - 6V2R to 62R

### QUICK REFERENCE DATA

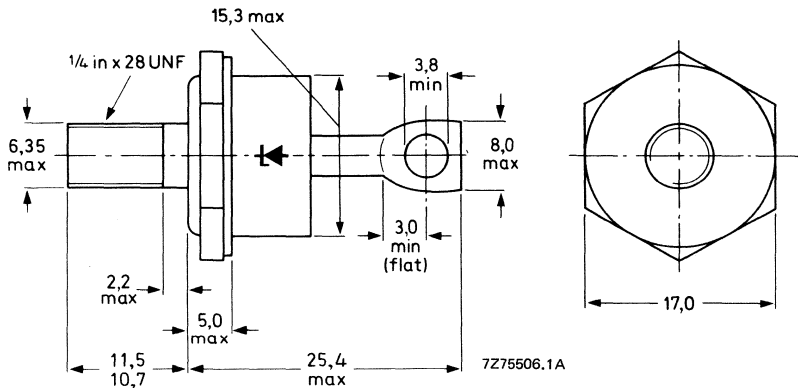
Stand-off voltage (15% range)*	$V_R$	6,2 to 62	V
Reverse breakdown voltage	$V_{(BR)R}$	7,0 to 70	V
Non-repetitive peak reverse power dissipation; $T_j = 25^\circ\text{C}$ prior to surge; $t_p = 100 \mu\text{s}$ (exponential pulse)	$P_{RSM}$	max.	27 kW

\* The stand-off voltage is the maximum reverse voltage recommended for continuous operation; at this value non-conduction is ensured.

### MECHANICAL DATA

Dimensions in mm

DO-5



Supplied with device: 1 nut, 1 lock washer

Nut dimensions across the flats: 11,1 mm

Diameter of clearance hole: max. 6,5 mm

Net mass: 16,5 kg

Accessories available: 56264A; 56309B; 56309R

The mark shown applies to the normal polarity types.

Torque on nut: min. 1,7 Nm.  
(17 kgcm)

max. 3,5 Nm  
(35 kgcm)

CHARACTERISTICS – WHEN USED AS TRANSIENT SUPPRESSOR DIODES;  $T_{mb} = 25\text{ }^{\circ}\text{C}$

clamping voltage $t_p = 500\ \mu\text{s}$ exp. pulse $V_{(CL)R}$ V		at	non-repetitive peak reverse current $I_{RSM}$ A	reverse current at recommended stand-off voltage $I_R$ mA $V_R$ V		BZW91- . . .
typ.	max.			max.		
9.5	10.5		150	20	6.2	6V2(R)
10	11		150	20	6.8	6V8(R)
11	12.5		150	5	7.5	7V5(R)
12	13.5		150	5	8.2	8V2(R)
13	15		150	5	9.1	9V1(R)
14.5	17		150	5	10	10(R)
16	19		150	5	11	11(R)
17.5	22		150	5	12	12(R)
19	26		150	5	13	13(R)
22	28		100	5	15	15(R)
24	31		100	5	16	16(R)
26	34		100	5	18	18(R)
28	37		100	5	20	20(R)
31	40		100	5	22	22(R)
34	44		100	5	24	24(R)
38	48		100	5	27	27(R)
40	52		50	5	30	30(R)
44	56		50	10	33	33(R)
49	61		50	10	36	36(R)
54	66		50	10	39	39(R)
60	72		50	10	43	43(R)
66	79		50	10	47	47(R)
72	87		50	10	51	51(R)
79	97		50	10	56	56(R)
86	97		50	10	62	62(R)

## REGULATOR DIODES

A range of diffused silicon diodes in plastic envelopes, intended for use as voltage regulator and transient suppressor diodes in medium power regulators and transient suppression circuits.

The series consists of the following types: BZX70-C7V5 to BZX70-C75.

### QUICK REFERENCE DATA

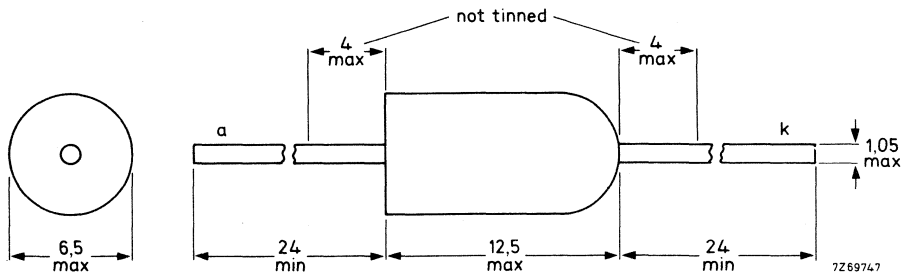
		voltage regulator		transient suppressor	
Working voltage (5% range)	$V_Z$ nom.	7,5 to 75	—	V	
Stand-off voltage	$V_R$	—	5,6 to 56	V	
Total power dissipation	$P_{tot}$ max.	2,5	—	W	
Non-repetitive peak reverse power dissipation	$PRSM$ max.	—	700	W	

### MECHANICAL DATA

Dimensions in mm

Fig. 1 SOD-18.

The rounded end indicates the cathode.



## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

Peak working current	$I_{ZM}$	max.	5 A
Average forward current (averaged over any 20 ms period)	$I_F(AV)$	max.	1 A
Non-repetitive peak reverse current $T_j = 25\text{ }^\circ\text{C}$ prior to surge; $t_p = 1\text{ ms}$ (exponential pulse); BZX70-C7V5 to BZX70-C75	$I_{RSM}$	max.	44 to 6 A
Total power dissipation at $T_{amb} = 25\text{ }^\circ\text{C}$ ; with 10 mm tie-points; Fig. 5	$P_{tot}$	max.	2,5 W
Non-repetitive peak reverse power dissipation $T_j = 25\text{ }^\circ\text{C}$ prior to surge; $t_p = 1\text{ ms}$ (exponential pulse)	$P_{RSM}$	max.	700 W
Storage temperature	$T_{stg}$		-55 to + 150 $^\circ\text{C}$
Junction temperature	$T_j$	max.	150 $^\circ\text{C}$

## THERMAL RESISTANCE

From junction to ambient in free air see Figs 4 and 5

## CHARACTERISTICS

Forward voltage $I_F = 1\text{ A}$ ; $T_{amb} = 25\text{ }^\circ\text{C}$	$V_F$	<	1,5 V
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**OPERATION AS A VOLTAGE REGULATOR** (see page 4)

Dissipation and heatsink considerations

## a. Steady-state conditions

The maximum permissible steady-state dissipation  $P_{s \max}$  is given by the relationship

$$P_{s \max} = \frac{T_{j \max} - T_{\text{amb}}}{R_{\text{th } j-a}}$$

where:  $T_{j \max}$  is the maximum permissible operating junction temperature $T_{\text{amb}}$  is the ambient temperature $R_{\text{th } j-a}$  is the total thermal resistance from junction to ambient

## b. Pulse conditions (see Fig. 2)

The maximum permissible pulse power  $P_{p \max}$  is given by the formula

$$P_{p \max} = \frac{(T_{j \max} - T_{\text{amb}}) - (P_s \cdot R_{\text{th } j-a})}{R_{\text{th } t}}$$

where:  $P_s$  is any steady-state dissipation excluding that in pulses $R_{\text{th } t}$  is the effective transient thermal resistance of the device between junction and ambient.It is a function of the pulse duration  $t_p$  and duty factor  $\delta$ . $\delta$  is the duty factor ( $t_p/T$ )

The steady-state power  $P_s$  when biased in the zener direction at a given zener current can be found from Fig. 3. With the additional pulse power dissipation  $P_{p \max}$  calculated from the above expression, the total peak zener power dissipation  $P_{\text{tot}} = P_{\text{ZRM}} = P_s + P_p$ . From Fig. 3 the corresponding maximum repetitive peak zener current at  $P_{\text{tot}}$  can now be read. This repetitive peak zener current is subject to the absolute maximum rating. For pulse durations longer than the temperature stabilization time of the diode  $t_{\text{stab}}$ , the maximum permissible repetitive peak dissipation  $P_{\text{ZRM}}$  is equal to the steady-state power  $P_s$ . The temperature stabilization time for the BZX70 is 100 seconds (see Figs 17 and 18).

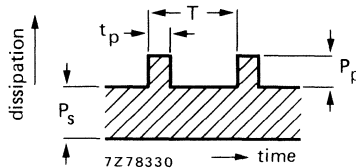


Fig. 2.

**NOTES WHEN OPERATING AS A TRANSIENT SUPPRESSOR** (see page 5)

1. Recommended stand-off voltage is defined as being the maximum reverse voltage to be applied without causing conduction in the avalanche mode or significant reverse dissipation.
2. Maximum clamping voltage is the maximum reverse avalanche breakdown voltage which will appear across the diode at the specified pulse duration and junction temperature. For square pulses see Figs 19 and 20, for exponential pulses see Figs 21 and 22.
3. Duration of an exponential pulse is defined as the time taken for the pulse to fall to 37% of its initial value. It is assumed that energy content does not continue beyond twice this time.

# BZX70 SERIES

CHARACTERISTICS – WHEN USED AS VOLTAGE REGULATOR DIODES;  $T_{amb} = 25\text{ }^{\circ}\text{C}$

BZX70-...	working voltage * $V_Z$ V		differential resistance * $r_Z$ $\Omega$		temperature coefficient * $S_Z$ mV/ $^{\circ}\text{C}$	test $I_Z$ A	reverse current <sup>at</sup> $I_R$ $\mu\text{A}$	reverse voltage $V_R$ V
	min.	max.	typ.	max.	typ.		max.	
C7V5	7.0	7.9	0.45	3.5	3.0	50	50	2.0
C8V2	7.7	8.7	0.45	3.5	4.0	50	20	5.6
C9V1	8.5	9.6	0.55	4.0	5.5	50	10	6.2
C10	9.4	10.6	0.75	4.0	7.0	50	10	6.8
C11	10.4	11.6	0.8	4.5	7.5	50	10	7.5
C12	11.4	12.7	0.85	5.0	8.0	50	10	8.2
C13	12.4	14.1	0.9	6.0	8.5	50	10	9.1
C15	13.8	15.6	1.0	8.0	10	50	10	10
C16	15.3	17.1	2.4	9.0	11	20	10	11
C18	16.8	19.1	2.5	11	12	20	10	12
C20	18.8	21.2	2.8	12	14	20	10	13
C22	20.8	23.3	3.0	13	16	20	10	15
C24	22.7	25.9	3.4	14	18	20	10	16
C27	25.1	28.9	3.8	18	20	20	10	18
C30	28	32	4.5	22	25	20	10	20
C33	31	35	5.0	25	30	20	10	22
C36	34	38	5.5	30	32	20	10	24
C39	37	41	12	35	35	10	10	27
C43	40	46	13	40	40	10	10	30
C47	44	50	14	50	45	10	10	33
C51	48	54	15	55	50	10	10	36
C56	52	60	17	63	55	10	10	39
C62	58	66	18	75	60	10	10	43
C68	64	72	18	90	65	10	10	47
C75	70	79	20	100	70	10	10	51

\*At test  $I_Z$ ; measured using a pulse method with  $t_p \leq 100\text{ }\mu\text{s}$  and  $\delta \leq 0.001$  so that the values correspond to a  $T_j$  of approximately  $25\text{ }^{\circ}\text{C}$ .

CHARACTERISTICS — WHEN USED AS TRANSIENT SUPPRESSOR DIODES;  $T_{amb} = 25\text{ }^{\circ}\text{C}$ 

clamping voltage at $t_p = 500\text{ }\mu\text{s}$ exp. pulse $V_{(CL)R}$ V		non-repetitive peak reverse current $I_{RSM}$ A	reverse current at recommended stand-off voltage $I_R$ mA		BZX70-...
typ.	max.		max.	$V_R$ V	
9	10	20	0.5	5.6	C7V5
10	11.2	20	0.5	6.2	C8V2
11	12.5	20	0.5	6.8	C9V1
12	14	20	0.1	7.5	C10
13.5	15.5	20	0.1	8.2	C11
15	17.5	20	0.1	9.1	C12
17	19	20	0.1	10	C13
19	21	20	0.1	11	C15
21	23	20	0.1	12	C16
23	26	20	0.1	13	C18
22	26	10	0.1	15	C20
25	29	10	0.1	16	C22
28	33	10	0.1	18	C24
32	38	10	0.1	20	C27
36	43	10	0.1	22	C30
41	48	10	0.1	24	C33
47	54	10	0.1	27	C36
44	52	5	0.1	30	C39
49	58	5	0.1	33	C43
56	65	5	0.1	36	C47
63	72	5	0.1	39	C51
71	82	5	0.1	43	C56
80	93	5	0.1	47	C62
89	104	5	0.1	51	C68
98	116	5	0.1	56	C75

### SOLDERING AND MOUNTING INSTRUCTIONS

1. When using a soldering iron, diodes may be soldered directly into the circuit, but heat conducted to the junction should be kept to a minimum.
2. Diodes may be dip-soldered at a solder temperature of 245 °C for a maximum soldering time of 5 seconds. The case temperature during dip-soldering must not at any time exceed the maximum storage temperature. These recommendations apply to a diode with the anode end mounted flush on a printed-circuit board having punched-through holes. For mounting the anode end onto a printed-circuit board, the diode must be spaced at least 5 mm from the underside of the printed-circuit board having punched-through holes, or 5 mm from the top of the printed circuit board having plated-through holes.
3. Care should be taken not to bend the leads nearer than 1,5 mm from the seal; exert no axial pull when bending.

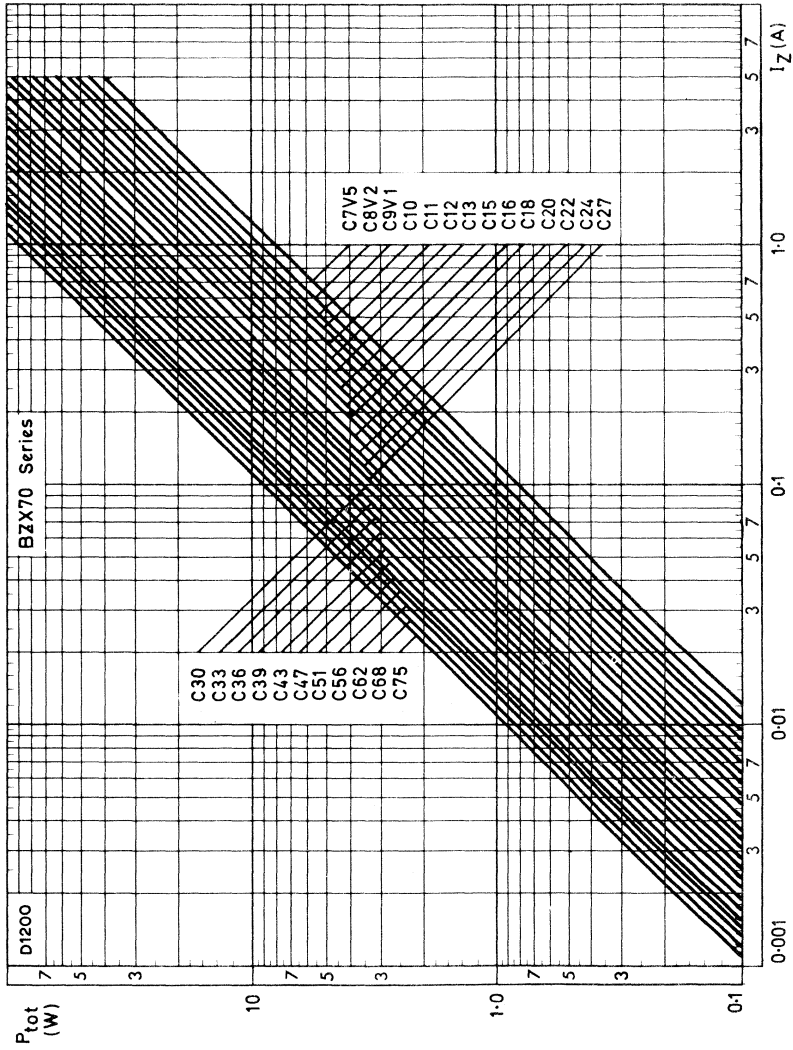


Fig. 3 Maximum permissible repetitive peak dissipation ( $P_{tot} = P_{ZRM}$ ).

# BZX70 SERIES

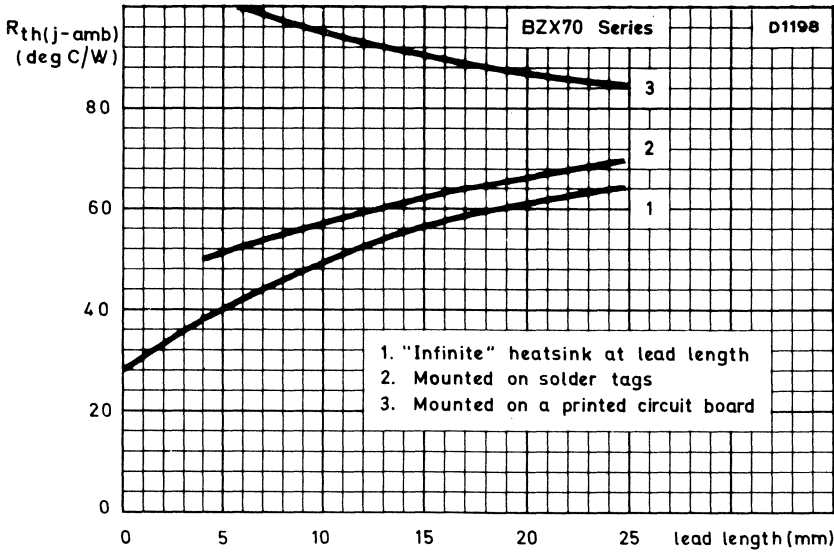


Fig. 4 Thermal resistance as a function of lead length under various mounting conditions.

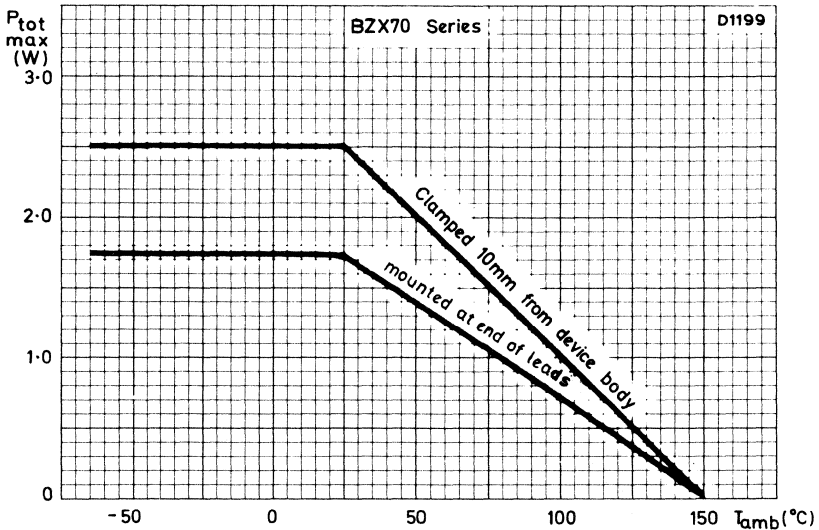


Fig. 5 Maximum permissible power dissipation; the top curve is for mounting method 1 from Fig. 4 at 10 mm lead length.

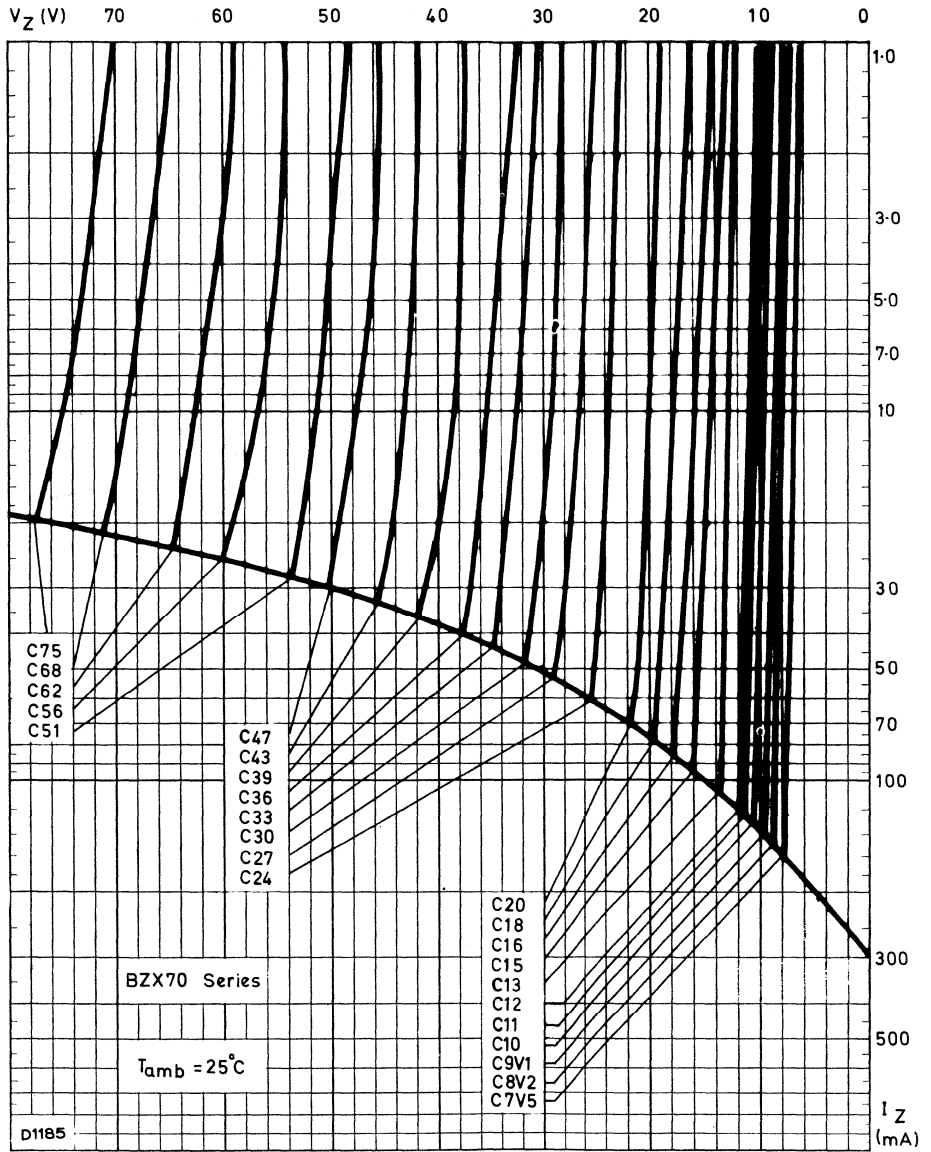


Fig. 6 Typical static zener characteristics.

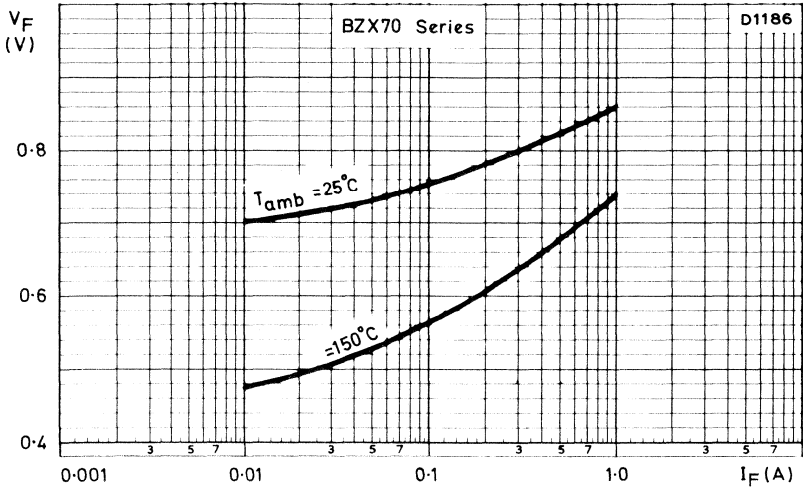


Fig. 7.

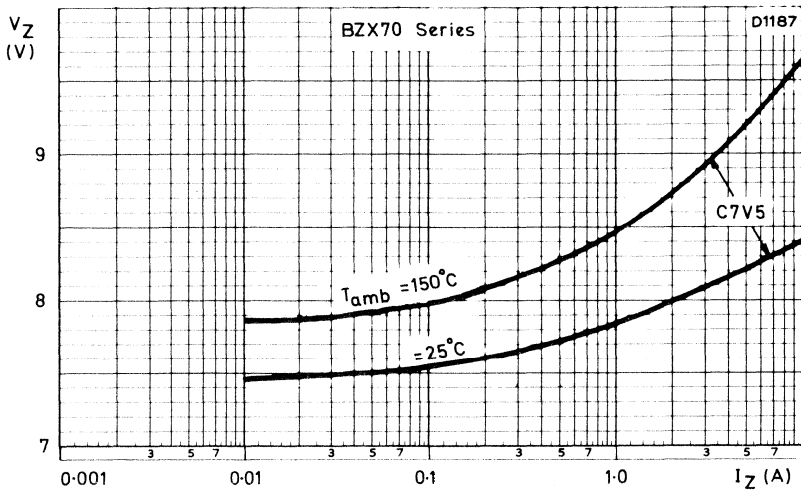


Fig. 8 Typical dynamic zener characteristics for BZX70-C7V5.



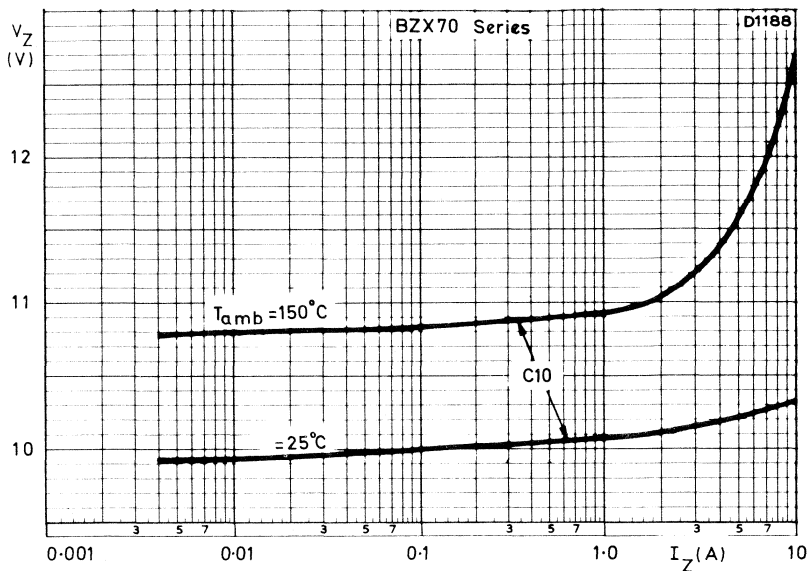


Fig. 9 Typical dynamic zener characteristics for BZX70-C10.

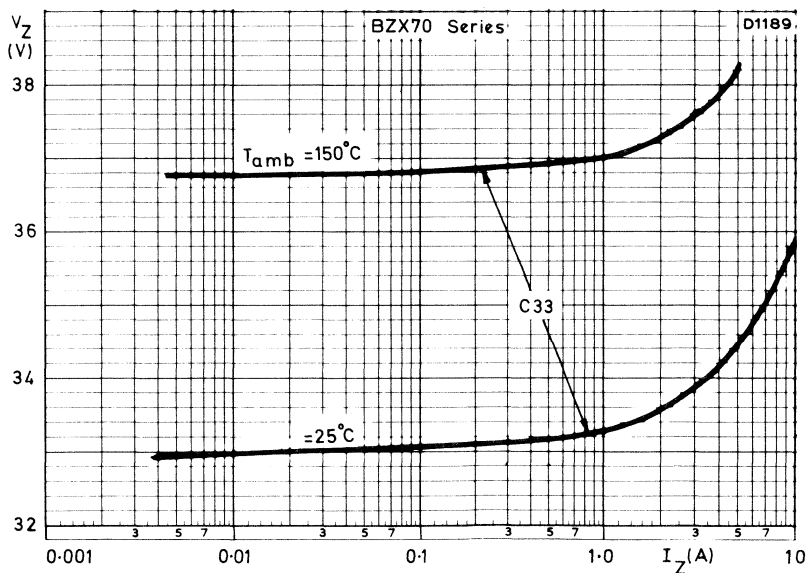


Fig. 10 Typical dynamic zener characteristics for BZX70-C33.

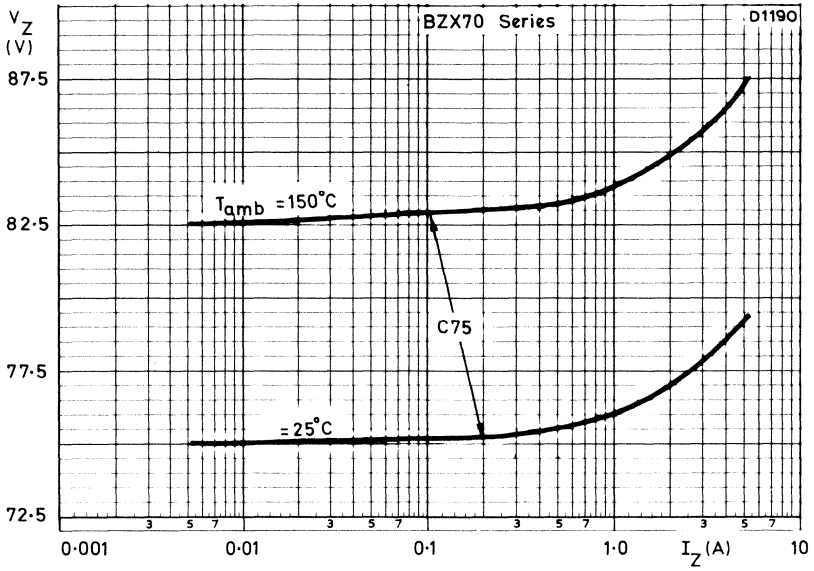


Fig. 11 Typical dynamic zener characteristics for BZX70-C75.

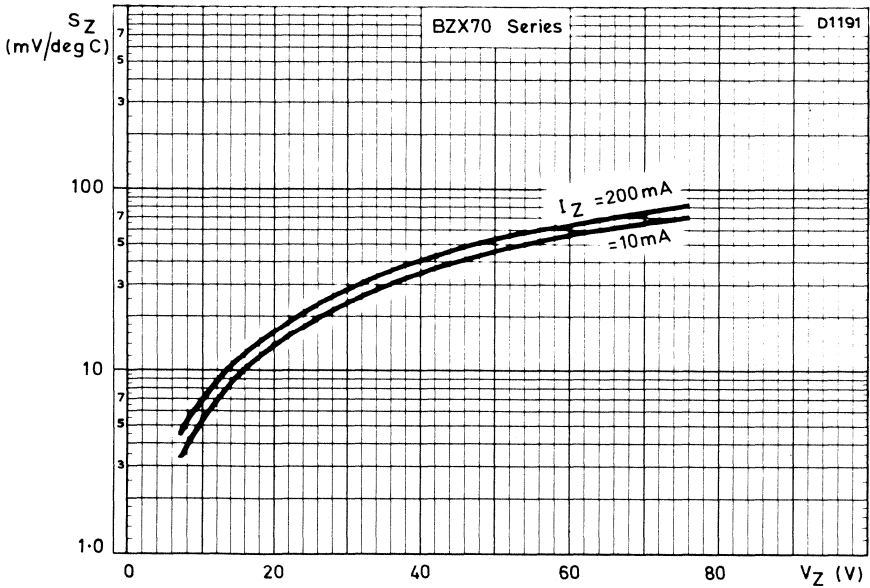


Fig. 12.

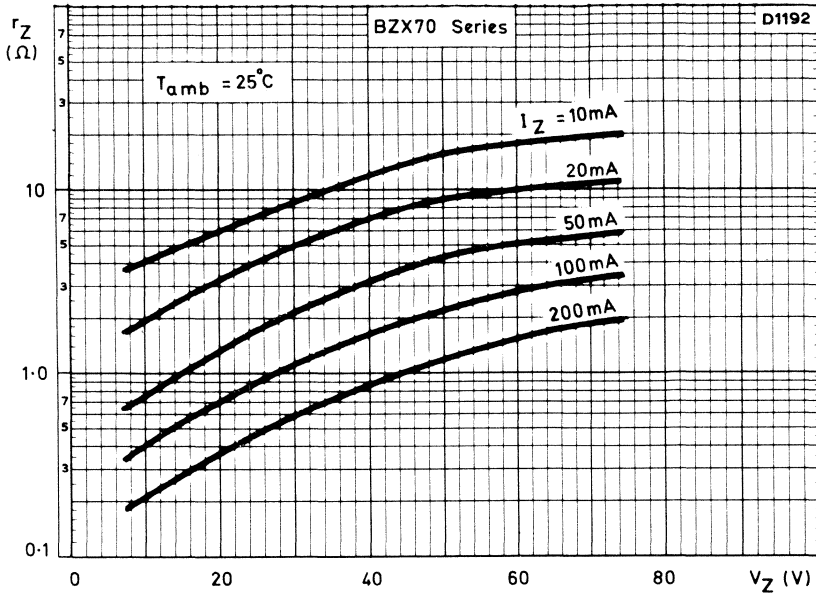


Fig. 13.

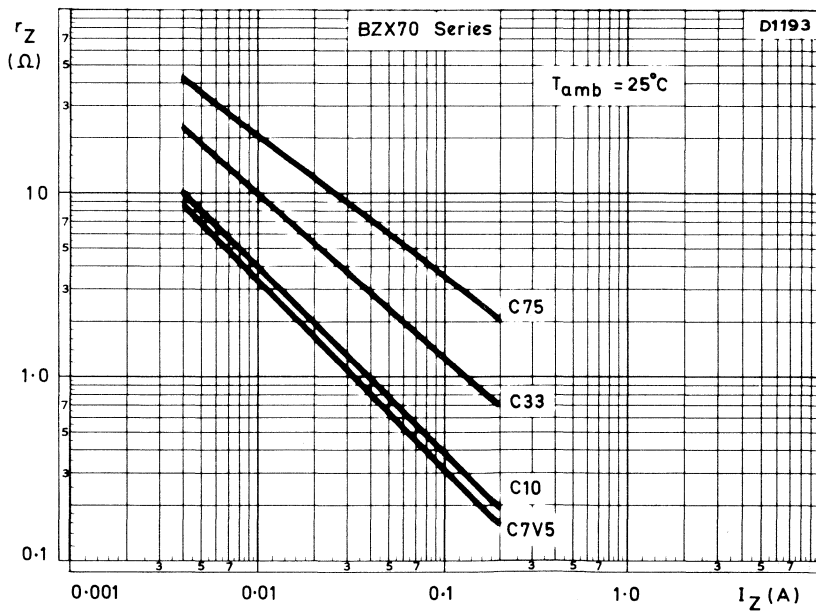


Fig. 14.

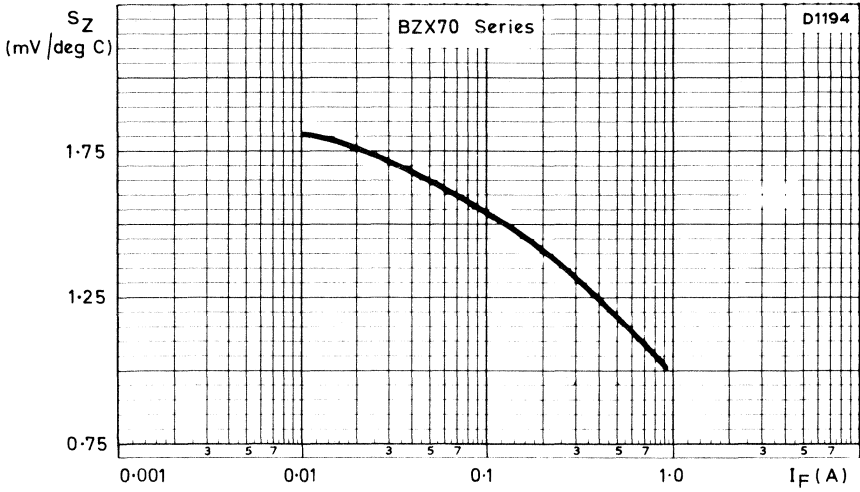


Fig. 15 Typical values.

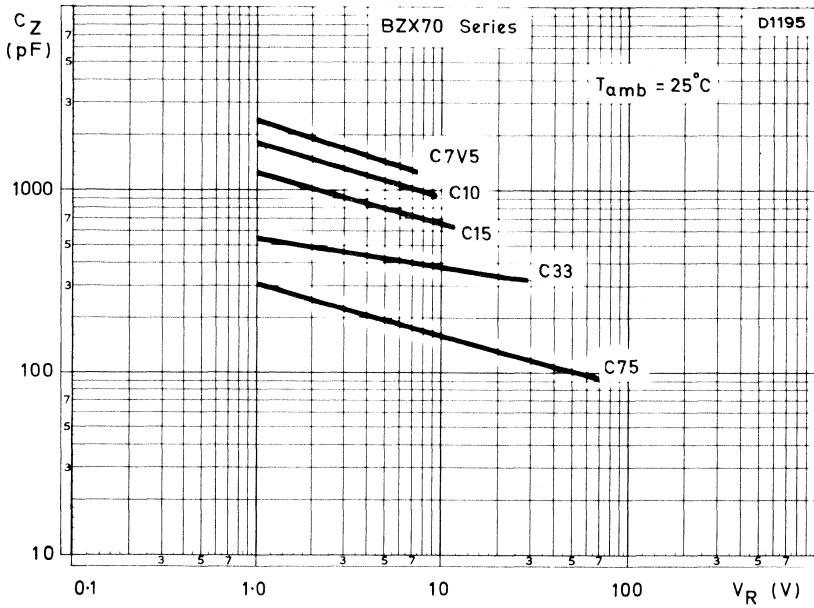


Fig. 16 Typical values.

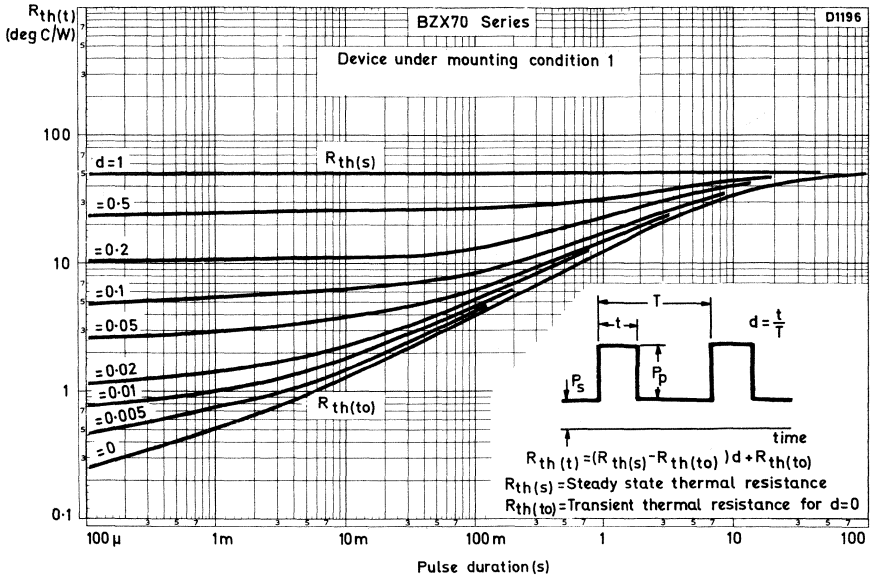


Fig. 17 Device under mounting condition 1 (infinite heatsink); see Fig. 4.

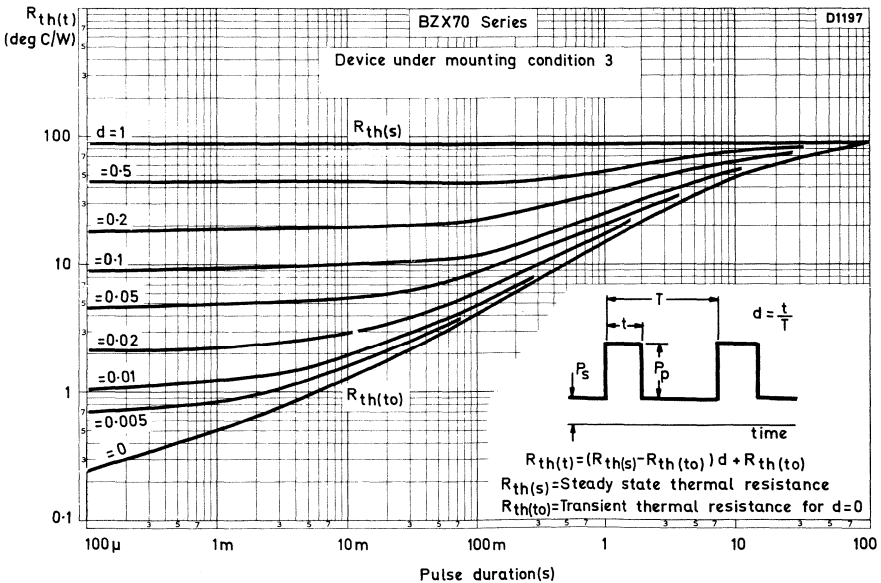


Fig. 18 Device under mounting method 3 (mounted on a printed-circuit board); see Fig. 4.

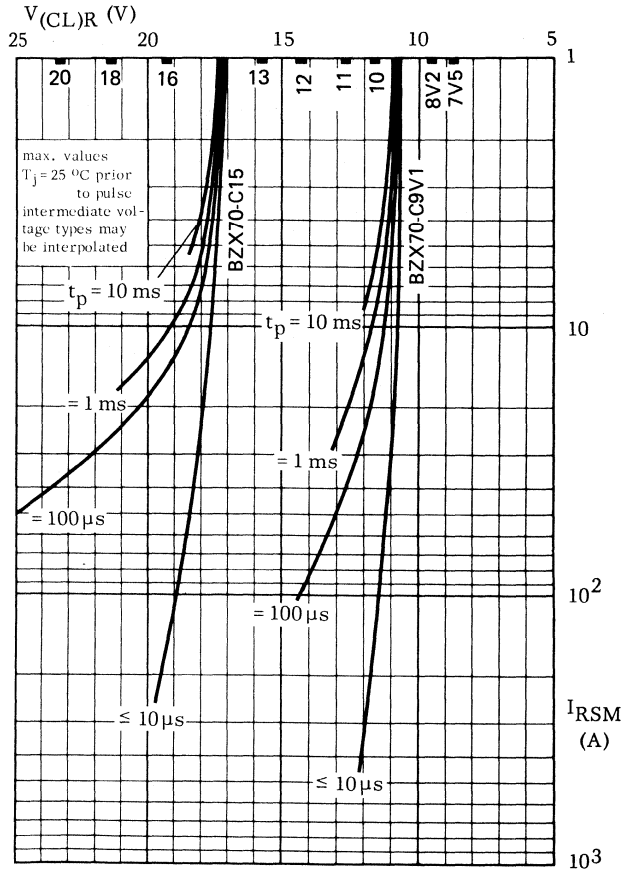


Fig. 19 Square pulses.

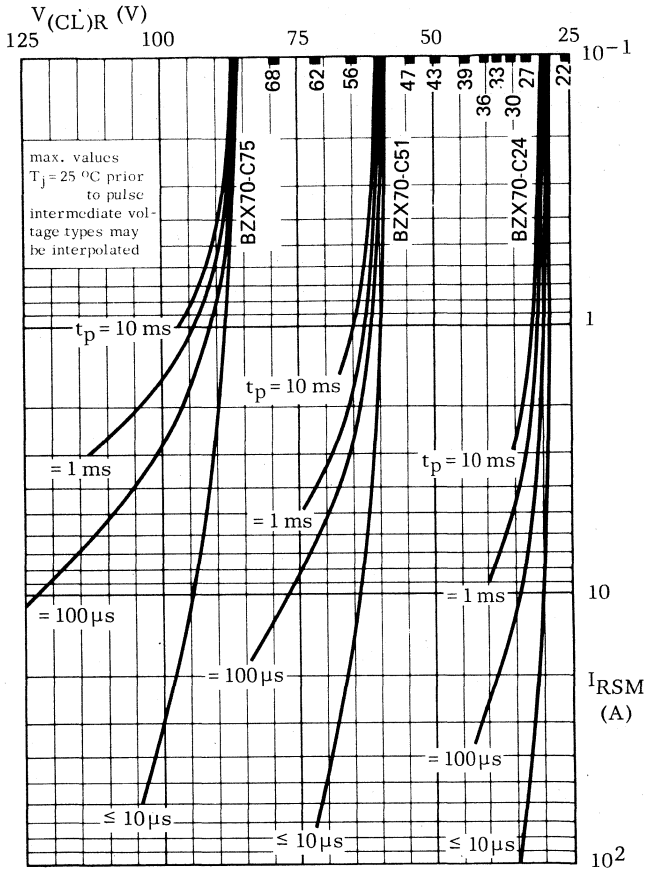


Fig. 20 Square pulses.

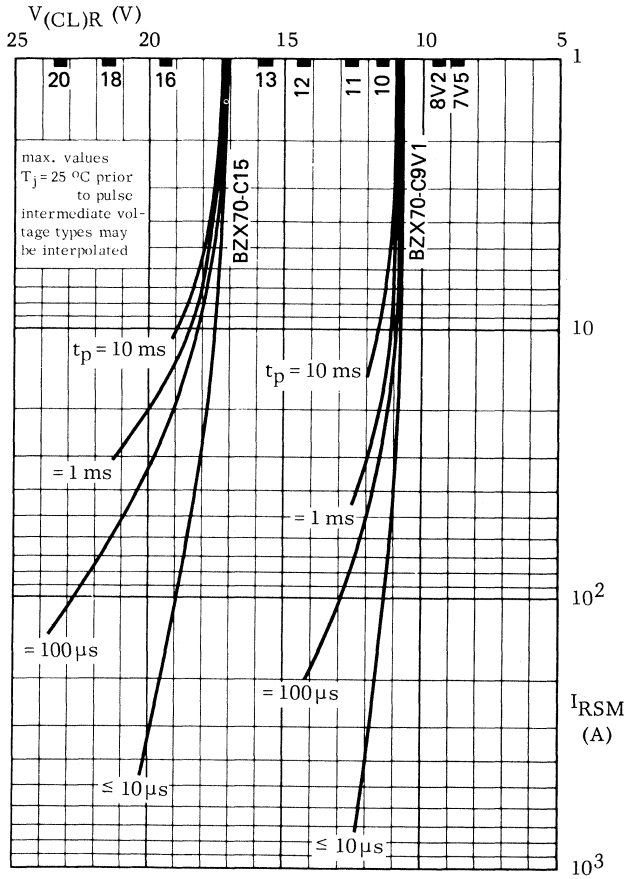


Fig. 21 Exponential pulses.



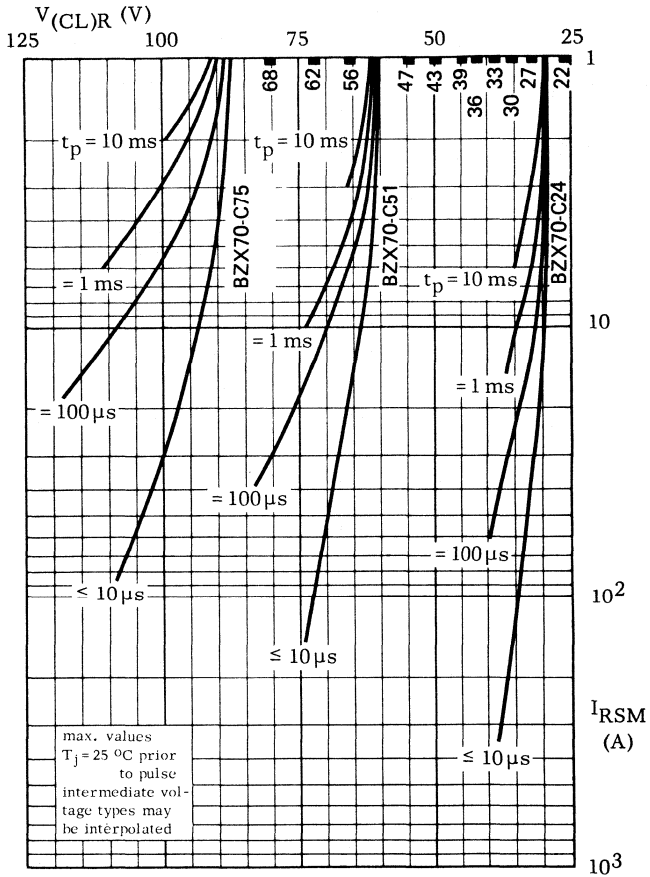


Fig. 22 Exponential pulses.

# BZX70 SERIES

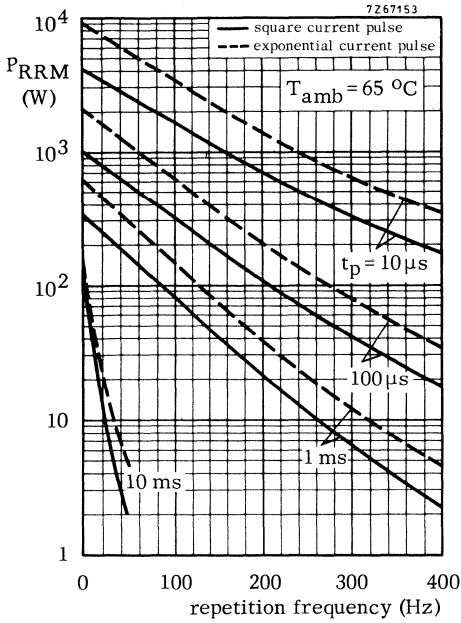


Fig. 23.

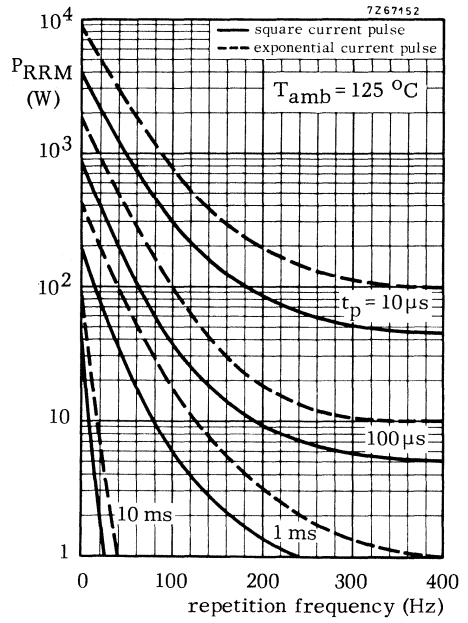


Fig. 24.

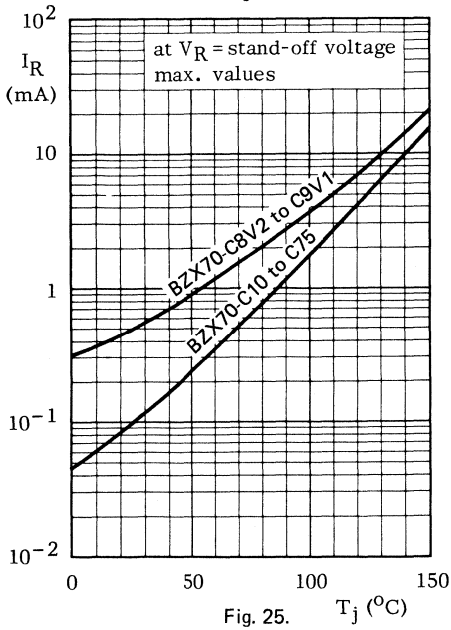


Fig. 25.

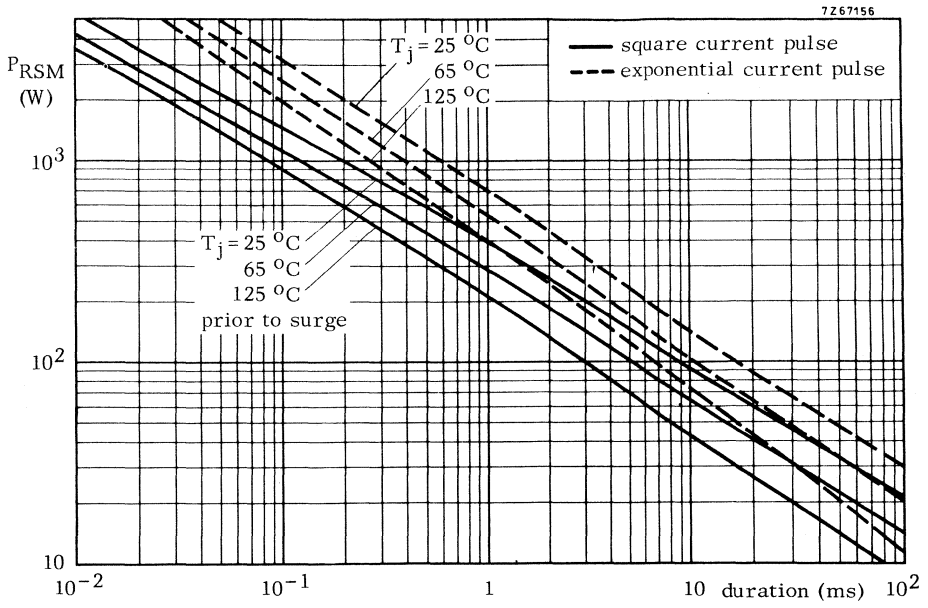


Fig. 26.



## REGULATOR DIODES

Also available to BS9305—F052

A range of diffused silicon diodes in DO-5 metal envelopes, intended for use as voltage regulator and transient suppressor diodes in power stabilization and transient suppression circuits.

The series consists of the following types:

Normal polarity (cathode to stud): BZY91-C7V5 to BZY91-C75.

Reverse polarity (anode to stud): BZY91-C7V5R to BZY91-C75R.

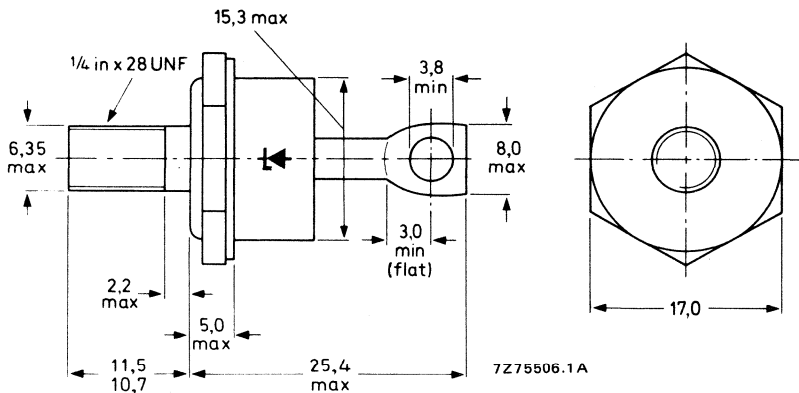
### QUICK REFERENCE DATA

		voltage regulator		transient suppressor	
Working voltage (5% range)	$V_Z$ nom.	7,5 to 75	—	V	
Stand-off voltage	$V_R$	—	5,6 to 56	V	
Total power dissipation	$P_{tot}$ max.	100	—	W	
Non-repetitive peak reverse power dissipation	$P_{RSM}$ max.	—	9,5	kW	

### MECHANICAL DATA

Dimensions in mm

Fig. 1 DO-5.



Net mass: 22 g

Diameter of clearance hole: max. 6,5 mm

Accessories supplied on request: 56264A  
(mica washer, insulating ring, tag)

Supplied with device: 1 nut, 1 lock washer  
Nut dimensions across the flats: 11,1 mm

Torque on nut: min. 1,7 Nm (17 kg cm)  
max. 3,5 Nm (35 kg cm)

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

Peak working current	$I_{ZM}$	max.	400 A
Average forward current (averaged over any 20 ms period)	$I_{F(AV)}$	max.	20 A
Non-repetitive peak reverse current $T_j = 25\text{ }^\circ\text{C}$ prior to surge; $t_p = 1\text{ ms}$ (exponential pulse); BZY91-C7V5(R) to BZY91-C75(R)	$I_{RSM}$	max.	1000 to 85 A
Total power dissipation up to $T_{mb} = 25\text{ }^\circ\text{C}$ at $T_{mb} = 65\text{ }^\circ\text{C}$	$P_{tot}$	max.	100 W
	$P_{tot}$	max.	75 W
Non-repetitive peak reverse power dissipation $T_j = 25\text{ }^\circ\text{C}$ prior to surge; $t_p = 1\text{ ms}$ (exponential pulse)	$P_{RSM}$	max.	9,5 kW
Storage temperature	$T_{stg}$		-55 to +175 $^\circ\text{C}$
Junction temperature	$T_j$	max.	175 $^\circ\text{C}$

## THERMAL RESISTANCE

From junction to mounting base	$R_{th\ j-mb}$	=	1,5 $^\circ\text{C/W}$
From mounting base to heatsink	$R_{th\ mb-h}$	=	0,2 $^\circ\text{C/W}$

## CHARACTERISTICS

Forward voltage $I_F = 10\text{ A}$ ; $T_{mb} = 25\text{ }^\circ\text{C}$	$V_F$	<	1,5 V
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## OPERATION AS A VOLTAGE REGULATOR (see page 4)

Dissipation and heatsink considerations

### a. Steady-state conditions

The maximum permissible steady-state dissipation  $P_{s\ max}$  is given by the relationship

$$P_{s\ max} = \frac{T_{j\ max} - T_{amb}}{R_{th\ j-a}}$$

where:  $T_{j\ max}$  is the maximum permissible operating junction temperature

$T_{amb}$  is the ambient temperature

$R_{th\ j-a}$  is the total thermal resistance from junction to ambient

$$R_{th\ j-a} = R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a}$$

$R_{th\ mb-h}$  is the thermal resistance from mounting base to heatsink, that is, 0,2  $^\circ\text{C/W}$ .

$R_{th\ h-a}$  is the thermal resistance of the heatsink.

### b. Pulse conditions (see Fig. 2)

The heating effect of repetitive power pulses can be found from the curves in Figs 5 and 6 which are given for operation as a transient suppressor at 50 Hz and 400 Hz respectively. This value  $\Delta T$  is in addition to the mean heating effect. The value of  $\Delta T$  found from the curves for the particular operating condition should be added to the known value for ambient temperature used in calculating the required heatsink.

The value of the peak power for a given peak zener current is found from the curves in Figs 3 and 4.

The required heatsink is calculated as follows:

$$R_{th\ j-a} = \frac{T_{j\ max} - T_{amb} - \Delta T}{P_s + \delta \cdot P_p}$$

where:  $T_{j\ max} = 175\ ^\circ C$

$T_{amb}$  = ambient temperature

$\Delta T$  = from Fig. 5 or 6

$P_s$  = any steady-state dissipation excluding that in pulses

$P_p$  = peak pulse power

$\delta$  = duty factor ( $t_p/T$ )

$R_{th\ j-a} = R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a} = 1,5 + 0,2 + R_{th\ h-a}\ ^\circ C/W.$

Thus  $R_{th\ h-a}$  can be found.

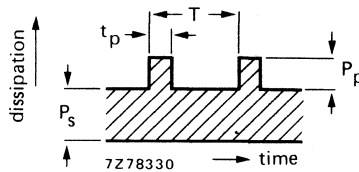


Fig. 2.

### OPERATION AS A TRANSIENT SUPPRESSOR (see page 5)

Heatsink considerations

- For non-repetitive transients, the device may be used without a heatsink for pulses up to 10 ms in duration.
- For repetitive transients which fall within the permitted operating range shown in Figs 26 and 27 the required heatsink is found as follows:

$$R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a} = \frac{T_{j\ max} - T_{amb}}{P_s + \delta \cdot P_{RRM}}$$

where:  $T_{j\ max} = 175\ ^\circ C$

$T_{amb}$  = ambient temperature

$P_s$  = any steady-state dissipation excluding that in pulses

$\delta$  = duty factor ( $t_p/T$ )

$R_{th\ j-mb} = 1,5\ ^\circ C/W$

$R_{th\ mb-h} = 0,2\ ^\circ C/W$

Thus  $R_{th\ h-a}$  can be found.

### Notes

- The stand-off voltage is the maximum reverse voltage recommended for continuous operation; at this value non-conduction is ensured.
- The maximum clamping voltage is the maximum reverse voltage which appears across the diode at the specified pulse duration and junction temperature. For square pulses see Figs 22 and 23, for exponential pulses see Figs 24 and 25.
- Duration of an exponential pulse is defined as the time taken for the pulse to fall to 37% of its initial value. It is assumed that the energy content does not continue beyond twice this time.
- Surge suppressor diodes are extremely fast in clamping, switching on in less than 5 ns.

CHARACTERISTICS – WHEN USED AS VOLTAGE REGULATOR DIODES;  $T_{mb} = 25\text{ }^{\circ}\text{C}$

BZY91-...	working voltage *V <sub>Z</sub> V		differential resistance *r <sub>Z</sub> Ω	temperature coefficient *S <sub>Z</sub> %/°C	test I <sub>Z</sub> A	reverse current I <sub>R</sub> mA	reverse voltage V <sub>R</sub> V
	min.	max.	max.	typ.		max.	
C7V5(R)	7.0	7.9	0.2	0.09	5.0	5.0	2.0
C8V2(R)	7.7	8.7	0.3	0.09	5.0	5.0	5.6
C9V1(R)	8.5	9.6	0.4	0.07	2.0	5.0	6.2
C10(R)	9.4	10.6	0.4	0.07	2.0	1.0	6.8
C11(R)	10.4	11.6	0.4	0.07	2.0	1.0	7.5
C12(R)	11.4	12.7	0.5	0.07	2.0	1.0	8.2
C13(R)	12.4	14.1	0.5	0.07	2.0	1.0	9.1
C15(R)	13.8	15.6	0.6	0.075	2.0	1.0	10
C16(R)	15.3	17.1	0.6	0.075	2.0	1.0	11
C18(R)	16.8	19.1	0.7	0.075	2.0	1.0	12
C20(R)	18.8	21.2	0.8	0.075	1.0	1.0	13
C22(R)	20.8	23.3	0.8	0.075	1.0	1.0	15
C24(R)	22.7	25.9	0.9	0.08	1.0	1.0	16
C27(R)	25.1	28.9	1.0	0.082	1.0	1.0	18
C30(R)	28	32	1.1	0.085	1.0	1.0	20
C33(R)	31	35	1.2	0.088	1.0	1.0	22
C36(R)	34	38	1.3	0.09	1.0	1.0	24
C39(R)	37	41	1.4	0.09	0.5	1.0	27
C43(R)	40	46	1.5	0.092	0.5	1.0	30
C47(R)	44	50	1.7	0.093	0.5	1.0	33
C51(R)	48	54	1.8	0.093	0.5	1.0	36
C56(R)	52	60	2.0	0.094	0.5	1.0	39
C62(R)	58	66	2.2	0.094	0.5	1.0	43
C68(R)	64	72	2.4	0.094	0.5	1.0	47
C75(R)	70	79	2.6	0.095	0.5	1.0	51

\*At test I<sub>Z</sub>; measured using a pulse method with  $t_p \leq 100\text{ }\mu\text{s}$  and  $\delta \leq 0.001$  so that the values correspond to a  $T_j$  of approximately 25 °C.



CHARACTERISTICS — WHEN USED AS TRANSIENT SUPPRESSOR DIODES;  $T_{mb} = 25\text{ }^{\circ}\text{C}$ 

clamping voltage at $t_p = 500\text{ }\mu\text{s}$ exp. pulse $V_{(CL)R}$ V		non-repetitive peak reverse current $I_{RSM}$ A	reverse current at recommended stand-off voltage $I_R$ mA		$V_R$ V	BZY91-...
typ.	max.		max.			
—	—	—	—	—	—	C7V5(R)
9.5	10.5	150	20	6.2		C8V2(R)
10	11	150	20	6.8		C9V1(R)
11	12.5	150	5	7.5		C10(R)
12	13.5	150	5	8.2		C11(R)
13	15	150	5	9.1		C12(R)
14.5	17	150	5	10		C13(R)
16	19	150	5	11		C15(R)
17.5	22	150	5	12		C16(R)
19	26	150	5	13		C18(R)
22	28	100	5	15		C20(R)
24	31	100	5	16		C22(R)
26	34	100	5	18		C24(R)
28	37	100	5	20		C27(R)
31	40	100	5	22		C30(R)
34	44	100	5	24		C33(R)
38	48	100	5	27		C36(R)
40	52	50	5	30		C39(R)
44	56	50	10	33		C43(R)
49	61	50	10	36		C47(R)
54	66	50	10	39		C51(R)
60	72	50	10	43		C56(R)
66	79	50	10	47		C62(R)
72	87	50	10	51		C68(R)
79	97	50	10	56		C75(R)

**MOUNTING INSTRUCTIONS**

The top connector should neither be bent nor twisted; it should be soldered into the circuit so that there is no strain on it.

During soldering the heat conduction to the junction should be kept to a minimum.

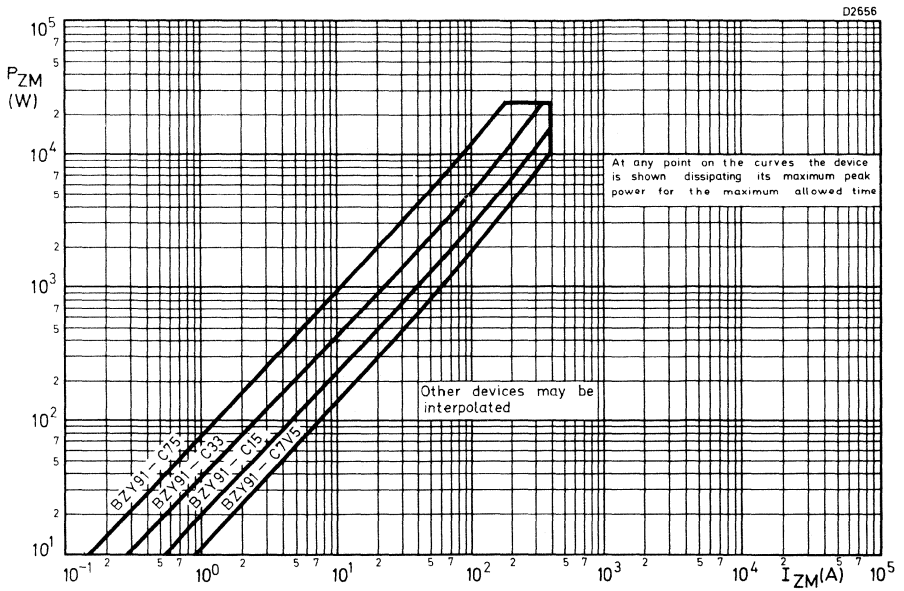


Fig. 3.

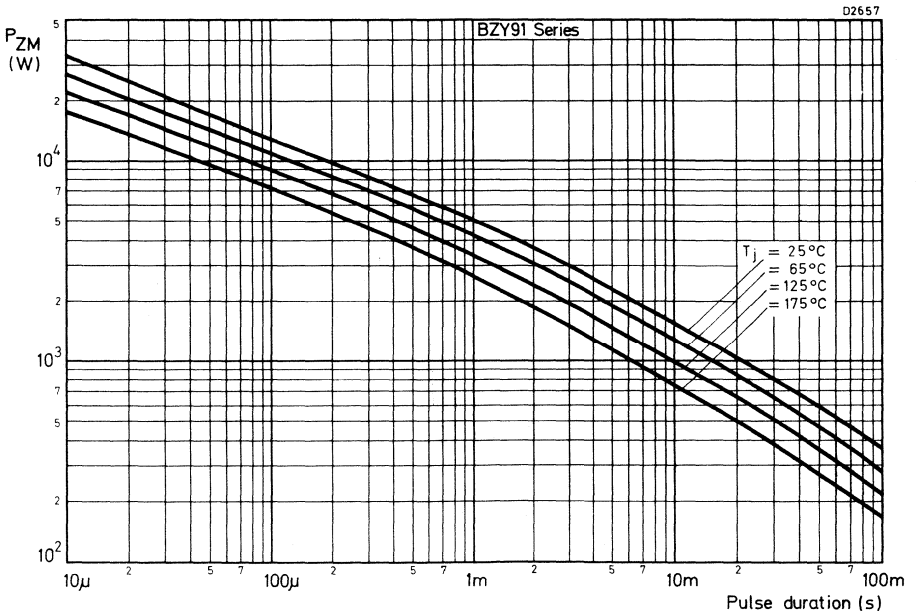


Fig. 4.

# BZY91 SERIES

D2658

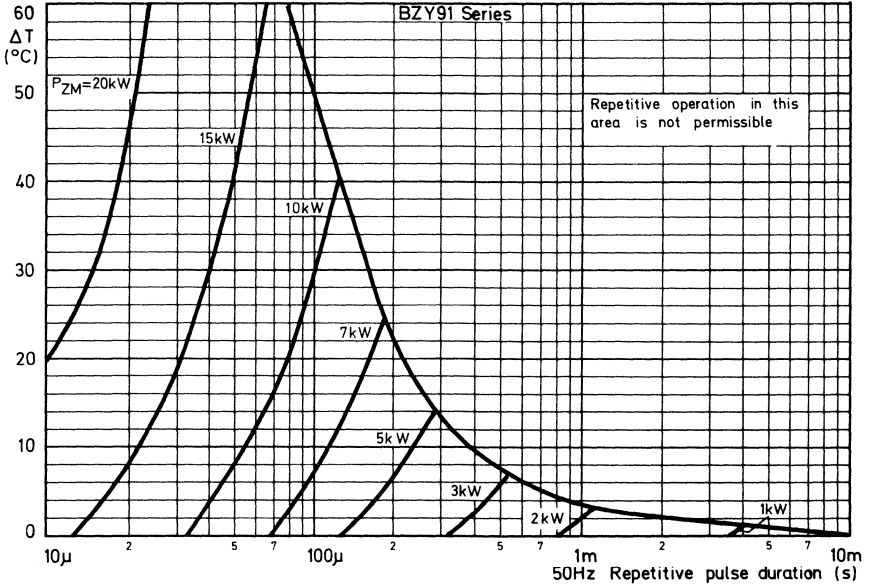


Fig. 5.

D2659

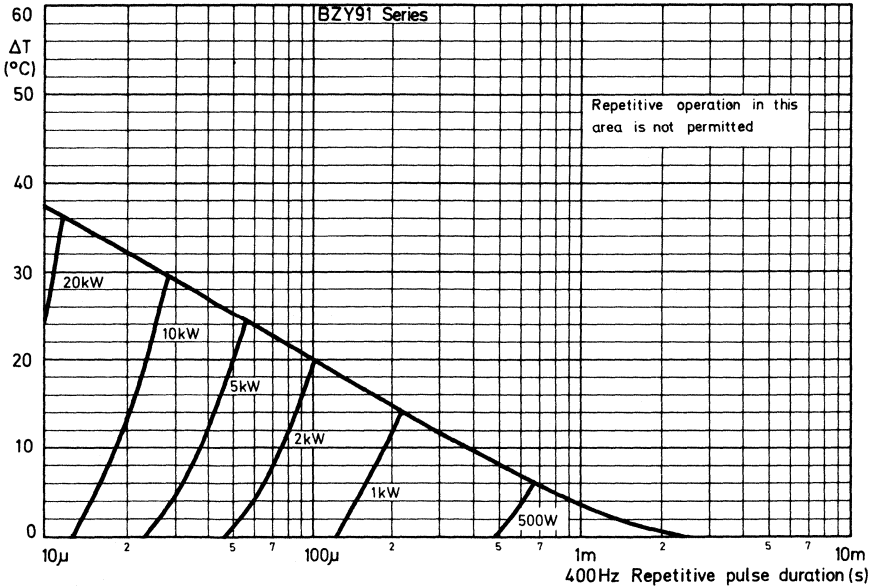


Fig. 6.

D2655

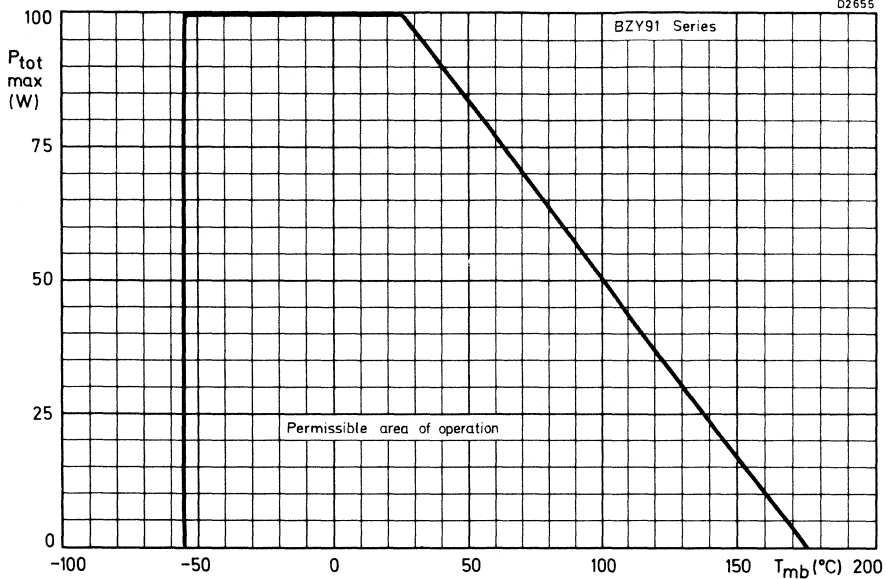


Fig. 7.

D2660

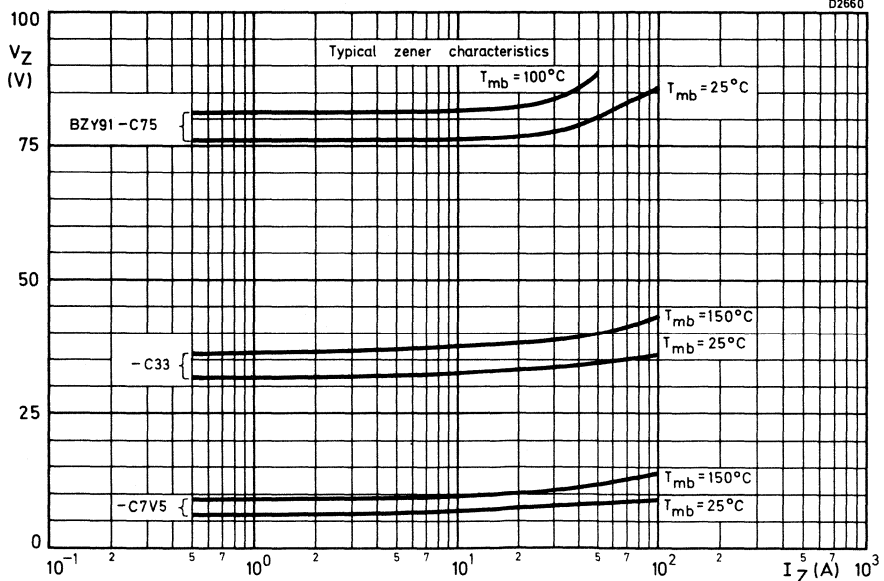


Fig. 8 Typical dynamic zener characteristics.

# BZY91 SERIES

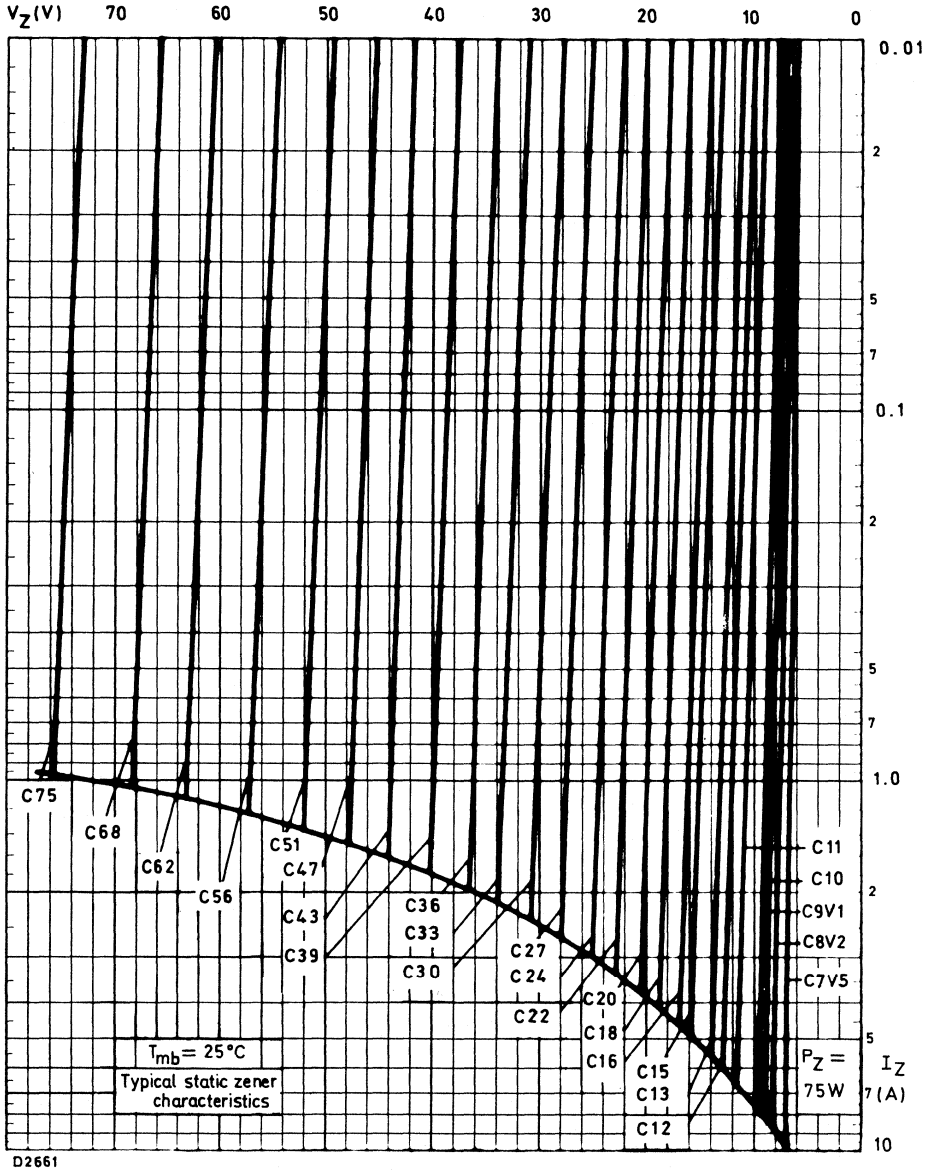


Fig. 9 Typical static zener characteristics.

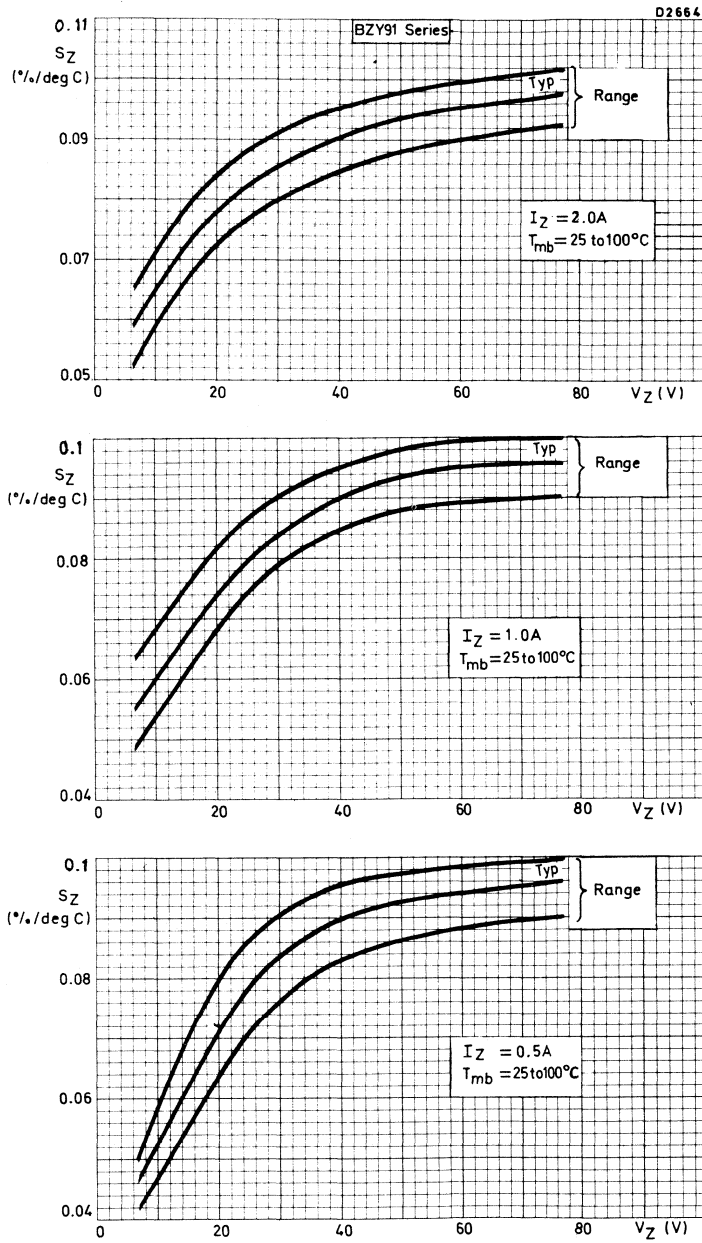
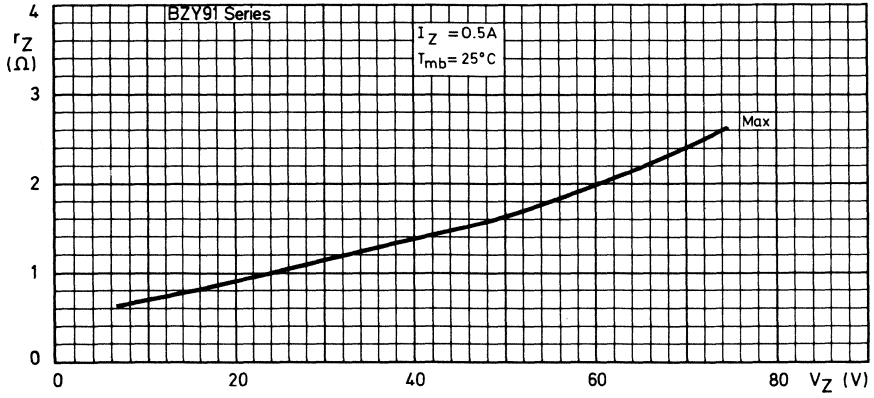


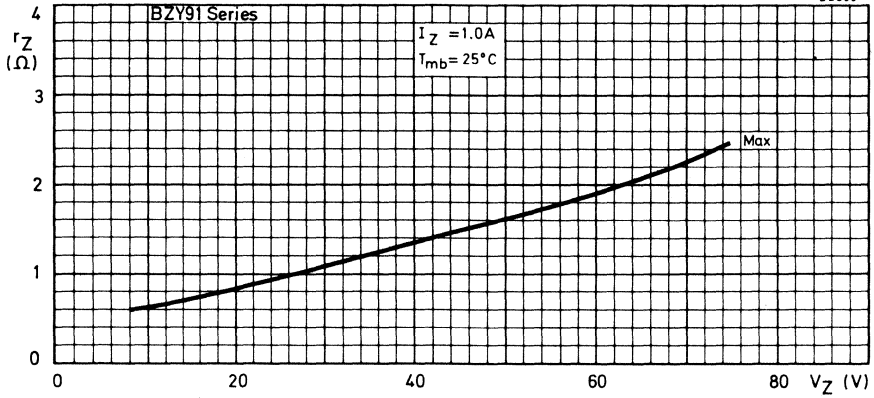
Fig. 10.

# BZY91 SERIES

D2665



D2666



D2667

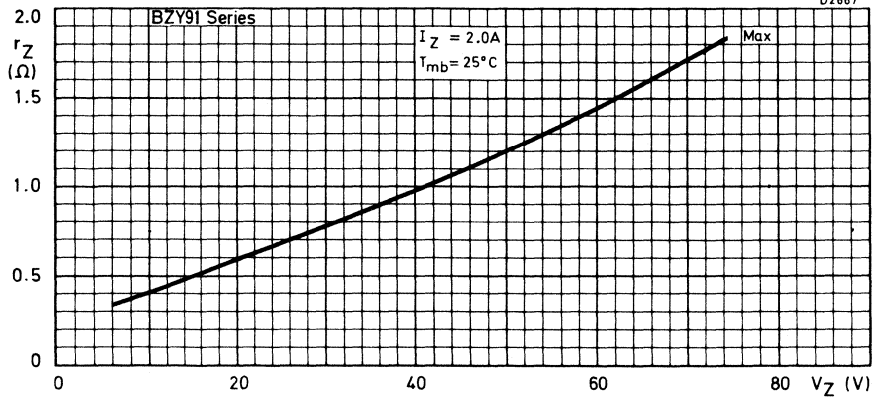


Fig. 11.



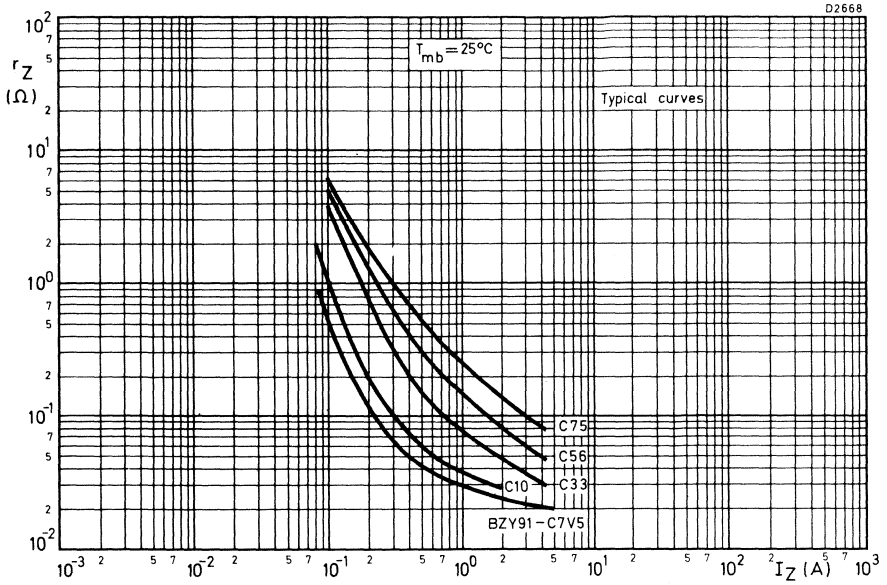


Fig. 12.

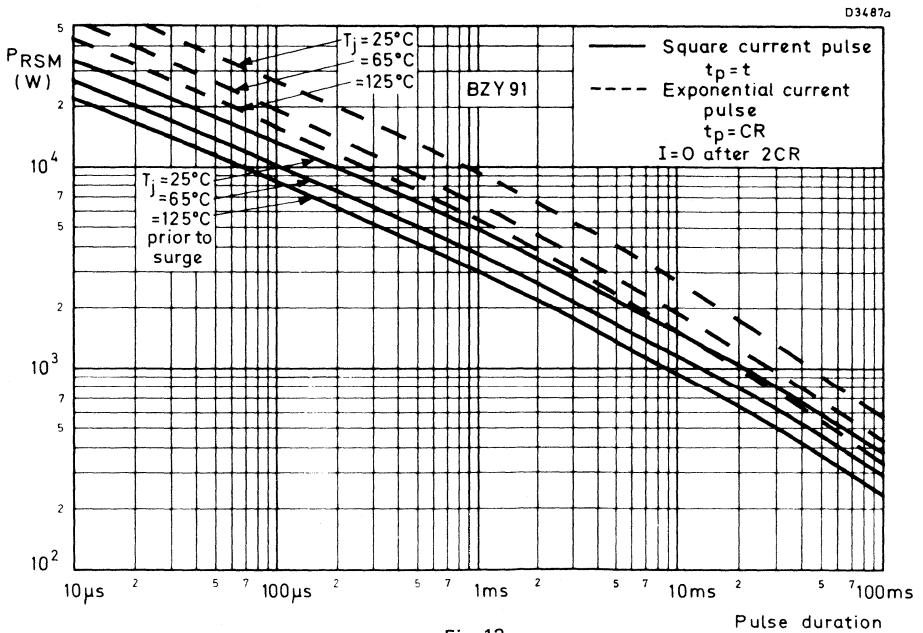


Fig. 13.

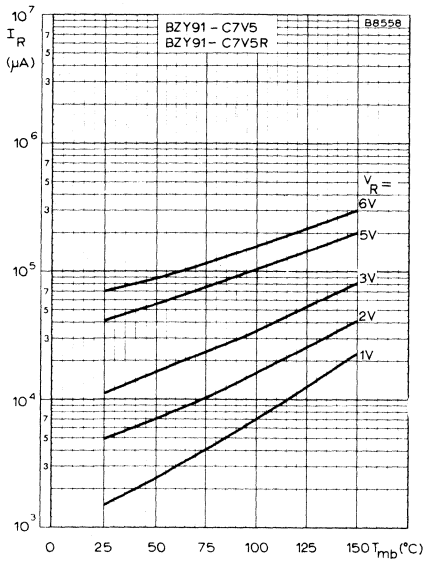


Fig. 14.

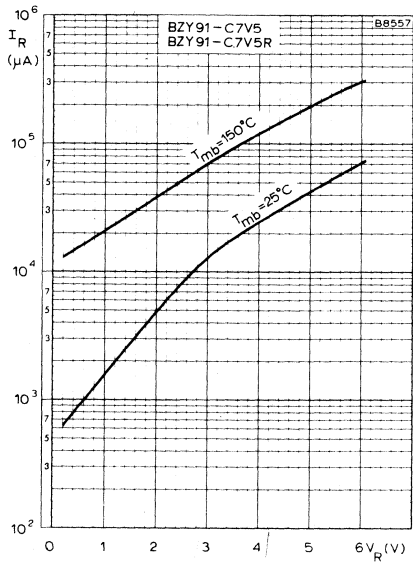


Fig. 15.

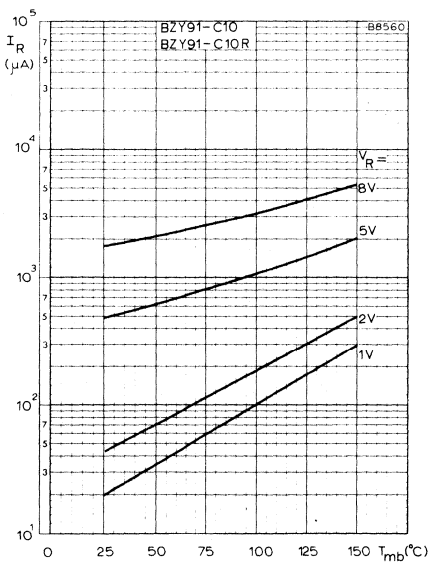


Fig. 16.

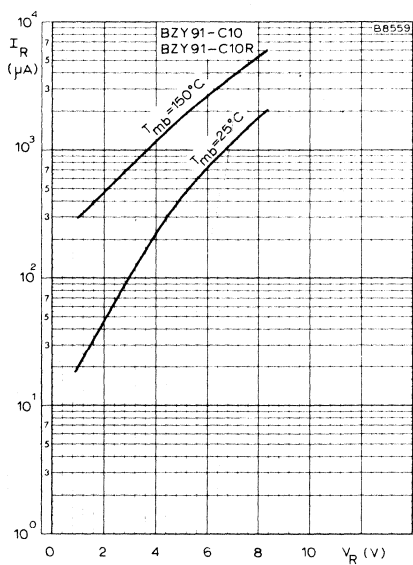


Fig. 17.

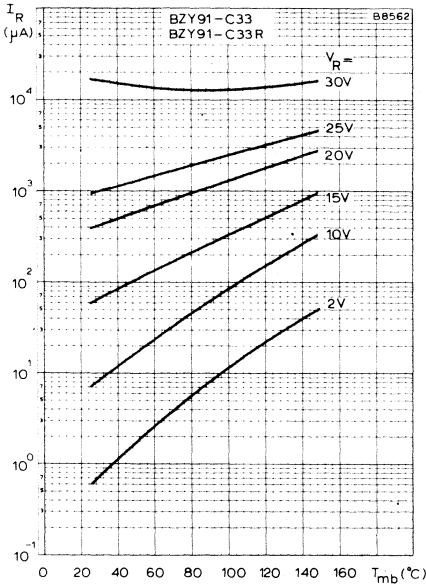


Fig. 18.

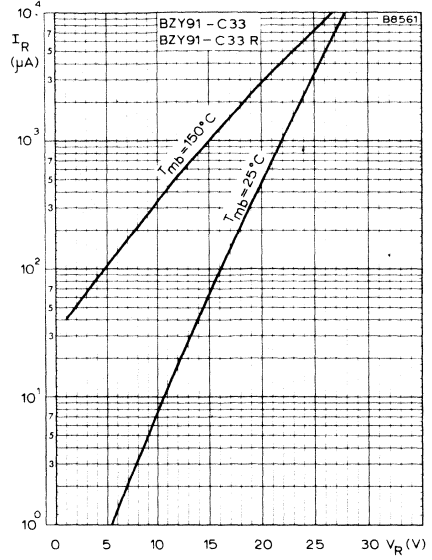


Fig. 19.

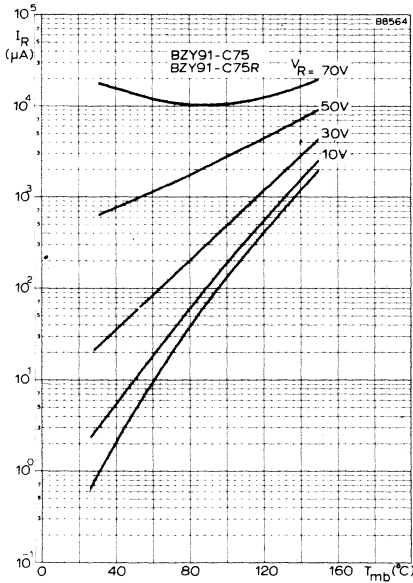


Fig. 20.

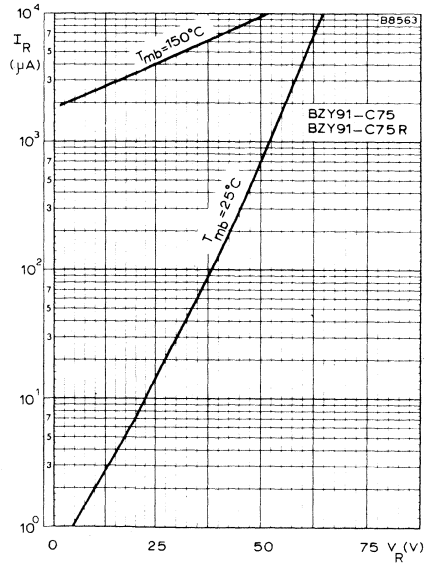
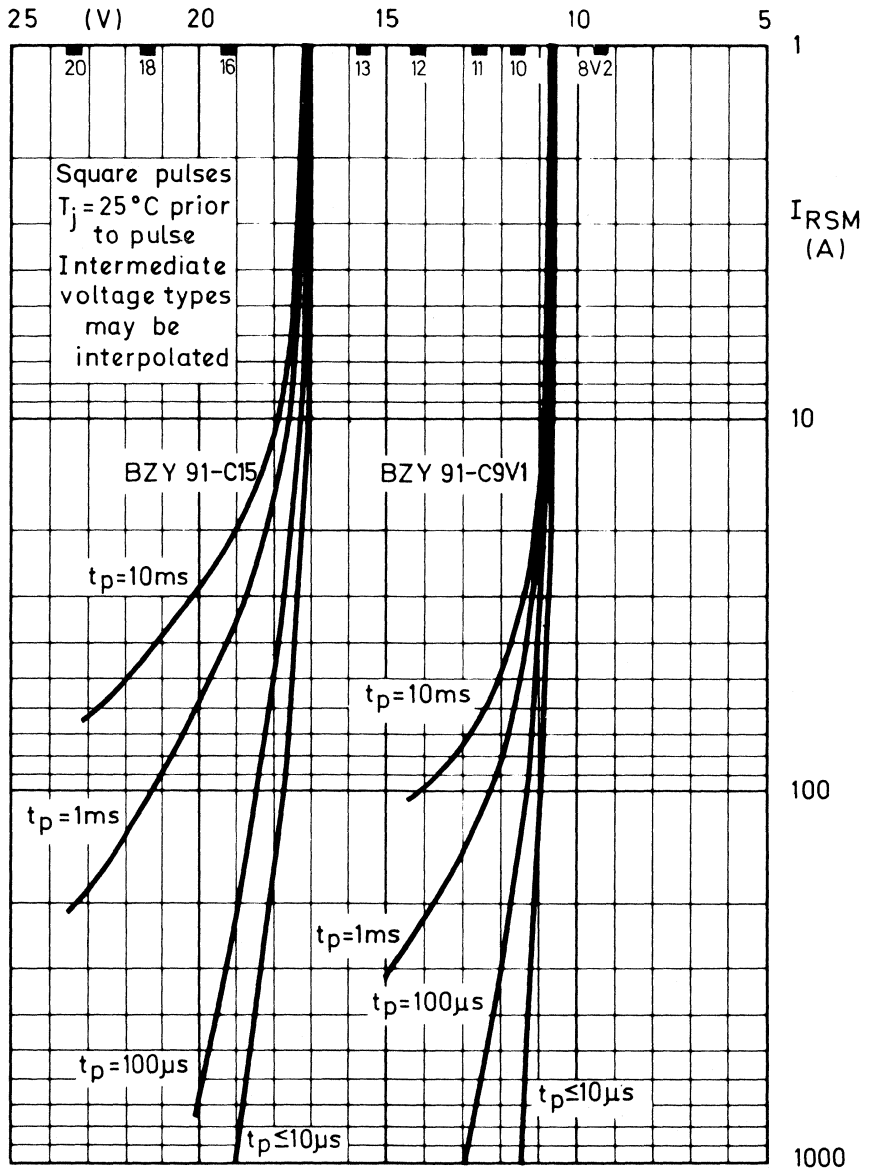


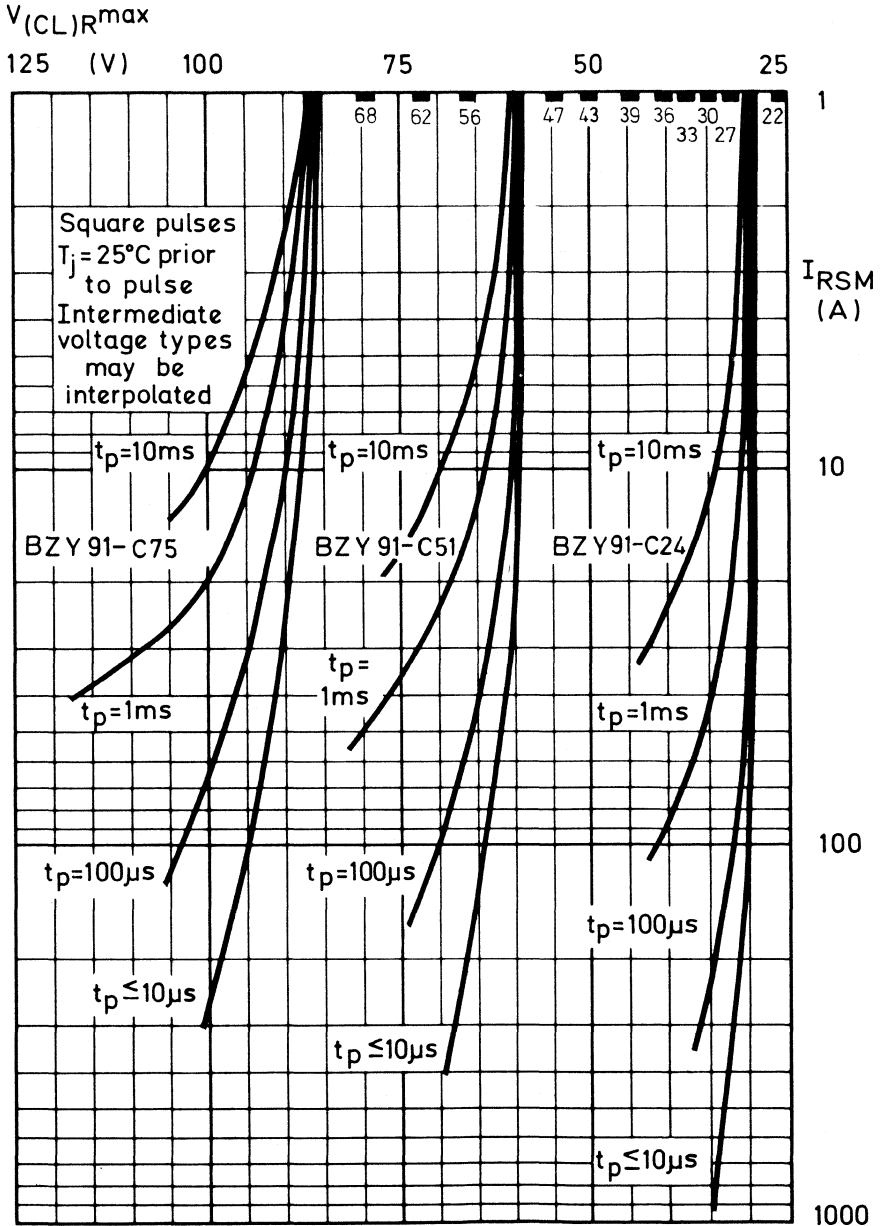
Fig. 21.

$V_{(CL)R}^{max}$



D8027

Fig. 22.



D8028

Fig. 23.

# BZY91 SERIES

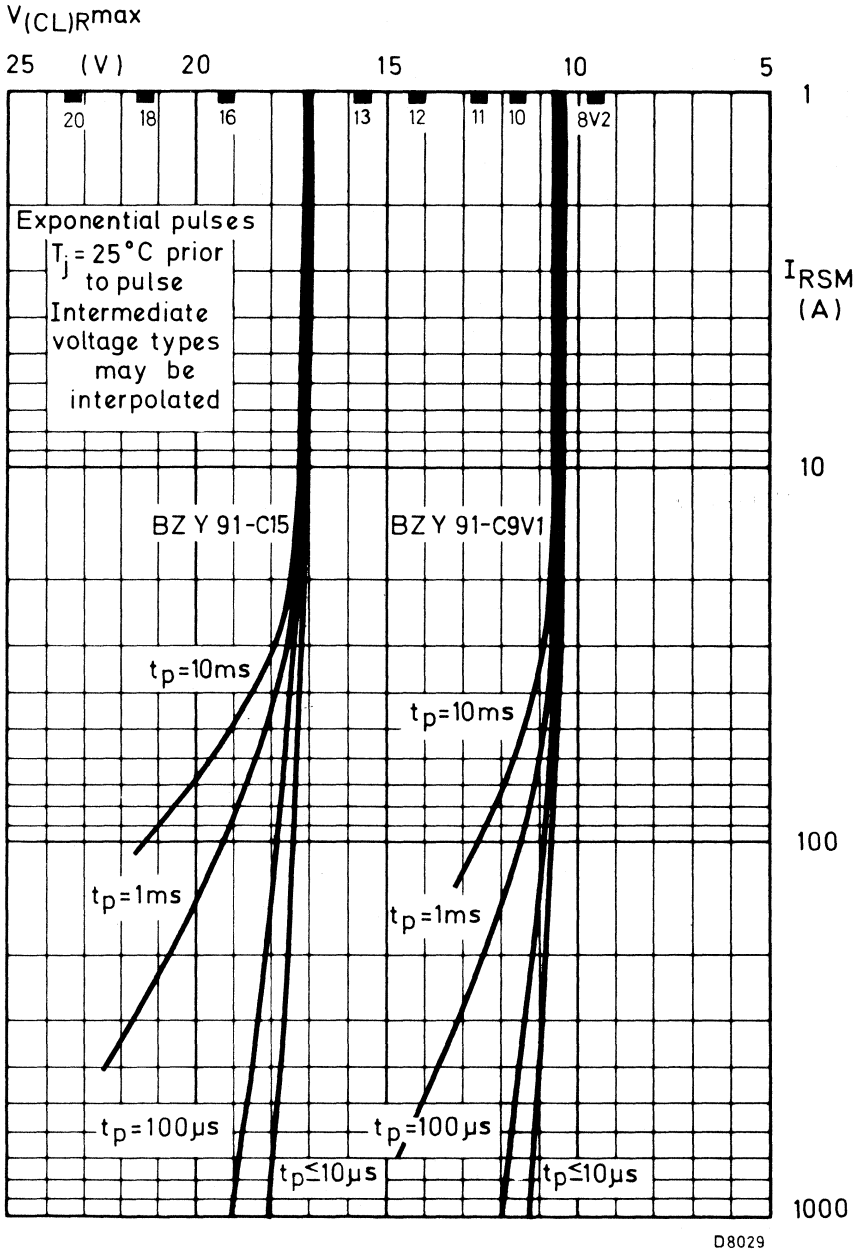
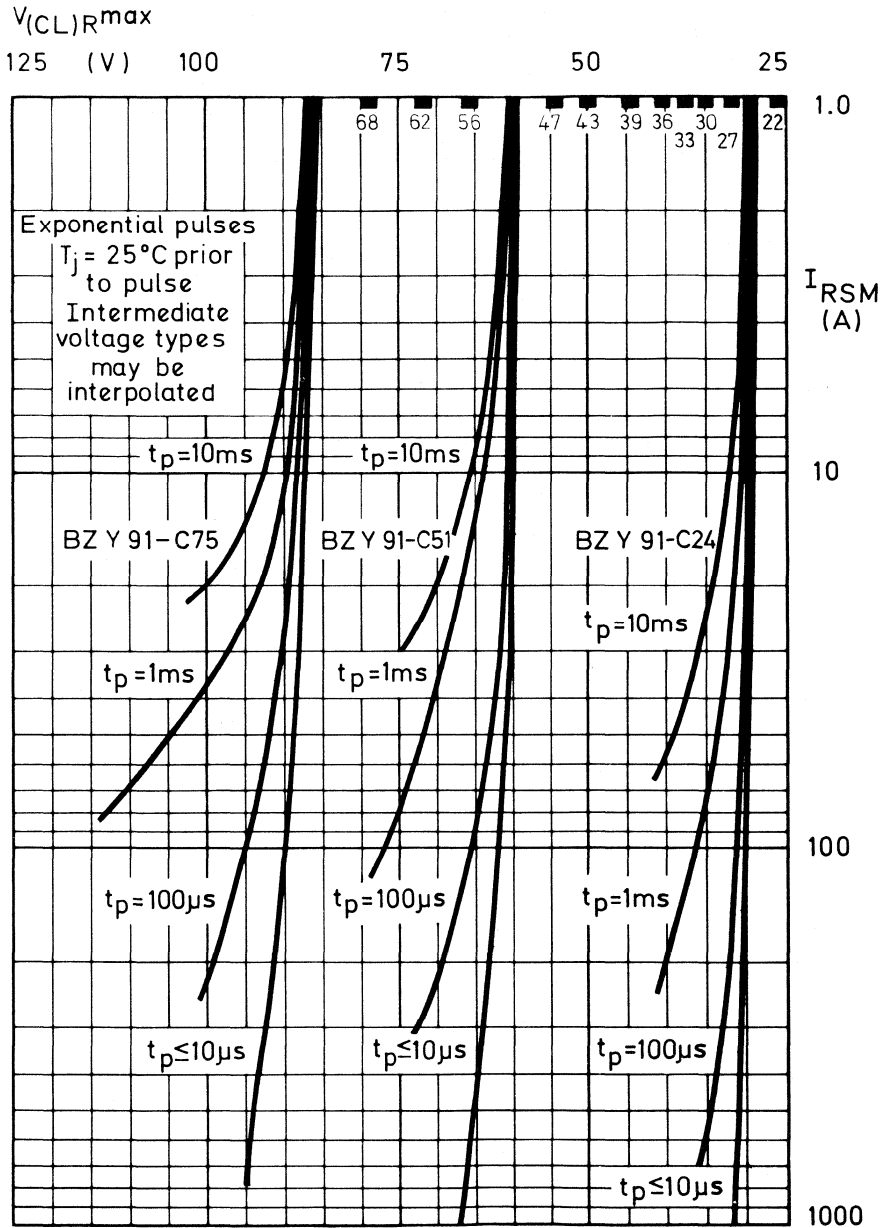


Fig. 24.



D8030

Fig. 25.

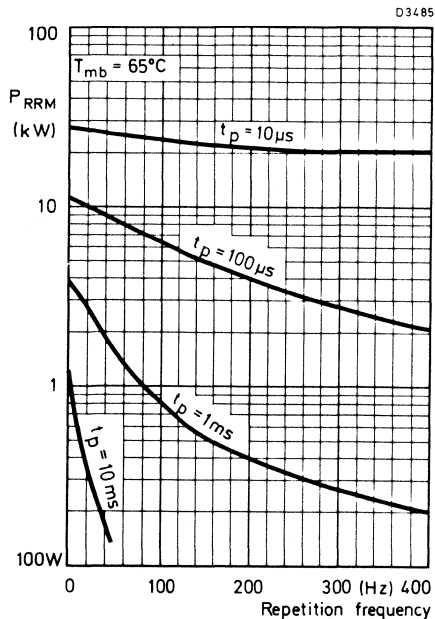


Fig. 26.

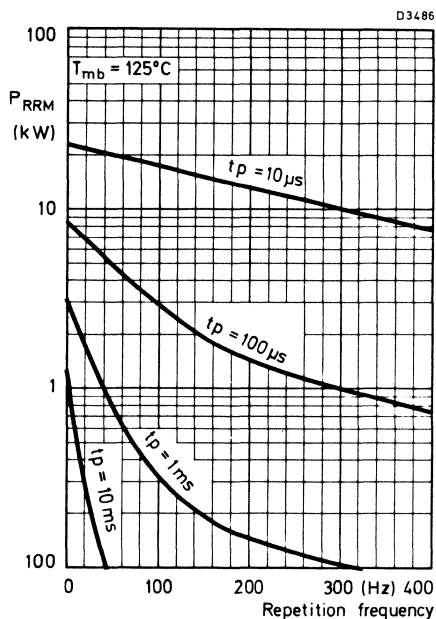


Fig. 27.

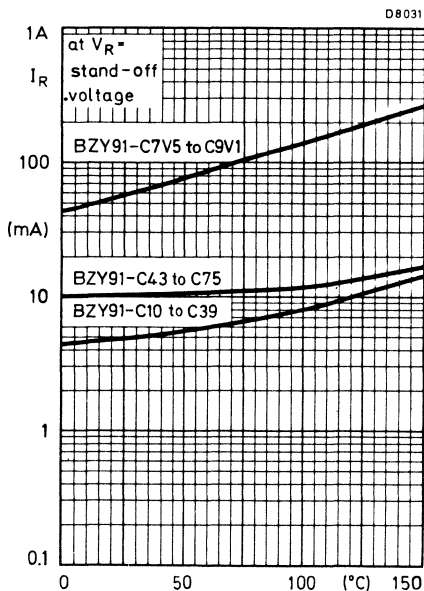


Fig. 28.



## REGULATOR DIODES

Also available to BS9305—F051

A range of diffused silicon diodes in DO-4 metal envelopes, intended for use as voltage regulator and transient suppressor diodes in power stabilization and transient suppression circuits.

The series consists of the following types:

Normal polarity (cathode to stud): BZY93-C7V5 to BZY93-C75.

Reverse polarity (anode to stud): BZY93-C7V5R to BZY93-C75R.

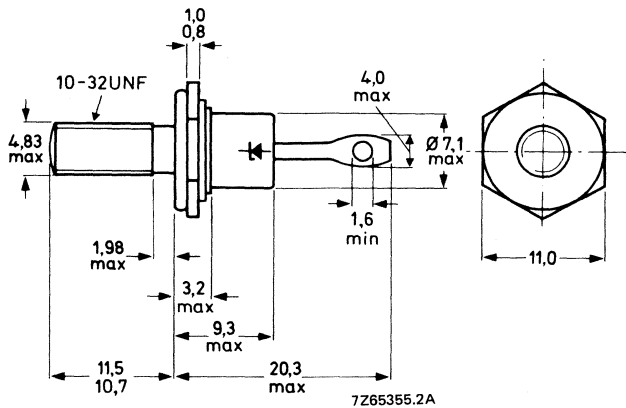
### QUICK REFERENCE DATA

		voltage regulator		transient suppressor	
Working voltage (5% range)	$V_Z$ nom.	7,5 to 75	—	V	
Stand-off voltage	$V_R$	—	5,6 to 56	V	
Total power dissipation	$P_{tot}$ max.	20	—	W	
Non-repetitive peak reverse power dissipation	$P_{RSM}$ max.	—	700	W	

### MECHANICAL DATA

Dimensions in mm

Fig. 1 DO-4.



Net mass: 6 g

Diameter of clearance hole: max. 5,2 mm

Accessories supplied on request: 56295  
(PTFE bush, 2 mica washers, plain washer, tag)

Supplied with device: 1 nut, 1 lock washer

Nut dimensions across the flats: 9,5 mm

Torque on nut: min. 0,9 Nm (9 kg cm)  
max. 1,7 Nm (17 kg cm)

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

Peak working current	$I_{ZM}$	max.	20 A
Average forward current (averaged over any 20 ms period)	$I_{F(AV)}$	max.	5 A
Non-repetitive peak reverse current $T_j = 25\text{ °C}$ prior to surge; $t_p = 1\text{ ms}$ (exponential pulse); BZY93-C7V5(R) to BZY93-C75(R)	$I_{RSM}$	max.	55 to 6 A
Total power dissipation up to $T_{mb} = 75\text{ °C}$	$P_{tot}$	max.	20 W
Non-repetitive peak reverse power dissipation $T_j = 25\text{ °C}$ prior to surge; $t_p = 1\text{ ms}$ (exponential pulse)	$P_{RSM}$	max.	700 W
Storage temperature	$T_{stg}$		-55 to +175 °C
Junction temperature	$T_j$	max.	175 °C

## THERMAL RESISTANCE

From junction to mounting base	$R_{th\ j-mb}$	=	5 °C/W
From junction to ambient	$R_{th\ j-a}$	=	50 °C/W
From mounting base to heatsink (minimum torque: 0,9 Nm)	$R_{th\ mb-h}$	=	0,6 °C/W

## CHARACTERISTICS

Forward voltage $I_F = 5\text{ A}$ ; $T_{mb} = 25\text{ °C}$	$V_F$	<	1,5 V
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## OPERATION AS A VOLTAGE REGULATOR (see page 4)

Dissipation and heatsink considerations

### a. Steady-state conditions

The maximum permissible steady-state dissipation  $P_{s\ max}$  is given by the relationship

$$P_{s\ max} = \frac{T_{j\ max} - T_{amb}}{R_{th\ j-a}}$$

where:  $T_{j\ max}$  is the maximum permissible operating junction temperature

$T_{amb}$  is the ambient temperature

$R_{th\ j-a}$  is the total thermal resistance from junction to ambient

$$R_{th\ j-a} = R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a}$$

$R_{th\ mb-h}$  is the thermal resistance from mounting base to heatsink, that is, 0,6 °C/W.

$R_{th\ h-a}$  is the thermal resistance of the heatsink.

### b. Pulse conditions (see Fig. 2)

The maximum permissible pulse power  $P_{p\ max}$  is given by the formula

$$P_{p\ max} = \frac{(T_{j\ max} - T_{amb}) - (P_s \cdot R_{th\ j-a})}{R_{th\ t} + \delta \cdot R_{th\ mb-a}}$$

where:  $P_s$  is any steady-state dissipation excluding that in pulses

$R_{th\ t}$  is the effective transient thermal resistance of the device between junction and mounting base. It is a function of the pulse duration  $t_p$  and duty factor  $\delta$ .

$\delta$  is duty factor ( $t_p/T$ )

$R_{th\ mb-a}$  is the total thermal resistance between the mounting base and ambient

( $R_{th\ mb-a} = R_{th\ mb-h} + R_{th\ h-a}$ ).

The steady-state power  $P_s$  when biased in the zener direction at a given zener current can be found from Fig. 14. With the additional pulse power dissipation  $P_{p\ max}$  calculated from the above expression, the total peak zener power dissipation  $P_{tot} = P_{ZRM} = P_s + P_p$ . From Fig. 14 the corresponding maximum repetitive peak zener current at  $P_{ZRM}$  can now be read. This repetitive peak zener current is subject to the absolute maximum rating. For pulse durations larger than the temperature stabilization time of the diode  $t_{stab}$ , the maximum permissible repetitive peak dissipation  $P_{ZRM}$  is equal to the steady-state power  $P_s$ . The temperature stabilization time for the BZY93 is 5 seconds (see Fig. 9).

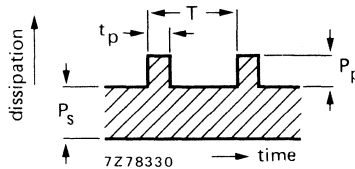


Fig. 2.

#### OPERATION AS A TRANSIENT SUPPRESSOR (see page 5)

##### Heatsink considerations

- For non-repetitive transients, the device may be used without a heatsink for pulses up to 10 ms in duration.
- For repetitive transients which fall within the permitted operating range shown in Figs 19 and 20 the required heatsink is found as follows:

$$R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a} = \frac{T_{j\ max} - T_{amb}}{P_s + \delta \cdot P_{RRM}}$$

where:  $T_{j\ max} = 175\ ^\circ\text{C}$   
 $T_{amb}$  = ambient temperature  
 $P_s$  = any steady-state dissipation excluding that in pulses  
 $\delta$  = duty factor ( $t_p/T$ )  
 $R_{th\ j-mb} = 5\ ^\circ\text{C/W}$   
 $R_{th\ mb-h} = 0,6\ ^\circ\text{C/W}$

Thus  $R_{th\ h-a}$  can be found.

##### Notes

- The stand-off voltage is the maximum reverse voltage recommended for continuous operation; at this value non-conduction is ensured.
- The maximum clamping voltage is the maximum reverse voltage which appears across the diode at the specified pulse duration and junction temperature. For square pulses see Figs 15 and 16, for exponential pulses see Figs 17 and 18.
- Duration of an exponential pulse is defined as the time taken for the pulse to fall to 37% of its initial value. It is assumed that the energy content does not continue beyond twice this time.
- Surge suppressor diodes are extremely fast in clamping, switching on in less than 5 ns.

CHARACTERISTICS – WHEN USED AS VOLTAGE REGULATOR DIODES;  $T_{mb} = 25\text{ }^{\circ}\text{C}$

BZY93-...	working voltage $*V_Z$ V		differential resistance $*r_Z$ $\Omega$		temperature coefficient $*S_Z$ mV/ $^{\circ}\text{C}$	test $I_Z$ A	reverse current $I_R$ $\mu\text{A}$	reverse voltage at $V_R$ V
	min.	max.	typ.	max.	typ.		max.	
C7V5(R)	7.0	7.9	0.04	0.3	3.0	2.0	100	2.0
C8V2(R)	7.7	8.7	0.05	0.3	4.0	2.0	100	5.6
C9V1(R)	8.5	9.6	0.07	0.5	5.0	1.0	50	6.2
C10(R)	9.4	10.6	0.07	0.5	7.0	1.0	50	6.8
C11(R)	10.4	11.6	0.08	1.0	7.5	1.0	50	7.5
C12(R)	11.4	12.7	0.08	1.0	8.0	1.0	50	8.2
C13(R)	12.4	14.1	0.08	1.0	8.5	1.0	50	9.1
C15(R)	13.8	15.6	0.10	1.2	10	1.0	50	10
C16(R)	15.3	17.1	0.18	1.2	11	0.5	50	11
C18(R)	16.8	19.1	0.2	1.5	12	0.5	50	12
C20(R)	18.8	21.2	0.2	1.5	14	0.5	50	13
C22(R)	20.8	23.3	0.21	1.8	16	0.5	50	15
C24(R)	22.7	25.9	0.22	2.0	18	0.5	50	16
C27(R)	25.1	28.9	0.25	2.0	21	0.5	50	18
C30(R)	28	32	0.3	2.5	25	0.5	50	20
C33(R)	31	35	0.32	3.0	30	0.5	50	22
C36(R)	34	38	0.75	4.0	32	0.2	50	24
C39(R)	37	41	0.85	5.0	35	0.2	50	27
C43(R)	40	46	0.90	6.5	40	0.2	50	30
C47(R)	44	50	1.0	7.0	45	0.2	50	33
C51(R)	48	54	1.2	7.5	50	0.2	50	36
C56(R)	52	60	1.3	8.0	55	0.2	50	39
C62(R)	58	66	1.5	9.0	60	0.2	50	43
C68(R)	64	72	1.8	10	65	0.2	50	47
C75(R)	70	79	2.0	10.5	70	0.2	50	51

\*At test  $I_Z$ ; measured using a pulse method with  $t_p \leq 100\ \mu\text{s}$  and  $\delta \leq 0.001$  so that the values correspond to a  $T_j$  of approximately  $25\text{ }^{\circ}\text{C}$ .

CHARACTERISTICS – WHEN USED AS TRANSIENT SUPPRESSOR DIODES;  $T_{mb} = 25\text{ }^{\circ}\text{C}$ 

clamping voltage at $t_p = 500\text{ }\mu\text{s}$ exp. pulse $V_{(CL)R}$ V		non-repetitive peak reverse current $I_{RSM}$ A	reverse current at recommended stand-off voltage $I_R$ mA $V_R$ V		BZY93-...
typ.	max.		max.		
8	9.2	20	0.5	5.6	C7V5(R)
9	10.2	20	0.5	6.2	C8V2(R)
10	11.5	20	0.5	6.8	C9V1(R)
11	12.5	20	0.1	7.5	C10(R)
12.3	14	20	0.1	8.2	C11(R)
14	16	20	0.1	9.1	C12(R)
15.3	17.5	20	0.1	10	C13(R)
17	19.5	20	0.1	11	C15(R)
19.3	22	20	0.1	12	C16(R)
21	24	20	0.1	13	C18(R)
23	27	10	0.1	15	C20(R)
26	30	10	0.1	16	C22(R)
29	34	10	0.1	18	C24(R)
33	39	10	0.1	20	C27(R)
38	44	10	0.1	22	C30(R)
42	50	10	0.1	24	C33(R)
47	56	10	0.1	27	C36(R)
40	47	5	0.1	30	C39(R)
45	52	5	0.1	33	C43(R)
51	59	5	0.1	36	C47(R)
57	66	5	0.1	39	C51(R)
64	75	5	0.1	43	C56(R)
73	85	5	0.1	47	C62(R)
81	94	5	0.1	51	C68(R)
90	105	5	0.1	56	C75(R)

**MOUNTING INSTRUCTIONS**

The top connector should neither be bent nor twisted; it should be soldered into the circuit so that there is no strain on it.

During soldering the heat conduction to the junction should be kept to a minimum.

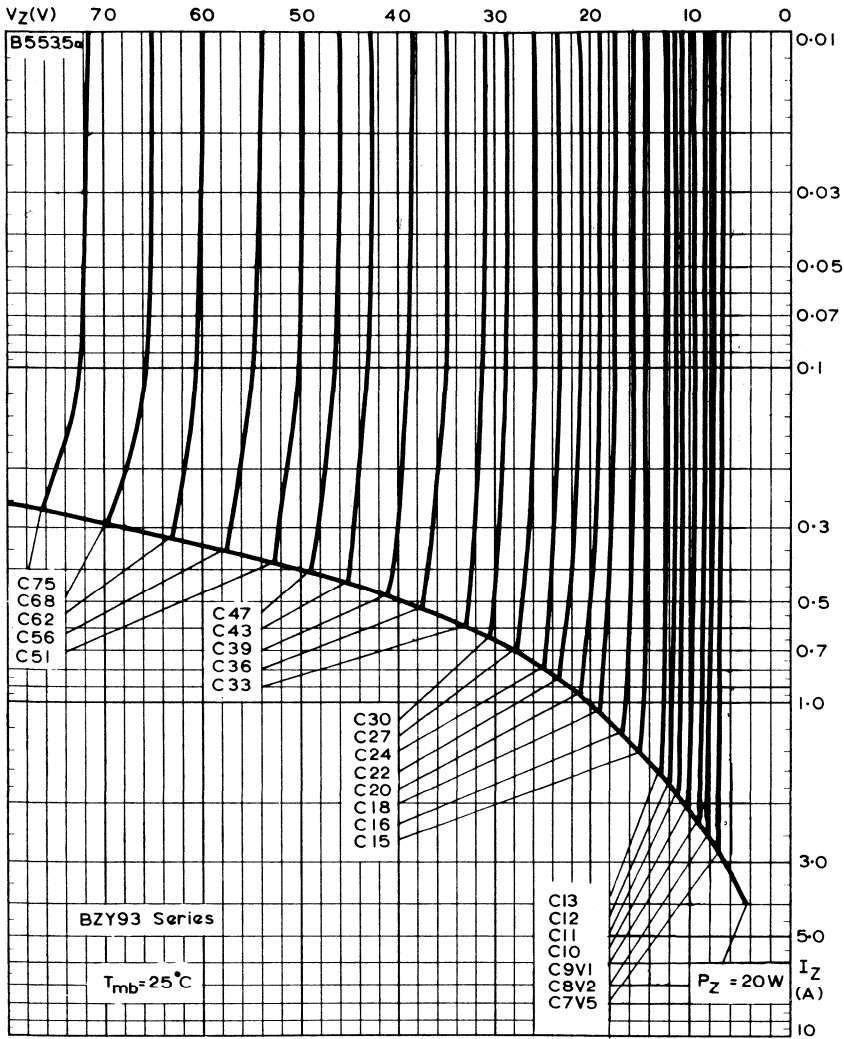


Fig. 3 Typical static zener characteristics.

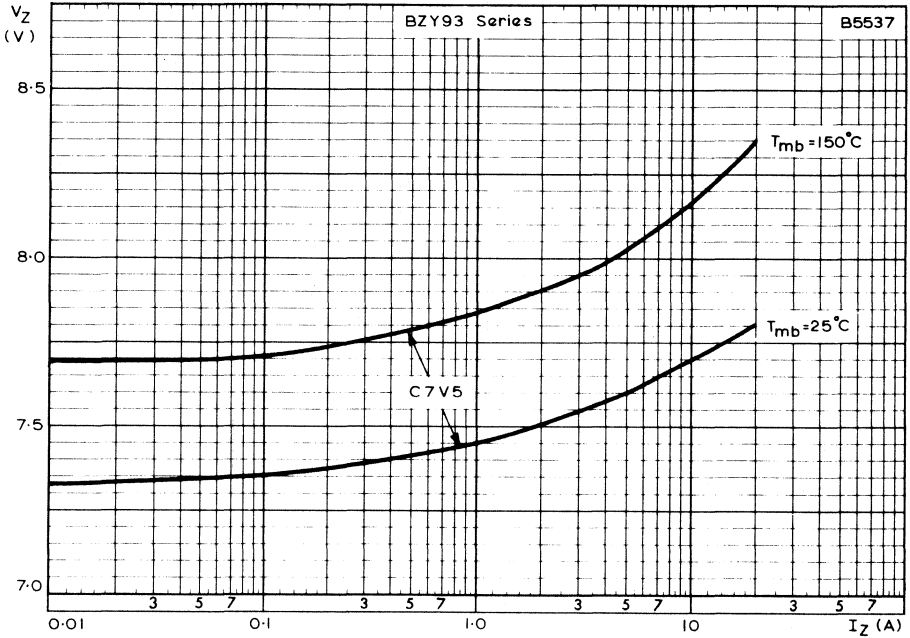


Fig. 4 Typical dynamic zener characteristics for BZY93-C7V5.

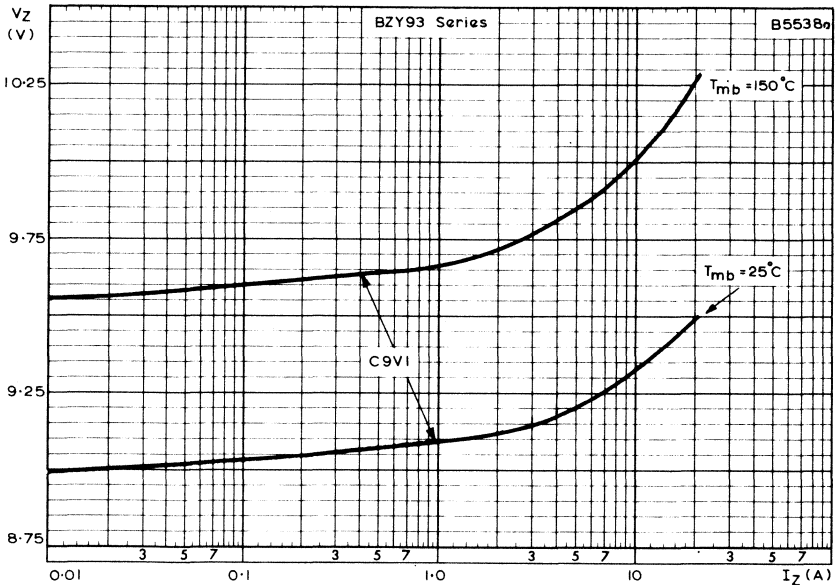


Fig. 5 Typical dynamic zener characteristics for BZY93-C9V1.



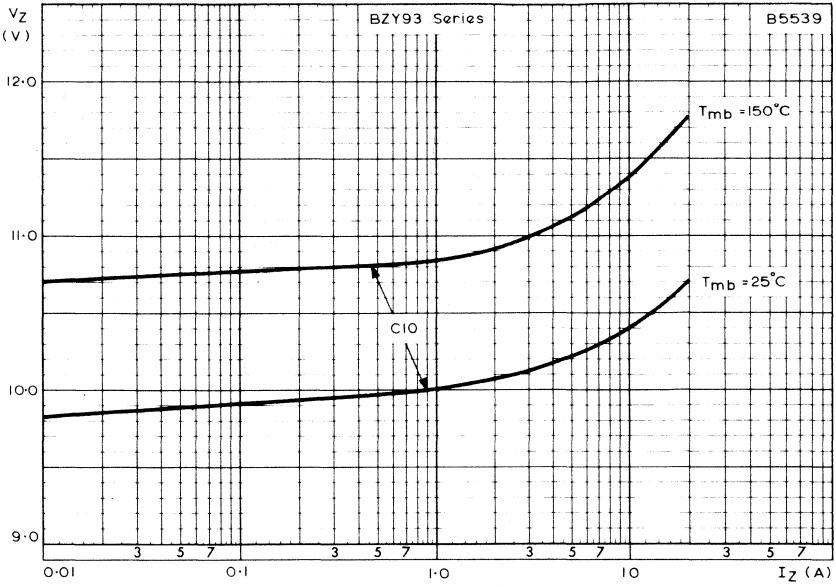


Fig. 6 Typical dynamic zener characteristics for BZY93-C10.

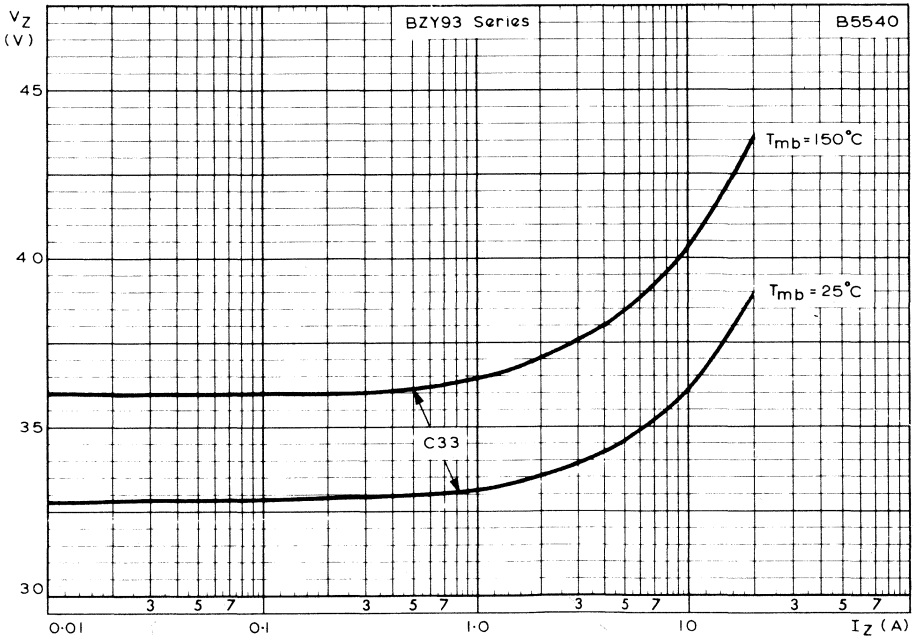


Fig. 7 Typical dynamic zener characteristics for BZY93-C33.

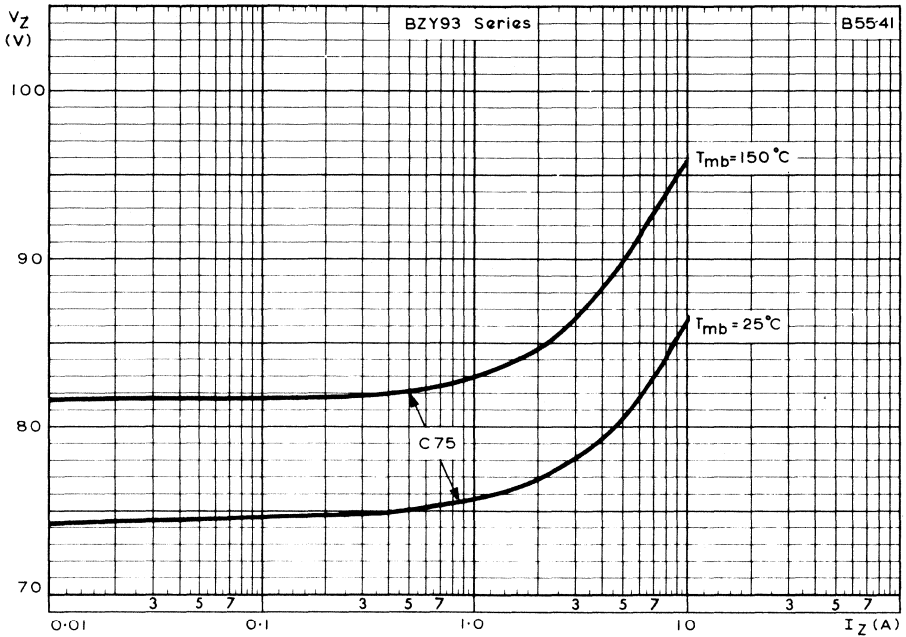


Fig. 8 Typical dynamic zener characteristics for BZY93-C75.

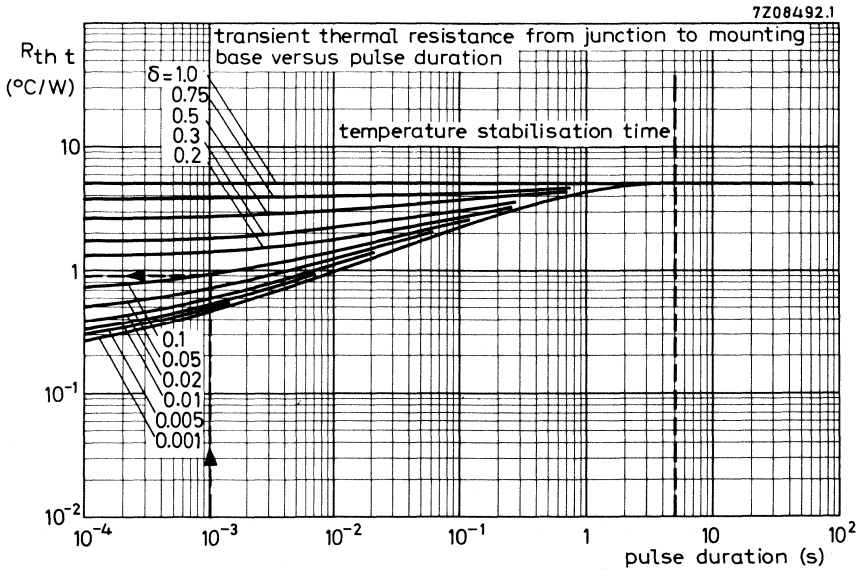


Fig. 9.

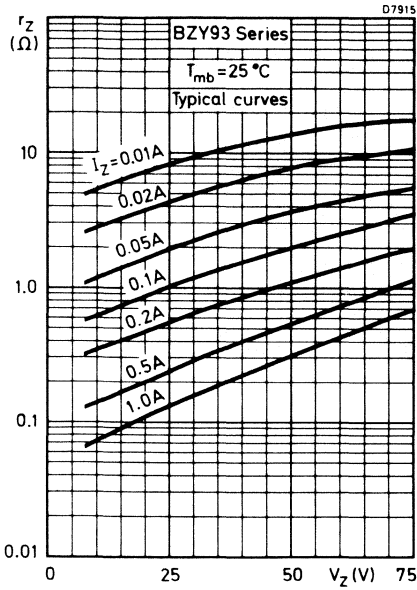


Fig. 10.

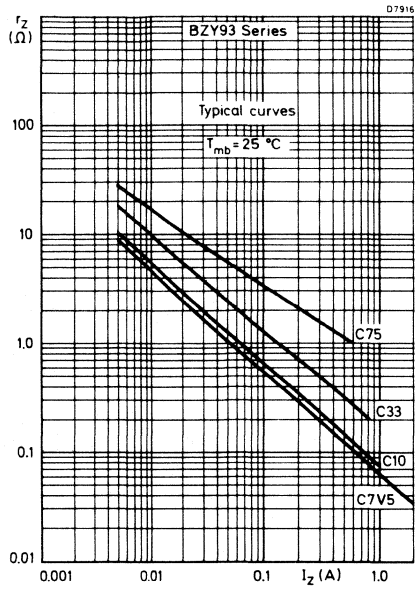


Fig. 11.

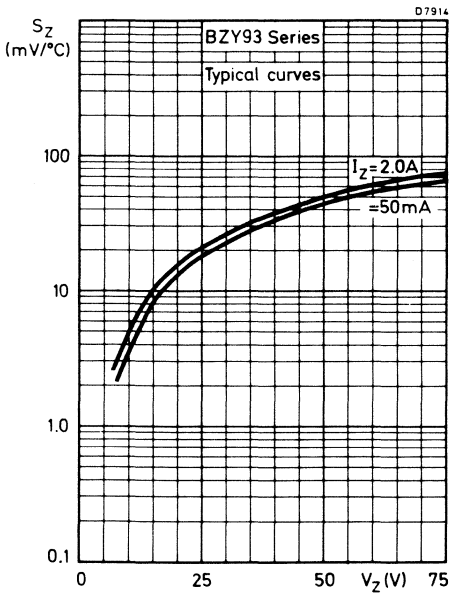


Fig. 12.

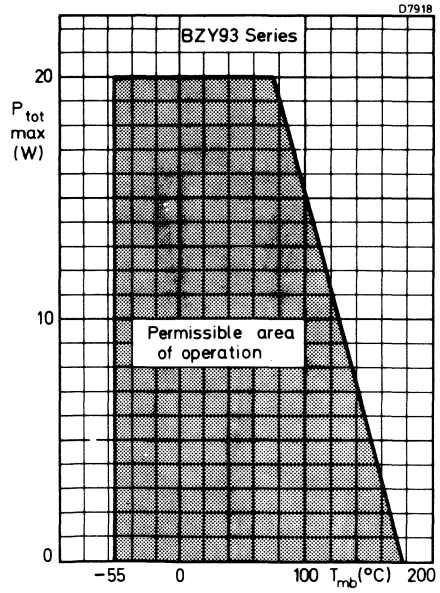


Fig. 13.

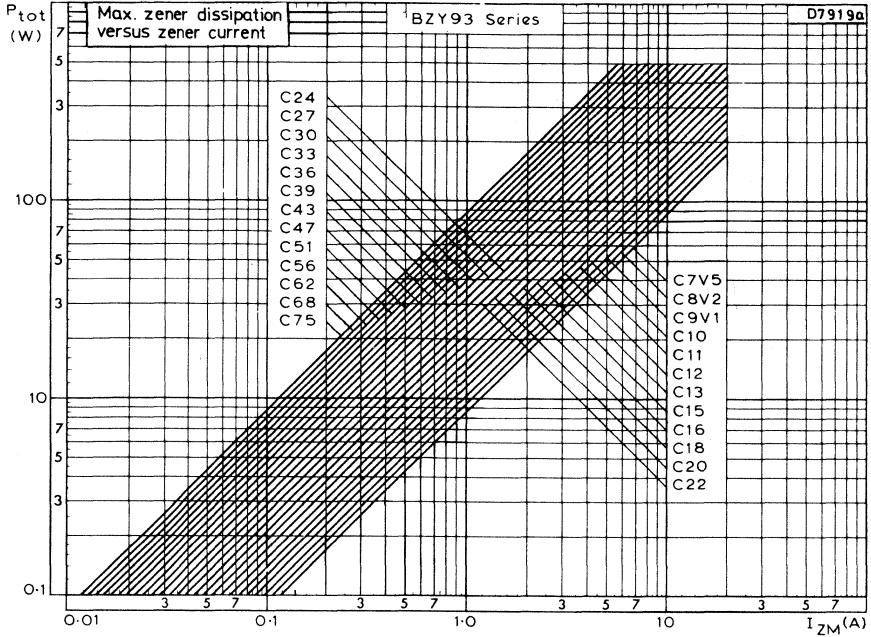


Fig. 14 Maximum permissible repetitive peak dissipation ( $P_{tot} = P_{ZRM}$ ).

D7921

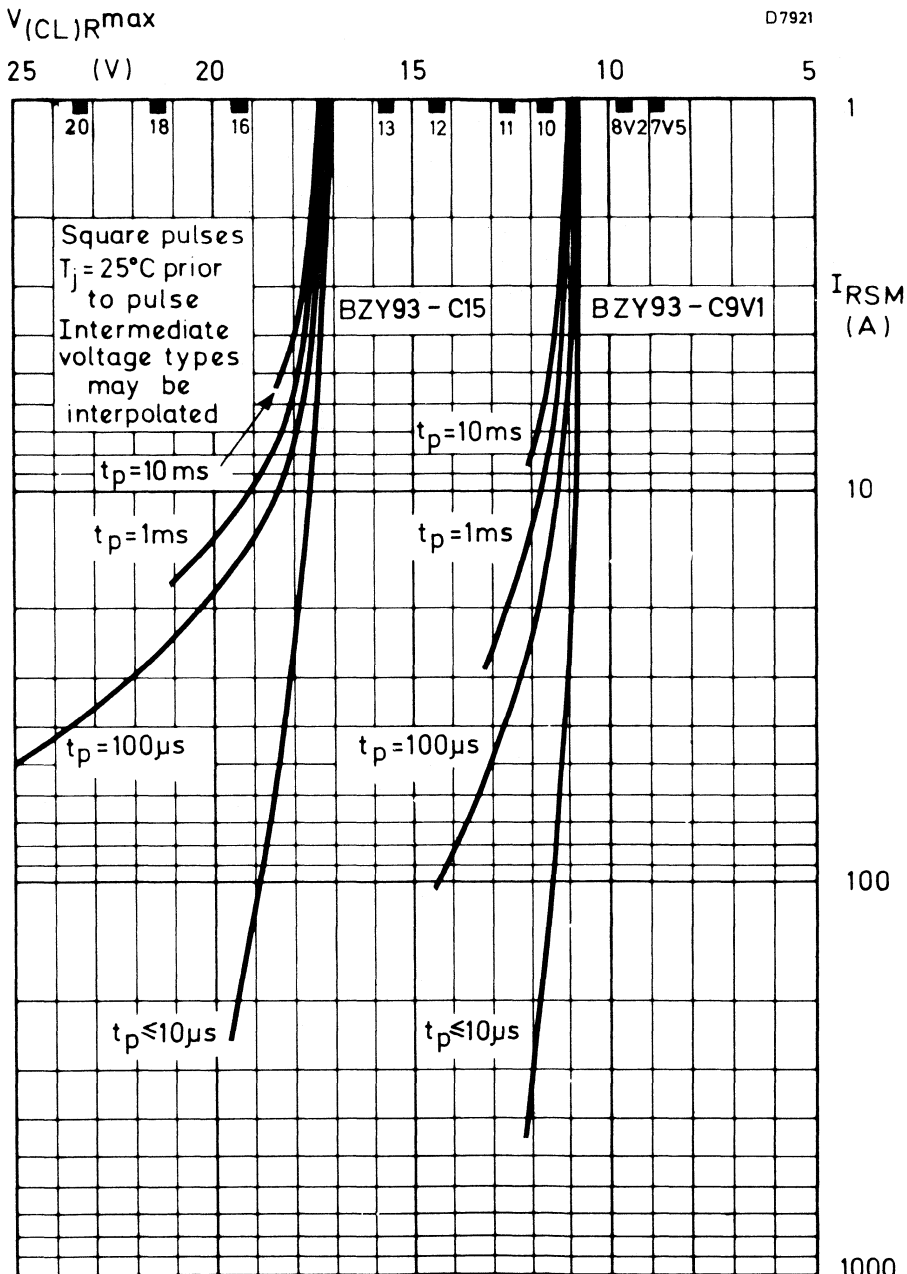


Fig. 15.

BZY93 SERIES

$V_{(CL)R}^{max}$

07920

125 (V)

100

75

50

25

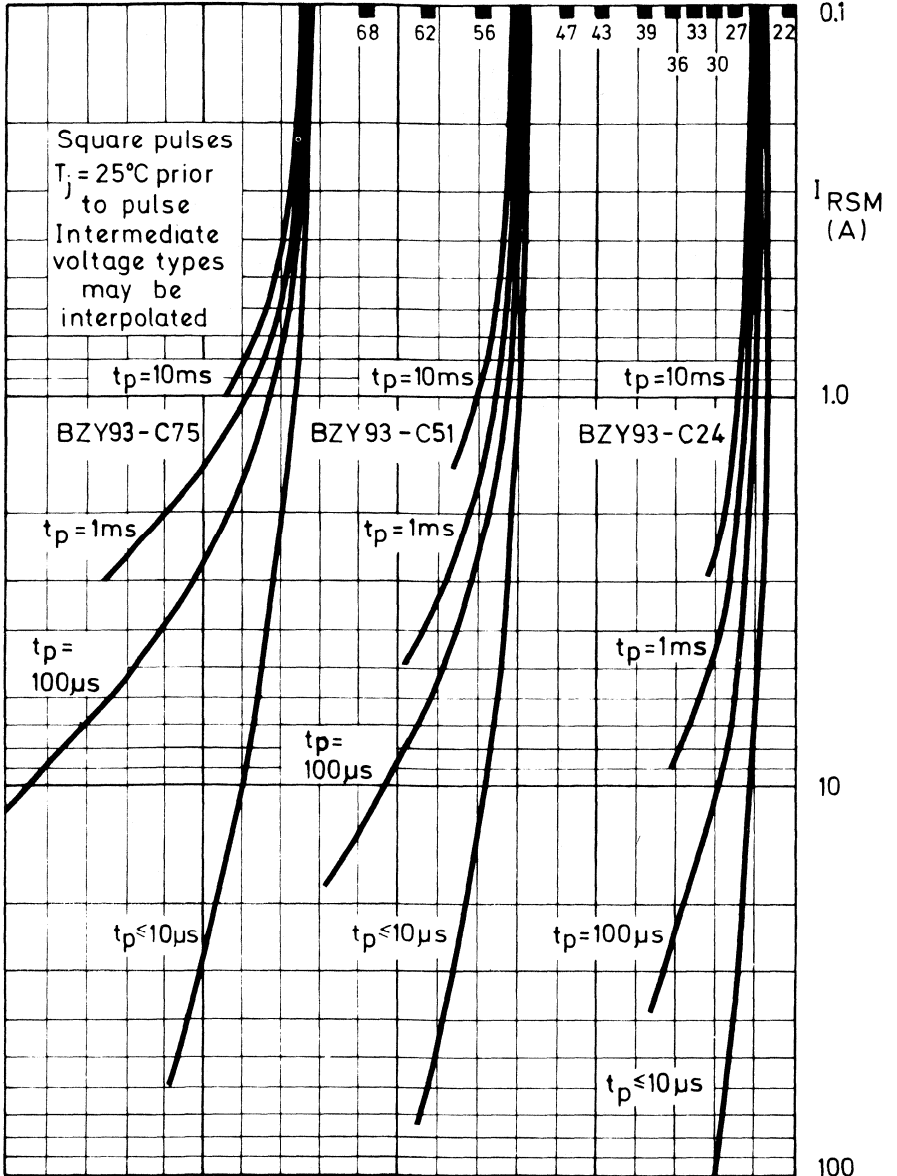


Fig. 16.

D7922

$V_{(CL)R} \text{ max}$

25 (V) 20 15 10 5

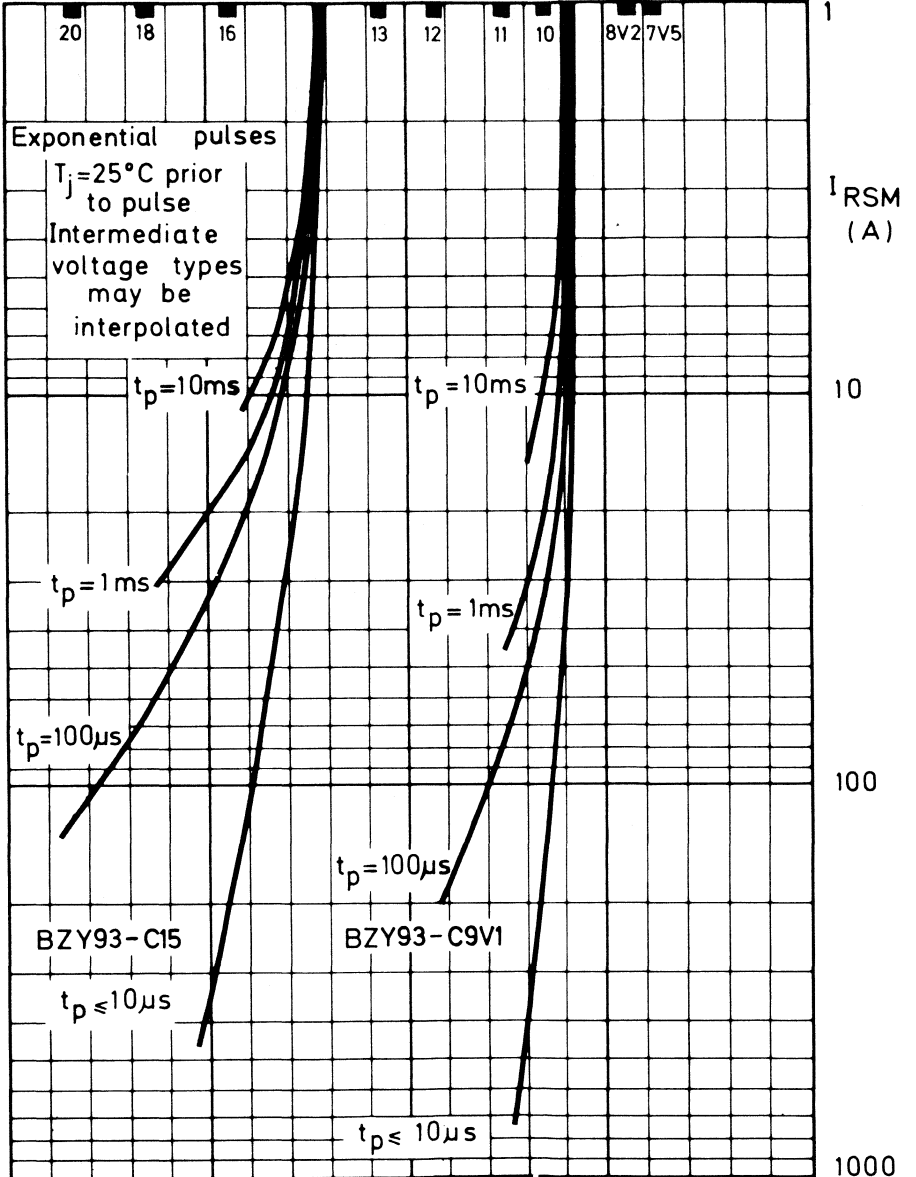


Fig. 17.

$V_{(CL)R}^{max}$

D7923

125 (V) 100 75 50 25

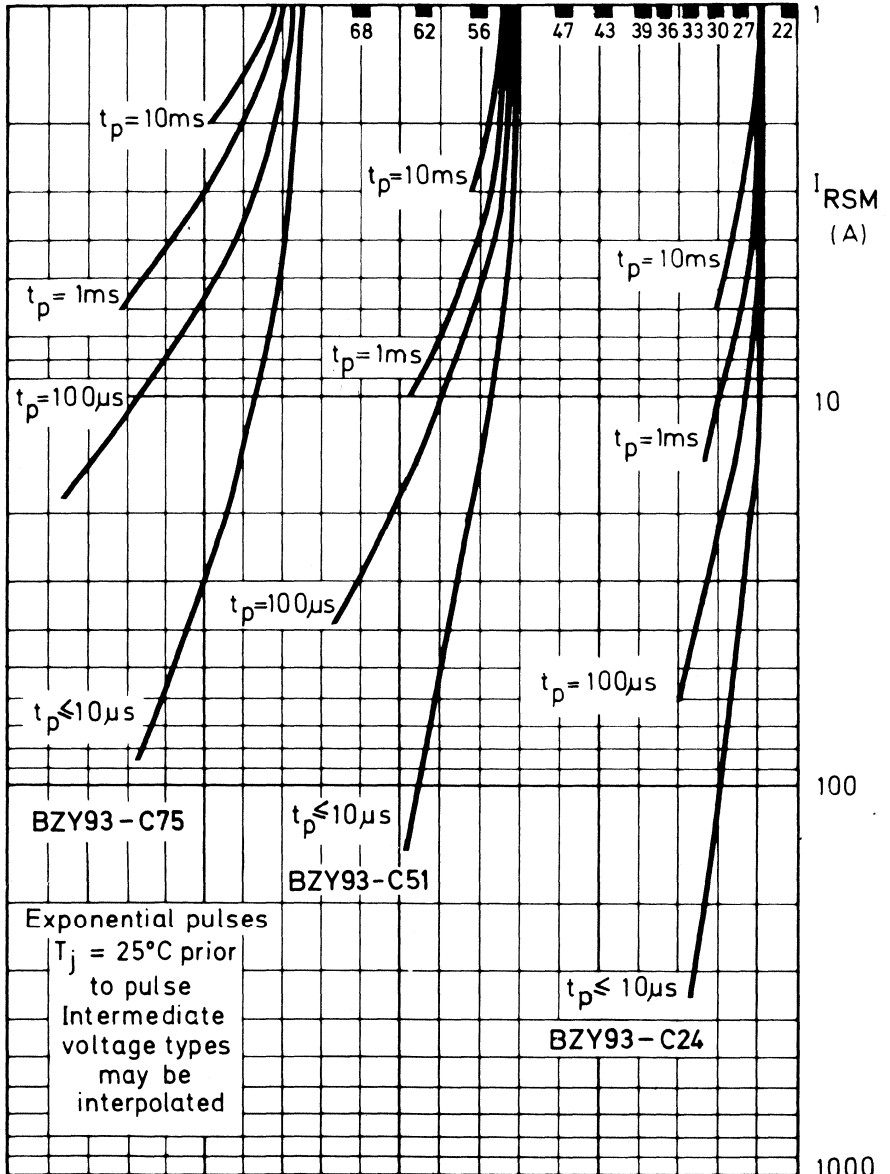


Fig. 18.



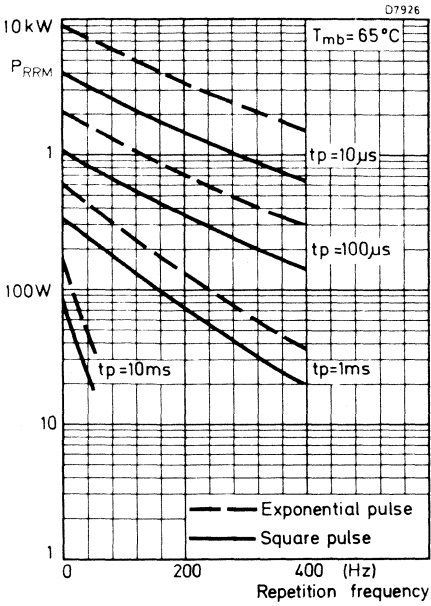


Fig. 19.

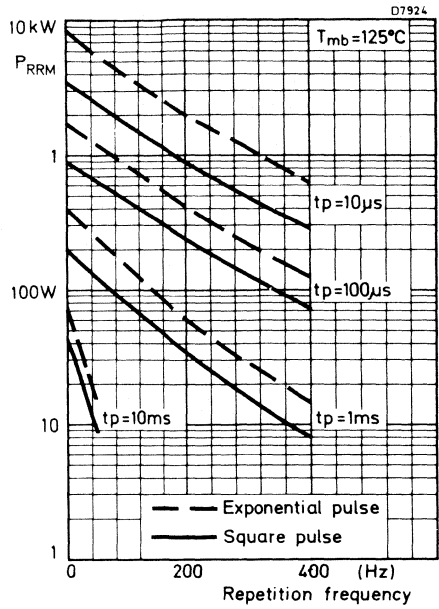


Fig. 20.

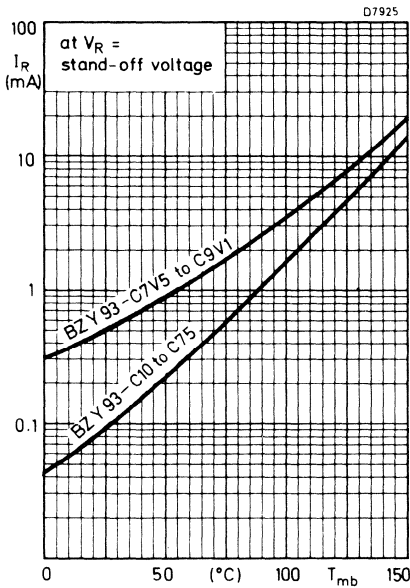


Fig. 21.

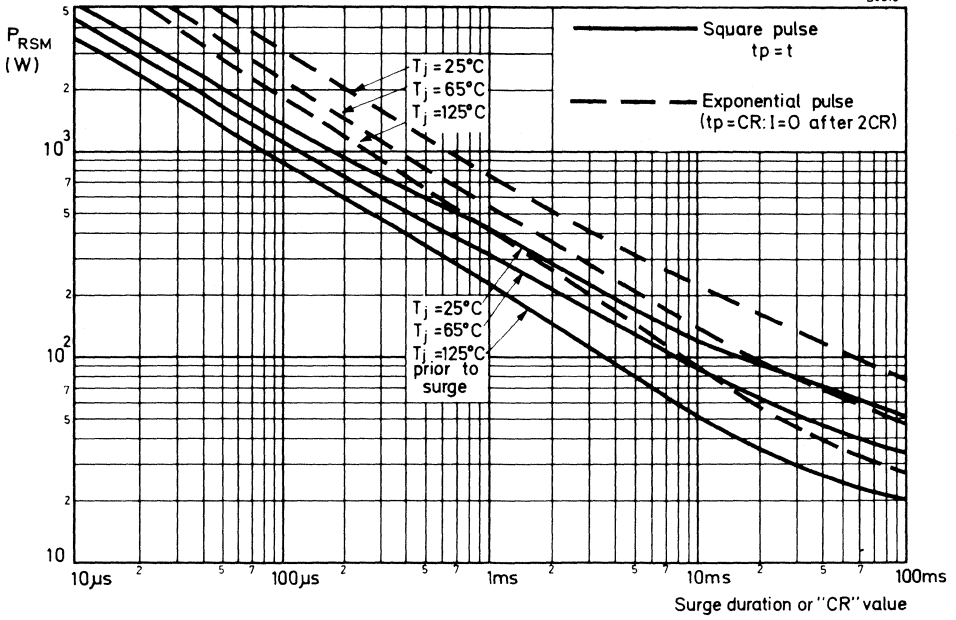


Fig. 22.

## REGULATOR DIODES

Also available to BS9305—F050

A range of diffused silicon diodes in DO-1 envelopes, intended for use as voltage regulator and transient suppressor diodes in medium power regulators and transient suppression circuits.

The series consists of the following types: BZY95-C10 to BZY95-C75.

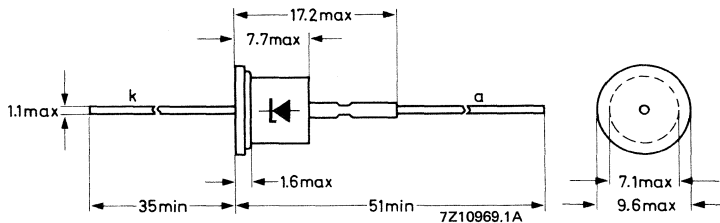
### QUICK REFERENCE DATA

		voltage regulator		transient suppressor	
Working voltage (5% range)	$V_Z$ nom.	10 to 75	—	V	
Stand-off voltage	$V_R$	—	7,5 to 56	V	
Total power dissipation	$P_{tot}$ max.	2,5	—	W	
Non-repetitive peak reverse power dissipation	$P_{RSM}$ max.	—	700	W	

### MECHANICAL DATA

Dimensions in mm

Fig. 1 DO-1.



## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

Peak working current	$I_{ZM}$	max.	5 A
Average forward current (averaged over any 20 ms period)	$I_{F(AV)}$	max.	1 A
Non-repetitive peak reverse current $T_j = 25\text{ }^\circ\text{C}$ prior to surge; $t_p = 1\text{ ms}$ (exponential pulse); BZY95-C10 to BZY95-C75	$I_{RSM}$	max.	70 to 5 A
Total power dissipation up to $T_{amb} = 25\text{ }^\circ\text{C}$ at $T_{amb} = 75\text{ }^\circ\text{C}$	$P_{tot}$ $P_{tot}$	max.	2,5 W 1,67 W
Non-repetitive peak reverse power dissipation $T_j = 25\text{ }^\circ\text{C}$ prior to surge; $t_p = 1\text{ ms}$ (exponential pulse)	$P_{RSM}$	max.	700 W
Storage temperature	$T_{stg}$		-65 to +175 $^\circ\text{C}$
Junction temperature	$T_j$	max.	175 $^\circ\text{C}$

## THERMAL RESISTANCE

The quoted values of  $R_{th\ j-a}$  should be used only when no leads of other dissipating components run to the same tie-points.

Thermal resistance from junction to ambient in free air:

mounted on soldering tags

- at lead length  $a = 10\text{ mm}$
- at lead length  $a = \text{maximum}$

$$R_{th\ j-a} = 60\text{ }^\circ\text{C/W}$$

$$R_{th\ j-a} = 70\text{ }^\circ\text{C/W}$$

mounted on a printed-circuit board

- at lead length  $a = \text{maximum}$
- at lead length  $a = 10\text{ mm}$

$$R_{th\ j-a} = 80\text{ }^\circ\text{C/W}$$

$$R_{th\ j-a} = 90\text{ }^\circ\text{C/W}$$

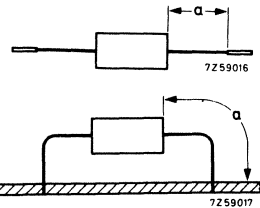


Fig.2

## CHARACTERISTICS

Forward voltage

$$I_F = 1\text{ A}; T_{amb} = 25\text{ }^\circ\text{C}$$

$$V_F < 1,5\text{ V}$$

**OPERATION AS A VOLTAGE REGULATOR** (see page 4)

Dissipation and heatsink considerations

## a. Steady-state conditions

The maximum permissible steady-state dissipation  $P_{s \max}$  is given by the relationship

$$P_{s \max} = \frac{T_{j \max} - T_{\text{amb}}}{R_{\text{th } j-a}}$$

where:  $T_{j \max}$  is the maximum permissible operating junction temperature $T_{\text{amb}}$  is the ambient temperature $R_{\text{th } j-a}$  is the total thermal resistance from junction to ambient

## b. Pulse conditions (see Fig.3)

The maximum permissible pulse power  $P_{p \max}$  is given by the formula

$$P_{p \max} = \frac{(T_{j \max} - T_{\text{amb}}) - (P_s \cdot R_{\text{th } j-a})}{R_{\text{th } t}}$$

where:  $P_s$  is any steady-state dissipation excluding that in pulses. $R_{\text{th } t}$  is the effective transient thermal resistance of the device between junction and ambient.It is a function of the pulse duration  $t_p$  and duty factor  $\delta$ . $\delta$  is the duty factor ( $t_p/T$ ).

The steady-state power  $P_s$  when biased in the zener direction at a given zener current can be found from Fig. 4. With the additional pulse power dissipation  $P_{p \max}$  calculated from the above expression, the total peak zener power dissipation  $P_{\text{tot}} = P_{\text{ZRM}} = P_s + P_p$ . From Fig. 4 the corresponding maximum repetitive peak zener current at  $P_{\text{tot}}$  can now be read. This repetitive peak zener current is subject to the absolute maximum rating. For pulse durations longer than the temperature stabilization time of the diode  $t_{\text{stab}}$ , the maximum permissible repetitive peak dissipation  $P_{\text{ZRM}}$  is equal to the steady-state power  $P_s$ . The temperature stabilization time for the BZY95 is 100 seconds (see Fig. 10).

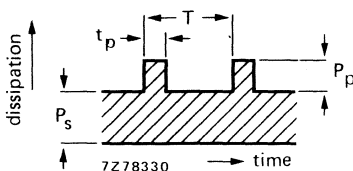


Fig. 3.

**NOTES WHEN OPERATING AS A TRANSIENT SUPPRESSOR** (see page 5)

1. The stand-off voltage is the maximum reverse voltage recommended for continuous operation; at this value non-conduction is ensured.
2. The maximum clamping voltage is the maximum reverse voltage which appears across the diode at the specified pulse duration and junction temperature. For square pulses see Figs 14 and 15, for exponential pulses see Figs 16 and 17.
3. Duration of an exponential pulse is defined as the time taken for the pulse to fall to 37% of its initial value. It is assumed that the energy content does not continue beyond twice this time.
4. Surge suppressor diodes are extremely fast in clamping, switching on in less than 5 ns.

# BZY95 SERIES

## CHARACTERISTICS – WHEN USED AS VOLTAGE REGULATOR DIODES; $T_{mb} = 25\text{ }^{\circ}\text{C}$

BZY95...	working voltage $^*V_Z$ V		differential resistance $^*r_Z$ $\Omega$		temperature coefficient $^*S_Z$ mV/ $^{\circ}\text{C}$	test $I_Z$ mA	reverse current at $I_R$ $\mu\text{A}$	reverse voltage $V_R$ V
	min.	max.	typ.	max.	typ.		max.	
C10	9.4	10.6	0.75	4.0	7.0	50	10	6.8
C11	10.4	11.6	0.8	4.5	7.5	50	10	7.5
C12	11.4	12.7	0.85	5.0	8.0	50	10	8.2
C13	12.4	14.1	0.9	6.0	8.5	50	10	9.1
C15	13.8	15.6	1.0	8.0	10	50	10	10
C16	15.3	17.1	2.4	9.0	11	20	10	11
C18	16.8	19.1	2.5	11	12	20	10	12
C20	18.8	21.2	2.8	12	14	20	10	13
C22	20.8	23.3	3.0	13	16	20	10	15
C24	22.7	25.9	3.4	14	18	20	10	16
C27	25.1	28.9	3.8	18	20	20	10	18
C30	28	32	4.5	22	25	20	10	20
C33	31	35	5.0	25	30	20	10	22
C36	34	38	5.5	30	32	20	10	24
C39	37	41	12	35	35	10	10	27
C43	40	46	13	40	40	10	10	30
C47	44	50	14	50	45	10	10	33
C51	48	54	15	55	50	10	10	36
C56	52	60	17	63	55	10	10	39
C62	58	66	18	75	60	10	10	43
C68	64	72	18	90	65	10	10	47
C75	70	79	20	100	70	10	10	51

\*At test  $I_Z$ ; measured using a pulse method with  $t_p \leq 100\ \mu\text{s}$  and  $\delta \leq 0.001$  so that the values correspond to a  $T_j$  of approximately  $25\text{ }^{\circ}\text{C}$ .

CHARACTERISTICS – WHEN USED AS TRANSIENT SUPPRESSOR DIODES;  $T_{mb} = 25\text{ }^{\circ}\text{C}$ 

clamping voltage at $t_p = 500\text{ }\mu\text{s}$ exp. pulse $V_{(CL)R}$ V		non-repetitive peak reverse current $I_{RSM}$ A	reverse current at recommended stand-off voltage $I_R$ mA		BZY95...
typ.	max.		max.	$V_R$ V	
11	12.5	20	0.1	7.5	C10
12.3	14	20	0.1	8.2	C11
14	16	20	0.1	9.1	C12
15.3	17.5	20	0.1	10	C13
17	19.5	20	0.1	11	C15
19.3	22	20	0.1	12	C16
21	24	20	0.1	13	C18
23	27	10	0.1	15	C20
26	30	10	0.1	16	C22
29	34	10	0.1	18	C24
33	39	10	0.1	20	C27
38	44	10	0.1	22	C30
42	50	10	0.1	24	C33
47	56	10	0.1	27	C36
40	47	5	0.1	30	C39
45	52	5	0.1	33	C43
51	59	5	0.1	36	C47
57	66	5	0.1	39	C51
64	75	5	0.1	43	C56
73	85	5	0.1	47	C62
81	94	5	0.1	51	C68
90	105	5	0.1	56	C75

### SOLDERING AND MOUNTING INSTRUCTIONS

1. When using a soldering iron, diodes may be soldered directly into the circuit, but heat conducted to the junction should be kept to a minimum.
2. Diodes may be dip-soldered at a solder temperature of 245 °C for a maximum soldering time of 5 seconds. The case temperature during dip-soldering must not at any time exceed the maximum storage temperature. These recommendations apply to a diode with the anode end mounted flush on a printed-circuit board having punched-through holes. For mounting the anode end onto a printed-circuit board, the diode must be spaced at least 5 mm from the underside of the printed-circuit board having punched-through holes, or 5 mm from the top of the printed-circuit board having plated-through holes.
3. Care should be taken not to bend the leads nearer than 1,5 mm from the seal; exert no axial pull when bending.



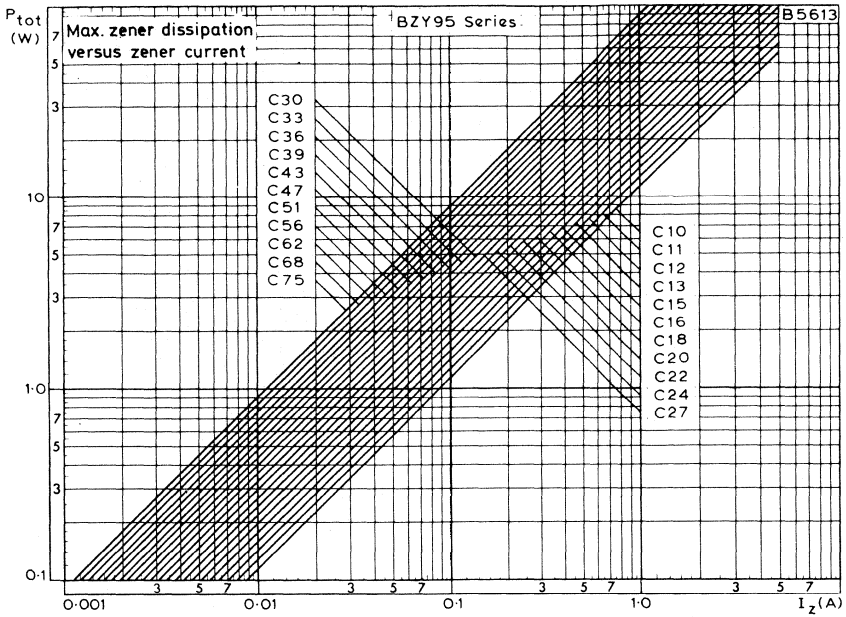


Fig. 4 Maximum permissible repetitive peak dissipation ( $P_{tot} = P_{ZRM}$ ).

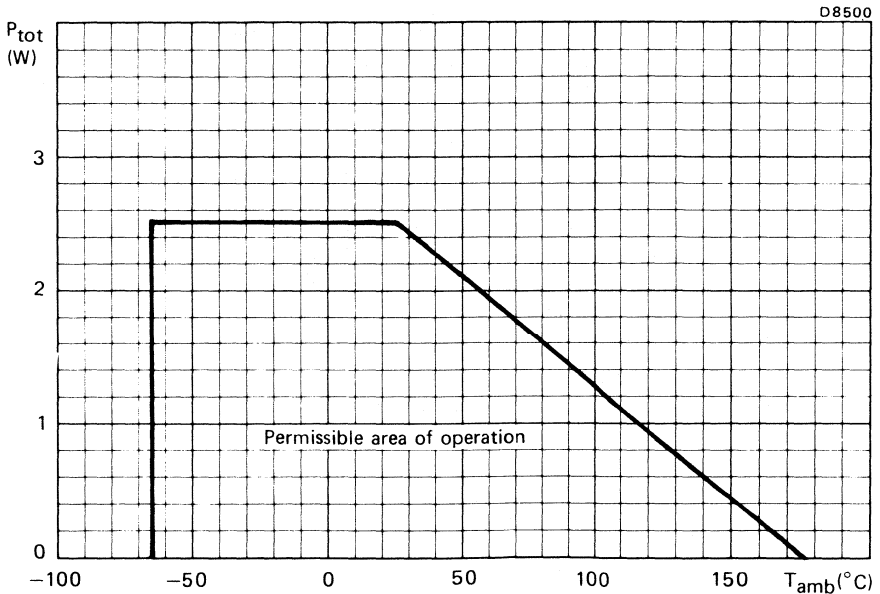


Fig. 5 Maximum permissible total power dissipation versus ambient temperature.

# BZY95 SERIES

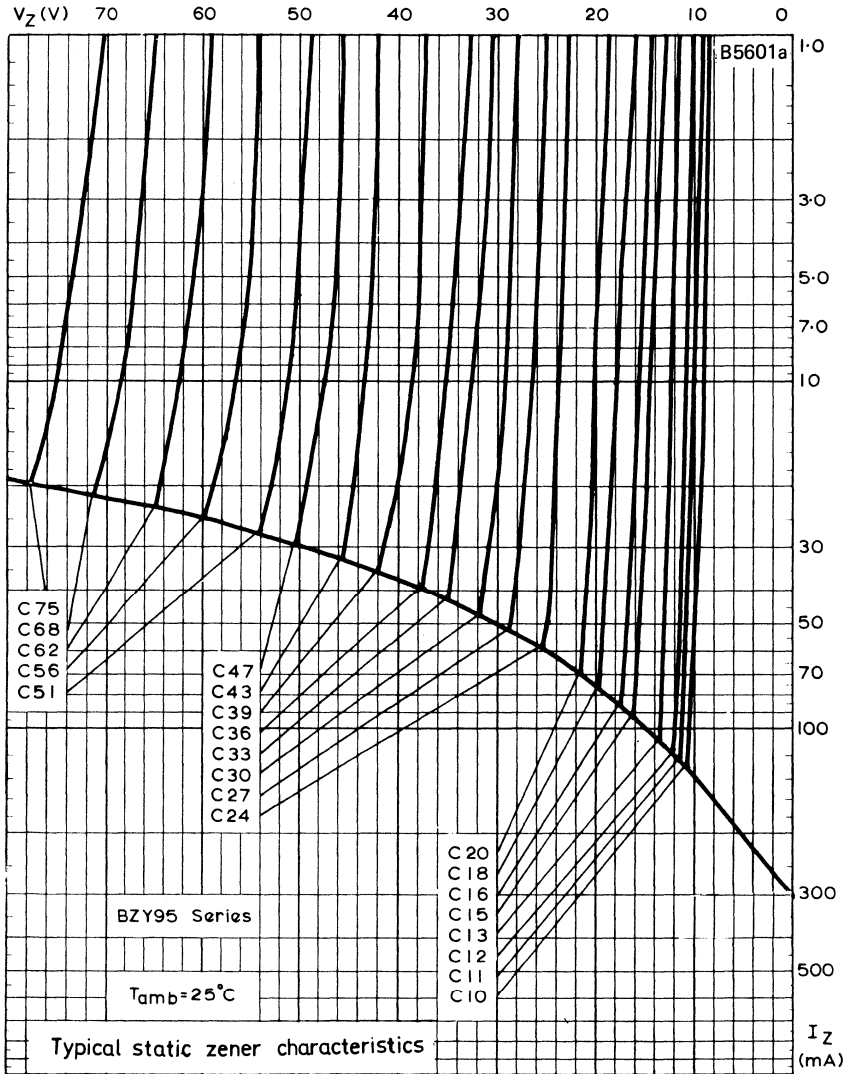


Fig. 6 Typical static zener characteristics.

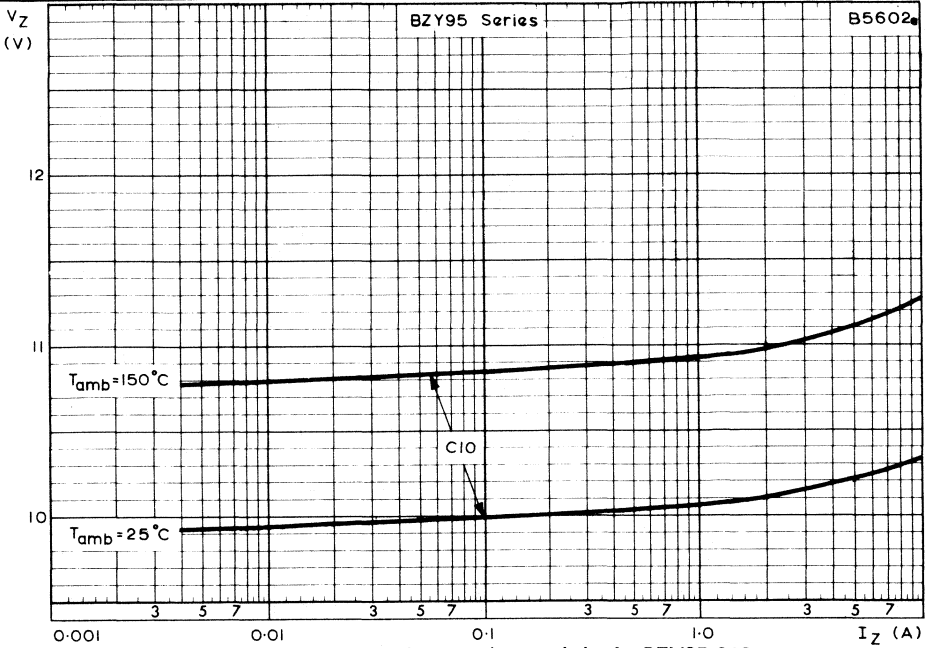


Fig. 7 Typical dynamic zener characteristics for BZY95-C10.

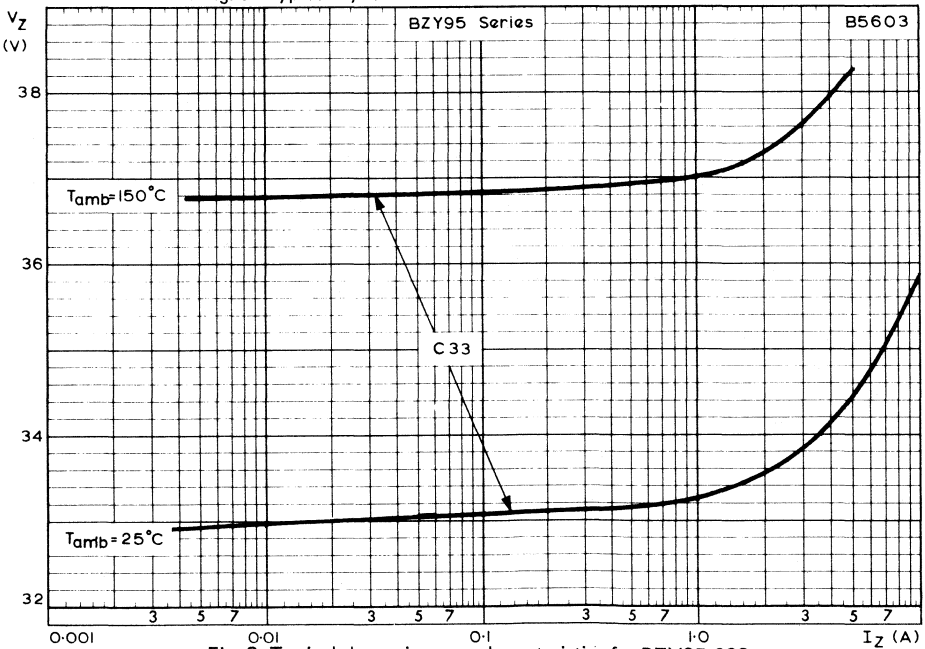


Fig. 8 Typical dynamic zener characteristics for BZY95-C33.

# BZY95 SERIES

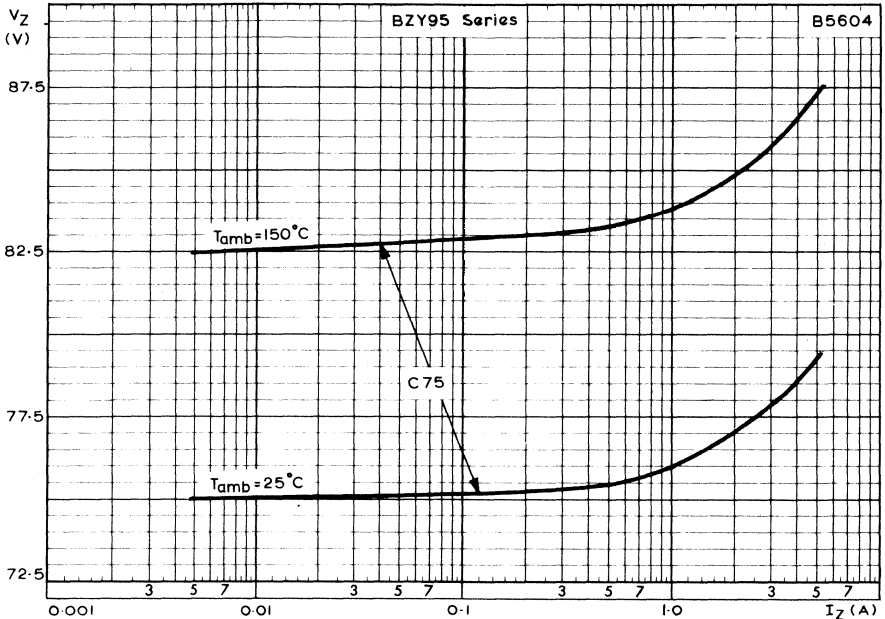


Fig. 9 Typical dynamic zener characteristics for BZY95-C75.

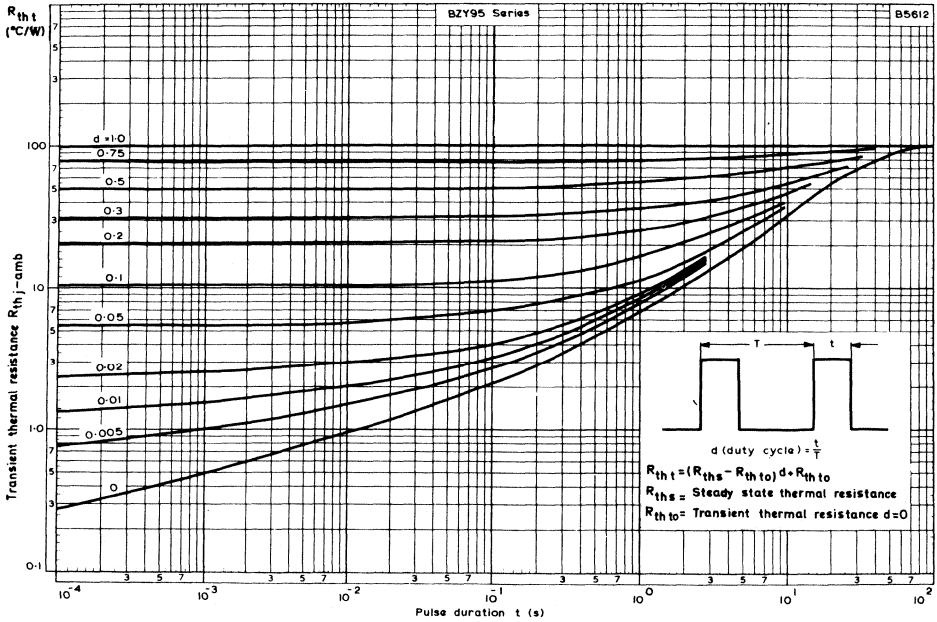


Fig. 10.

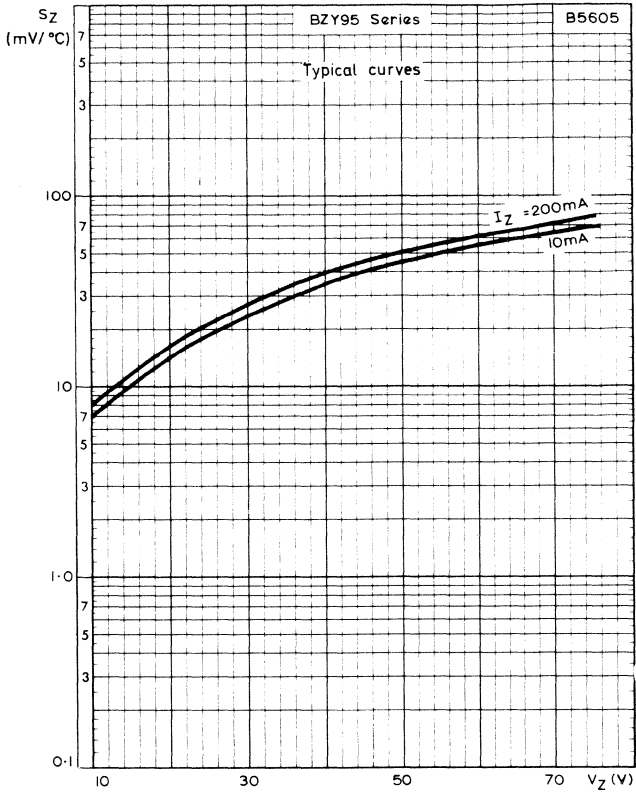


Fig. 11.

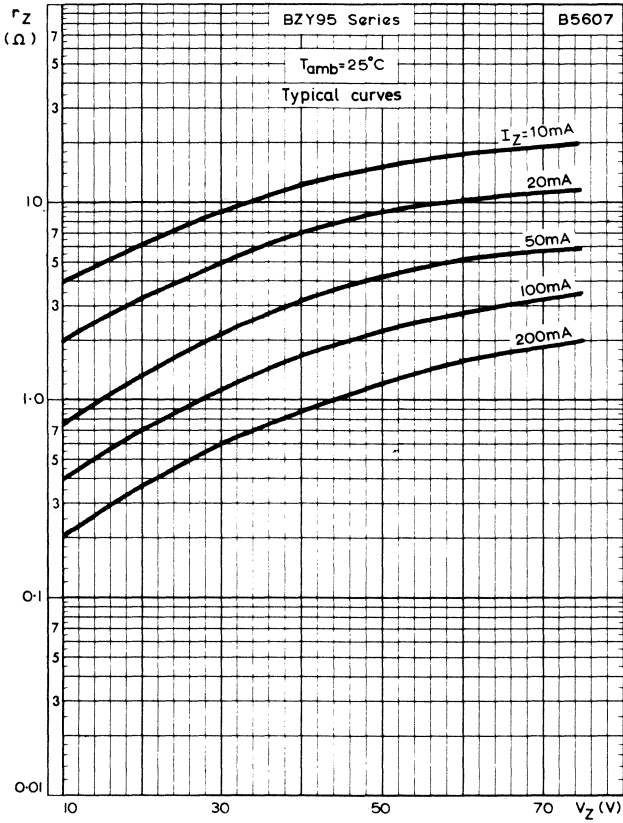


Fig. 12.

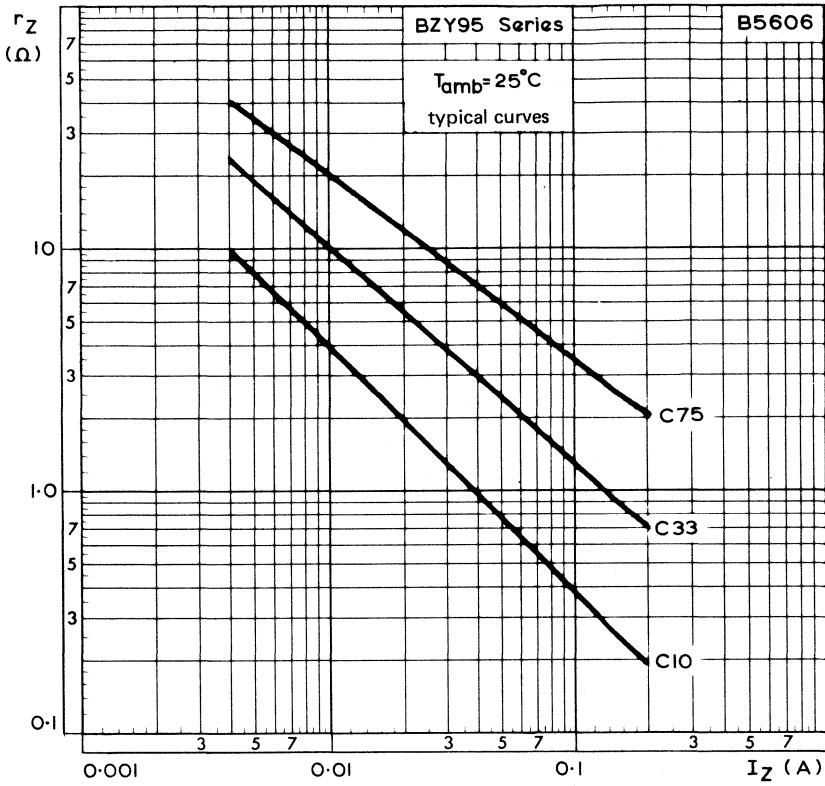


Fig. 13.

$V_{(CL)Rmax}$

25 (V) 20

15

10

D3809a  
5

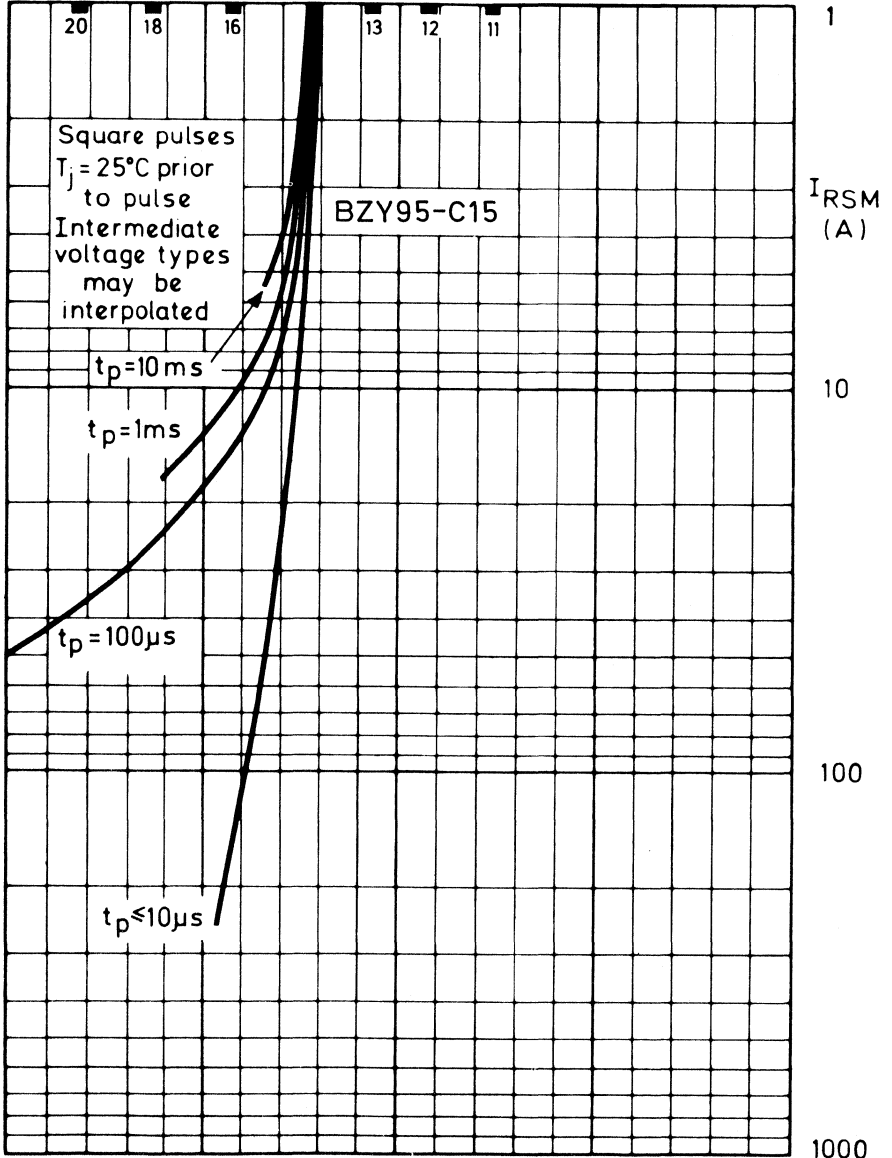


Fig. 14.



$V_{(CL)Rmax}$

D3810

125 (V)

100

75

50

25

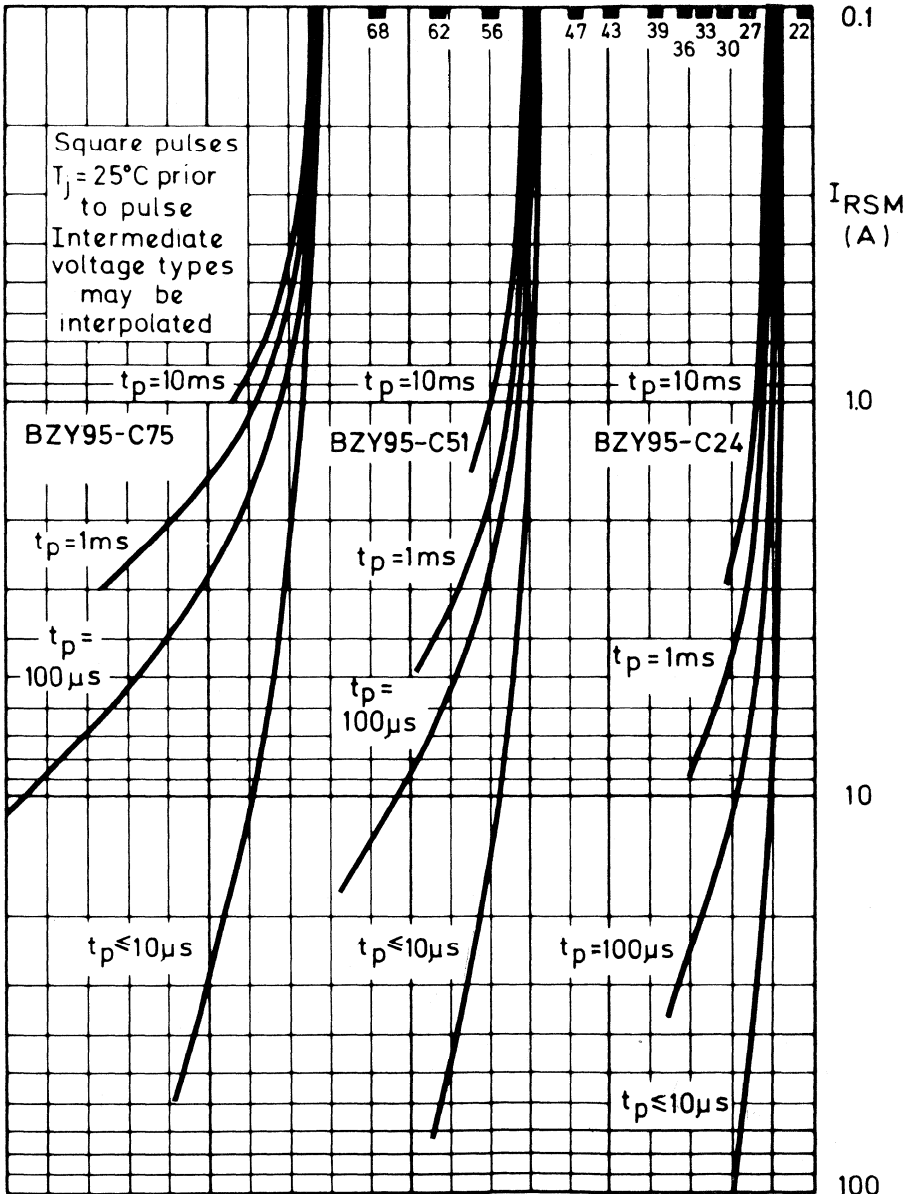


Fig. 15.

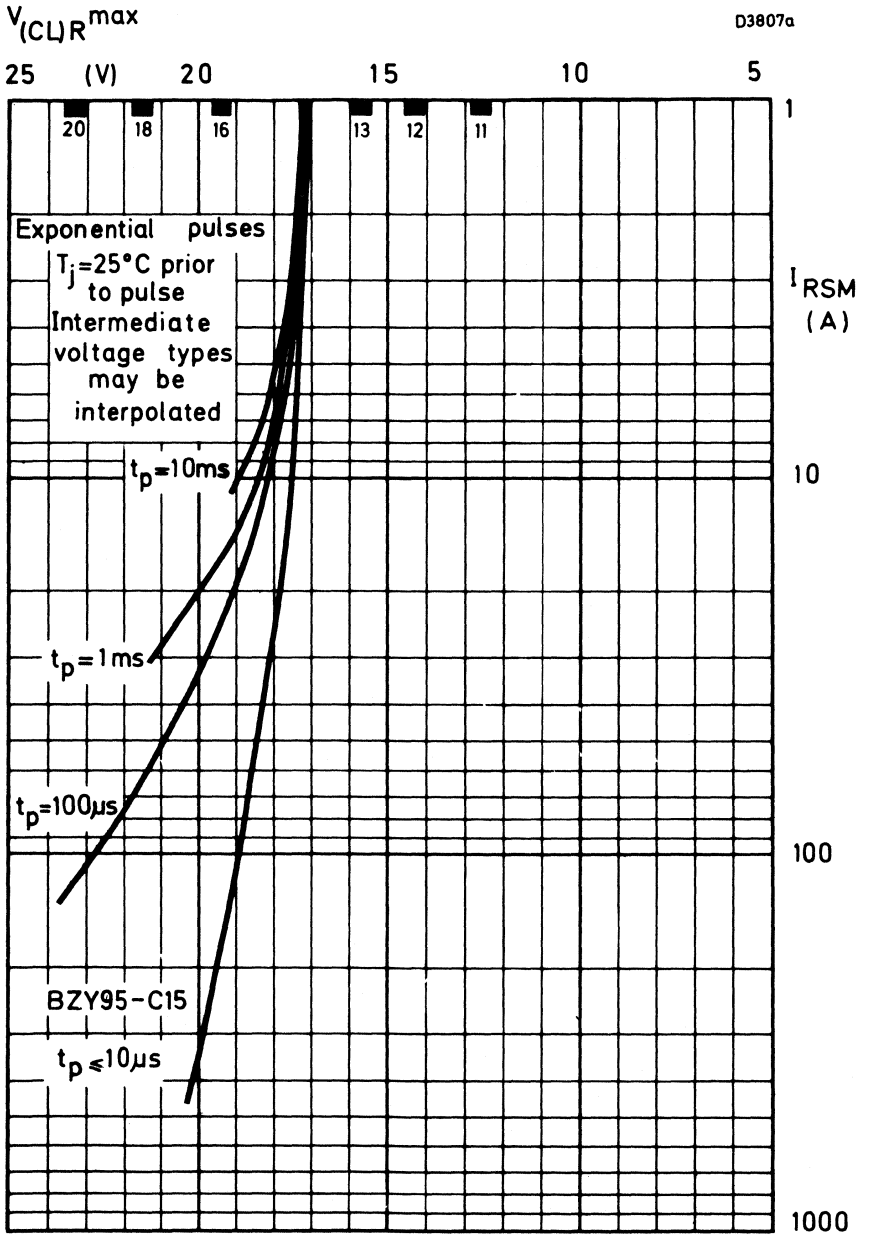


Fig. 16.

D3808

$V_{(CL)R}^{max}$

125 (V) 100 75 50 25

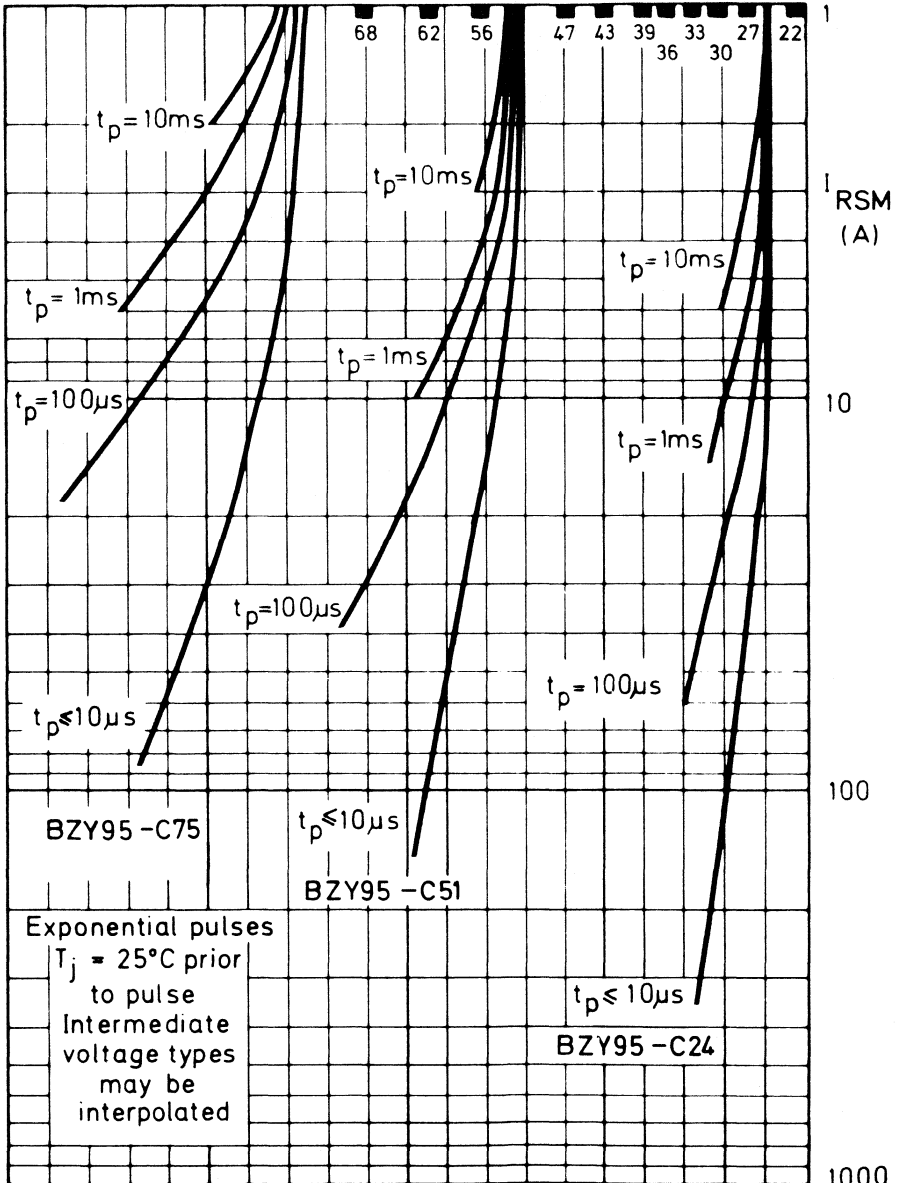


Fig. 17.

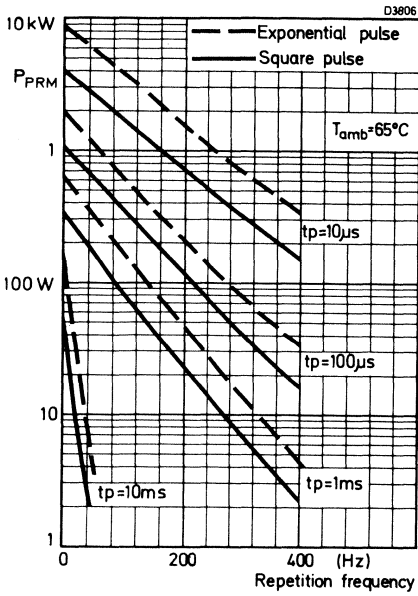


Fig. 18.

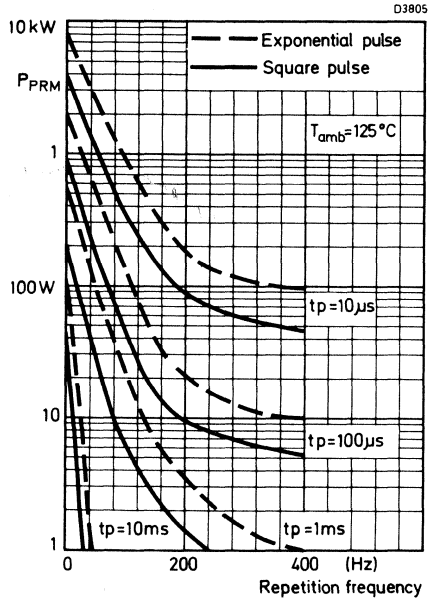


Fig. 19.

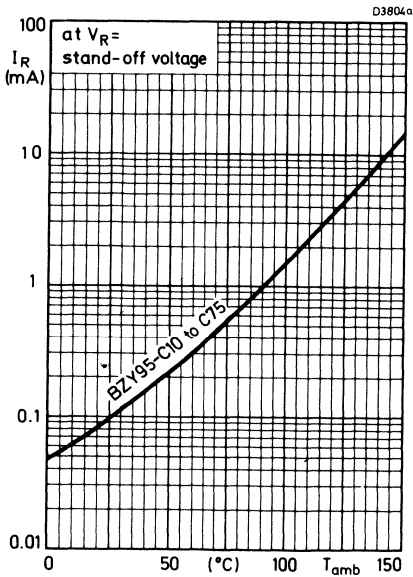


Fig. 20.

D3811

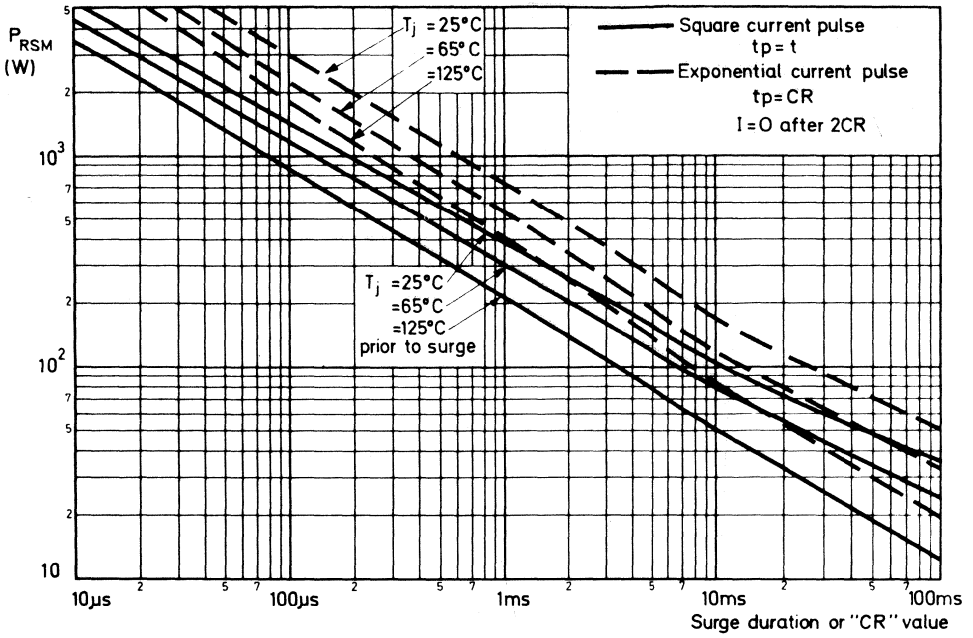


Fig. 21.



## REGULATOR DIODES

Also available to BS9305—F049

A range of alloyed silicon diodes in DO-1 envelopes, intended for use as voltage regulator and transient suppressor diodes in medium power regulators and transient suppression circuits.

The series consists of the following types: BZY96-C4V7 to BZY96-C9V1.

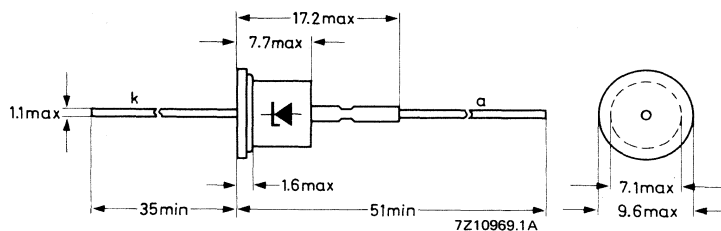
## QUICK REFERENCE DATA

			voltage regulator		transient suppressor	
Working voltage (5% range)	$V_Z$	nom.	4,7 to 9,1	—	—	V
Stand-off voltage	$V_R$		—	3,6 to 6,8	—	V
Total power dissipation	$P_{tot}$	max.	2,5	—	—	W
Non-repetitive peak reverse power dissipation	$P_{RSM}$	max.	—	190	—	W

## MECHANICAL DATA

Dimensions in mm

Fig. 1 DO-1.



## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

Peak working current	$I_{ZM}$	max.	3,5 A
Average forward current (averaged over any 20 ms period)	$I_{F(AV)}$	max.	1 A
Non-repetitive peak reverse current $T_j = 25\text{ }^\circ\text{C}$ prior to surge; $t_p = 1\text{ ms}$ (exponential pulse); BZY96-C4V7 to BZY96-C9V1	$I_{RSM}$	max.	22 to 12 A
Total power dissipation up to $T_{amb} = 25\text{ }^\circ\text{C}$ at $T_{amb} = 75\text{ }^\circ\text{C}$	$P_{tot}$	max.	2,5 W
	$P_{tot}$	max.	1,67 W
Non-repetitive peak reverse power dissipation $T_j = 25\text{ }^\circ\text{C}$ prior to surge; $t_p = 1\text{ ms}$ (exponential pulse)	$P_{RSM}$	max.	190 W
Storage temperature	$T_{stg}$		-65 to + 175 $^\circ\text{C}$
Junction temperature	$T_j$	max.	175 $^\circ\text{C}$

## THERMAL RESISTANCE

The quoted values of  $R_{th\ j-a}$  should be used only when no leads of other dissipating components run to the same tie-points.

Thermal resistance from junction to ambient in free air:

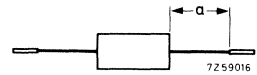
mounted on soldering tags

at lead length  $a = 10\text{ mm}$

at lead length  $a = \text{maximum}$

$$R_{th\ j-a} = 60\text{ }^\circ\text{C/W}$$

$$R_{th\ j-a} = 70\text{ }^\circ\text{C/W}$$



mounted on a printed-circuit board

at lead length  $a = \text{maximum}$

at lead length  $a = 10\text{ mm}$

$$R_{th\ j-a} = 80\text{ }^\circ\text{C/W}$$

$$R_{th\ j-a} = 90\text{ }^\circ\text{C/W}$$

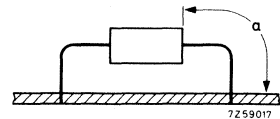


Fig. 2.

## CHARACTERISTICS

Forward voltage

$I_F = 1\text{ A}$ ;  $T_{amb} = 25\text{ }^\circ\text{C}$

$$V_F < 1,5\text{ V}$$



## CHARACTERISTICS

 $T_{amb} = 25^{\circ}\text{C}$ 

## WHEN USED AS VOLTAGE REGULATOR DIODES

BZY96... C4V7 C5V1 C5V6 C6V2 C6V8 C7V5 C8V2 C9V1	working voltage		differential resistance		temperature coefficient		test I <sub>Z</sub>		reverse current at voltage	
	min.	max.	*I <sub>Z</sub> Ω	typ. max.	*S <sub>Z</sub> mV/°C	typ.	mA	IR μA	VR V	
	4.4	5.0	2.5	10	-0.6		100	20	1.0	
	4.8	5.4	1.0	5.0	-0.4		100	20	1.0	
	5.2	6.0	0.7	4.0	+1.0		100	20	1.0	
	5.8	6.6	0.6	3.0	+2.0		100	20	2.0	
	6.4	7.2	0.6	3.0	+3.0		100	20	2.0	
	7.0	7.9	1.0	3.5	+4.0		50	20	3.0	
	7.7	8.7	1.2	3.5	+5.0		50	20	5.6	
	8.5	9.6	1.8	4.5	+6.4		50	20	6.2	

## WHEN USED AS TRANSIENT SUPPRESSOR DIODES

BZY96... C4V7 C5V1 C5V6 C6V2 C6V8 C7V5 C8V2 C9V1	clamping at voltage t <sub>p</sub> = 500 μs exp. pulse		non-repetitive peak reverse current		reverse current at recommended stand-off voltage	
	V <sub>(CL)R</sub> V	typ. max.	I <sub>RSM</sub> A	max.	IR mA	VR V
	6.5	7.8	10	2.0	2.0	3.6
	7.0	8.2	10	2.0	2.0	3.9
	7.5	8.8	10	0.2	0.2	4.3
	8.0	9.4	10	0.2	0.2	4.7
	8.5	10	10	0.2	0.2	5.1
	9.5	11	10	0.2	0.2	5.6
	11	13	10	0.1	0.1	6.2
	13	15	10	0.1	0.1	6.8

\* At test I<sub>Z</sub> using a pulse method with t<sub>p</sub> ≤ 100 μs and δ ≤ 0.001 so that the values correspond to a T<sub>j</sub> of approximately 25 °C

**OPERATION AS A VOLTAGE REGULATOR**

Dissipation and heatsink considerations

a. Steady-state conditions

The maximum permissible steady-state dissipation  $P_{s \max}$  is given by the relationship

$$P_{s \max} = \frac{T_{j \max} - T_{amb}}{R_{th \ j-a}}$$

where:  $T_{j \max}$  is the maximum permissible operating junction temperature  
 $T_{amb}$  is the ambient temperature  
 $R_{th \ j-a}$  is the total thermal resistance from junction to ambient

b. Pulse conditions (see Fig. 3)

The maximum permissible pulse power  $P_{p \max}$  is given by the formula

$$P_{p \max} = \frac{(T_{j \max} - T_{amb}) - (P_s \cdot R_{th \ t})}{R_{th \ t}}$$

Where:  $P_s$  is any steady-state dissipation excluding that in pulses

$R_{th \ t}$  is the effective transient thermal resistance of the device between junction and ambient.

It is a function of the pulse duration  $t_p$  and duty factor  $\delta$ .

$\delta$  is the duty factor ( $t_p/T$ )

The steady-state power  $P_s$  when biased in the zener direction at a given zener current can be found from Fig. 4. With the additional pulse power dissipation  $P_{p \max}$  calculated from the above expression, the total peak zener power dissipation  $P_{tot} = P_{ZRM} = P_s + P_p$ . From Fig. 4 the corresponding maximum repetitive peak zener current at  $P_{tot}$  can now be read. This repetitive peak zener current is subject to the absolute maximum rating. For pulse durations longer than the temperature stabilization time of the diode  $t_{stab}$ , the maximum permissible repetitive peak dissipation  $P_{ZRM}$  is equal to the steady-state power  $P_s$ . The temperature stabilization time for the BZY96 is 100 seconds (see Fig. 10).

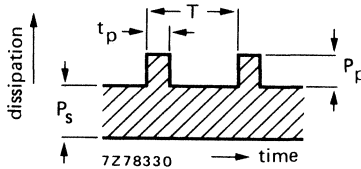


Fig. 3.

**NOTES WHEN OPERATING AS A TRANSIENT SUPPRESSOR**

1. The stand-off voltage is the maximum reverse voltage recommended for continuous operation; at this value non-conduction is ensured.
2. The maximum clamping voltage is the maximum reverse voltage which appears across the diode at the specified pulse duration and junction temperature. For square pulses see Fig. 13 and for exponential pulses see Fig. 14.
3. Duration of an exponential pulse is defined as the time taken for the pulse to fall to 37% of its initial value. It is assumed that the energy content does not continue beyond twice this time.
4. Surge suppressor diodes are extremely fast in clamping, switching on in less than 5 ns.

**SOLDERING AND MOUNTING INSTRUCTIONS**

1. When using a soldering iron, diodes may be soldered directly into the circuit, but heat conducted to the junction should be kept to a minimum.
2. Diodes may be dip-soldered at a solder temperature of 245 °C for a maximum soldering time of 5 seconds. The case temperature during dip-soldering must not at any time exceed the maximum storage temperature. These recommendations apply to a diode with the anode end mounted flush on a printed-circuit board having punched-through holes. For mounting the anode end onto a printed-circuit board, the diode must be spaced at least 5 mm from the underside of the printed-circuit board having punched-through holes, or 5 mm from the top of the printed-circuit board having plated-through holes.
3. Care should be taken not to bend the leads nearer than 1,5 mm from the seal; exert no axial pull when bending.

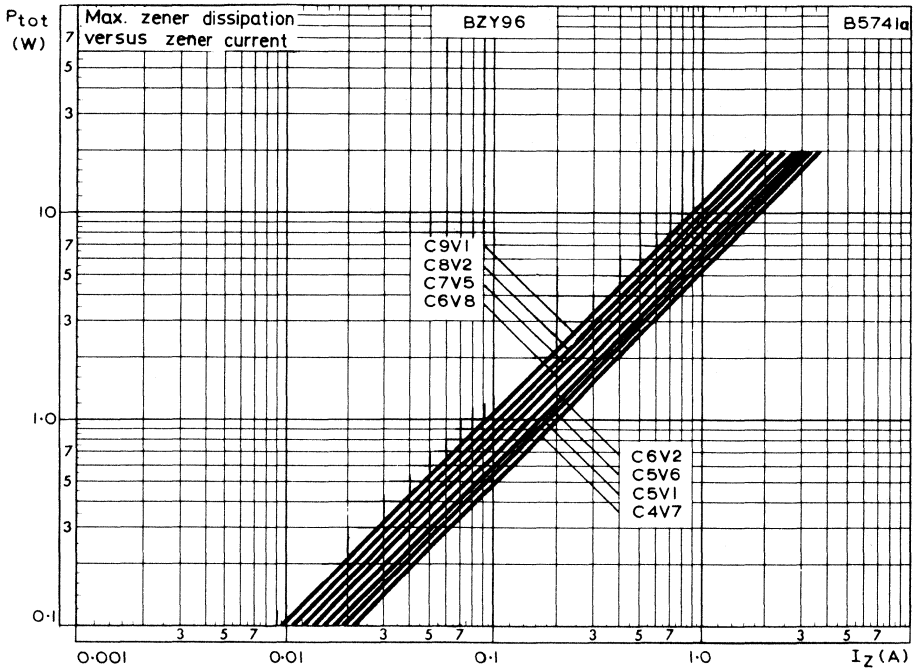


Fig. 4 Maximum permissible repetitive peak dissipation ( $P_{tot} = P_{ZRM}$ ).

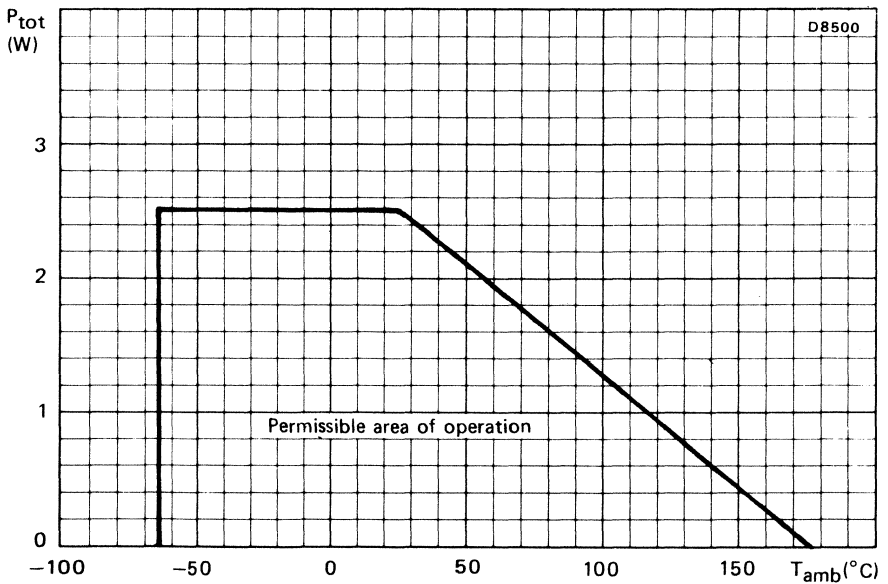


Fig. 5 Maximum permissible total power dissipation versus ambient temperature.

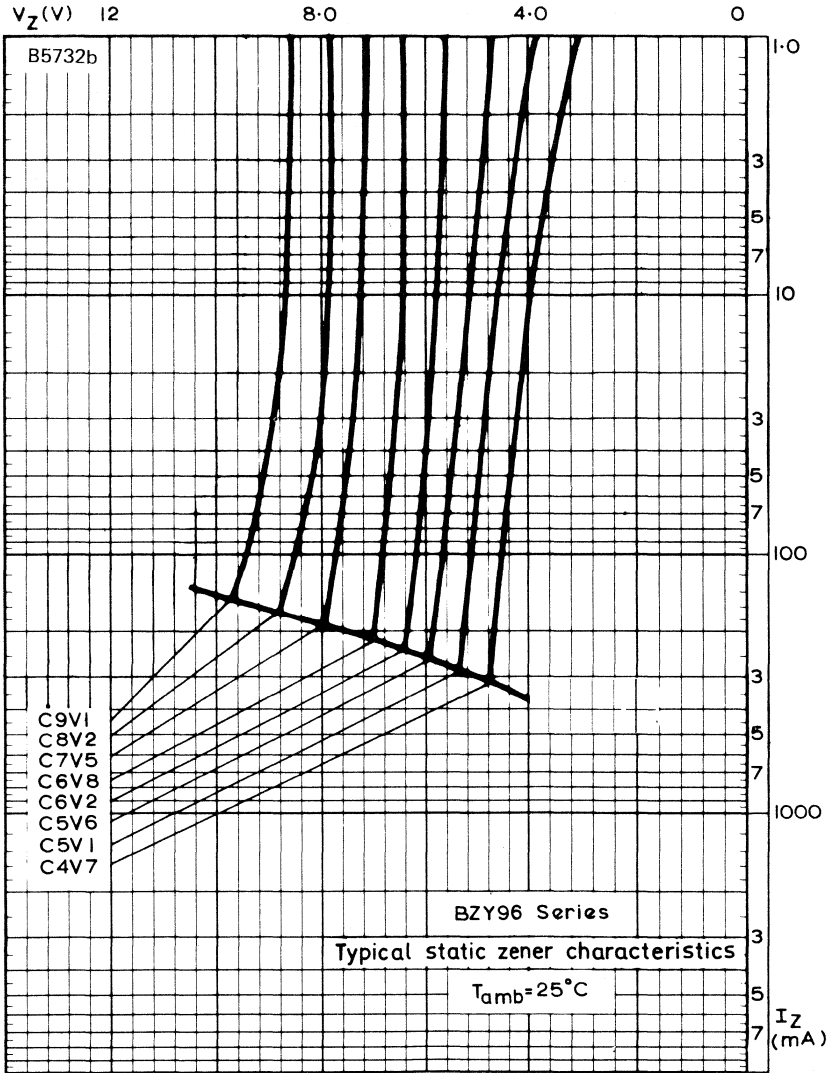


Fig. 6 Typical static zener characteristics.

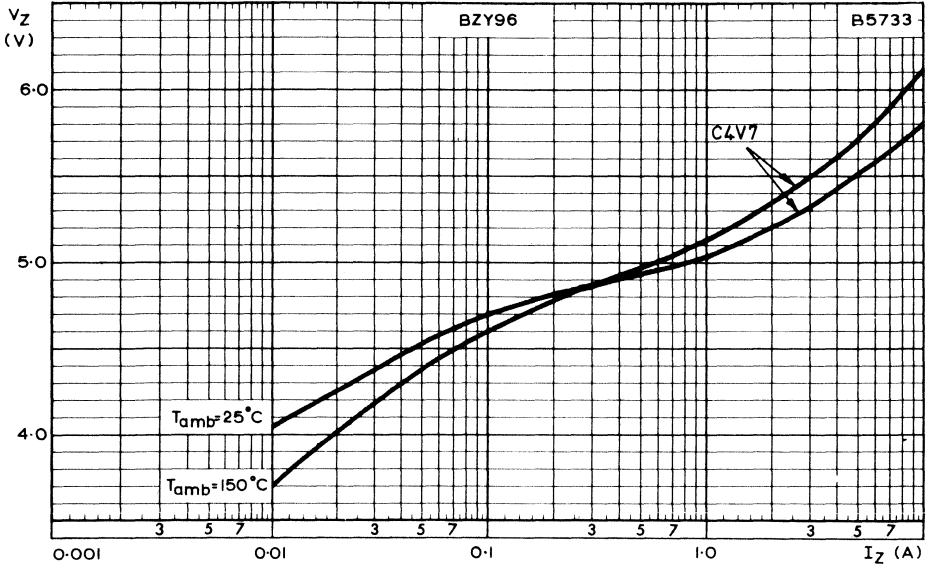


Fig. 7 Typical dynamic zener characteristics for BZY96-C4V7.

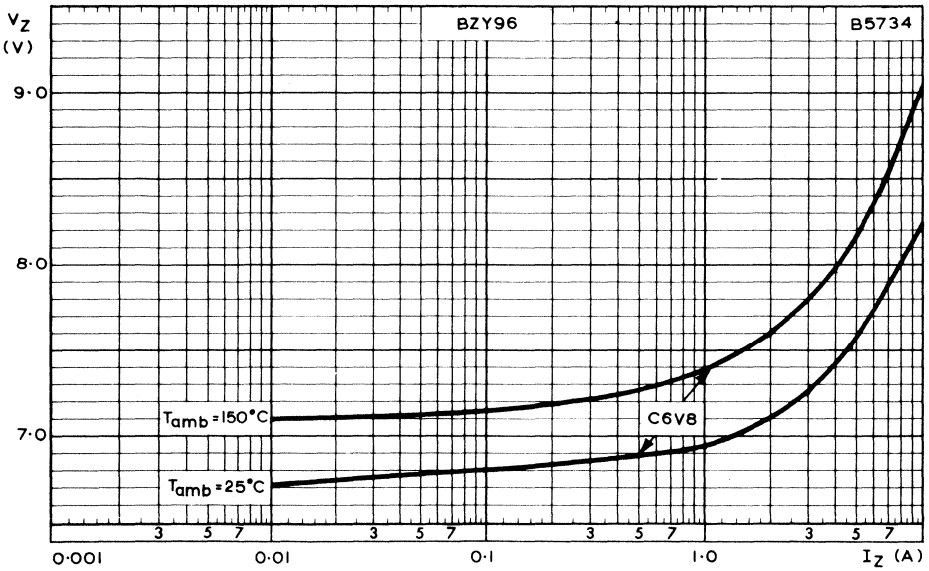


Fig. 8 Typical dynamic zener characteristics for BZY96-C6V8.

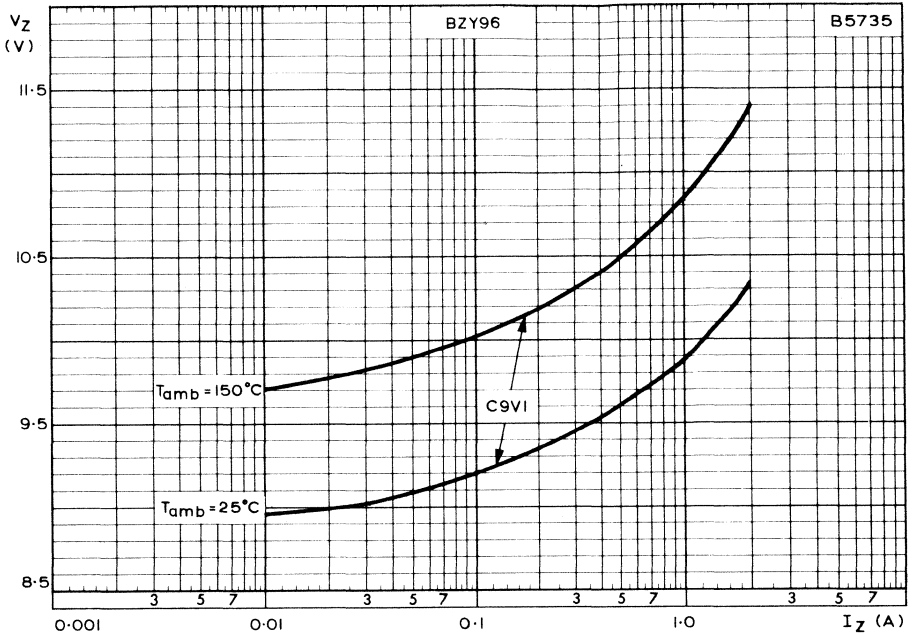
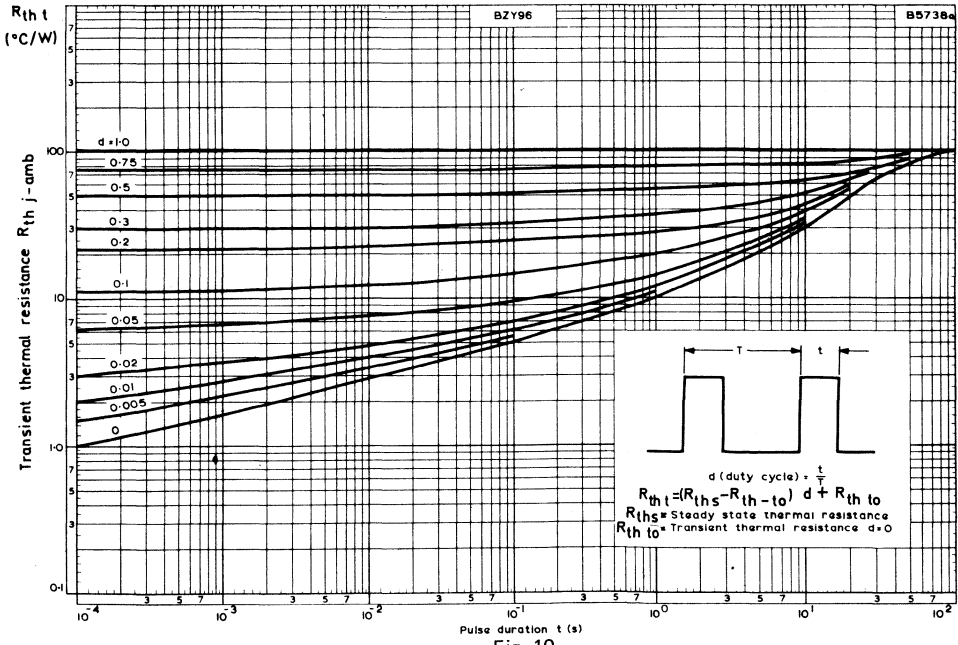


Fig. 9 Typical dynamic zener characteristics for BZY96-C9V1.



$$d \text{ (duty cycle)} = \frac{t}{T}$$

$$R_{thj} = (R_{thj} - R_{th0}) d + R_{th0}$$

$R_{thj}$  = Steady state thermal resistance  
 $R_{th0}$  = Transient thermal resistance  $d=0$

Fig. 10.

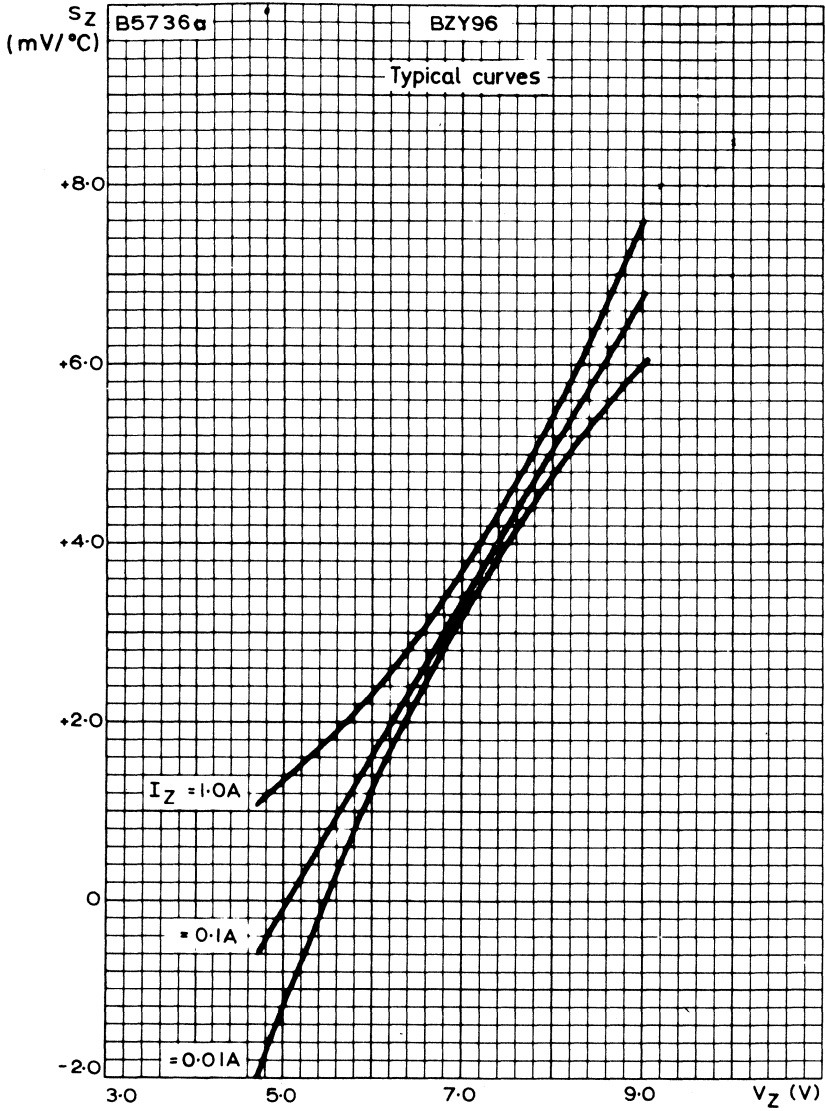


Fig. 11.



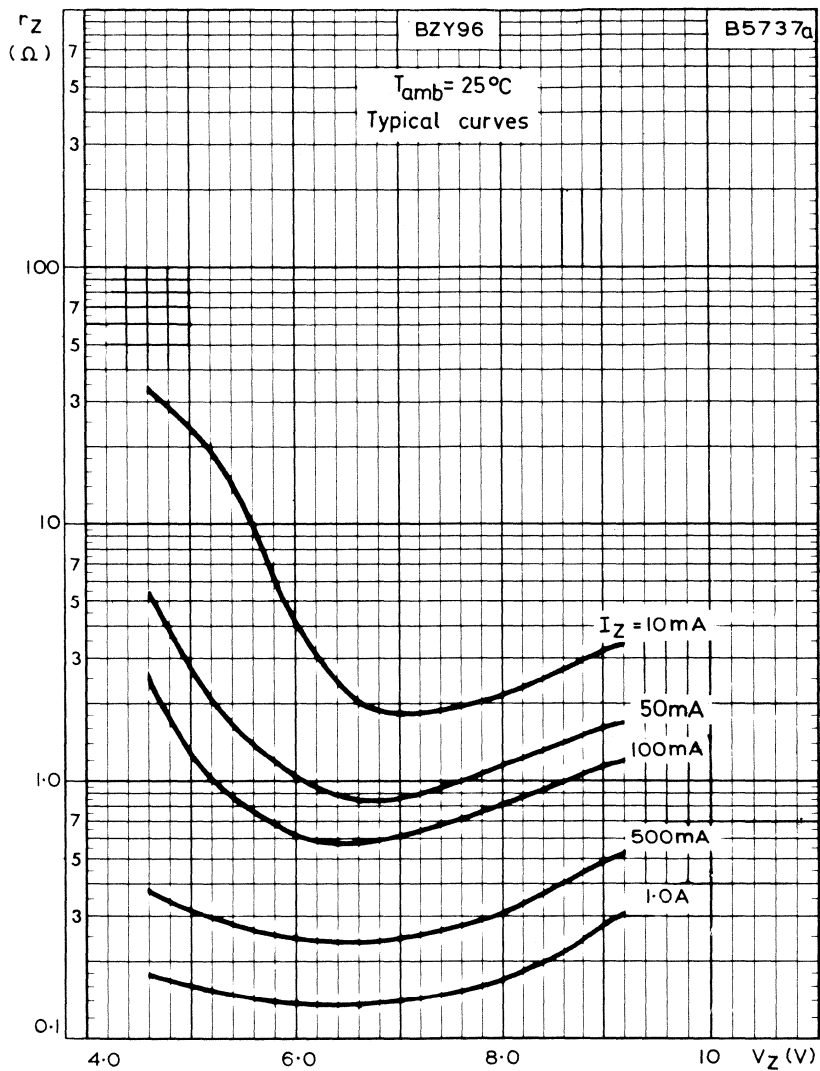


Fig. 12.

$V_{(CL)Rmax}$

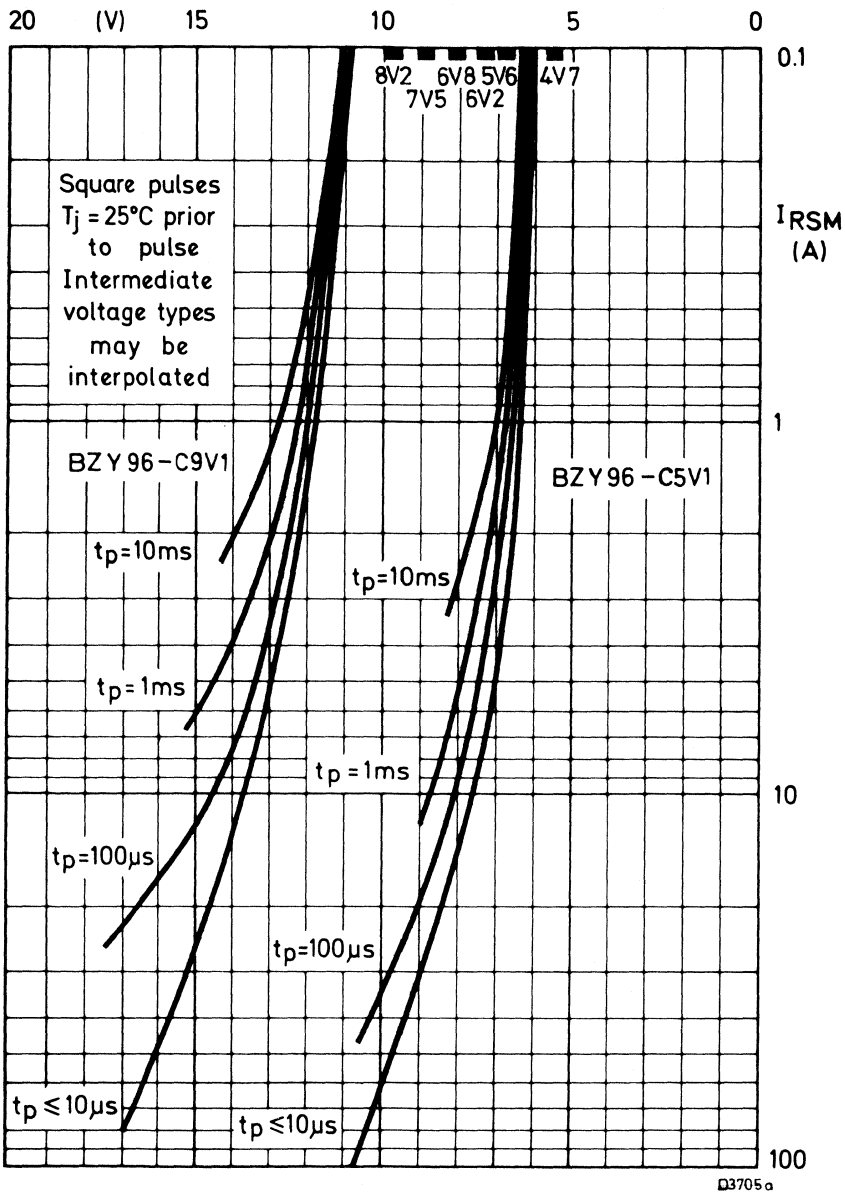


Fig. 13.

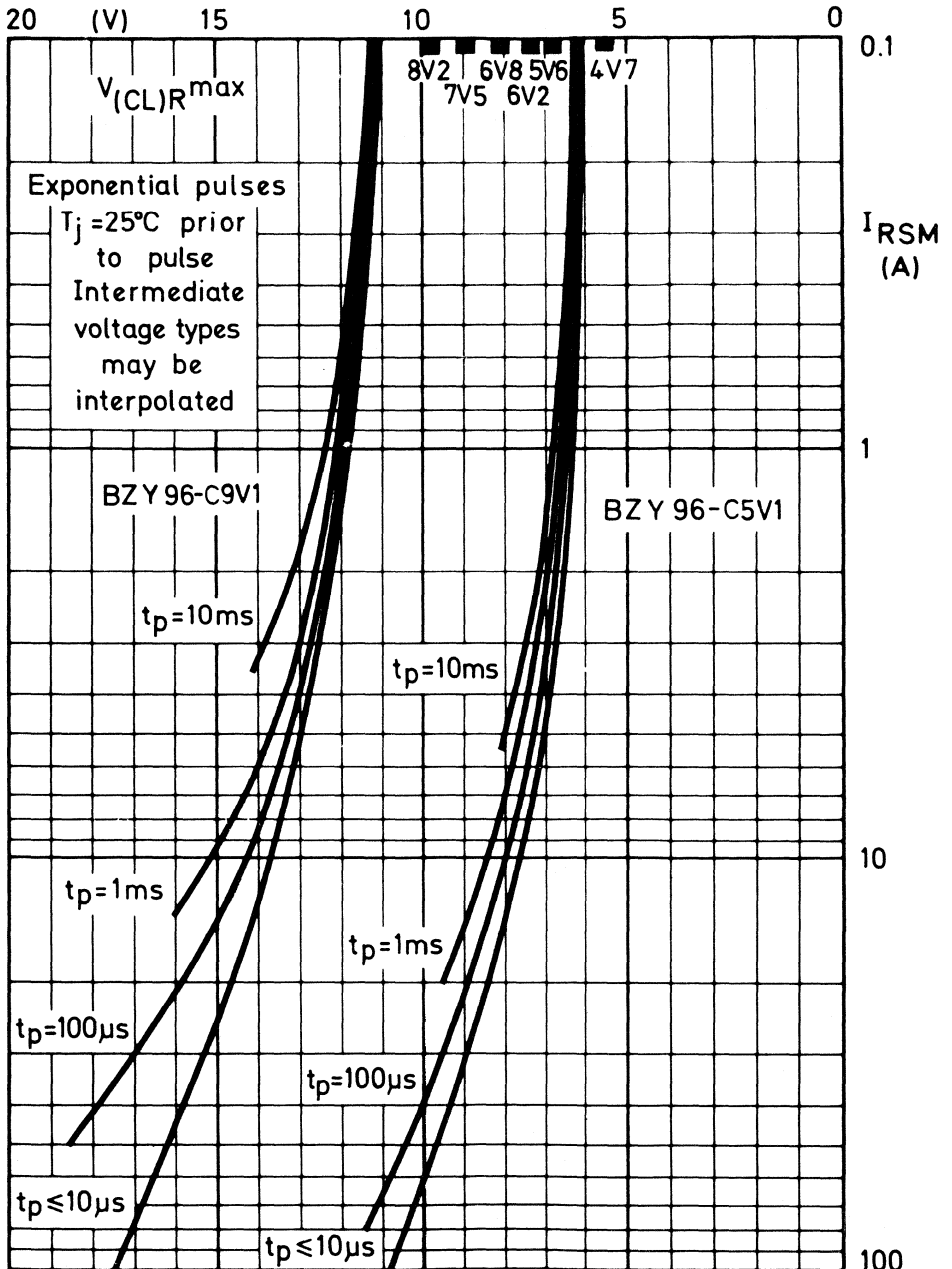


Fig. 14.

D3704a

# BZY96 SERIES

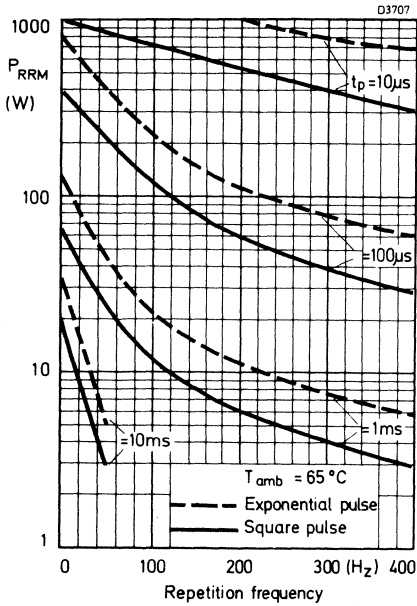


Fig. 15.

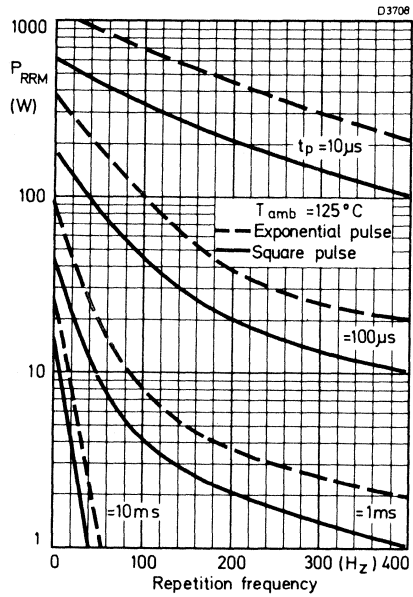


Fig. 16.

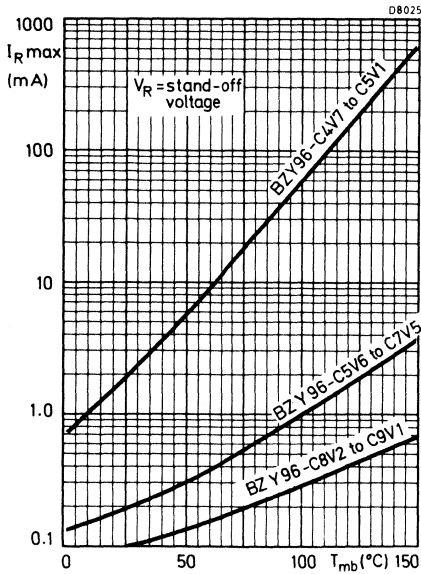


Fig. 17.

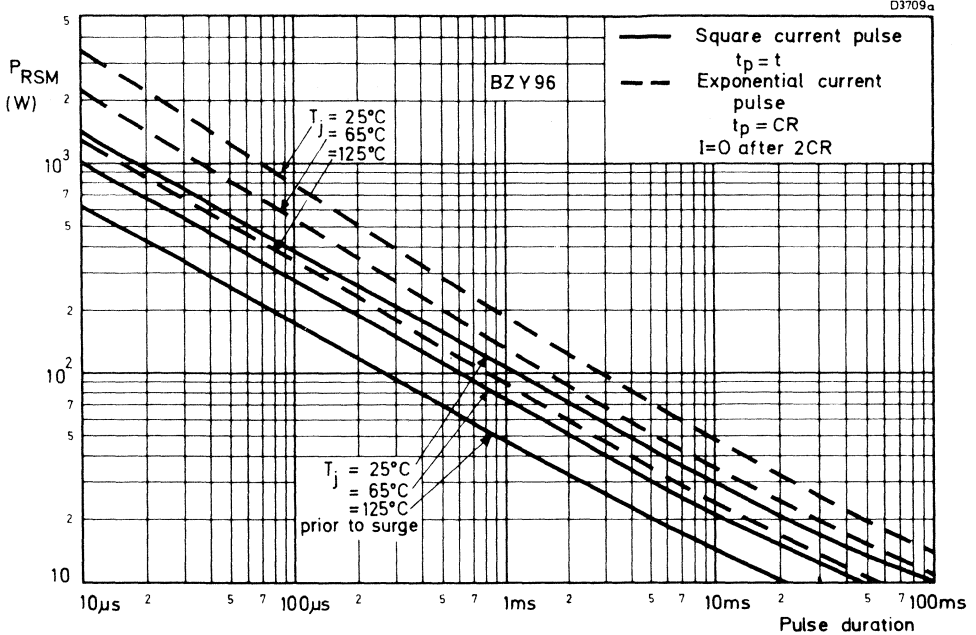


Fig. 18.



# **HIGH-VOLTAGE RECTIFIER STACKS**

**D**



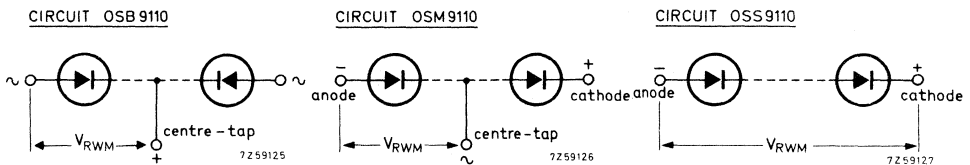
**D**



## HIGH VOLTAGE RECTIFIER STACKS

The OSB9110, OSM9110 and OSS9110series are ranges of high voltage rectifier assemblies, incorporating controlled avalanche diodes mounted on fire proof triangular formers. The OSB9110series is intended for application in two phase half wave rectifier circuits. The OSM9110series is intended for application in single phase or three phase bridges or in voltage doubler circuits.

The OSS9110series is intended for all kinds of high voltage rectification. The assemblies are supplied with M6 studs or with standard valve bases. The OSB9110-series and OSM9110series are supplied with a centre tap (8-32UNC). The maximum crest working voltages of the OSB9110 and OSM9110series cover the range from 2 kV to 15 kV, and of the OSS9110series the range from 3 kV to 30 kV, in 1 kV steps.



### QUICK REFERENCE DATA

Crest working reverse voltage from centre tap to end	$V_{RWM}$	OSB9110 -4 -6	...	-28 -30
		OSM9110-4 -6	...	-28 -30
		max. 2 3	...	14 15 kV
Crest working reverse voltage	$V_{RWM}$	OSS9110 -3 -4	...	-29 -30
		max. 3 4	...	29 30 kV
Average forward current with R and L load (averaged over any 20 ms period)				
		in free air up to $T_{amb} = 35^{\circ}C$	$I_{F(AV)}$	max. 3.5 A
		in oil up to $T_{oil} = 100^{\circ}C$	$I_{F(AV)}$	max. 6 A
Non-repetitive peak forward current $t = 10ms$ ; half sine wave; $T_j = 175^{\circ}C$ prior to surge			$I_{FSM}$	max. 125 A

MECHANICAL DATA see pages 4 and 5.

All information applies to frequencies up to 400 Hz

**RATINGS** Limiting values in accordance with the Absolute Maximum System (IEC 134)

		OSB9110 -4 -6		...	-28 -30	
<u>Voltages</u>		OSM9110-4 -6		...	-28 -30	
Crest working reverse voltage	$V_{RWM}$	max.	2 3	...	14	15 kV

		OSS9110 -3 -4		...	-29 -30	
Crest working reverse voltage	$V_{RWM}$	max.	3 4	...	29	30 kV

Currents

Average forward current (averaged over any 20 ms period)						
in free air up to $T_{amb} = 35\text{ }^{\circ}\text{C}$		$I_{F(AV)}$	max.	3.5	A	
in oil up to $T_{oil} = 100\text{ }^{\circ}\text{C}$		$I_{F(AV)}$	max.	6	A	
Repetitive peak forward current		$I_{FRM}$	max.	120	A	
Non-repetitive peak forward current						
$t = 10\text{ ms}$ ; half sine wave; $T_j = 175\text{ }^{\circ}\text{C}$ prior to surge		$I_{FSM}$	max.	125	A	

Reverse power dissipation

		OSB9110 -4 -6		...	-28 -30	
		OSM9110-4 -6		...	-28 -30	
Repetitive peak reverse power						
$t = 10\text{ }\mu\text{s}$ (square wave; $f = 50\text{ Hz}$ )						
$T_j = 175\text{ }^{\circ}\text{C}$	$P_{RRM}$	max.	1.2 1.8	...	8.4	9 kW

Non-repetitive peak reverse power						
$t = 10\text{ }\mu\text{s}$ (square wave)						
$T_j = 25\text{ }^{\circ}\text{C}$ prior to surge	$P_{RSM}$	max.	6 9	...	42	45 kW
$T_j = 125\text{ }^{\circ}\text{C}$ prior to surge	$P_{RSM}$	max.	1.2 1.8	...	8.4	9 kW

		OSS9110 -3 -4		...	-29 -30	
Repetitive peak reverse power dissipation						
$t = 10\text{ }\mu\text{s}$ (square wave; $f = 50\text{ Hz}$ )						
$T_j = 175\text{ }^{\circ}\text{C}$	$P_{RRM}$	max.	1.8 2.4	...	17.4	18 kW

Non-repetitive peak reverse power dissipation						
$t = 10\text{ }\mu\text{s}$ (square wave)						
$T_j = 25\text{ }^{\circ}\text{C}$ prior to surge	$P_{RSM}$	max.	9 12	...	87	90 kW
$T_j = 175\text{ }^{\circ}\text{C}$ prior to surge	$P_{RSM}$	max.	1.8 2.4	...	17.4	18 kW

Temperatures

Storage temperature	$T_{stg}$	-55 to +175	$^{\circ}\text{C}$
Junction temperature	$T_j$	max.	175 $^{\circ}\text{C}$

**CHARACTERISTICS** (See note 1)

		OSB9110 -4 -6	...	-28	-30
<u>Forward voltage</u>		OSM9110-4 -6	...	-28	-30
$I_F = 20 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$	$V_F$	< 4 6	...	28	30 V
<u>Reverse avalanche breakdown voltage</u> <sup>1)</sup>					
$I_R = 5 \text{ mA}; T_j = 25 \text{ }^\circ\text{C}$	$V_{(BR)R}$	> 2.5 3.75	...	17.5	18.75 kV
		< 3.76 5.64	...	26.32	28.2 kV
<u>Forward voltage</u>		OSS9110 -3 -4	...	-29	-30
$I_F = 20 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$	$V_F$	< 6 8	...	58	60 V
<u>Reverse avalanche breakdown voltage</u> <sup>1)</sup>					
$I_R = 5 \text{ mA}; T_j = 25 \text{ }^\circ\text{C}$	$V_{(BR)R}$	> 3.75 5.0	...	36.25	37.5 kV
		< 5.64 7.52	...	54.52	56.4 kV
<u>Reverse current</u>					
$V_{RM} = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$	$I_{RM}$	< 0.6 mA			

**NOTES**

1. The Ratings and Characteristics given apply from centre tap to end. (Not for OSS9110series)

2. Type number suffix

The suffix consists of a figure indicating the total number of diodes, followed by a letter indicating the base.

A = M6 studs at the ends

B = 4 pin Super Jumbo (B4D)

C = Goliath

E = 4 pin Jumbo (B4F)

F = A3-20

3. Operating position

The rectifier units can be operated at their maximum ratings when mounted in any position.

<sup>1)</sup> The breakdown voltage increases by approximately 0.1% per  $^\circ\text{C}$  with increasing junction temperature.

**OSB 9110 SERIES**  
**OSM9110 SERIES**  
**OSS 9110 SERIES**

**MECHANICAL DATA**

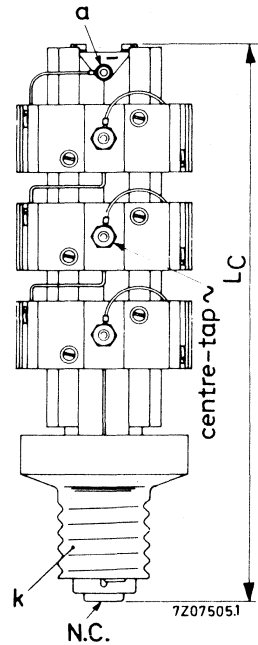
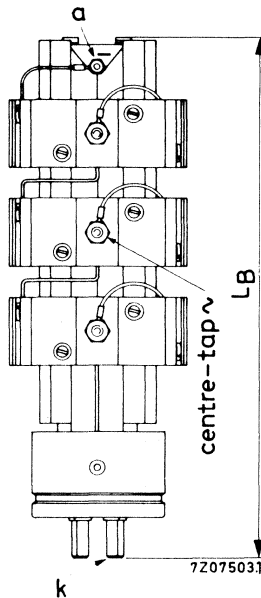
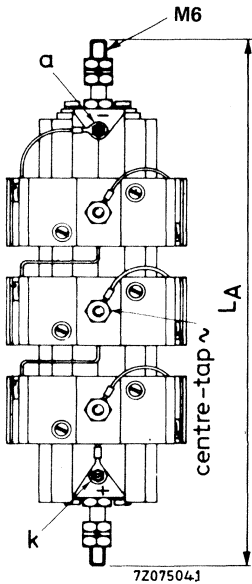
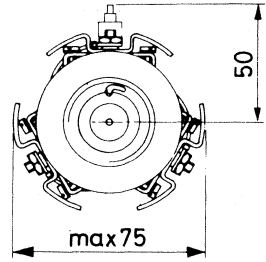
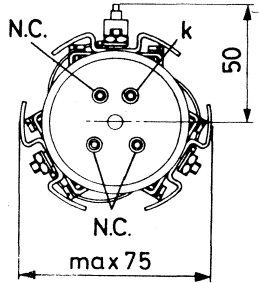
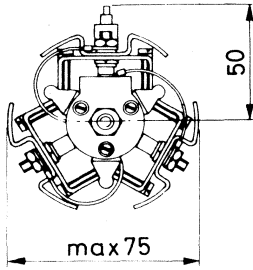
n = total number of diodes

Dimensions in mm

OSM9110-nA

OSM9110-nB

OSM9110-nC



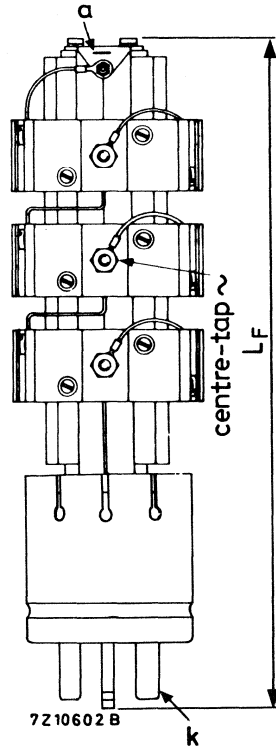
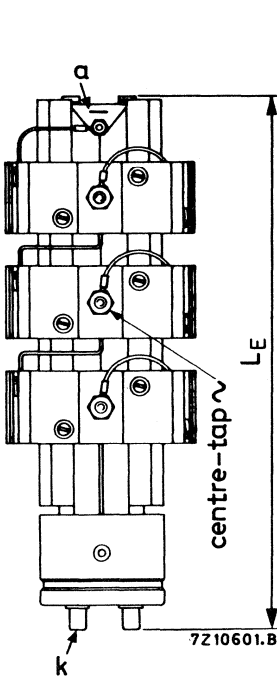
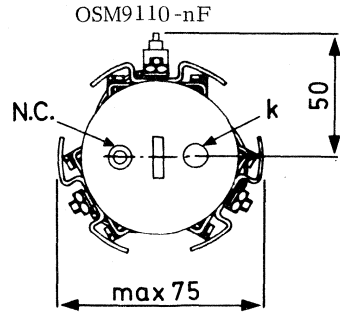
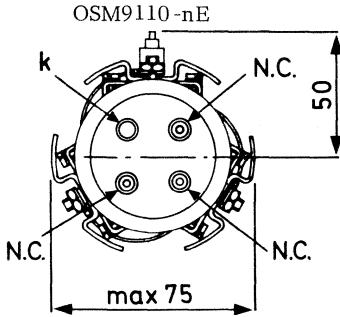
The drawings show the OSM9110series; the OSB9110 and OSS9110series differ in the following respects:

OSB9110series - terminals marked a(-) and k(+) in the drawings are both marked ~ ;  
the centre-tap is marked + (instead of ~ as in the drawings).

OSS9110series - has no centre-tap.

**MECHANICAL DATA** (continued)

n = total number of diodes.



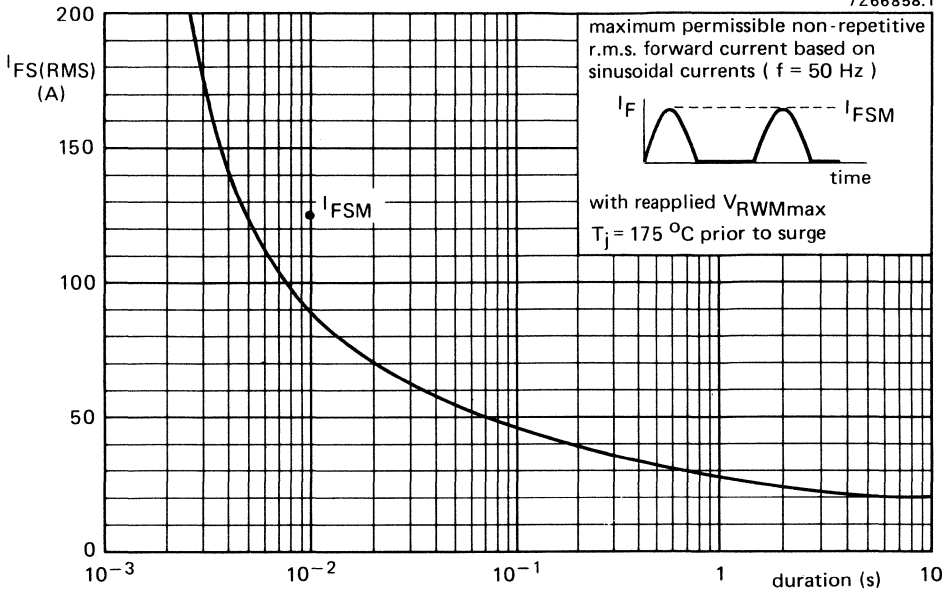
For lengths and weights see table on page 6.

Table of lengths and weights (mm and g)

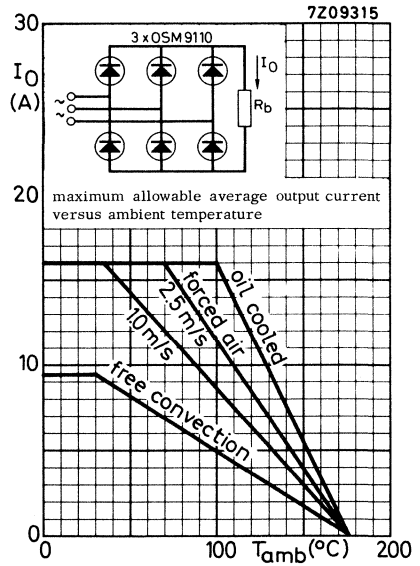
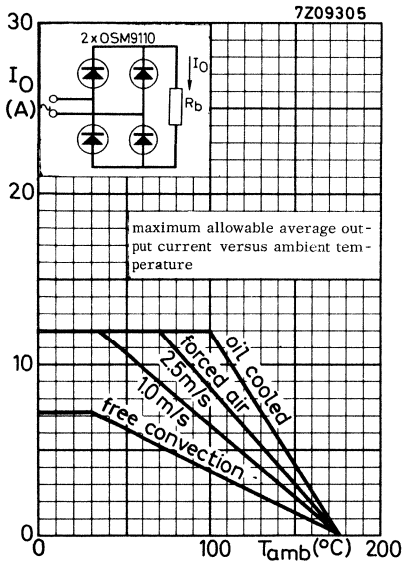
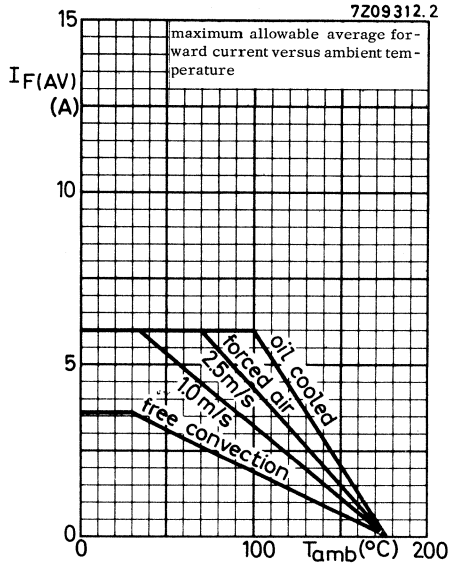
number of diodes	n	3	4 to 6	7 to 9	10 to 12	13 to 15
maximum lengths	$L_A$	143	184	224	264	305
	$L_B$	147	188	228	268	309
	$L_C$	159	199	239	279	320
	$L_E$	132	173	213	253	294
	$L_F$	184	225	265	305	346
weights	$W_A$	153	286	419	552	685
	$W_B = W_C = W_E$	218	351	484	617	750
	$W_F$	379	512	645	778	911

number of diodes	n	16 to 18	19 to 21	22 to 24	25 to 27	28 to 30
maximum lengths	$L_A$	345	385	426	466	506
	$L_B$	349	389	430	470	510
	$L_C$	360	400	441	481	521
	$L_E$	334	374	415	455	495
	$L_F$	386	426	467	507	547
weights	$W_A$	818	951	1048	1217	1350
	$W_B = W_C = W_E$	883	1016	1149	1282	1415
	$W_F$	1044	1177	1310	1443	1576

7Z66858.1



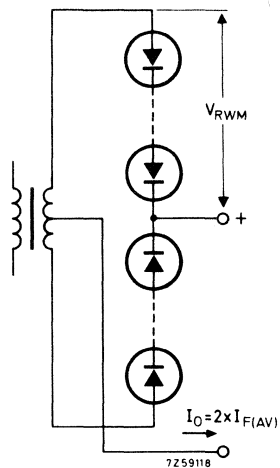
**OSB9110SERIES**  
**OSM9110SERIES**  
**OSS9110SERIES**



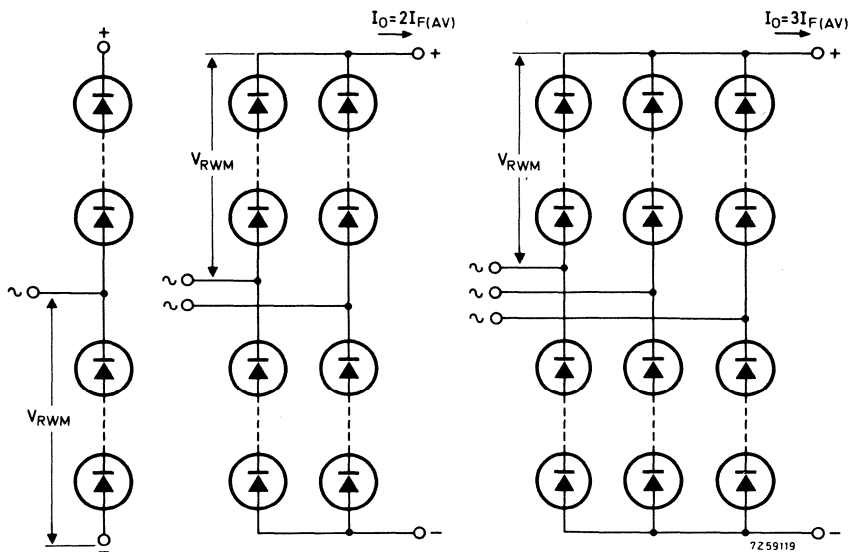


**APPLICATION INFORMATION**

OSB9110-4



OSM9110series



voltage doubler  
1x OSM 9110

rectifier circuits with 2x OSM9110 and 3x OSM9110 respectively

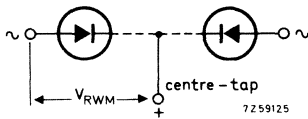


## HIGH VOLTAGE RECTIFIER STACKS

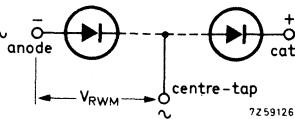
The OSB9210, OSM9210 and OSS9210 series are ranges of high voltage rectifier assemblies, incorporating controlled avalanche diodes mounted on fire proof triangular formers. The OSB9210 series is intended for application in two phase half wave rectifier circuits. The OSM9210 series is intended for application in single phase or three phase bridges or in voltage doubler circuits.

The OSS9210 series is intended for all kinds of high voltage rectification. The assemblies are supplied with M6 studs or with standard valve bases. The OSB9210 series and OSM9210 series are supplied with a centre tap (8-32UNC). The maximum crest working voltages of the OSB9210 and OSM9210 series cover the range from 2 kV to 15 kV, and of the OSS9210 series the range from 3 kV to 30 kV, in 1 kV steps.

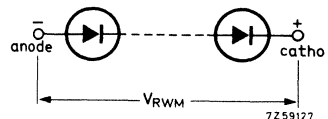
CIRCUIT OSB9210



CIRCUIT OSM9210



CIRCUIT OSS9210



### QUICK REFERENCE DATA

				OSB9210 -4 -6	...	-28 -30	
				OSM9210-4 -6	...	-28 -30	
Crest working reverse voltage from centre tap to end	$V_{RWM}$	max.	2 3	...	14	15 kV	
Crest working reverse voltage	$V_{RWM}$			OSS9210 -3 -4	...	-29 -30	
		max.	3 4	...	29	30 kV	
Average forward current with R and L load (averaged over any 20 ms period)							
				in free air up to $T_{amb} = 35\text{ }^{\circ}\text{C}$	$I_{F(AV)}$	max.	5 A
				in oil up to $T_{oil} = 30\text{ }^{\circ}\text{C}$	$I_{F(AV)}$	max.	20 A
Non-repetitive peak forward current $t = 10\text{ ms}$ ; half sine wave; $T_j = 175\text{ }^{\circ}\text{C}$ prior to surge							
					$I_{FSM}$	max.	360 A

**MECHANICAL DATA** see page 4 and 5

**OSB9210SERIES**  
**OSM9210SERIES**  
**OSS 9210 SERIES**

All information applies to frequencies up to 400 Hz

**RATINGS** Limiting values in accordance with the Absolute Maximum System (IEC 134)

<u>Voltages</u>		OSB9210 -4 -6	...	-28 -30
		OSM9210-4 -6	...	-28 -30
Crest working reverse voltage	$V_{RWM}$	max. 2 3	...	14 15 kV
<u>Currents</u>		OSS9210 -3 -4	...	-29 -30
Crest working reverse voltage	$V_{RWM}$	max. 3 4	...	29 30 kV

Currents

Average forward current (averaged over any 20 ms period)				
in free air up to $T_{amb} = 35\text{ }^{\circ}\text{C}$		$I_{F(AV)}$	max.	5 A
in oil up to $T_{oil} = 30\text{ }^{\circ}\text{C}$		$I_{F(AV)}$	max.	20 A
Repetitive peak forward current		$I_{FRM}$	max.	440 A
Non-repetitive peak forward current				
$t = 10\text{ ms}$ ; half sine wave; $T_j = 175\text{ }^{\circ}\text{C}$ prior to surge		$I_{FSM}$	max.	360 A

Reverse power dissipation

Repetitive peak reverse power		OSB9210 -4 -6	...	-28 -30
$t = 10\text{ }\mu\text{s}$ (square wave; $f = 50\text{ Hz}$ )		OSM9210-4 -6	...	-28 -30
$T_j = 175\text{ }^{\circ}\text{C}$	$P_{RRM}$	max. 4 6	...	28 30 kW
Non-repetitive peak reverse power				
$t = 10\text{ }\mu\text{s}$ (square wave)				
$T_j = 25\text{ }^{\circ}\text{C}$ prior to surge	$P_{RSM}$	max. 26 39	...	182 195 kW
$T_j = 175\text{ }^{\circ}\text{C}$ prior to surge	$P_{RSM}$	max. 4 6	...	28 30 kW
Repetitive peak reverse power dissipation		OSS9210 -3 -4	...	-29 -30 kW
$t = 10\text{ }\mu\text{s}$ (square wave; $f = 50\text{ Hz}$ )				
$T_j = 175\text{ }^{\circ}\text{C}$	$P_{RRM}$	max. 6 8	...	58 60 kW
Non-repetitive peak reverse power dissipation				
$t = 10\text{ }\mu\text{s}$ (square wave)				
$T_j = 25\text{ }^{\circ}\text{C}$ prior to surge	$P_{RSM}$	max. 39 52	...	377 390 kW
$T_j = 175\text{ }^{\circ}\text{C}$ prior to surge	$P_{RSM}$	max. 6 8	...	58 60 kW

Temperatures

Storage temperature	$T_{stg}$	-55 to +175 $^{\circ}\text{C}$
Junction temperature	$T_j$	max. 175 $^{\circ}\text{C}$

**CHARACTERISTICS** (See note 1)

		OSB9210 -4 -6	...	-28 -30
		OSM9210-4 -6	...	-28 -30
<u>Forward voltage</u>				
$I_F = 50 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$	$V_F$	< 3.6 5.4	...	25.2 27 V
<u>Reverse breakdown voltage</u> <sup>1)</sup>				
$I_R = 5 \text{ mA}; T_j = 25 \text{ }^\circ\text{C}$	$V_{(BR)R}$	> 2.5 3.75 < 3.76 5.64	...	17.5 18.75 kV 26.32 28.2 kV

		OSS9210 -3 -4	...	-29 -30
<u>Forward voltage</u>				
$I_F = 50 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$	$V_F$	< 5.4 7.2	...	52.2 54 V
<u>Reverse breakdown voltage</u> <sup>1)</sup>				
$I_R = 5 \text{ mA}; T_j = 25 \text{ }^\circ\text{C}$	$V_{(BR)R}$	> 3.75 5.0 < 5.64 7.52	...	36.25 37.5 kV 54.52 56.4 kV

Reverse current

$$V_{RM} = V_{RWM} \text{ max}; T_j = 125 \text{ }^\circ\text{C} \quad I_{RM} < 0.6 \text{ mA}$$

**NOTES**

1. The Ratings and Characteristics given apply from centre tap to end. (Not for OSS9210series).
2. Type number suffix

The suffix consists of a figure indicating the total number of diodes, followed by a letter indicating the base.

- A = M6 studs at the ends
- B = 4 pin Super Jumbo (B4D)
- C = Goliath
- E = 4 pin Jumbo (B4F)
- F = A3-20

3. Operating position

The rectifier units can be operated at their maximum ratings when mounted in any position.

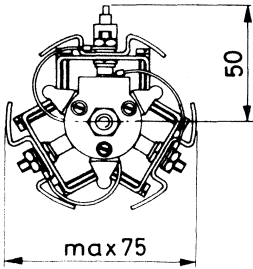
<sup>1)</sup> The breakdown voltage increases by approximately 0.1% per  $^\circ\text{C}$  with increasing junction temperature.

MECHANICAL DATA

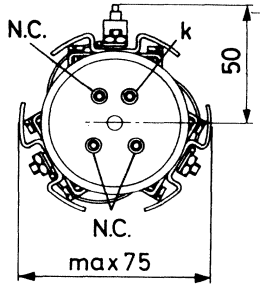
n = total number of diodes

Dimensions in mm

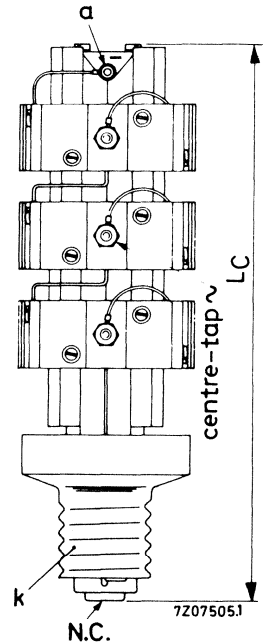
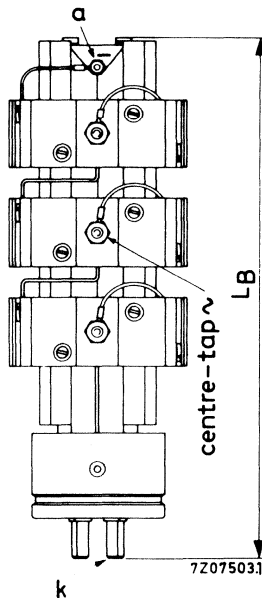
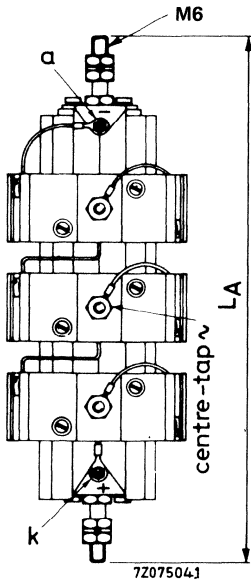
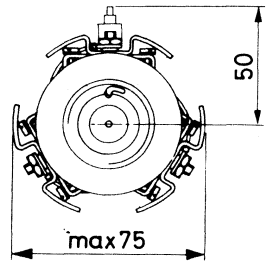
OSM9210-nA



OSM9210-nB



OSM9210-nC



The drawings show the OSM9210series; the OSB9210 and OSS9210series differ in the following respects:

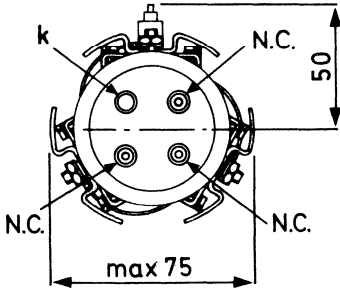
OSB9210series - terminals marked a(-) and k(+) in the drawings are both marked ~; the centre-tap is marked + (instead of ~ as in the drawings).

OSS9210series - has no centre-tap.

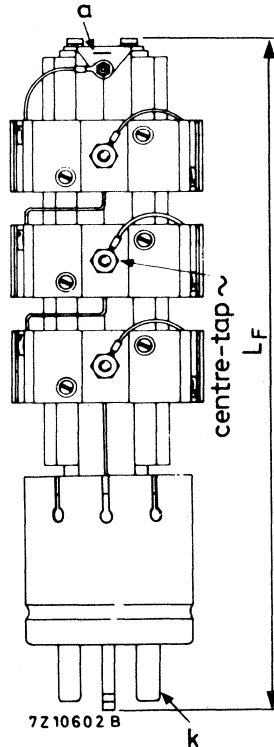
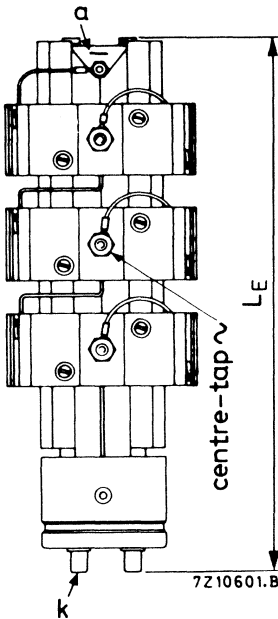
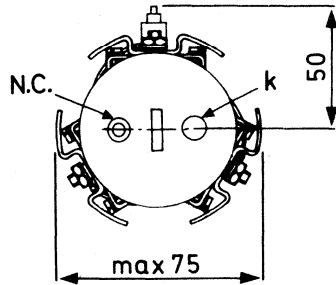
**MECHANICAL DATA**

n = total number of diodes .

OSM9210-nE



OSM9210-nF



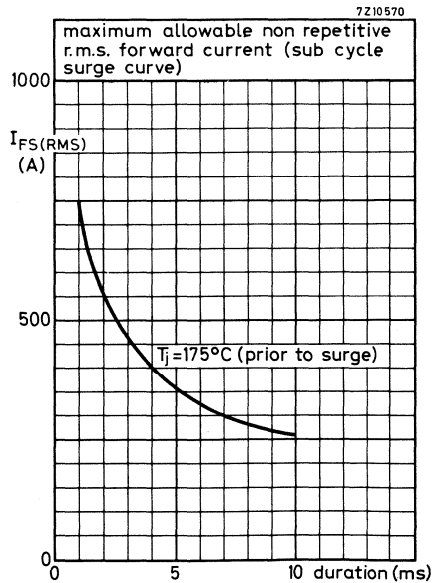
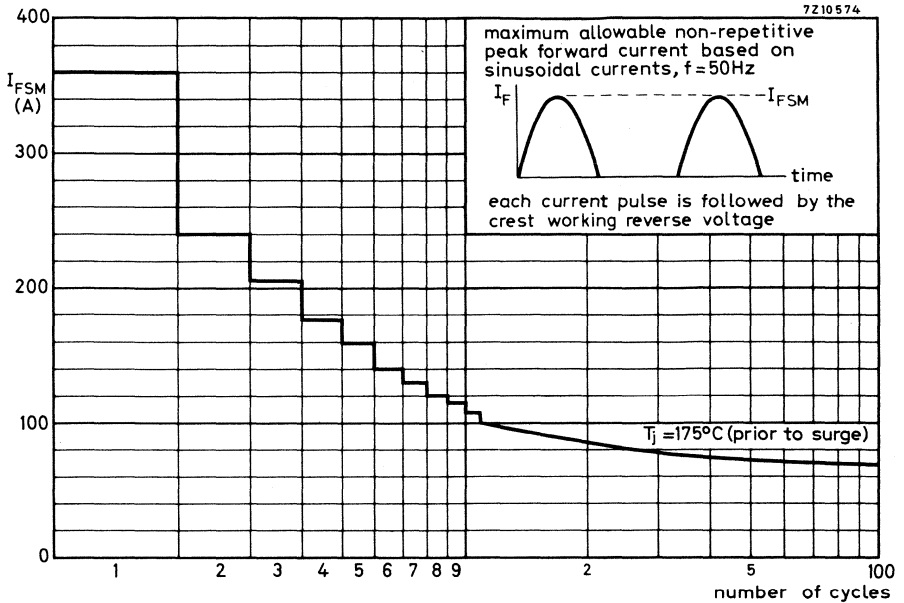
For lengths and weights see table on page 6.

Table of lengths and weights (mm and g)

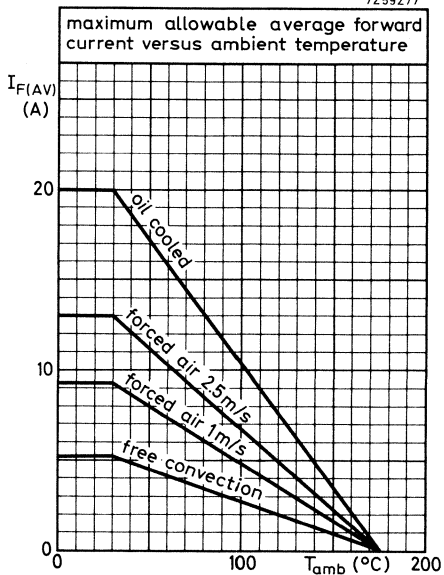
number of diodes	n	3	4 to 6	7 to 9	10 to 12	13 to 15
maximum lengths	L <sub>A</sub>	143	184	224	264	305
	L <sub>B</sub>	147	188	228	268	309
	L <sub>C</sub>	159	199	239	279	320
	L <sub>E</sub>	132	173	213	253	294
	L <sub>F</sub>	184	225	265	305	346
weight	W <sub>A</sub>	153	286	419	552	685
	W <sub>B</sub> = W <sub>C</sub> = W <sub>E</sub>	218	351	484	617	750
	W <sub>F</sub>	379	512	645	778	911

number of diodes	n	16 to 18	19 to 21	22 to 24	25 to 27	28 to 30
maximum lengths	L <sub>A</sub>	345	385	426	466	506
	L <sub>B</sub>	349	389	430	470	510
	L <sub>C</sub>	360	400	441	481	521
	L <sub>E</sub>	334	374	415	455	495
	L <sub>F</sub>	386	426	467	507	547
weights	W <sub>A</sub>	818	951	1084	1217	1350
	W <sub>B</sub> = W <sub>C</sub> = W <sub>E</sub>	883	1016	1149	1282	1415
	W <sub>F</sub>	1044	1177	1310	1443	1576

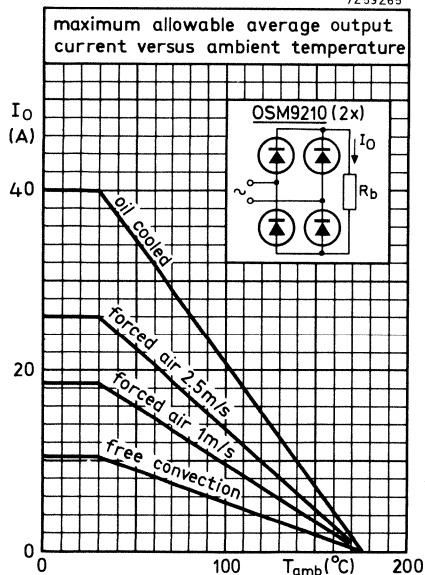




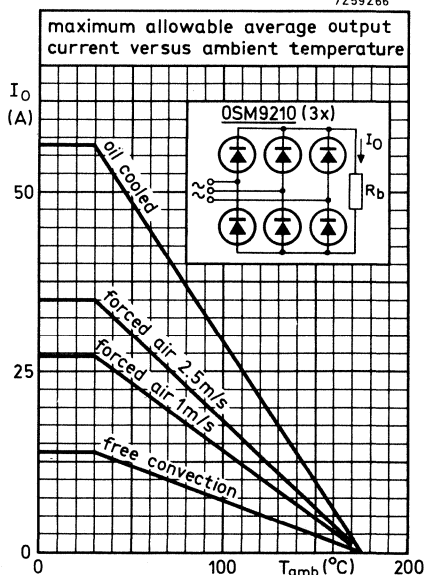
7Z59277



7Z59265

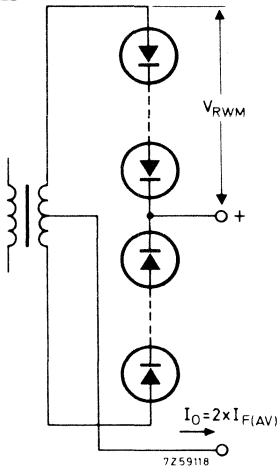


7Z59266

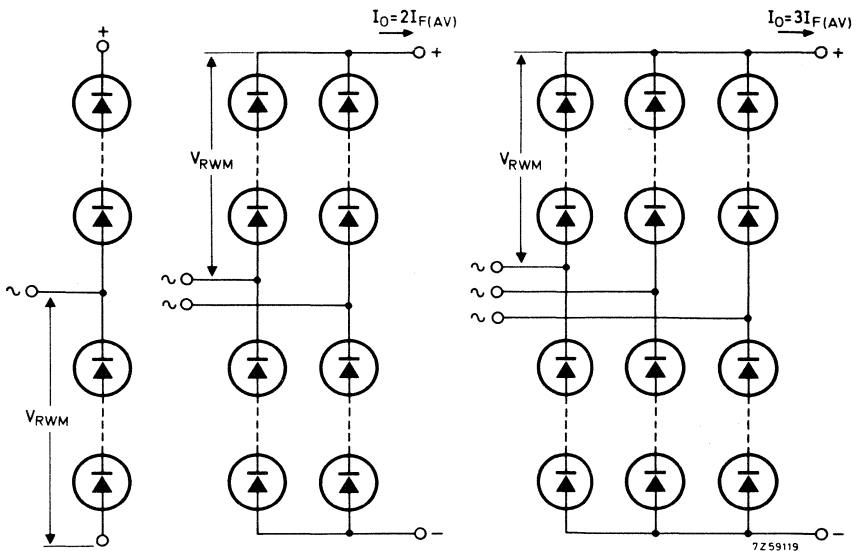


**APPLICATION INFORMATION**

OSB9210-4



OSM9210series



voltage doubler  
1x OSM9210

rectifier circuits with respectively  
2x OSM9210 and 3x OSM9210

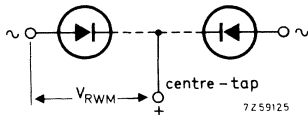


## HIGH VOLTAGE RECTIFIER STACKS

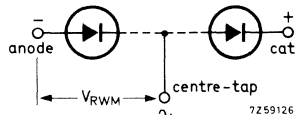
The OSB9310, OSM9310 and OSS9310 series are ranges of high voltage rectifier assemblies, incorporating controlled avalanche diodes mounted on fire proof triangular formers. The OSB9310 series is intended for application in two phase half wave rectifier circuits. The OSM9310 series is intended for application in single phase or three phase bridges or in voltage doubler circuits.

The OSS9310 series is intended for all kinds of high voltage rectification. The assemblies are supplied with M6 studs or with standard valve bases. The OSB9310 series and OSM9310 series are supplied with a centre tap (8-32UNC). The maximum crest working voltages of the OSB9310 and OSM9310 series cover the range from 2kV to 15 kV, and of the OSS9310 series the range from 3kV to 30 kV, in 1 kV steps.

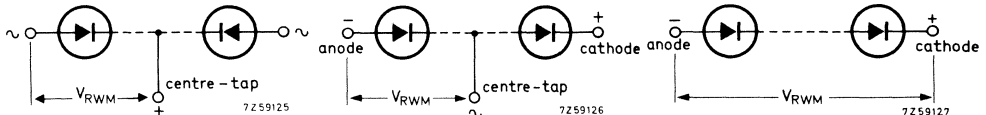
circuit OSB 9310



circuit OSM 9310



circuit OSS 9310



### QUICK REFERENCE DATA

				OSB9310	-4	-6	...	-28	-30
				OSM9310	-4	-6	...	-28	-30
Crest working reverse voltage from centre tap to end	$V_{RWM}$	max.	2	3	...	14	15	kV	
Crest working reverse voltage	$V_{RWM}$	max.	3	4	...	29	30	kV	
Average forward current with R and L load (averaged over any 20 ms period)	in free air up to $T_{amb} = 35^{\circ}\text{C}$				$I_{F(AV)}$ max.	4 A			
	in oil up to $T_{oil} = 65^{\circ}\text{C}$				$I_{F(AV)}$ max.	12 A			
	Non-repetitive peak forward current $t = 10\text{ ms}$ ; half sine wave; $T_j = 175^{\circ}\text{C}$ prior to surge				$I_{FSM}$ max.	180 A			

**MECHANICAL DATA** see page 4 and 5

All information applies to frequencies up to 400 Hz

**RATINGS** Limiting values in accordance with the Absolute Maximum System (IEC 134)

<u>Voltages</u>		OSB9310	-4	-6	...	-28	-30
		OSM9310	-4	-6	...	-28	-30
Crest working reverse voltage	$V_{RWM}$	max.	2	3	...	14	15 kV
		OSS9310	-3	-4	...	-29	-30
Crest working reverse voltage	$V_{RWM}$	max.	3	4	...	29	30 kV

Currents

Average forward current (averaged over any 20 ms period)

in free air up to  $T_{amb} = 35\text{ }^{\circ}\text{C}$

in oil up to  $T_{oil} = 65\text{ }^{\circ}\text{C}$

$I_{F(AV)}$  max. 4 A

$I_{F(AV)}$  max. 12 A

Repetitive peak forward current

$I_{FRM}$  max. 250 A

Non-repetitive peak forward current

$t = 10\text{ ms}$ ; half sine wave;  $T_j = 175\text{ }^{\circ}\text{C}$  prior to surge

$I_{FSM}$  max. 180 A

Reverse power dissipation

Repetitive peak reverse power dissipation

$t = 10\text{ }\mu\text{s}$  (square wave;  $f = 50\text{ Hz}$ )

$T_j = 175\text{ }^{\circ}\text{C}$

$PRRM$

OSB9310	-4	-6	...	-28	-30
OSM9310	-4	-6	...	-28	-30

max. 2 3 ... 14 15 kW

Non-repetitive peak reverse power dissipation

$t = 10\text{ }\mu\text{s}$  (square wave)

$T_j = 25\text{ }^{\circ}\text{C}$  prior to surge

$T_j = 175\text{ }^{\circ}\text{C}$  prior to surge

$PRSM$

$PRSM$

max. 12 18 ... 84 90 kW

max. 2 3 ... 14 15 kW

Repetitive peak reverse power dissipation

$t = 10\text{ }\mu\text{s}$  (square wave;  $f = 50\text{ Hz}$ )

$T_j = 175\text{ }^{\circ}\text{C}$

$PRRM$

OSS9310	-3	-4		-29	-30
---------	----	----	--	-----	-----

max. 3 4 ... 29 30 kW

Non-repetitive peak reverse power dissipation

$t = 10\text{ }\mu\text{s}$  (square wave)

$T_j = 25\text{ }^{\circ}\text{C}$  prior to surge

$T_j = 175\text{ }^{\circ}\text{C}$  prior to surge

$PRSM$

$PRSM$

max. 18 24 ... 174 180 kW

max. 3 4 ... 29 30 kW

Temperatures

Storage temperature

$T_{stg}$

-55 to +175  $^{\circ}\text{C}$

Junction temperature

$T_j$

max. 175  $^{\circ}\text{C}$

**CHARACTERISTICS** (See note 1)

	OSB9310	-4	-6	...	-28	-30	
	OSM9310	-4	-6	...	-28	-30	
<u>Forward voltage</u>							
$I_F = 50 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$	$V_F$	< 5	7.5	...	35	37.5	V
<u>Reverse breakdown voltage</u> <sup>1)</sup>							
$I_R = 5 \text{ mA}; T_j = 25 \text{ }^\circ\text{C}$	$V_{(BR)R}$	> 2.5	3.75	...	17.5	18.75	kV
		< 4	6	...	28	30	kV
	OSS9310	-3	-4	...	-29	-30	
<u>Forward voltage</u>							
$I_F = 50 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$	$V_F$	< 7.5	10	...	72.5	75	V
<u>Reverse breakdown voltage</u> <sup>1)</sup>							
$I_R = 5 \text{ mA}; T_j = 25 \text{ }^\circ\text{C}$	$V_{(BR)R}$	> 3.75	5	...	36.25	37.5	kV
		< 6	8	...	58	60	kV
<u>Reverse current</u>							
$V_{RM} = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$	$I_{RM}$	<				0.3	mA

**NOTES**

1. The Ratings and Characteristics given apply from centre tap to end. (Not for OSS9310series).

2. Type number suffix

The suffix consists of a figure indicating the total number of diodes, followed by a letter indicating the base.

- A = M6 studs at the ends
- B = 4 pin Super Jumbo (B4D)
- C = Goliath
- E = 4 pin Jumbo (B4F)
- F = A3-20

3. Operating position

The rectifier units can be operated at their maximum ratings when mounted in any position.

1) The breakdown voltage increases by approximately 0.1% per  $^\circ\text{C}$  with increasing junction temperature.

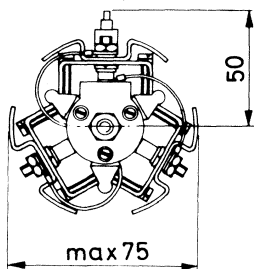
**OSB 9310 SERIES**  
**OSM9310 SERIES**  
**OSS 9310 SERIES**

**MECHANICAL DATA**

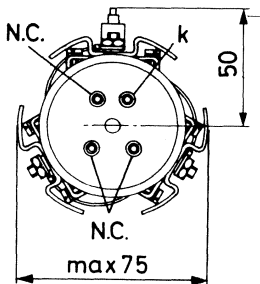
Dimensions in mm

n = total number of diodes

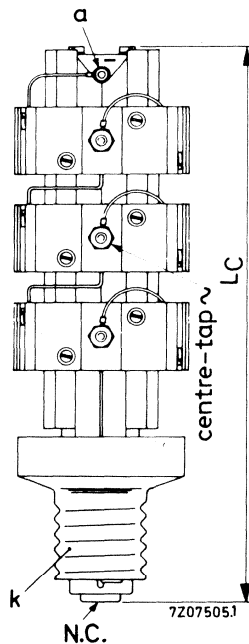
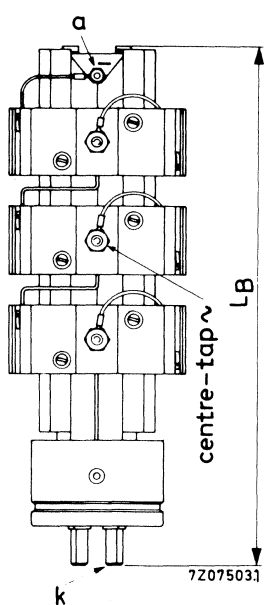
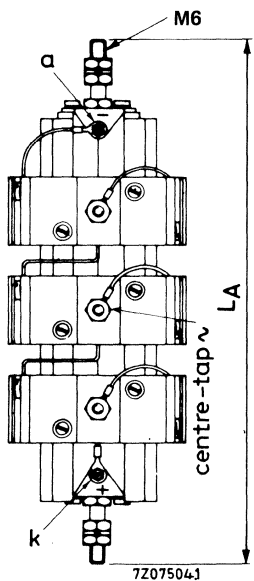
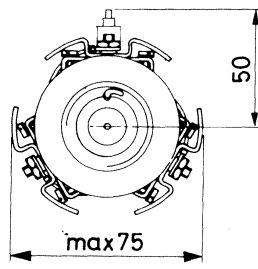
OSM9310-nA



OSM9310-nB



OSM9310-nC



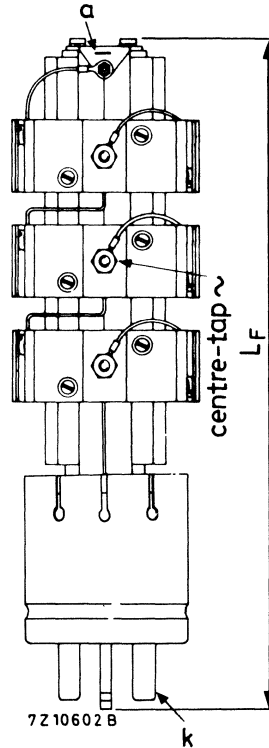
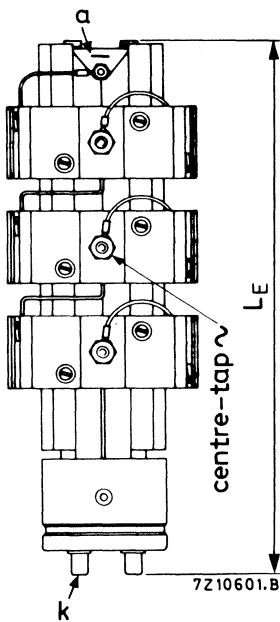
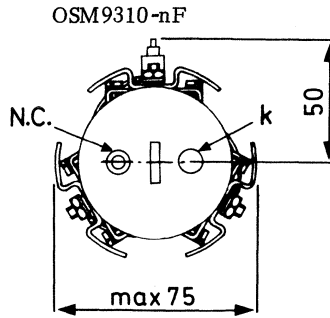
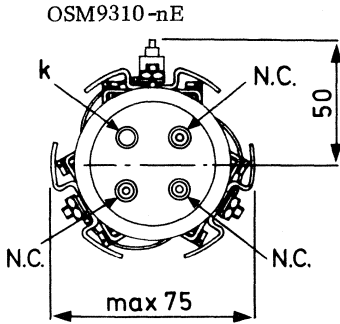
The drawings show the OSM9310series; the OSB9310 and OSS9310series differ in the following respects:

- OSB9310series - terminals marked a(-) and k(+) in the drawings are both marked ~; the centre-tap is marked + (instead of ~ as in the drawings).
- OSS9310series - has no centre-tap.



**MECHANICAL DATA**

n = total number of diodes

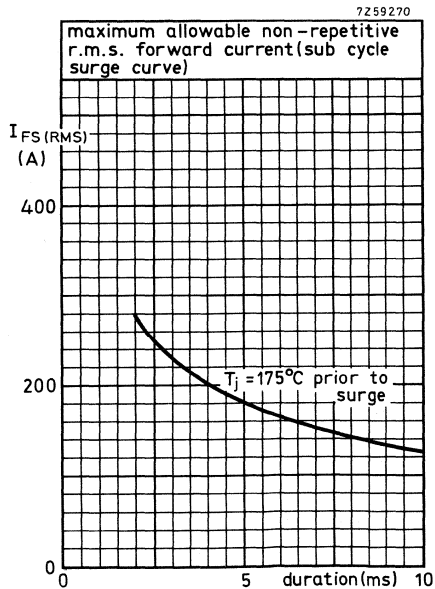
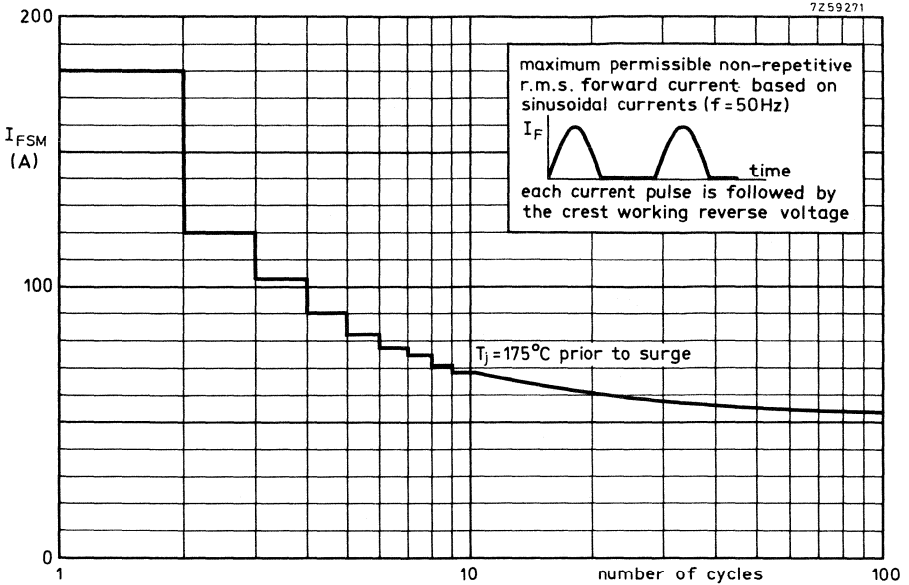


For lengths and weights see table on page 6.

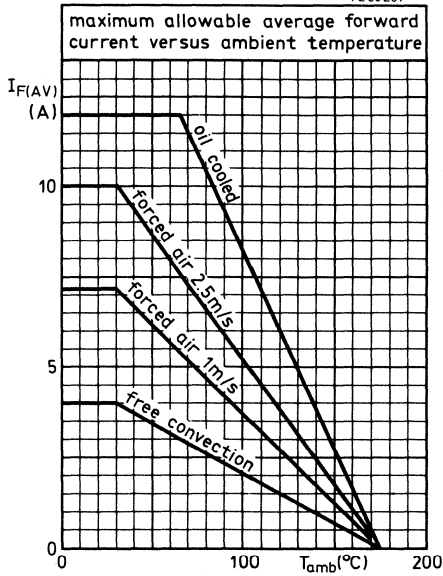
Table of lengths and weights (mm and g)

number of diodes	n	3	4 to 6	7 to 9	10 to 12	13 to 15
maximum lengths	L <sub>A</sub>	143	184	224	264	305
	L <sub>B</sub>	147	188	228	268	309
	L <sub>C</sub>	159	199	239	279	320
	L <sub>E</sub>	132	173	213	253	294
	L <sub>F</sub>	184	225	265	305	346
weight	W <sub>A</sub>	153	286	419	552	685
	W <sub>B</sub> = W <sub>C</sub> = W <sub>E</sub>	218	351	484	617	750
	W <sub>F</sub>	379	512	645	778	911

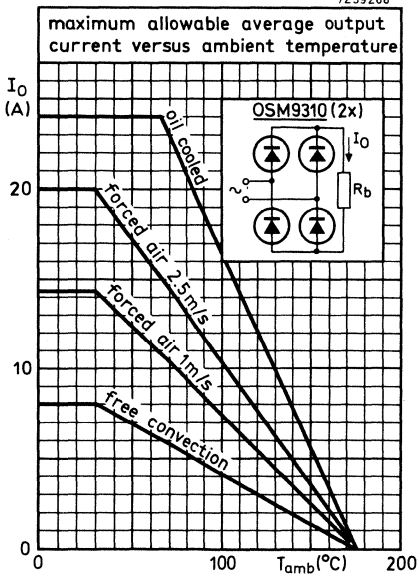
number of diodes	n	16 to 18	19 to 21	22 to 24	25 to 27	28 to 30
maximum lengths	L <sub>A</sub>	345	385	426	466	506
	L <sub>B</sub>	349	389	430	470	510
	L <sub>C</sub>	360	400	441	481	521
	L <sub>E</sub>	334	374	415	455	495
	L <sub>F</sub>	386	426	467	507	547
weights	W <sub>A</sub>	818	951	1084	1217	1350
	W <sub>B</sub> = W <sub>C</sub> = W <sub>E</sub>	883	1016	1149	1282	1415
	W <sub>F</sub>	1044	1177	1310	1443	1576



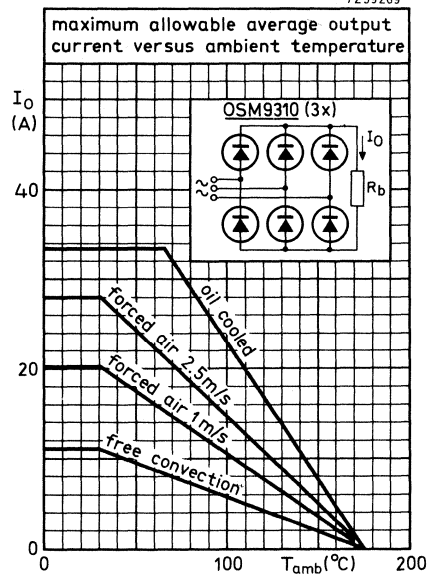
7Z59267



7Z59268

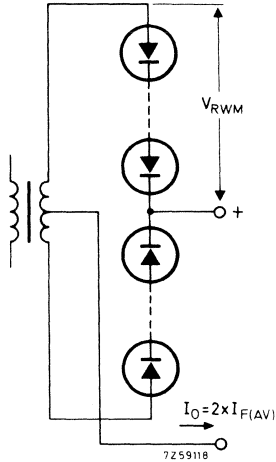


7Z59269

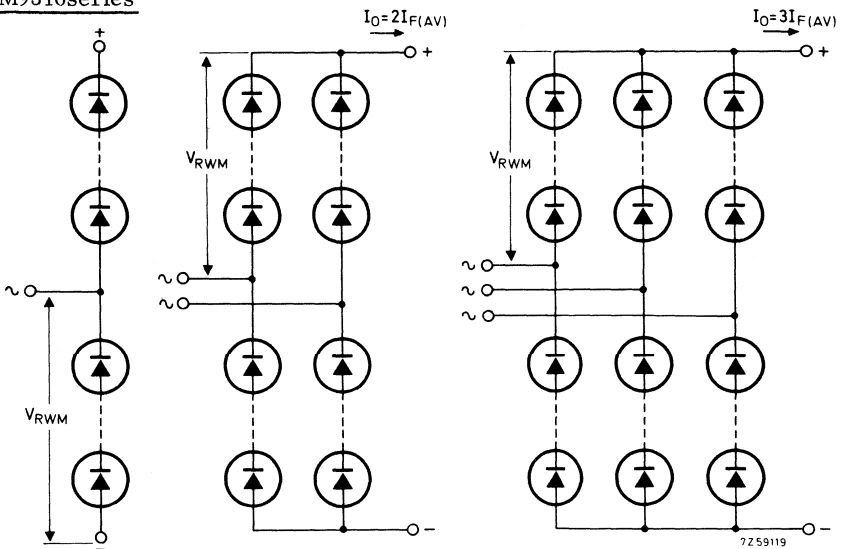


APPLICATION INFORMATION

OSB9310series



OSM9310series



voltage doubler  
1x OSM9310

rectifier circuits with respectively  
2x OSM9310 and 3x OSM9310



## HIGH VOLTAGE RECTIFIER STACKS

Ranges of high voltage rectifier assemblies, incorporating controlled avalanche diodes mounted on fire proof triangular formers. They are supplied with **M6 studs**.

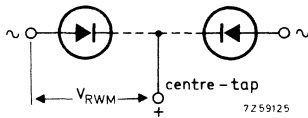
The OSB9410series is intended for application in two phase half wave rectifier circuits. The OSM9410series is intended for application in single phase or three phase bridges or in voltage doubler circuits.

The OSS9410series is intended for all kinds of high voltage rectification.

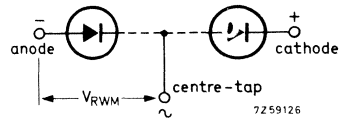
The OSB9410series and OSM9410series are supplied with a centre tap (8-32UNC).

The maximum crest working voltages of the OSB9410 and OSM9410series cover the range from 2 kV to 15 kV, and of the OSS9410series the range from 3 kV to 30 kV, in 1 kV steps.

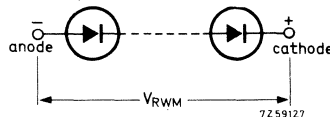
CIRCUIT OSB9410



CIRCUIT OSM9410



CIRCUIT OSS9410



### QUICK REFERENCE DATA

		OSB9410	-4	-6	...	-28	-30
Crest working reverse voltage from centre tap to end	$V_{RWM}$	OSM9410	-4	-6	...	-28	-30
		max.	2	3		14	15
Crest working reverse voltage	$V_{RWM}$	OSS9410	-3	-4	...	-29	-30
		max.	3	4	...	29	30
Average forward current with R and L load (averaged over any 20 ms period)							
in free air up to $T_{amb} = 35^{\circ}\text{C}$						$I_{F(AV)}$ max. 10 A	
in oil up to $T_{oil} = 35^{\circ}\text{C}$						$I_{F(AV)}$ max. 30 A	
Non-repetitive peak forward current $t = 10$ ms; half sine wave; $T_j = 175^{\circ}\text{C}$ prior to surge						$I_{FSM}$ max. 800 A	

**MECHANICAL DATA** see page 4

All information applies to frequencies up to 400 Hz

**RATINGS** Limiting values in accordance with the Absolute Maximum System (IEC 134)

		OSB9410	-4	-6	...	-28	-30
<u>Voltages</u>		OSM9410	-4	-6	...	-28	-30
Crest working reverse voltage	$V_{RWM}$	max.	2	3	...	14	15 kV
		OSS9410	-3	-4	...	-29	-30
Crest working reverse voltage	$V_{RWM}$	max.	3	4	...	29	30 kV

Currents

Average forward current (averaged over any 20 ms period)

in free air up to  $T_{amb} = 35\text{ }^{\circ}\text{C}$

$I_{F(AV)}$  max. 10 A

in oil up to  $T_{oil} = 35\text{ }^{\circ}\text{C}$

$I_{F(AV)}$  max. 30 A

Repetitive peak forward current

$I_{FRM}$  max. 450 A

Non-repetitive peak forward current

$t = 10\text{ ms}$ ; half sine wave;  $T_j = 175\text{ }^{\circ}\text{C}$  prior to surge

$I_{FSM}$  max. 800 A

Reverse power dissipation

		OSB9410	-4	-6	...	-28	-30
Repetitive peak reverse power dissipation		OSM9410	-4	-6	...	-28	-30
$t = 10\mu\text{s}$ (square wave; $f = 50\text{ Hz}$ )							
$T_j = 175\text{ }^{\circ}\text{C}$	$P_{RRM}$	max.	9	13.5	...	63	67.5 kW
Non-repetitive peak reverse power dissipation							
$t = 10\mu\text{s}$ (square wave)							
$T_j = 25\text{ }^{\circ}\text{C}$ prior to surge	$P_{RSM}$	max.	55	80	...	375	400 kW
$T_j = 175\text{ }^{\circ}\text{C}$ prior to surge	$P_{RSM}$	max.	8.5	13	...	60.5	65 kW
Repetitive peak reverse power dissipation		OSS9410	-3	-4	...	-29	-30
$t = 10\mu\text{s}$ (square wave; $f = 50\text{ Hz}$ )							
$T_j = 175\text{ }^{\circ}\text{C}$	$P_{RRM}$	max.	13.5	18	...	130.5	135 kW
Non-repetitive peak reverse power dissipation							
$t = 10\mu\text{s}$ (square wave)							
$T_j = 25\text{ }^{\circ}\text{C}$ prior to surge	$P_{RSM}$	max.	80	105	...	775	800 kW
$T_j = 175\text{ }^{\circ}\text{C}$ prior to surge	$P_{RSM}$	max.	13	17	...	126	130 kW

Temperatures

Storage temperature	$T_{stg}$	- 55 to + 175	$^{\circ}\text{C}$
Junction temperature	$T_j$	max. 175	$^{\circ}\text{C}$



**CHARACTERISTICS** (See note 1)

		OSB9410 -4	-6	...	-28	-30
		OSM9410 -4	-6	...	-28	-30
<u>Forward voltage</u>						
$I_F = 150 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$	$V_F$	< 3.6	5.4	...	25.2	27 V
<u>Reverse avalanche breakdown voltage</u> <sup>1)</sup>						
$I_R = 5 \text{ mA}; T_j = 25 \text{ }^\circ\text{C}$	$V_{(BR)R}$	> 2.5	3.75	...	17.5	18.75 kV
		< 4	6	...	28	30 kV

		OSS9410 -3	-4	...	-29	-30
<u>Forward voltage</u>						
$I_F = 150 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$	$V_F$	< 5.4	7.2	...	52.2	54 V
<u>Reverse avalanche breakdown voltage</u> <sup>1)</sup>						
$I_R = 5 \text{ mA}; T_j = 25 \text{ }^\circ\text{C}$	$V_{(BR)R}$	> 3.75	5	...	36.25	37.5 kV
		< 6	8	...	58	60 kV

Reverse current

$$V_{RM} = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$$

$$I_{RM} < 1.6 \text{ mA}$$

**NOTES**

1. The Ratings and Characteristics given apply from centre tap to end. (Not for OSS9410series).
2. Type number suffix  
 The suffix consists of a figure indicating the total number of diodes, followed by a letter indicating the base.  
 A = M6 studs at the ends.
3. Operating position  
 The rectifier units can be operated at their maximum ratings when mounted in any position.

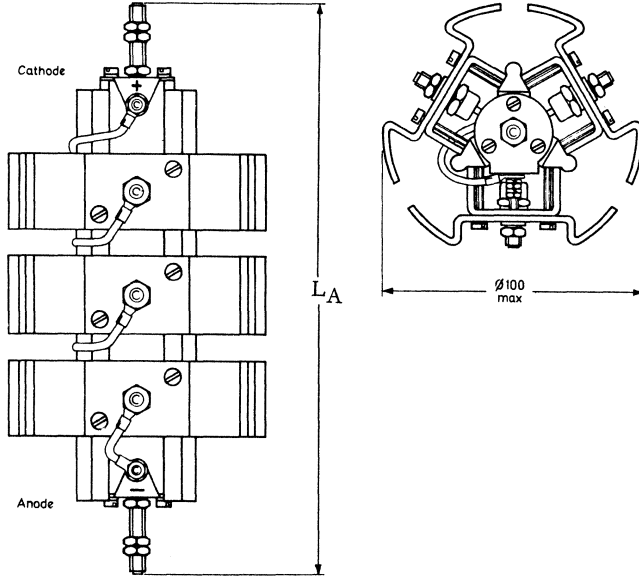
<sup>1)</sup> The breakdown voltage increases, by approximately 0.1% per  $^\circ\text{C}$  with increasing junction temperature.

**MECHANICAL DATA**

Dimensions in mm

n = total number of diodes.

OSS9410-nA



The drawing shows the OSS9410series.

The OSB9410 and OSM9410series differ in the following respects:

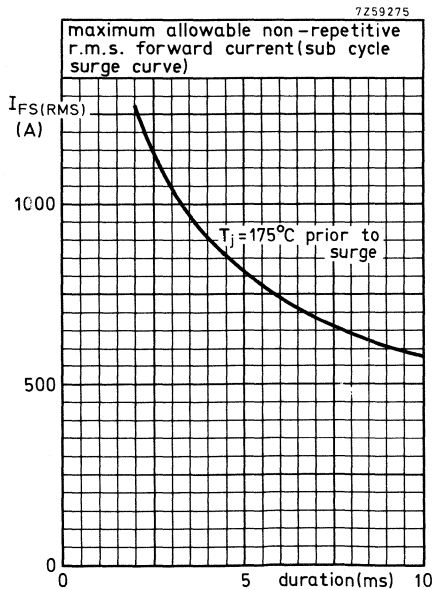
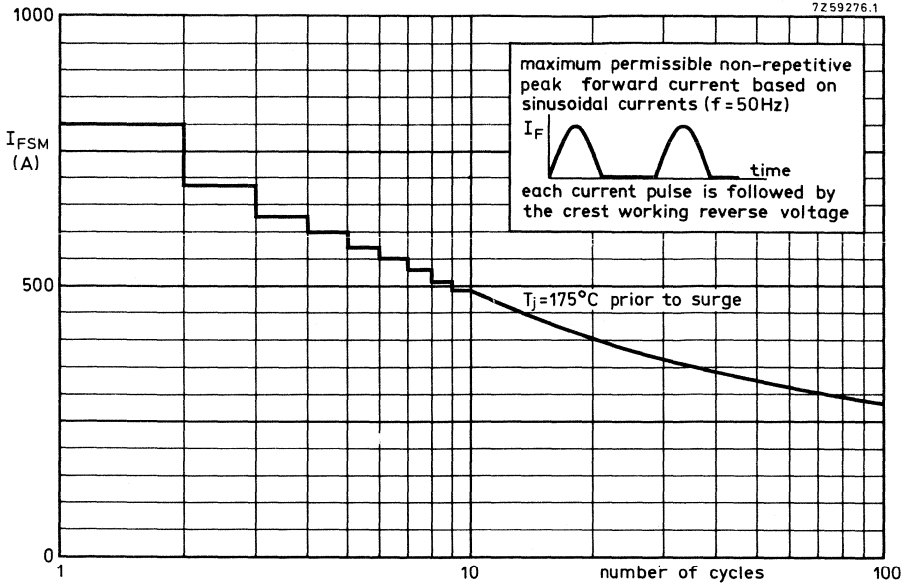
OSB9410 series - has a centre tap marked +; anode and cathode terminals are both marked ~.

OSM9410series - has a centre tap marked ~.

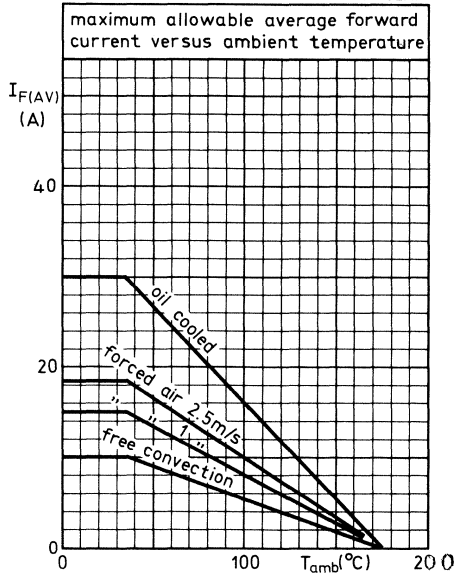
Table of lengths and weights (mm and g)

number of diodes	n	3	4 to 6	7 to 9	10 to 12	13 to 15
maximum lengths	$L_A$	143	184	224	264	305
weights	$W_A$	215	413	611	809	1007

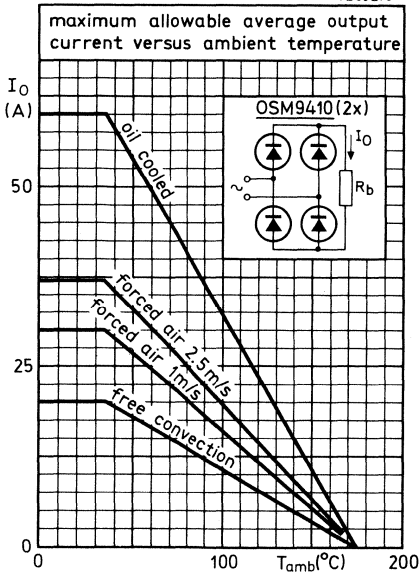
number of diodes	n	16 to 18	19 to 21	22 to 24	25 to 27	28 to 30
maximum lengths	$L_A$	345	385	426	466	506
weights	$W_A$	1208	1406	1604	1802	2000



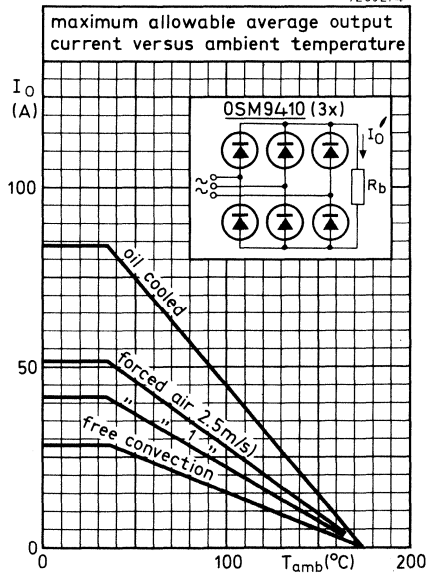
7Z59272



7Z59273

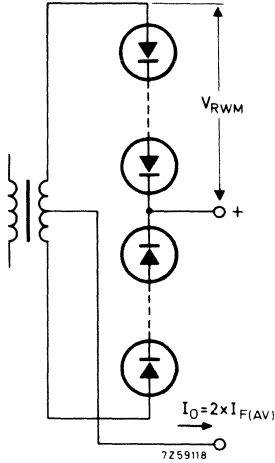


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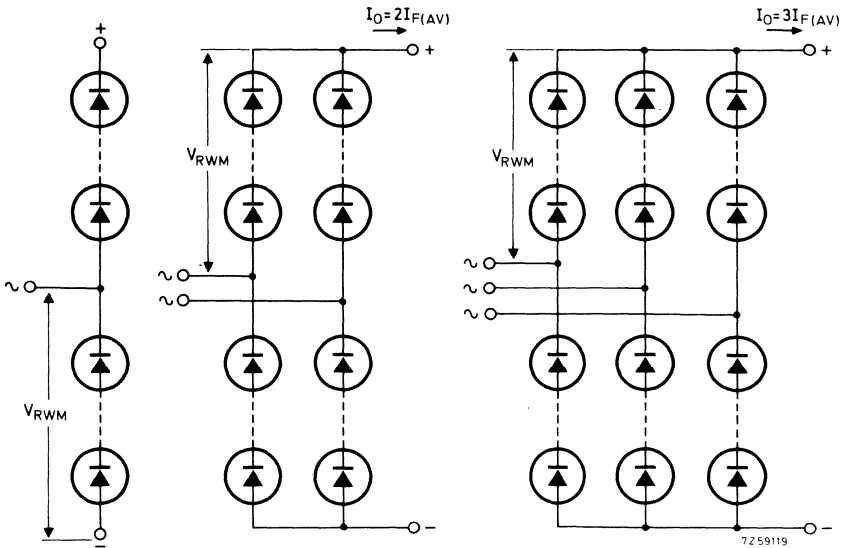


**APPLICATION INFORMATION**

OSB9410series



OSM9410series



voltage doubler  
1x OSM9410

rectifier circuits with respectively  
2x OSM9410 and 3x OSM9410



## HIGH-VOLTAGE RECTIFIER STACK

The OSM9510-12 is a silicon rectifier stack for high voltage applications, up to 12kV in half-wave circuits, or up to 6kV as one of the arms of a bridge configuration, where the centre-tap is utilised. Because of its controlled avalanche characteristics it is capable of withstanding reverse transients generated in the circuit.

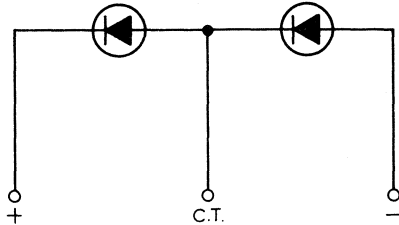
### QUICK REFERENCE DATA

$V_{RWM}$ max.	12	kV
$V_{(BR)R}$ min.	15	kV
$I_{F(AV)}$ max., in free air, $T_{amb} = 50^{\circ}C$	1.5	A
$P_{RSM}$ max., $t = 10\mu s$ , $T_{amb} = 25^{\circ}C$	20	kW

### OUTLINE AND DIMENSIONS

For details see page 3

### CIRCUIT DIAGRAM



Also available: 8 kV type with  $V_{(BR)R \min} = 12.5$  kV

## RATINGS

Limiting values of operation according to the absolute maximum system.  
 These ratings apply for the frequency range 50 to 400Hz.  
 Simultaneous application of all ratings is inferred unless otherwise stated.

## Electrical

$V_{RWM}$ max.	Crest working reverse voltage	12	kV
$I_{F(AV)}$ max.	Mean forward current in free air, $T_{amb} \leq 50^{\circ}C$ , $180^{\circ}$ conduction	1.5	A
		See derating curves on page 4	
$I_{FRM}$ max.	Repetitive peak forward current, $30^{\circ}$ conduction	15	A
$I_{FSM}$ max.	Surge forward current, 1 cycle (10ms peak of half sinewave)	35	A
$P_{RSM}$ max.	Non-repetitive peak reverse power ( $10\mu s$ square wave, $T_j = 25^{\circ}C$ )	20	kW
$P_{RRM}$ max.	50Hz repetitive peak reverse transient power ( $10\mu s$ square wave, $T_j = 150^{\circ}C$ )	5.0	kW

## Temperature

$T_{stg}$	Storage temperature	-55 to 150	$^{\circ}C$
$T_j$	Junction temperature	-55 to 150	$^{\circ}C$

ELECTRICAL CHARACTERISTICS ( $T_j = 25^{\circ}C$  unless otherwise stated)

		Min.	Max.	
$*V_F$	Forward voltage at $I_F = 5A$	-	17.5	V
$I_R$	Reverse current at $V_{RWM}$ , $T_j = 125^{\circ}C$	-	100	$\mu A$
$V_{(BR)R}$	**Avalanche breakdown voltage, $I_{(BR)R} = 1mA$	15	25	kV

\*Measured under pulsed conditions so that  $T_j$  is at, or near, the stated value.

\*\*The avalanche voltage increases by approximately 0.1%/degC with increasing  $T_j$ .

## MECHANICAL DATA

Weight	130	g
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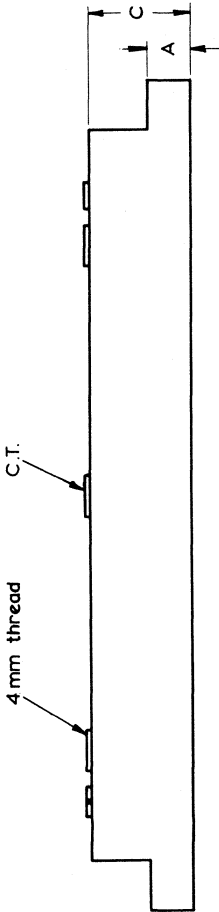
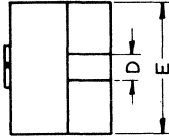
## MOUNTING POSITION

The rectifier units can be operated at their maximum ratings when mounted in any position.

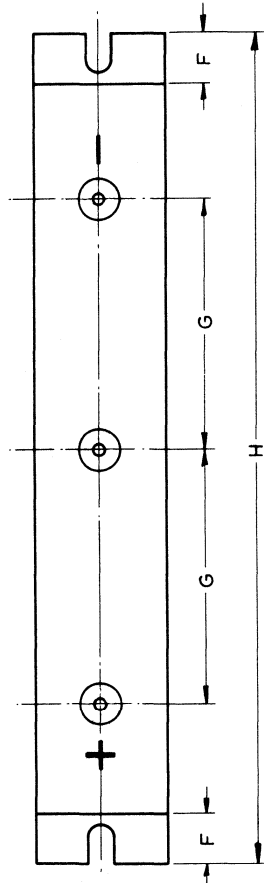


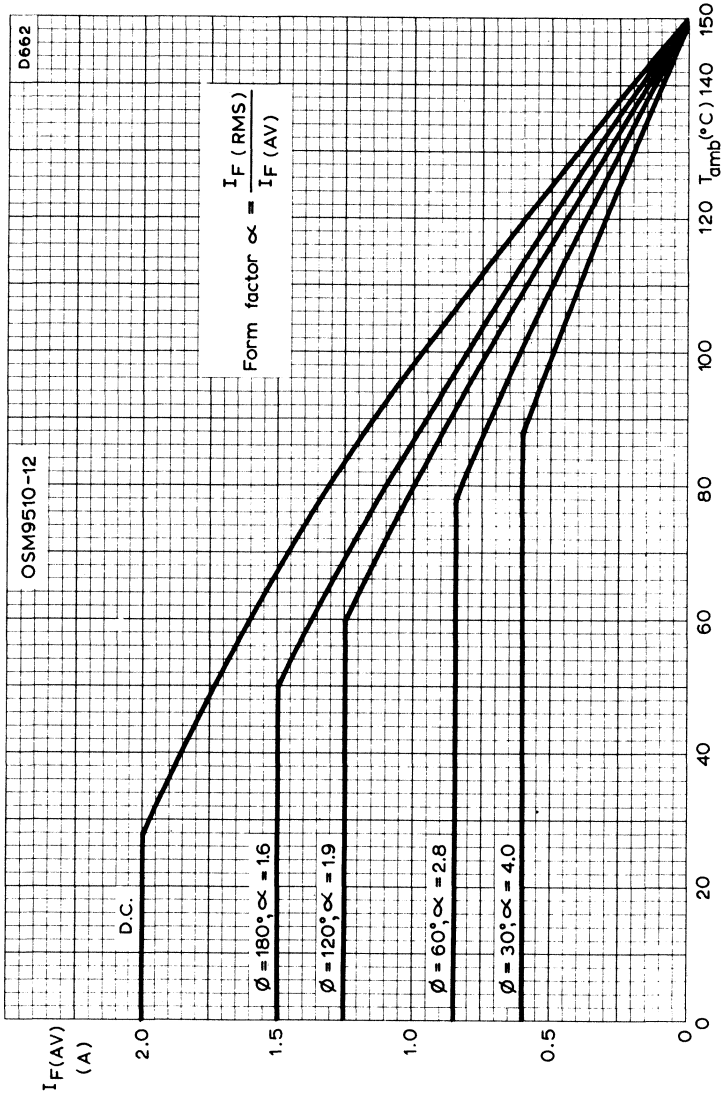
OUTLINE AND DIMENSIONS

D661

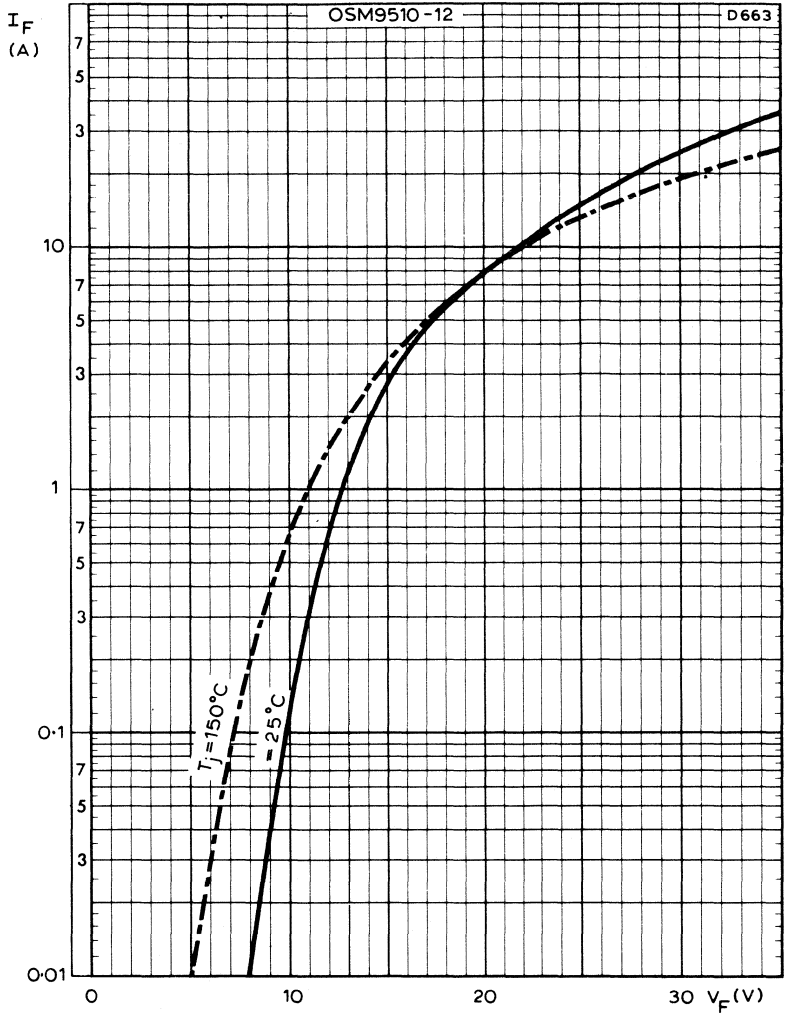


Millimetres	A	C	D	E	F	G	H
	8.0	18.5	5.3	26	10	50	165

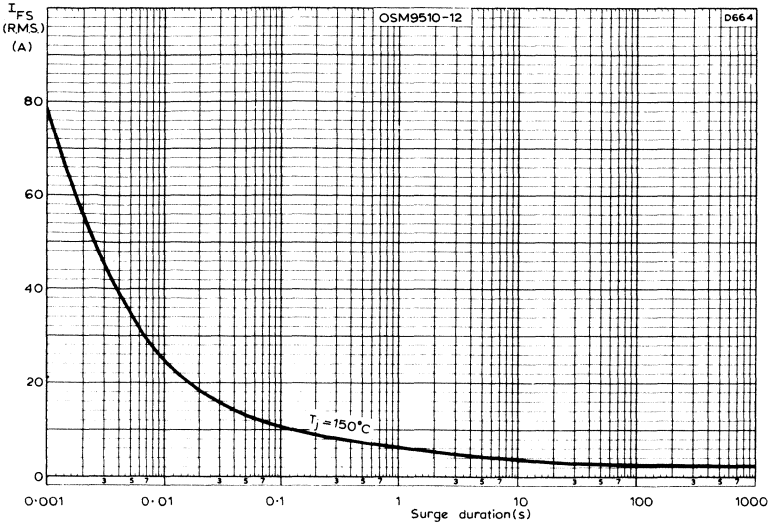




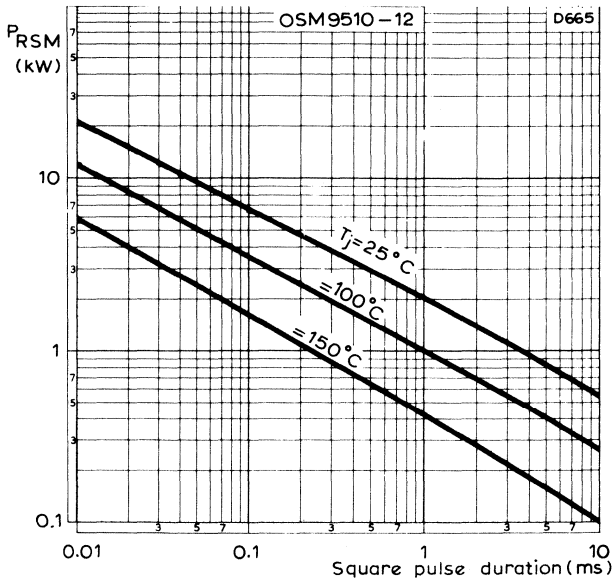
MAXIMUM MEAN FORWARD CURRENT AS A FUNCTION OF AMBIENT TEMPERATURE AND CONDUCTION ANGLE



MAXIMUM FORWARD CONDUCTION CHARACTERISTICS



MAXIMUM R.M.S. SURGE CURRENT PLOTTED AGAINST SURGE DURATION



NON-REPETITIVE PEAK REVERSE POWER PLOTTED AGAINST SQUARE PULSE DURATION

# THYRISTORS



**E**



**E**

## THYRISTORS

### SWITCHING CHARACTERISTICS

Thyristors are not perfect switches. They take a finite time to go from the off to the on-state and vice-versa. At frequencies up to about 400 Hz these effects can often be ignored, but in many applications involving fast switching action the departure from the ideal is important.

#### Gate-controlled turn-on time

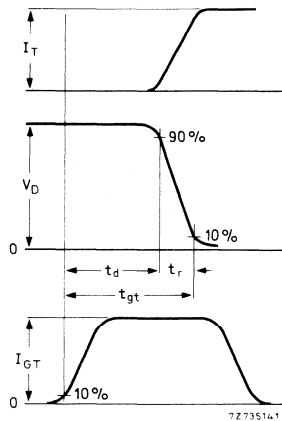
Anode current does not commence flowing at the instant the gate current is applied.

There is a period which elapses between the application of gate current and the onset of anode current known as delay time ( $t_d$ ). The rise time of anode current is known as  $t_r$  and is measured as the time taken for the anode voltage to fall from 90% to 10% of its initial value.

The conditions which need to be specified are:

- Off-state voltage ( $V_D$ ).
- On-state current ( $I_T$ ).
- Gate trigger current ( $I_G$ ) – high gate currents reduce turn-on time.
- Rate of rise of gate trigger current ( $dI_G/dt$ ) – high values reduce turn-on time.
- Junction temperature ( $T_j$ ) – high temperatures reduce turn-on time.

The waveforms are shown in the following diagram:



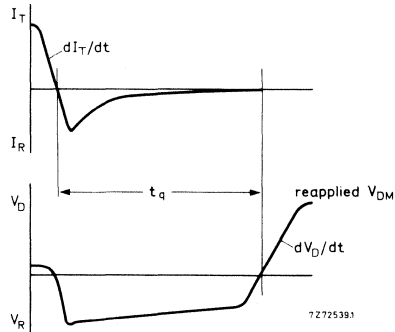
### CIRCUIT-COMMUTATED TURN-OFF TIME

When a thyristor has been conducting and is reverse biased it cannot go immediately into the forward blocking state. Thyristors exhibit a stored charge in a similar fashion to rectifiers; it is only after this charge has been recombined or been swept out that the device can block reapplied off-state voltage. The turn-off time ( $t_q$ ) is measured from the instant the anode current passes through zero to the instant the thyristor is capable of blocking reapplied off-state voltage.

The conditions which need to be specified are:

- a) On-state current ( $I_T$ ) – high peak currents mean longer turn-off times.
- b) Reverse voltage ( $V_R$ ) – low reverse voltages mean longer turn-off times.  
An example of this is when the thyristor is in anti-parallel with a diode, limiting the reverse voltage to a volt or so.
- c) Rate of fall of anode current ( $dI/dt$ ) – high rates mean shorter turn-off times.
- d) Rate of rise of reapplied off-state voltage ( $dV_D/dt$ ) – high rates mean longer turn-off times.
- e) Temperature ( $T_j$  or  $T_{mb}$ ) – high temperatures mean longer turn-off times.
- f) Gate conditions ( $-V_{GG}$ ,  $R_{tot}$ ) – the application of a negative gate voltage during reverse recovery can be used to reduce the turn-off time. Care must be taken not to exceed the reverse gate voltage rating ( $V_{RGMmax}$ ).

The waveforms are shown in the following diagram:





## MOUNTING INSTRUCTIONS FOR TO-220 ENVELOPES

## GENERAL DATA AND INSTRUCTIONS FOR HEATSINK OPERATION

**General rules**

1. First fasten the devices to the heatsink before soldering the leads.
2. Use of heatsink compound is recommended.
3. Avoid axial stress to the leads.
4. Keep mounting tool (e.g. screwdriver) clear of the plastic body.
5. It is recommended that the circuit connections be made to the leads rather than direct to the heatsink.

**Heatsink requirements**

Flatness in the mounting area: 0,02 mm maximum per 10 mm.  
Mounting holes must be deburred.

**Heatsink compound**

Values of the thermal resistance from mounting base to heatsink ( $R_{th\ mb-h}$ ) given for mounting with heatsink compound refer to the use of a metallic oxide-loaded compound. The compound should be an electrical insulator and be applied sparingly and evenly to both interfaces. Ordinary silicone grease is not recommended.

For insulated mounting, the compound should be applied to the bottom of both device and insulator.

**Mounting methods for thyristors and triacs**

## 1. Clip mounting.

Mounting by means of spring clip offers:

- a. A good thermal contact under the crystal area, and slightly lower  $R_{th\ mb-h}$  values than screw mounting.
- b. Safe insulation for mains operation.

Recommended force of clip on device is 120 N (12 kgf).

## 2. M3 screw mounting.

Care should be taken to avoid damage to the plastic body. It is therefore recommended that a cross-recess pan-headed screw be used. Do not use self-tapping screws.

Mounting torque for screw mounting:

Minimum torque (for good heat transfer)	0,55 Nm (5,5 kgcm)
Maximum torque (to avoid damaging the device)	0,80 Nm (8,0 kgcm)

N.B.: When a nut or screw is not driven direct against a curved spring washer or lock washer, the torques are as follows:

Minimum torque (for good heat transfer)	0,4 Nm (4 kgcm)
Maximum torque (to avoid damaging the device)	0,6 Nm (6 kgcm)

N.B.: Data on accessories are given in separate data sheets.

## 3. Rivet mounting (only possible for non-insulated mounting)

Devices may be rivetted to flat heatsinks; such a process **must neither** deform the mounting tab, **nor** enlarge the mounting hole.

GENERAL DATA AND INSTRUCTIONS FOR HEATSINK OPERATION (continued)

**Thermal data**

	clip mounting	screw mounting
Thermal resistance from mounting base to heatsink with heatsink compound, direct mounting	$R_{th\ mb-h} = 0,3$	$0,5\ ^\circ C/W$
without heatsink compound, direct mounting	$R_{th\ mb-h} = 1,4$	$1,4\ ^\circ C/W$
with heatsink compound and mica insulator 56369	$R_{th\ mb-h} = 2,2$	$-\ ^\circ C/W$
with heatsink compound and alumina insulator 56367	$R_{th\ mb-h} = 0,8$	$-\ ^\circ C/W$

**Lead bending**

Maximum permissible tensile force on the body, for 5 seconds is 5 N (0,5 kgf).

The leads can be bent through 90° maximum, twisted or straightened. To keep forces within the above-mentioned limits, the leads are generally clamped near the body. The leads should neither be bent nor twisted less than 2,4 mm from the body.

**Soldering**

Lead soldering temperature at 4,7 mm from the body;  $t_{sld} < 5\ s$ ;  $T_{sld\ max} = 275\ ^\circ C$ .

Avoid any force on body and leads during or after soldering: do not move the device or leads after soldering.

It is not permitted to solder the metal tab of the device to a heatsink, otherwise its junction temperature rating will be exceeded.

## INSTRUCTIONS FOR CLIP MOUNTING (TO-220 envelopes)

## Direct mounting with clip 56363

1. Place the device on the heatsink, applying heatsink compound to the mounting base.
2. Push the short end of the clip into the narrow slot in the heatsink with the clip at an angle of  $10^{\circ}$  to  $30^{\circ}$  to the vertical (see Fig. 1).
3. Push down the clip over the device until the long end of the clip snaps into the wide slot in the heatsink. The clip should bear on the plastic body, not on the tab (see Fig. 1(c)).

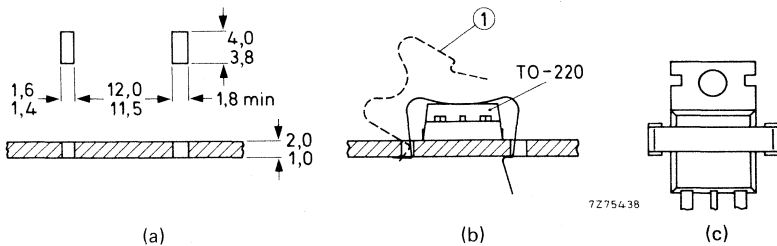


Fig. 1 (a) Heatsink requirements; (b) mounting (1 = spring clip); (c) position of the device (top view).

## Insulated mounting with clip 56364

With the insulators 56367 or 56369 insulation up to 2 kV is obtained.

1. Place the device with the insulator on the heatsink, applying heatsink compound to the bottom of both device and insulator.
2. Push the short end of the clip into the narrow slot in the heatsink with the clip at an angle of  $10^{\circ}$  to  $30^{\circ}$  to the vertical (see Fig. 2).
3. Push down the clip over the device until the long end of the clip snaps into the wide slot in the heatsink. The clip should bear on the plastic body, not on the tab (see Fig. 2(c)). There should be minimum 3 mm distance between the device and the edge of the insulator for adequate creepage.

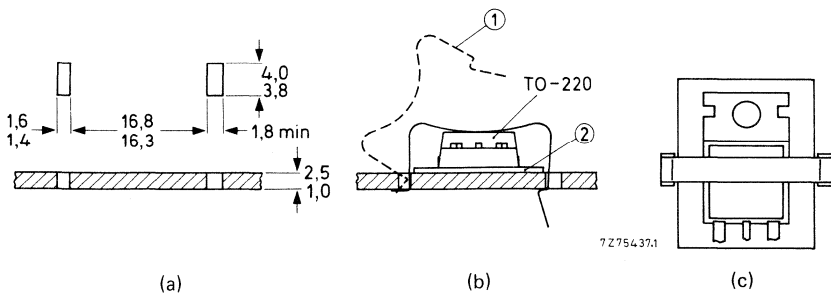


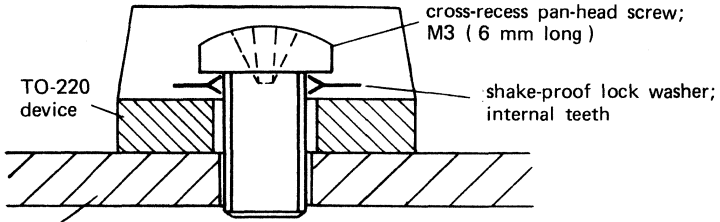
Fig. 2 (a) Heatsink requirements; (b) mounting (1 = spring clip, 2 = insulator 56369 or 56367); (c) position of the device (top view).

# GENERAL EXPLANATORY NOTES

## INSTRUCTIONS FOR SCREW MOUNTING (TO-220 envelopes)

### Direct mounting with screw

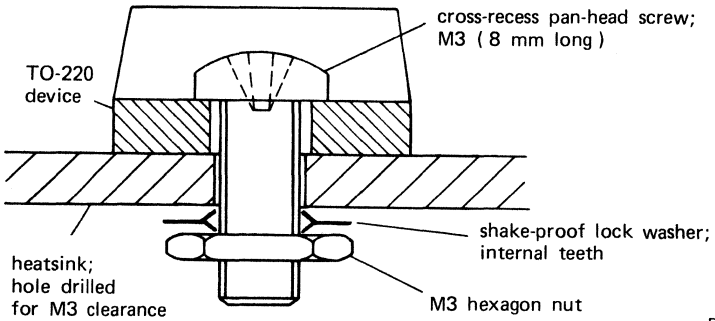
- *into tapped heatsink*



heatsink; hole drilled 2,70 mm dia

D7509A

- *through heatsink with nut*



heatsink;  
hole drilled  
for M3 clearance

M3 hexagon nut

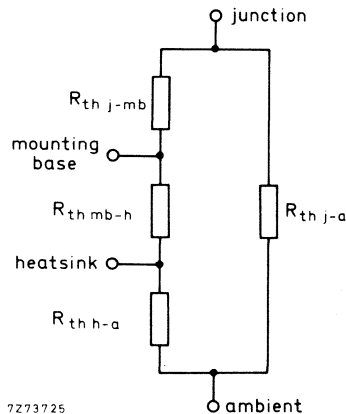
D7510A

## MOUNTING CONSIDERATIONS FOR STUD-MOUNTED THYRISTORS

Losses generated in a silicon device must flow through the case and to a lesser extent the leads. The greatest proportion of the losses flow out through the case into a heat exchanger which can be either free convection cooled, forced convection or even liquid cooled. For the majority of devices in our range natural convection is generally adequate, however, where other considerations such as space saving must be taken into account then methods such as forced convection etc. can be considered. The thermal path from junction to ambient may be considered as a number of resistances in series. The first thermal resistance will be that of junction to mounting base, usually denoted by  $R_{th\ j-mb}$ . The second is the contact thermal resistance  $R_{th\ mb-h}$  and finally there is the thermal resistance of the heatsink  $R_{th\ h-a}$ .

In the rating curves, the contact thermal resistance and heatsink thermal resistances are combined as a single figure -  $R_{th\ mb-a}$ .

In addition to the steady state thermal conditions of the system, consideration should also be given to the possibility of any transient thermal excursions. These can be caused for example by starting conditions or overloads and in order to calculate the effect on the device, a graph of transient thermal resistance  $Z_{th\ j-mb}$  as a function of time is given in each data sheet.



When mounting the device on the heatsink, care should be taken that the contact surfaces are free from burrs or projections of any kind and must be thoroughly clean.

In the case where an anodised heatsink is used, the anodising should be removed from the contact surface ensuring good electrical and thermal contact.

The contact surfaces should be smeared with a metallic oxide-loaded grease to ensure good heat transfer.

Where the device is mounted in a tapped hole, care should be taken that the hole is perpendicular to the surface of the heatsink. When mounting the device to the heatsink, it is essential that a proper torque wrench is used, applying the correct amount of torque as specified in the published data.

Excessive torque can distort the threads of the device and may even cause mechanical stress on the wafer, leading to the possible failure.

Where isolation of the device from the heatsink is required, it is common practice to use a mica washer between contact surfaces, and where a clearance hole is used, a p.t.f.e. insulating bush is inserted. A metallic oxide-loaded heatsink compound should be smeared on all contact surfaces, including the mica washer, to ensure optimum heat transfer. The use of ordinary silicone grease is not recommended.

**OPERATING NOTES**

When there is a possibility that transients, due to the energy stored in the transformer, will exceed the maximum permissible non-repetitive peak reverse voltage, a damping circuit should be connected across the transformer.

Either a series RC circuit or a voltage dependent resistor may be used. Suitable component values for an RC circuit across the transformer primary or secondary may be calculated as follows:

$\frac{V_{RSM}}{V_{RWM}}$	RC across primary of transformer		RC across secondary of transformer	
	C ( $\mu F$ )	R ( $\Omega$ )	C ( $\mu F$ )	R ( $\Omega$ )
2.0	$200 \frac{I_{mag}}{V_1}$	$\frac{150}{C}$	$225 \frac{I_{mag} T^2}{V_1}$	$\frac{200}{C}$
1.5	$400 \frac{I_{mag}}{V_1}$	$\frac{225}{C}$	$450 \frac{I_{mag} T^2}{V_1}$	$\frac{275}{C}$
1.25	$550 \frac{I_{mag}}{V_1}$	$\frac{260}{C}$	$620 \frac{I_{mag} T^2}{V_1}$	$\frac{310}{C}$
1.0	$800 \frac{I_{mag}}{V_1}$	$\frac{300}{C}$	$900 \frac{I_{mag} T^2}{V_1}$	$\frac{350}{C}$

where  $I_{mag}$  = magnetising primary r.m.s. current (A)

$V_1$  = transformer primary r.m.s. voltage (V)

$V_2$  = transformer secondary r.m.s. voltage (V)

T =  $V_1/V_2$

$V_{RSM}$  = the transient voltage peak produced by the transformer

$V_{RWM}$  = the actually applied crest working reverse voltage

The capacitance values calculated from the above table are minimum values; to allow for circuit variations and component tolerances, larger values should be used.

## SILICON BI-DIRECTIONAL TRIGGER DEVICE

Silicon bi-directional trigger device intended for use in triac and thyristor trigger circuits.

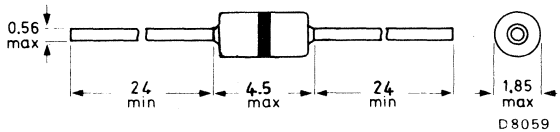
### QUICK REFERENCE DATA

Breakover voltage	$V_{(BO)}$		28 to 36	V
Output voltage	$V_O$	>	5	V
Repetitive peak current	$I_{FRM}$	max.	2	A

### MECHANICAL DATA

Dimensions in mm

Fig. 1



### RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC134)

Total power dissipation up to $T_{amb} = 50\text{ }^{\circ}\text{C}$	$P_{tot}$	max.	150	mW
Repetitive peak current ( $t \leq 20\text{ }\mu\text{s}$ )	$I_{FRM}$	max.	2	A
Storage temperature	$T_{stg}$		-55 to +125	$^{\circ}\text{C}$
Junction temperature	$T_j$	max.	100	$^{\circ}\text{C}$

### THERMAL RESISTANCE

From junction to ambient in free air	$R_{th\ j-a}$	=	0.33	K/mW
--------------------------------------	---------------	---	------	------

**CHARACTERISTICS**

$T_j = 25\text{ }^\circ\text{C}$

Breakover voltage at $\frac{dV}{dt} = 10\text{ V/ms}$	$V_{(BO)}$		28 to 36	V
Breakover voltage symmetry	$ V_{(BO)I} - V_{(BO)III} $	<	3	V
Output voltage at $\frac{dV}{dt} = 10\text{ V/ms}$	$V_O$	>	5	V
Breakover current at $V = 0.98 V_{(BO)}$	$I_{(BO)}$	<	100	$\mu\text{A}$

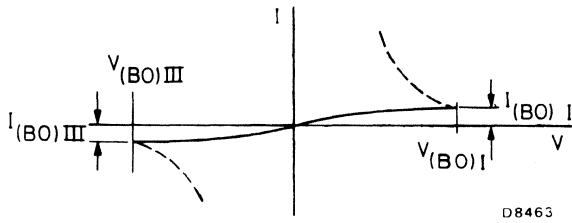


Fig.2

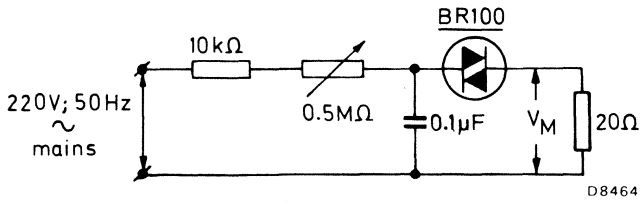


Fig. 3 Test circuit for output voltage



## THYRISTOR TETRODE

The BRY39T is a planar p-n-p-n trigger device in a TO-72 metal envelope, intended for use in low-power switching applications such as relay and lamp drivers, sensing network for temperature and as a trigger device for thyristors and triacs.

For BRY39P and BRY39S see 'Small signal transistors' handbook.

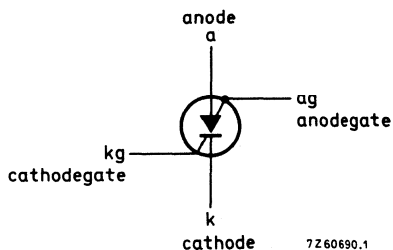
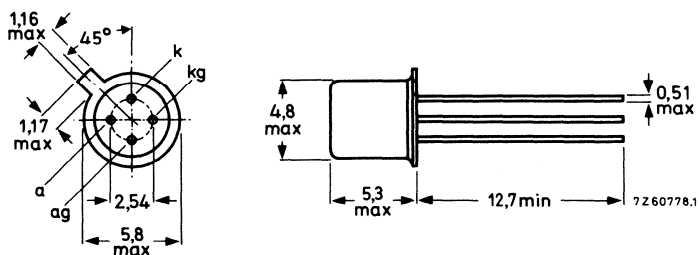
### QUICK REFERENCE DATA

Repetitive peak voltages	$V_{DRM} = V_{RRM}$	max.	70 V
Average on-state current	$I_{T(AV)}$	max.	250 mA
Non-repetitive peak on-state current	$I_{TSM}$	max.	3 A

### MECHANICAL DATA

Dimensions in mm

Fig.1 TO-72; Anode gate connected to case.



Accessories supplied on request: 56246 (distance disc)

**RATINGS**

Limiting values in accordance with the Absolute Maximum System (IEC 134)

**Anode to cathode**

Non-repetitive peak voltages	$V_{DSM} = V_{RSM}$	max.	70 V*
Repetitive peak voltages	$V_{DRM} = V_{RRM}$	max.	70 V*
Continuous voltages	$V_D = V_R$	max.	70 V*
Average on-state current up to $T_{case} = 85\text{ }^\circ\text{C}$ in free air up to $T_{amb} = 25\text{ }^\circ\text{C}$	$I_{T(AV)}$	max.	250 mA
	$I_{T(AV)}$	max.	175 mA
Repetitive peak on-state current $t = 10\text{ }\mu\text{s}; \delta = 0.01$	$I_{TRM}$	max.	2.5 A
Non-repetitive peak on-state current $t = 10\text{ }\mu\text{s}; T_j = 150\text{ }^\circ\text{C}$ prior to surge	$I_{TSM}$	max.	3 A
Rate of rise of on-state current after triggering to $I_T = 2.5\text{ A}$	$\frac{dI_T}{dt}$	max.	20 A/ $\mu\text{s}$

**Cathode gate to cathode**

Peak reverse voltage	$V_{RGKM}$	max.	5 V
Peak forward current	$I_{FGKM}$	max.	100 mA

**Anode gate to anode**

Peak reverse voltage	$V_{RGAM}$	max.	70 V
Peak forward current	$I_{FGAM}$	max.	100 mA

**Temperatures**

Storage temperature	$T_{stg}$		-65 to +200 $^\circ\text{C}$
Junction temperature	$T_j$	max.	150 $^\circ\text{C}$

**THERMAL RESISTANCE**

From junction to ambient in free air	$R_{th\ j-a}$	=	0.45 $^\circ\text{C}/\text{mW}$
From junction to case	$R_{th\ j-c}$	=	0.15 $^\circ\text{C}/\text{mW}$

\*These ratings apply for zero or negative bias on the cathode gate with respect to the cathode, and when a resistor  $R \leq 10\text{ k}\Omega$  is connected between cathode gate and cathode.

## CHARACTERISTICS

## Anode to cathode

On-state voltage $I_T = 100 \text{ mA}; T_j = 25 \text{ }^\circ\text{C}$	$V_T$	<	1.4 V*
Rate of rise of off-state voltage that will not trigger any device	$\frac{dV_D^{**}}{dt}$		
Reverse current $V_R = 70 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$	$I_R$	typ. <	1 nA 100 nA
$T_j = 150 \text{ }^\circ\text{C}$	$I_R$	<	2 $\mu\text{A}$
Off-state current $V_D = 70 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$	$I_D$	typ. <	1 nA 100 nA
$T_j = 150 \text{ }^\circ\text{C}$	$I_D$	<	2 $\mu\text{A}$
Holding current $R_{GK} = 10 \text{ k}\Omega; R_{GA} = 220 \text{ k}\Omega; T_j = 25 \text{ }^\circ\text{C}$	$I_H$	<	250 $\mu\text{A}$

## Cathode gate to cathode

Voltage that will trigger all devices $V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$	$V_{GKT}$	>	0.5 V
Current that will trigger all devices $V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$	$I_{GKT}$	>	1 $\mu\text{A}$

## Anode gate to anode

Voltage that will trigger all devices $V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$	$-V_{GAT}$	>	1 V
Current that will trigger all devices $V_D = 6 \text{ V}; R_{GK} = 10 \text{ k}\Omega; T_j = 25 \text{ }^\circ\text{C}$	$-I_{GAT}$	>	100 $\mu\text{A}$

\*Measured under pulse conditions to avoid excessive dissipation.

\*\*The  $dV_D/dt$  is unlimited when the anode gate lead is returned to the supply voltage through a current limiting resistor.

**Switching characteristics**

Gate-controlled turn-on time ( $t_{gt} = t_d + t_r$ )

when switched from  $V_D = 15\text{ V}$   
 to  $I_T = 150\text{ mA}$ ;  $I_{GK} = 5\text{ }\mu\text{A}$ ;  
 $dI_{GK}/dt = 5\text{ }\mu\text{A}/\mu\text{s}$ ;  $T_j = 25\text{ }^\circ\text{C}$

$$t_{gt} < 300\text{ ns}$$

Circuit-commutated turn-off time

when switched from  $I_T = 150\text{ mA}$   
 to  $V_R = 15\text{ V}$ ;  $-dI_T/dt = 3\text{ A}/\mu\text{s}$ ;  
 $dV_D/dt = 70\text{ V}/\mu\text{s}$ ;  $V_D = 15\text{ V}$

$$t_q < 3\text{ }\mu\text{s}$$

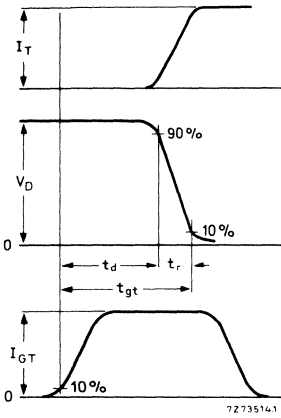


Fig.2 Gate-controlled turn-on time definition.

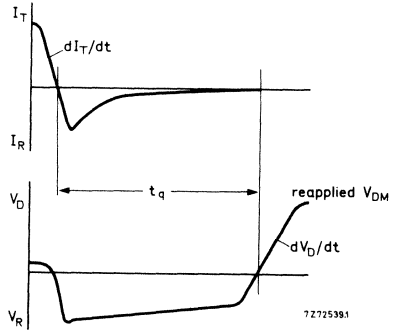


Fig.3 Circuit-commutated turn-off time definition.

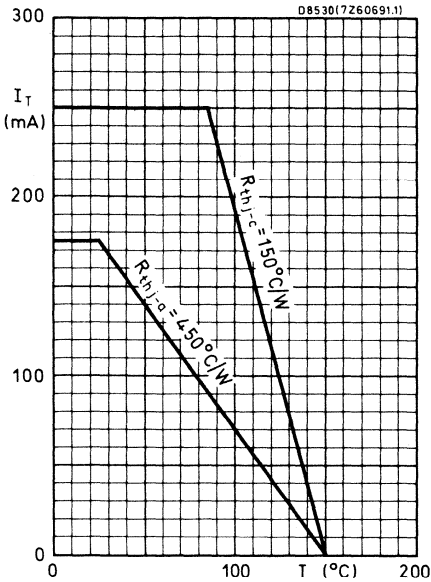


Fig.4

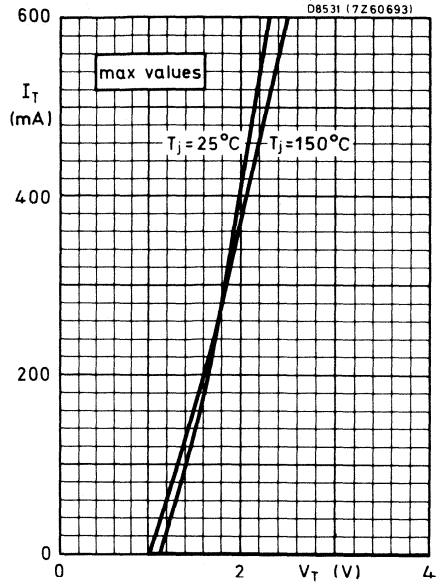


Fig.5

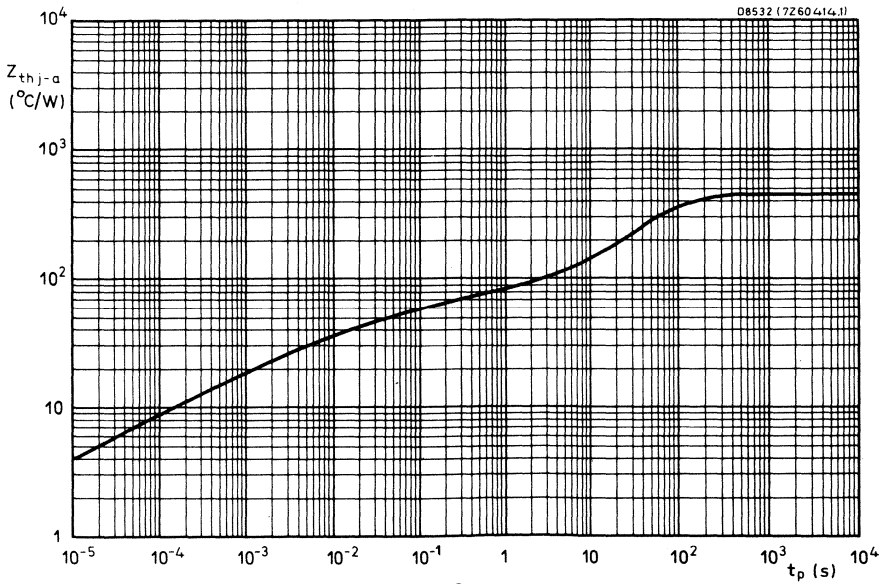


Fig.6

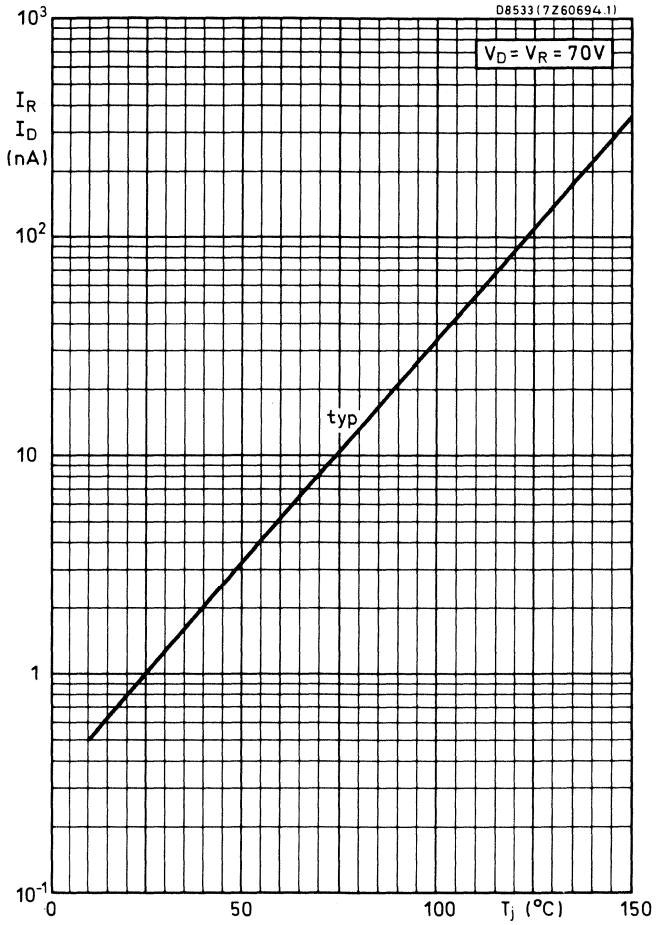


Fig.7

## APPLICATION INFORMATION

## Sensing network

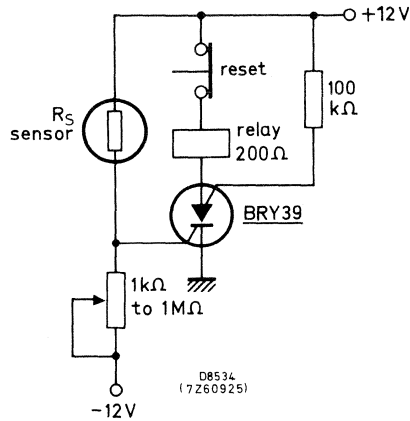


Fig.8

$R_S$  must be chosen in accordance with the light, temperature, or radiation intensity to be sensed; its resistance should be of the same order as that of the potentiometer.

In the arrangement shown, a decline in resistance of  $R_S$  triggers the thyristor, closing the relay that activates the warning system. If the positions of  $R_S$  and the potentiometer are interchanged, an increase in the resistance of  $R_S$  triggers the thyristor.





## THYRISTORS

Glass-passivated thyristors in TO-220AB envelopes, featuring eutectic bonding, thus being particularly suitable in situations creating high fatigue stresses involved in thermal cycling and repeated switching. Applications include temperature control, motor control, regulators in transformerless power supply applications, relay and coil pulsing and power supply crowbar protection circuits.

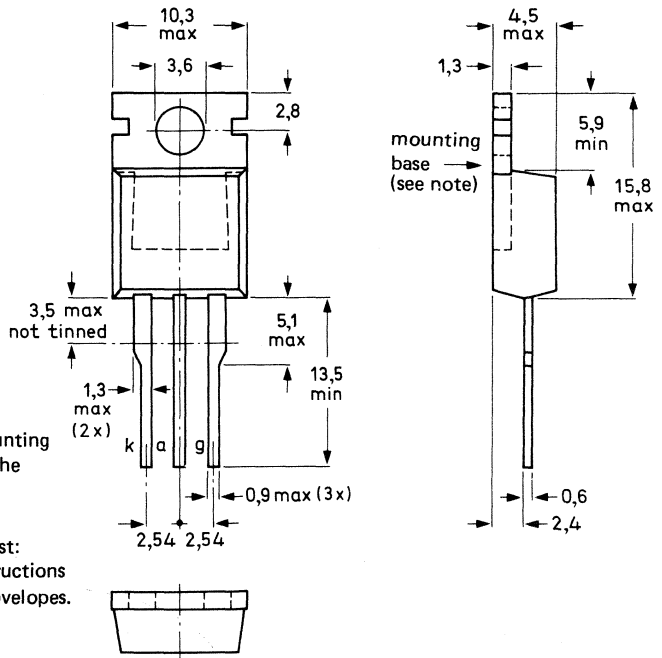
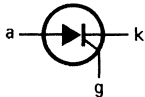
### QUICK REFERENCE DATA

		BT151-500R   650R	
		max.	500   650 V
Repetitive peak voltages	$V_{DRM}/V_{RRM}$	max.	500   650 V
Average on-state current	$I_T(AV)$	max.	7,5 A
R.M.S. on-state current	$I_T(RMS)$	max.	12 A
Non-repetitive peak on-state current	$I_{TSM}$	max.	100 A

### MECHANICAL DATA

Fig. 1 TO-220AB.

Dimensions in mm



Net mass: 2 g

Note: The exposed metal mounting base is directly connected to the anode.

Accessories supplied on request:  
see data sheets Mounting instructions  
and accessories for TO-220 envelopes.

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

<b>Anode to cathode</b>		BT151-500R   650R	
Non-repetitive peak voltages ( $t \leq 10$ ms)	$V_{DSM}/V_{RSM}$	max. 500	650 V*
Repetitive peak voltages ( $\delta \leq 0,01$ )	$V_{DRM}/V_{RRM}$	max. 500	650 V
Crest working voltages	$V_{DWM}/V_{RWM}$	max. 400	400 V
Continuous voltages	$V_D/V_R$	max. 400	400 V
Average on-state current (averaged over any 20 ms period) up to $T_{mb} = 95$ °C			
→ R.M.S. on-state current	$I_{T(AV)}$	max.	7,5 A
Repetitive peak on-state current	$I_{T(RMS)}$	max.	12 A
Repetitive peak on-state current	$I_{TRM}$	max.	65 A
Non-repetitive peak on-state current; $t = 10$ ms; half sine-wave; $T_j = 110$ °C prior to surge; with reapplied $V_{RWMmax}$			
→ $I^2 t$ for fusing ( $t = 10$ ms)	$I_{TSM}$	max.	100 A
	$I^2 t$	max.	50 A <sup>2</sup> s
Rate of rise of on-state current after triggering with $I_G = 50$ mA to $I_T = 20$ A; $dI_G/dt = 50$ mA/ $\mu$ s			
	$dI_T/dt$	max.	50 A/ $\mu$ s
<b>Gate to cathode</b>			
Reverse peak voltage	$V_{RGM}$	max.	5 V
Average power dissipation (averaged over any 20 ms period)	$P_{G(AV)}$	max.	0,5 W
Peak power dissipation	$P_{GM}$	max.	5 W
<b>Temperatures</b>			
Storage temperature	$T_{stg}$		-40 to +125 °C
→ Operating junction temperature	$T_j$	max.	110 °C

\* Although not recommended, higher off-state voltages may be applied without damage, but the thyristor may switch into the on-state. The rate of rise of on-state current should not exceed 15 A/ $\mu$ s.

**THERMAL RESISTANCE**

From junction to mounting base

$$R_{th\ j-mb} = 1,3\ ^\circ C/W$$

Transient thermal impedance;  $t = 1\ ms$ 

$$Z_{th\ j-mb} = 0,2\ ^\circ C/W$$

**Influence of mounting method**

## 1. Heatsink mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound

$$R_{th\ mb-h} = 0,3\ ^\circ C/W$$

b. with heatsink compound and 0,06 mm maximum mica insulator

$$R_{th\ mb-h} = 1,4\ ^\circ C/W$$

c. with heatsink compound and 0,1 mm maximum mica insulator (56369)

$$R_{th\ mb-h} = 2,2\ ^\circ C/W$$

d. with heatsink compound and 0,25 mm max. alumina insulator (56367)

$$R_{th\ mb-h} = 0,8\ ^\circ C/W$$

e. without heatsink compound

$$R_{th\ mb-h} = 1,4\ ^\circ C/W$$

## 2. Free-air operation

The quoted values of  $R_{th\ j-a}$  should be used only when no leads of other dissipating components run to the same tie-point.

Thermal resistance from junction to ambient in free air:  
mounted on a printed-circuit board at a = any lead length  
and with copper laminate

$$R_{th\ j-a} = 60\ ^\circ C/W$$

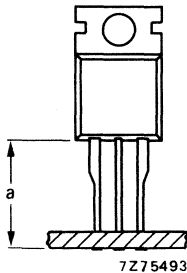


Fig. 2.

→ CHARACTERISTICS

**Anode to cathode**

On-state voltage

$I_T = 23 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_T < 1,75 \text{ V}^*$

Rate of rise of off-state voltage that will not trigger any device;  $T_j = 110 \text{ }^\circ\text{C}$ ; see Fig.10

$R_{GK} = \text{open circuit}$

$R_{GK} = 100 \text{ } \Omega$

$dV_D/dt < 50 \text{ V}/\mu\text{s}$   
 $dV_D/dt < 200 \text{ V}/\mu\text{s}$

Reverse current

$V_R = V_{RWMmax}; T_j = 110 \text{ }^\circ\text{C}$

$I_R < 0,5 \text{ mA}$

Off-state current

$V_D = V_{DWMmax}; T_j = 110 \text{ }^\circ\text{C}$

$I_D < 0,5 \text{ mA}$

Latching current;  $T_j = 25 \text{ }^\circ\text{C}$

$I_L < 40 \text{ mA}$

Holding current;  $T_j = 25 \text{ }^\circ\text{C}$

$I_H < 20 \text{ mA}$

**Gate to cathode**

Voltage that will trigger all devices

$V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$

$V_D = 6 \text{ V}; T_j = -40 \text{ }^\circ\text{C}$

$V_{GT} > 1,5 \text{ V}$   
 $V_{GT} > 2,3 \text{ V}$

Voltage that will not trigger any device

$V_D = V_{DRMmax}; T_j = 110 \text{ }^\circ\text{C}$

$V_{GD} < 250 \text{ mV}$

Current that will trigger all devices

$V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$

$V_D = 6 \text{ V}; T_j = -40 \text{ }^\circ\text{C}$

$I_{GT} > 15 \text{ mA}$   
 $I_{GT} > 20 \text{ mA}$

**Switching characteristics**

Gate-controlled turn-on time ( $t_{gt} = t_d + t_r$ ) when switched from  $V_D = V_{DRMmax}$  to  $I_T = 40 \text{ A}$ ;

$I_{GT} = 100 \text{ mA}; dI_G/dt = 5 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

$t_{gt} \text{ typ. } 2 \text{ } \mu\text{s}$

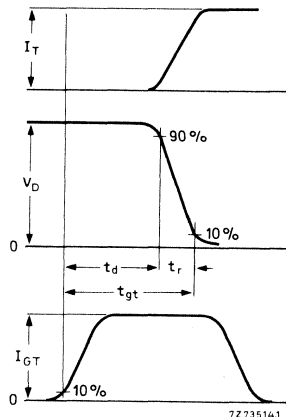


Fig.2a Gate controlled turn-on time definition.

\*Measured under pulse conditions to avoid excessive dissipation.

### MOUNTING INSTRUCTIONS

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; it must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4,7 mm from the seal.
2. The leads should not be bent less than 2,4 mm from the seal, and should be supported during bending.
3. It is recommended that the circuit connection be made to the anode tag, rather than direct to the heatsink.
4. Mounting by means of a spring clip is the best mounting method because it offers:
  - a. a good thermal contact under the crystal area and slightly lower  $R_{th\ mb-h}$  values than screw mounting.
  - b. safe isolation for mains operation.
 However, if a screw is used, it should be M3 cross-recess pan-head. Care should be taken to avoid damage to the plastic body.
5. For good thermal contact heatsink compound should be used between mounting base and heatsink. Values of  $R_{th\ mb-h}$  given for mounting with heatsink compound refer to the use of a metallic-oxide loaded compound. Ordinary silicone grease is not recommended.
6. The device should not be pop-ripped to the heatsink. However, it is permissible to press-rivet providing that rivets of soft material are used, and the press forces are slowly and carefully controlled so as to avoid shock and deformation of either heatsink or mounting tab.

### OPERATING NOTES

Dissipation and heatsink considerations:

- a. The various components of junction temperature rise above ambient are illustrated in Fig. 3.

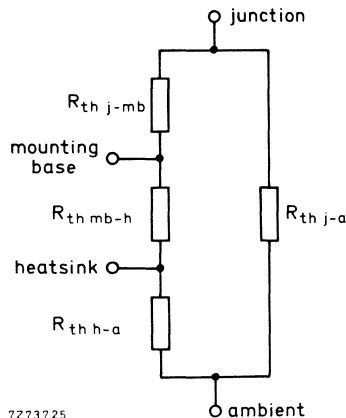


Fig. 3.

- b. The method of using Fig. 4 is as follows:

Starting with the required current on the  $I_T(AV)$  axis, trace upwards to meet the appropriate form factor curve. Trace right horizontally and upwards from the appropriate value on the  $T_{amb}$  scale.

The intersection determines the  $R_{th\ mb-a}$ . The heatsink thermal resistance value ( $R_{th\ h-a}$ ) can now be calculated from:

$$R_{th\ h-a} = R_{th\ mb-a} - R_{th\ mb-h}$$

- c. Any measurement of heatsink temperature should be made immediately adjacent to the device.

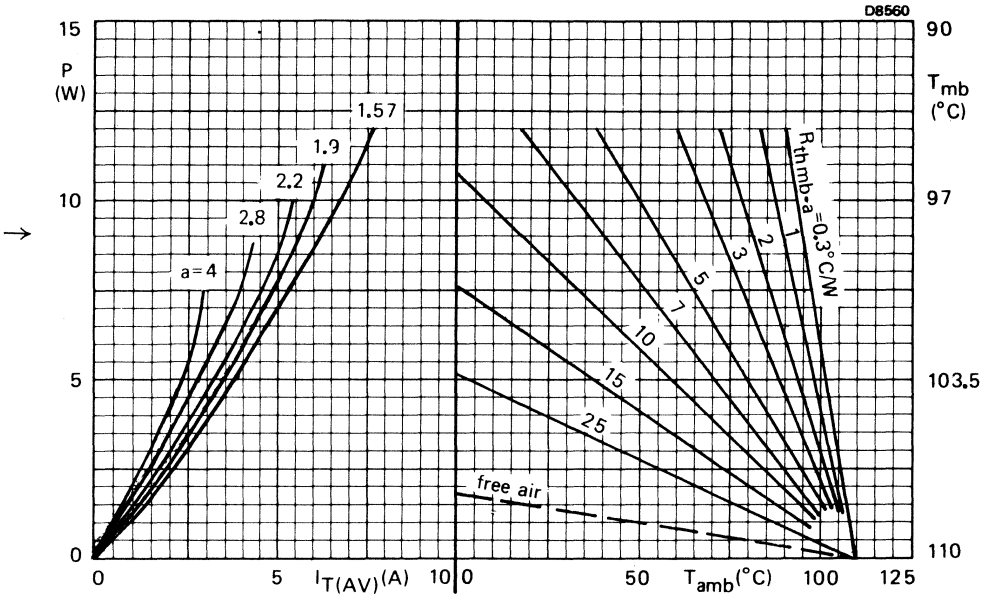
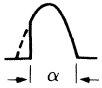


Fig. 4 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.



$\alpha$  = conduction angle per half cycle

$$a = \text{form factor} = \frac{I_T(\text{RMS})}{I_T(\text{AV})}$$

$\alpha$	a
30°	4
60°	2,8
90°	2,2
120°	1,9
180°	1,57

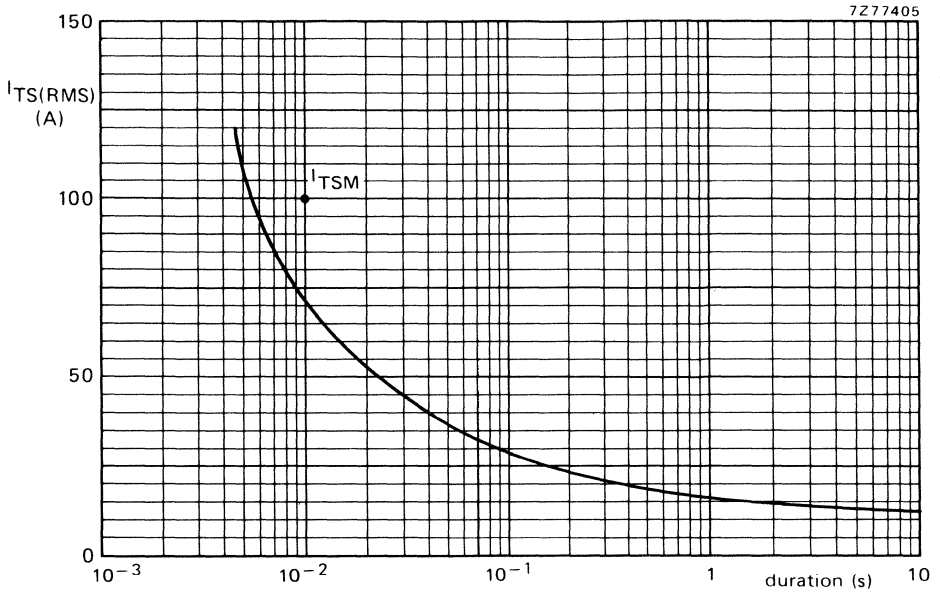
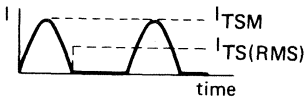


Fig.5 Maximum permissible non-repetitive r.m.s. on-state current based on sinusoidal currents ( $f = 50$  Hz);  $T_j = 110$  °C prior to surge; with reapplied  $V_{RWMmax}$ .



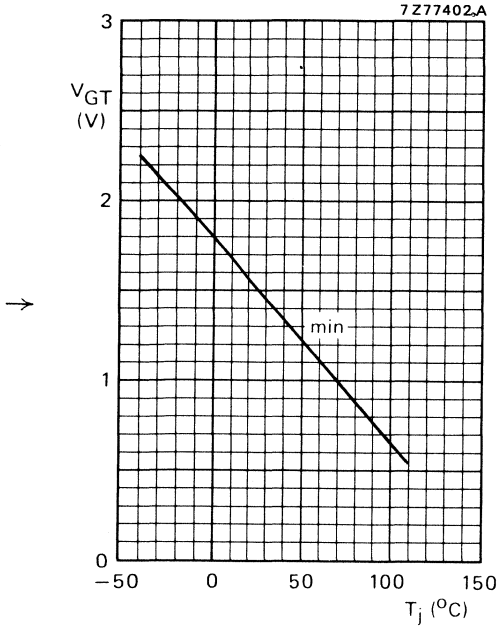


Fig. 6 Minimum gate voltage that will trigger all devices as a function of junction temperature.

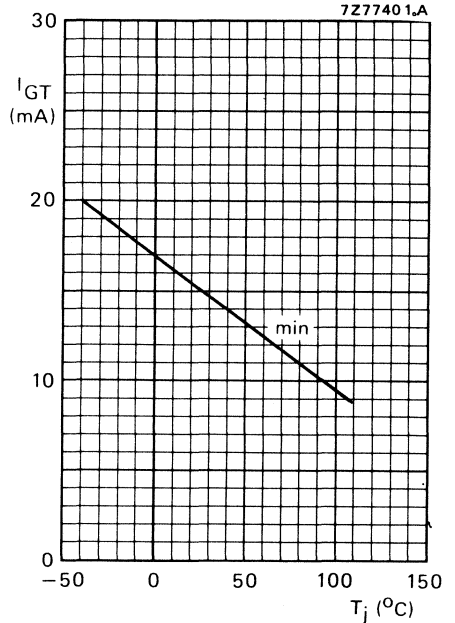


Fig. 7 Minimum gate current that will trigger all devices as a function of junction temperature.

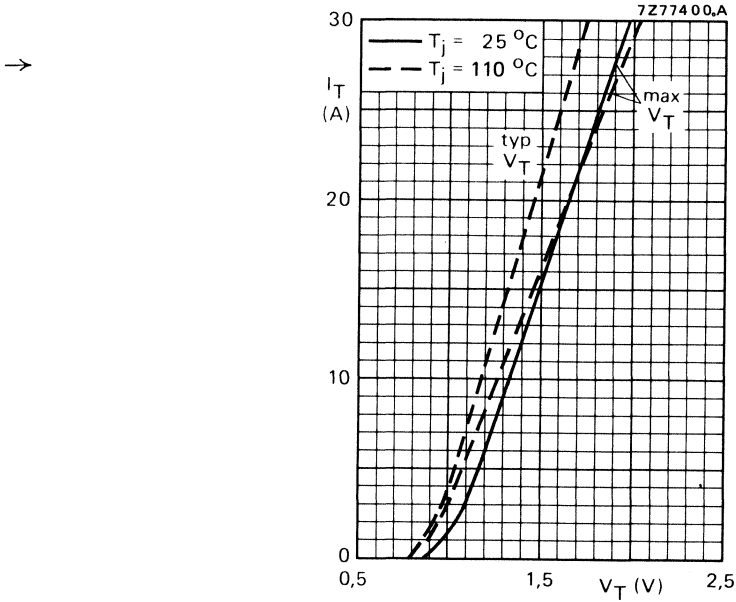


Fig. 8.



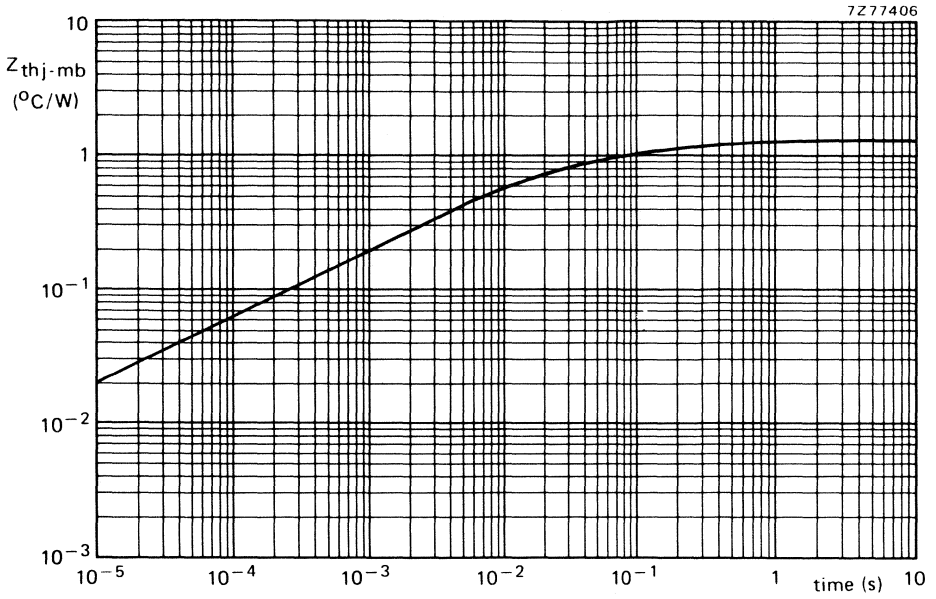


Fig. 9.

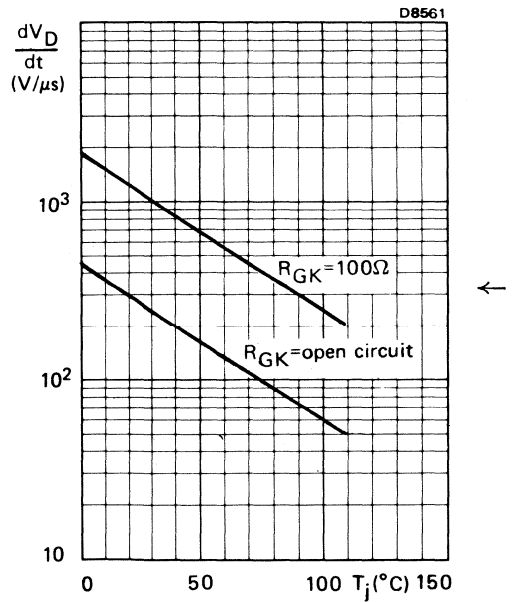


Fig. 10 Maximum rate of rise of off-state voltage that will not trigger any device (exponential method) as a function of junction temperature.



## THYRISTORS

Glass-passivated thyristors in TO-220AB envelopes, featuring eutectic bonding, thus being particularly suitable in situations creating high fatigue stresses involved in thermal cycling and repeated switching. Applications include temperature control, motor control, regulators in transformerless power supply applications, relay and coil pulsing and power supply crowbar protection circuits.

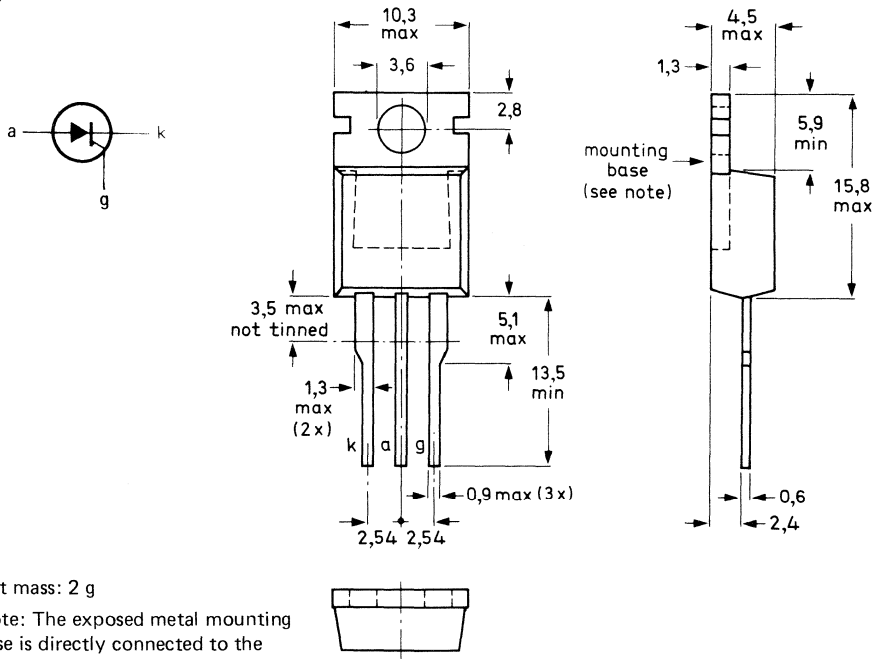
### QUICK REFERENCE DATA

		BT152-400R			600R	800R	
Repetitive peak voltages	$V_{DRM}/V_{RRM}$	max.	400	600	800	V	
Average on-state current	$I_{T(AV)}$	max.		13		A	
R.M.S. on-state current	$I_{T(RMS)}$	max.		20		A	
Non-repetitive peak on-state current	$I_{TSM}$	max.		200		A	

### MECHANICAL DATA

Dimensions in mm

Fig.1 TO-220AB



Net mass: 2 g

Note: The exposed metal mounting base is directly connected to the anode.

Accessories supplied on request:  
see data sheets Mounting instructions  
and accessories for TO-220 envelopes.

**RATINGS**

Limiting values in accordance with the Absolute Maximum System (IEC 134)

		BT152-400R				600R	800R
		max.	450	650	850	V	
<b>Anode to cathode</b>							
Non-repetitive peak voltages	$V_{DSM}/V_{RSM}$	max.	450	650	850	V	
Repetitive peak voltages	$V_{DRM}/V_{RRM}$	max.	400	600	800	V	
Crest working voltages	$V_{DWM}/V_{RWM}$	max.	400	400	400	V	
Average on-state current (averaged over any 20 ms period) up to $T_{mb} = 93\text{ }^{\circ}\text{C}$		$I_{T(AV)}$	max.	13		A	
R.M.S. on-state current		$I_{T(RMS)}$	max.	20		A	
Repetitive peak on-state current		$I_{TRM}$	max.	200		A	
Non-repetitive peak on-state current; $t = 10\text{ ms}$ ; half sine-wave; $T_j = 115\text{ }^{\circ}\text{C}$ prior to surge; with reapplied $V_{RWMmax}$		$I_{TSM}$	max.	200		A	
$I^2t$ for fusing ( $t = 10\text{ ms}$ )		$I^2t$	max.	200		$\text{A}^2\text{s}$	
Rate of rise of on-state current after triggering with $I_G = 160\text{ mA}$ to $I_T = 50\text{ A}$ ; $dI_G/dt = 160\text{ A/ms}$		$dI_T/dt$	max.	200		$\text{A}/\mu\text{s}$	
<b>Gate to cathode</b>							
Reverse peak voltage		$V_{RGM}$	max.	5		V	
Average power dissipation (averaged over any 20 ms period)		$P_{G(AV)}$	max.	0.5		W	
Peak power dissipation; $t \leq 10\text{ }\mu\text{s}$		$P_{GM}$	max.	20		W	
<b>Temperature</b>							
Storage temperature		$T_{stg}$		-40 to +150		$^{\circ}\text{C}$	
Junction temperature		$T_j$	max.	115		$^{\circ}\text{C}$	
<b>THERMAL RESISTANCE</b>							
From junction to mounting base		$R_{th\ j-mb}$	=	1.1		$^{\circ}\text{C/W}$	
From mounting base to heatsink with heatsink compound		$R_{th\ mb-h}$	=	0.3		$^{\circ}\text{C/W}$	

**CHARACTERISTICS**

**Anode to cathode**

On-state voltage (measured under pulse conditions)

$I_T = 40 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_T < 1.75 \text{ V}$

Rate of rise of off-state voltage that will not trigger any device

$T_j = 115 \text{ }^\circ\text{C}; R_{GK} = \text{open circuit}$

$dV_D/dt < 200 \text{ V}/\mu\text{s}$

Reverse current

$V_R = V_{RWMmax}; T_j = 115 \text{ }^\circ\text{C}$

$I_R < 1.0 \text{ mA}$

Off-state current

$V_D = V_{DWMmax}; T_j = 115 \text{ }^\circ\text{C}$

$I_D < 1.0 \text{ mA}$

Latching current;  $T_j = 25 \text{ }^\circ\text{C}$

$I_L < 80 \text{ mA}$

Holding current;  $T_j = 25 \text{ }^\circ\text{C}$

$I_H < 60 \text{ mA}$

**Gate to cathode**

Voltage that will trigger all devices

$V_D = 12 \text{ V}; T_j = -40 \text{ }^\circ\text{C}$

$V_{GT} > 1.5 \text{ V}$

$V_D = 12 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$

$V_{GT} > 1.0 \text{ V}$

Voltage that will not trigger any device

$V_D = V_{DRMmax}; T_j = 115 \text{ }^\circ\text{C}$

$V_{GD} < 0.25 \text{ V}$

Current that will trigger all devices

$V_D = 12 \text{ V}; T_j = -40 \text{ }^\circ\text{C}$

$I_{GT} > 50 \text{ mA}$

$V_D = 12 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$

$I_{GT} > 32 \text{ mA}$

**Switching characteristics**

Gate-controlled turn-on time ( $t_{gt} = t_d + t_r$ ) when switched from  $V_D = V_{DRMmax}$  to  $I_T = 40 \text{ A}$ ;  $I_{GT} = 100 \text{ mA}; dI_{GT}/dt = 5 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

$t_{gt} \text{ typ. } 2 \mu\text{s}$

Circuit-commutated turn-off time when switched from  $I_T = 40 \text{ A}$  to  $V_R > 50 \text{ V}$  with  $-dI_T/dt = 10 \text{ A}/\mu\text{s}$ ;  $dV_D/dt = 50 \text{ V}/\mu\text{s}; T_j = 115 \text{ }^\circ\text{C}$

$t_q \text{ typ. } 35 \mu\text{s}$

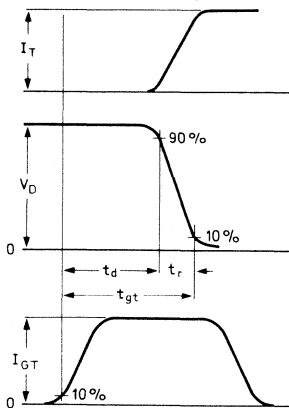


Fig.2 Gate-controlled turn-on time definition.

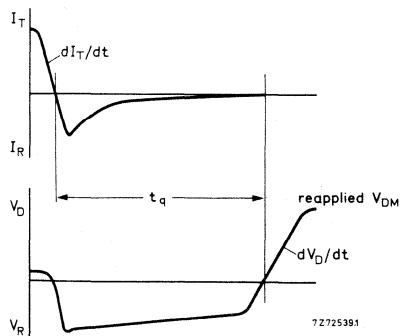


Fig.3 Circuit-commutated turn-off time definition.

**MOUNTING INSTRUCTIONS**

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; it must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
2. The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending.
3. It is recommended that the circuit connection be made to the anode tag, rather than direct to the heatsink.
4. Mounting by means of a spring clip is the best mounting method because it offers:
  - a. a good thermal contact under the crystal area and slightly lower  $R_{th\ mb-h}$  values than screw mounting.
  - b. safe isolation for mains operation.
 However, if a screw is used, it should be M3 cross-recess pan-head. Care should be taken to avoid damage to the plastic body.
5. For good thermal contact heatsink compound should be used between mounting base and heatsink. Values of  $R_{th\ mb-h}$  given for mounting with heatsink compound refer to the use of a metallic-oxide loaded compound. Ordinary silicone grease is not recommended.
6. The device should not be pop-riveted to the heatsink. However, it is permissible to press-rivet providing that rivets of soft material are used, and the press forces are slowly and carefully controlled so as to avoid shock and deformation of either heatsink or mounting tab.

**OPERATING NOTES**

Dissipation and heatsink considerations:

- a. The various components of junction temperature rise above ambient are illustrated in Fig.4.

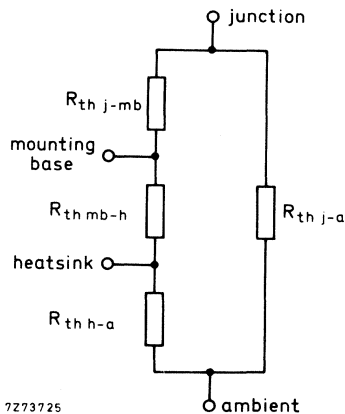


Fig.4

- b. The method of using Fig.5 is as follows:  
 Starting with the required current on the  $I_T(AV)$  axis, trace upwards to meet the appropriate form factor curve. Trace right horizontally and upwards from the appropriate value on the  $T_{amb}$  scale. The intersection determines the  $R_{th\ mb-a}$ . The heatsink thermal resistance value ( $R_{th\ h-a}$ ) can now be calculated from:

$$R_{th\ h-a} = R_{th\ mb-a} - R_{th\ mb-h}$$

- c. Any measurement of heatsink temperature should be made immediately adjacent to the device.

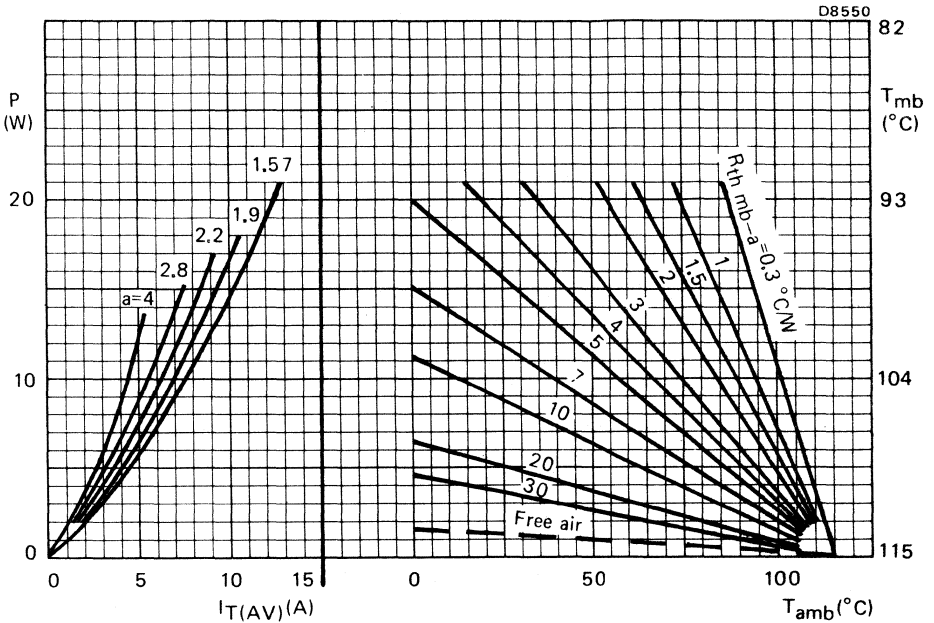


Fig.5 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.



$\alpha$  = conduction angle per half cycle

$$a = \text{form factor} = \frac{I_T \text{ (RMS)}}{I_T \text{ (AV)}}$$

$\alpha$	a
30°	4
60°	2.8
90°	2.2
120°	1.9
180°	1.57

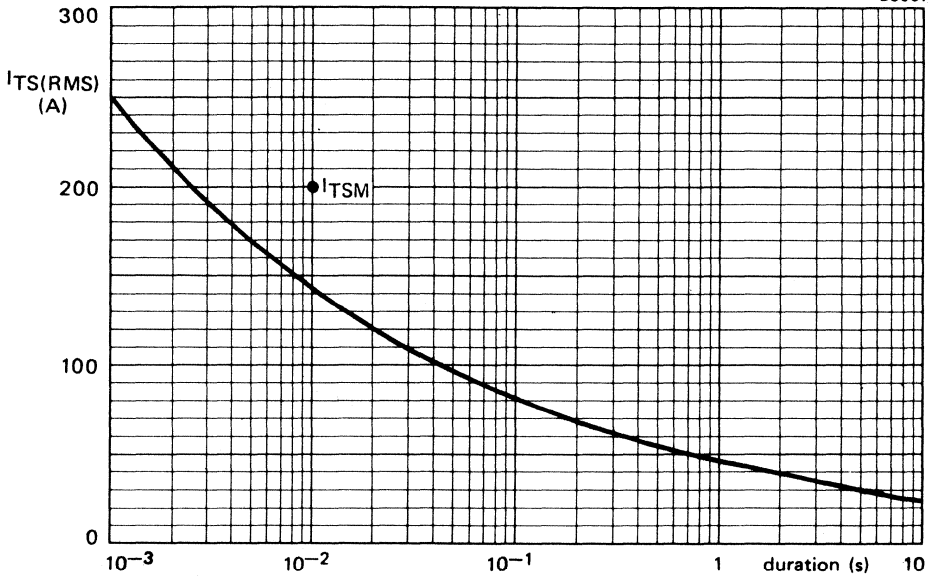
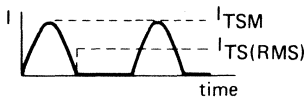


Fig.6 Maximum permissible non-repetitive r.m.s. on-state current based on sinusoidal currents ( $f = 50$  Hz);  $T_j = 115$  °C prior to surge; with reapplied  $V_{RWMmax}$ .





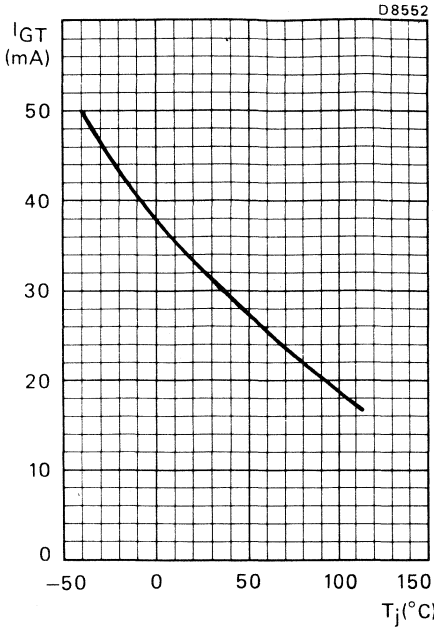


Fig. 7 Minimum gate current that will trigger all devices as a function of junction temperature.

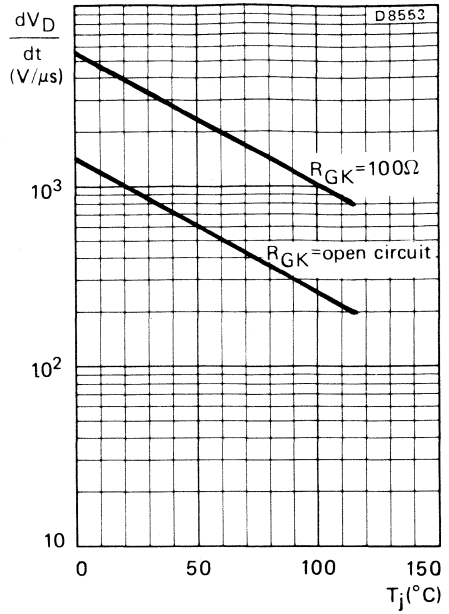


Fig.8 Maximum rate of rise of off-state voltage that will not trigger any device as a function of junction temperature.

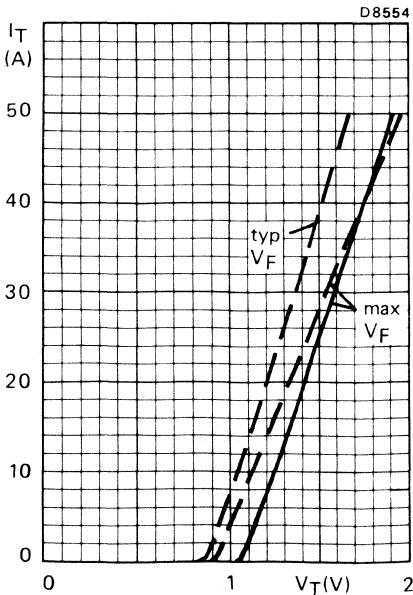


Fig.9 —  $T_j = 25^\circ\text{C}$ ; ---  $T_j = 115^\circ\text{C}$

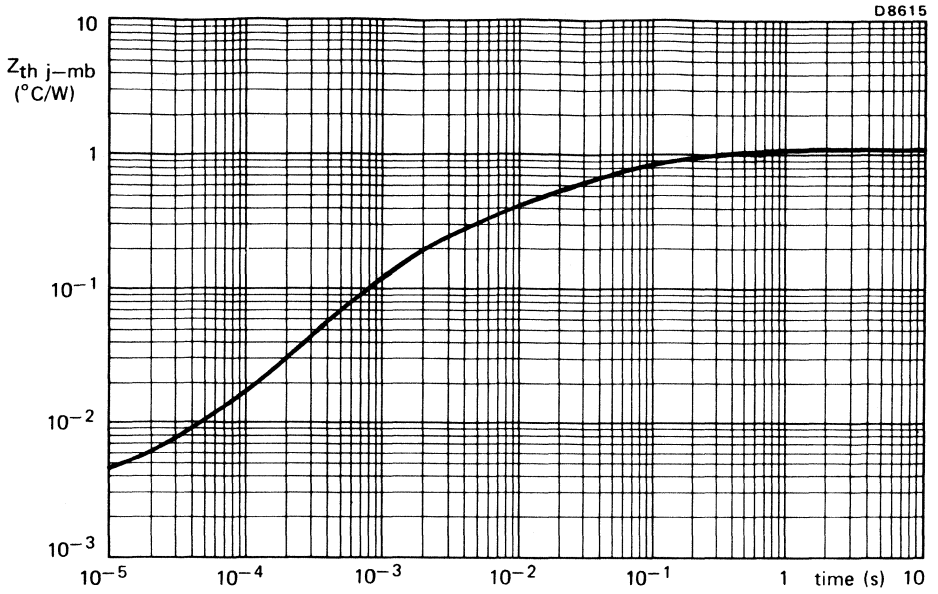


Fig. 10

## FAST TURN-OFF THYRISTOR

Glass-passivated, eutectically bonded, fast turn-off thyristor in a TO-220AB envelope, intended for use in inverter, pulse and switching applications. Its characteristics make the device extremely suitable for use in regulator, vertical deflection, and east/west correction circuits of colour television receivers.

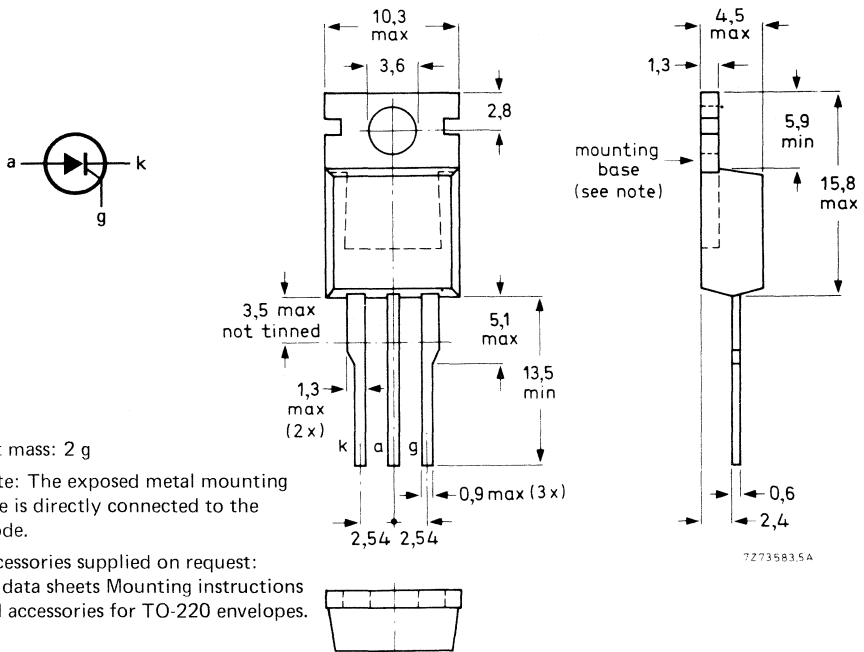
## QUICK REFERENCE DATA

Repetitive peak off-state voltage	$V_{DRM}$	max.	500 V
Average on-state current	$I_{T(AV)}$	max.	4 A
R.M.S. on-state current	$I_{T(RMS)}$	max.	6 A
Repetitive peak on-state current	$I_{TRM}$	max.	30 A
Circuit-commutated turn-off time	$t_q$	<	20 $\mu$ s

## MECHANICAL DATA

Dimensions in mm

Fig. 1 TO-220AB.



**RATINGS**

Limiting values in accordance with the Absolute Maximum System (IEC 134)

**Anode to cathode**

Non-repetitive peak voltages ( $t \leq 10$ ms)	$V_{DSM}/V_{RSM}$	max.	550 V
Repetitive peak voltages	$V_{DRM}/V_{RRM}$	max.	500 V
Working voltages	$V_{DW}/V_{RW}$	max.	400 V *
Average on-state current (averaged over any 20 ms period) up to $T_{mb} = 95$ °C	$I_{T(AV)}$	max.	4 A
R.M.S. on-state current	$I_{T(RMS)}$	max.	6 A
Working peak on-state current	$I_{TWM}$	max.	10 A
Repetitive peak on-state current	$I_{TRM}$	max.	30 A
Non-repetitive peak on-state current; $t = 10$ ms; half sine-wave; $T_j = 110$ °C prior to surge; with reapplied $V_{RWMmax}$	$I_{TSM}$	max.	40 A
$I^2t$ for fusing; $t = 10$ ms; $T_j = 25$ °C	$I^2t$	max.	10 A <sup>2</sup> s
Rate of rise of on-state current after triggering up to $f = 20$ kHz; $V_{DM} = 300$ V to $I_{TM} = 6$ A	$dI_T/dt$	max.	200 A/ $\mu$ s

**Gate to cathode**

Average power dissipation (averaged over any 20 ms period)	$P_{G(AV)}$	max.	1 W
Peak power dissipation; $t = 10$ $\mu$ s	$P_{GM}$	max.	25 W

**Temperatures**

Storage temperature	$T_{stg}$	-40 to + 125 °C
Operating junction temperature	$T_j$	max. 110 °C

\* Voltage shapes as occurring in the intended application.

**THERMAL RESISTANCE**

From junction to mounting base

$$R_{th\ j-mb} = 1,5\ ^\circ C/W$$

Transient thermal impedance;  $t = 1\ ms$ 

$$Z_{th\ j-mb} = 0,2\ ^\circ C/W$$

**Influence of mounting method**

1. Heatsink mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound

$$R_{th\ mb-h} = 0,3\ ^\circ C/W$$

b. with heatsink compound and 0,06 mm maximum mica insulator

$$R_{th\ mb-h} = 1,4\ ^\circ C/W$$

c. with heatsink compound and 0,1 mm maximum mica insulator (56369)

$$R_{th\ mb-h} = 2,2\ ^\circ C/W$$

d. with heatsink compound and 0,25 mm max. alumina insulator (56367)

$$R_{th\ mb-h} = 0,8\ ^\circ C/W$$

e. without heatsink compound

$$R_{th\ mb-h} = 1,4\ ^\circ C/W$$

2. Free-air operation

The quoted values of  $R_{th\ j-a}$  should be used only when no leads of other dissipating components run to the same tie-point.

Thermal resistance from junction to ambient in free air:  
mounted on a printed-circuit board at  $a =$  any lead length  
and with copper laminate

$$R_{th\ j-a} = 60\ ^\circ C/W$$

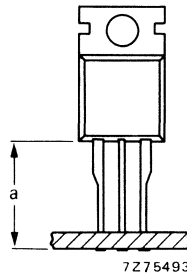


Fig. 2.

**CHARACTERISTICS**

**Anode to cathode**

On-state voltage

$$I_T = 10 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$$

$$V_T < 2,5 \text{ V}^*$$

Rate of rise of off-state voltage that will not trigger any device;  $T_j \leq 110 \text{ }^\circ\text{C}$

$$dV_D/dt < 200 \text{ V}/\mu\text{s}$$

Off-state current

$$V_D = V_{DRMmax}; T_j = 110 \text{ }^\circ\text{C}$$

$$I_D < 1,5 \text{ mA}$$

Holding current;  $T_j = 25 \text{ }^\circ\text{C}$

$$I_H < 100 \text{ mA}$$

**Gate to cathode**

Voltage that will trigger all devices

$$V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}; t_p \geq 5 \mu\text{s}$$

$$V_{GT} > 2,5 \text{ V}$$

Current that will trigger all devices

$$V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}; t_p \geq 5 \mu\text{s}$$

$$I_{GT} > 40 \text{ mA}$$

**Switching characteristics**

Circuit-commutated turn-off time (in regulating circuits)

when switched from  $I_T = 6 \text{ A}$  to  $V_R \geq 50 \text{ V}$  with  
 $-dI_T/dt = 10 \text{ A}/\mu\text{s}$ ;  $dV_D/dt = 200 \text{ V}/\mu\text{s}$ ;  $V_{DM} = 500 \text{ V}$ ;  
 $R_{GK} = 68 \Omega$ ;  $T_{mb} = 80 \text{ }^\circ\text{C}$ ;  $t_p \leq 50 \mu\text{s}$

$$t_q < 20 \mu\text{s}$$

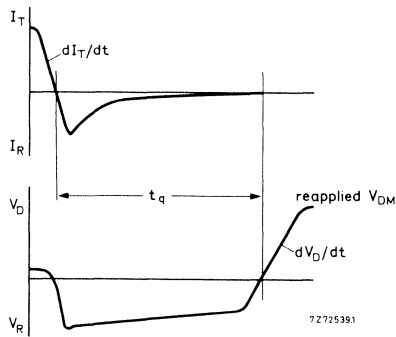


Fig. 3 Circuit-commutated turn-off time definition.

\* Measured under pulse conditions to avoid excessive dissipation.

### MOUNTING INSTRUCTIONS

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; it must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4,7 mm from the seal.
2. The leads should not be bent less than 2,4 mm from the seal, and should be supported during bending.
3. It is recommended that the circuit connection be made to the anode tag, rather than direct to the heatsink.
4. Mounting by means of a spring clip is the best mounting method because it offers:
  - a. a good thermal contact under the crystal area and slightly lower  $R_{th\ mb-h}$  values than screw mounting.
  - b. safe isolation for mains operation.
 However, if a screw is used, it should be M3 cross-recess pan-head. Care should be taken to avoid damage to the plastic body.
5. For good thermal contact heatsink compound should be used between mounting base and heatsink. Values of  $R_{th\ mb-h}$  given for mounting with heatsink compound refer to the use of a metallic-oxide loaded compound. Ordinary silicone grease is not recommended.
6. The device should not be pop-riveted to the heatsink. However, it is permissible to press-rivet providing that rivets of soft material are used, and the press forces are slowly and carefully controlled so as to avoid shock and deformation of either heatsink or mounting tab.

### OPERATING NOTES

Dissipation and heatsink considerations:

- a. The various components of junction temperature rise above ambient are illustrated in Fig. 4.

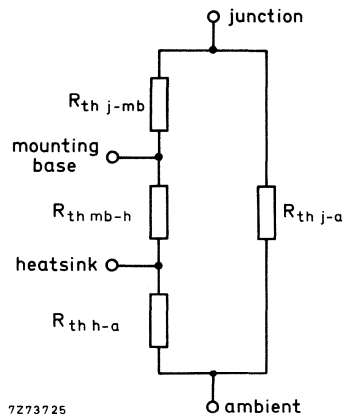


Fig. 4.

- b. The method of using Fig. 5 is as follows:

Starting with the required current on the  $I_T(AV)$  axis, trace upwards to meet the appropriate form factor curve. Trace right horizontally and upwards from the appropriate value on the  $T_{amb}$  scale. The intersection determines the  $R_{th\ mb-a}$ . The heatsink thermal resistance value ( $R_{th\ h-a}$ ) can now be calculated from:

$$R_{th\ h-a} = R_{th\ mb-a} - R_{th\ mb-h}$$

- c. Any measurement of heatsink temperature should be made immediately adjacent to the device.

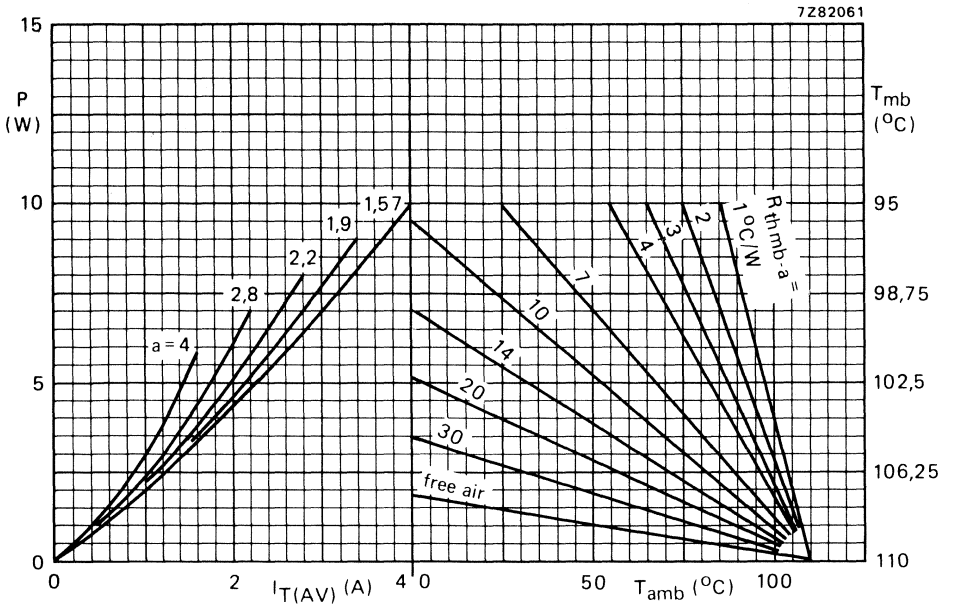


Fig. 5 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.



$\alpha$  = conduction angle per half cycle

$$a = \text{form factor} = \frac{I_T(\text{RMS})}{I_T(\text{AV})}$$

$\alpha$	a
30°	4
60°	2,8
90°	2,2
120°	1,9
180°	1,57



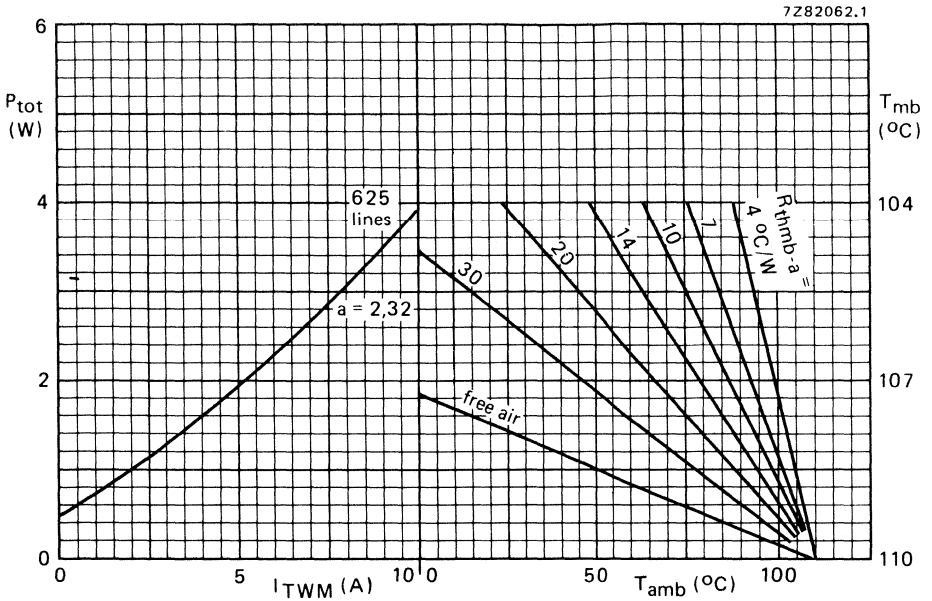


Fig. 6 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.  $P_{tot}$  = maximum power dissipation including gate and switching losses.  $I_{TWM}$  = maximum working peak on-state current.

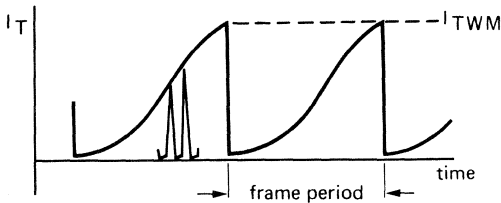


Fig. 7 Waveform defining  $I_{TWM}$ .

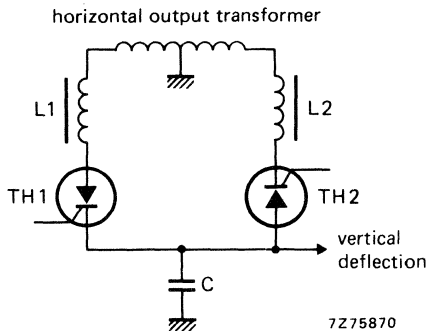


Fig. 8 Basic circuit of a vertical deflection system.

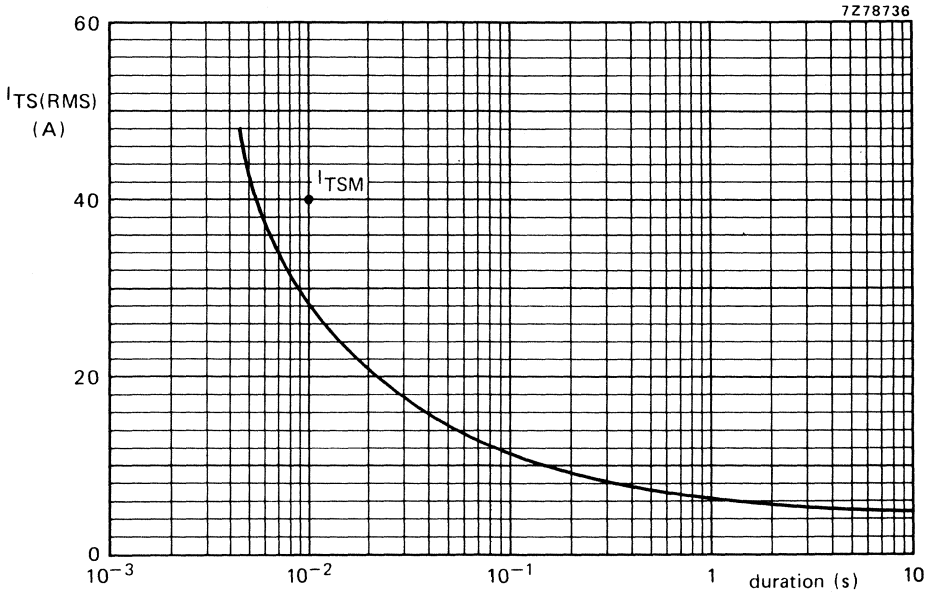
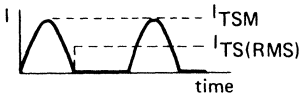


Fig. 9 Maximum permissible non-repetitive r.m.s. on-state current based on sinusoidal currents (f = 50 Hz);  $T_j = 110^\circ\text{C}$  prior to surge; with reapplied  $V_{RWMmax}$ .



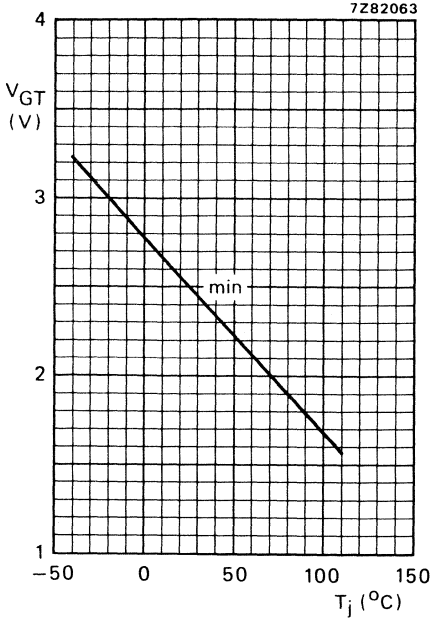


Fig. 10 Minimum gate voltage that will trigger all devices as a function of junction temperature.

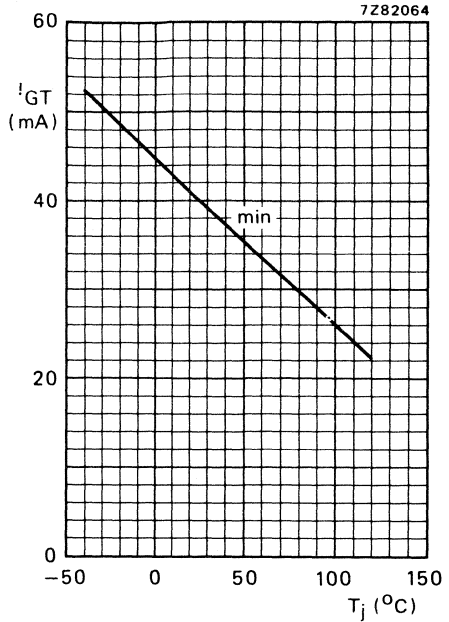


Fig. 11 Minimum gate current that will trigger all devices as a function of junction temperature.

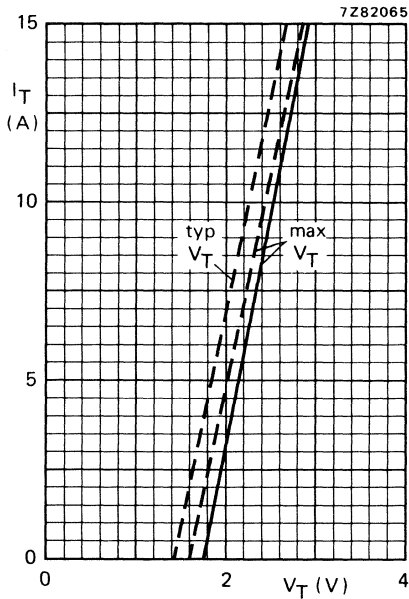


Fig. 12 —  $T_j = 25^{\circ}\text{C}$ ; ---  $T_j = 110^{\circ}\text{C}$ .

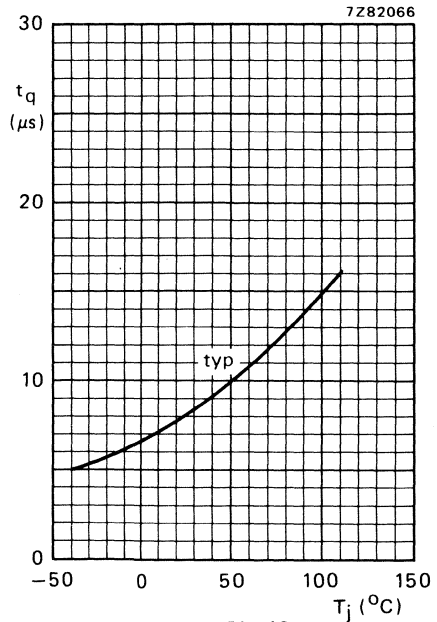


Fig. 13.

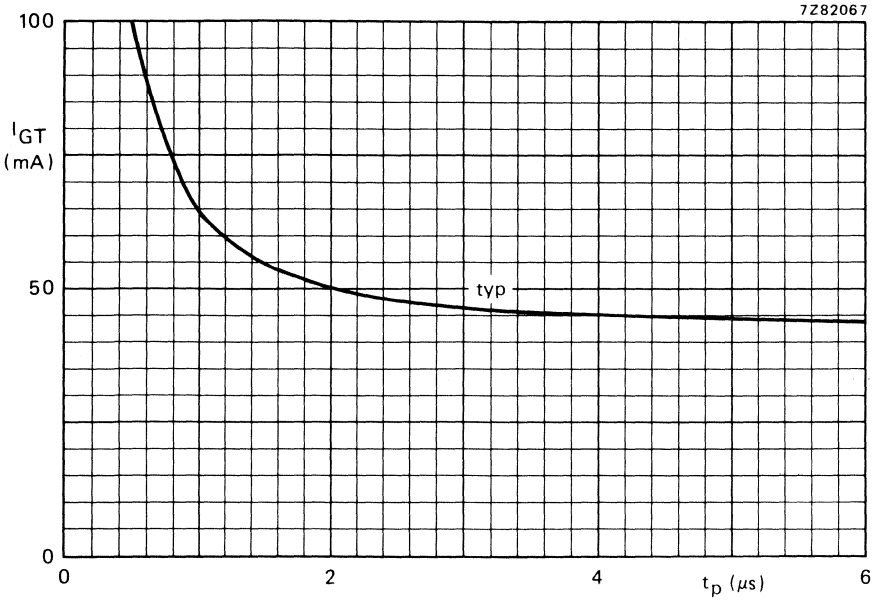
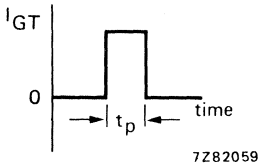


Fig. 14 Gate current that will trigger all devices as a function of rectangular pulse width;  $T_j = 25^\circ C$ .



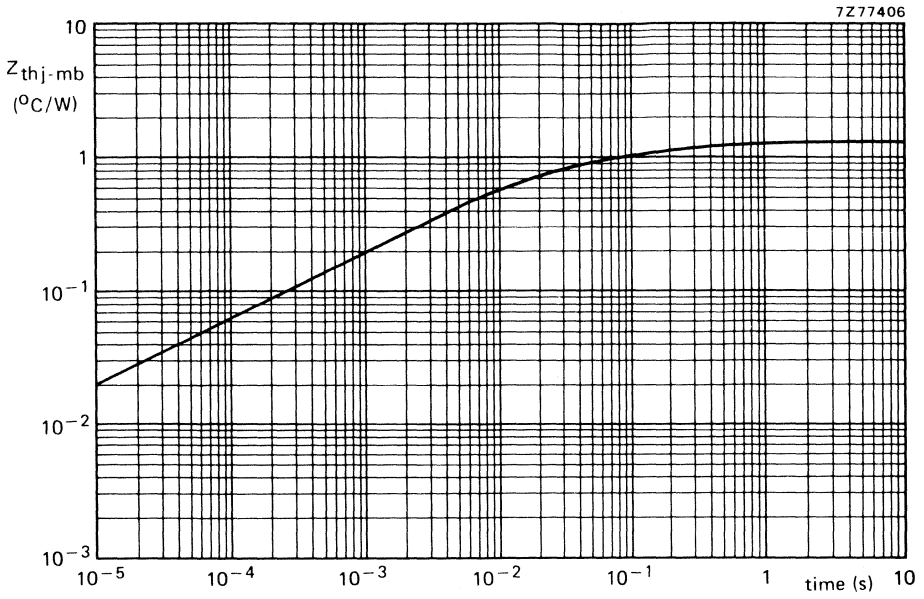


Fig. 15.



## FAST TURN-OFF THYRISTOR

Glass-passivated, eutectically bonded, fast turn-off forward blocking thyristor in a TO-220AB envelope, intended for use in high-frequency inverters, power supply, motor control, electronic flash systems and for horizontal deflection circuits of colour television receivers.

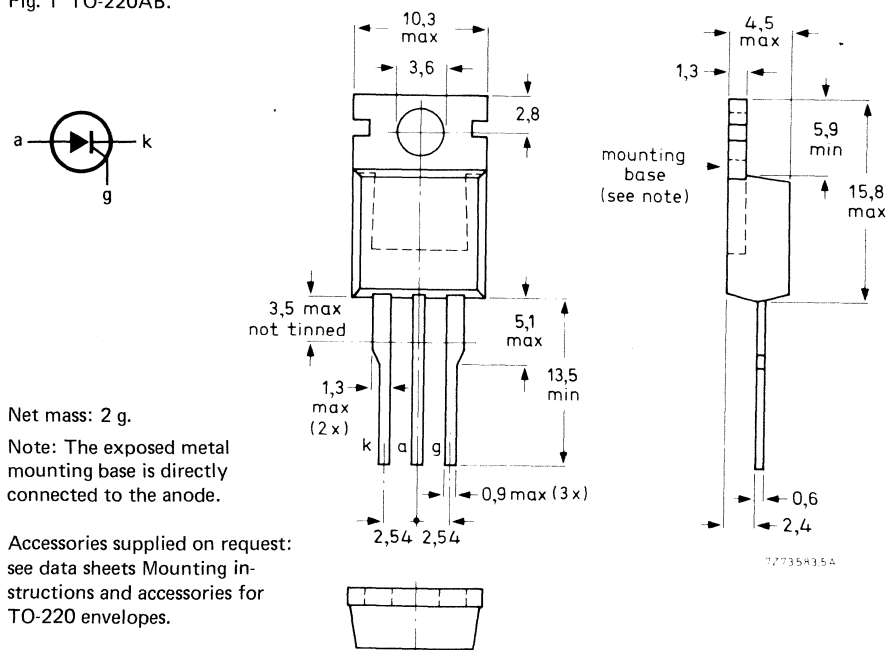
## QUICK REFERENCE DATA

Repetitive peak off-state voltage	$V_{DRM}$	max.	750 V
Average on-state current	$I_{T(AV)}$	max.	5 A
R.M.S. on-state current	$I_{T(RMS)}$	max.	8 A
Repetitive peak on-state current	$I_{TRM}$	max.	60 A
Circuit-commutated turn-off time	$t_q$	<	2,4 $\mu s$

## MECHANICAL DATA

Fig. 1 TO-220AB.

Dimensions in mm



**RATINGS**

Limiting values in accordance with the Absolute Maximum System (IEC 134)

**Anode to cathode**

Non-repetitive peak off-state voltage; $t \leq 10$ ms	$V_{DSM}$	max.	800 V
Repetitive peak off-state voltage	$V_{DRM}$	max.	750 V
Working off-state voltage $t_p \leq 20 \mu s$ ; $\delta = t_p/T \leq 0,25$	$V_{DW}$	max.	600 V
Average on-state current (averaged over any 20 ms period) up to $T_{mb} = 77$ °C; at $T_{mb} = 85$ °C	$I_T(AV)$	max.	5 A
	$I_T(AV)$	max.	4 A
R.M.S. on-state current	$I_T(RMS)$	max.	8 A
Working peak on-state current (horizontal deflection application)	$I_{TWM}$	max.	10 A
Repetitive peak on-state current	$I_{TRM}$	max.	60 A
Peak pulse on-state current	$I_{TM}$	max.	240 A
$I^2 t$ for fusing; $t = 10$ ms; $T_j = 25$ °C	$I^2 t$	max.	18 A <sup>2</sup> s
Rate of rise of on-state current after triggering up to $f = 20$ kHz	$dI_T/dt$	max.	60 A/ $\mu s$

**Gate to cathode**

Peak power dissipation	$P_{GM}$	max.	25 W
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**Temperatures**

Storage temperature	$T_{stg}$	-40 to +125 °C
Operating junction temperature	$T_j$	max. 110 °C



**THERMAL RESISTANCE**

From junction to mounting base

$$R_{th\ j-mb} = 2,5\ ^\circ C/W$$

Transient thermal impedance;  $t = 1\ ms$ 

$$Z_{th\ j-mb} = 0,24\ ^\circ C/W$$

**Influence of mounting method****1. Heatsink mounted with clip (see mounting instructions)**

Thermal resistance from mounting base to heatsink

a. with heatsink compound

$$R_{th\ mb-h} = 0,3\ ^\circ C/W$$

b. with heatsink compound and 0,06 mm maximum mica insulator

$$R_{th\ mb-h} = 1,4\ ^\circ C/W$$

c. with heatsink compound and 0,1 mm maximum mica insulator (56369)

$$R_{th\ mb-h} = 2,2\ ^\circ C/W$$

d. with heatsink compound and 0,25 mm max. alumina insulator (56367)

$$R_{th\ mb-h} = 0,8\ ^\circ C/W$$

e. without heatsink compound

$$R_{th\ mb-h} = 1,4\ ^\circ C/W$$

**2. Free-air operation**

The quoted values of  $R_{th\ j-a}$  should be used only when no leads of other dissipating components run to the same tie-point.

Thermal resistance from junction to ambient in free air:  
mounted on a printed-circuit board at  $a =$  any lead length  
and with copper laminate

$$R_{th\ j-a} = 60\ ^\circ C/W$$

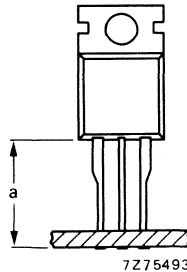


Fig. 2.

**CHARACTERISTICS**

**Anode to cathode**

On-state voltage

$I_T = 20 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_T < 3 \text{ V}^*$

Rate of rise of off-state voltage that will not trigger any device; exponential method;

$V_D = 2/3 V_{DRMmax}; T_j \leq 110 \text{ }^\circ\text{C}$

$V_{GK} = 0 \text{ V}$

$dV_D/dt < 200 \text{ V}/\mu\text{s}$

$-V_{GK} = 6 \text{ V}$

$dV_D/dt < 1000 \text{ V}/\mu\text{s}$

Off-state current

$V_D = V_{DRMmax}; T_j = 110 \text{ }^\circ\text{C}$

$I_D < 1,5 \text{ mA}$

**Gate to cathode**

Voltage that will trigger all devices

$V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$

$V_{GT} > 2,5 \text{ V}$

Current that will trigger all devices

$V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$

$I_{GT} > 40 \text{ mA}$

**Switching characteristics**

Circuit-commutated turn-off time (in horizontal deflection trace switch) when switched from

$I_T = 8 \text{ A}$  to  $V_R = 0,8 \text{ V}; V_{DM} = 700 \text{ V}; -V_{GG} = 25 \text{ V}$   
from  $R_{tot} = 62 \text{ } \Omega^{**}; T_{mb} = 80 \text{ }^\circ\text{C}$ ; see also Fig. 11

$t_p \leq 30 \text{ } \mu\text{s}$

$t_q < 2,4 \text{ } \mu\text{s}$

$t_p \leq 150 \text{ } \mu\text{s}$

$t_q < 4,8 \text{ } \mu\text{s}$

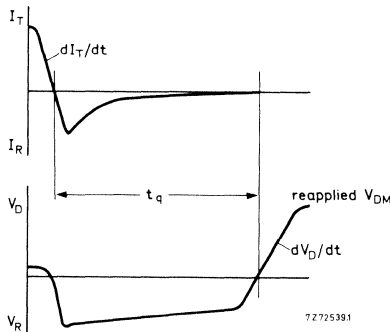


Fig. 3 Circuit-commutated turn-off time definition.

\* Measured under pulse conditions to avoid excessive dissipation.

\*\*  $R_{tot}$  is the total series resistance including source resistance.

### MOUNTING INSTRUCTIONS

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; it must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4,7 mm from the seal.
2. The leads should not be bent less than 2,4 mm from the seal, and should be supported during bending.
3. It is recommended that the circuit connection be made to the anode tag, rather than direct to the heatsink.
4. Mounting by means of a spring clip is the best mounting method because it offers:
  - a. a good thermal contact under the crystal area and slightly lower  $R_{th\ mb-h}$  values than screw mounting.
  - b. safe isolation for mains operation.
 However, if a screw is used, it should be M3 cross-recess pan-head. Care should be taken to avoid damage to the plastic body.
5. For good thermal contact heatsink compound should be used between mounting base and heatsink. Values of  $R_{th\ mb-h}$  given for mounting with heatsink compound refer to the use of a metallic-oxide loaded compound. Ordinary silicone grease is not recommended.
6. The device should not be pop-riveted to the heatsink. However, it is permissible to press-rivet providing that rivets of soft material are used, and the press forces are slowly and carefully controlled so as to avoid shock and deformation of either heatsink or mounting tab.

### OPERATING NOTES

Dissipation and heatsink considerations:

- a. The various components of junction temperature rise above ambient are illustrated in Fig. 4.

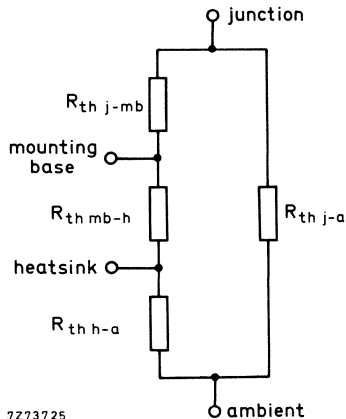


Fig. 4.

- b. The method of using Fig. 5 is as follows:  
 Starting with the required current on the  $I_{T(AV)}$  axis, trace upwards to meet the appropriate form factor curve. Trace right horizontally and upwards from the appropriate value on the  $T_{amb}$  scale. The intersection determines the  $R_{th\ mb-a}$ . The heatsink thermal resistance value ( $R_{th\ h-a}$ ) can now be calculated from:

$$R_{th\ h-a} = R_{th\ mb-a} - R_{th\ mb-h}$$

- c. Any measurement of heatsink temperature should be made immediately adjacent to the device.

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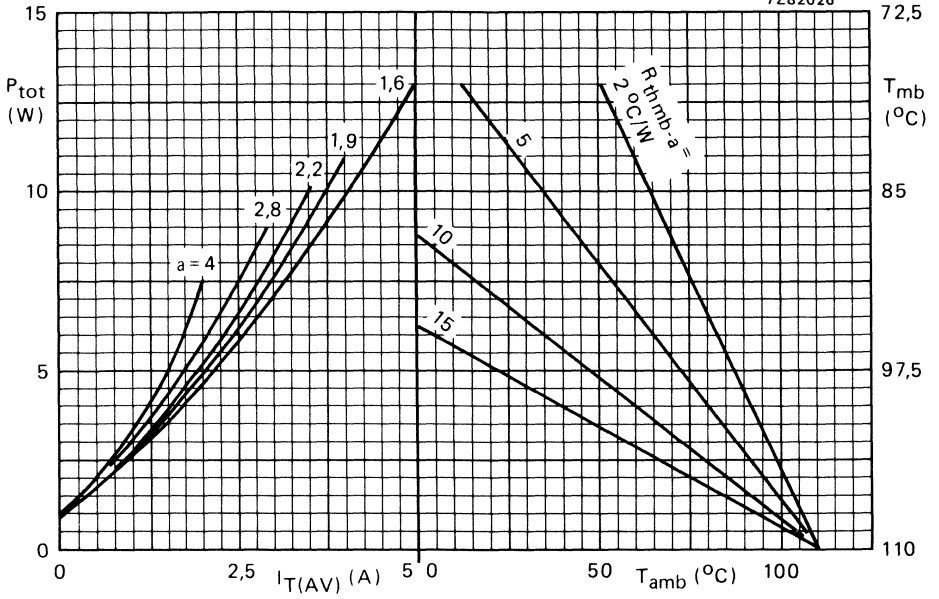


Fig. 5 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.



$\alpha$  = conduction angle per half cycle

$$a = \text{form factor} = \frac{I_T(\text{RMS})}{I_T(\text{AV})}$$

$\alpha$	a
30°	4
60°	2,8
90°	2,2
120°	1,9
180°	1,57

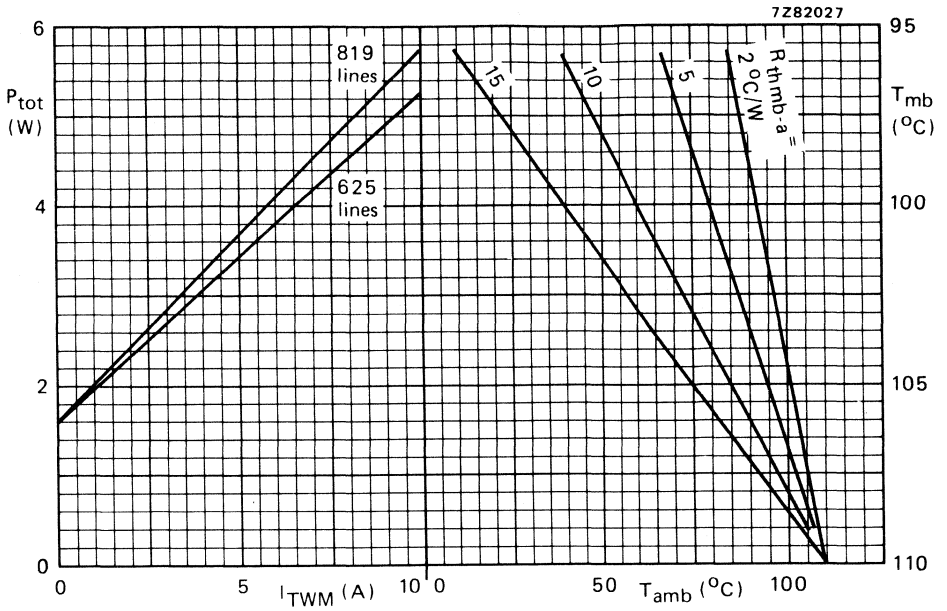


Fig. 6 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures (horizontal deflection application).

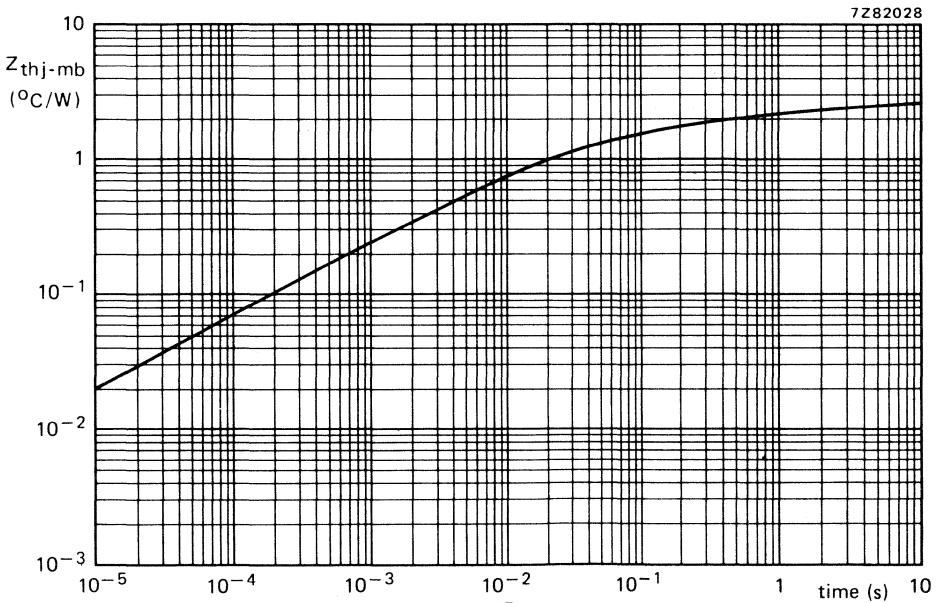


Fig. 7.

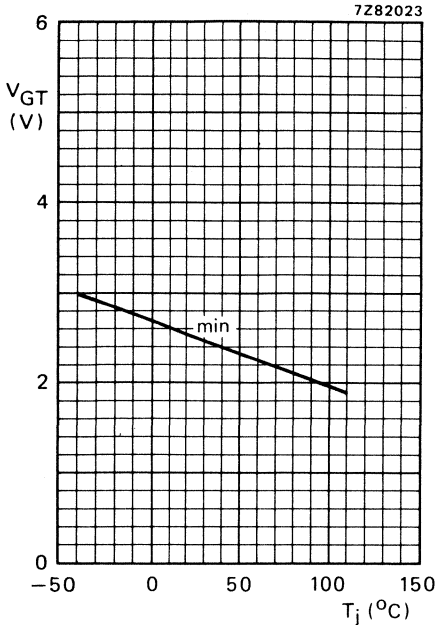


Fig. 8 Minimum gate voltage that will trigger all devices as a function of junction temperature.

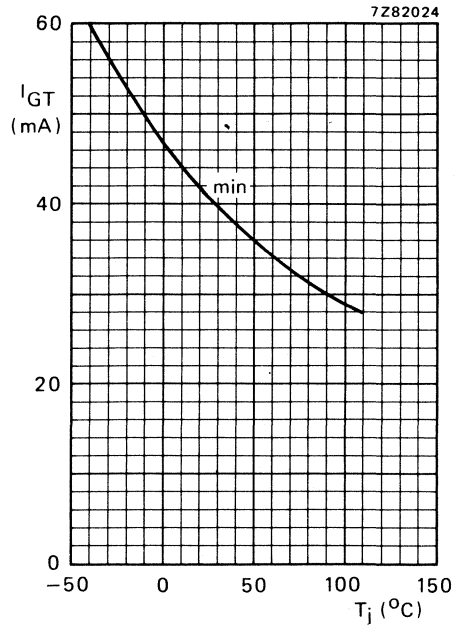


Fig. 9 Minimum gate current that will trigger all devices as a function of junction temperature.

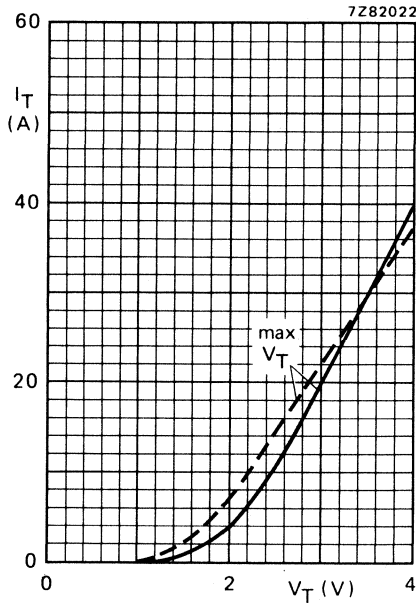


Fig. 10 —  $T_j = 25^{\circ}\text{C}$ ; - - -  $T_j = 110^{\circ}\text{C}$ .

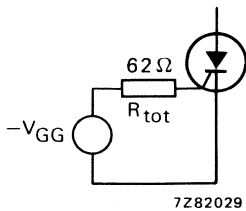
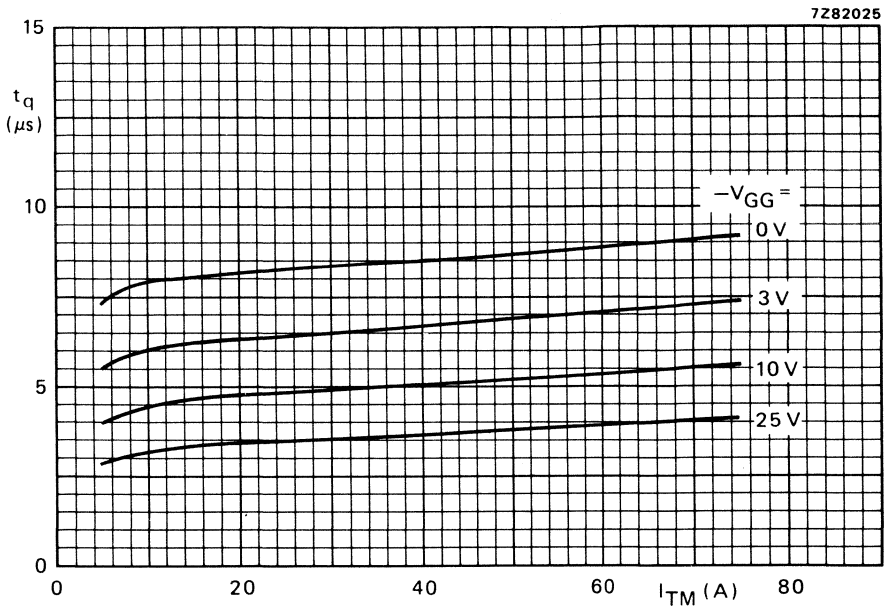


Fig. 11 Typical variation of  $t_q$  with  $I_{TM}$  and  $-V_{GG}$  at  $-dI_T/dt = 10 A/\mu s$ ;  $dV_D/dt = 200$  to  $700 V/\mu s$ ;  $t_p = 150 \mu s$ .

APPLICATION INFORMATION

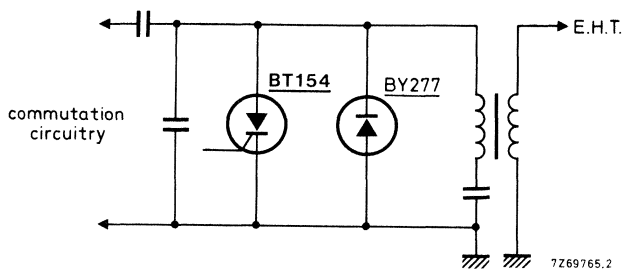
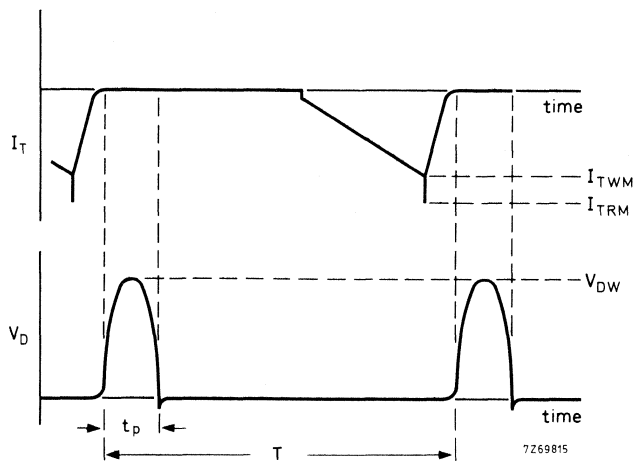


Fig. 12 Basic circuit and waveforms.

Note

For reverse blocking operation use a series diode, for reverse conducting operation use an anti-parallel diode.



## THYRISTORS

Silicon thyristors in metal envelopes, intended for general purpose single-phase or three-phase mains operation.

The series consists of reverse polarity types (anode to stud) identified by a suffix R: BTW23-600R to 1600R.

### QUICK REFERENCE DATA

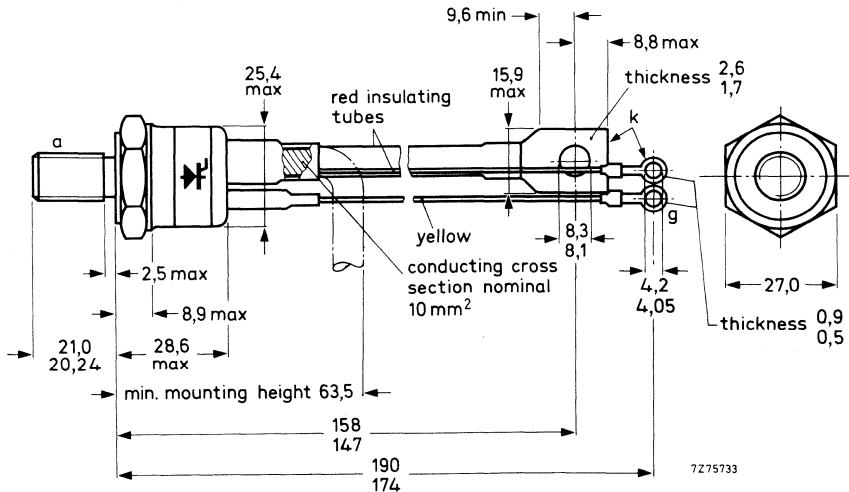
	BTW23-600R	800R	1000R	1200R	1400R	1600R
Repetitive peak voltages $V_{DRM} = V_{RRM}$	max. 600	800	1000	1200	1400	1600 V
Average on-state current				$I_{T(AV)}$	max. 90 A	
R.M.S. on-state current				$I_{T(RMS)}$	max. 140 A	
Non-repetitive peak on-state current				$I_{TSM}$	max. 2000 A	
Rate of rise of off-state voltage that will not trigger any device				$dV_D/dt$	< 200 V/ $\mu$ s	
On request (see ordering note on page 4)				$dV_D/dt$	< 1000 V/ $\mu$ s	

### MECHANICAL DATA

Dimensions in mm

Fig. 1 TO-94: with metric M12 stud ( $\varnothing$  12 mm); e.g. BTW23-600R.

Types with  $\frac{1}{2}$  in x 20 UNF stud ( $\varnothing$  12,7 mm) are available on request. These are indicated by the suffix U: e.g. BTW23-600RU.



Net mass: 134 g  
 Diameter of clearance hole: max. 13,0 mm  
 Torque on nut: min. 9 Nm (90 kg cm)  
 max. 17,5 Nm (175 kg cm)

Supplied with device: 1 nut, 1 lock washer  
 Nut dimensions across the flats;  
 M12 : 19 mm  
 $\frac{1}{2}$  in x 20 UNF: 19 mm

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

### Anode to cathode

		BTW23-600R	800R	1000R	1200R	1400R	1600R	
Non-repetitive peak voltages ( $t \leq 10$ ms)	$V_{DSM}/V_{RSM}$	max. 600	800	1000	1200	1400	1600	V
Repetitive peak voltages	$V_{DRM}/V_{RRM}$	max. 600	800	1000	1200	1400	1600	V
Crest working voltages	$V_{DWM}/V_{RWM}$	max. 400	600	700	800	800	800	V*
Average on-state current (averaged over any 20 ms period) up to $T_{mb} = 85$ °C					$I_T(AV)$	max.	90	A
R.M.S. on-state current					$I_T(RMS)$	max.	140	A
Repetitive peak on-state current					$I_{TRM}$	max.	1250	A
Non-repetitive peak on-state current; $t = 10$ ms; half sine-wave; $T_j = 125$ °C prior to surge; with reapplied $V_{RWM}$ max					$I_{TSM}$	max.	2000	A
$I^2t$ for fusing ( $t = 10$ ms)					$I^2t$	max.	20 000	A <sup>2</sup> s
Rate of rise of on-state current after triggering with $I_G = 750$ mA to $I_T = 300$ A; $dI_G/dt = 1$ A/ $\mu$ s					$dI_T/dt$	max.	300	A/ $\mu$ s
Rate of change of commutation current								see Fig. 14

### Gate to cathode

Reverse peak voltage	$V_{RGM}$	max.	10	V
Average power dissipation (averaged over any 20 ms period)	$P_G(AV)$	max.	2	W
Peak power dissipation	$P_{GM}$	max.	10	W

### Temperatures

Storage temperature	$T_{stg}$	-55 to + 125	°C	
Junction temperature	$T_j$	max.	125	°C

### THERMAL RESISTANCE

From junction to mounting base	$R_{th j-mb}$	=	0,3	°C/W
From mounting base to heatsink	$R_{th mb-h}$	=	0,1	°C/W
Transient thermal impedance ( $t = 1$ ms)	$Z_{th j-mb}$	=	0,015	°C/W

\* To ensure thermal stability:  $R_{th j-a} < 0,75$  °C/W (d.c. blocking) or  $< 1,5$  °C/W (a.c.). For smaller heatsinks  $T_{j max}$  should be derated. For a.c. see Fig. 4.

**CHARACTERISTICS**

**Anode to cathode**

On-state voltage $I_T = 500 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$	$V_T$	<	2,2 V*
Rate of rise of off-state voltage that will not trigger any device; exponential method; $V_D = 2/3 V_{DRM \text{ max}};$ $T_j = 125 \text{ }^\circ\text{C}$	$dV_D/dt$	<	200 V/ $\mu\text{s}$
Reverse current $V_R = V_{RWM \text{ max}}; T_j = 125 \text{ }^\circ\text{C}$	$I_R$	<	15 mA
Off-state current $V_D = V_{DWM \text{ max}}; T_j = 125 \text{ }^\circ\text{C}$	$I_D$	<	15 mA
Holding current; $T_j = 25 \text{ }^\circ\text{C}$	$I_H$	<	200 mA

**Gate to cathode**

Voltage that will trigger all devices $V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$	$V_{GT}$	>	2,5 V
Voltage that will not trigger any device $V_D = V_{DRM \text{ max}}; T_j = 125 \text{ }^\circ\text{C}$	$V_{GD}$	<	250 mV
Current that will trigger any device $V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$	$I_{GT}$	>	150 mA

**Switching characteristics**

Gate-controlled turn-on time ( $t_{gt} = t_d + t_r$ ) when switched from $V_D = V_{DWM \text{ max}}$ to $I_T = 100 \text{ A};$ $I_{GT} = 200 \text{ mA}; dI_G/dt = 1 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$	$t_{gt}$	<	2,5 $\mu\text{s}$
	$t_r$	typ.	1 $\mu\text{s}$

\* Measured under pulse conditions to avoid excessive dissipation.

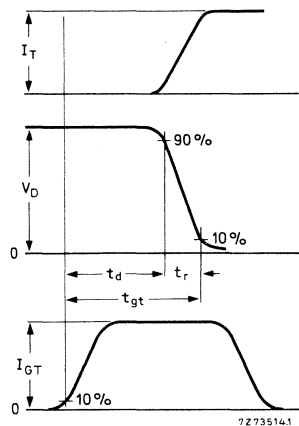


Fig. 2 Gate-controlled turn-on time definitions.

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**CHARACTERISTICS** (continued)

Circuit-commutated turn-off when switched

from  $I_T = 50$  A to  $V_R \geq 50$  V with  $-dI_T/dt = 50$  A/ $\mu$ s;

$dV_D/dt = 200$  V/ $\mu$ s;

$T_j = 125$  °C

$T_j = 25$  °C

$t_q$	typ.	100 $\mu$ s
	<	200 $\mu$ s
$t_q$	typ.	60 $\mu$ s
	<	120 $\mu$ s

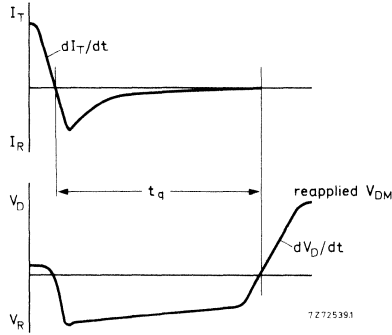


Fig. 3 Circuit-commutated turn-off time definition.

**OPERATING NOTE**

Switching losses in commutation

For applications in which the thyristor is forced to switch from an on-state current  $I_{TRM}$  to a high reverse voltage at a high commutation rate ( $-dI_T/dt$ ), consult Fig. 14 (nomogram) to find the increase in total average power. This increase must be added to the loss from the curves in Fig. 4.

**ORDERING NOTE**

Types with  $dV_D/dt$  of 1000 V/ $\mu$ s are available on request. Add suffix C to the type number when ordering; e.g. BTW23-600RC.

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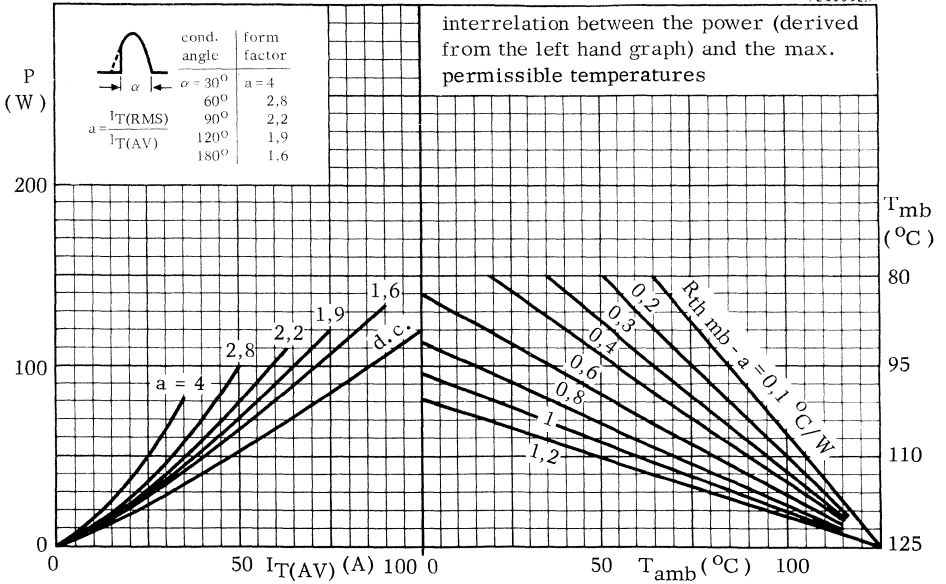


Fig. 4.

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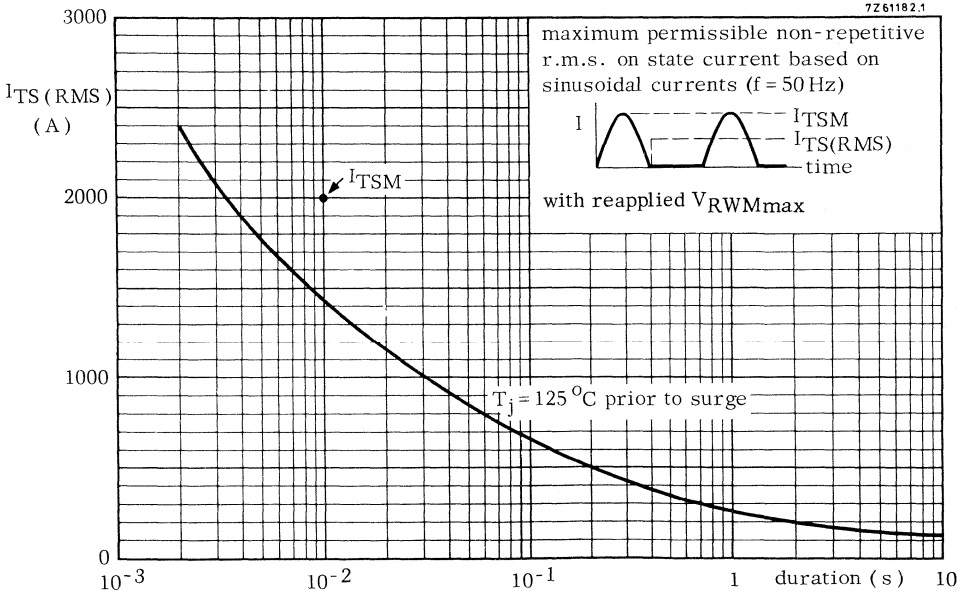


Fig. 5.

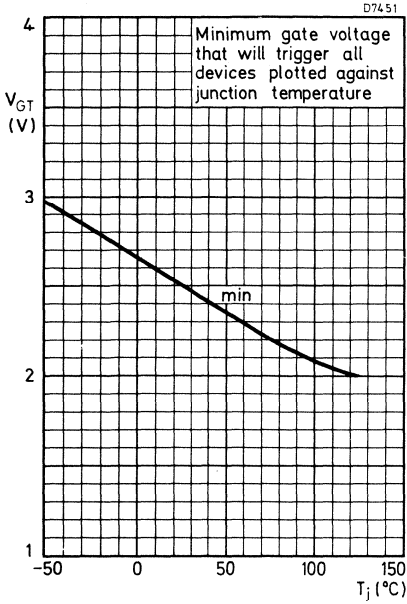


Fig. 6.

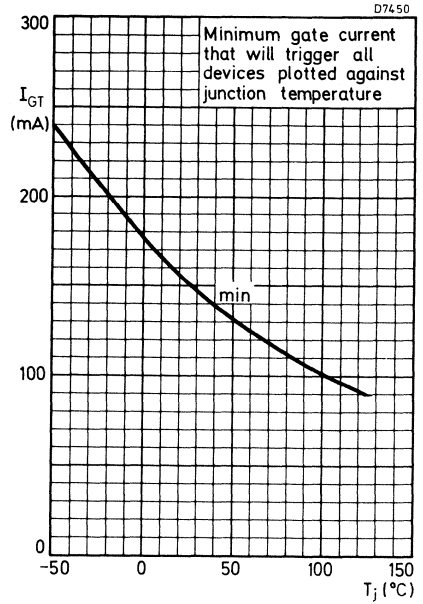


Fig. 7.

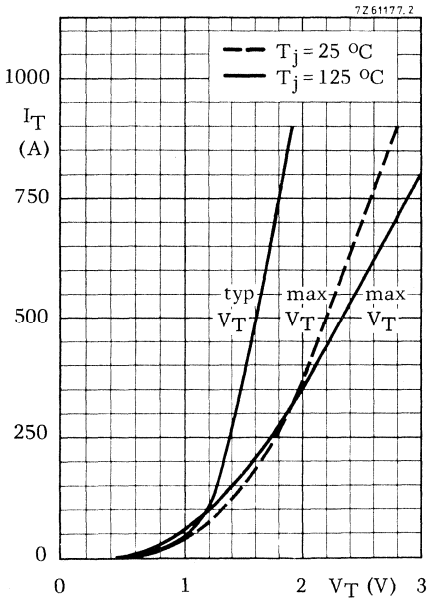


Fig. 8.

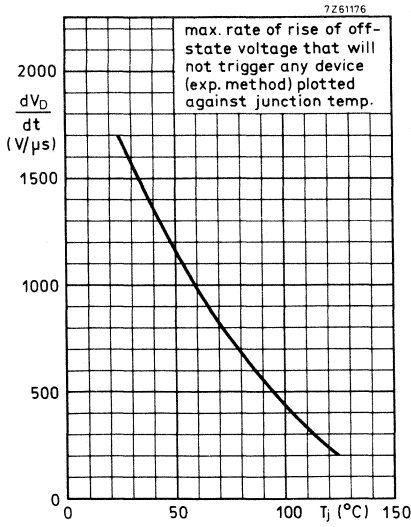


Fig. 9.

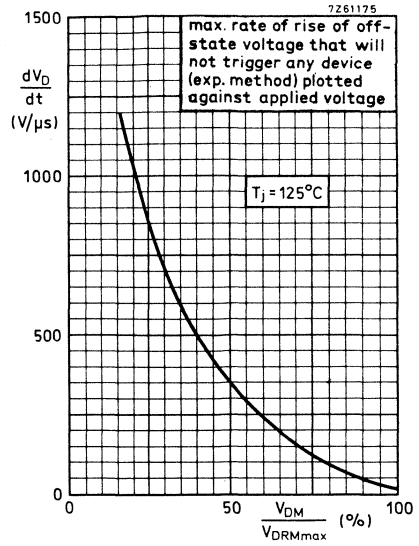


Fig. 10.

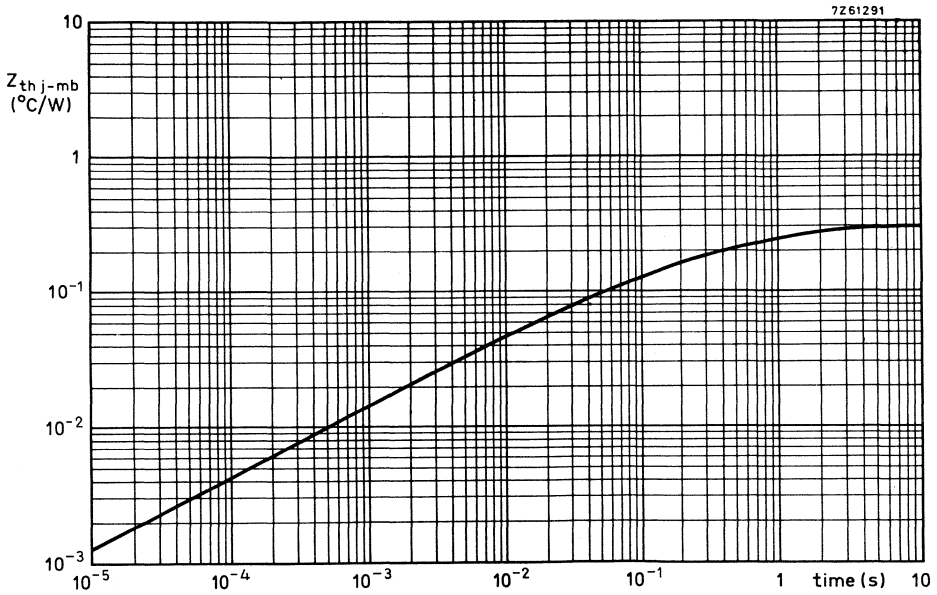


Fig. 11.

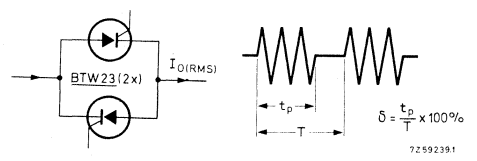
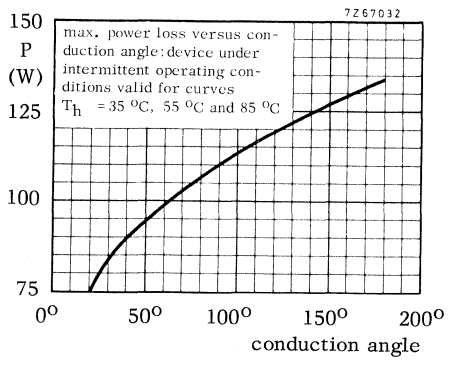
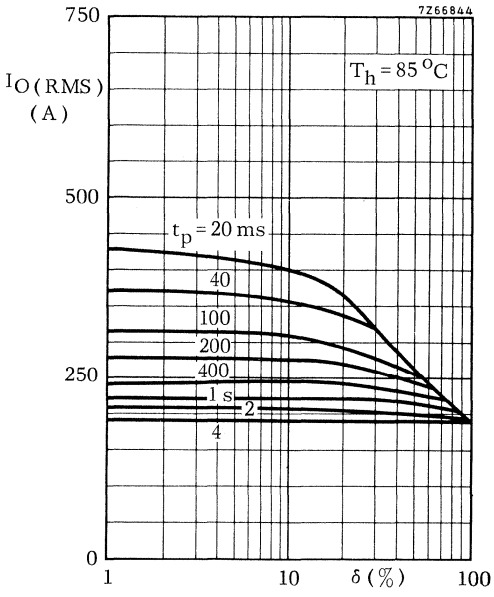
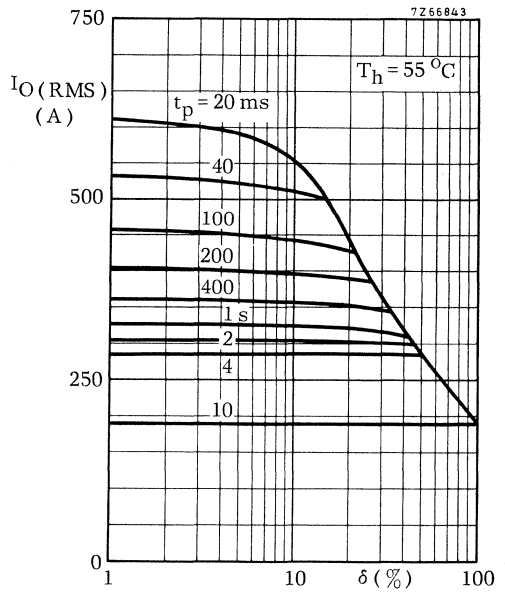
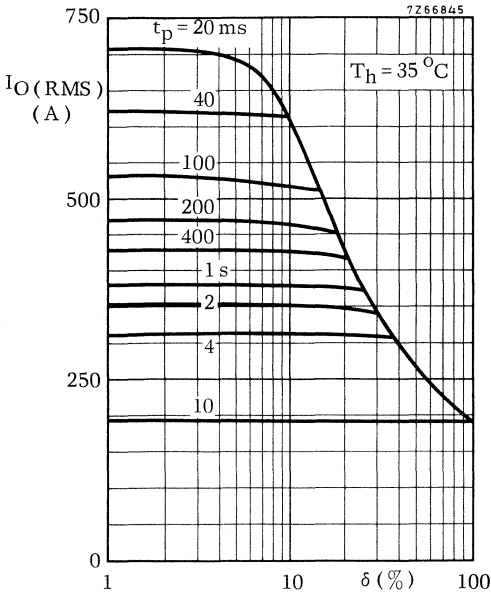


Fig. 12 Intermittent overload capability of two BTW23 thyristors in anti-parallel connection in a single phase a.c. control circuit (e.g. welding); conduction angle 360°.



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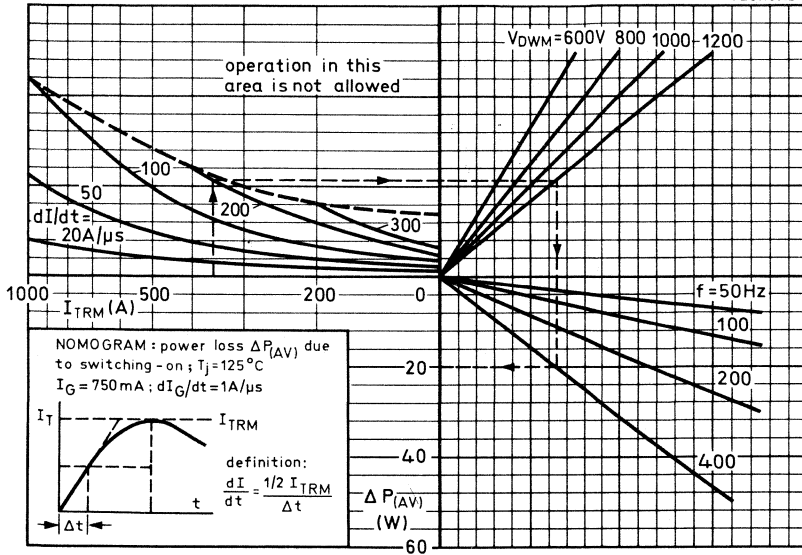


Fig. 13.

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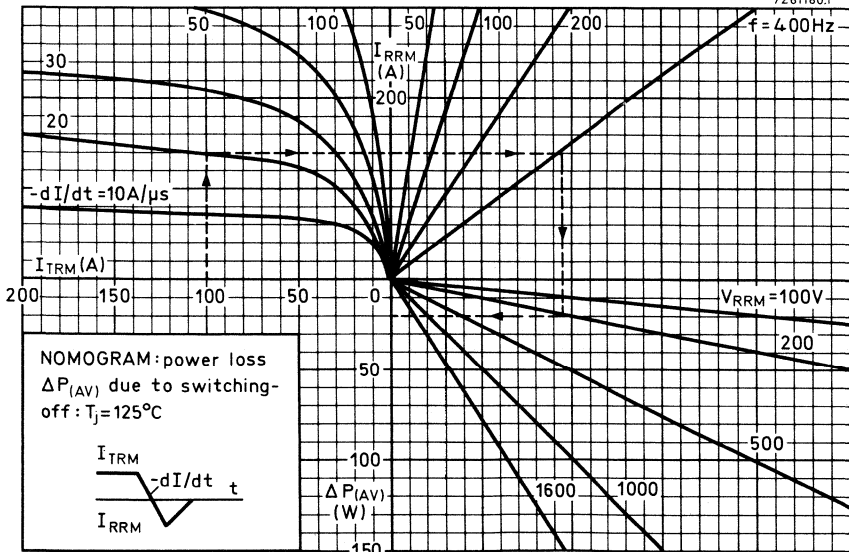


Fig. 14.

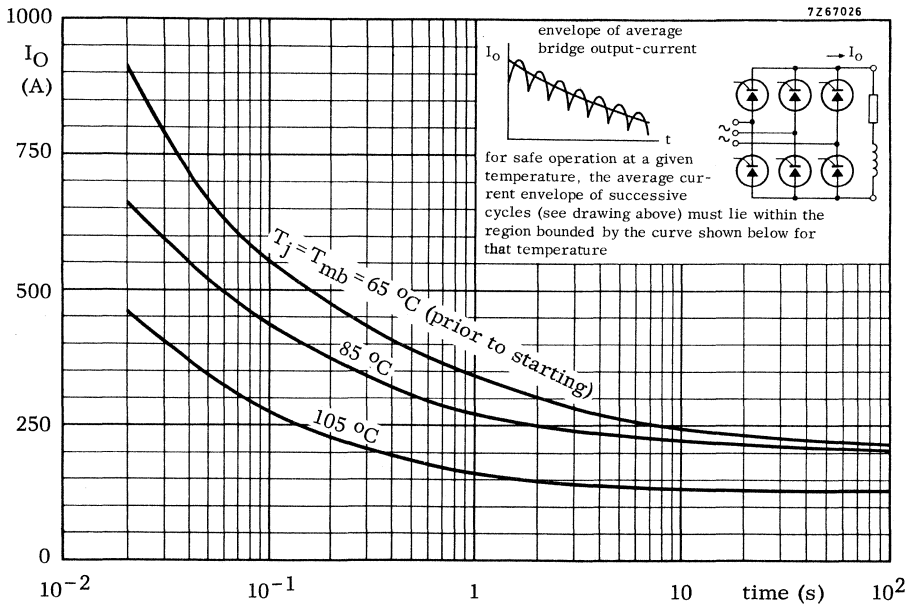
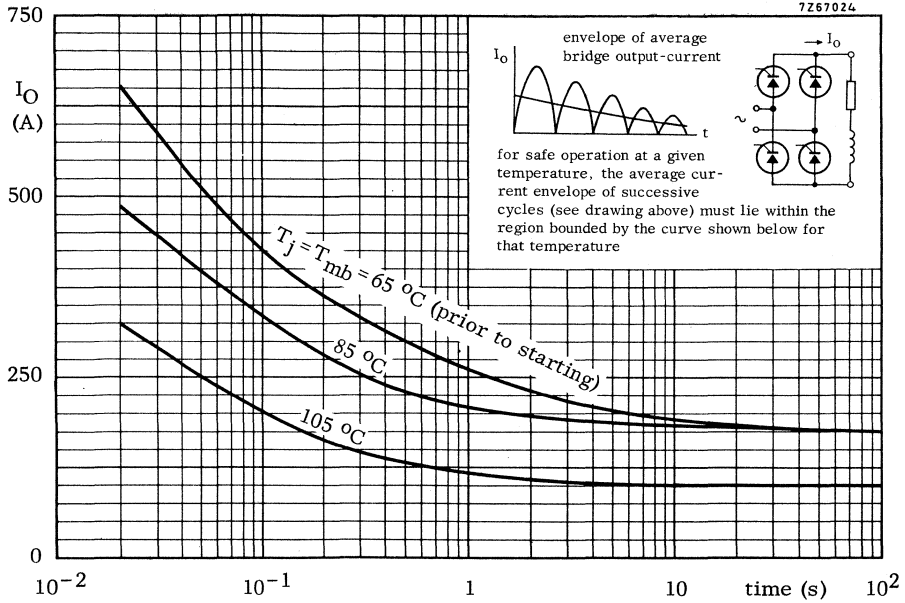


Fig. 15 Limits for starting or inrush currents.

## THYRISTORS

Silicon thyristors in metal envelopes, intended for general purpose single-phase or three-phase mains operation.

The series consists of reverse polarity types (anode to stud) identified by a suffix R: BTW24-600R to 1600R.

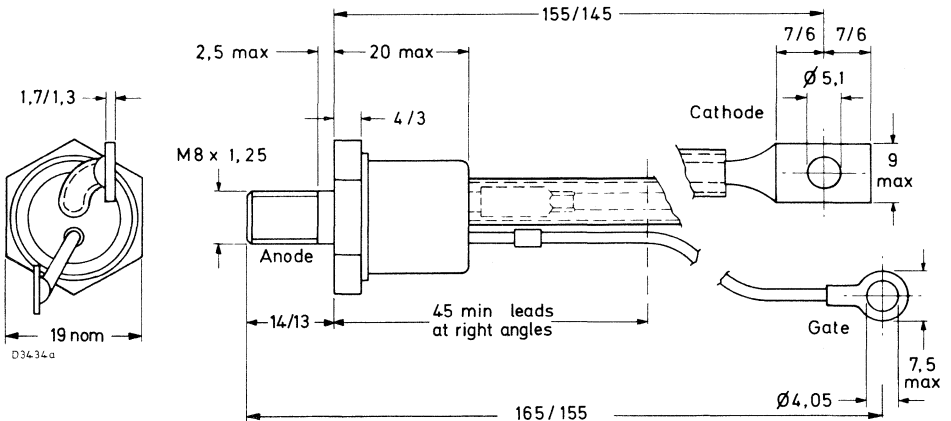
### QUICK REFERENCE DATA

	BTW24-600R	800R	1000R	1200R	1400R	1600R	
Repetitive peak voltages $V_{DRM} = V_{RRM}$	max. 600	800	1000	1200	1400	1600	V
Average on-state current				$I_T(AV)$	max. 35	A	
R.M.S. on-state current				$I_T(RMS)$	max. 55	A	
Non-repetitive peak on-state current				$I_{TSM}$	max. 800	A	
Rate of rise of off-state voltage that will not trigger any device				$dV_D/dt$	< 200	V/ $\mu s$	
On request (see ordering note on page 4)				$dV_D/dt$	< 1000	V/ $\mu s$	

### MECHANICAL DATA

Dimensions in mm

Fig. 1 TO-103.



Net mass: 46 g  
 Diameter of clearance hole: 8,5 mm  
 Torque on nut: min. 4 Nm (40 kg cm)  
 max. 6 Nm (60 kg cm)

Supplied with device: 1 nut, 1 lock washer  
 Nut dimensions across the flats: 13 mm

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

### Anode to cathode

		BTW24-600R	800R	1000R	1200R	1400R	1600R	
Non-repetitive peak voltages ( $t \leq 10$ ms)	$V_{DSM}/V_{RSM}$	max. 600	800	1000	1200	1400	1600	V
Repetitive peak voltages	$V_{DRM}/V_{RRM}$	max. 600	800	1000	1200	1400	1600	V
Crest working voltages	$V_{DWM}/V_{RWM}$	max. 400	600	700	800	800	800	V *
Average on-state current (averaged over any 20 ms period) up to $T_{mb} = 85$ °C					$I_{T(AV)}$	max.	35	A
R.M.S. on-state current					$I_{T(RMS)}$	max.	55	A
Repetitive peak on-state current					$I_{TRM}$	max.	450	A
Non-repetitive peak on-state current; $t = 10$ ms; half sine-wave; $T_j = 125$ °C prior to surge; with reapplied $V_{RWMmax}$					$I_{TSM}$	max.	800	A
$I^2t$ for fusing ( $t = 10$ ms)					$I^2t$	max.	3200	A <sup>2</sup> s
Rate of rise of on-state current after triggering with $I_G = 500$ mA to $I_T = 100$ A; $dI_G/dt = 1$ A/ $\mu$ s					$dI_T/dt$	max.	300	A/ $\mu$ s
Rate of change of commutation current					see Fig. 14			

### Gate to cathode

Reverse peak voltage				$V_{RGM}$	max.	10	V
Average power dissipation (averaged over any 20 ms period)				$P_{G(AV)}$	max.	1	W
Peak power dissipation				$P_{GM}$	max.	5	W

### Temperatures

Storage temperature		$T_{stg}$	-55 to + 125	°C	
Junction temperature		$T_j$	max.	125	°C

### THERMAL RESISTANCE

From junction to mounting base	$R_{th\ j-mb}$	=	0,6	°C/W
From mounting base to heatsink	$R_{th\ mb-h}$	=	0,2	°C/W
Transient thermal impedance ( $t = 1$ ms)	$Z_{th\ j-mb}$	=	0,04	°C/W

\* To ensure thermal stability:  $R_{th\ j-a} < 1$  °C/W (d.c. blocking) or  $< 2$  °C/W (a.c.). For smaller heatsinks  $T_{j\ max}$  should be derated. For a.c. see Fig. 4.

**CHARACTERISTICS**

**Anode to cathode**

On-state voltage

$$I_T = 100 \text{ A}; T_j = 25 \text{ }^\circ\text{C} \quad V_T < 1,9 \text{ V}^*$$

Rate of rise of off-state voltage that will not trigger any device; exponential method;  $V_D = 2/3 V_{DRMmax}$ ;  $T_j = 125 \text{ }^\circ\text{C}$

$$dV_D/dt < 200 \text{ V}/\mu\text{s}$$

Reverse current

$$V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C} \quad I_R < 10 \text{ mA}$$

Off-state current

$$V_D = V_{DWMmax}; T_j = 125 \text{ }^\circ\text{C} \quad I_D < 10 \text{ mA}$$

Latching current;  $T_j = 25 \text{ }^\circ\text{C}$

$$I_L < 300 \text{ mA}$$

Holding current;  $T_j = 25 \text{ }^\circ\text{C}$

$$I_H < 200 \text{ mA}$$

**Gate to cathode**

Voltage that will trigger all devices

$$V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C} \quad V_{GT} > 2,5 \text{ V}$$

Voltage that will not trigger any device

$$V_D = V_{DRMmax}; T_j = 125 \text{ }^\circ\text{C} \quad V_{GD} < 200 \text{ mV}$$

Current that will trigger all devices

$$V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C} \quad I_{GT} > 100 \text{ mA}$$

**Switching characteristics**

Gate-controlled turn-on time ( $t_{gt} = t_d + t_r$ ) when switched from  $V_D = V_{DWMmax}$  to  $I_T = 100 \text{ A}$ ;  $I_{GT} = 150 \text{ mA}$ ;  $dI_G/dt = 1 \text{ A}/\mu\text{s}$ ;  $T_j = 25 \text{ }^\circ\text{C}$

$$t_{gt} \quad \text{typ.} \quad 2 \mu\text{s}$$

$$t_r \quad \text{typ.} \quad 1 \mu\text{s}$$

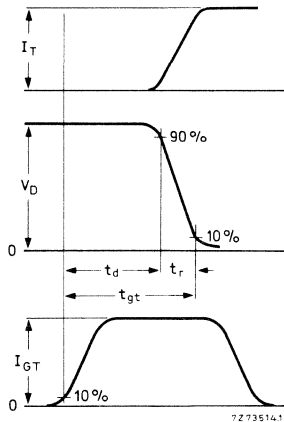


Fig. 2 Gate-controlled turn-on time definitions.

\* Measured under pulse conditions to avoid excessive dissipation.

**CHARACTERISTICS** (continued)

Circuit-commutated turn-off time when switched

from  $I_T = 30$  A to  $V_R \geq 50$  V with  $-dI_T/dt = 30$  A/ $\mu$ s;

$dV_D/dt = 100$  V/ $\mu$ s;

$T_j = 125$  °C

$T_j = 25$  °C

$t_q$	typ.	140 $\mu$ s
	<	200 $\mu$ s
$t_q$	<	100 $\mu$ s

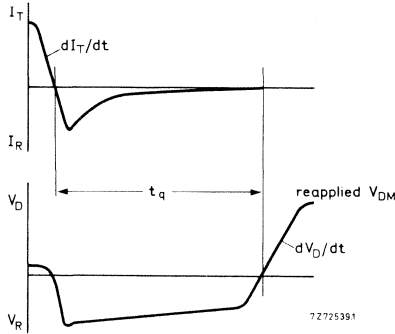


Fig. 3 Circuit-commutated turn-off time definition.

**OPERATING NOTE**

Switching losses in commutation

For applications in which the thyristor is forced to switch from an on-state current  $I_{TRM}$  to a high reverse voltage at a high commutation rate ( $-dI_T/dt$ ), consult Fig. 14 (nomogram) to find the increase in total average power. This increase must be added to the loss from the curves in Fig. 4.

**ORDERING NOTE**

Types with  $dV_D/dt$  of 1000 V/ $\mu$ s are available on request. Add suffix C to the type number when ordering; e.g. BTW24-600RC.

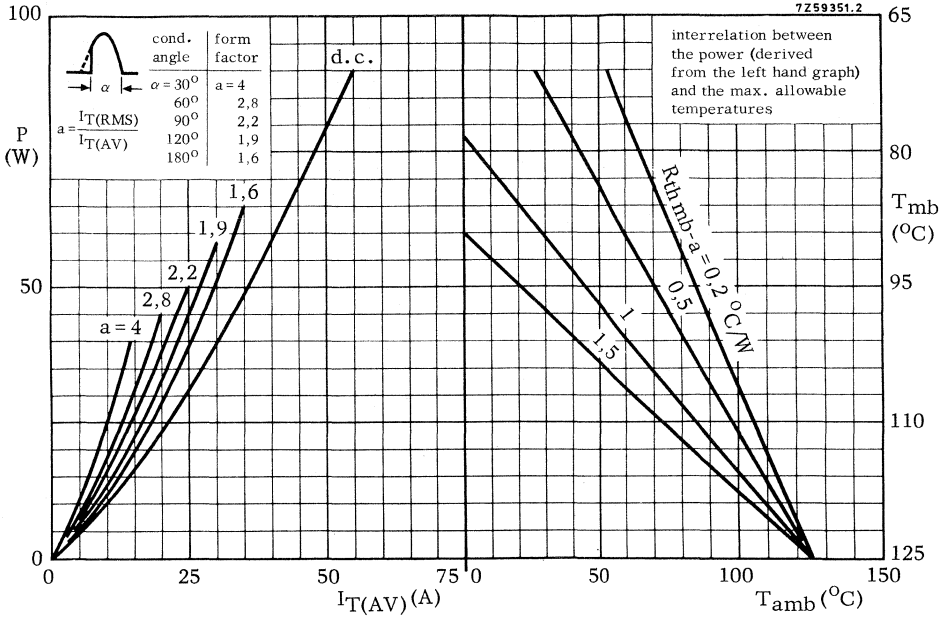


Fig. 4.

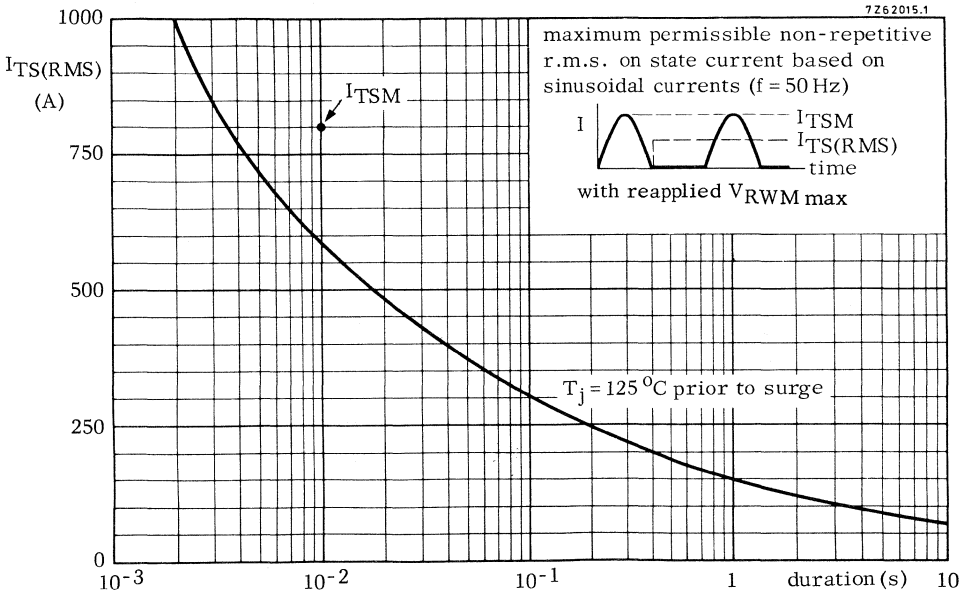


Fig. 5.

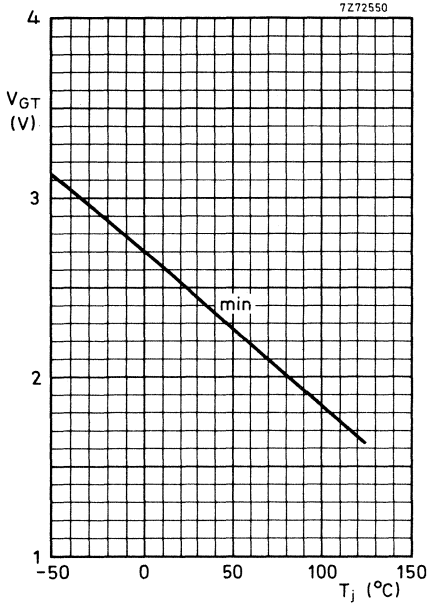


Fig. 6 Minimum gate voltage that will trigger all devices plotted against junction temperature.

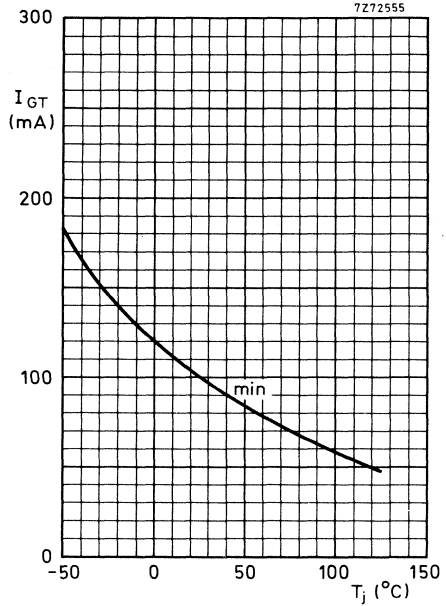


Fig. 7 Minimum gate current that will trigger all devices plotted against junction temperature.

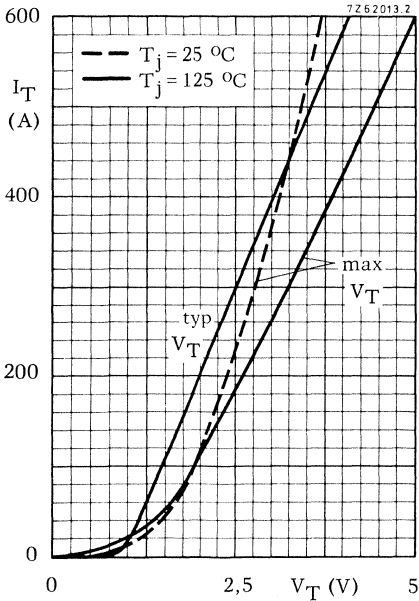


Fig. 8.



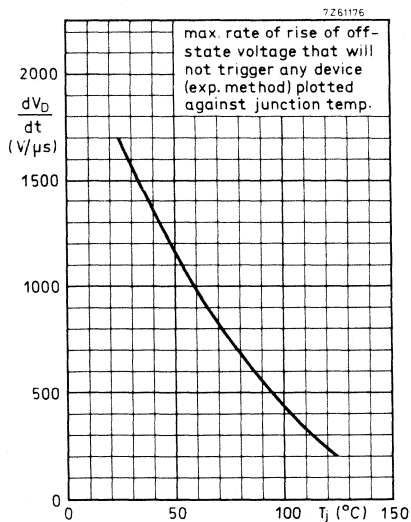


Fig. 9.

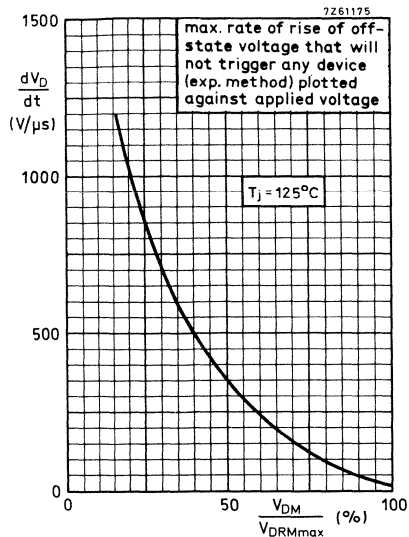


Fig. 10.

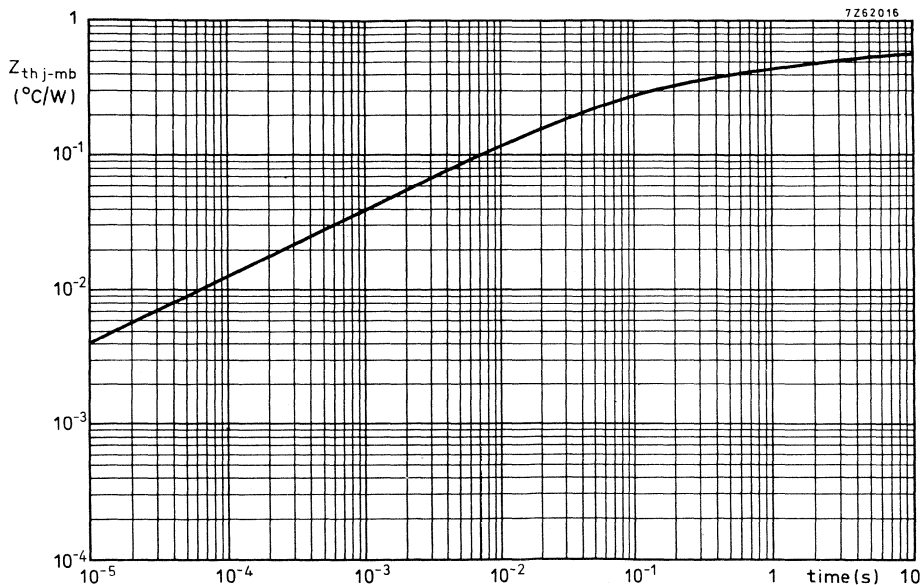


Fig. 11.

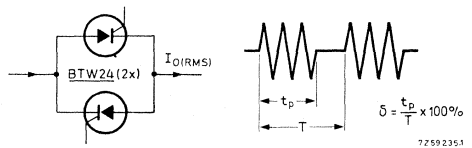
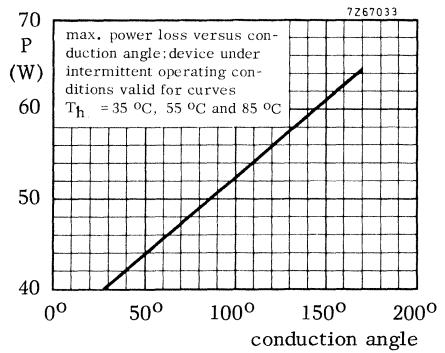
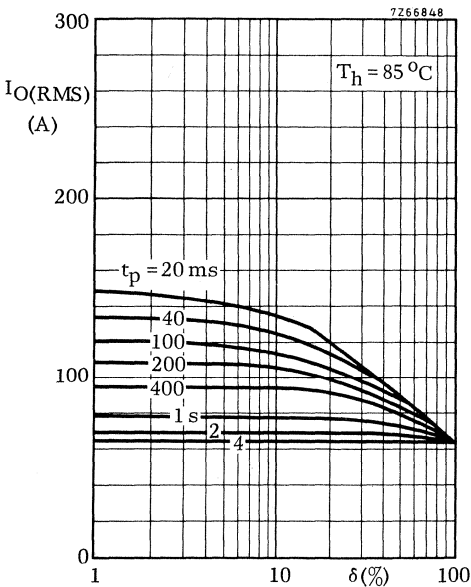
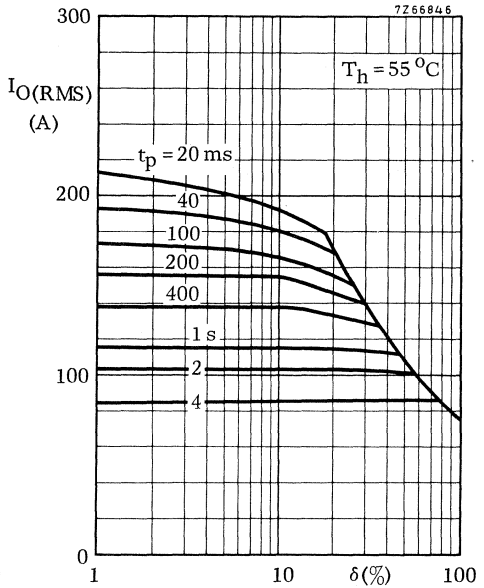
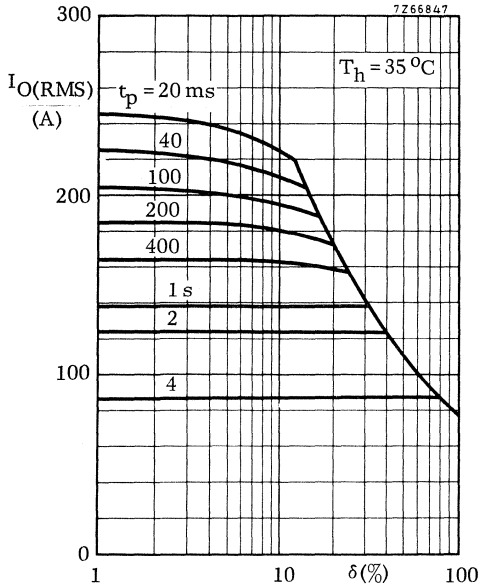


Fig. 12 Intermittent overload capability of two BTW24 thyristors in anti-parallel connection in a single phase a.c. control circuit (e.g. welding); conduction angle:  $360^\circ$ .

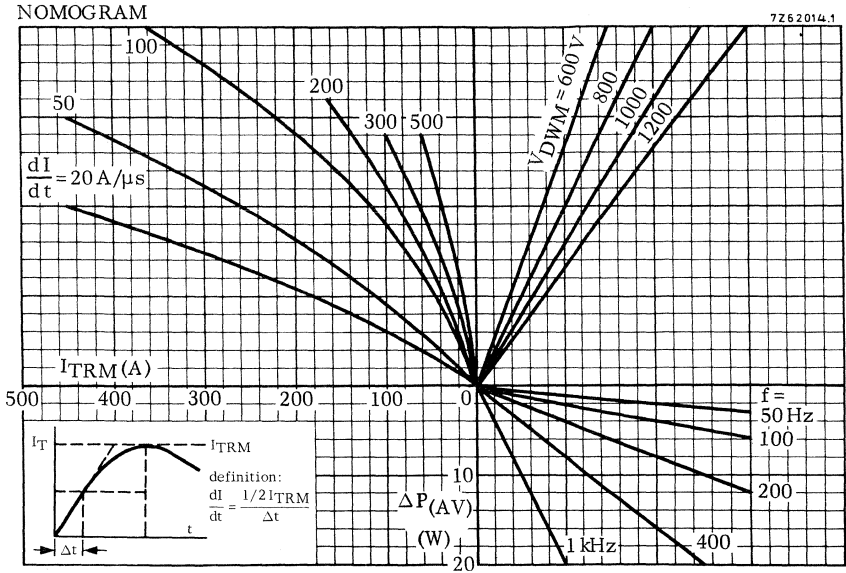


Fig. 13 Power loss  $\Delta P_{(AV)}$  due to switching-on;  $T_j = 125^\circ\text{C}$ ;  $I_G = 500 \text{ mA}$ ;  $dI/dt = 1 \text{ A}/\mu\text{s}$ .

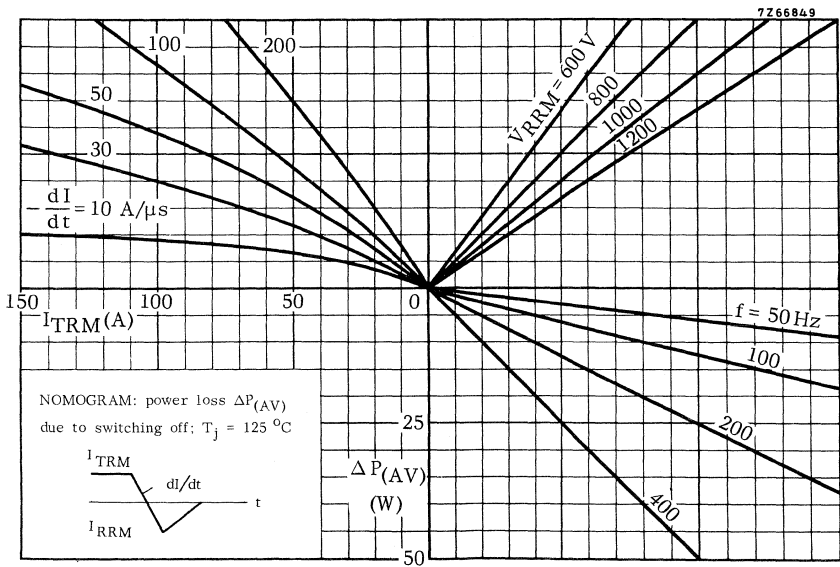


Fig. 14.

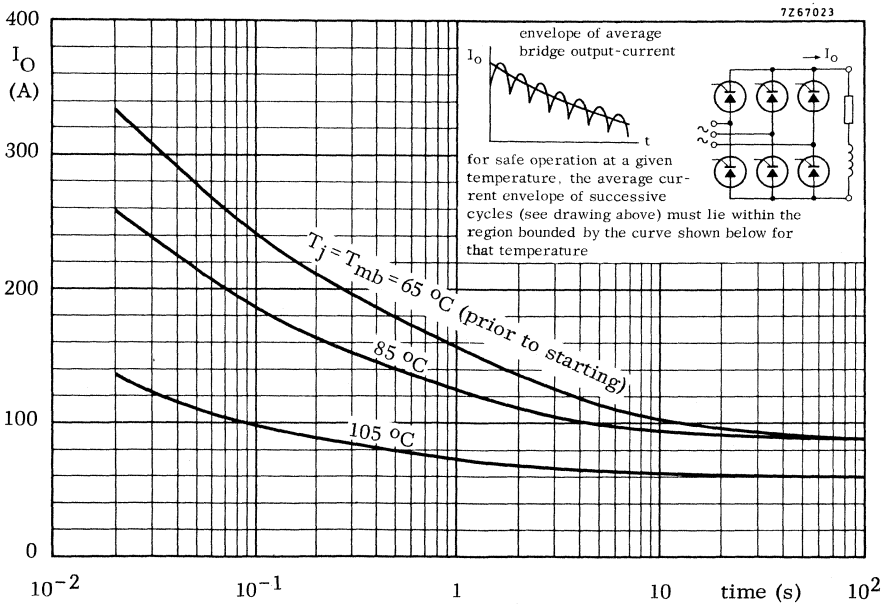
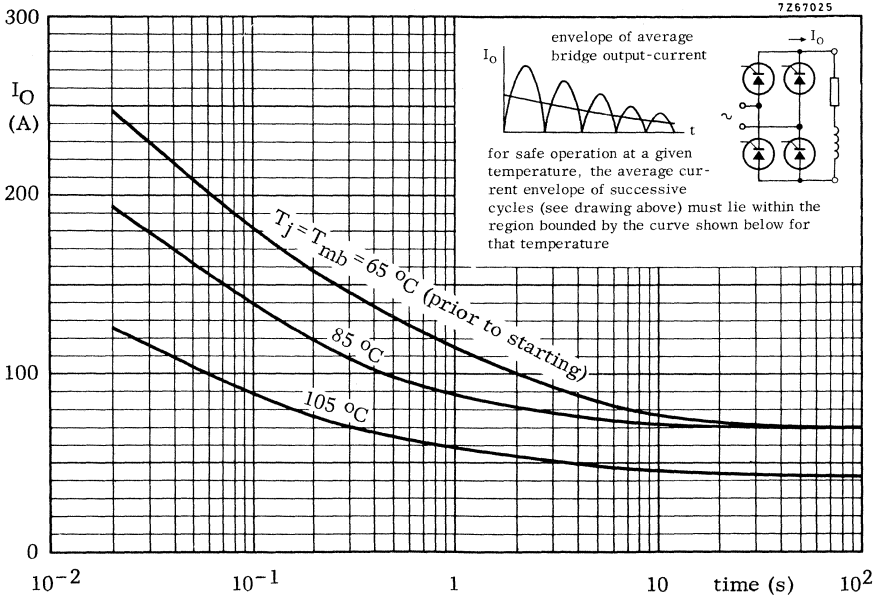


Fig. 15 Limits for starting or inrush currents.

## FAST TURN-OFF THYRISTORS

A range of medium current fast turn-off thyristors in metal envelopes, intended for use in inverter applications.

The series consists of reverse polarity types (anode to stud) identified by a suffix R: BTW30-800RS to 1200RS.

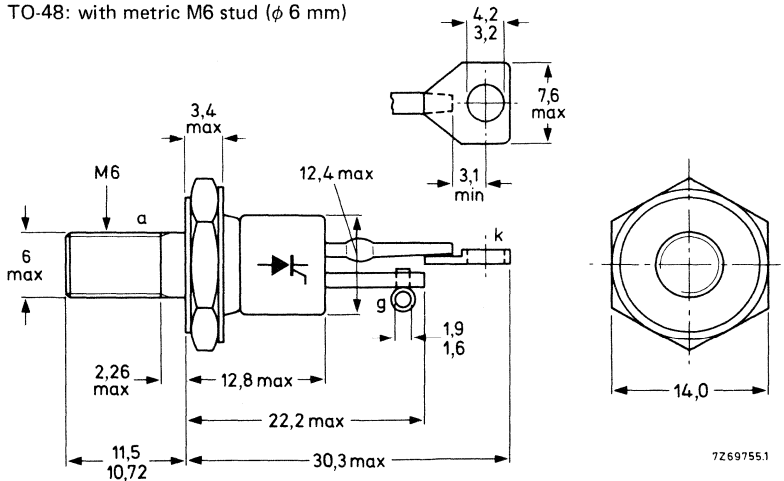
### QUICK REFERENCE DATA

		BTW30-800RS	1000RS	1200RS
Repetitive peak voltages	$V_{DRM}/V_{RRM}$	max. 800	1000	1200 V
Average on-state current		$I_T(AV)$	max. 16 A	
R.M.S. on-state current		$I_T(RMS)$	max. 24 A	
Non-repetitive peak on-state current		$I_{TSM}$	max. 150 A	
Rate of rise of on-state current		$dI_T/dt$	max. 100 A/ $\mu s$	
Rate of rise of off-state voltage that will not trigger any device		$dV_D/dt$	< 200 V/ $\mu s$	
Circuit-commutated turn-off time		$t_q$	< 15 $\mu s$	

### MECHANICAL DATA

Dimensions in mm

Fig. 1 TO-48: with metric M6 stud ( $\phi$  6 mm)



Net mass: 14 g  
 Diameter of clearance hole: max. 6,5 mm  
 Accessories supplied on request: 56264A  
 (mica washer, insulating ring, soldering tag)

Torque on nut: min. 1,7 Nm (17 kg cm)  
 max. 3,5 Nm (35 kg cm)

Supplied with device:  
 1 nut, 1 lock washer  
 Nut dimensions across the flats: 10 mm

**RATINGS**

Limiting values in accordance with the Absolute Maximum System (IEC 134)

**Anode to cathode**

		BTW30-800RS	1000RS	1200RS
Non-repetitive peak voltages ( $t \leq 10$ ms)	$V_{DSM}^{**}/V_{RSM}$	max. 800	1000	1200 V
Repetitive peak voltages	$V_{DRM}/V_{RRM}$	max. 800	1000	1200 V▲
Crest working off-state voltage square-wave; $\delta = 0,5$	$V_{DWM}$	max. 600	800	1000 V*
Average on-state current assuming zero switching losses (averaged over any 20 ms period)				
square-wave; $\delta = 0,5$ ; up to $T_{mb} = 65$ °C		$I_T(AV)$	max.	16 A
square-wave; $\delta = 0,5$ ; at $T_{mb} = 85$ °C		$I_T(AV)$	max.	12 A
sinusoidal; at $T_{mb} = 85$ °C		$I_T(AV)$	max.	10 A
R.M.S. on-state current		$I_T(RMS)$	max.	24 A
Repetitive peak on-state current		$I_{TRM}$	max.	150 A
Non-repetitive peak on-state current				
$T_j = 125$ °C prior to surge (see Fig. 6)		$I_{TSM}$	max.	150 A
$t = 10$ ms; half sine-wave		$I_{TSM}$	max.	150 A
$t = 5$ ms; square pulse				
$I^2 t$ for fusing ( $t = 10$ ms)		$I^2 t$	max.	115 A <sup>2</sup> s
Rate of rise of on-state current after triggering with $I_G = 1$ A to $I_T = 50$ A; $dI_G/dt = 1$ A/ $\mu$ s		$dI_T/dt$	max.	100 A/ $\mu$ s

**Gate to cathode**

Reverse peak voltage	$V_{RGM}$	max.	10 V
Average power dissipation (averaged over any 20 ms period)	$P_G(AV)$	max.	1 W
Peak power dissipation	$P_{GM}$	max.	5 W

**Temperatures**

Storage temperature	$T_{stg}$	-55 to + 125 °C
Junction temperature	$T_j$	max. 125 °C

**THERMAL RESISTANCE**

From junction to mounting base	$R_{th j-mb}$	=	1 °C/W
From mounting base to heatsink	$R_{th mb-h}$	=	0,2 °C/W
Transient thermal impedance ( $t = 1$ ms)	$Z_{th j-mb}$	=	0,06 °C/W

\* To ensure thermal stability:  $R_{th j-a} < 3$  °C/W (d.c. blocking) or  $< 6$  °C/W (square-wave;  $\delta = 0,5$ ). For smaller heatsinks  $T_{jmax}$  should be derated. For square-wave see Fig. 5.

\*\* Although not recommended, higher off-state voltages may be applied without damage, but the thyristor may switch into the on-state. The rate of rise of on-state current should not exceed 30 A/ $\mu$ s.

▲ Thermal stability at higher voltage ratings is dependent on duty factor. See Figs 15 and 16.

**CHARACTERISTICS**

**Anode to cathode**

On-state voltage

$I_T = 20 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_T < 3,5 \text{ V}^*$

Rate of rise of off-state voltage that will not trigger

any device; exponential method;  $V_D = 2/3 V_{DRM \text{ max}}$ ;

$T_j = 125 \text{ }^\circ\text{C}$

$dV_D/dt < 200 \text{ V}/\mu\text{s}$

Off-state current

$V_D = V_{DWM \text{ max}}; T_j = 125 \text{ }^\circ\text{C}$

$I_D < 7 \text{ mA}$

Holding current;  $T_j = 25 \text{ }^\circ\text{C}$

$I_H < 200 \text{ mA}$

**Gate to cathode**

Voltage that will trigger all devices

$V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$

$V_{GT} > 2,5 \text{ V}$

Voltage that will not trigger any device

$V_D = V_{DRM \text{ max}}; T_j = 125 \text{ }^\circ\text{C}$

$V_{GD} < 0,2 \text{ V}$

Current that will trigger all devices

$V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$

$I_{GT} > 200 \text{ mA}$

**Switching characteristics**

Gate-controlled turn-on time ( $t_{gt} = t_d + t_r$ ) when

switched from  $V_D = V_{DWM \text{ max}}$  to  $I_T = 50 \text{ A}$ ;

$I_{GT} = 200 \text{ mA}; dI_G/dt = 1 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

$t_d < 1 \mu\text{s}$

$t_r < 1 \mu\text{s}$

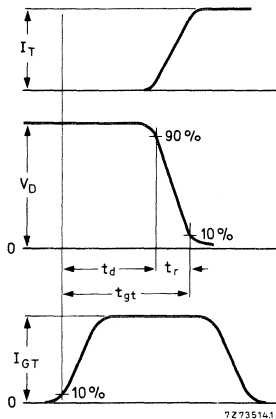


Fig. 2 Gate-controlled turn-on time definitions.

\* Measured under pulse conditions to avoid excessive dissipation.

**CHARACTERISTICS** (continued)

Circuit-commutated turn-off time when switched  
 from  $I_T = 10$  A to  $V_R \geq 50$  V with  $-dI_T/dt = 10$  A/ $\mu$ s;  
 $dV_D/dt = 50$  V/ $\mu$ s;  $T_j = 125$  °C

$$t_q < 15 \mu s$$

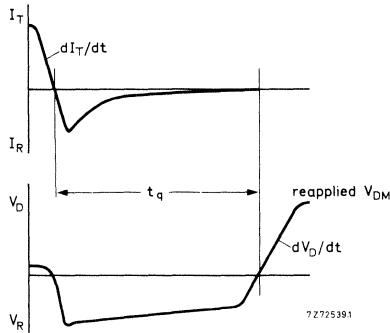
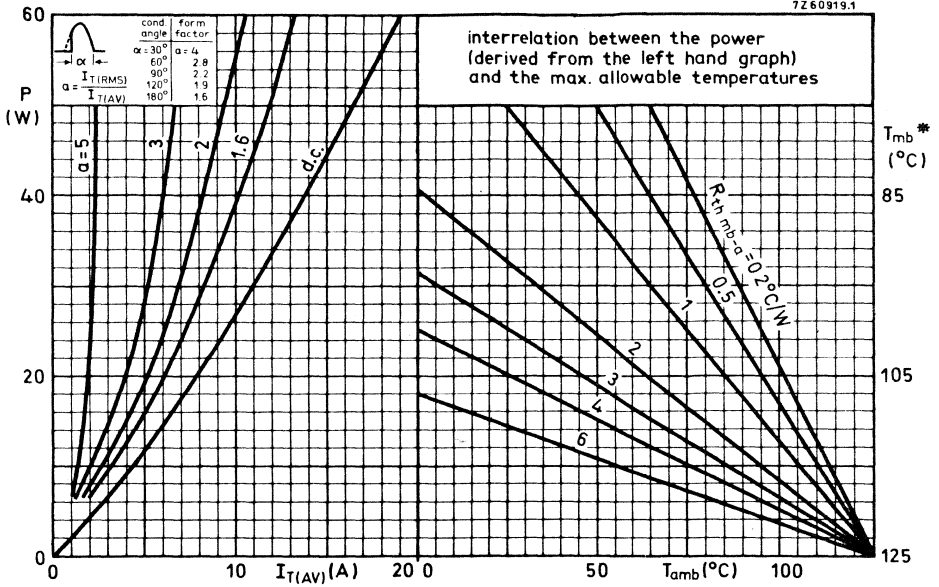


Fig. 3 Circuit-commutated turn-off time definitions.

**OPERATING NOTES**

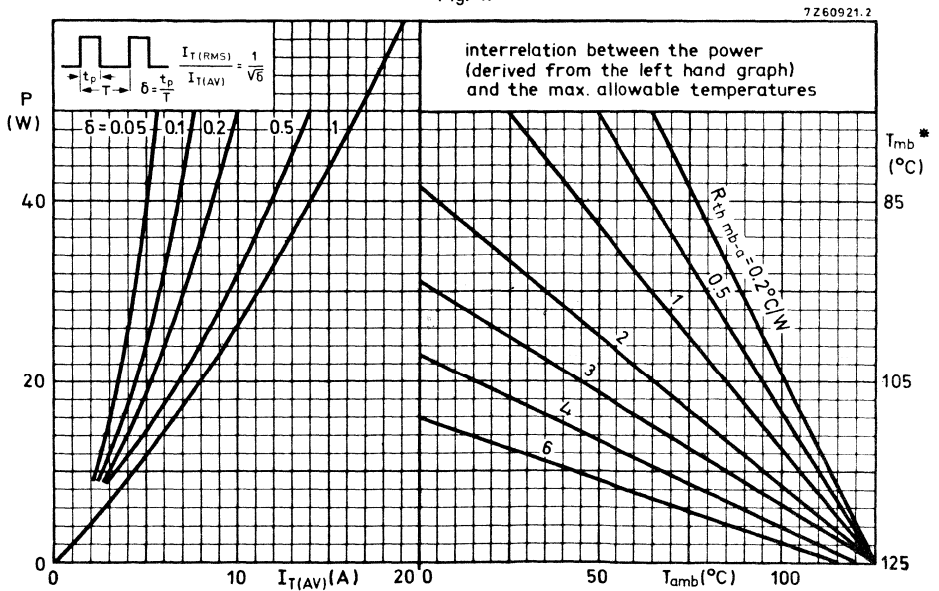
1. The terminals should neither be bent nor twisted; they should be soldered into the circuit so that there is no strain on them.  
 During soldering the heat conduction to the junction should be kept to a minimum.
2. High frequency operation.
  - a. The curves in Figs 13 and 14 show the additional average power losses due to turning on and turning off the thyristor in square pulse operation. This power should be added to that derived from the curves in Fig. 5.
  - b. Power loss due to turn-off may be discounted if an inverse parallel diode is connected across the thyristor to clip any reverse voltage which may occur following commutation. Note should be taken of the consequent increase in turn-off time (see Fig. 11).





\*  $T_{mb}$ -scale is for comparison purposes only and is correct only for  $R_{th\ mb-a} \leq 6^\circ C/W$

Fig. 4.



\*  $T_{mb}$ -scale is for comparison purposes only and is correct only for  $R_{th\ mb-a} \leq 2^\circ C/W$

Fig. 5.

7262267

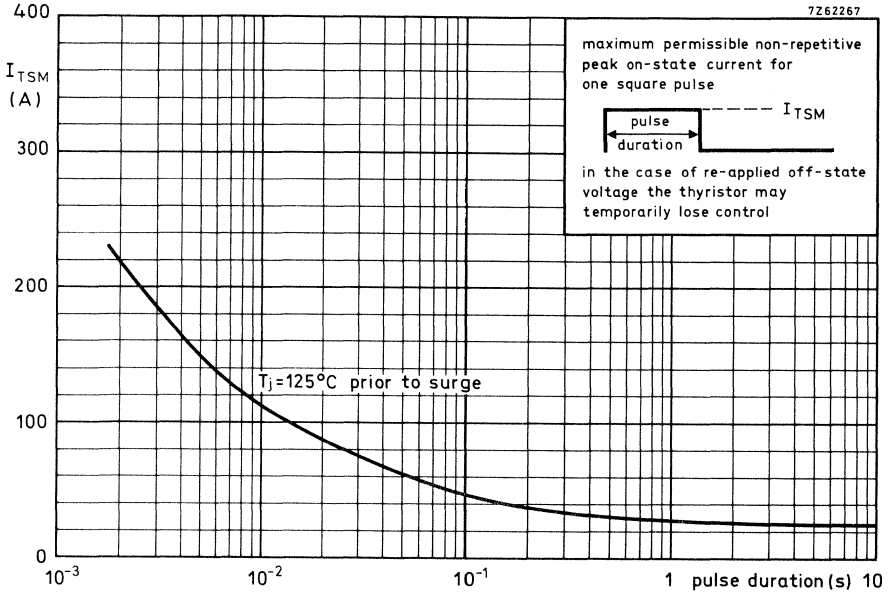


Fig. 6.

D7476

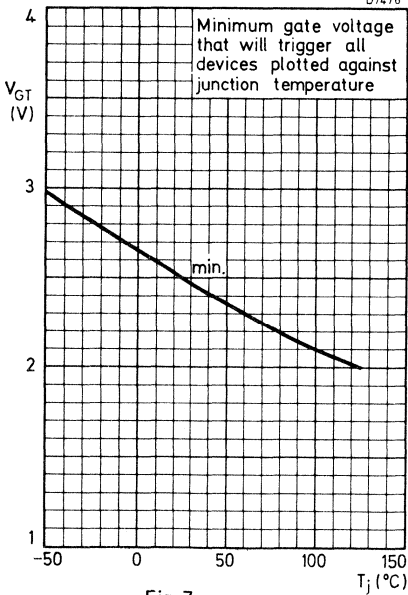


Fig. 7.

D7477

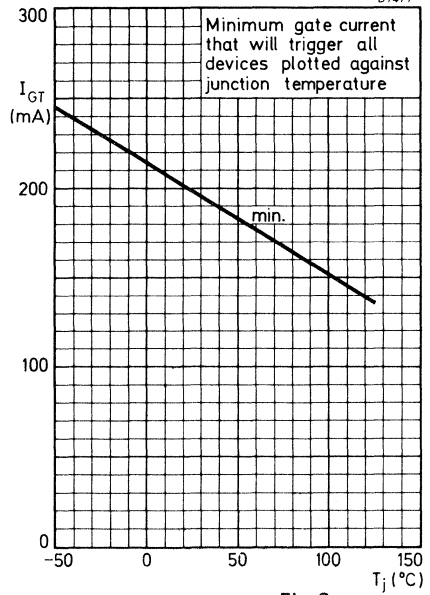


Fig. 8.

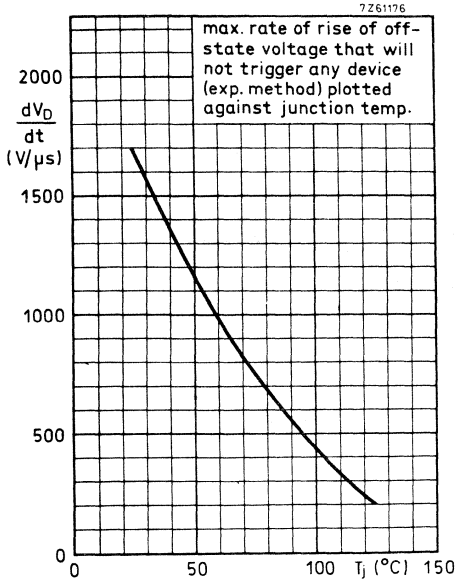


Fig. 9.

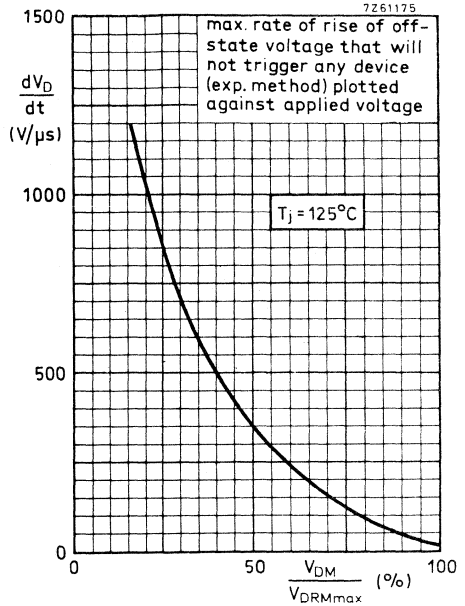


Fig. 10.

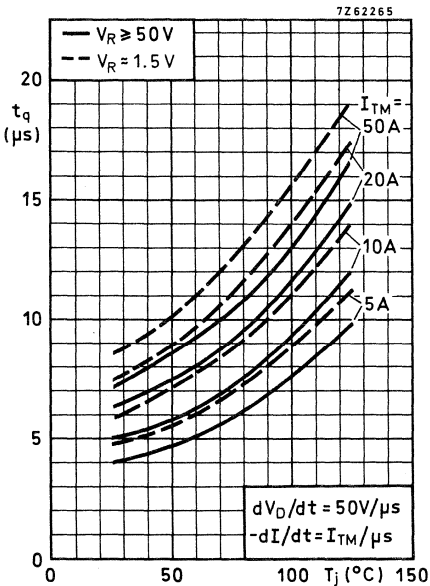


Fig. 11.

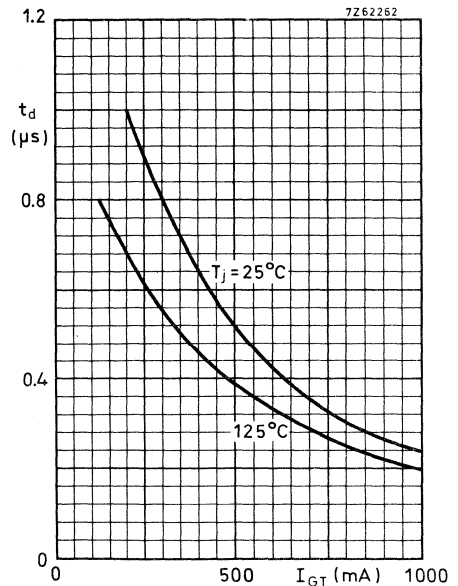


Fig. 12.

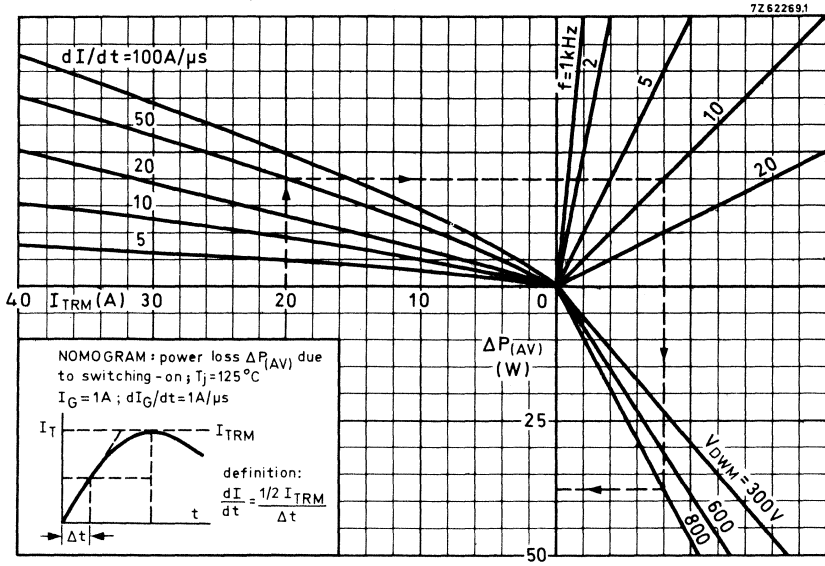


Fig. 13.

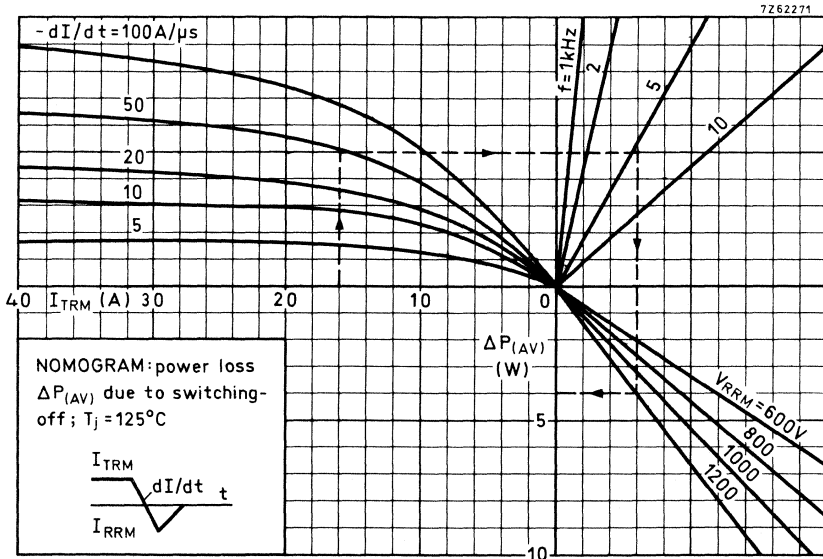


Fig. 14.

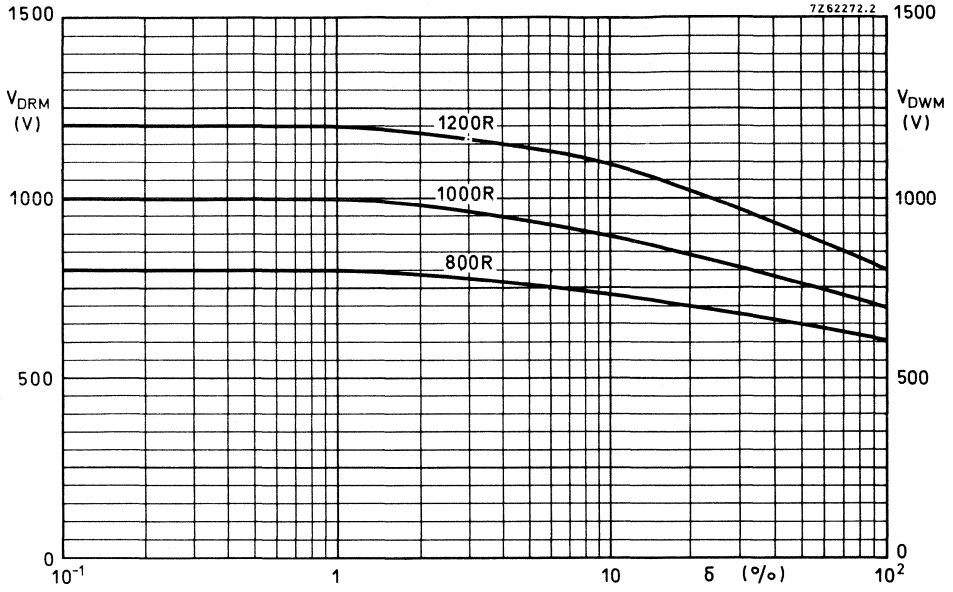


Fig. 15.

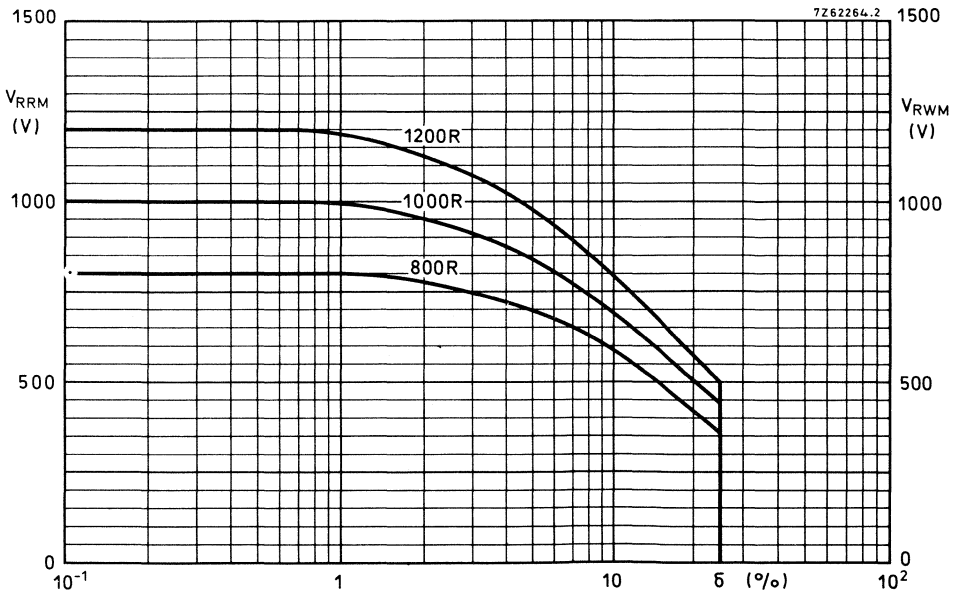


Fig. 16.

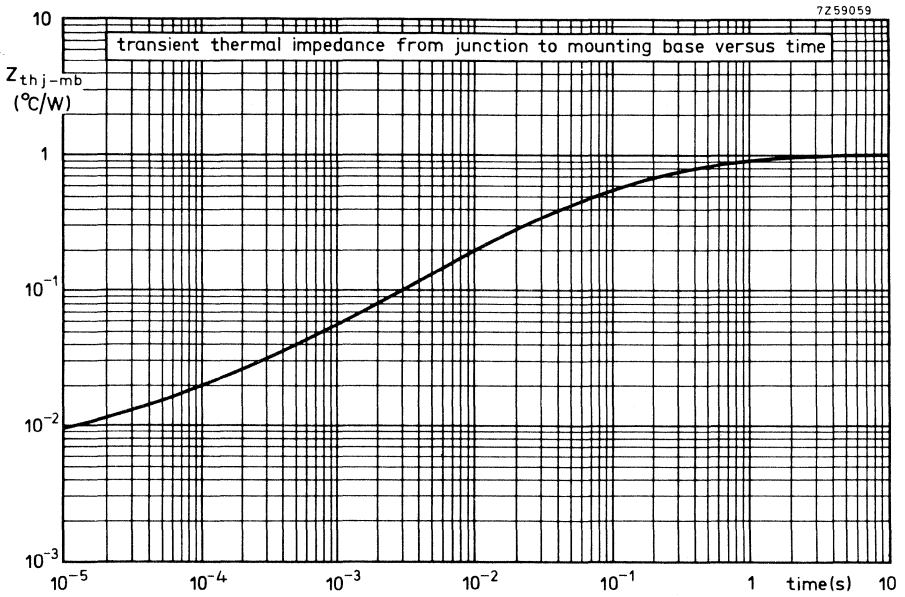


Fig. 17.

## FAST TURN-OFF THYRISTORS

A range of medium current fast turn-off thyristors in metal envelopes, intended for use in inverter applications.

The series consists of reverse polarity types (anode to stud) identified by a suffix R: BTW31-800RW to 1200RW.

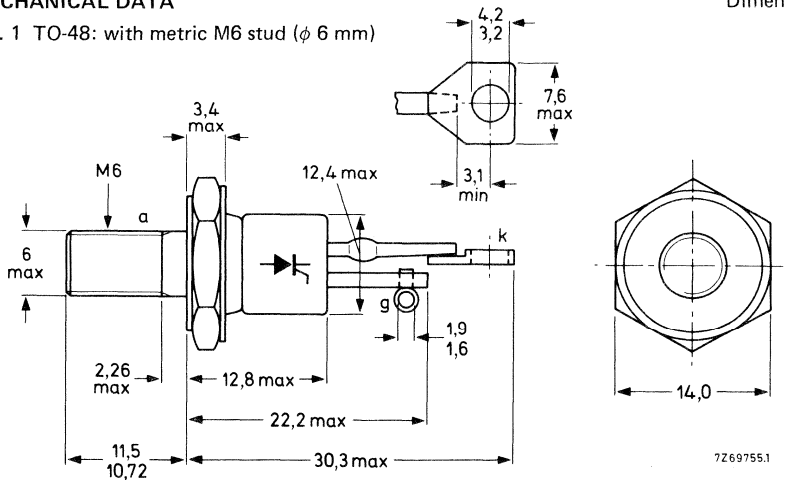
### QUICK REFERENCE DATA

		BTW31-800RW   1000RW   1200RW		
		$V_{DRM}/V_{RRM}$ max.	800	1000
Repetitive peak voltages	$V_{DRM}/V_{RRM}$ max.	800	1000	1200 V
Average on-state current	$I_T(AV)$ max.		22	A
R.M.S. on-state current	$I_T(RMS)$ max.		31	A
Non-repetitive peak on-state current	$I_{TSM}$ max.		240	A
Rate of rise of on-state current	$di_T/dt$ max.		100	A/ $\mu$ s
Rate of rise of off-state voltage that will not trigger any device	$dV_D/dt$	<	200	V/ $\mu$ s
Circuit-commutated turn-off time	$t_q$	<	20	$\mu$ s

### MECHANICAL DATA

Dimensions in mm

Fig. 1 TO-48: with metric M6 stud ( $\phi$  6 mm)



7Z69755.1

Net mass: 14 g

Diameter of clearance hole: max. 6,5 mm

Accessories supplied on request: 56264A

(mica washer, insulating ring, soldering tag)

Torque on nut: min. 1,7 Nm (17 kg cm)  
max. 3,5 Nm (35 kg cm)

Supplied with device:

1 nut, 1 lock washer

Nut dimensions across the flats: 10 mm

**RATINGS**

Limiting values in accordance with the Absolute Maximum System (IEC 134)

**Anode to cathode**

		BTW31-800RW	1000RW	1200RW
Non-repetitive peak voltages ( $t \leq 10$ ms)	$V_{DSM}^{**}/V_{RSM}$	max. 800	1000	1200 V
Repetitive peak voltages	$V_{DRM}/V_{RRM}$	max. 800	1000	1200 V▲
Crest working off-state voltage square-wave; $\delta = 0,5$	$V_{DWM}$	max. 600	800	1000 V *
Average on-state current assuming zero switching losses (averaged over any 20 ms period)				
square-wave; $\delta = 0,5$ ; up to $T_{mb} = 65$ °C	$I_T(AV)$	max.	22	A
square-wave; $\delta = 0,5$ ; at $T_{mb} = 85$ °C	$I_T(AV)$	max.	16	A
sinusoidal; at $T_{mb} = 85$ °C	$I_T(AV)$	max.	15	A
R.M.S. on-state current	$I_T(RMS)$	max.	31	A
Repetitive peak on-state current	$I_{TRM}$	max.	240	A
Non-repetitive peak on-state current				
$T_j = 125$ °C prior to surge (see Fig. 6)				
$t = 10$ ms; half sine-wave	$I_{TSM}$	max.	240	A
$t = 5$ ms; square pulse	$I_{TSM}$	max.	240	A
$I^2 t$ for fusing ( $t = 10$ ms)	$I^2 t$	max.	290	A <sup>2</sup> s
Rate of rise of on-state current after triggering with $I_G = 1$ A to $I_T = 50$ A; $dI_G/dt = 1$ A/ $\mu$ s	$dI_T/dt$	max.	100	A/ $\mu$ s

**Gate to cathode**

Reverse peak voltage	$V_{RGM}$	max.	10	V
Average power dissipation (averaged over any 20 ms period)	$P_G(AV)$	max.	1	W
Peak power dissipation	$P_{GM}$	max.	5	W

**Temperatures**

Storage temperature	$T_{stg}$		-55 to +125	°C
Junction temperature	$T_j$	max.	125	°C

**THERMAL RESISTANCE**

From junction to mounting base	$R_{th j-mb}$	=	1	°C/W
From mounting base to heatsink	$R_{th mb-h}$	=	0,2	°C/W
Transient thermal impedance ( $t = 1$ ms)	$Z_{th j-mb}$	=	0,06	°C/W

\* To ensure thermal stability:  $R_{th j-a} < 3$  °C/W (d.c. blocking) or  $< 6$  °C/W (square-wave;  $\delta = 0,5$ ).  
For smaller heatsinks  $T_{j max}$  should be derated. For square-wave see Fig. 5.

\*\* Although not recommended, higher off-state voltages may be applied without damage, but the thyristor may switch into the on-state. The rate of rise of on-state current should not exceed 30 A/ $\mu$ s.

▲ Thermal stability at higher voltage ratings is dependent on duty factor. See Figs 15 and 16.



**CHARACTERISTICS**

**Anode to cathode**

On-state voltage

$$I_T = 50 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$$

$$V_T < 2,9 \text{ V}^*$$

Rate of rise of off-state voltage that will not trigger any device;  
exponential method;  $V_D = 2/3V_{DRMmax}; T_j = 125 \text{ }^\circ\text{C}$

$$dV_D/dt < 200 \text{ V}/\mu\text{s}$$

Off-state current

$$V_D = V_{DWMmax}; T_j = 125 \text{ }^\circ\text{C}$$

$$I_D < 7 \text{ mA}$$

Holding current;  $T_j = 25 \text{ }^\circ\text{C}$

$$I_H < 200 \text{ mA}$$

**Gate to cathode**

Voltage that will trigger all devices

$$V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$$

$$V_{GT} > 2,5 \text{ V}$$

Voltage that will not trigger any device

$$V_D = V_{DRMmax}; T_j = 125 \text{ }^\circ\text{C}$$

$$V_{GD} < 0,2 \text{ V}$$

Current that will trigger all devices

$$V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$$

$$I_{GT} > 200 \text{ mA}$$

**Switching characteristics**

Gate-controlled turn-on time ( $t_{gt} = t_d + t_r$ ) when  
switched from  $V_D = V_{DWMmax}$  to  $I_T = 50 \text{ A}$ ;

$$I_{GT} = 200 \text{ mA}; dI_G/dt = 1 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$$

$$t_d < 1 \mu\text{s}$$

$$t_r < 0,7 \mu\text{s}$$

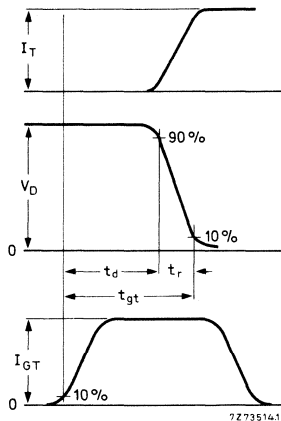


Fig. 2 Gate-controlled turn-on time definitions.

\* Measured under pulse conditions to avoid excessive dissipation.

**CHARACTERISTICS (continued)**

Circuit-commutated turn-off time when switched

from  $I_T = 10 \text{ A}$  to  $V_R \geq 50 \text{ V}$  with  $-dI_T/dt = 10 \text{ A}/\mu\text{s}$ ;  
 $dV_D/dt = 50 \text{ V}/\mu\text{s}$ ;  $T_j = 125 \text{ }^\circ\text{C}$

$$t_q < 20 \mu\text{s}$$

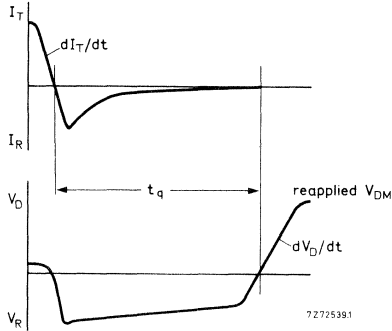
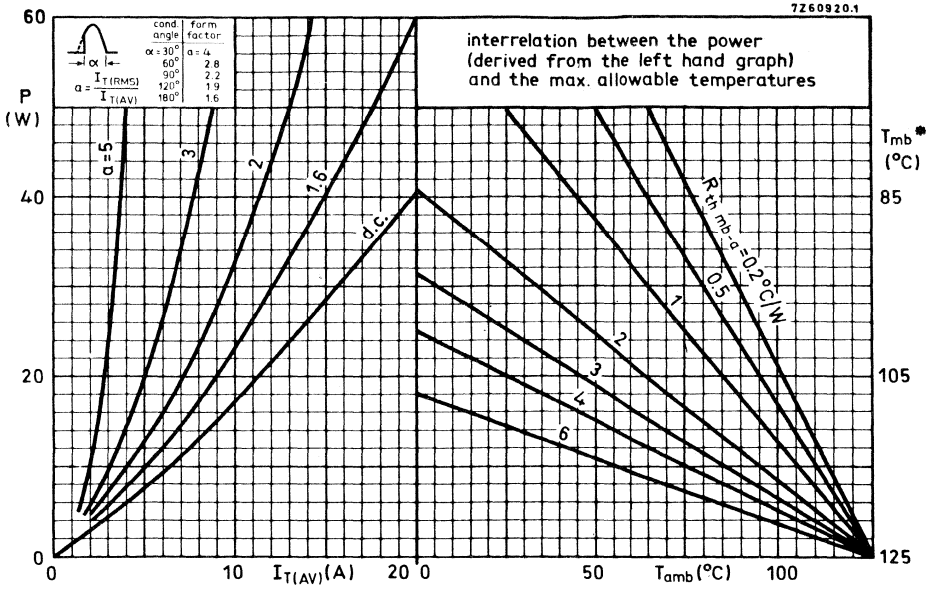


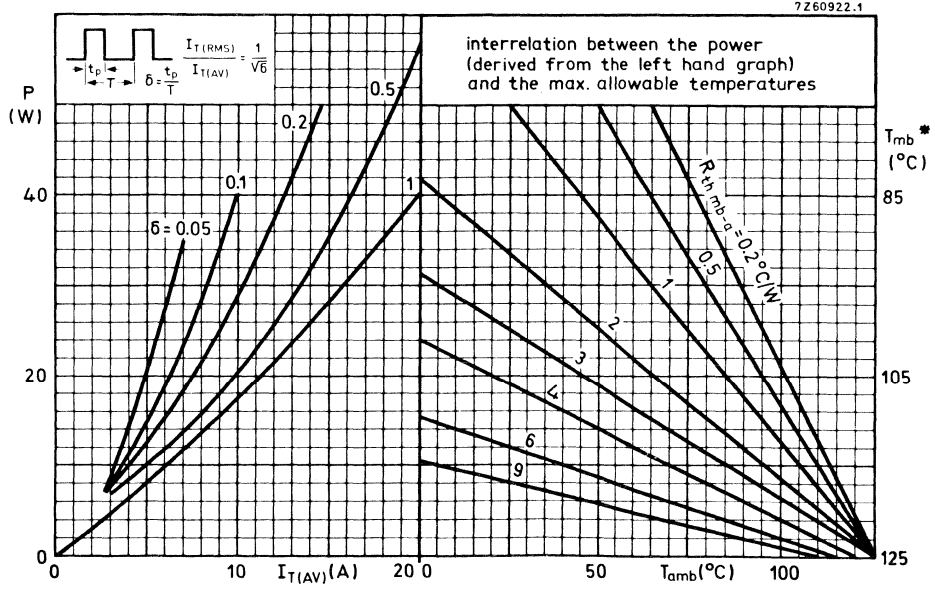
Fig. 3 Circuit-commutated turn-off time definitions.

**OPERATING NOTES**

1. The terminals should neither be bent nor twisted; they should be soldered into the circuit so that there is no strain on them.  
 During soldering the heat conduction to the junction should be kept to a minimum.
2. High frequency operation.
  - a. The curves in Figs 13 and 14 show the additional average power losses due to turning on and turning off the thyristor in square pulse operation. This power should be added to that derived from the curves in Fig. 5.
  - b. Power loss due to turn-off may be discounted if an inverse parallel diode is connected across the thyristor to clip any reverse voltage which may occur following commutation. Note should be taken of the consequent increase in turn-off time (see Fig. 11).



\*  $T_{mb}$ -scale is for comparison purposes only and is correct only for  $R_{th\ mb-a} \leq 6^\circ\text{C/W}$   
Fig. 4.



\*  $T_{mb}$ -scale is for comparison purposes only and is correct only for  $R_{th\ mb-a} \leq 2^\circ\text{C/W}$   
Fig. 5.

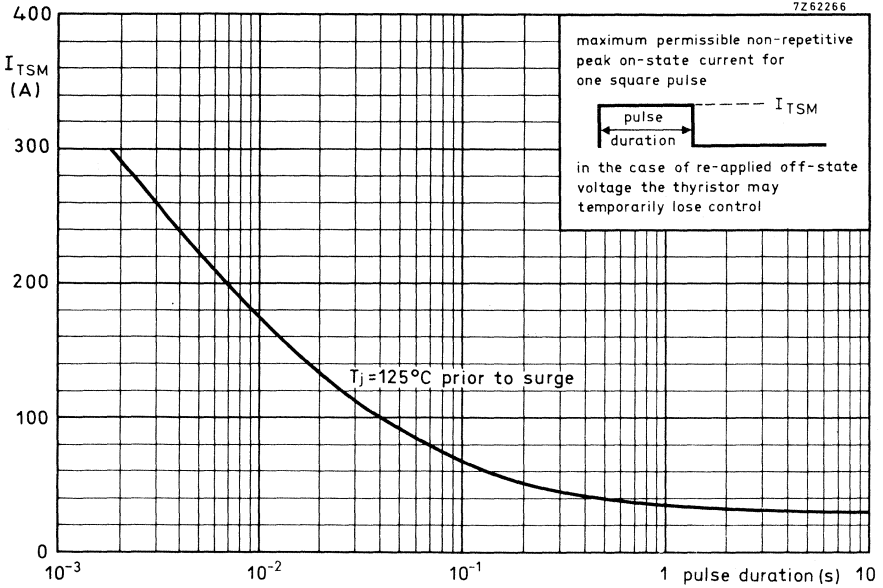


Fig. 6.

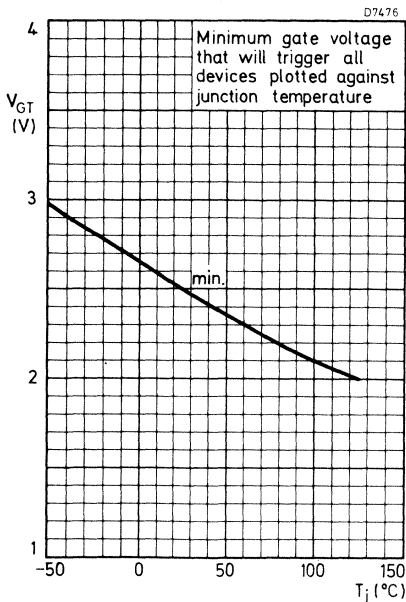


Fig. 7.

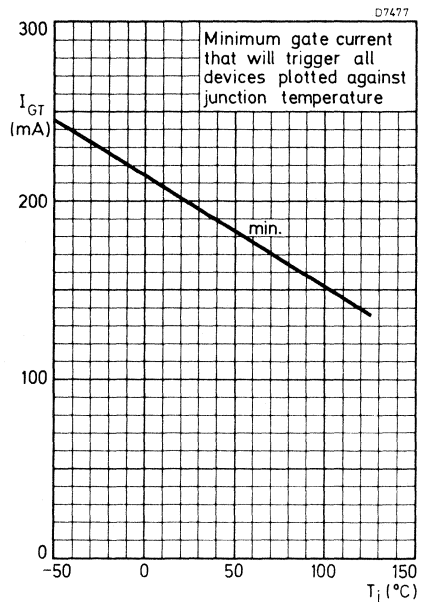


Fig. 8.

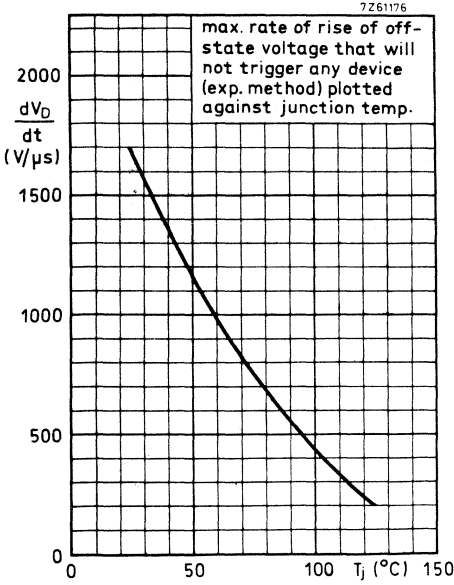


Fig. 9.

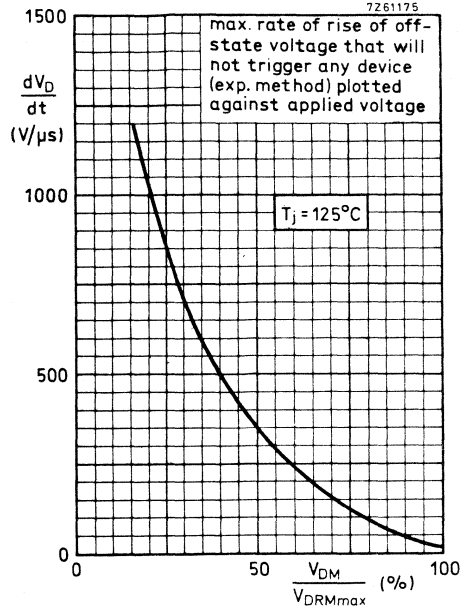


Fig. 10.

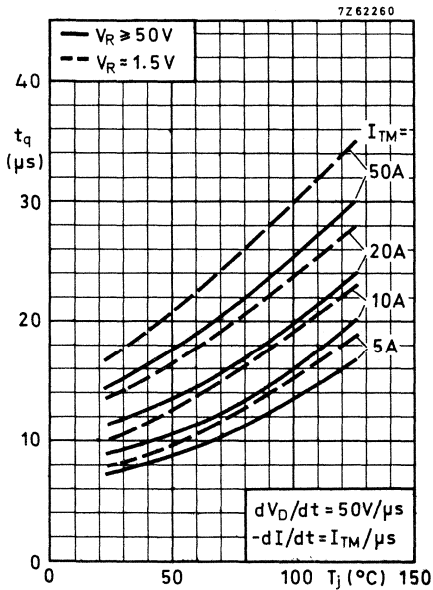


Fig. 11.

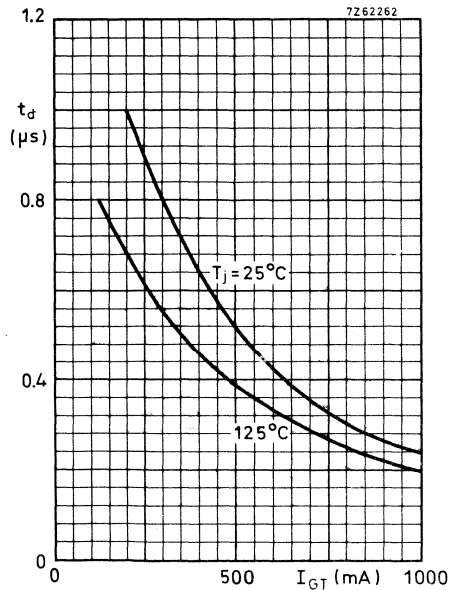


Fig. 12.

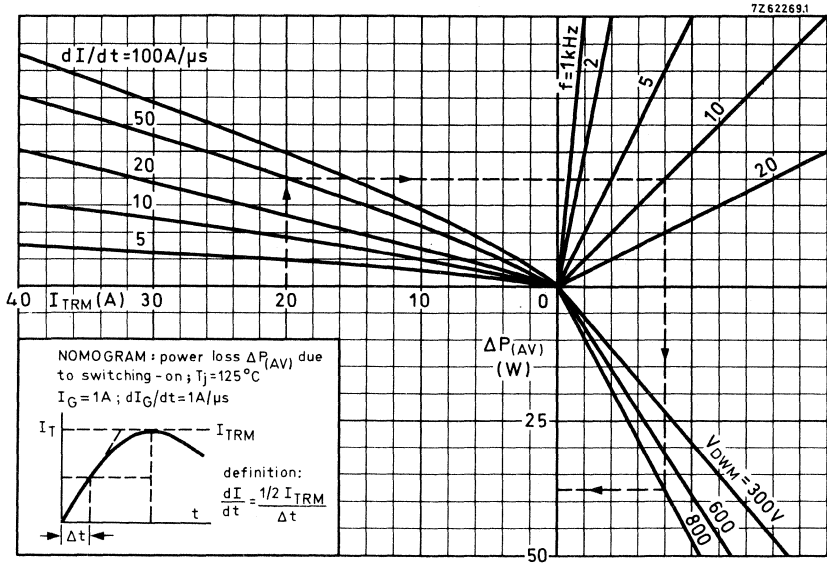


Fig. 13.

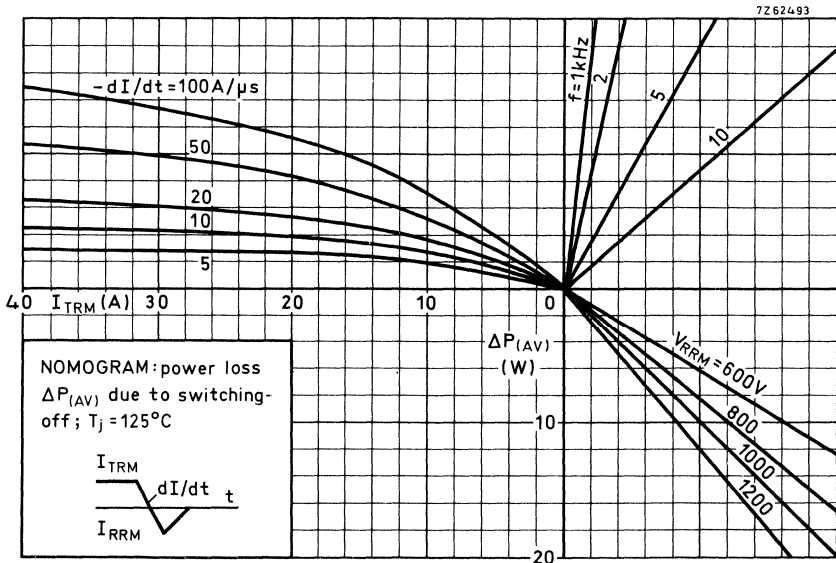


Fig. 14.

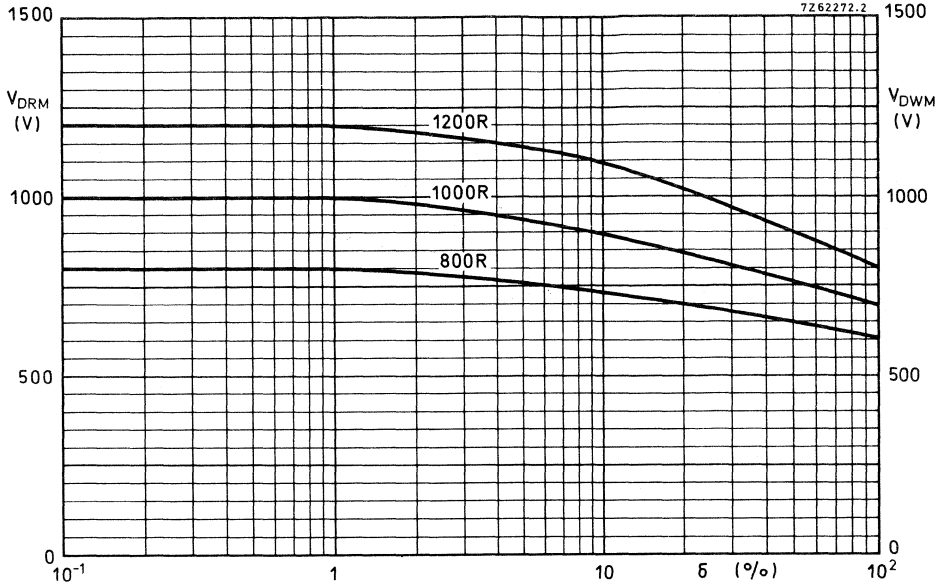


Fig. 15.

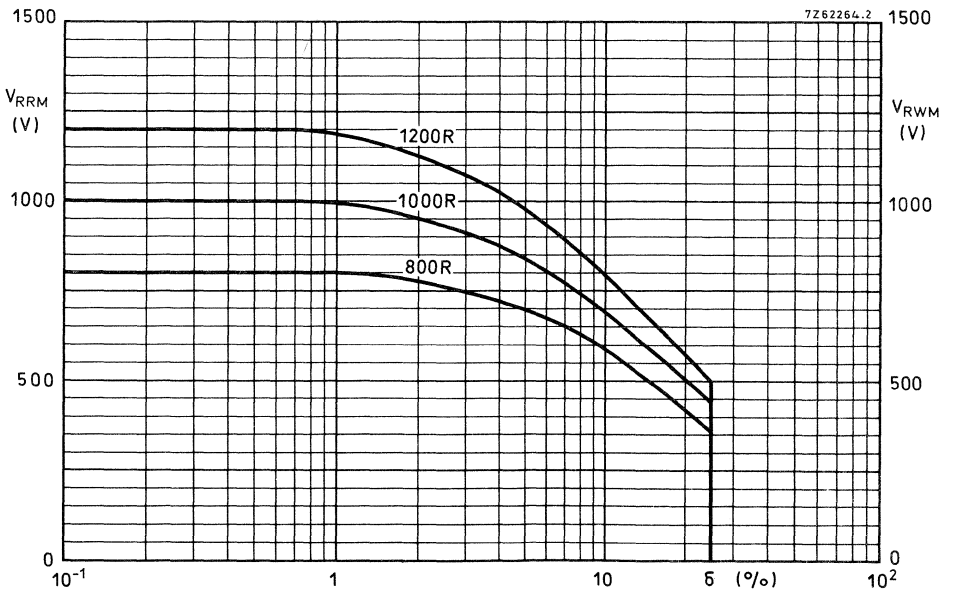


Fig. 16.

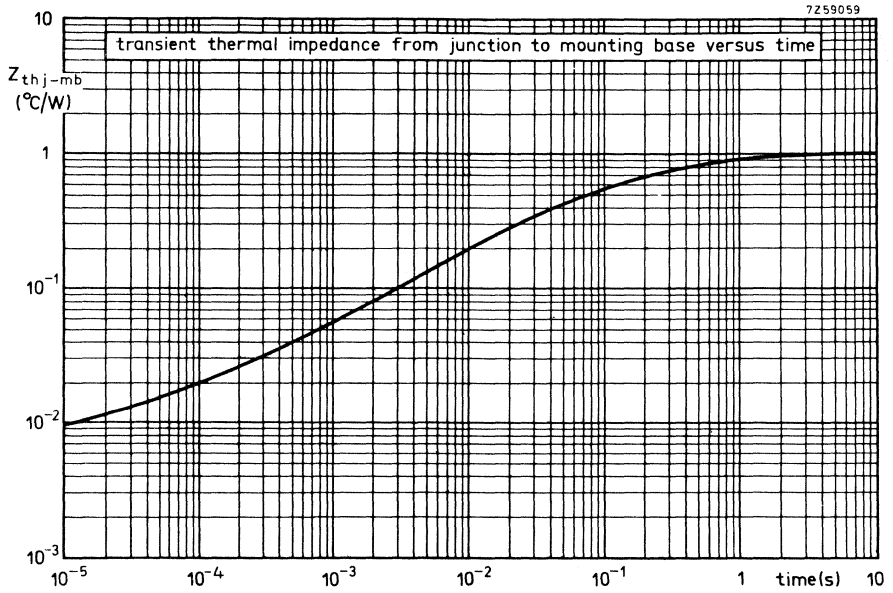


Fig. 17.



## FAST TURN-OFF THYRISTORS

A range of fast turn-off thyristors in metal envelopes, intended for use in inverter applications. The series consists of reverse polarity types (anode to stud) identified by a suffix R: BTW33-800R to 1200R.

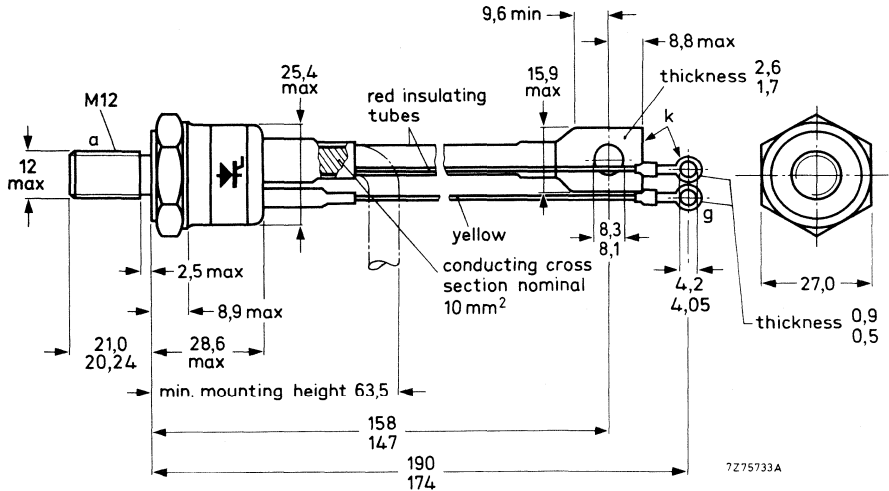
### QUICK REFERENCE DATA

	$V_{DRM}/V_{RRM}$	BTW33-800R	1000R	1200R
		max. 800	1000	1200 V
Repetitive peak voltages				
Average on-state current		$I_T(AV)$	max. 80	80 A
R.M.S. on-state current		$I_T(RMS)$	max. 110	110 A
Non-repetitive peak on-state current		$I_{TSM}$	max. 1500	1500 A
Circuit-commutated turn-off time		$t_q$	< 25	25 $\mu s$

### MECHANICAL DATA

Dimensions in mm

Fig. 1 TO-94; with metric M12 stud ( $\phi$  12 mm)



Net mass: 108 g  
 Diameter of clearance hole: max. 13,0 mm  
 Torque on nut: min. 9 Nm (90 kg cm)  
 max. 17,5 Nm (175 kg cm)

Supplied with device: 1 nut, 1 lock washer  
 Nut dimensions across the flats;  
 M12: 19 mm

**RATINGS**

Limiting values in accordance with the Absolute Maximum System (IEC 134)

**Anode to cathode**

		BTW33-800R	1000R	1200R
Non-repetitive peak voltages ( $t \leq 10$ ms)	$V_{DSM}^{**}/V_{RSM}$	max. 800	1000	1200 V
Repetitive peak voltages	$V_{DRM}/V_{RRM}$	max. 800	1000	1200 V▲
Crest working off-state voltage square-wave; $\delta = 0,5$	$V_{DWM}$	max. 600	800	1000 V *
Average on-state current assuming zero switching losses (averaged over any 20 ms period)				
square-wave; $\delta = 0,5$ ; up to $T_{mb} = 70$ °C		$I_{T(AV)}$	max.	80 A
square-wave; $\delta = 0,5$ ; at $T_{mb} = 85$ °C		$I_{T(AV)}$	max.	65 A
sinusoidal; at $T_{mb} = 85$ °C		$I_{T(AV)}$	max.	60 A
R.M.S. on-state current		$I_{T(RMS)}$	max.	110 A
Repetitive peak on-state current		$I_{TRM}$	max.	750 A
Non-repetitive peak on-state current				
$T_j = 125$ °C prior to surge				
$t = 10$ ms; half sine-wave (see Fig. 8)		$I_{TSM}$	max.	1500 A
$t = 5$ ms; square pulse (see Fig. 7)		$I_{TSM}$	max.	1500 A
$I^2t$ for fusing ( $t = 10$ ms)		$I^2t$	max.	11 250 A <sup>2</sup> s
Rate of rise of on-state current after triggering with $I_G = 750$ mA to $I_T = 200$ A; $di_G/dt = 1$ A/ $\mu$ s		$di_T/dt$	max.	100 A/ $\mu$ s

**Gate to cathode**

Reverse peak voltage	$V_{RGM}$	max.	10 V
Average power dissipation (averaged over any 20 ms period)	$P_{G(AV)}$	max.	2 W
Peak power dissipation	$P_{GM}$	max.	10 W
	$T_{stg}$		-55 to + 125 °C

**Temperatures**

Storage temperature	$T_{stg}$		-55 to + 125 °C
Junction temperature	$T_j$	max.	125 °C

**THERMAL RESISTANCE**

From junction to mounting base	$R_{th j-mb}$	=	0,3 °C/W
From mounting base to heatsink	$R_{th mb-h}$	=	0,1 °C/W
Transient thermal impedance ( $t = 1$ ms)	$Z_{th j-mb}$	=	0,015 °C/W

\* To ensure thermal stability:  $R_{th j-a} < 0,75$  °C/W (d.c. blocking) or  $< 1,5$  °C/W (square-wave;  $\delta = 0,5$ ). For smaller heatsinks  $T_{j max}$  should be derated. For square-wave see Fig. 6.

\*\* Although not recommended, higher off-state voltages may be applied without damage, but the thyristor may switch into the on-state. The rate of rise of on-state current should not exceed 20 A/ $\mu$ s.

▲ Thermal stability at higher voltage ratings is dependent on duty factor. See Figs 19 and 20.

**CHARACTERISTICS**

**Anode to cathode**

On-state voltage

$I_T = 200 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_T < 3 \text{ V}^*$

Rate of rise of off-state voltage that will not trigger

any device; exponential method;  $V_D = 2/3 V_{DRMmax}; T_j = 125 \text{ }^\circ\text{C}$

$dV_D/dt < 200 \text{ V}/\mu\text{s}$

Off-state current

$V_D = V_{DWMmax}; T_j = 125 \text{ }^\circ\text{C}$

$I_D < 25 \text{ mA}$

Holding current;  $T_j = 25 \text{ }^\circ\text{C}$

$I_H < 200 \text{ mA}$

Latching current;  $T_j = 25 \text{ }^\circ\text{C}$

$I_L < 400 \text{ mA}$

**Gate to cathode**

Voltage that will trigger all devices

$V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$

$V_{GT} > 2,5 \text{ V}$

Voltage that will not trigger any device

$V_D = V_{DRMmax}; T_j = 125 \text{ }^\circ\text{C}$

$V_{GD} < 0,2 \text{ V}$

Current that will trigger all devices

$V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$

$I_{GT} > 150 \text{ mA}$

**Switching characteristics**

Gate-controlled turn-on time ( $t_{gt} = t_d + t_r$ ) when switched from  $V_D = V_{DWMmax}$  to  $I_T = 200 \text{ A}$ ;

$I_{GT} = 200 \text{ mA}; dI_G/dt = 1 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

$t_d < 2 \mu\text{s}$

$t_r < 2 \mu\text{s}$

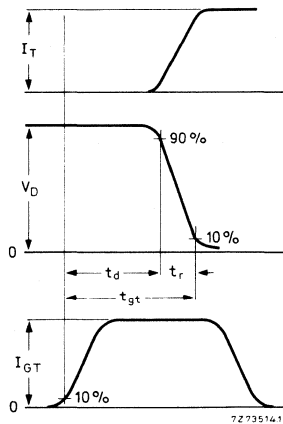


Fig. 2 Gate-controlled turn-on time definitions.

\* Measured under pulse conditions to avoid excessive dissipation.

**CHARACTERISTICS** (continued)

Circuit-commutated turn-off time when switched  
 from  $I_T = 50$  A to  $V_R \geq 50$  V with  $-dI_T/dt = 50$  A/ $\mu$ s;  
 $dV_D/dt = 25$  V/ $\mu$ s;  $T_j = 125$  °C

$$t_q < 25 \mu\text{s}$$

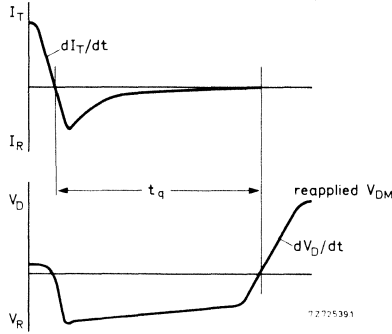


Fig. 3 Circuit-commutated turn-off time definitions.

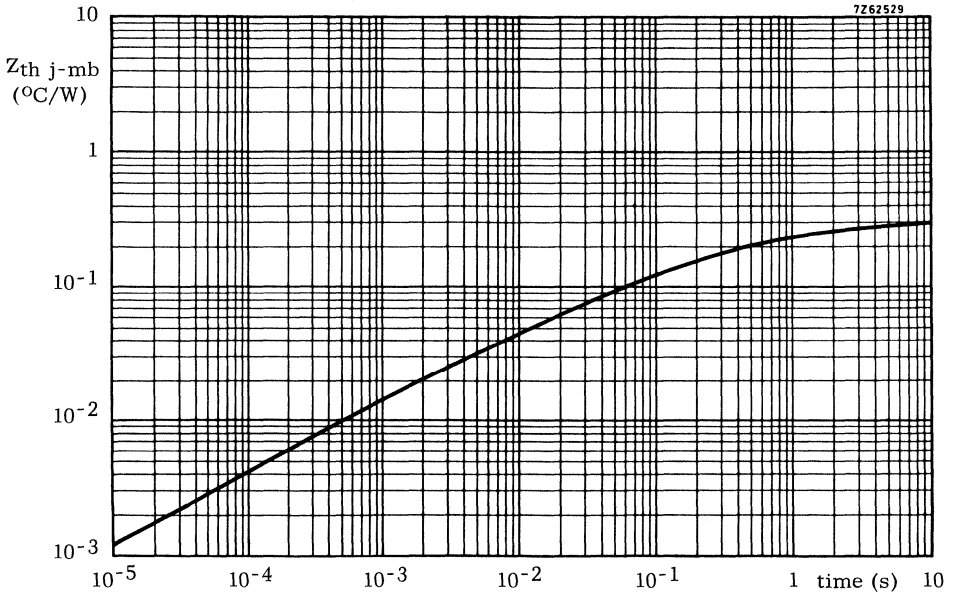


Fig. 4.

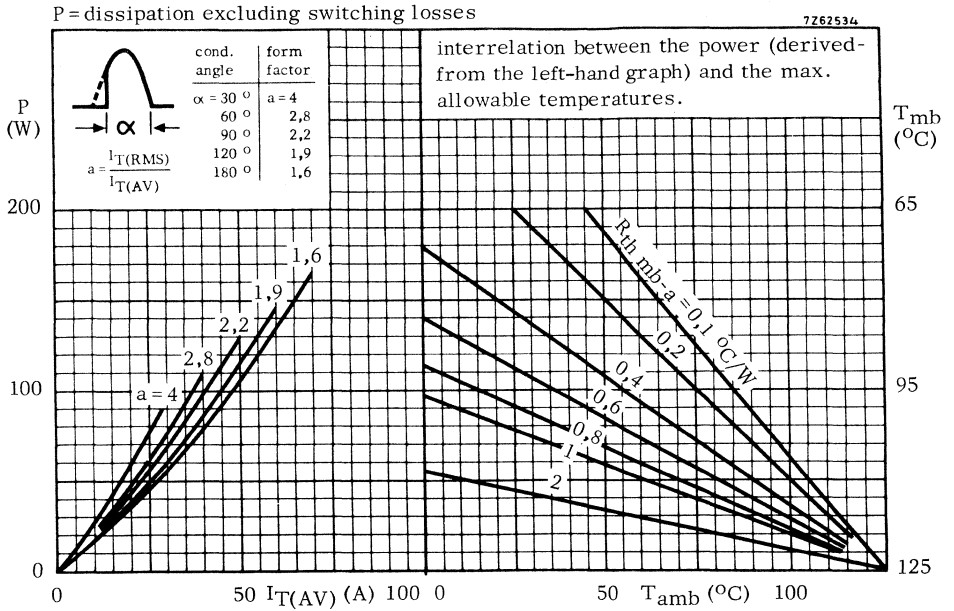
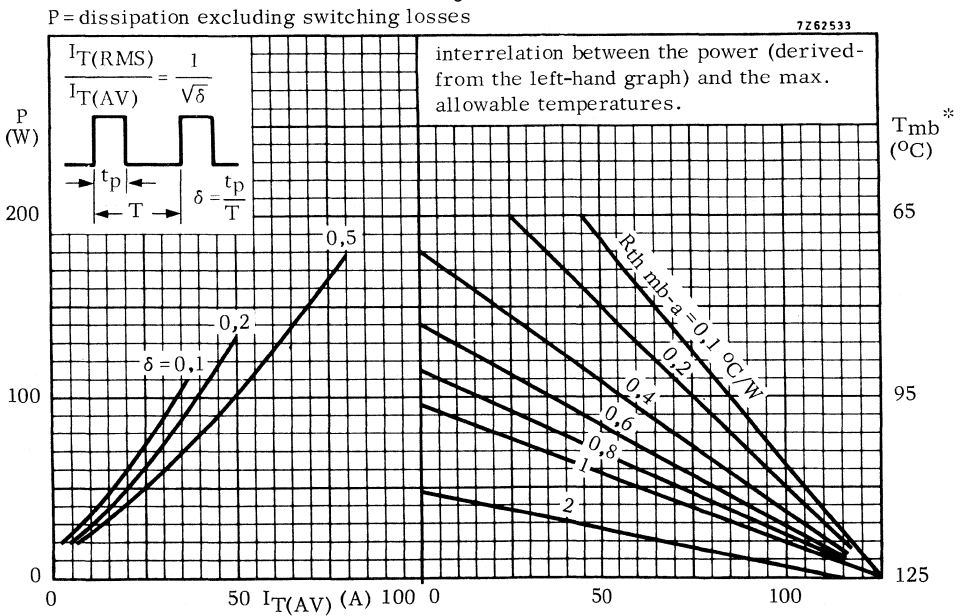


Fig. 5.



\*  $T_{mb}$ -scale is for comparison purposes only and is correct only for  $R_{th\ mb-a} \leq 1,0\ ^\circ\text{C/W}$ .

Fig. 6.

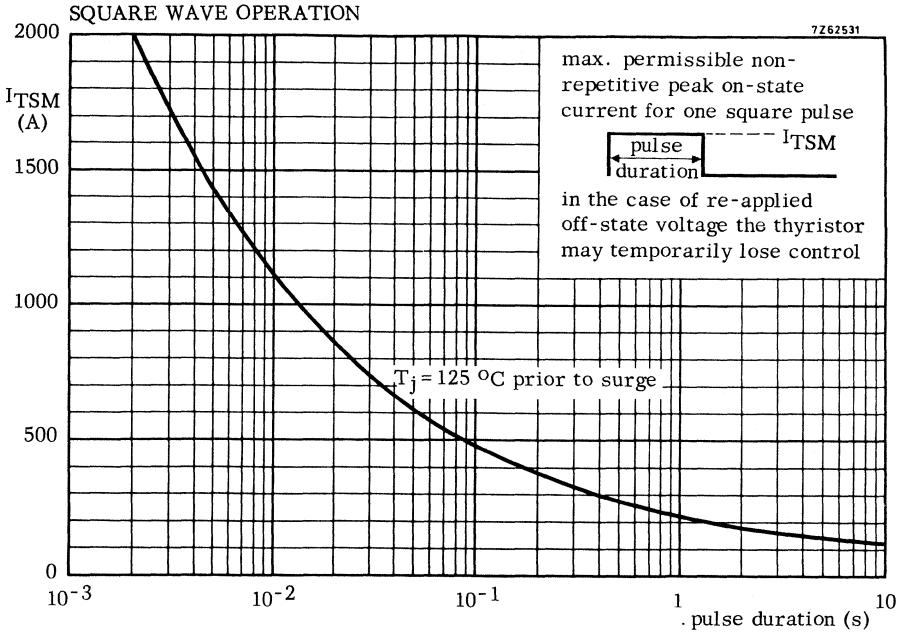


Fig. 7.

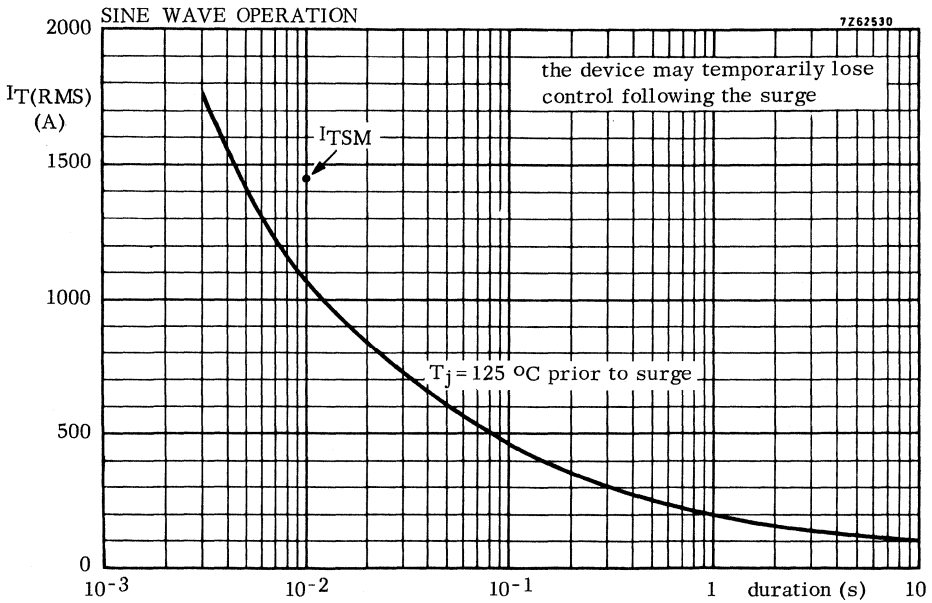


Fig. 8.

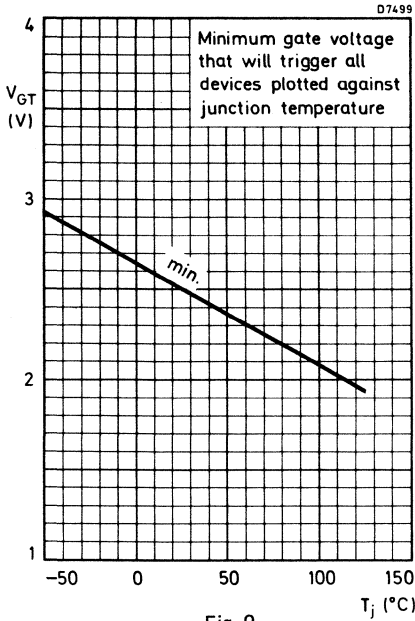


Fig. 9.

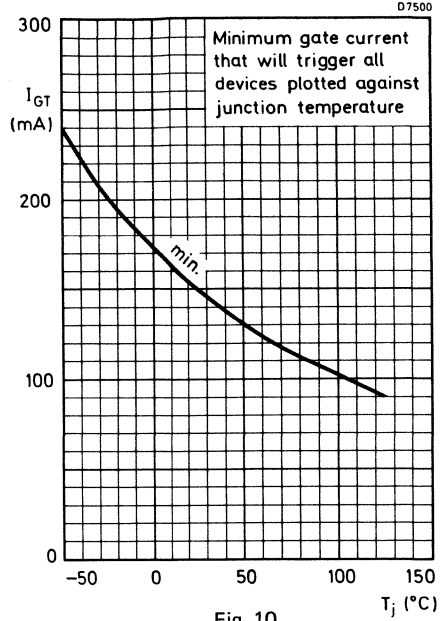


Fig. 10.

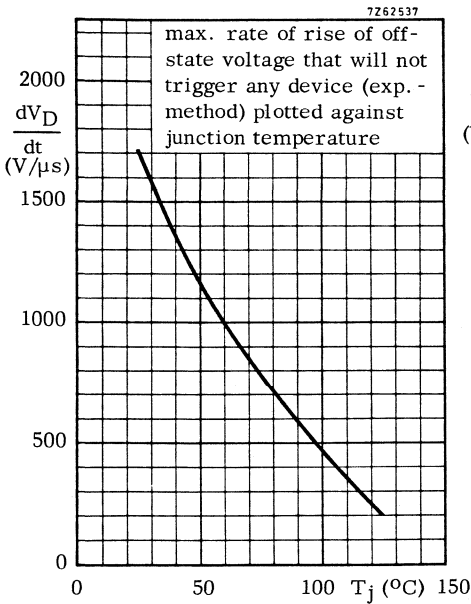


Fig. 11.

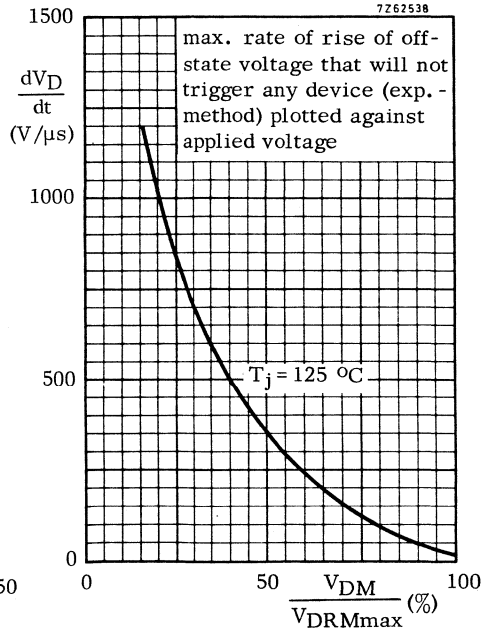
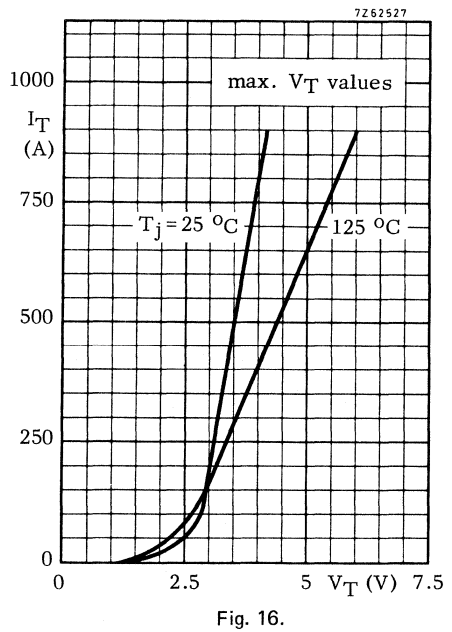
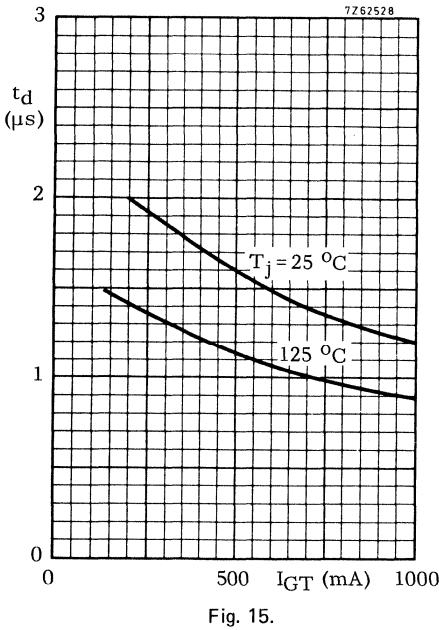
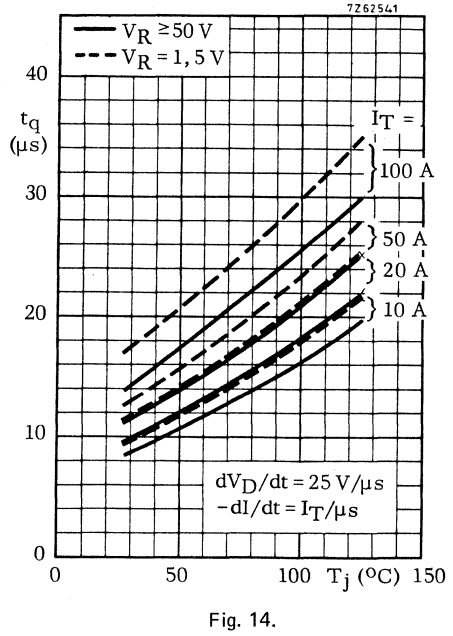
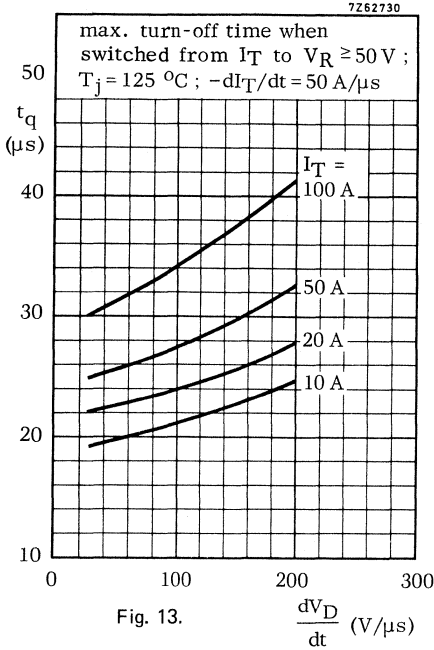


Fig. 12.





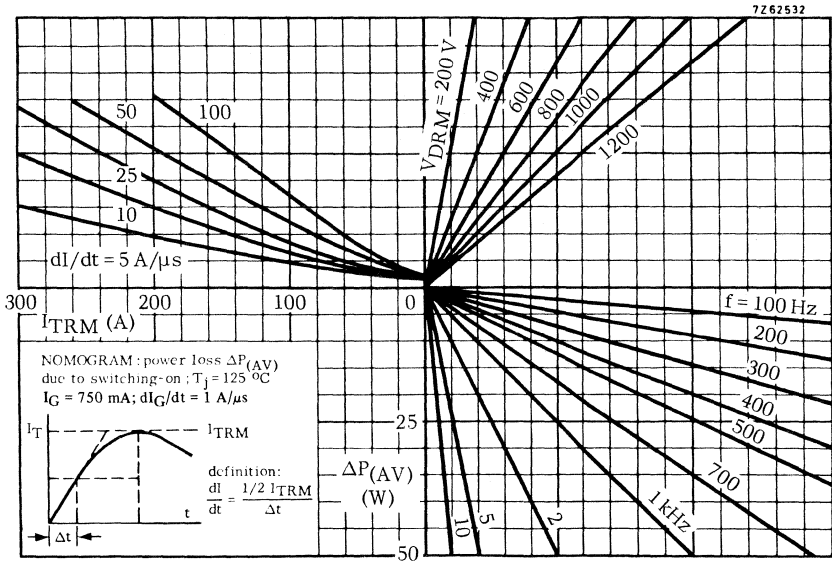


Fig. 17.

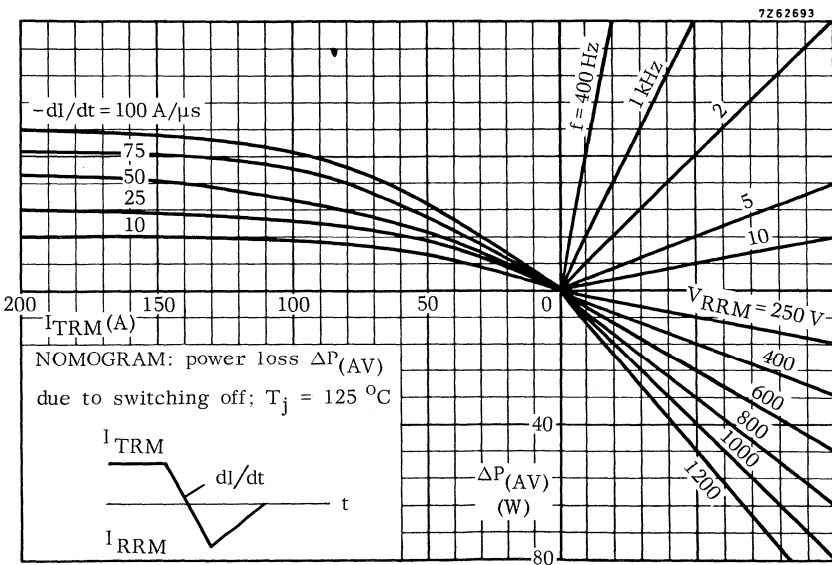


Fig. 18.

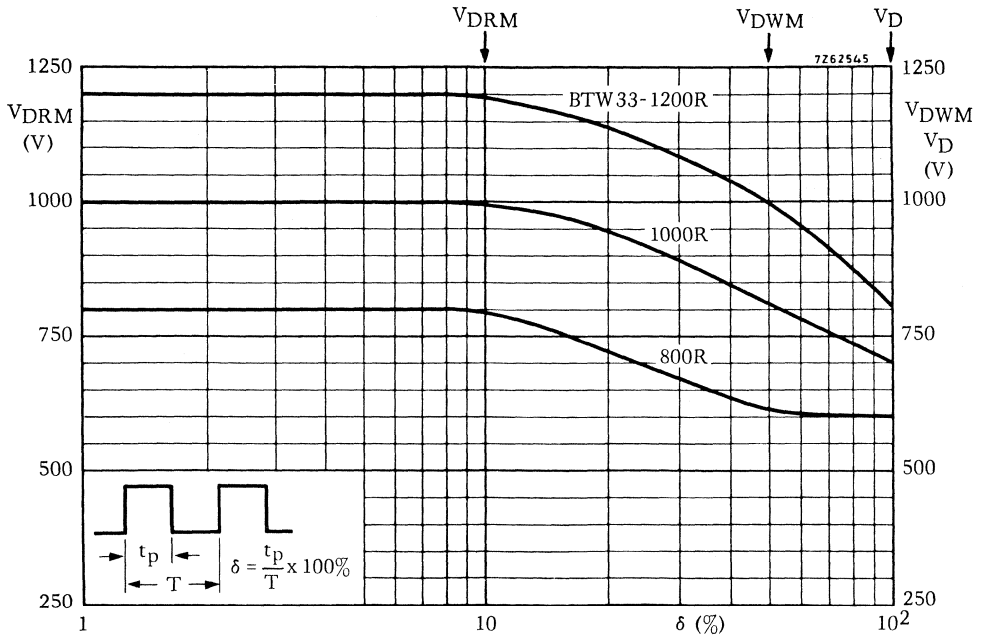


Fig. 19.

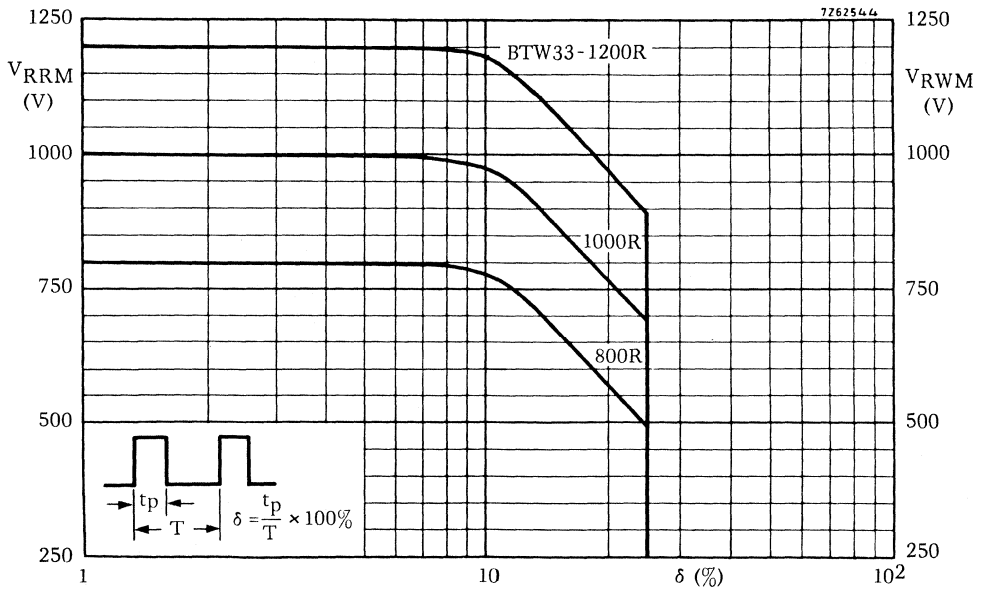


Fig. 20.

THYRISTORS

Also available to BS9341-F082

Silicon thyristors in metal envelopes, intended for use in power control circuits (e.g. light and motor control) and power switching systems.

The series consists of reverse polarity types (anode to stud) identified by a suffix R: BTW38-600R to 1200R.

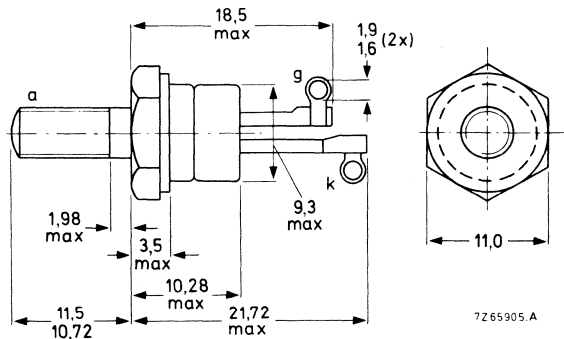
QUICK REFERENCE DATA

		BTW38-600R	800R	1000R	1200R
Repetitive peak voltages	$V_{DRM}/V_{RRM}$	max. 600	800	1000	1200 V
Average on-state current			$I_T(AV)$	max. 10 A	
R.M.S. on-state current			$I_T(RMS)$	max. 16 A	
Non-repetitive peak on-state current			$I_{TSM}$	max. 150 A	

MECHANICAL DATA

Dimensions in mm

Fig. 1 TO-64: with metric M5 stud ( $\phi$  5 mm); e.g. BTW38-600R.



- Net mass: 7 g
- Diameter of clearance hole: max. 5,2 mm
- Accessories supplied on request:
  - 56295 (PTFE bush, 2 mica washers, plain washer, tag)
  - 56262A (mica washer, insulating ring, plain washer)

- Torque on nut: min. 0,9 Nm (9 kg cm)
- max. 1,7 Nm (17 kg cm)

- Supplied with device: 1 nut, 1 lock washer
- Nut dimensions: across the flats; M5; 8,0 mm

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

Anode to cathode		BTW38-600R	800R	1000R	1200R
Non-repetitive peak voltages ( $t \leq 10$ ms)	$V_{DSM}/V_{RSM}$	max. 600	800	1000	1200 V
Repetitive peak voltages	$V_{DRM}/V_{RRM}$	max. 600	800	1000	1200 V
Crest working voltages	$V_{DWM}/V_{RWM}$	max. 400	600	700	800 V *
Average on-state current (averaged over any 20 ms period) up to $T_{mb} = 85$ °C		$I_T(AV)$		max.	10 A
R.M.S. on-state current		$I_T(RMS)$		max.	16 A
Repetitive peak on-state current		$I_{TRM}$		max.	75 A
Non-repetitive peak on-state current; $t = 10$ ms; half sine-wave; $T_j = 125$ °C prior to surge; with reapplied $V_{RWMmax}$		$I_{TSM}$		max.	150 A
$I^2 t$ for fusing ( $t = 10$ ms)		$I^2 t$		max.	112 A <sup>2</sup> s
Rate of rise of on-state current after triggering with $I_G = 250$ mA to $I_T = 25$ A; $dI_G/dt = 0,25$ A/ $\mu$ s		$dI_T/dt$		max.	50 A/ $\mu$ s
<b>Gate to cathode</b>					
Average power dissipation (averaged over any 20 ms period)		$P_G(AV)$		max.	0,5 W
Peak power dissipation		$P_{GM}$		max.	5 W
<b>Temperatures</b>					
Storage temperature		$T_{stg}$			-55 to +125 °C
Junction temperature		$T_j$		max.	125 °C
<b>THERMAL RESISTANCE</b>					
From junction to mounting base		$R_{th j-mb}$	=		1,8 °C/W
From mounting base to heatsink with heatsink compound		$R_{th mb-h}$	=		0,5 °C/W
From junction to ambient in free air		$R_{th j-a}$	=		45 °C/W
Transient thermal impedance ( $t = 1$ ms)		$Z_{th j-mb}$	=		0,1 °C/W

## OPERATING NOTE

The terminals should neither be bent nor twisted; they should be soldered into the circuit so that there is no strain on them.

During soldering the heat conduction to the junction should be kept to a minimum.

\* To ensure thermal stability:  $R_{th j-a} < 4$  °C/W (d.c. blocking) or  $< 8$  °C/W (a.c.). For smaller heat-sinks  $T_j max$  should be derated. For a.c. see Fig. 3.

**CHARACTERISTICS**

**Anode to cathode**

On-state voltage

$I_T = 20 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_T < 2 \text{ V}^*$

Rate of rise of off-state voltage that will not trigger

any device; exponential method;  $V_D = 2/3 V_{DRMmax}; T_j = 125 \text{ }^\circ\text{C}$

$dV_D/dt < 50 \text{ V}/\mu\text{s}$

Reverse current

$V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$

$I_R < 3 \text{ mA}$

Off-state current

$V_D = V_{DWMmax}; T_j = 125 \text{ }^\circ\text{C}$

$I_D < 3 \text{ mA}$

Latching current;  $T_j = 25 \text{ }^\circ\text{C}$

$I_L < 150 \text{ mA}$

Holding current;  $T_j = 25 \text{ }^\circ\text{C}$

$I_H < 75 \text{ mA}$

**Gate to cathode**

Voltage that will trigger all devices

$V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$

$V_{GT} > 1,5 \text{ V}$

Voltage that will not trigger any device

$V_D = V_{DRMmax}; T_j = 125 \text{ }^\circ\text{C}$

$V_{GD} < 200 \text{ mV}$

Current that will trigger all devices

$V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$

$I_{GT} > 50 \text{ mA}$

**Switching characteristics**

Gate-controlled turn-on time ( $t_{gt} = t_d + t_r$ ) when

switched from  $V_D = 800 \text{ V}$  to  $I_T = 25 \text{ A}$ ;

$I_{GT} = 250 \text{ mA}; dI_G/dt = 0,25 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

$t_{gt} < 1,5 \mu\text{s}$   
 $t_r \text{ typ. } 0,2 \mu\text{s}$

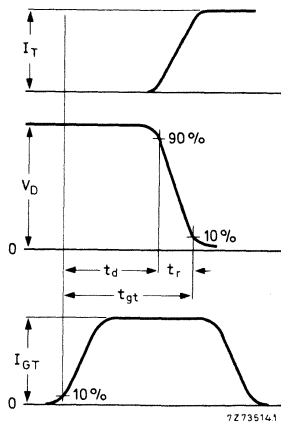


Fig. 2 Gate-controlled turn-on time definitions.

\* Measured under pulse conditions to avoid excessive dissipation.

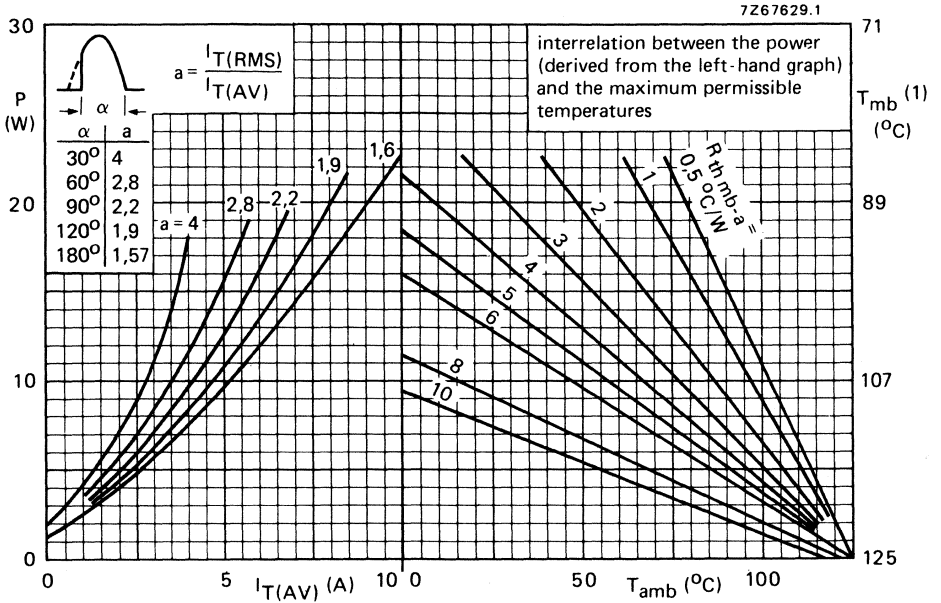


Fig. 3 (1)  $T_{mb}$ -scale is for comparison purposes only and is correct only for  $R_{th\ mb-a} \leq 6\text{ }^\circ\text{C/W}$ .

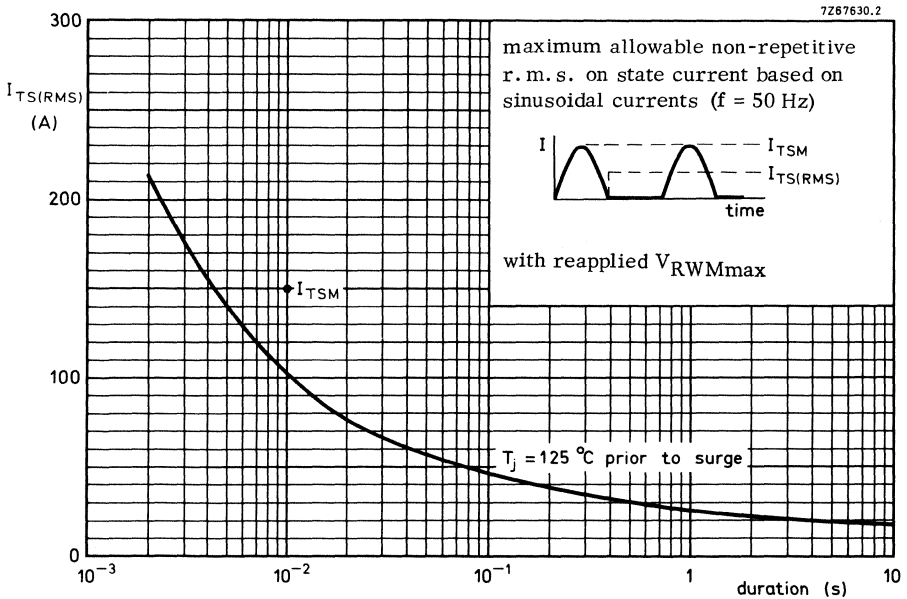


Fig. 4.

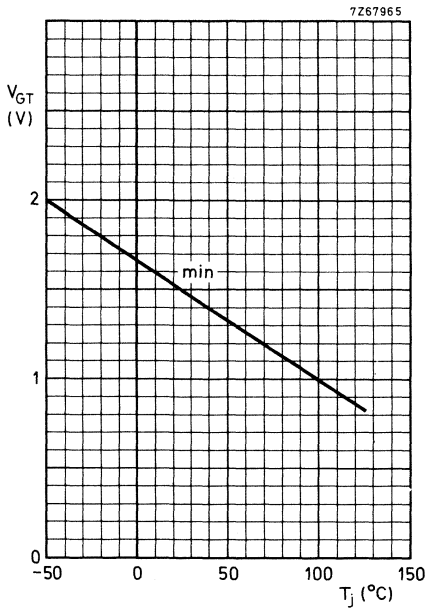


Fig. 5 Minimum gate voltage that will trigger all devices as a function of  $T_J$ .

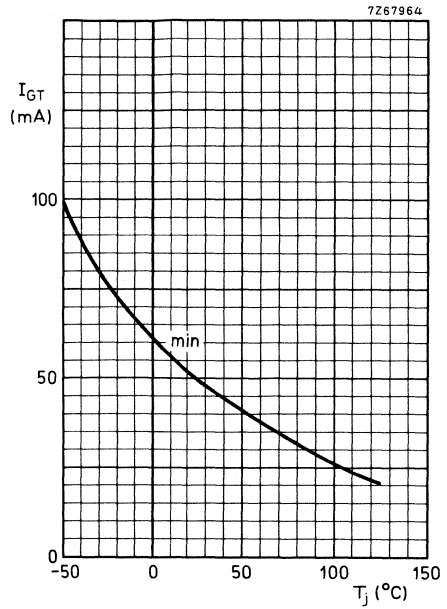


Fig. 6 Minimum gate current that will trigger all devices as a function of  $T_J$ .

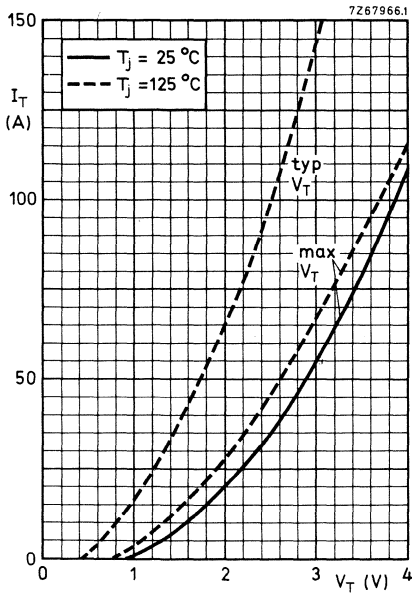


Fig. 7.

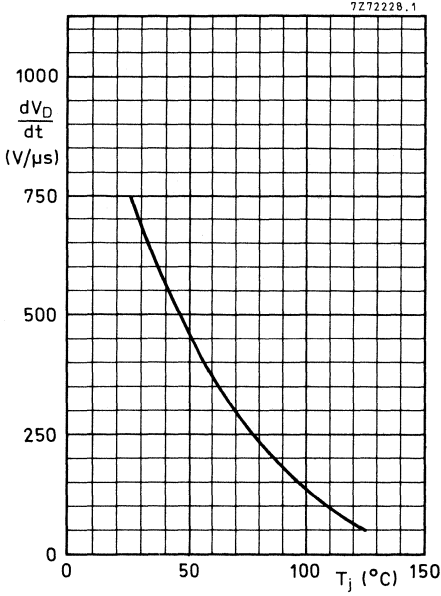


Fig. 8 Maximum rate of rise of off-state voltage that will not trigger any device (exponential method) as a function of  $T_j$ .

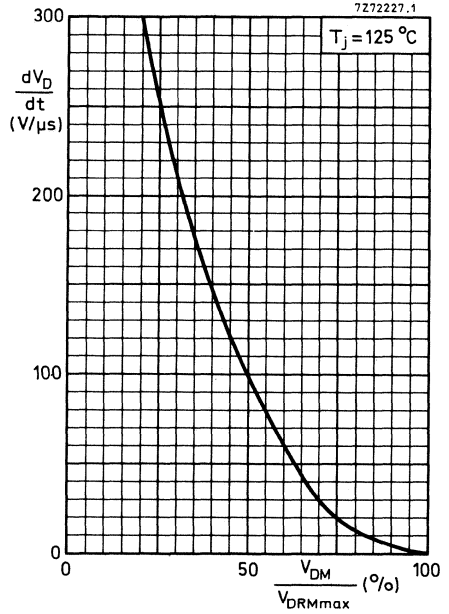


Fig. 9 Maximum rate of rise of off-state voltage that will not trigger any device (exponential method) as a function of applied voltage.



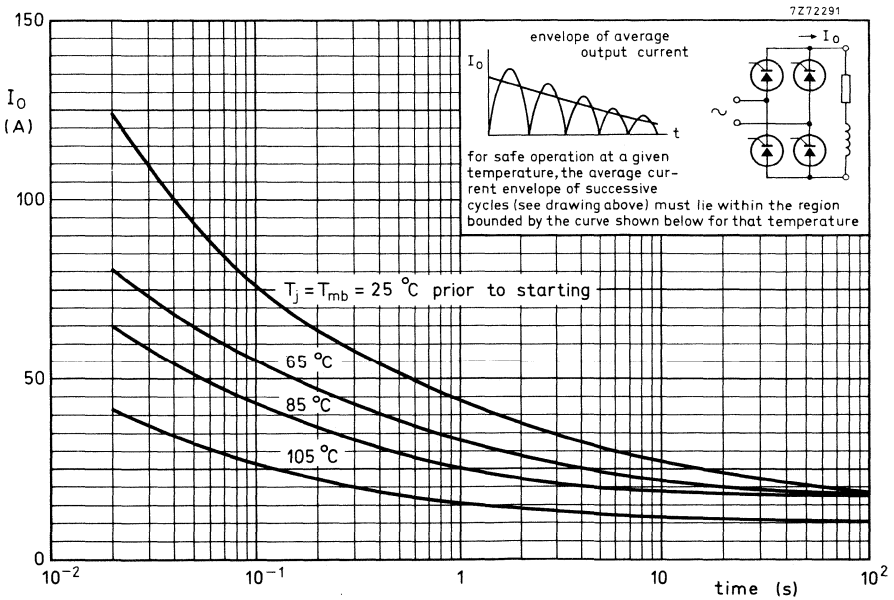
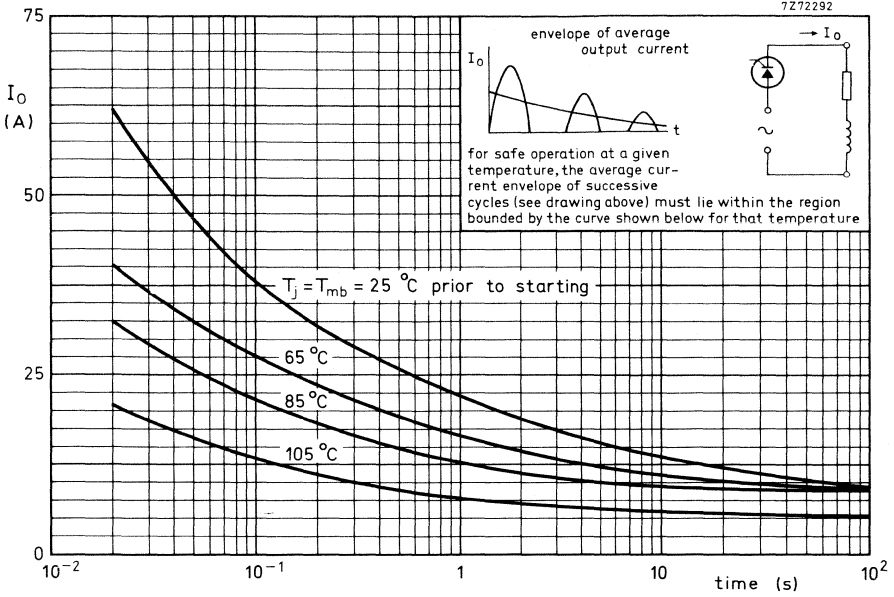


Fig. 10 Limits for starting or inrush currents.

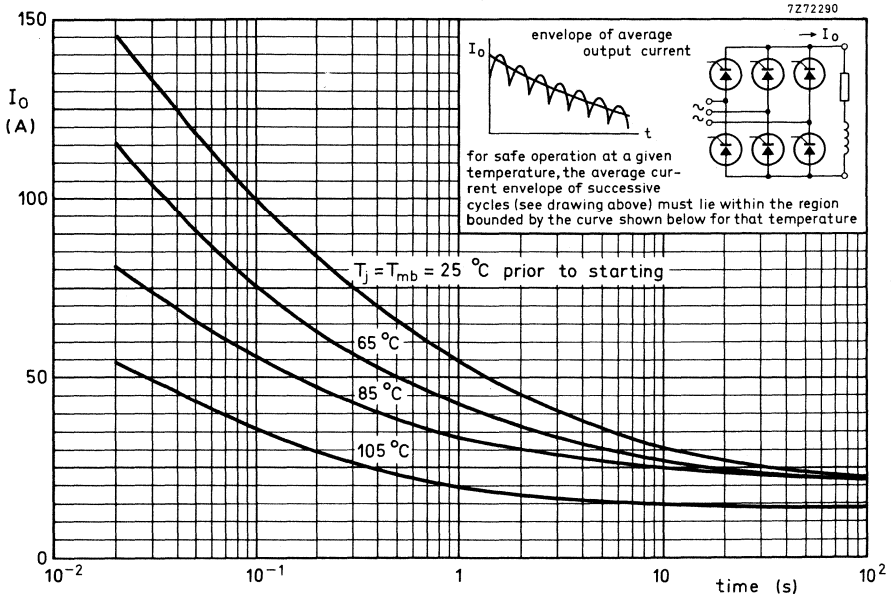


Fig. 11 Limits for starting or inrush currents.

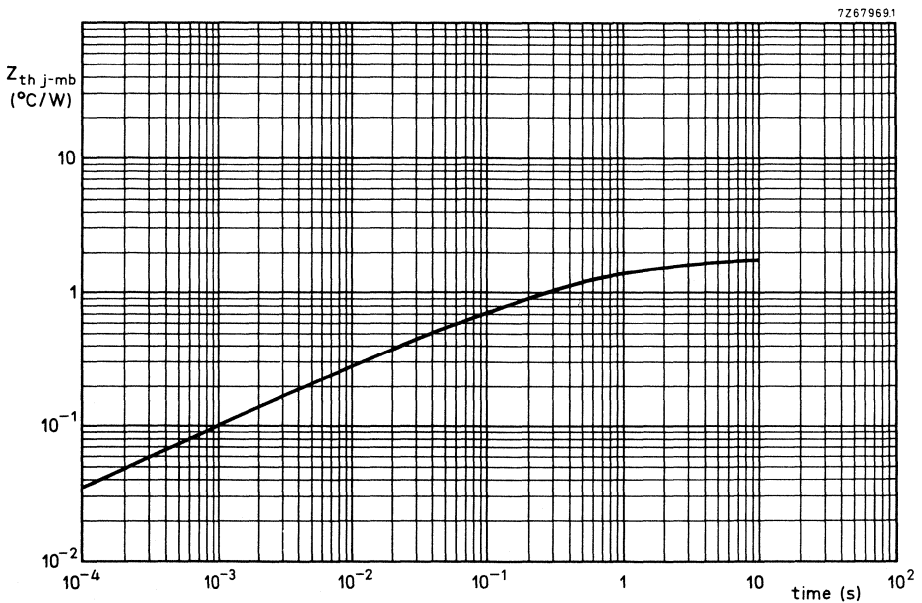


Fig. 12.

THYRISTORS

Also available to BS9341-F083

Silicon thyristors in metal envelopes, intended for use in power control applications in general, and lighting control (in a.c. controller circuit) up to 2,5 kW in particular. A feature of the thyristors is their high surge rating.

The series consists of reverse polarity types (anode to stud) identified by a suffix R: BTW40-400R to 800R.

QUICK REFERENCE DATA

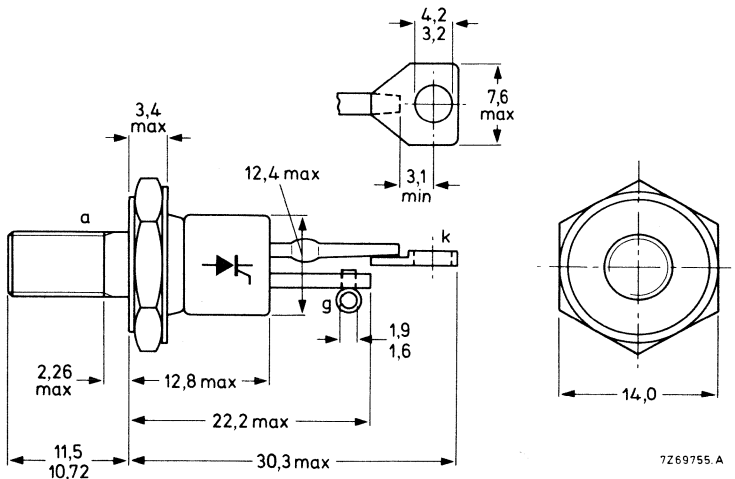
	$V_{DRM}/V_{RRM}$	BTW40-400R	600R	800R	V
Repetitive peak voltages	max.	400	600	800	
Average on-state current	$I_T(AV)$	max.		20	A
R.M.S. on-state current	$I_T(RMS)$	max.		32	A
Non-repetitive peak on-state current	$I_{TSM}$	max.		400	A

MECHANICAL DATA

Dimensions in mm

Fig. 1 TO-48: with metric M6 stud ( $\phi 6$  mm); e.g. BTW40-400R.

Types with  $\frac{1}{4}$  in x 28 UNF stud ( $\phi 6,35$  mm) are available on request. These are indicated by the suffix U: e.g. BTW40-400RU.



7269755.A

Net mass: 14 g  
 Diameter of clearance hole: max. 6,5 mm  
 Accessories supplied on request: 56264A  
 (mica washer, insulating ring, soldering tag)

Torque on nut: min. 1,7 Nm (17 kg cm)  
 max. 3,5 Nm (35 kg cm)  
 Supplied with the device:  
 1 nut, 1 lock washer  
 Nut dimensions across the flats;  
 M6: 10 mm  
 $\frac{1}{4}$  in x 28 UNF: 11,1 mm

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

### Anode to cathode

		BTW40-400R	600R	800R
Non-repetitive peak voltages ( $t \leq 10$ ms)	$V_{DSM}/V_{RSM}$	max. 400	600	800 V
Repetitive peak voltages	$V_{DRM}/V_{RRM}$	max. 400	600	800 V
Crest working voltages	$V_{DWM}/V_{RWM}$	max. 300	400	600 V *
Average on-state current (averaged over any 20 ms period) up to $T_{mb} = 85$ °C	$I_{T(AV)}$	max.	20 A	
R.M.S. on-state current	$I_{T(RMS)}$	max.	32 A	
Repetitive peak on-state current	$I_{TRM}$	max.	200 A	
Non-repetitive peak on-state current; $t = 10$ ms; half sine-wave; $T_j = 125$ °C prior to surge; with reapplied $V_{RWMmax}$	$I_{TSM}$	max.	400 A	
$I^2 t$ for fusing ( $t = 10$ ms)	$I^2 t$	max.	800 A <sup>2</sup> s	
Rate of rise of on-state current after triggering with $I_G = 400$ mA to $I_T = 60$ A; $dI_G/dt = 0,4$ A/ $\mu$ s	$dI_T/dt$	max.	100 A/ $\mu$ s	

### Gate to cathode

Reverse peak voltage	$V_{RGM}$	max.	10 V	
Average power dissipation (averaged over any 20 ms period)	$P_{G(AV)}$	max.	1 W	
Peak power dissipation	$P_{GM}$	max.	5 W	

### Temperatures

Storage temperature	$T_{stg}$	-55 to + 125 °C		
Junction temperature	$T_j$	max.	125 °C	

### THERMAL RESISTANCE

From junction to mounting base	$R_{th\ j-mb}$	=	1 °C/W	
From mounting base to heatsink with heatsink compound	$R_{th\ mb-h}$	=	0,2 °C/W	
Transient thermal impedance ( $t = 1$ ms)	$Z_{th\ j-mb}$	=	0,1 °C/W	

### OPERATING NOTE

The terminals should neither be bent not twisted; they should be soldered into the circuit so that there is no strain on them.

During soldering the heat conduction to the junction should be kept to a minimum.

\* To ensure thermal stability:  $R_{th\ j-a} < 6,5$  °C/W (d.c. blocking) or  $< 13$  °C/W (a.c.). For smaller heatsinks  $T_{j\ max}$  should be derated. For a.c. see Fig. 3.

**CHARACTERISTICS**

**Anode to cathode**

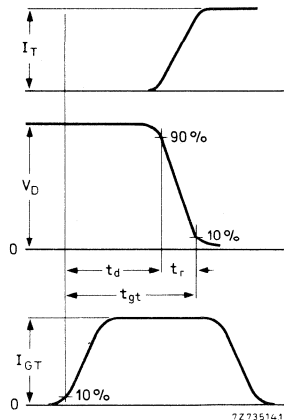
On-state voltage $I_T = 50 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$	$V_T$	<	2,1 V *
Rate of rise of off-state voltage that will not trigger any device; exponential method; $V_D = 2/3 V_{DRMmax}; T_j = 125 \text{ }^\circ\text{C}$	$dV_D/dt$	<	100 V/ $\mu\text{s}$
Reverse current $V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$	$I_R$	<	3 mA
Off-state current $V_D = V_{DWMmax}; T_j = 125 \text{ }^\circ\text{C}$	$I_D$	<	3 mA
Latching current; $T_j = 25 \text{ }^\circ\text{C}$	$I_L$	<	150 mA
Holding current; $T_j = 25 \text{ }^\circ\text{C}$	$I_H$	<	75 mA

**Gate to cathode**

Voltage that will trigger all devices $V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$	$V_{GT}$	>	1,5 V
Voltage that will not trigger any device $V_D = V_{DRMmax}; T_j = 125 \text{ }^\circ\text{C}$	$V_{GD}$	<	200 mV
Current that will trigger all devices $V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$	$I_{GT}$	>	75 mA

**Switching characteristics**

Gate-controlled turn-on time ( $t_{gt} = t_d + t_r$ ) when switched from $V_D = V_{DWMmax}$ to $I_T = 100 \text{ A}; I_{GT} = 400 \text{ mA}; dI_G/dt = 1 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$	$t_{gt}$	<	1 $\mu\text{s}$
	$t_r$	<	0,5 $\mu\text{s}$



Gate-controlled turn-on time definition

\*Measured under pulse conditions to avoid excessive dissipation.

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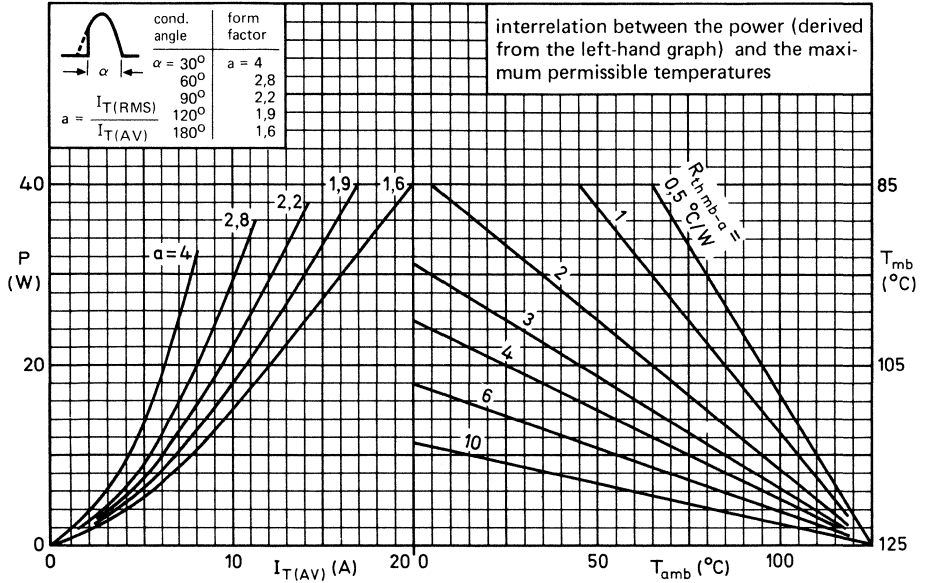


Fig. 2.

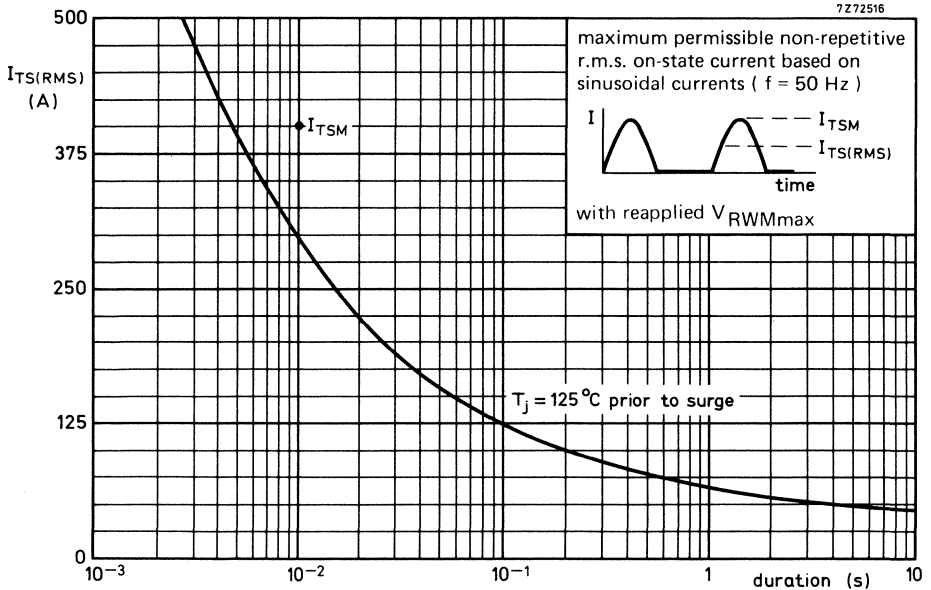


Fig. 3.

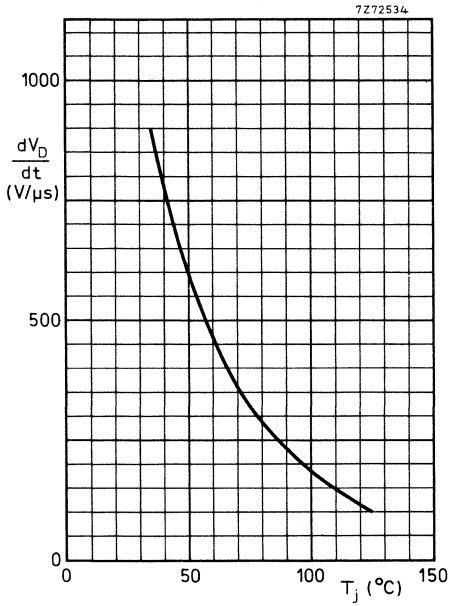


Fig. 4 Maximum rate of rise of off-state voltage that will not trigger any device (exponential method) as a function of  $T_j$ .

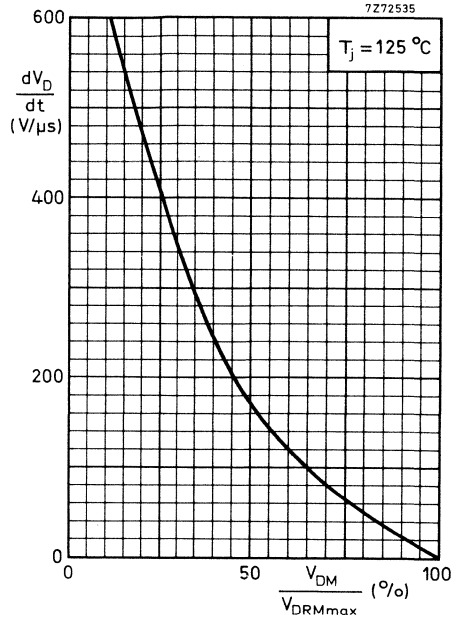


Fig. 5 Maximum rate of rise of off-state voltage that will not trigger any device (exponential method) as a function of applied voltage.

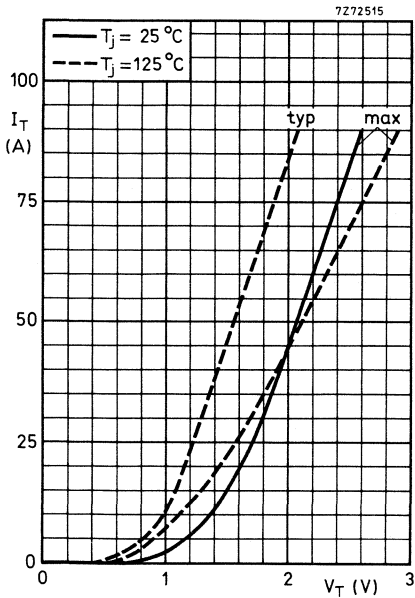


Fig. 6.

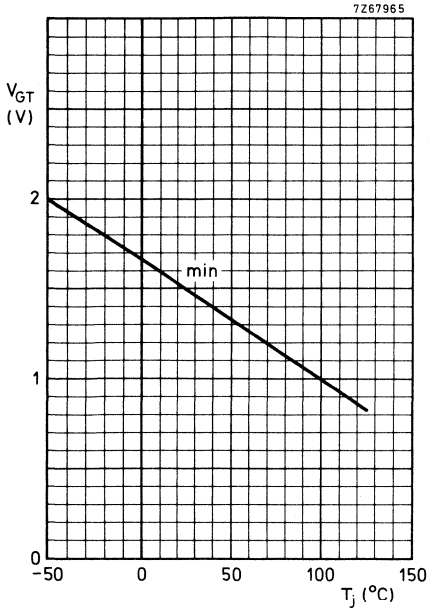


Fig. 7 Minimum gate voltage that will trigger all devices as a function of  $T_j$ .

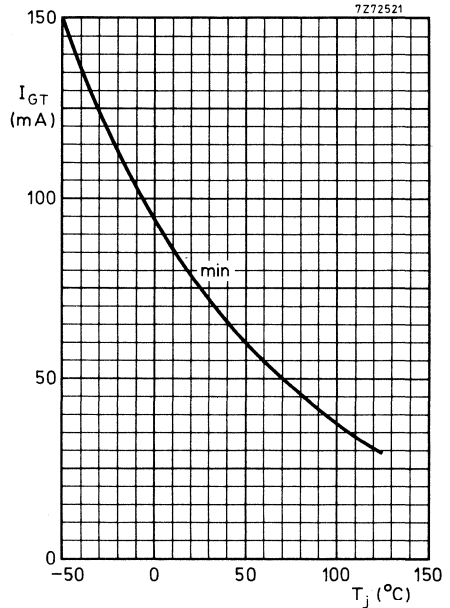


Fig. 8 Minimum gate current that will trigger all devices as a function of  $T_j$ .

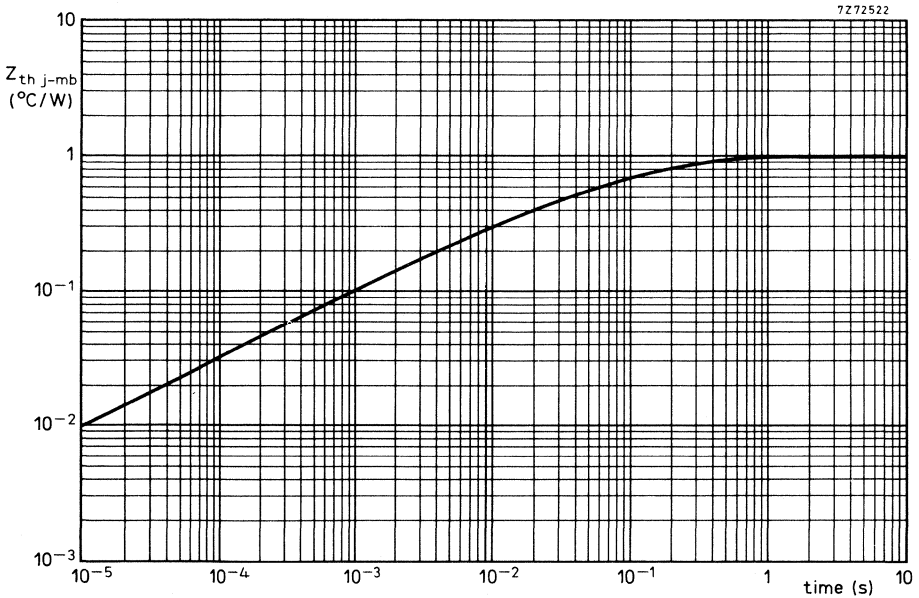


Fig. 9.



## THYRISTORS

Also available to BS9341-F084

Silicon thyristors in metal envelopes with high  $dV_D/dt$  capabilities. They are intended for use in power control circuits and switching systems where high transients can occur (e.g. phase control in three-phase systems).

The series consists of reverse polarity types (anode to stud) identified by a suffix R: BTW42-600R to 1200R.

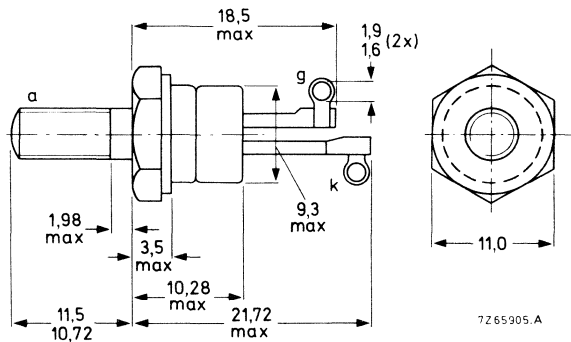
### QUICK REFERENCE DATA

	$V_{DRM}/V_{RRM}$	BTW42-600R	800R	1000R	1200R
		max.	600	800	1000
Repetitive peak voltages					
Average on-state current		$I_T(AV)$		max.	10 A
R.M.S. on-state current		$I_T(RMS)$		max.	16 A
Non-repetitive peak on-state current		$I_{TSM}$		max.	150 A
Rate of rise of off-state voltage that will not trigger any device		$dV_D/dt$		<	200 V/ $\mu$ s
On request (see ordering note on page 2)		$dV_D/dt$		<	1000 V/ $\mu$ s

### MECHANICAL DATA

Dimensions in mm

Fig. 1 TO-64: with metric M5 stud ( $\phi$ 5 mm); e.g. BTW42-600R.



Net mass: 7 g

Diameter of clearance hole: max. 5,2 mm

Accessories supplied on request:

56295 (PTFE bush, 2 mica washers, plain washer, tag)

56262A (mica washer, insulating ring, plain washer)

Torque on nut: min. 0,9 Nm  
(9 kg cm)

max. 1,7 Nm  
(17 kg cm)

Supplied with device: 1 nut, 1 lock washer

Nut dimensions across the flats; M5: 8,0 mm

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

### Anode to cathode

		BTW42-600R	800R	1000R	1200R
Non-repetitive peak voltages ( $t \leq 10$ ms)	$V_{DSM}/V_{RSM}$	max. 600	800	1000	1200 V
Repetitive peak voltages	$V_{DRM}/V_{RRM}$	max. 600	800	1000	1200 V
Crest working voltages	$V_{DWM}/V_{RWM}$	max. 400	600	700	800 V *
Average on-state current (averaged over any 20 ms period) up to $T_{mb} = 85$ °C		$I_T(AV)$	max.	10	A
R.M.S. on-state current		$I_T(RMS)$	max.	16	A
Repetitive peak on-state current		$I_{TRM}$	max.	75	A
Non-repetitive peak on-state current; $t = 10$ ms; half sine-wave; $T_j = 125$ °C prior to surge; with reapplied $V_{RWMmax}$		$I_{TSM}$	max.	150	A
$I^2t$ for fusing ( $t = 10$ ms)		$I^2t$	max.	112	A <sup>2</sup> s
Rate of rise of on-state current after triggering with $I_G = 250$ mA to $I_T = 25$ A; $dI_G/dt = 0,25$ A/ $\mu$ s		$dI_T/dt$	max.	50	A/ $\mu$ s

### Gate to cathode

Average power dissipation (averaged over any 20 ms period)	$P_G(AV)$	max.	0,5	W
Peak power dissipation	$P_{GM}$	max.	5	W

### Temperatures

Storage temperature	$T_{stg}$	-55 to +125	°C
Junction temperature	$T_j$	max.	125 °C

### THERMAL RESISTANCE

From junction to mounting base	$R_{th j-mb}$	=	1,8	°C/W
From mounting base to heatsink with heatsink compound	$R_{th mb-h}$	=	0,5	°C/W
From junction to ambient in free air	$R_{th j-a}$	=	45	°C/W
Transient thermal impedance ( $t = 1$ ms)	$Z_{th j-mb}$	=	0,1	°C/W

### OPERATING NOTE

The terminals should neither be bent nor twisted; they should be soldered into the circuit so that there is no strain on them.

During soldering the heat conduction to the junction should be kept to a minimum.

### ORDERING NOTE

Types with  $dV_D/dt$  of 1000 V/ $\mu$ s are available on request. Add suffix C to the type number when ordering; e.g. BTW42-600RC.

\* To ensure thermal stability:  $R_{th j-a} < 4$  °C/W (d.c. blocking) or  $< 8$  °C/W (a.c.). For smaller heatsinks  $T_{jmax}$  should be derated. For a.c. see Fig. 3.

**CHARACTERISTICS**

**Anode to cathode**

On-state voltage $I_T = 20 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$	$V_T$	<	2 V *
Rate of rise of off-state voltage that will not trigger any device; exponential method; $V_D = 2/3 V_{DRMmax}; T_j = 125 \text{ }^\circ\text{C}$	$dV_D/dt$	<	200 V/ $\mu\text{s}$
Reverse current $V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$	$I_R$	<	3 mA
Off-state current $V_D = V_{DWMmax}; T_j = 125 \text{ }^\circ\text{C}$	$I_D$	<	3 mA
Latching current; $T_j = 25 \text{ }^\circ\text{C}$	$I_L$	<	150 mA
Holding current; $T_j = 25 \text{ }^\circ\text{C}$	$I_H$	<	75 mA

**Gate to cathode**

Voltage that will trigger all devices $V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$	$V_{GT}$	>	1,5 V
Voltage that will not trigger any device $V_D = V_{DRMmax}; T_j = 125 \text{ }^\circ\text{C}$	$V_{GD}$	<	200 mV
Current that will trigger all devices $V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$	$I_{GT}$	>	50 mA

**Switching characteristics**

Gate-controlled turn-on time ( $t_{gt} = t_d + t_r$ ) when switched from $V_D = 800 \text{ V}$ to $I_T = 25 \text{ A}$ ; $I_{GT} = 250 \text{ mA}; dI_G/dt = 0,25 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$	$t_{gt}$ $t_r$	< typ.	1,5 $\mu\text{s}$ 0,2 $\mu\text{s}$
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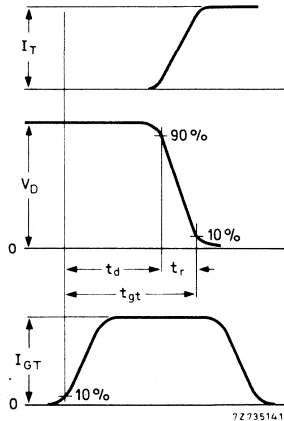


Fig. 2 Gate-controlled turn-on time definitions.

\* Measured under pulse conditions to avoid excessive dissipation.

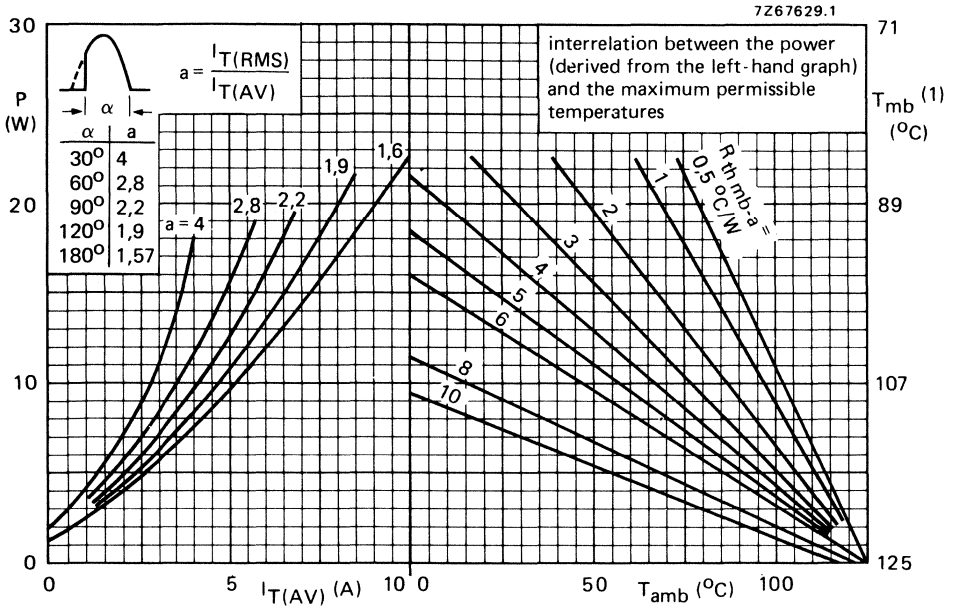


Fig. 3 (1)  $T_{mb}$ -scale is for comparison purposes only and is correct only for  $R_{th\ mb-a} \leq 6\ ^\circ C/W$ .

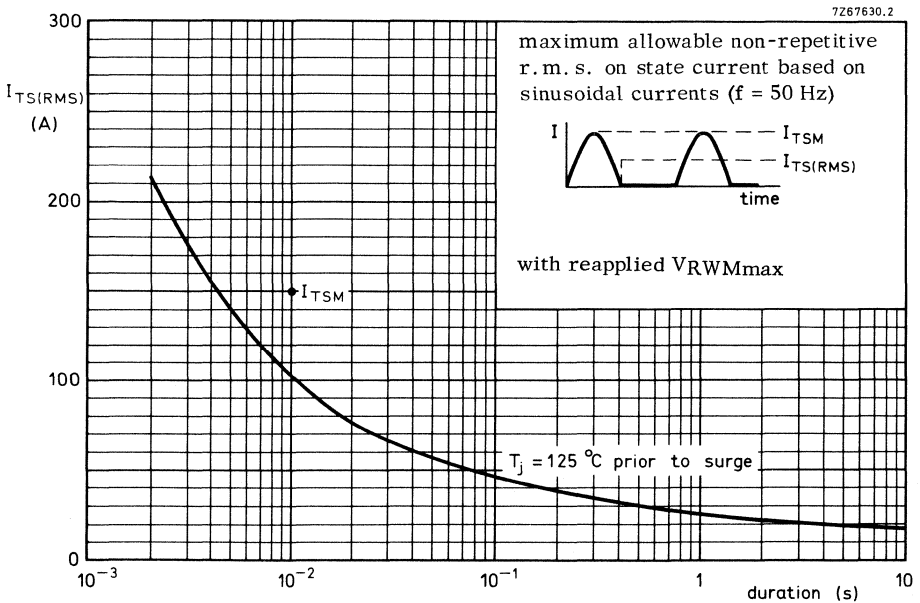


Fig. 4.

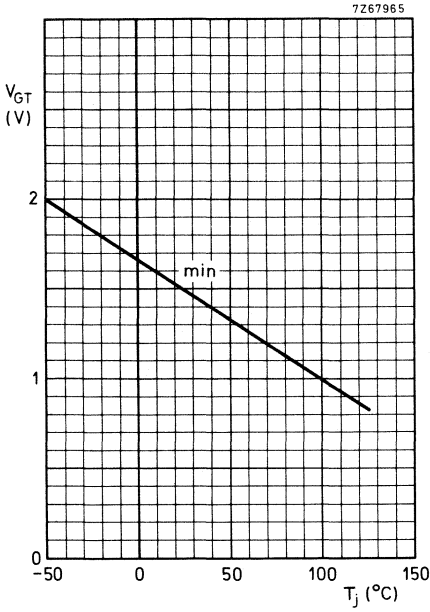


Fig. 5 Minimum gate voltage that will trigger all devices as a function of  $T_j$ .

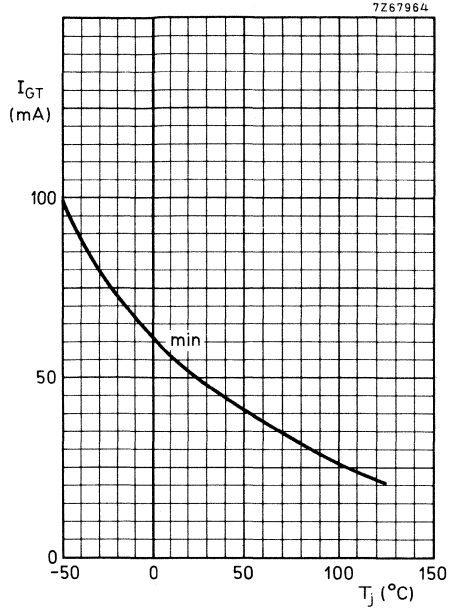


Fig. 6 Minimum gate current that will trigger all devices as a function of  $T_j$ .

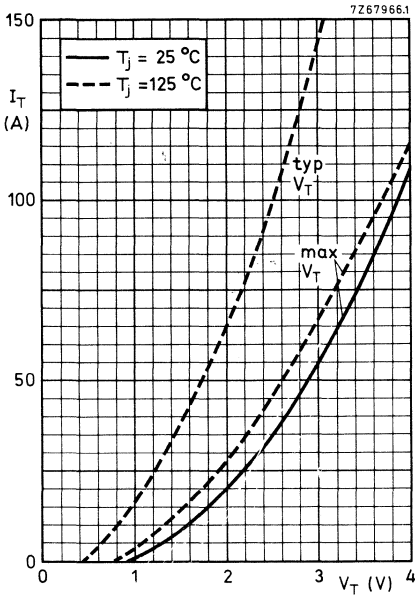


Fig. 7.

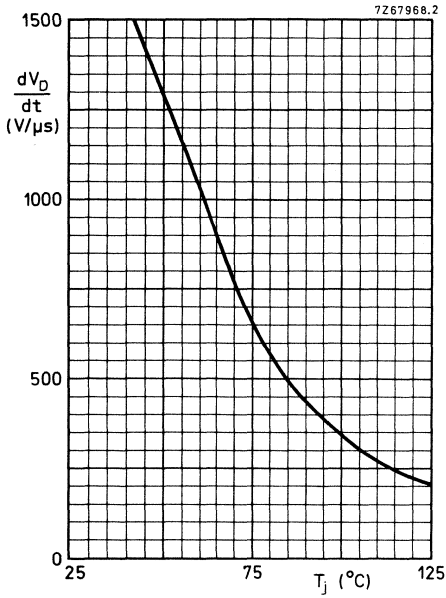


Fig. 8 Maximum rate of rise of off-state voltage that will not trigger any device (exponential method) as a function of  $T_j$ .

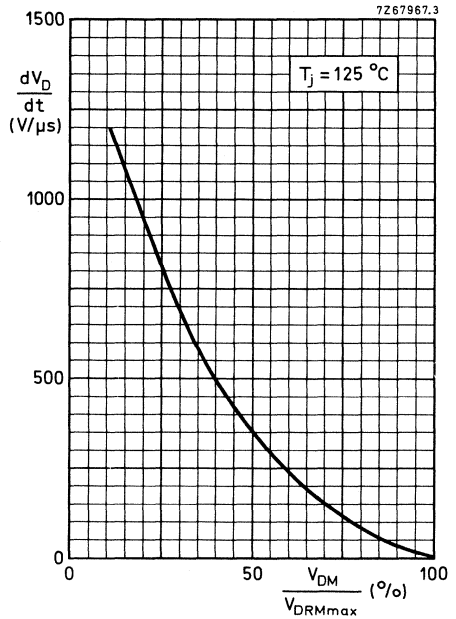


Fig. 9 Maximum rate of rise of off-state voltage that will not trigger any device (exponential method) as a function of applied voltage.

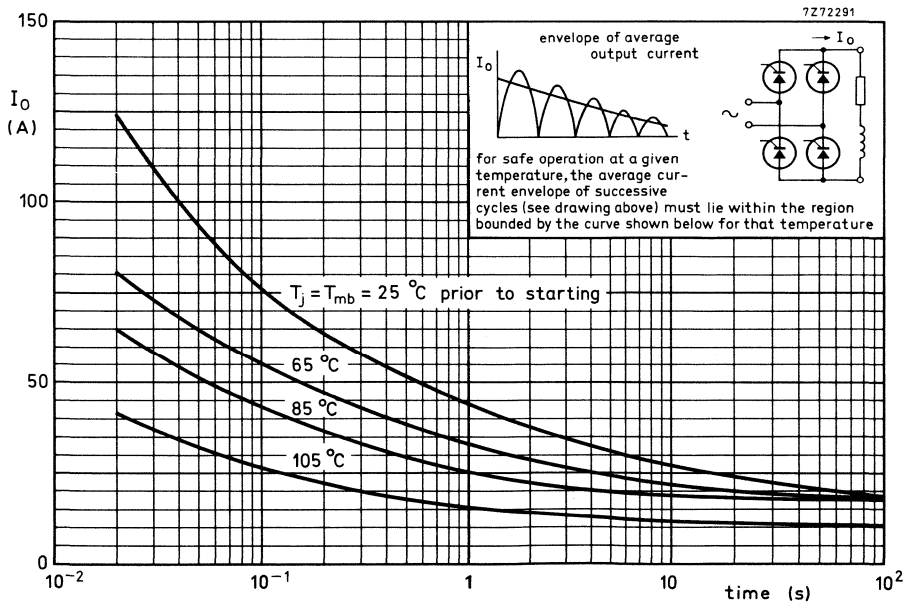
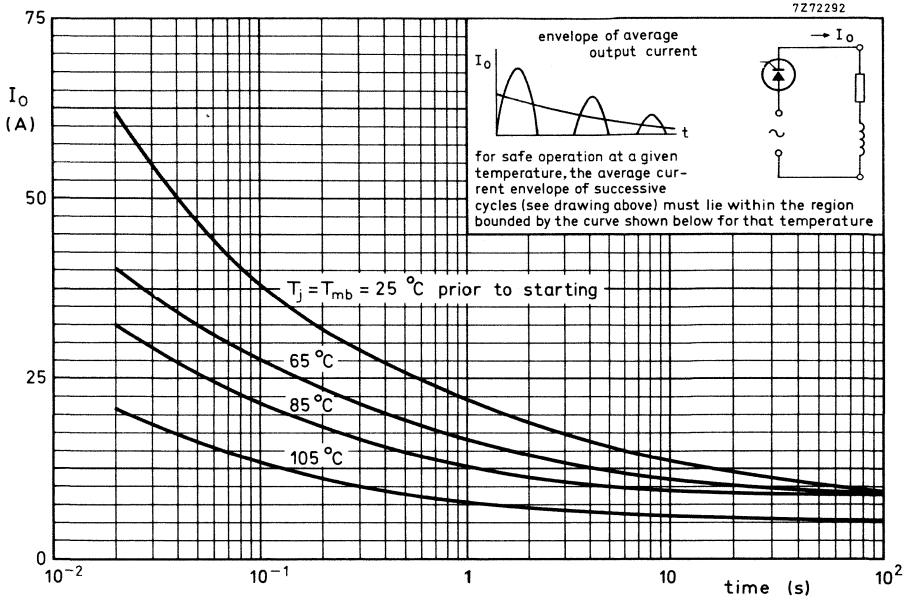


Fig. 10 Limits for starting or inrush currents.

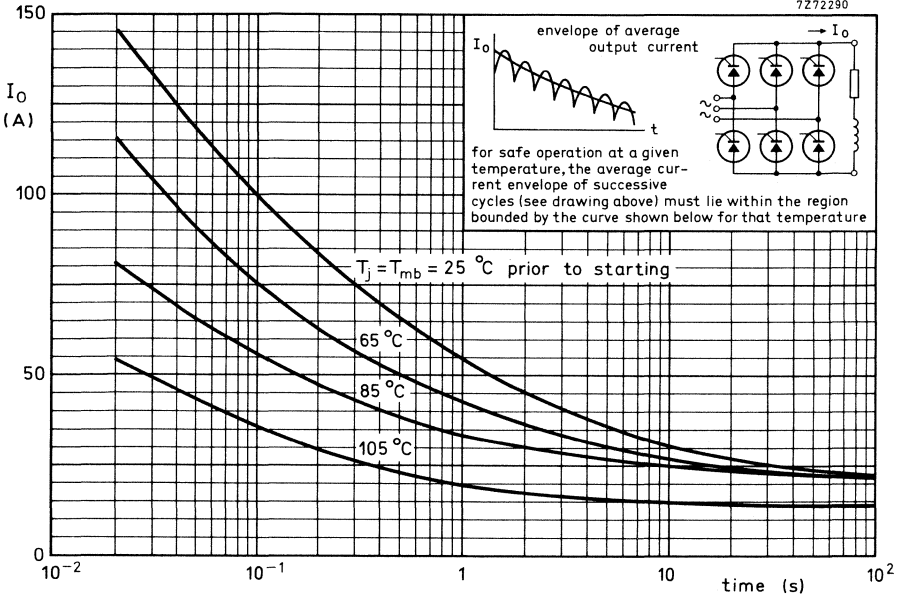


Fig. 11 Limits for starting or inrush currents.

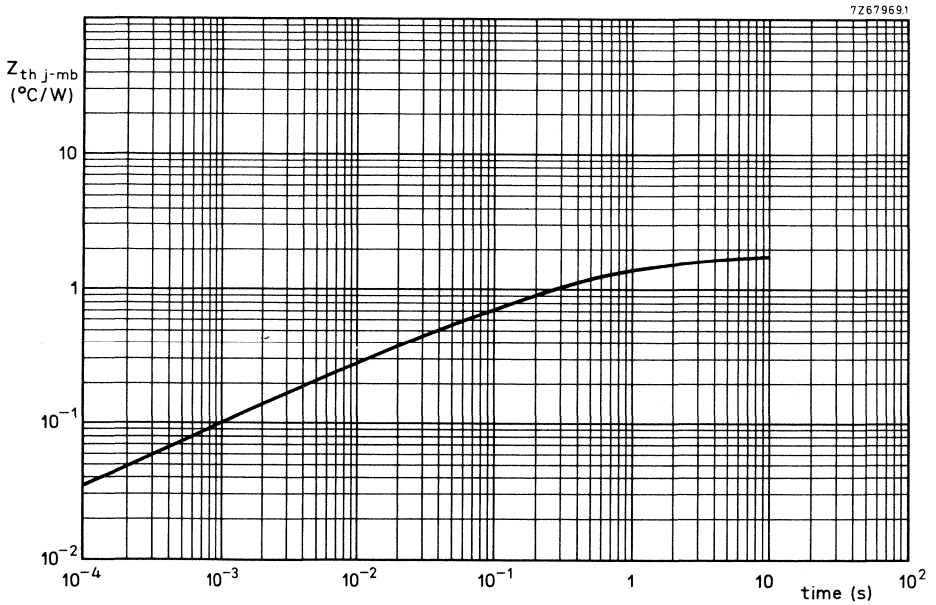


Fig. 12.



THYRISTORS



Silicon thyristors in metal envelopes, intended for power control applications.

The series consists of reverse polarity types (anode to stud) identified by a suffix R: BTW45-400R to 1200R.

QUICK REFERENCE DATA

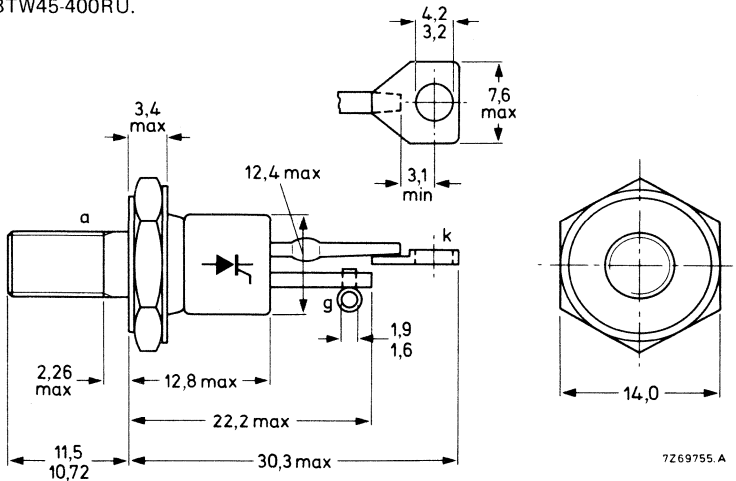
	BTW45-400R	600R	800R	1000R	1200R
Repetitive peak voltages $V_{DRM} = V_{RRM}$	max. 400	600	800	1000	1200
Average on-state current			$I_T(AV)$	max. 16	A
R.M.S. on-state current			$I_T(RMS)$	max. 25	A
Non-repetitive peak on-state current			$I_{TSM}$	max. 300	A
Rate of rise of off-state voltage that will not trigger any device			$dV_D/dt$	< 200	V/ $\mu$ s
On request (see ordering note on page 3)			$dV_D/dt$	< 1000	V/ $\mu$ s

MECHANICAL DATA

Dimensions in mm

Fig. 1 TO-48: with metric M6 stud ( $\phi$  6 mm); e.g. BTW45-400R.

Types with  $\frac{1}{4}$  in x 28 UNF stud ( $\phi$  6,35 mm) are available on request. These are indicated by the suffix U: BTW45-400RU.



Net mass: 14 g  
 Diameter of clearance hole: max. 6,5 mm  
 Accessories supplied on request: 56264A  
 (mica washer, insulating ring, soldering tag)

Torque on nut: min. 1,7 Nm (17 kg cm)  
 max. 3,5 Nm (35 kg cm)

Supplied with the device:  
 1 nut, 1 lock washer  
 Nut dimensions across the flats:  
 M6: 10 mm  
 $\frac{1}{4}$  in x 28 UNF: 11,1 mm

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

### Anode to cathode

		BTW45-400R	600R	800R	1000R	1200R
Non-repetitive peak voltages ( $t \leq 10$ ms)	$V_{DSM}/V_{RSM}$	max. 400	600	800	1000	1200 V
Repetitive peak voltages	$V_{DRM}/V_{RRM}$	max. 400	600	800	1000	1200 V
Crest working voltages	$V_{DWM}/V_{RWM}$	max. 300	400	600	700	800 V*
Average on-state current (averaged over any 20 ms period) up to $T_{mb} = 85$ °C				$I_{T(AV)}$	max.	16 A
R.M.S. on-state current				$I_{T(RMS)}$	max.	25 A
Repetitive peak on-state current				$I_{TRM}$	max.	200 A
Non-repetitive peak on-state current; $t = 10$ ms; half sine-wave; $T_j = 125$ °C prior to surge; with reapplied $V_{RWM}$ max				$I_{TSM}$	max.	300 A
$I^2 t$ for fusing ( $t = 10$ ms)				$I^2 t$	max.	450 A <sup>2</sup> s
Rate of rise of on-state current after triggering with $I_G = 400$ mA to $I_T = 60$ A; $dI_G/dt = 0,4$ A/ $\mu$ s				$dI_T/dt$	max.	100 A/ $\mu$ s

### Gate to cathode

Reverse peak voltage		$V_{RGM}$	max.	10 V
Average power dissipation (averaged over any 20 ms period)		$P_{G(AV)}$	max.	1 W
Peak power dissipation		$P_{GM}$	max.	5 W

### Temperatures

Storage temperature		$T_{stg}$	-55 to + 125 °C
Junction temperature		$T_j$	max. 125 °C

### THERMAL RESISTANCE

From junction to mounting base		$R_{th\ j-mb}$	=	1,33 °C/W
From mounting base to heatsink; with heatsink compound		$R_{th\ mb-h}$	=	0,2 °C/W
Transient thermal impedance ( $t = 1$ ms)		$Z_{th\ j-mb}$	=	0,1 °C/W

### OPERATING NOTE

The terminals should neither be bent nor twisted; they should be soldered into the circuit so that there is no strain on them.

During soldering the heat conduction to the junction should be kept to a minimum.

\* To ensure thermal stability:  $R_{th\ j-a} < 6,5$  °C/W (d.c. blocking) or  $< 13$  °C/W (a.c.). For smaller heatsinks  $T_{j\ max}$  should be derated. For a.c. see Fig. 2.

**CHARACTERISTICS**

**Anode to cathode**

On-state voltage

$$I_T = 50 \text{ A}; T_j = 25 \text{ }^\circ\text{C} \quad V_T < 2 \text{ V}^*$$

Rate of rise of off-state voltage that will not trigger any device; exponential method;  $V_D = 2/3 V_{DRM \text{ max}}$ ;  $T_j = 125 \text{ }^\circ\text{C}$

$$dV_D/dt < 200 \text{ V}/\mu\text{s}$$

Reverse current

$$V_R = V_{RWM \text{ max}}; T_j = 125 \text{ }^\circ\text{C} \quad I_R < 3 \text{ mA}$$

Off-state current

$$V_D = V_{DWM \text{ max}}; T_j = 125 \text{ }^\circ\text{C} \quad I_D < 3 \text{ mA}$$

Latching current;  $T_j = 25 \text{ }^\circ\text{C}$

$$I_L < 150 \text{ mA}$$

Holding current;  $T_j = 25 \text{ }^\circ\text{C}$

$$I_H < 75 \text{ mA}$$

**Gate to cathode**

Voltage that will trigger all devices

$$V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C} \quad V_{GT} > 1,5 \text{ V}$$

Voltage that will not trigger any device

$$V_D = V_{DRM \text{ max}}; T_j = 125 \text{ }^\circ\text{C} \quad V_{GD} < 200 \text{ mV}$$

Current that will trigger all devices

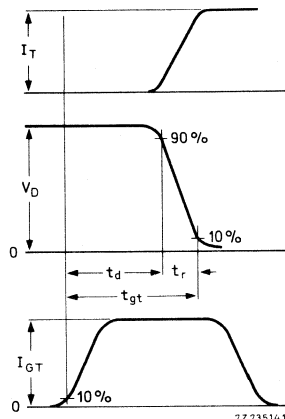
$$V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C} \quad I_{GT} > 75 \text{ mA}$$

**Switching characteristics**

Gate-controlled turn-on time ( $t_{gt} = t_d + t_r$ ) when switched from  $V_D = V_{DWM \text{ max}}$  to  $I_T = 100 \text{ A}$ ;  $I_{GT} = 400 \text{ mA}$ ;  $dI_G/dt = 1 \text{ A}/\mu\text{s}$ ;  $T_j = 25 \text{ }^\circ\text{C}$

$$t_{gt} < 1 \mu\text{s}$$

$$t_r < 0,5 \mu\text{s}$$



Gate-controlled turn-on time definition.

**ORDERING NOTE**

Types with  $dV_D/dt$  of  $1000 \text{ V}/\mu\text{s}$  are available on request. Add suffix C to the type number when ordering; e.g. BTW45-400RC.

\*Measured under pulse conditions to avoid excessive dissipation.

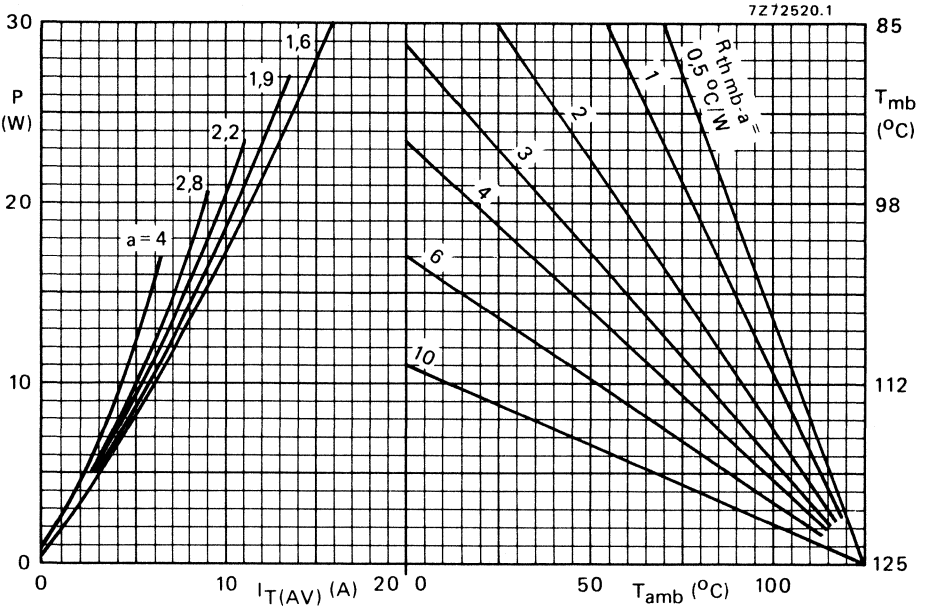


Fig. 2.

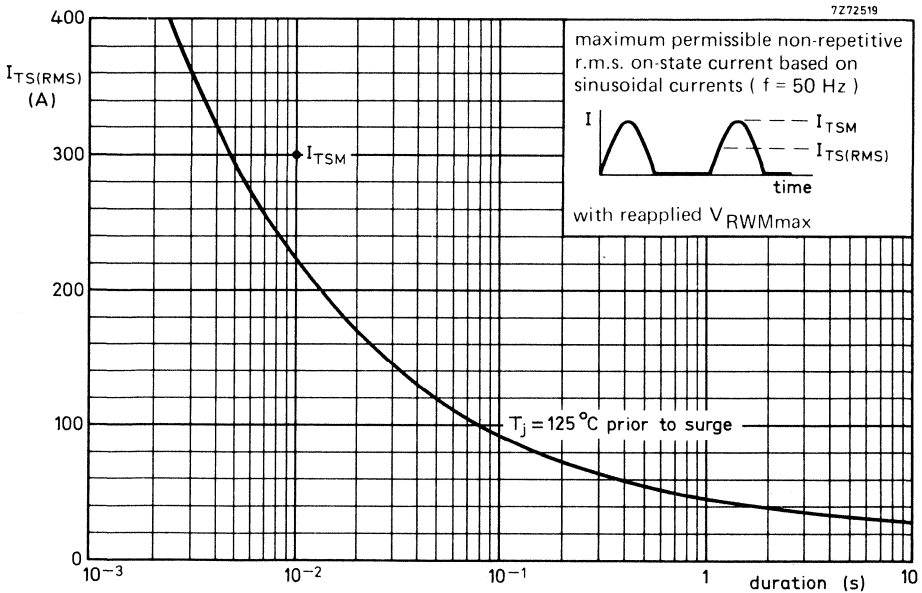


Fig. 3.

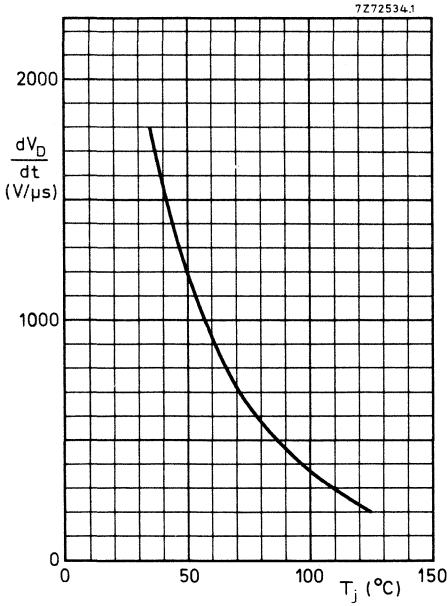


Fig. 4 Maximum rate of rise of off-state voltage that will not trigger any device (exponential method) as a function of  $T_j$ .

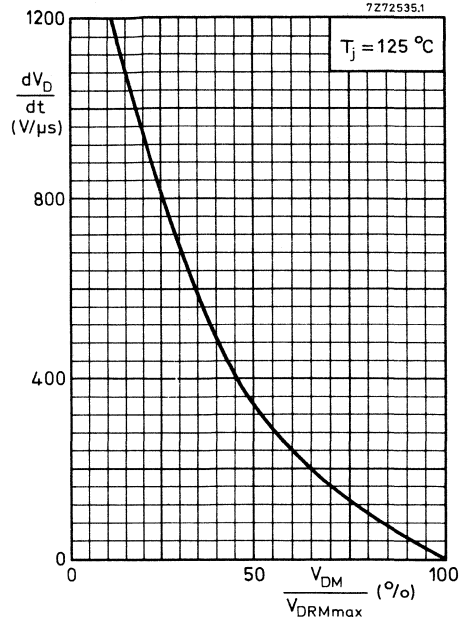


Fig. 5 Maximum rate of rise of off-state voltage that will not trigger any device (exponential method) as a function of applied voltage.

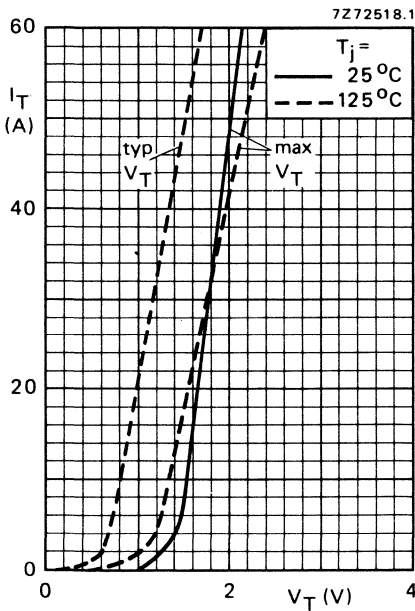


Fig. 6.

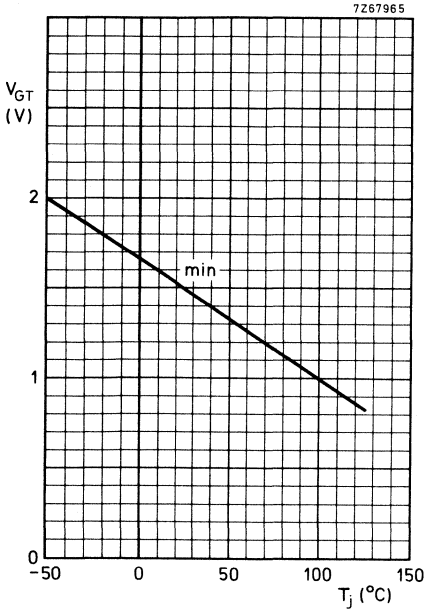


Fig. 7 Minimum gate voltage that will trigger all devices as a function of  $T_j$ .

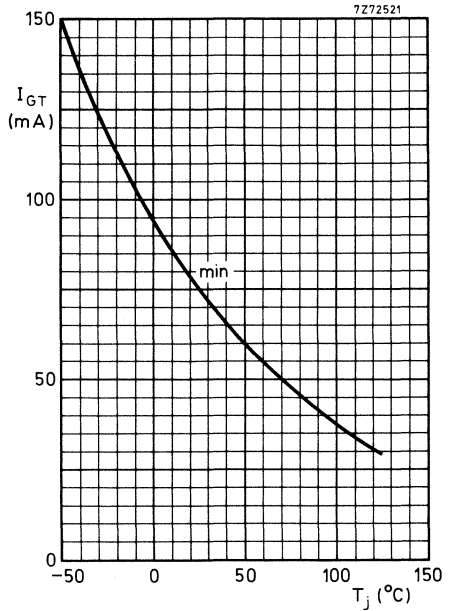


Fig. 8 Minimum gate current that will trigger all devices as a function of  $T_j$ .

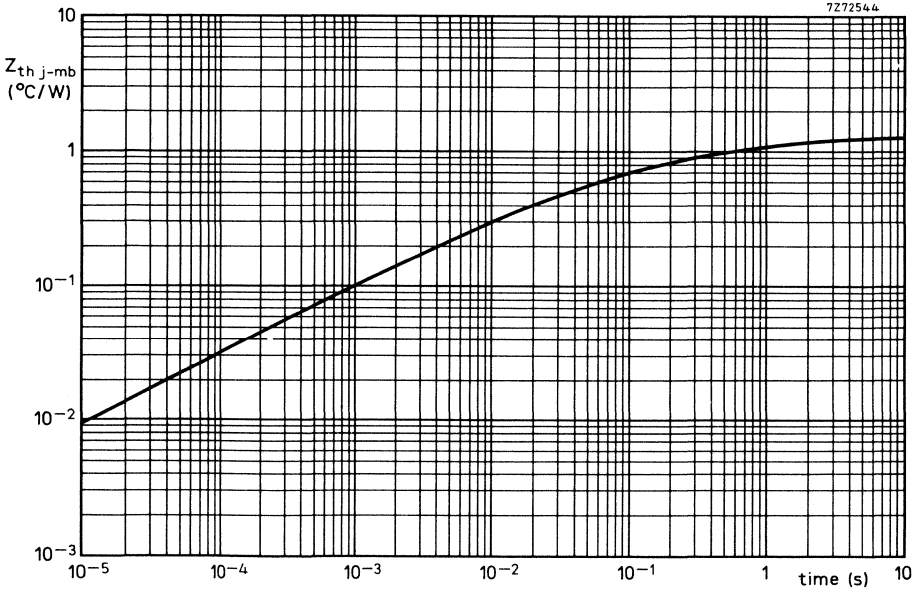


Fig. 9.

THYRISTORS

Silicon thyristors in metal envelopes, primarily intended for three-phase mains operation. The series consists of reverse polarity types (anode to stud) identified by a suffix R: BTW47-800R to 1600R.

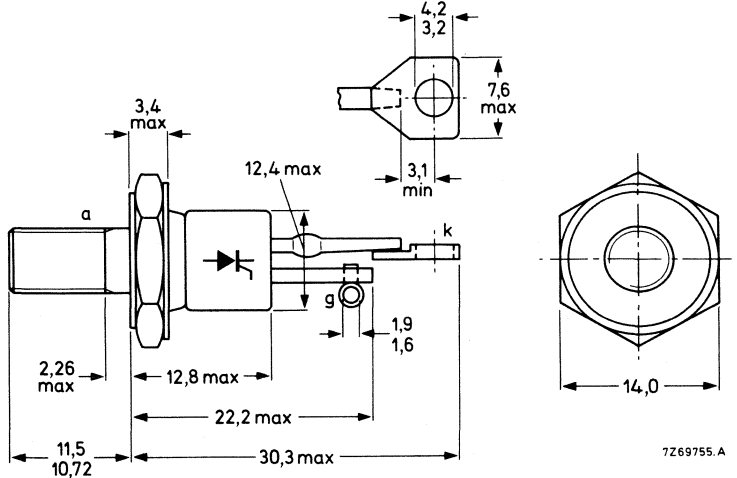
QUICK REFERENCE DATA

	BTW47-800R	1000R	1200R	1400R	1600R
Repetitive peak voltages $V_{DRM} = V_{RRM}$	max. 800	1000	1200	1400	1600 V
Average on-state current			$I_{T(AV)}$ max.		16 A
R.M.S. on-state current			$I_{T(RMS)}$ max.		25 A
Non-repetitive peak on-state current			$I_{TSM}$ max.		300 A
Rate of rise of off-state voltage that will not trigger any device			$dV_D/dt$ <		300 V/ $\mu$ s
On request (see ordering note on page 4)			$dV_D/dt$ <		1000 V/ $\mu$ s

MECHANICAL DATA

Dimensions in mm

Fig. 1 TO-48: with metric M6 stud ( $\phi$  6 mm); e.g. BTW47-800R.  
Types with  $\frac{1}{4}$  in x 28UNF stud ( $\phi$  6,35 mm) are available on request. These are indicated by the suffix U: BTW47-800RU.



Net mass: 14 g  
Diameter of clearance hole: max. 6,5 mm  
Accessories supplied on request: 56264A  
(mica washer, insulating ring, soldering tag)

Torque on nut: min. 1,7 Nm (17 kg cm)  
max. 3,5 Nm (35 kg cm)

Supplied with the device:  
1 nut, 1 lock washer  
Nut dimensions across the flats:  
M6: 10 mm  
 $\frac{1}{4}$  in x 28 UNF: 11,1 mm

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

### Anode to cathode

		BTW47-800R	1000R	1200R	1400R	1600R
Non-repetitive peak voltages ( $t \leq 10$ ms)	$V_{DSM}/V_{RSM}$	max. 800	1000	1200	1400	1600 V
Repetitive peak voltages	$V_{DRM}/V_{RRM}$	max. 800	1000	1200	1400	1600 V
Crest working voltages	$V_{DWM}/V_{RWM}$	max. 600	700	800	800	800 V*

Average on-state current (averaged over any 20 ms period) up to  $T_{mb} = 77$  °C  
at  $T_{mb} = 85$  °C

$I_T(AV)$	max.	16 A
$I_T(AV)$	max.	14 A

R.M.S. on-state current

$I_T(RMS)$	max.	25 A
------------	------	------

Repetitive peak on-state current

$I_{TRM}$	max.	150 A
-----------	------	-------

Non-repetitive peak on-state current;  $t = 10$  ms;  
half sine-wave;  $T_j = 125$  °C prior to surge;  
with reapplied  $V_{RWMmax}$

$I_{TSM}$	max.	300 A
-----------	------	-------

$I^2 t$  for fusing ( $t = 10$  ms)

$I^2 t$	max.	450 A <sup>2</sup> s
---------	------	----------------------

Rate of rise of on-state current after triggering  
with  $I_G = 500$  mA to  $I_T = 50$  A

$dI_T/dt$	max.	200 A/ $\mu$ s
-----------	------	----------------

Rate of change of commutation current

see Fig. 9

### Gate to cathode

Reverse peak voltage

$V_{RGM}$	max.	10 V
-----------	------	------

Average power dissipation (averaged over any 20 ms period)

$P_G(AV)$	max.	1 W
-----------	------	-----

Peak power dissipation

$P_{GM}$	max.	5 W
----------	------	-----

### Temperatures

Storage temperature

$T_{stg}$	-55 to +125 °C
-----------	----------------

Junction temperature

$T_j$	max. 125 °C
-------	-------------

### THERMAL RESISTANCE

From junction to mounting base

$R_{th j-mb}$	=	1 °C/W
---------------	---	--------

From mounting base to heatsink

$R_{th mb-h}$	=	0,2 °C/W
---------------	---	----------

Transient thermal impedance ( $t = 1$  ms)

$Z_{th j-mb}$	=	0,06 °C/W
---------------	---	-----------

\* To ensure thermal stability:  $R_{th j-a} < 1,5$  °C/W (d.c. blocking) or  $< 3$  °C/W (a.c.). For smaller heat-sinks  $T_{j max}$  should be derated. For a.c. see Fig. 3.



**CHARACTERISTICS**

**Anode to cathode**

On-state voltage $I_T = 50 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$	$V_T < 3 \text{ V}^*$
Rate of rise of off-state voltage that will not trigger any device; exponential method; $V_D = 2/3 V_{DRMmax}; T_j = 125 \text{ }^\circ\text{C}$	$dV_D/dt < 300 \text{ V}/\mu\text{s}$
Reverse current $V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$	$I_R < 5 \text{ mA}$
Off-state current $V_D = V_{DWMmax}; T_j = 125 \text{ }^\circ\text{C}$	$I_D < 5 \text{ mA}$
Latching current; $T_j = 25 \text{ }^\circ\text{C}$	$I_L < 200 \text{ mA}$
Holding current; $T_j = 25 \text{ }^\circ\text{C}$	$I_H < 200 \text{ mA}$

**Gate to cathode**

Voltage that will trigger all devices $V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$	$V_{GT} > 3,5 \text{ V}$
Voltage that will not trigger any device $V_D = V_{DRMmax}; T_j = 125 \text{ }^\circ\text{C}$	$V_{GD} < 200 \text{ mV}$
Current that will trigger all devices $V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$	$I_{GT} > 100 \text{ mA}$

**Switching characteristics**

Gate-controlled turn-on time ( $t_{gt} = t_d + t_r$ ) when switched from $V_D = V_{DWMmax}$ to $I_T = 10 \text{ A}; I_{GT} = 150 \text{ mA}; dI_G/dt = 1 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$	$t_{gt}$ typ. $2 \mu\text{s}$
	$t_r$ typ. $1,2 \mu\text{s}$

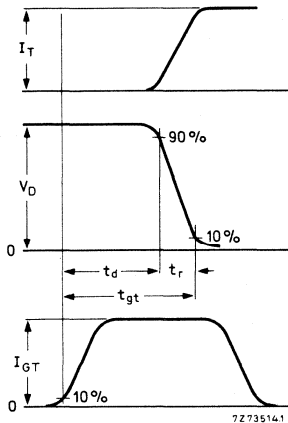


Fig. 2 Gate-controlled turn-on time definitions.

\* Measured under pulse conditions to avoid excessive dissipation.

**OPERATING NOTES**

1. The terminals should neither be bent nor twisted; they should be soldered into the circuit so that there is no strain on them.  
During soldering the heat conduction to the junction should be kept to a minimum.
2. Switching losses in commutation

For applications in which the thyristor is forced to switch from an on-state current  $I_{TRM}$  to a high reverse voltage at a high commutation rate ( $-di_T/dt$ ), consult Fig. 9 (nomogram) to find the increase in total average power. This increase must be added to the loss from the curves in Fig. 3.

**ORDERING NOTE**

Types with  $dV_D/dt$  of 1000 V/ $\mu$ s are available on request. Add suffix C to the type number when ordering; e.g. BTW47-800RC.

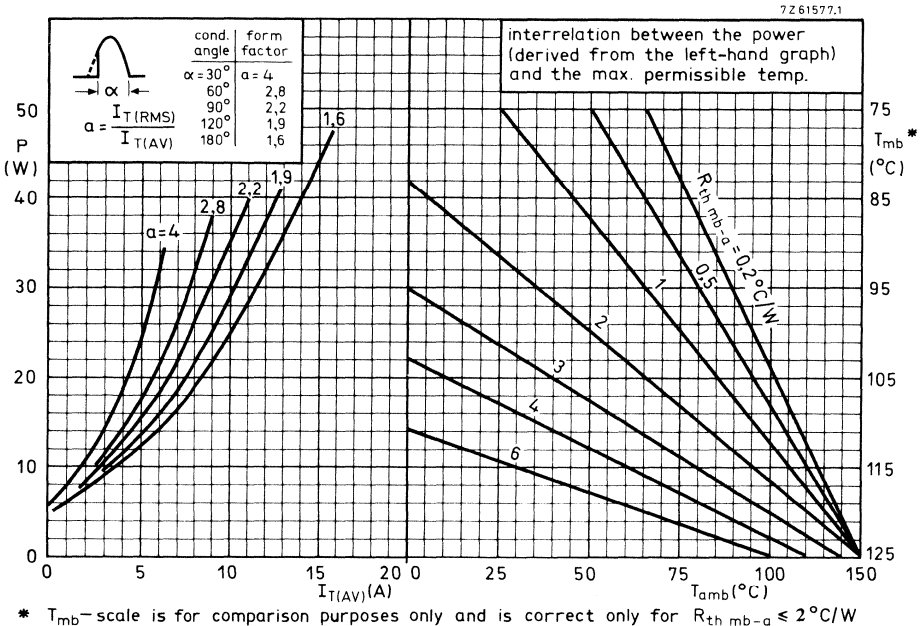


Fig. 3.

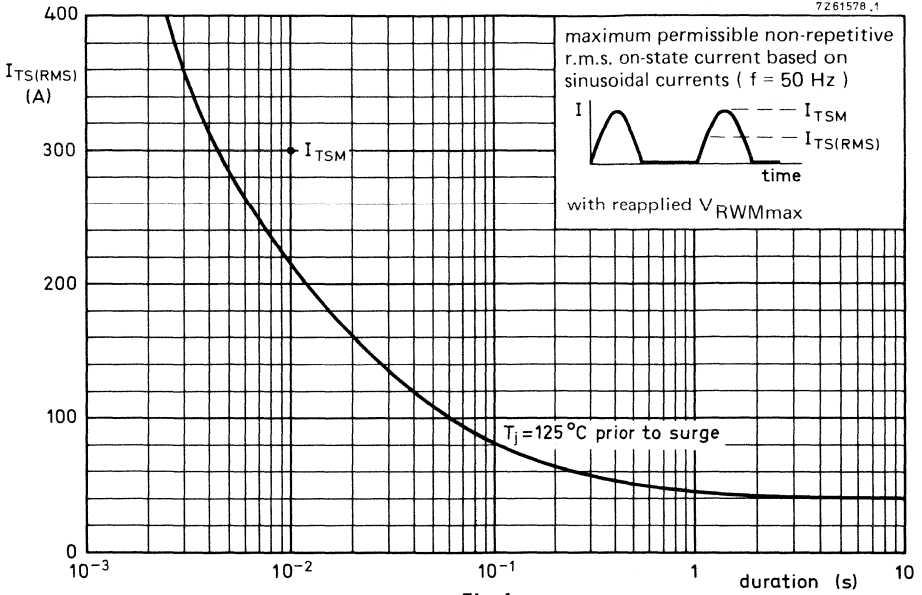


Fig. 4.

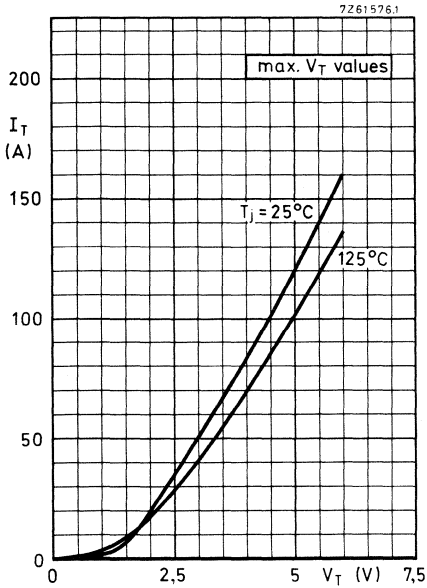


Fig. 5.

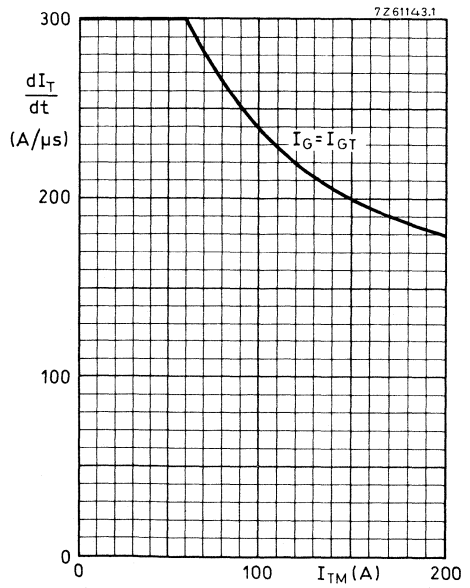


Fig. 6.

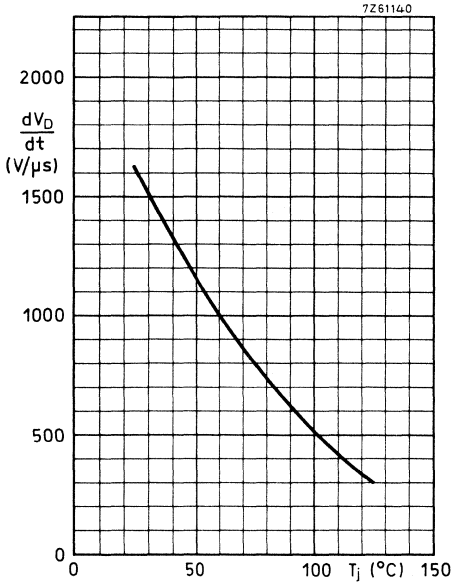


Fig. 7 Maximum rate of rise of off-state voltage that with not trigger any device (exponential method) as a function of  $T_j$ .

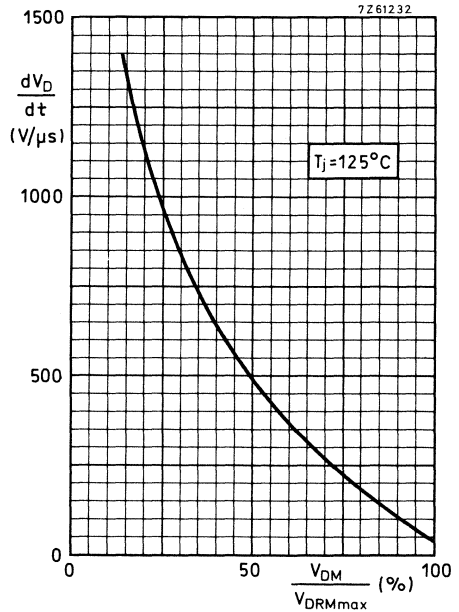


Fig. 8 Maximum rate of rise of off-state voltage that with not trigger any device (exponential method) as a function of applied voltage.

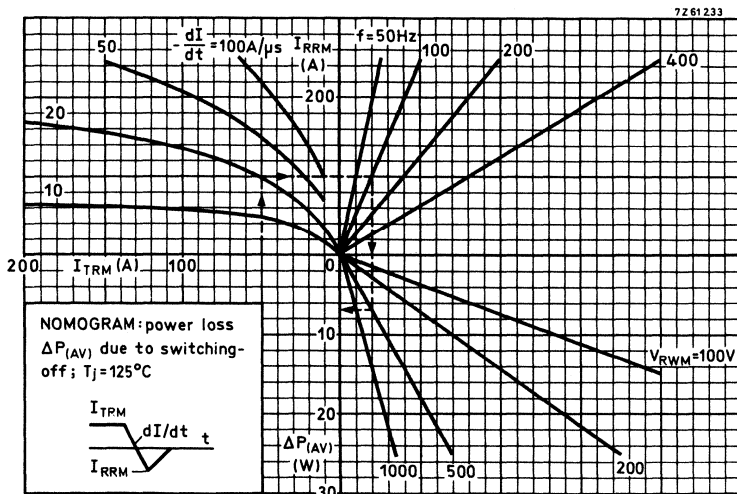


Fig. 9.

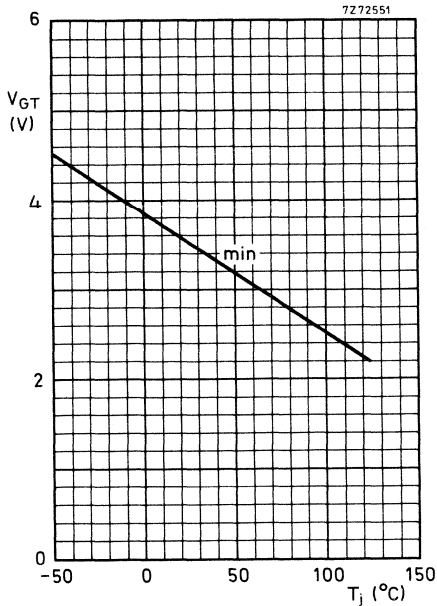


Fig. 10 Minimum gate voltage that will trigger all devices as a function of  $T_j$ .

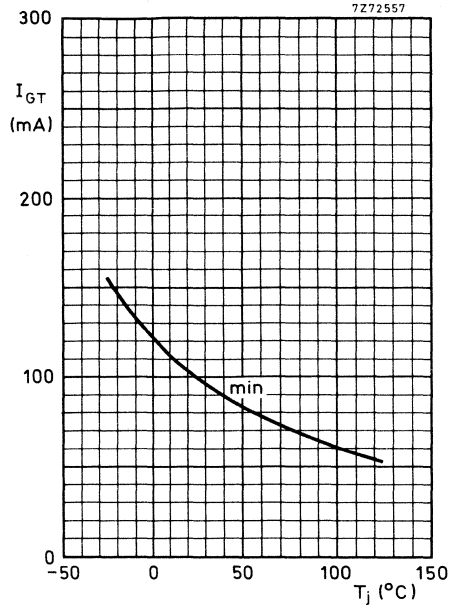


Fig. 11 Minimum gate current that will trigger all devices as a function of  $T_j$ .

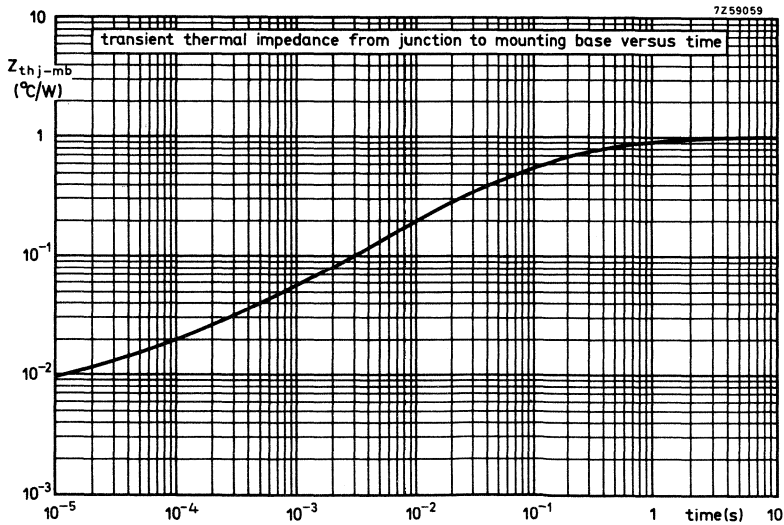


Fig. 12.

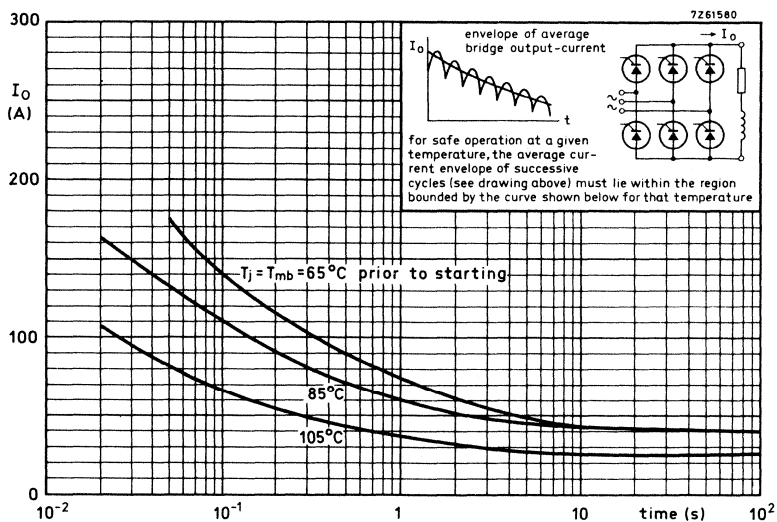
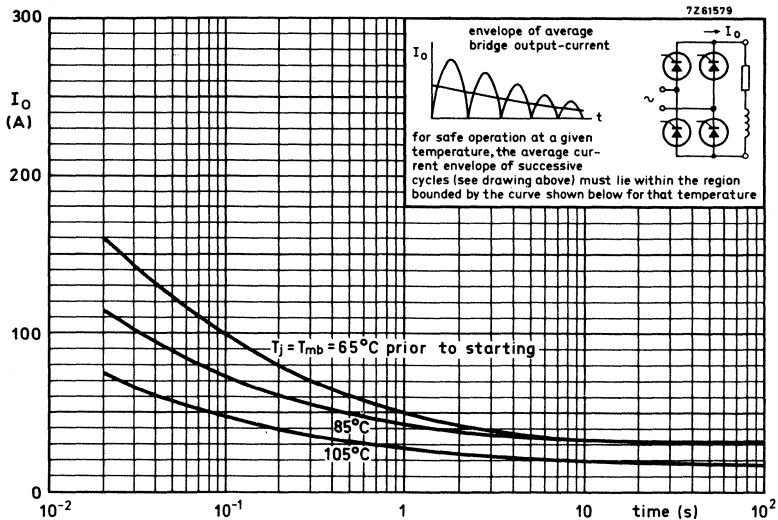


Fig. 13 Limits for starting or inrush currents.

THYRISTORS

Also available to BS9341-F039

Silicon thyristors in metal envelopes, intended for use in general purpose three-phase power control circuits.

The series consists of reverse polarity types (anode to stud) identified by a suffix R: BTW92-800R to 1600R.

QUICK REFERENCE DATA

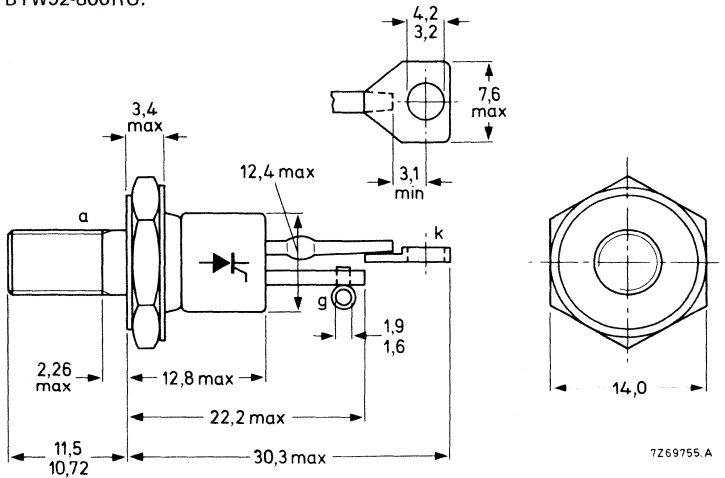
	$V_{DRM}/V_{RRM}$	BTW92-800R   1000R   1200R   1400R   1600R				
		max.	800	1000	1200	1400
Repetitive peak voltages						
Average on-state current			$I_T(AV)$		max.	20 A
R.M.S. on-state current			$I_T(RMS)$		max.	31 A
Non-repetitive peak on-state current			$I_{TSM}$		max.	400 A
Rate of rise of off-state voltage that will not trigger any device			$dV_D/dt$		<	300 V/ $\mu s$
On request (see ordering note on page 4)			$dV_D/dt$		<	1000 V/ $\mu s$

MECHANICAL DATA

Dimensions in mm

Fig. 1 TO-48: with metric M6 stud ( $\phi$  6 mm); e.g. BTW92-800R.

Types with  $\frac{1}{4}$  in x 28 UNF stud ( $\phi$  6,35 mm) are available on request. These are indicated by the suffix U: BTW92-800RU.



Net mass: 14 g  
 Diameter of clearance hole: max. 6,5 mm  
 Accessories supplied on request: 56264A  
 (mica washer, insulating ring, soldering tag)

Torque on nut: min. 1,7 Nm (17 kg cm)  
 max. 3,5 Nm (35 kg cm)

Supplied with the device:  
 1 nut, 1 lock washer  
 Nut dimensions across the flats:  
 M6: 10 mm  
 $\frac{1}{4}$  in x 28 UNF: 11,1 mm

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

### Anode to cathode

		BTW92-800R	1000R	1200R	1400R	1600R
Non-repetitive peak voltages ( $t \leq 10$ ms)	$V_{DSM}/V_{RSM}$	max. 800	1000	1200	1400	1600 V
Repetitive peak voltages	$V_{DRM}/V_{RRM}$	max. 800	1000	1200	1400	1600 V
Crest working voltages	$V_{DWM}/V_{RWM}$	max. 600	700	800	800	800 V *
Average on-state current (averaged over any 20 ms period) up to $T_{mb} = 85$ °C			$I_T(AV)$	max.	20 A	
R.M.S. on-state current			$I_T(RMS)$	max.	31 A	
Repetitive peak on-state current			$I_{TRM}$	max.	200 A	
Non-repetitive peak on-state current; $t = 10$ ms; half sine-wave; $T_j = 125$ °C prior to surge; with reapplied $V_{RWMmax}$			$I_{TSM}$	max.	400 A	
$I^2t$ for fusing ( $t = 10$ ms)			$I^2t$	max.	800 A <sup>2</sup> s	
Rate of rise of on-state current after triggering with $I_G = 500$ mA to $I_T = 60$ A			$dI_T/dt$	max.	300 A/ $\mu$ s	
Rate of change of commutation current			see Fig. 9			
<b>Gate to cathode</b>						
Reverse peak voltage			$V_{RGM}$	max.	10 V	
Average power dissipation (averaged over any 20 ms period)			$P_G(AV)$	max.	1 W	
Peak power dissipation			$P_{GM}$	max.	5 W	
<b>Temperatures</b>						
Storage temperature			$T_{stg}$	-55 to + 125 °C		
Junction temperature			$T_j$	max.	125 °C	

### THERMAL RESISTANCE

From junction to mounting base	$R_{th\ j-mb}$	=	1 °C/W
From mounting base to heatsink	$R_{th\ mb-h}$	=	0,2 °C/W
Transient thermal impedance ( $t = 1$ ms)	$Z_{th\ j-mb}$	=	0,06 °C/W

\* To ensure thermal stability:  $R_{th\ j-a} < 1,5$  °C/W (d.c. blocking) or  $< 3$  °C/W (a.c.). For smaller heatsinks  $T_{j\ max}$  should be derated. For a.c. see Fig. 3.



**CHARACTERISTICS**

**Anode to cathode**

On-state voltage $I_T = 50 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$	$V_T$	<	2,3 V *
Rate of rise of off-state voltage that will not trigger any device; exponential method; $V_D = 2/3 V_{DRMmax}; T_j = 125 \text{ }^\circ\text{C}$	$dV_D/dt$	<	300 V/ $\mu\text{s}$
Reverse current $V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$	$I_R$	<	5 mA
Off-state current $V_D = V_{DWMmax}; T_j = 125 \text{ }^\circ\text{C}$	$I_D$	<	5 mA
Latching current; $T_j = 25 \text{ }^\circ\text{C}$	$I_L$	<	200 mA
Holding current; $T_j = 25 \text{ }^\circ\text{C}$	$I_H$	<	200 mA

**Gate to cathode**

Voltage that will trigger all devices $V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$	$V_{GT}$	>	3,5 V
Voltage that will not trigger any device $V_D = V_{DRMmax}; T_j = 125 \text{ }^\circ\text{C}$	$V_{GD}$	<	200 mV
Current that will trigger all devices $V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$	$I_{GT}$	>	100 mA

**Switching characteristics**

Gate-controlled turn-on time ( $t_{gt} = t_d + t_r$ ) when switched from $V_D = V_{DWMmax}$ to $I_T = 10 \text{ A}; I_{GT} = 150 \text{ mA}; dI_G/dt = 1 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$	$t_{gt}$	typ.	2 $\mu\text{s}$
	$t_r$	typ.	1,2 $\mu\text{s}$

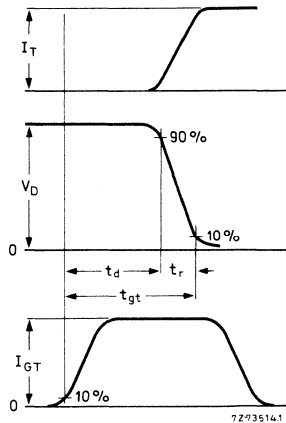


Fig. 2 Gate-controlled turn-on time definitions.

\* Measured under pulse conditions to avoid excessive dissipation.

## OPERATING NOTES

1. The terminals should neither be bent nor twisted; they should be soldered into the circuit so that there is no strain on them.

During soldering the heat conduction to the junction should be kept to a minimum.

2. Switching losses in commutation.

For applications in which the thyristor is forced to switch from an on-state current  $I_{TRM}$  to a high reverse voltage at a high commutation rate ( $-dI_T/dt$ ), consult Fig. 9 (nomogram) to find the increase in total average power. This increase must be added to the loss from the curves in Fig. 3.

## ORDERING NOTE

Types with  $dV_D/dt$  of 1000 V/ $\mu$ s are available on request. Add suffix C to the type number when ordering; e.g. BTW92-800RC.

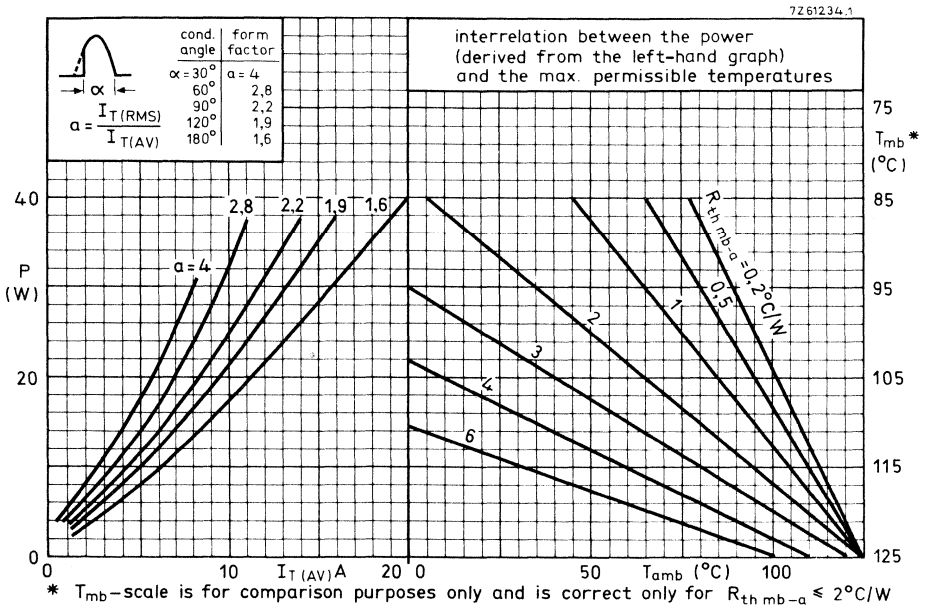


Fig. 3.

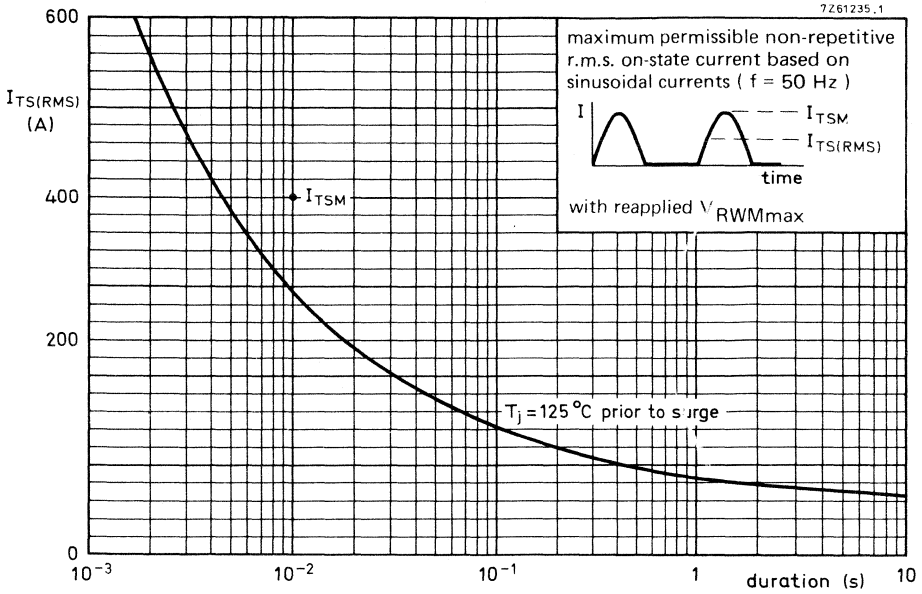


Fig. 4.

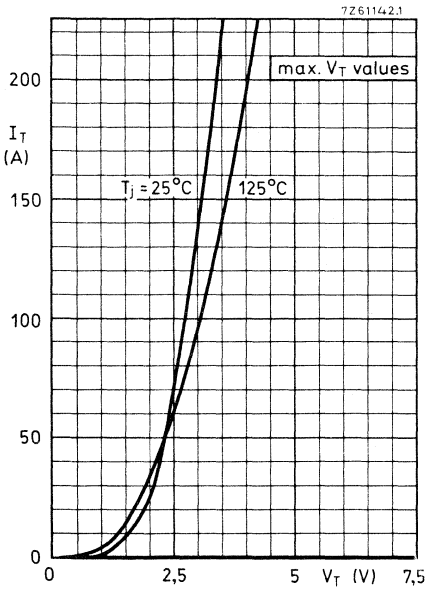


Fig. 5.

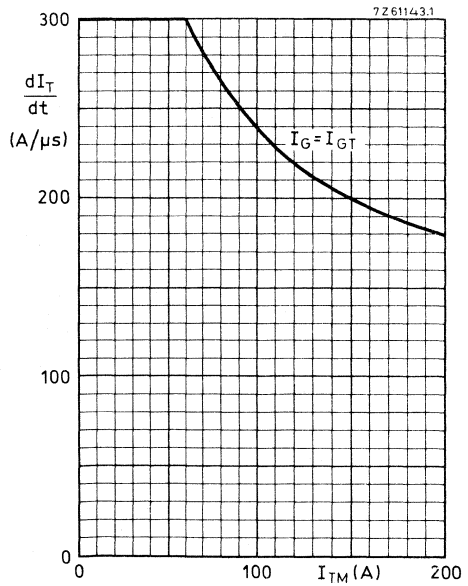


Fig. 6.

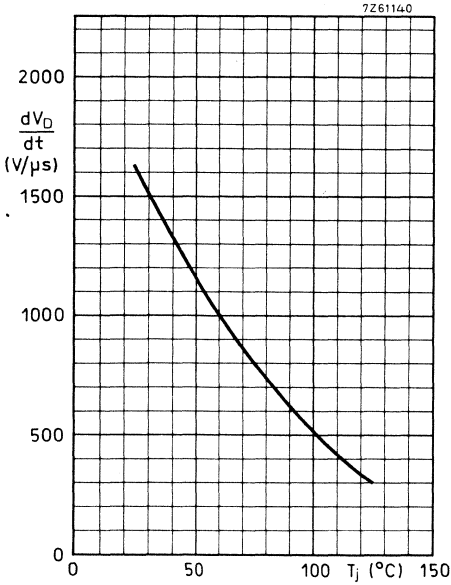


Fig. 7 Maximum rate of rise of off-state voltage that will not trigger any device (exponential method) as a function of  $T_j$ .

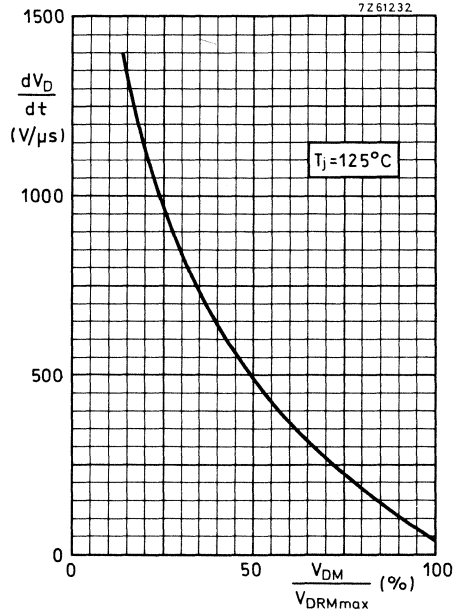


Fig. 8 Maximum rate of rise of off-state voltage that will not trigger any device (exponential method) as a function of applied voltage.

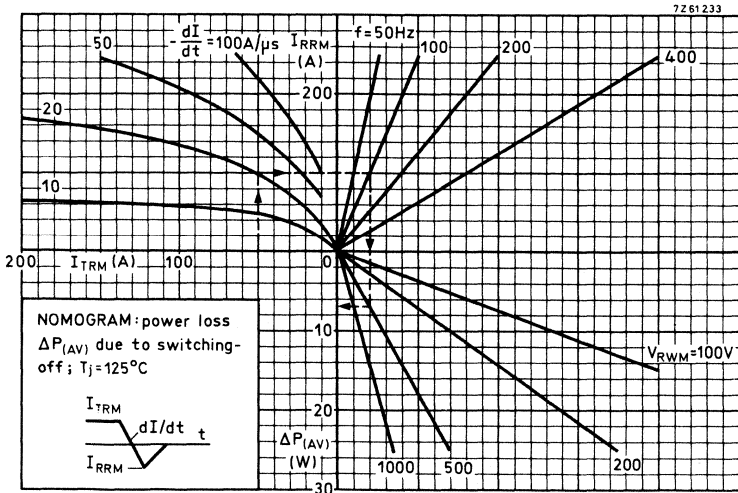


Fig. 9.

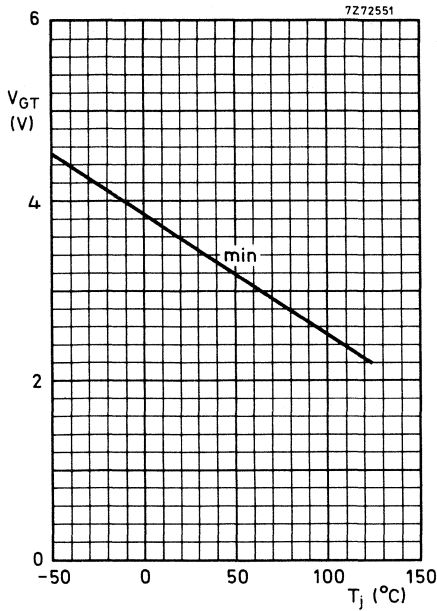


Fig. 10 Minimum gate voltage that will trigger all devices as a function of  $T_j$ .

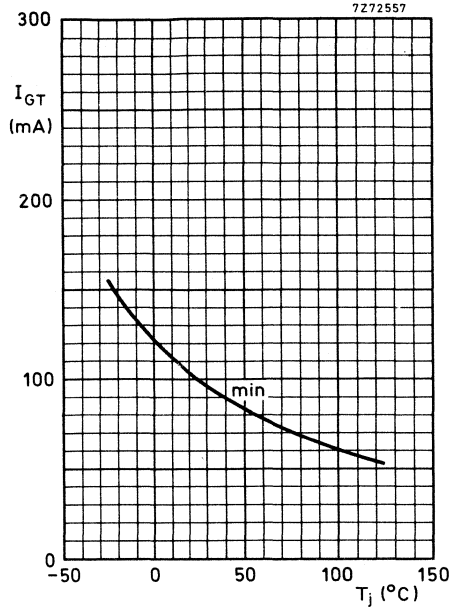


Fig. 11 Minimum gate current that will trigger all devices as a function of  $T_j$ .

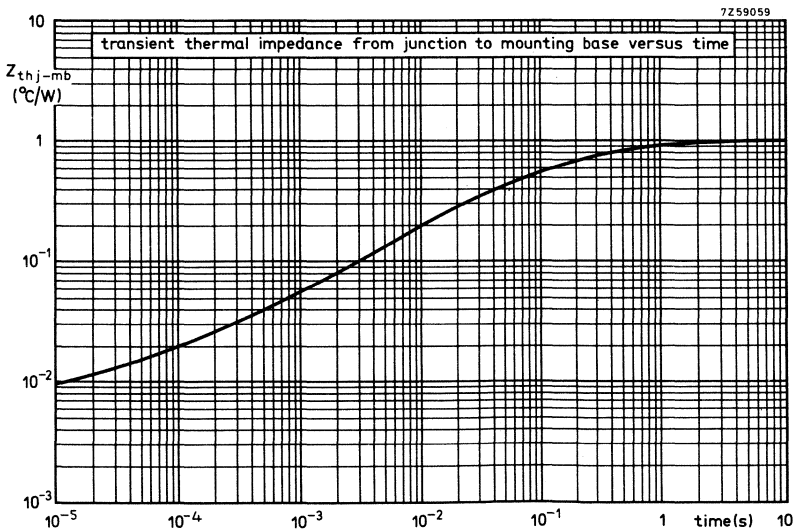


Fig. 12.

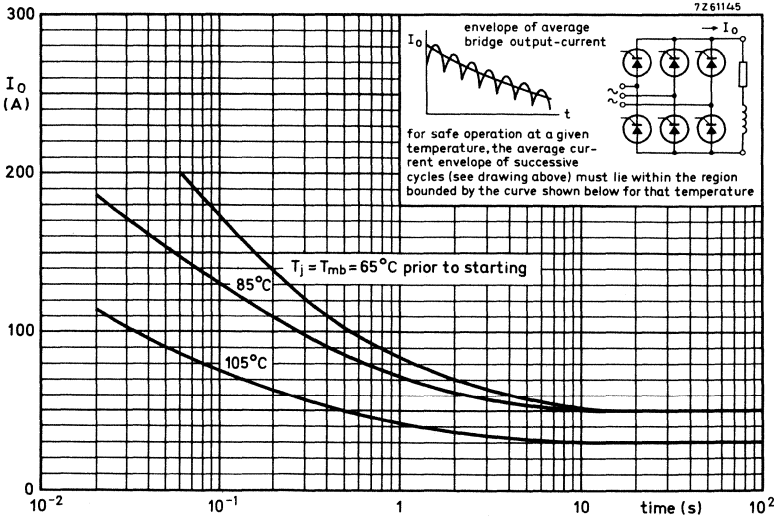
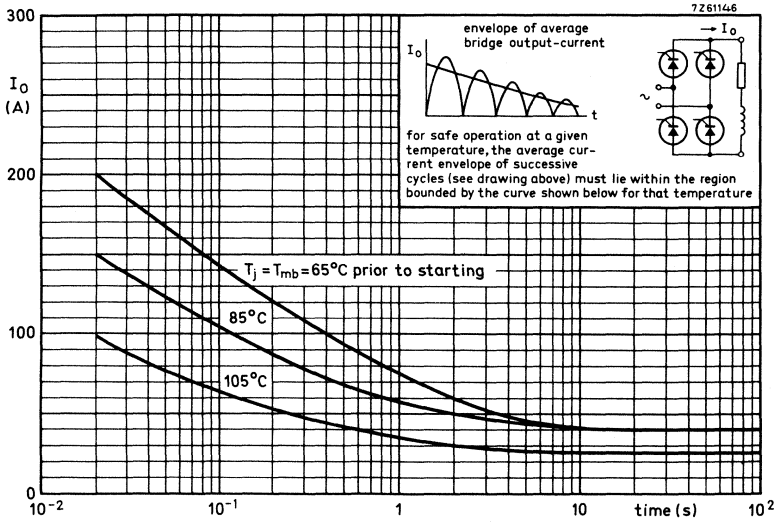


Fig. 13 Limits for starting or inrush currents.

**SILICON THYRISTORS**

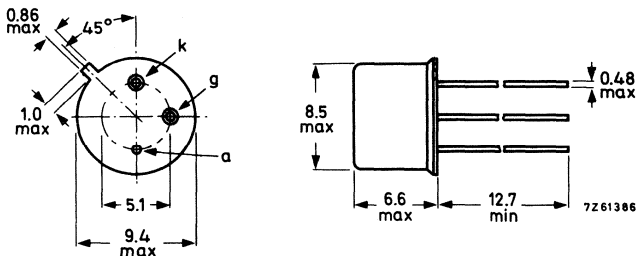
The BTX18series is a range of p-gate reverse blocking thyristors, in a TO-5 metal envelope, intended for use in general low power applications up to 1 A average on-state current

		<b>QUICK REFERENCE DATA</b>				
		BTX18-100	200	300	400	500
Crest working reverse voltage	$V_{RWM}$	max. 100	200	300	400	500 V
Crest working off-state voltage	$V_{DWM}$	max. 100	200	300	400	500 V
Average on-state current up to $T_{case} = 105\text{ }^{\circ}\text{C}$	$I_{T(AV)}$	max.	1.0 A			
$T_{amb} = 60\text{ }^{\circ}\text{C}$ ; in free air	$I_{T(AV)}$	max.	250 mA			
Non-repetitive peak on-state current $t = 10\text{ ms}$ ; $T_j = 125\text{ }^{\circ}\text{C}$ prior to surge	$I_{TSM}$	max.	10 A			
Junction temperature	$T_j$	max.	125 $^{\circ}\text{C}$			

**MECHANICAL DATA**

Dimensions in mm

Anode connected to the case  
TO-39



Accessories **supplied on request: 56218; 56245.**

# BTX18 SERIES

All information applies to frequencies up to 400 Hz

**RATINGS** Limiting values in accordance with the Absolute Maximum System (IEC 134)

## ANODE TO CATHODE

### Voltages<sup>1)</sup>

		BTX18-100	200	300	400	500
Continuous reverse voltage	$V_R$	max. 100	200	300	400	500 V
Crest working reverse voltage	$V_{RWM}$	max. 100	200	300	400	500 V
Repetitive peak reverse voltage ( $\delta = 0.01$ ; $f = 50$ Hz)	$V_{RRM}$	max. 120	240	350	500	600 V
<b>Non-repetitive</b> peak reverse voltage ( $t \leq 10$ ms)	$V_{RSM}$	max. 120	240	350	500	600 V
Continuous off-state voltage	$V_D$	max. 100	200	300	400	500 V
Crest working off-state voltage	$V_{DWM}$	max. 100	200	300	400	500 V
Repetitive peak off-state voltage ( $\delta = 0.01$ ; $f = 50$ Hz)	$V_{DRM}$	max. 120	240	350	500	600 V <sup>2)</sup>
<b>Non-repetitive</b> peak off-state voltage ( $t \leq 10$ ms)	$V_{DSM}$	max. 120	240	350	500	600 V <sup>2)</sup>

### Currents

Average on-state current (averaged over  
any 20 ms period) up to  $T_{case} = 105$  °C

$I_{T(AV)}$  max. 1.0 A

at  $T_{amb} = 60$  °C

$I_{T(AV)}$  max. 250 mA

On-state current (d.c.)

$T_{case} = 100$  °C

$I_T$  max. 1.6 A

R.M.S. on-state current

$I_{T(RMS)}$  max. 1.6 A

Repetitive peak on-state current

$I_{TRM}$  max. 10 A

**Non-repetitive** peak on-state current  
( $t = 10$  ms, half sinewave)

$I_{TSM}$  max. 10 A

1) These ratings apply for zero or negative bias on the gate with respect to the cathode, and when a resistor  $R \leq 1$  k $\Omega$  is connected between gate and cathode.

2) The device is not suitable for operation in the forward breakover mode.



**RATINGS**

GATE TO CATHODE (with 1 kΩ resistor between gate and cathode)

Voltages

Forward peak voltage	$V_{FGM}$	max.	10	V
Reverse peak voltage	$V_{RGM}$	max.	5	V

Current

Forward peak current	$I_{FGM}$	max.	0.2	A
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Power dissipation

Average power dissipation (averaged over any 20 ms period)	$P_{G(AV)}$	max.	0.05	W
Peak power dissipation	$P_{GM}$	max.	0.5	W

TEMPERATURES

Storage temperature	$T_{stg}$	-55 to +125	°C
Junction temperature	$T_j$	max.	125 °C

**THERMAL RESISTANCE**

From junction to case	$R_{th j-c}$	=	10	°C/W
From junction to ambient	$R_{th j-a}$	=	200	°C/W
Transient thermal resistance (t = 10 ms)	$Z_{th j-c}$	=	2.5	°C/W

**CHARACTERISTICS**

ANODE TO CATHODE

Voltages

On-state voltage

$I_T = 1.0$  A;  $T_j = 25$  °C

	BTX18-100	200	300	400	500
$V_T$	< 1.5	1.5	1.5	1.5	1.5 V <sup>1)</sup>

Rate of rise of off-state voltage that will not trigger any device

RGK = 1 kΩ;  $T_j = 125$  °C

$\frac{dV_D}{dt}$	See page 6
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Currents

Peak reverse current

$V_{RM} = V_{RWMmax}$ ;  $T_j = 125$  °C

$I_{RM}$	< 800	400	275	200	160	μA
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Peak off-state current

$V_{DM} = V_{DWMmax}$ ;  $T_j = 125$  °C

$I_{DM}$	< 800	400	275	200	160	μA
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<sup>1)</sup>  $V_T$  is measured along the leads at 1 cm from the case.

**CHARACTERISTICS (continued)**

Latching current; $T_j = 125\text{ }^\circ\text{C}$	$I_L$	typ. 10 mA
Holding current; $T_j = 25\text{ }^\circ\text{C}$	$I_H$	< 5.0 mA <sup>1)</sup>

GATE TO CATHODE

Voltages

Voltage that will trigger all devices; $T_j = 25\text{ }^\circ\text{C}$	$V_{GT}$	> 2.0 V
Voltage that will not trigger any device; $T_j = 125\text{ }^\circ\text{C}$	$V_{GD}$	< 200 mV

Current

Current that will trigger all devices; $T_j = 25\text{ }^\circ\text{C}$	$I_{GT}$	> 5.0 mA
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**SWITCHING CHARACTERISTICS**

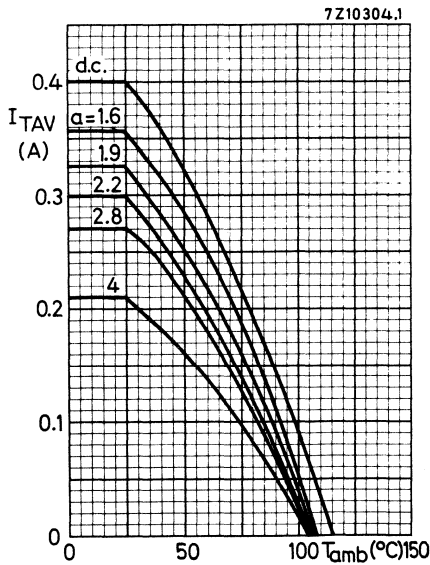
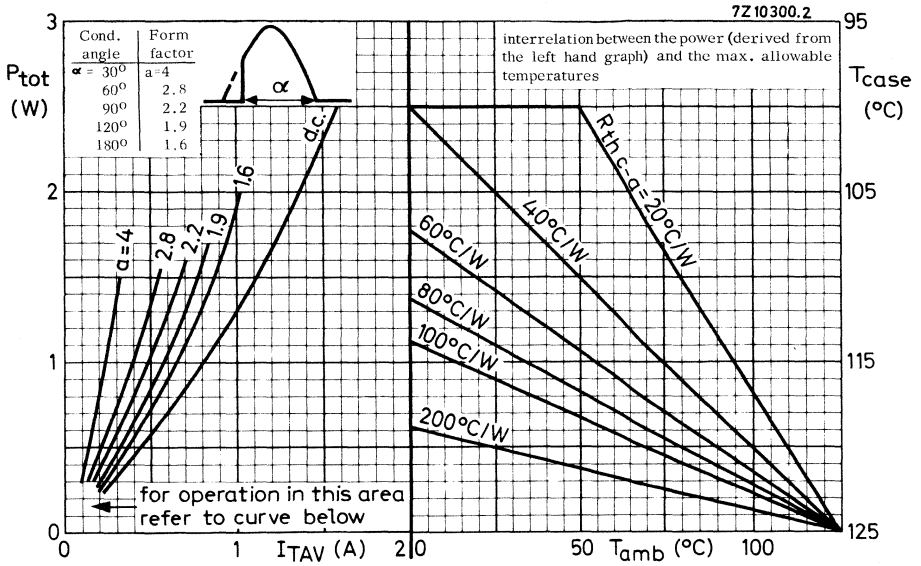
Turn off time when switched from

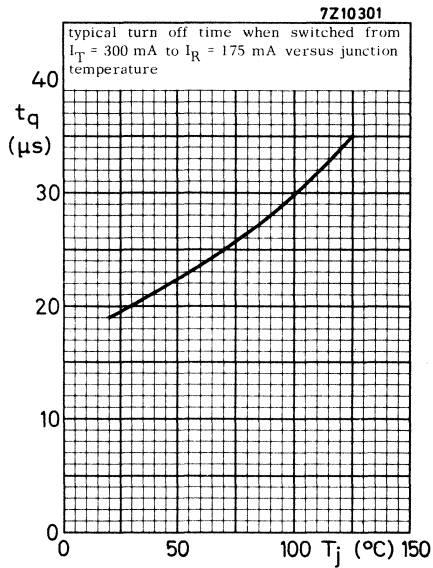
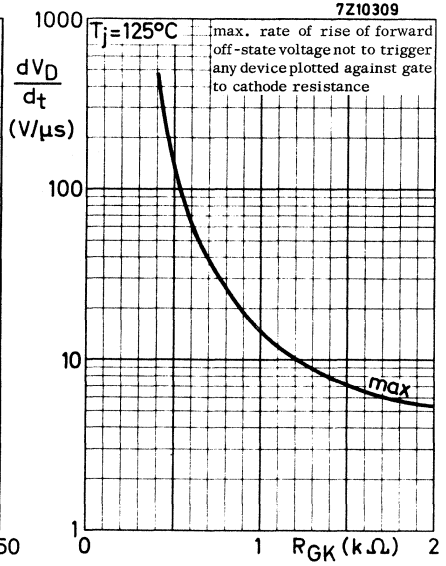
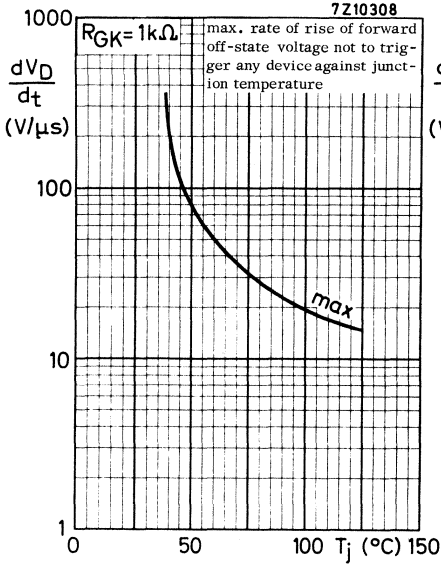
$I_T = 300\text{ mA}$ to $I_R = 175\text{ mA}$ ; $T_j = 25\text{ }^\circ\text{C}$	$t_q$	typ. 20 $\mu\text{s}$
$T_j = 125\text{ }^\circ\text{C}$	$t_q$	typ. 35 $\mu\text{s}$

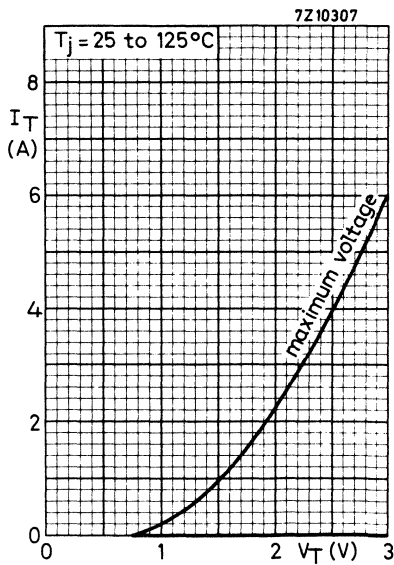
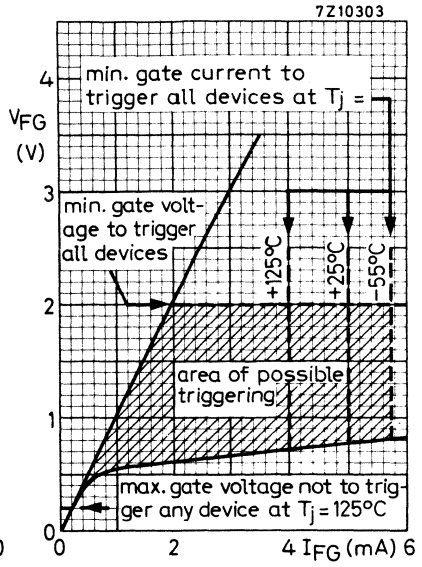
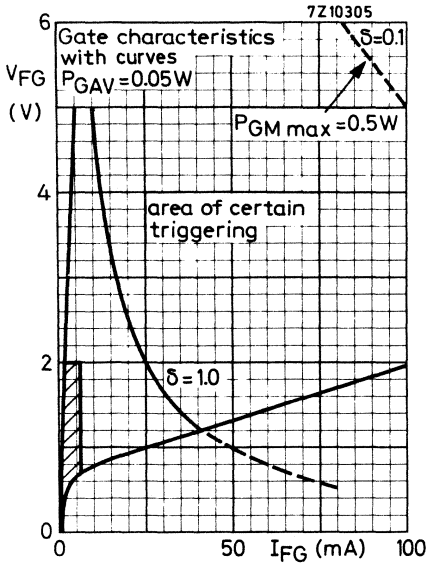
**NOTES**

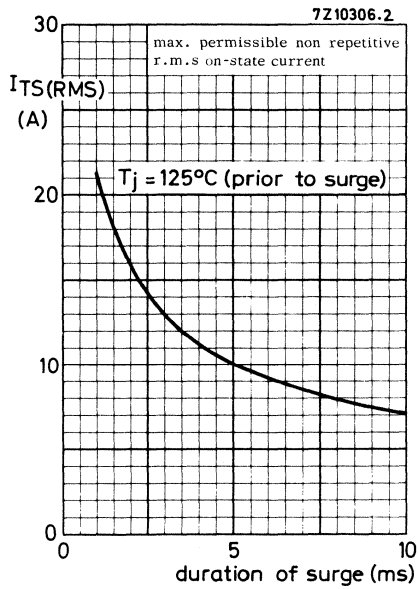
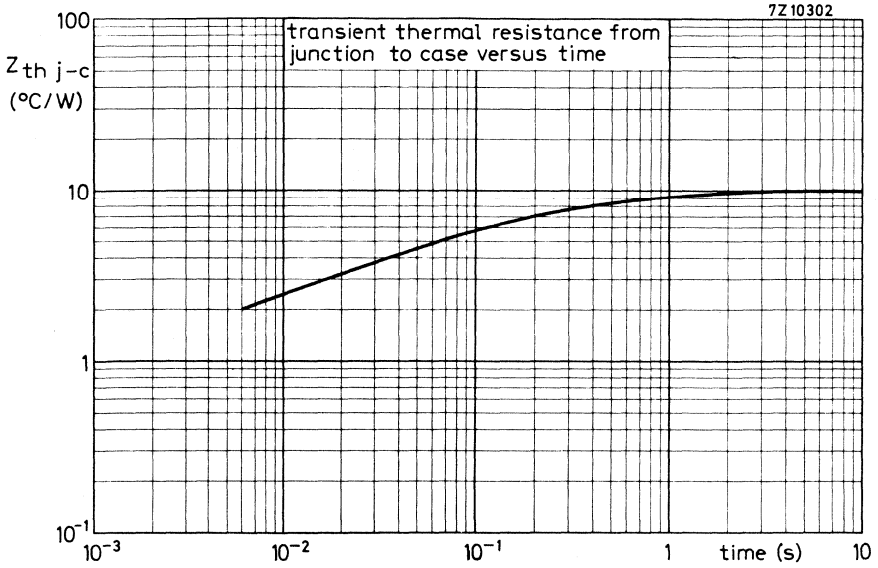
1. When using a soldering iron the thyristor may be soldered directly into the circuit, but the heat conduction to the junction should be kept to a minimum by using a thermal shunt.
2. Thyristors may be dip soldered at a solder temperature of  $245\text{ }^\circ\text{C}$ , for a maximum soldering time of 5 seconds. The case temperature during dip soldering must not at any time exceed the maximum storage temperature. These recommendations apply to a thyristor mounted flush on a board with punched-through holes, or spaced 1.5 mm above a board having plated-through holes.
3. Care should be taken not to bend the leads nearer than 1.5 mm from the seal.

<sup>1)</sup> Measured under the following conditions: Anode supply voltage = +6.0 V.  
Initial on-state current after gate triggering = 50 mA.  
The current is reduced until the device turns off.









THYRISTORS

Also available to BS9341-F001 to F009

Silicon thyristors in metal envelopes, intended for use in power control circuits (e.g. light and motor control) and power switching systems.

The series consists of reverse polarity types (anode to stud) identified by a suffix R: BTY79-400R to 1000R.

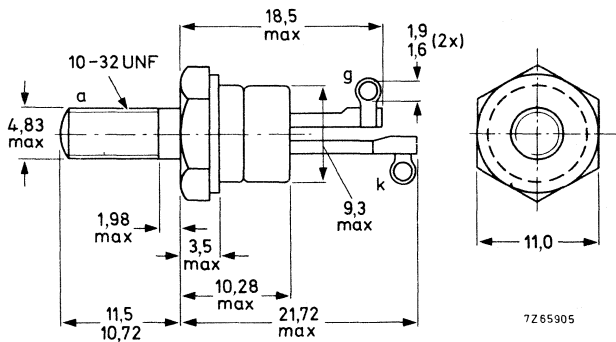
QUICK REFERENCE DATA

	BTY79-400R	500R	600R	800R	1000R
Repetitive peak voltages $V_{DRM}/V_{RRM}$ max.	400	500	600	800	1000 V
Average on-state current				$I_{T(AV)}$ max.	10 A
R.M.S. on-state current				$I_{T(RMS)}$ max.	16 A
Non-repetitive peak on-state current				$I_{TSM}$ max.	150 A

MECHANICAL DATA

Dimensions in mm

Fig. 1 TO-64: with 10-32 UNF stud ( $\phi$  4,83 mm).



Net mass: 7 g

Diameter of clearance hole: max. 5,2 mm

Accessories supplied on request:

56295 (PTFE bush, 2 mica washers, plain washer, tag)

56262A (mica washer, insulating ring, plain washer)

Torque on nut: min. 0,9 Nm  
(9 kg cm)

max. 1,7 Nm  
(17 kg cm)

Supplied with device: 1 nut, 1 lock washer

Nut dimensions: across the flats: 9,5 mm

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

### Anode to cathode

		BTY79-400R	500R	600R	800R	1000R
Non-repetitive peak off-state voltage ( $t \leq 10$ ms)	$V_{DSM}^{**}$ max.	500	1100	1100	1100	1100 V
Non-repetitive peak reverse voltage ( $t \leq 5$ ms)	$V_{RSM}$ max.	500	600	720	960	1100 V
Repetitive peak voltages	$V_{DRM}/V_{RRM}$ max.	400	500	600	800	1000 V
Crest working voltages	$V_{DWM}/V_{RWM}$ max.	400	500	600	800	1000 V*

Average on-state current (averaged over any 20 ms period) up to  $T_{mb} = 85$  °C

$I_T(AV)$  max. 10 A

R.M.S. on-state current

$I_T(RMS)$  max. 16 A

Repetitive peak on-state current

$I_{TRM}$  max. 75 A

Non-repetitive peak on-state current;  $t = 10$  ms;  
half sine-wave;  $T_j = 125$  °C prior to surge;  
with reapplied  $V_{RWMmax}$

$I_{TSM}$  max. 150 A

$I^2 t$  for fusing ( $t = 10$  ms)

$I^2 t$  max. 112 A<sup>2</sup>s

Rate of rise of on-state current after triggering with  
 $I_G = 150$  mA to  $I_T = 30$  A;  $dI_G/dt = 0,25$  A/ $\mu$ s

$dI_T/dt$  max. 50 A/ $\mu$ s

### Gate to cathode

Average power dissipation (averaged over any 20 ms period)

$P_G(AV)$  max. 0,5 W

Peak power dissipation

$P_{GM}$  max. 5 W

### Temperatures

Storage temperature

$T_{stg}$  -55 to +125 °C

Junction temperature

$T_j$  max. 125 °C

### THERMAL RESISTANCE

From junction to mounting base

$R_{th j-mb} = 1,8$  °C/W

From mounting base to heatsink  
with heatsink compound

$R_{th mb-h} = 0,5$  °C/W

From junction to ambient in free air

$R_{th j-a} = 45$  °C/W

Transient thermal impedance ( $t = 1$  ms)

$Z_{th j-mb} = 0,1$  °C/W

\* To ensure thermal stability:  $R_{th j-a} < 4$  °C/W (d.c. blocking) or  $< 8$  °C/W (a.c.). For smaller heat-sinks  $T_{j max}$  should be derated. For a.c. see Fig. 3.

\*\* Although not recommended, higher off-state voltages may be applied without damage, but the thyristor may switch into the on-state. The rate of rise of on-state current should not exceed 100 A/ $\mu$ s.



**CHARACTERISTICS**

**Anode to cathode**

On-state voltage

$I_T = 20 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_T < 2 \text{ V}^*$

Rate of rise of off-state voltage that will not trigger any device;

exponential method;  $V_D = 2/3 V_{DRMmax}; T_j = 125 \text{ }^\circ\text{C}$

$dV_D/dt < 50 \text{ V}/\mu\text{s}$

Reverse current

$V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$

$I_R < 3 \text{ mA}$

Off-state current

$V_D = V_{DWMmax}; T_j = 125 \text{ }^\circ\text{C}$

$I_D < 3 \text{ mA}$

Latching current;  $T_j = 25 \text{ }^\circ\text{C}$

$I_L < 150 \text{ mA}$

Holding current;  $T_j = 25 \text{ }^\circ\text{C}$

$I_H < 75 \text{ mA}$

**Gate to cathode**

Voltage that will trigger all devices

$V_D = 6 \text{ V}; T_j = 25^\circ\text{C}$

$V_{GT} > 1,5 \text{ V}$

Voltage that will not trigger any device

$V_D = V_{DRMmax}; T_j = 125 \text{ }^\circ\text{C}$

$V_{GD} < 200 \text{ mV}$

Current that will trigger all devices

$V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$

$I_{GT} > 30 \text{ mA}$

On request (see ordering note on page 4)

$I_{GT} > 20 \text{ mA}$

**Switching characteristics**

Gate-controlled turn-on time ( $t_{gt} = t_d + t_r$ ) when switched

from  $V_D = 800 \text{ V}$  to  $I_T = 25 \text{ A}; I_{GT} = 250 \text{ mA};$

$dI_G/dt = 0,25 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

$t_{gt} < 1,5 \mu\text{s}$   
 $t_r$  typ.  $0,2 \mu\text{s}$

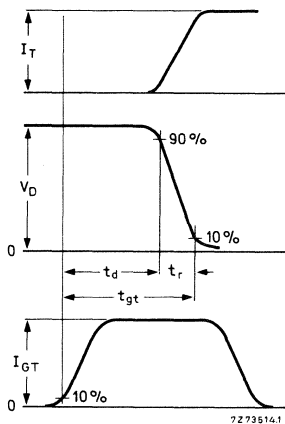


Fig. 2 Gate-controlled turn-on time definitions.

\* Measured under pulse conditions to avoid excessive dissipation.

**OPERATING NOTE**

The terminals should neither be bent nor twisted; they should be soldered into the circuit so that there is no strain on them.  
 During soldering the heat conduction to the junction should be kept to a minimum.

**ORDERING NOTE**

Types with low gate trigger current,  $I_{GT} > 20$  mA, are available on request. Add suffix A to the type number when ordering: e.g. BTY79A-400R.

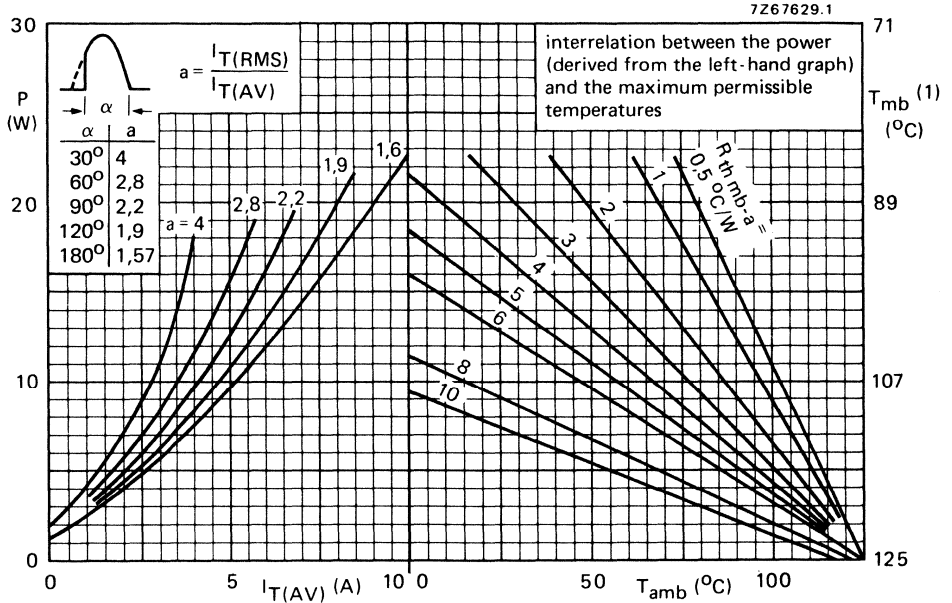


Fig. 3 (1)  $T_{mb}$ -scale is for comparison purposes only and is correct only for  $R_{th\ mb-a} \leq 6\ ^\circ C/W$ .

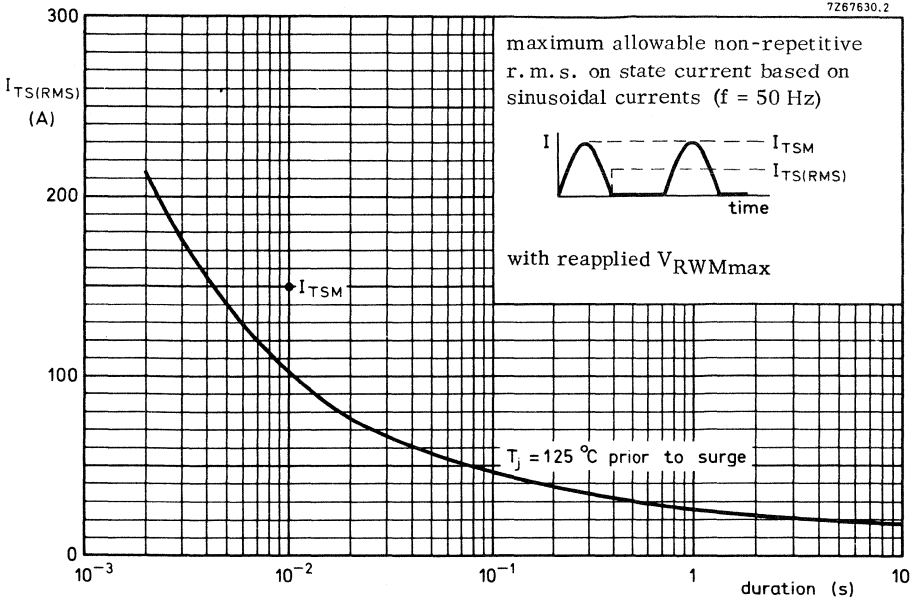


Fig. 4.

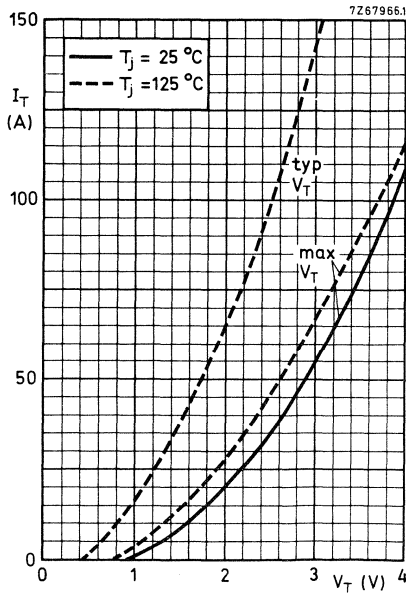


Fig. 5.

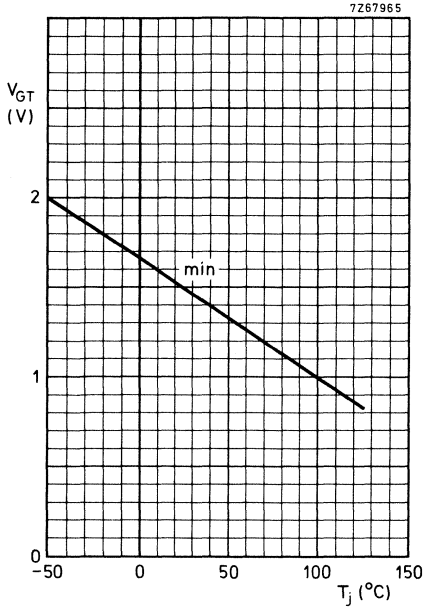


Fig. 6 Minimum gate voltage that will trigger all devices as a function of  $T_j$ .

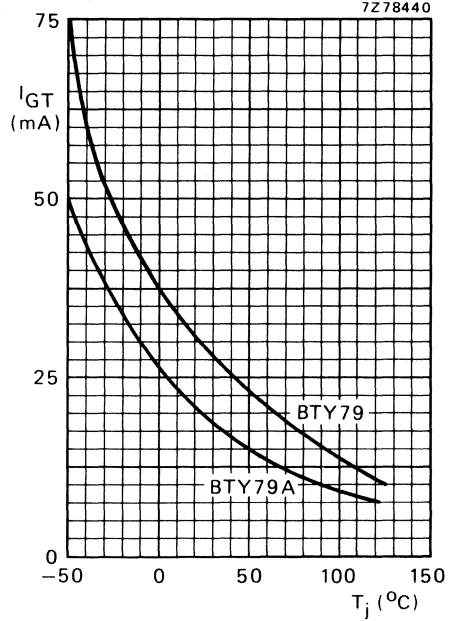


Fig. 7 Minimum gate current that will trigger all devices as a function of  $T_j$ .

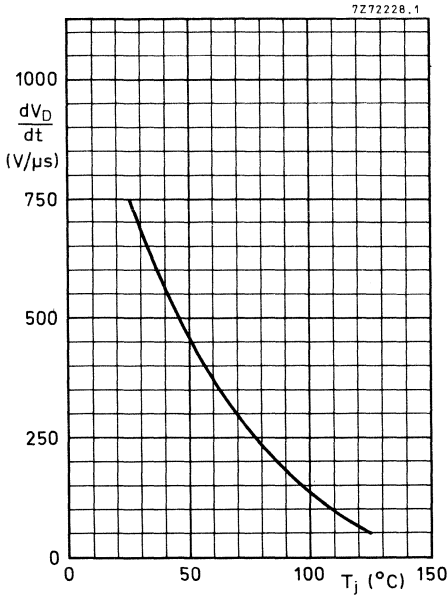


Fig. 8 Maximum rate of rise of off-state voltage that will not trigger any device (exponential method) as a function of  $T_j$ .

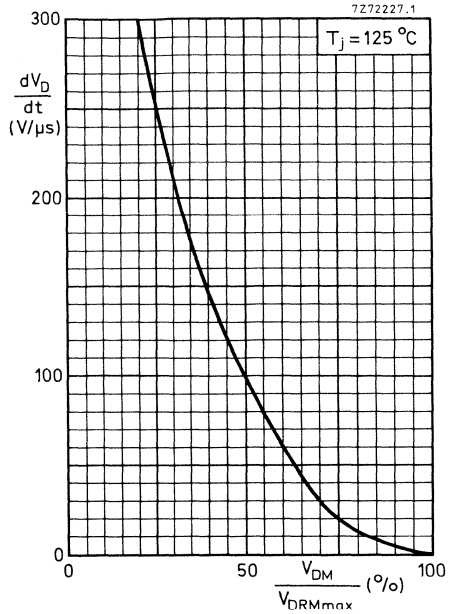


Fig. 9 Maximum rate of rise of off-state voltage that will not trigger any device (exponential method) as a function of applied voltage.

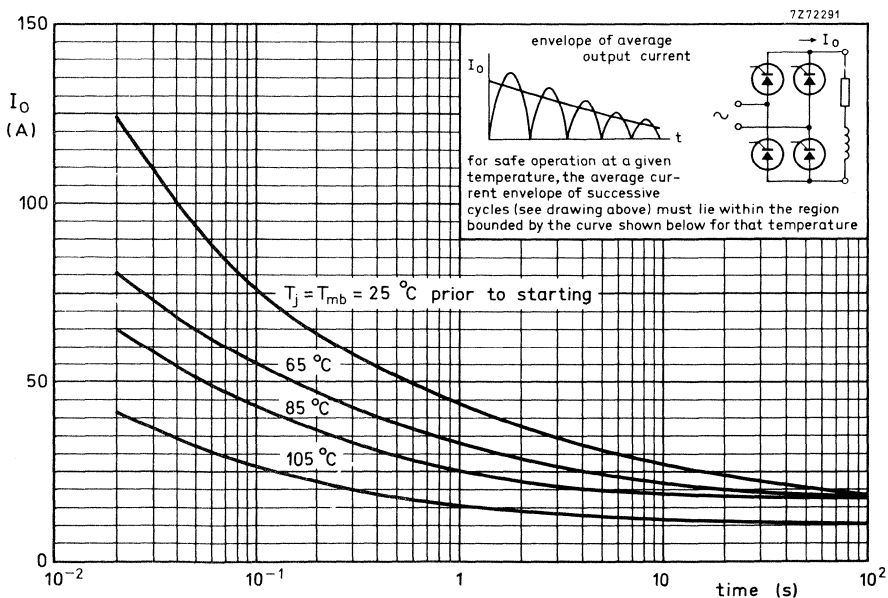
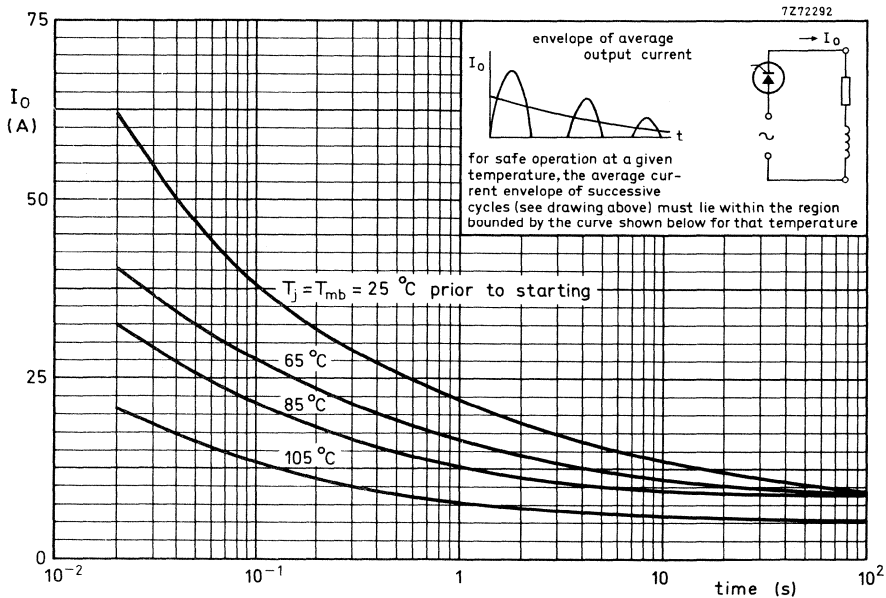


Fig. 10 Limits for starting or inrush currents.

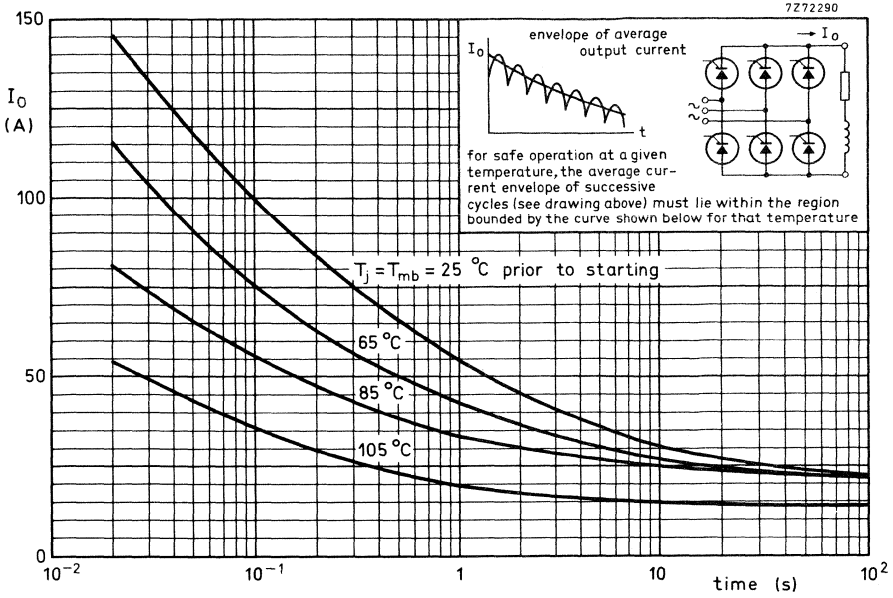


Fig. 11 Limits for starting or inrush currents.

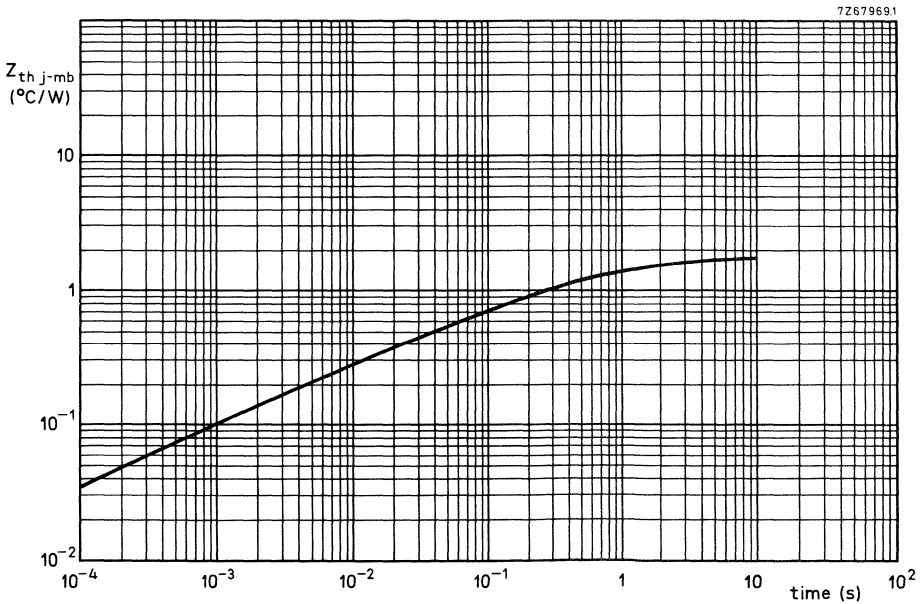


Fig. 12.







## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

Anode to cathode		BTY87-400R   500R   600R   800R			
Non-repetitive peak off-state voltage ( $t \leq 10$ ms)	$V_{DSM}$	max. 500	850	850	850 V
Non-repetitive peak reverse voltage ( $t \leq 5$ ms)	$V_{RSM}$	max. 500	600	850	960 V
Repetitive peak voltages	$V_{DRM}/V_{RRM}$	max. 400	500	600	800 V
Crest working voltages	$V_{DWM}/V_{RWM}$	max. 400	500	600	800 V *
Average on-state current (averaged over any 20 ms period) up to $T_{mb} = 52$ °C at $T_{mb} = 85$ °C		$I_T(AV)$	max.	16 A	
		$I_T(AV)$	max.	10 A	
R.M.S. on-state current		$I_T(RMS)$	max.	25 A	
Repetitive peak on-state current		$I_{TRM}$	max.	140 A	
Non-repetitive peak on-state current; $t = 10$ ms; half sine-wave; $T_j = 125$ °C prior to surge; with reapplied $V_{RWMmax}$		$I_{TSM}$	max.	140 A	
$I^2t$ for fusing ( $t = 10$ ms)		$I^2t$	max.	100 A <sup>2</sup> s	
Rate of rise of on-state current after triggering with $I_G = 325$ mA to $I_T = 50$ A		$dI_T/dt$	max.	20 A/ $\mu$ s	
<b>Gate to cathode</b>					
Reverse peak voltage		$V_{RGM}$	max.	5 V	
Average power dissipation (averaged over any 20 ms period)		$P_G(AV)$	max.	0,5 W	
Peak power dissipation		$P_{GM}$	max.	5 W	
<b>Temperatures</b>					
Storage temperature		$T_{stg}$	-55 to + 125 °C		
Junction temperature		$T_j$	max.	125 °C	

## THERMAL RESISTANCE

From junction to mounting base	$R_{th j-mb}$	=	1,6 °C/W
From mounting base to heatsink with heatsink compound	$R_{th mb-h}$	=	0,2 °C/W
Transient thermal impedance ( $t = 1$ ms)	$Z_{th j-mb}$	=	0,09 °C/W

## OPERATING NOTE

The terminals should neither be bent nor twisted; they should be soldered into the circuit so that there is no strain on them.

During soldering the heat conduction to the junction should be kept to a minimum.

\* To ensure thermal stability:  $R_{th j-a} < 4,5$  °C/W (d.c. blocking) or  $< 9$  °C/W (a.c.). For smaller heat-sinks  $T_{jmax}$  should be derated. For a.c. see Fig. 3.

**CHARACTERISTICS**

**Anode to cathode**

On-state voltage $I_T = 50 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$	$V_T < 3 \text{ V}^*$
Rate of rise of off-state voltage that will not trigger any device; exponential method; $V_D = 2/3 V_{DRMmax}; T_j = 125 \text{ }^\circ\text{C}$	$dV_D/dt < 20 \text{ V}/\mu\text{s}$
Reverse current $V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$	$I_R < 3 \text{ mA}$
Off-state current $V_D = V_{DWMmax}; T_j = 125 \text{ }^\circ\text{C}$	$I_D < 3 \text{ mA}$
Latching current; $T_j = 25 \text{ }^\circ\text{C}$	$I_L \text{ typ. } 20 \text{ mA}$
Holding current; $T_j = 25 \text{ }^\circ\text{C}$	$I_H \text{ typ. } 10 \text{ mA}$

**Gate to cathode**

Voltage that will trigger all devices $V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$	$V_{GT} > 3.5 \text{ V}$
Voltage that will not trigger any device $V_D = V_{DRMmax}; T_j = 125 \text{ }^\circ\text{C}$	$V_{GD} < 200 \text{ mV}$
Current that will trigger all devices $V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$	$I_{GT} > 65 \text{ mA}$

**Switching characteristics**

Gate-controlled turn-on time ( $t_{gt} = t_d + t_r$ ) when switched from $V_D = 400 \text{ V}$ to $I_T = 50 \text{ A}; I_{GT} = 200 \text{ mA}; T_j = 25 \text{ }^\circ\text{C}$	$t_{gt} \text{ typ. } 2 \mu\text{s}$
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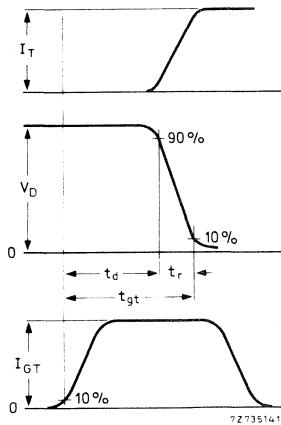


Fig. 2 Gate-controlled turn-on time definitions.

\* Measured under pulse conditions to avoid excessive dissipation.

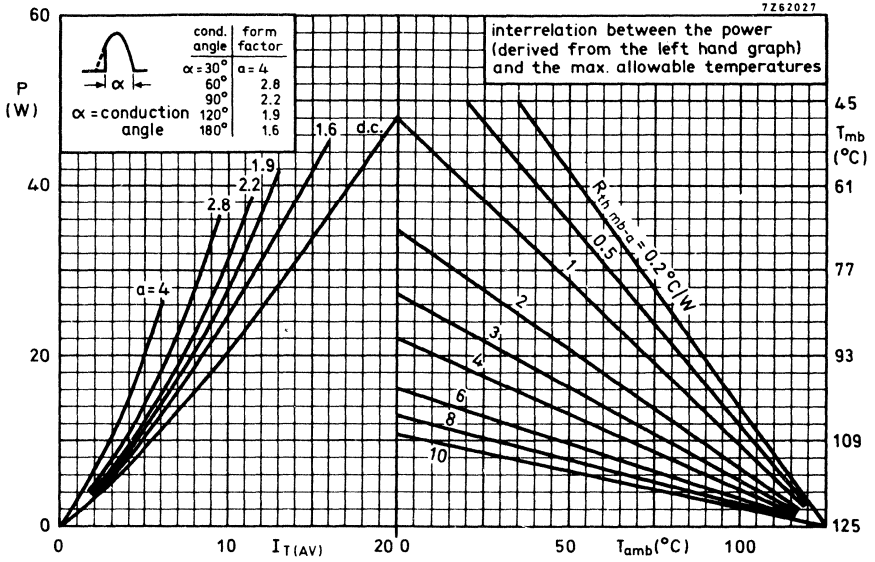


Fig. 3.

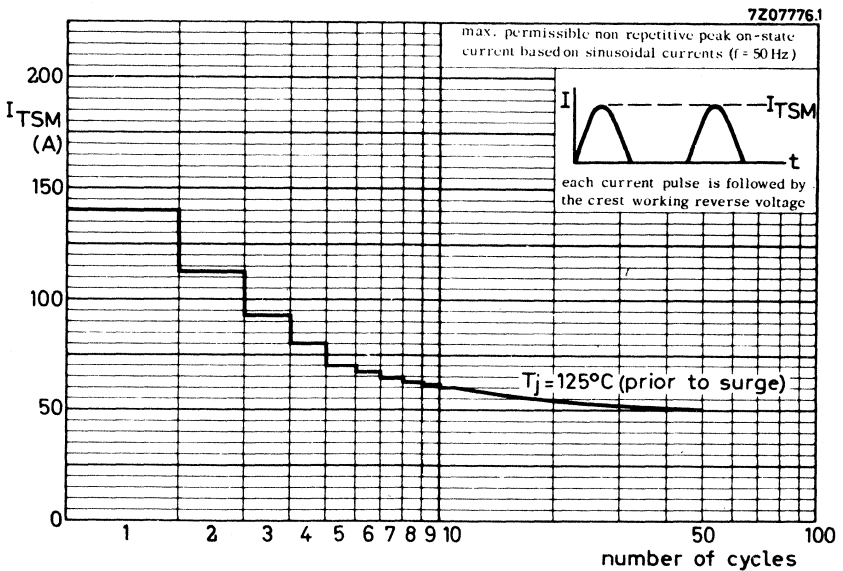


Fig. 4.

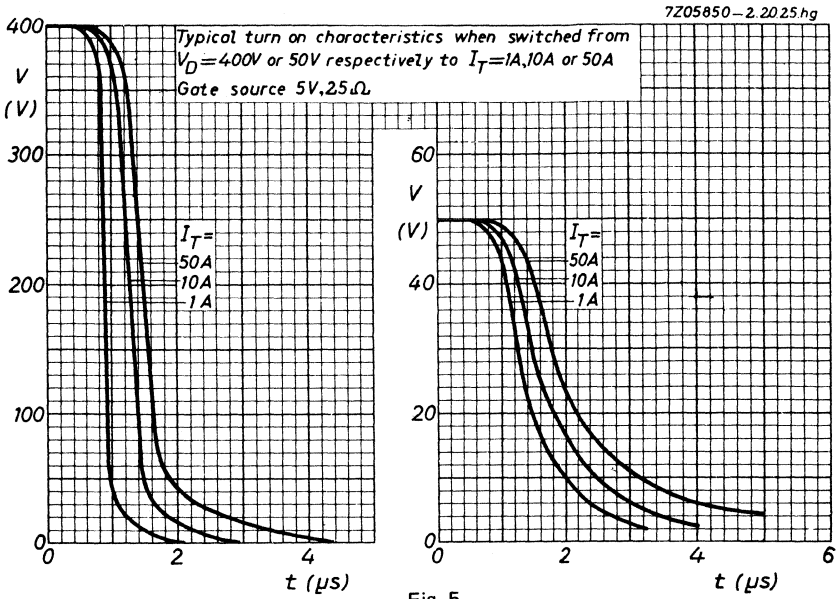


Fig. 5.

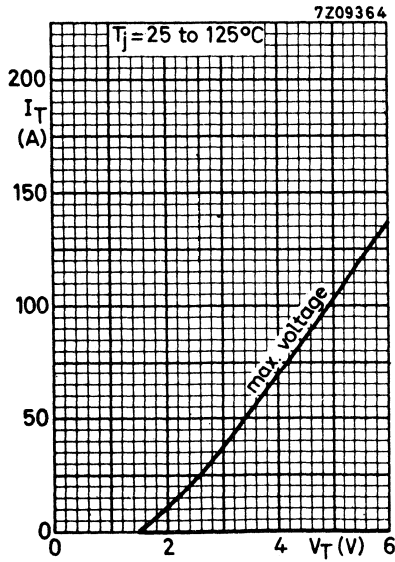


Fig. 6.

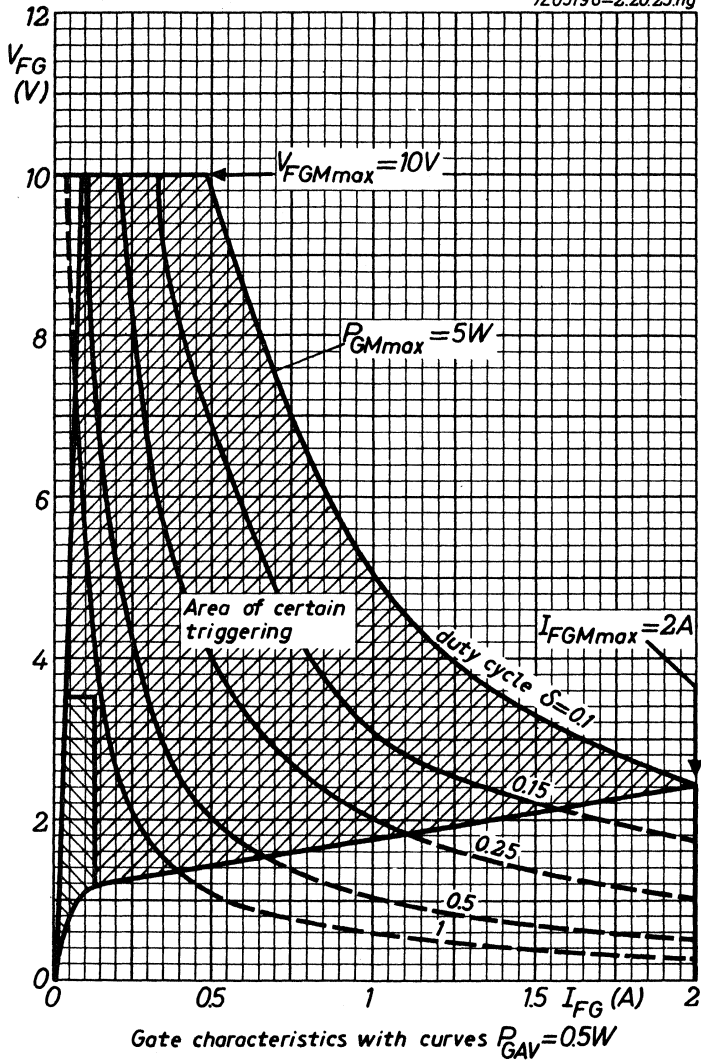


Fig. 7.

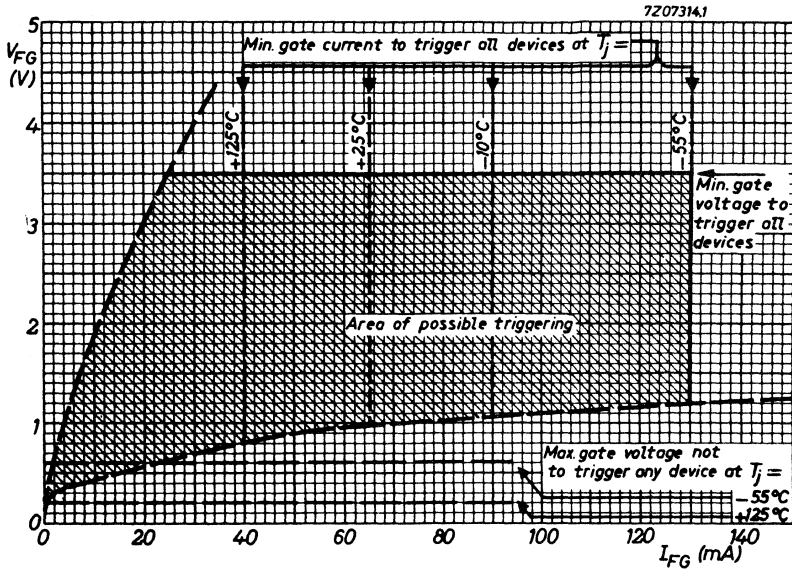


Fig. 8.

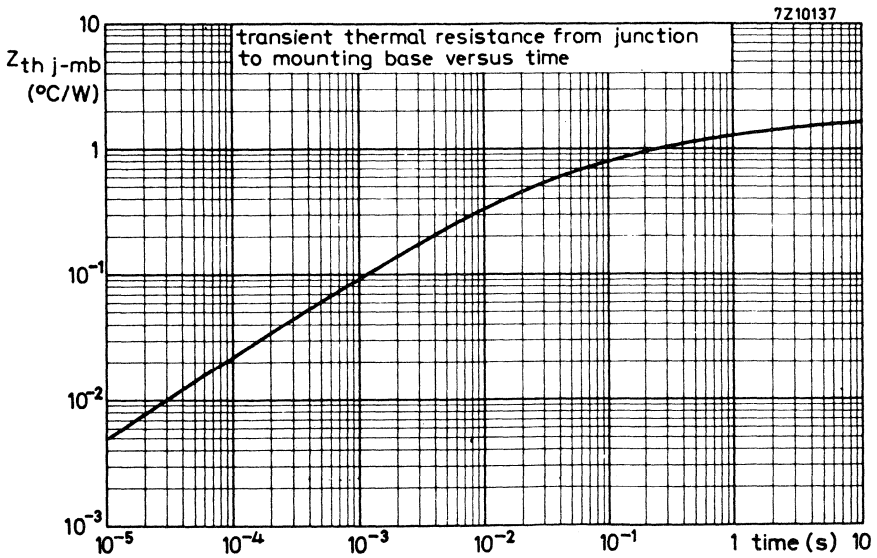


Fig. 9.

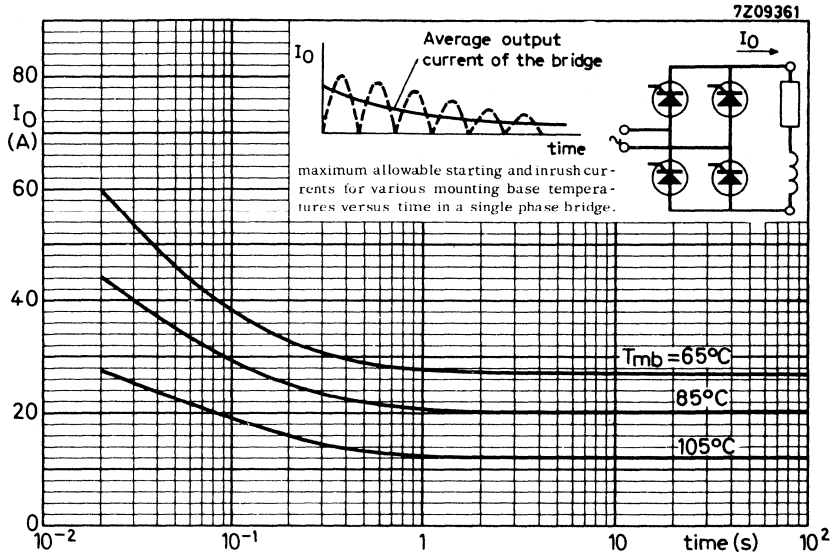


Fig. 10.

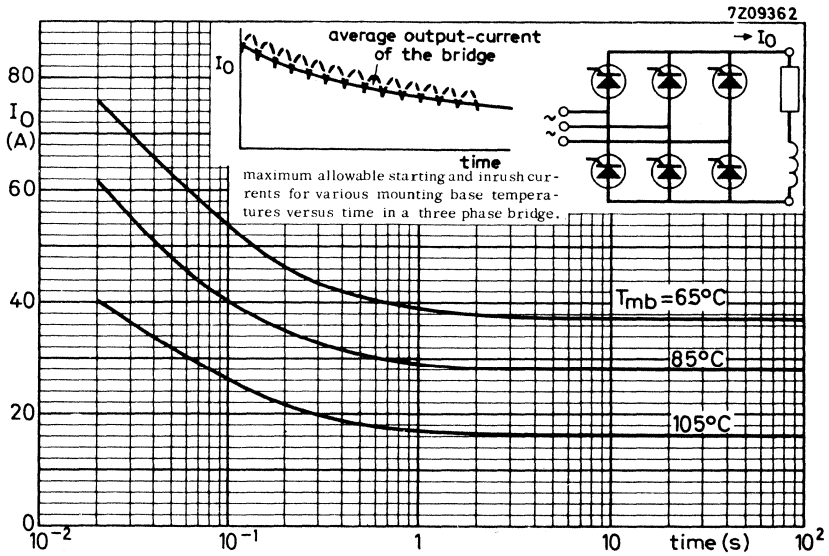


Fig. 11.



## THYRISTORS

Silicon thyristors in metal envelopes, intended for power control and power switching applications. The series consists of reverse polarity types (anode to stud) identified by a suffix R: BTY91-400R to 800R.

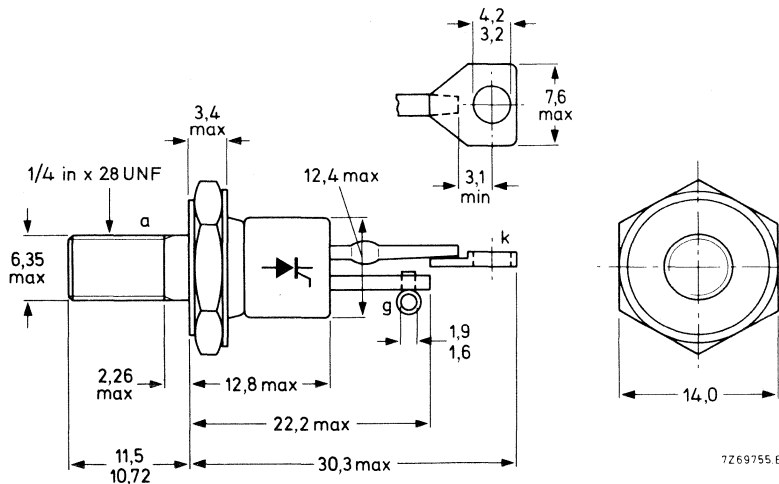
### QUICK REFERENCE DATA

		BTY91-400R	500R	600R	800R
Repetitive peak voltages	$V_{DRM}/V_{RRM}$	max. 400	500	600	800 V
Average on-state current	$I_T(AV)$	max.		16 A	
R.M.S. on-state current	$I_T(RMS)$	max.		25 A	
Non-repetitive peak on-state current	$I_{TSM}$	max.		200 A	

### MECHANICAL DATA

Dimensions in mm

Fig. 1 TO-48: with 1/4 in x 28 UNF stud ( $\phi$  6,35 mm).



Net mass: 14 g  
 Diameter of clearance hole: max. 6,5 mm  
 Accessories supplied on request: 56264A  
 (mica washer, insulating ring, soldering tag)

Torque on nut: min. 1,7 Nm (17 kg cm)  
 max. 3,5 Nm (35 kg cm)  
 Supplied with the device:  
 1 nut, 1 lock washer  
 Nut dimensions across the flats: 11,1 mm

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

Anode to cathode		BTY91-400R	500R	600R	800R
Non-repetitive peak off-state voltage ( $t \leq 10$ ms)	$V_{DSM}$	max. 500	850	850	850 V
Non-repetitive peak reverse voltage ( $t \leq 5$ ms)	$V_{RSM}$	max. 500	600	720	960 V
Repetitive peak voltages	$V_{DRM}/V_{RRM}$	max. 400	500	600	800 V
Crest working voltages	$V_{DWM}/V_{RWM}$	max. 400	500	600	800 V *
Average on-state current (averaged over any 20 ms period) up to $T_{mb} = 77$ °C at $T_{mb} = 85$ °C		$I_{T(AV)}$	max.	16 A	
R.M.S. on-state current		$I_{T(RMS)}$	max.	25 A	
Repetitive peak on-state current		$I_{TRM}$	max.	200 A	
Non-repetitive peak on-state current; $t = 10$ ms; half sine-wave; $T_j = 125$ °C prior to surge; with reapplied $V_{RWMmax}$		$I_{TSM}$	max.	200 A	
$I^2t$ for fusing ( $t = 10$ ms)		$I^2t$	max.	200 A <sup>2</sup> s	
Rate of rise of on-state current after triggering with $I_G = 200$ mA to $I_T = 50$ A		$di_T/dt$	max.	20 A/ $\mu$ s	

## Gate to cathode

Reverse peak voltage	$V_{RGM}$	max.	5 V
Average power dissipation (averaged over any 20 ms period)	$P_{G(AV)}$	max.	0,5 W
Peak power dissipation	$P_{GM}$	max.	5 W

## Temperatures

Storage temperature	$T_{stg}$	-55 to + 125 °C
Junction temperature	$T_j$	max. 125 °C

## THERMAL RESISTANCE

From junction to mounting base	$R_{th j-mb}$	=	1,6 °C/W
From mounting base to heatsink with heatsink compound	$R_{th mb-h}$	=	0,2 °C/W
Transient thermal impedance ( $t = 1$ ms)	$Z_{th j-mb}$	=	0,09 °C/W

## OPERATING NOTE

The terminals should neither be bent nor twisted; they should be soldered into the circuit so that there is no strain on them.

During soldering the heat conduction to the junction should be kept to a minimum.

\* To ensure thermal stability:  $R_{th j-a} < 4,5$  °C/W (d.c. blocking) or  $< 9$  °C/W (a.c.). For smaller heat-sinks  $T_{j max}$  should be derated. For a.c. see Fig. 3.

**CHARACTERISTICS**

**Anode to cathode**

On-state voltage

$I_T = 50 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$   $V_T < 2 \text{ V}^*$

Rate of rise of off-state voltage that will not trigger any device;  
exponential method;  $V_D = 2/3 V_{DRMmax}; T_j = 125 \text{ }^\circ\text{C}$

$dV_D/dt < 20 \text{ V}/\mu\text{s}$

Reverse current

$V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$   $I_R < 3 \text{ mA}$

Off-state current

$V_D = V_{DWMmax}; T_j = 125 \text{ }^\circ\text{C}$   $I_D < 3 \text{ mA}$

Latching current;  $T_j = 25 \text{ }^\circ\text{C}$

$I_L \text{ typ. } 20 \text{ mA}$

Holding current;  $T_j = 25 \text{ }^\circ\text{C}$

$I_H \text{ typ. } 10 \text{ mA}$

**Gate to cathode**

Voltage that will trigger all devices

$V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$   $V_{GT} > 3 \text{ V}$

Voltage that will not trigger any device

$V_D = V_{DRMmax}; T_j = 125 \text{ }^\circ\text{C}$   $V_{GD} < 200 \text{ mV}$

Current that will trigger all devices

$V_D = 6 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$   $I_{GT} > 40 \text{ mA}$

**Switching characteristics**

Gate-controlled turn-on time ( $t_{gt} = t_d + t_r$ ) when switched

from  $V_D = 400 \text{ V}$  to  $I_T = 10 \text{ A}; I_{GT} = 200 \text{ mA}; T_j = 25 \text{ }^\circ\text{C}$   $t_{gt} \text{ typ. } 2 \mu\text{s}$

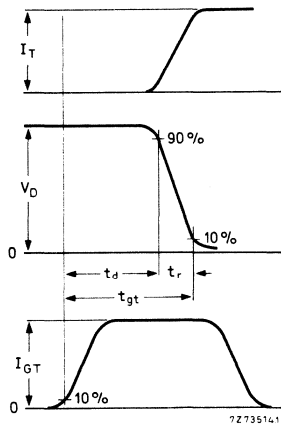


Fig. 2 Gate-controlled turn-on time definitions.

\* Measured under pulse conditions to avoid excessive dissipation.

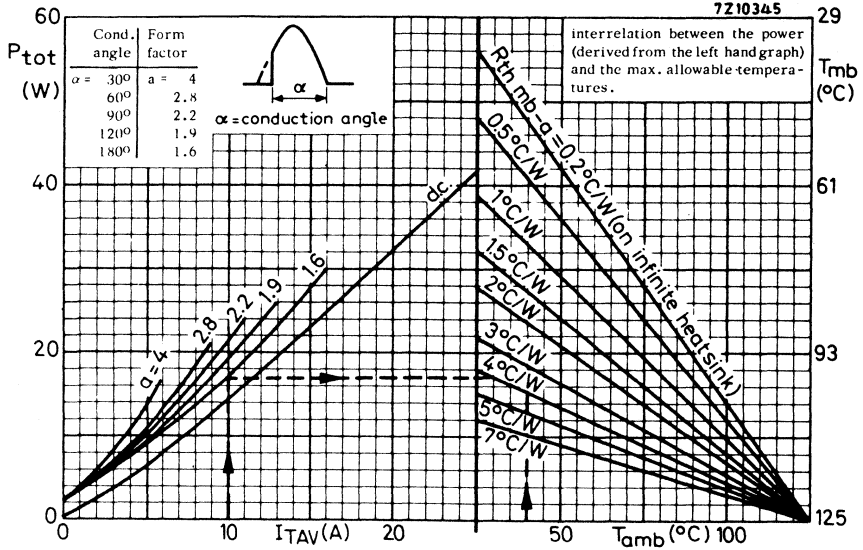


Fig. 3.

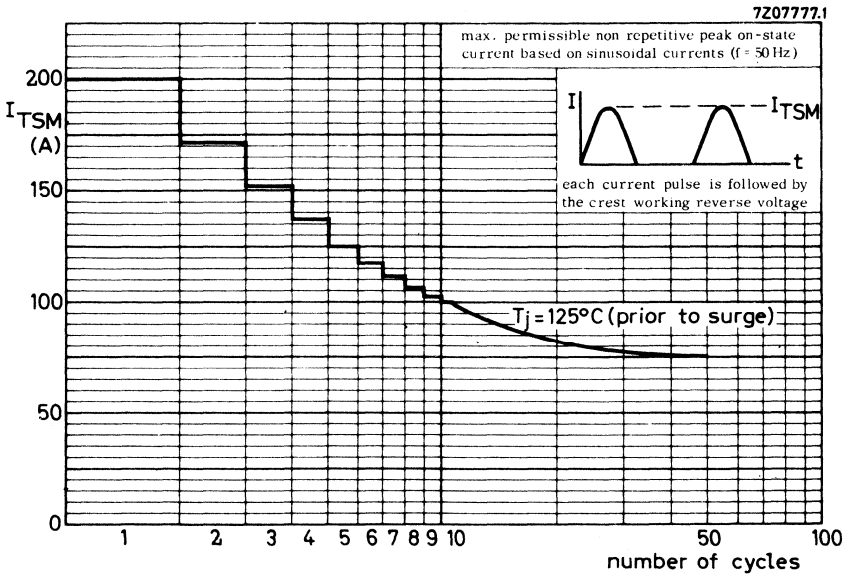


Fig. 4.

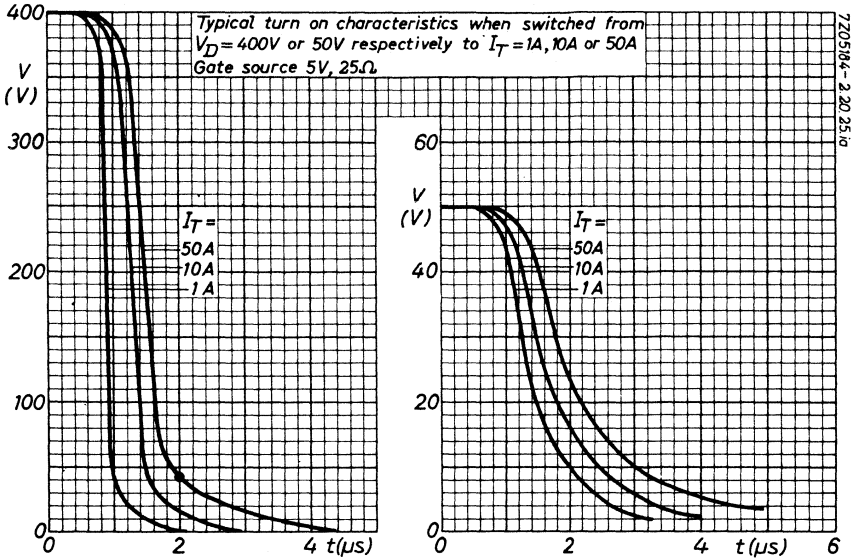


Fig. 5.

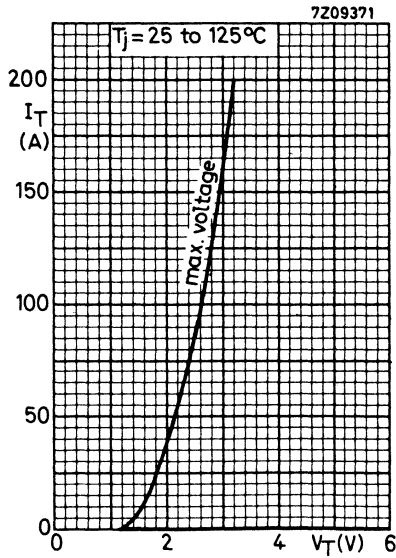


Fig. 6.

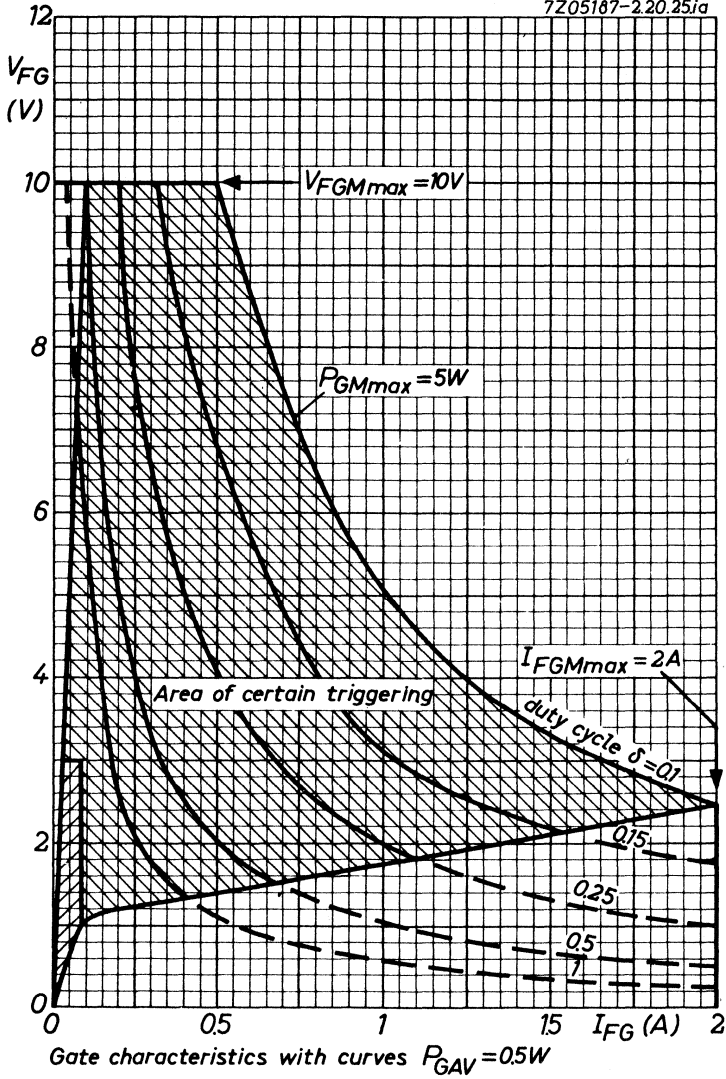


Fig. 7.

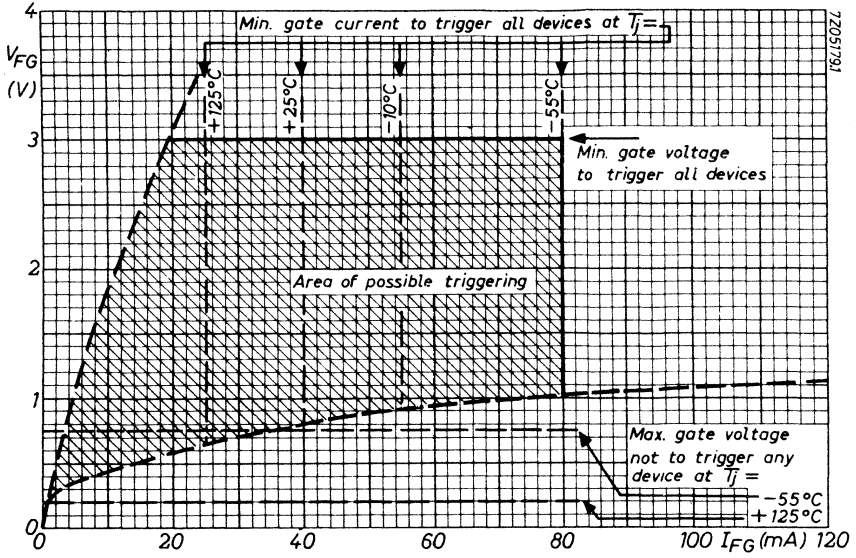


Fig. 8.

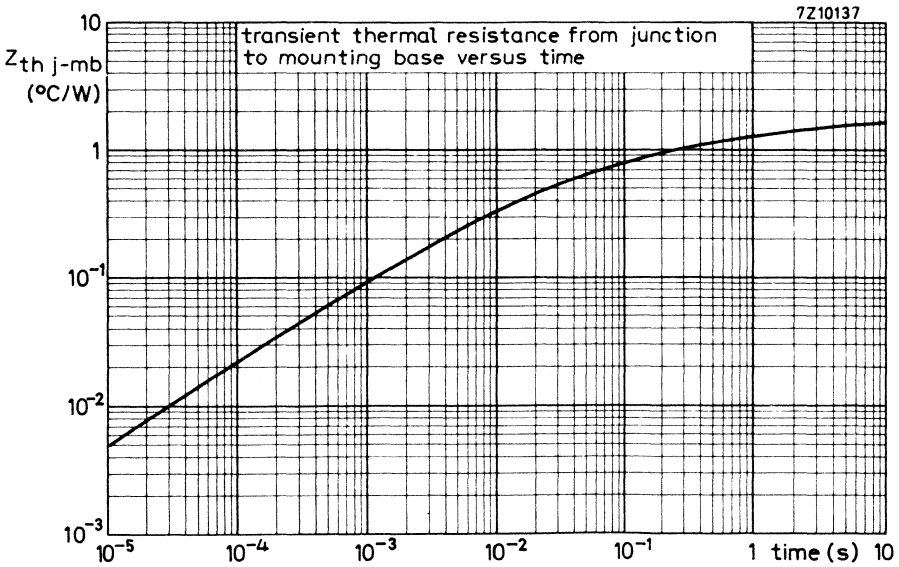


Fig. 9.

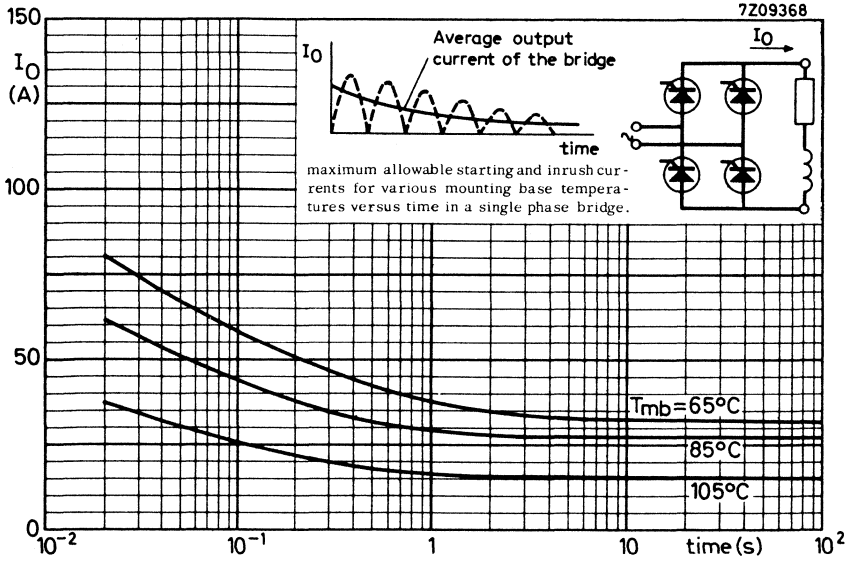


Fig. 10.

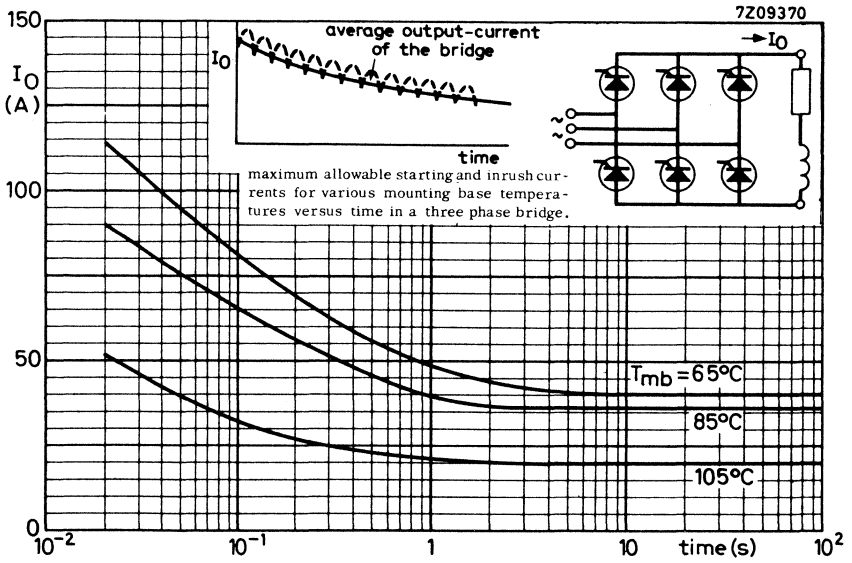


Fig. 11.



# TRIACS

**F**



**F**

## TRIACS

### SWITCHING CHARACTERISTICS

Triacs are not perfect switches. They take a finite time to go from the off to the on-state and vice-versa. At frequencies up to about 400 Hz these effects can often be ignored, but in many applications involving fast switching action the departure from the ideal is important.

#### Gate-controlled turn-on time

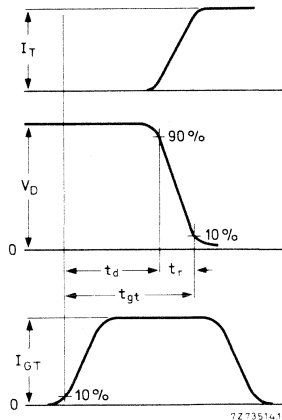
Anode current does not commence flowing at the instant the gate current is applied.

There is a period which elapses between the application of gate current and the onset of anode current known as delay time ( $t_d$ ). The rise time of anode current is known as  $t_r$  and is measured as the time for the anode voltage to fall from 90% to 10% of its initial value.

The conditions which need to be specified are:

- Off-state voltage ( $V_D$ ).
- On-state current ( $I_T$ ).
- Gate trigger current ( $I_G$ ) – high gate currents reduce turn-on time.
- Rate of rise of gate trigger current ( $dI_G/dt$ ) – high values reduce turn-on time.
- Junction temperature ( $T_j$ ) – high temperatures reduce turn-on time.

The waveforms are shown in the following diagram:



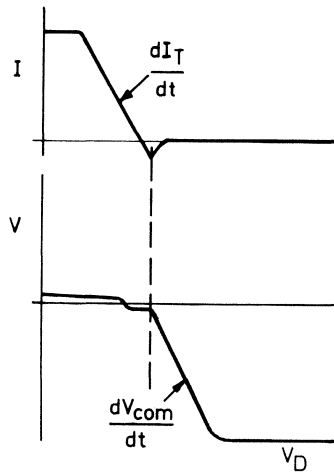
COMMUTATION  $dV_{com}/dt$

When a triac has been conducting current in one direction and is then required to block voltage in the other, it is faced with a difficult task. Reverse recovery current adds to the capacitive current from the reapplied  $dV_D/dt$  in such a fashion that the device's ability to withstand high rates of reapplication of voltage is impaired. For this reason the commutation  $dV_D/dt$  is invariably worse than the static  $dV_D/dt$ .

The conditions which need to be specified are:

- a) R.M.S. current ( $I_T(RMS)$ ) – high currents make commutation harder.
- b) Re-applied off-state voltage ( $V_D$ ), normally  $V_{DRM}$  max. – high voltage will make commutation harder.
- c) Temperature ( $T_j$  or  $T_{mb}$ ) – high temperatures make commutation harder.
- d)  $-di/dt$  – high rates of change make commutation harder.

The waveforms are shown in the following diagram:



## MOUNTING INSTRUCTIONS FOR TO-220 ENVELOPES

## GENERAL DATA AND INSTRUCTIONS FOR HEATSINK OPERATION

**General rules**

1. First fasten the devices to the heatsink before soldering the leads.
2. Use of heatsink compound is recommended.
3. Avoid axial stress to the leads.
4. Keep mounting tool (e.g. screwdriver) clear of the plastic body.
5. It is recommended that the circuit connections be made to the leads rather than direct to the heatsink.

**Heatsink requirements**

Flatness in the mounting area: 0,02 mm maximum per 10 mm.  
Mounting holes must be deburred.

**Heatsink compound**

Values of the thermal resistance from mounting base to heatsink ( $R_{th\ mb-h}$ ) given for mounting with heatsink compound refer to the use of a metallic oxide-loaded compound. The compound should be an electrical insulator and be applied sparingly and evenly to both interfaces. Ordinary silicone grease is not recommended.

For insulated mounting, the compound should be applied to the bottom of both device and insulator.

**Mounting methods for thyristors and triacs**

## 1. Clip mounting.

Mounting by means of spring clip offers:

- a. A good thermal contact under the crystal area, and slightly lower  $R_{th\ mb-h}$  values than screw mounting.
- b. Safe insulation for mains operation.

Recommended force of clip on device is 120 N (12 kgf).

## 2. M3 screw mounting.

Care should be taken to avoid damage to the plastic body. It is therefore recommended that a cross-recess pan-headed screw be used. Do not use self-tapping screws.

Mounting torque for screw mounting:

Minimum torque (for good heat transfer) 0,55 Nm (5,5 kgcm)

Maximum torque (to avoid damaging the device) 0,80 Nm (8,0 kgcm)

N.B.: When a nut or screw is not driven direct against a curved spring washer or lock washer, the torques are as follows:

Minimum torque (for good heat transfer) 0,4 Nm (4 kgcm)

Maximum torque (to avoid damaging the device) 0,6 Nm (6 kgcm)

N.B.: Data on accessories are given in separate data sheets.

## 3. Rivet mounting (only possible for non-insulated mounting)

Devices may be rivetted to flat heatsinks; such a process **must neither** deform the mounting tab, **nor** enlarge the mounting hole.

GENERAL DATA AND INSTRUCTIONS FOR HEATSINK OPERATION (continued)

**Thermal data**

	clip mounting	screw mounting
Thermal resistance from mounting base to heatsink with heatsink compound, direct mounting	$R_{th\ mb-h} = 0,3$	$0,5\ ^\circ C/W$
without heatsink compound, direct mounting	$R_{th\ mb-h} = 1,4$	$1,4\ ^\circ C/W$
with heatsink compound and mica insulator 56369	$R_{th\ mb-h} = 2,2$	— $^\circ C/W$
with heatsink compound and alumina insulator 56367	$R_{th\ mb-h} = 0,8$	— $^\circ C/W$

**Lead bending**

Maximum permissible tensile force on the body, for 5 seconds is 5 N (0,5 kgf).

The leads can be bent through 90° maximum, twisted or straightened. To keep forces within the above-mentioned limits, the leads are generally clamped near the body. The leads should neither be bent nor twisted less than 2,4 mm from the body.

**Soldering**

Lead soldering temperature at 4,7 mm from the body;  $t_{sld} < 5\ s$ :  $T_{sld\ max} = 275\ ^\circ C$ .

Avoid any force on body and leads during or after soldering; do not move the device or leads after soldering.

It is not permitted to solder the metal tab of the device to a heatsink, otherwise its junction temperature rating will be exceeded.

## INSTRUCTIONS FOR CLIP MOUNTING (TO-220 envelopes)

## Direct mounting with clip 56363

1. Place the device on the heatsink, applying heatsink compound to the mounting base.
2. Push the short end of the clip into the narrow slot in the heatsink with the clip at an angle of  $10^\circ$  to  $30^\circ$  to the vertical (see Fig. 1).
3. Push down the clip over the device until the long end of the clip snaps into the wide slot in the heatsink. The clip should bear on the plastic body, not on the tab (see Fig. 1(c)).

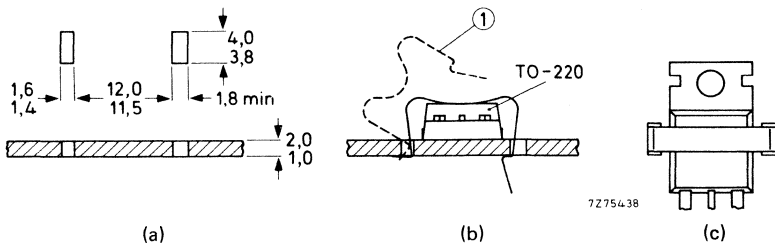


Fig. 1 (a) Heatsink requirements; (b) mounting (1 = spring clip); (c) position of the device (top view).

## Insulated mounting with clip 56364

With the insulators 56367 or 56369 insulation up to 2 kV is obtained.

1. Place the device with the insulator on the heatsink, applying heatsink compound to the bottom of both device and insulator.
2. Push the short end of the clip into the narrow slot in the heatsink with the clip at an angle of  $10^\circ$  to  $30^\circ$  to the vertical (see Fig. 2).
3. Push down the clip over the device until the long end of the clip snaps into the wide slot in the heatsink. The clip should bear on the plastic body, not on the tab (see Fig. 2(c)). There should be minimum 3 mm distance between the device and the edge of the insulator for adequate creepage.

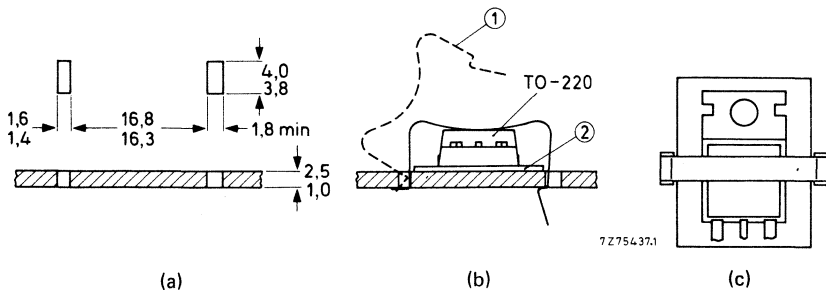
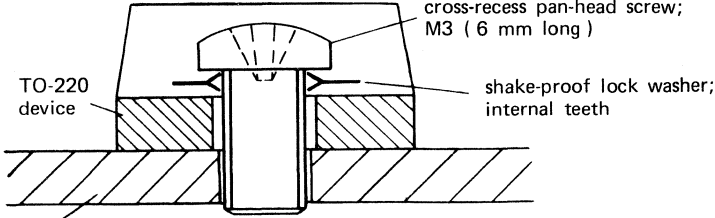


Fig. 2 (a) Heatsink requirements; (b) mounting (1 = spring clip, 2 = insulator 56369 or 56367); (c) position of the device (top view).

INSTRUCTIONS FOR SCREW MOUNTING (TO-220 envelopes)

Direct mounting with screw

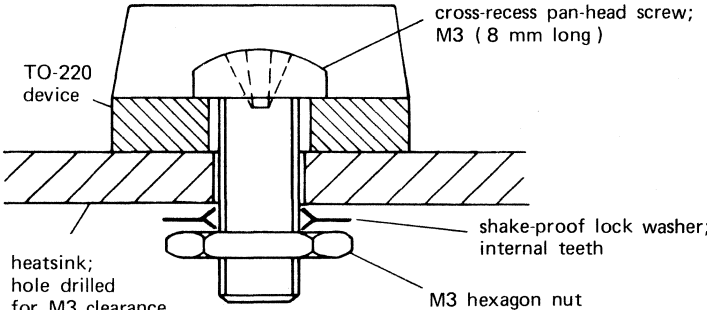
- into tapped heatsink



heatsink; hole drilled 2,70 mm dia

D7509A

- through heatsink with nut



D7510A



## MOUNTING CONSIDERATIONS FOR STUD-MOUNTED TRIACS

Losses generated in a silicon device must flow through the case and to a lesser extent the leads.

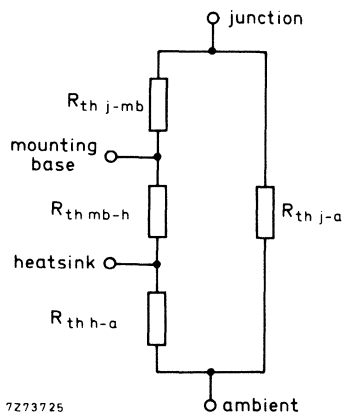
The greatest proportion of the losses flow out through the case into a heat exchanger which can be either free convection cooled, forced convection or even liquid cooled. For the majority of devices in our range natural convection is generally adequate, however, where other considerations such as space saving must be taken into account then methods such as forced convection etc. can be considered.

The thermal path from junction to ambient may be considered as a number of resistances in series.

The first thermal resistance will be that of junction to mounting base, usually denoted by  $R_{th\ j-mb}$ . The second is the contact thermal resistance  $R_{th\ mb-h}$  and finally there is the thermal resistance of the heatsink  $R_{th\ h-a}$ .

In the rating curves, the contact thermal resistance and heatsink thermal resistances are combined as a single figure -  $R_{th\ mb-a}$ .

In addition to the steady state thermal conditions of the system, consideration should also be given to the possibility of any transient thermal excursions. These can be caused for example by starting conditions or overloads and in order to calculate the effect on the device, a graph of transient thermal resistance  $Z_{th\ j-mb}$  as a function of time is given in each data sheet.



When mounting the device on the heatsink, care should be taken that the contact surfaces are free from burrs or projections of any kind and must be thoroughly clean.

In the case where an anodised heatsink is used, the anodising should be removed from the contact surface ensuring good electrical and thermal contact.

The contact surfaces should be smeared with a metallic oxide-loaded grease to ensure good heat transfer.

Where the device is mounted in a tapped hole, care should be taken that the hole is perpendicular to the surface of the heatsink. When mounting the device to the heatsink, it is essential that a proper torque wrench is used, applying the correct amount of torque as specified in the published data.

Excessive torque can distort the threads of the device and may even cause mechanical stress on the wafer, leading to the possible failure.

Where isolation of the device from the heatsink is required, it is common practice to use a mica washer between contact surfaces, and where a clearance hole is used, a p.t.f.e. insulating bush is inserted. A metallic oxide-loaded heatsink compound should be smeared on all contact surfaces, including the mica washer, to ensure optimum heat transfer. The use of ordinary silicone grease is not recommended.



## TRIACS

Glass-passivated, eutectic-bonded triacs intended for use in applications requiring high bidirectional transient and blocking voltage capability, and high thermal cycling performance with very low thermal resistances, e.g. a.c. power control applications such as lighting, industrial and domestic heating, motor control and switching systems.

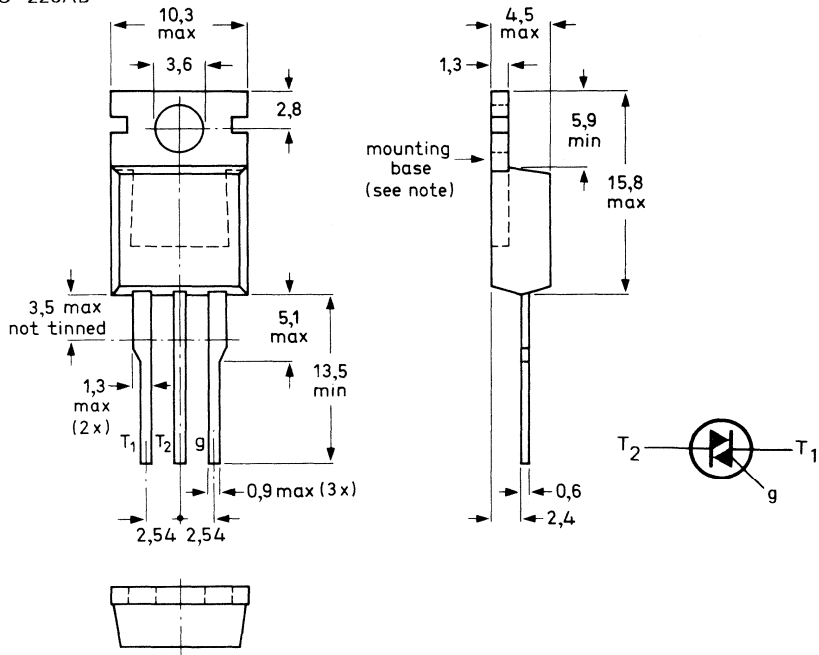
## QUICK REFERENCE DATA

		BT136-500		600	
		max.	500	600	
Repetitive peak off-state voltage	$V_{DRM}$	max.	500	600	V
R.M.S. on-state current	$I_T(RMS)$	max.	4		A
Non-repetitive peak on-state current	$I_{TSM}$	max.	25		A

## MECHANICAL DATA

Dimensions in mm

Fig.1 TO-220AB



Net mass: 2 g

Note: The exposed metal mounting base is directly connected to terminal T<sub>2</sub>.

Supplied on request: accessories (see data sheets Mounting instructions and accessories for TO-220 envelopes)

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

### Voltages (in either direction)

		BT136-500		600	
Non-repetitive peak off-state voltage ( $t \leq 10$ ms)	$V_{DSM}$ max.	500	600	V*	
Repetitive peak off-state voltage ( $\delta \leq 0.01$ )	$V_{DRM}$ max.	500	600	V	
Crest working off-state voltage	$V_{DWM}$ max.	400	400	V	

### Currents (in either direction)

R.M.S. on-state current (conduction angle $360^\circ$ ) up to $T_{mb} = 102^\circ\text{C}$	$I_{T(RMS)}$ max.	4	A
Average on-state current for half-cycle operation (averaged over any 20 ms period) up to $T_{mb} = 92^\circ\text{C}$	$I_{T(AV)}$ max.	2.5	A
Repetitive peak on-state current	$I_{TRM}$ max.	25	A
Non-repetitive peak on-state current; $T_j = 120^\circ\text{C}$ prior to surge; $t = 20$ ms; full sine-wave	$I_{TSM}$ max.	25	A
$I^2 t$ for fusing ( $t = 10$ ms)	$I^2 t$ max.	4	$\text{A}^2\text{s}$
Rate of rise of on-state current after triggering with $I_G = 200$ mA to $I_T = 6$ A; $dI_G/dt = 0.2$ A/ $\mu\text{s}$	$dI_T/dt$ max.	10	A/ $\mu\text{s}$

Gate to terminal 1

## POWER DISSIPATION

Average power dissipation (averaged over any 20 ms period)	$P_{G(AV)}$ max.	0.5	W
Peak power dissipation	$P_{GM}$ max.	5	W

## Temperatures

Storage temperature	$T_{stg}$	-40 to +125	$^\circ\text{C}$
Operating junction temperature full-cycle operation	$T_j$ max.	120	$^\circ\text{C}$
half-cycle operation	$T_j$ max.	110	$^\circ\text{C}$

\*Although not recommended, off-state voltages up to 800 V may be applied without damage, but the triac may switch into the on-state. The rate of rise of on-state current should not exceed 3 A/ $\mu\text{s}$ .

**THERMAL RESISTANCE**

From junction to mounting base

full-cycle operation

half-cycle operation

$$R_{th\ j-mb} = 3.0\ ^\circ\text{C/W}$$

$$R_{th\ j-mb} = 3.7\ ^\circ\text{C/W}$$

Transient thermal impedance;  $t = 1\ \text{ms}$ 

$$Z_{th\ j-mb} = 0.6\ ^\circ\text{C/W}$$

**Influence of mounting method**

1. Heatsink mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound

$$R_{th\ mb-h} = 0.3\ ^\circ\text{C/W}$$

b. with heatsink compound and 0.06 mm maximum mica insulator

$$R_{th\ mb-h} = 1.4\ ^\circ\text{C/W}$$

c. with heatsink compound and 0.1 mm max. mica insulator (56369)

$$R_{th\ mb-h} = 2.2\ ^\circ\text{C/W}$$

d. with heatsink compound and 0.25 mm max. alumina insulator (56367)

$$R_{th\ mb-h} = 0.8\ ^\circ\text{C/W}$$

e. without heatsink compound

$$R_{th\ mb-h} = 1.4\ ^\circ\text{C/W}$$

2. Free-air operation

The quoted value of  $R_{th\ j-a}$  should be used only when no leads of other dissipating components run to the same tie-point.

Thermal resistance from junction to ambient in free air:

mounted on a printed-circuit board at  $a =$  any lead length

$$R_{th\ j-a} = 60\ ^\circ\text{C/W}$$

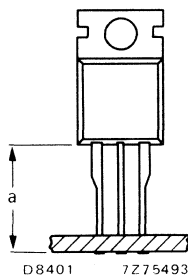


Fig.2.

**Notes**

1. Values of  $R_{th\ mb-h}$  given for mounting with heatsink compound refer to the use of a zinc-oxide-loaded compound. Ordinary silicone grease is not recommended.
2. Mounting by means of a spring clip is the best mounting method because it offers:
  - a. a good thermal contact under the crystal area and slightly lower  $R_{th\ mb-h}$  values than screw mounting.
  - b. safe isolation for mains operation.

**CHARACTERISTICS**

Polarities, positive or negative, are identified with respect to T<sub>1</sub>.

**Voltages and currents** (in either direction)

On-state voltage (Note 1)

$$I_T = 5 \text{ A}; T_j = 25 \text{ }^\circ\text{C} \qquad V_T < 1.70 \text{ V}$$

Rate of rise of off-state voltage that will not trigger any device; T<sub>j</sub> = 120 °C; see also Figs.9 and 10; gate open circuit

$$dV_D/dt < 50 \text{ V}/\mu\text{s}$$

Rate of rise of commutating voltage that will not trigger any device; I<sub>T(RMS)</sub> = 4 A; V<sub>D</sub> = V<sub>DWM max</sub>; T<sub>j</sub> = 120 °C; gate open circuit; see also Figs. 9 and 10

BT136 series	-dI <sub>T</sub> /dt = 2.5 A/ms	} dV <sub>com</sub> /dt < 6 V/μs
BT136 series F	-dI <sub>T</sub> /dt = 2.5 A/ms	
BT136 series E	-dI <sub>T</sub> /dt = 1.25 A/ms	

Off-state current

$$V_D = V_{DWM \text{ max}}; T_j = 120 \text{ }^\circ\text{C} \qquad I_D < 0.5 \text{ mA}$$

Holding current; T<sub>j</sub> = 25 °C

$$T_2 \text{ and G positive or negative} \qquad I_H < 15 \text{ mA}$$

Gate voltage and current that will trigger all devices

Latching current

$$V_D = 12 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$$

		T <sub>2</sub> <sup>+</sup> G <sup>+</sup>	T <sub>2</sub> <sup>+</sup> G <sup>-</sup>	T <sub>2</sub> <sup>-</sup> G <sup>-</sup>	T <sub>2</sub> <sup>-</sup> G <sup>+</sup>
BT136 series	G to T <sub>1</sub>	$\left\{ \begin{array}{l} V_{GT} > 1.5 \\ I_{GT} > 35 \\ I_L < 20 \end{array} \right.$	1.5 35 30	1.5 35 20	1.5 V 70 mA 30 mA
BT136 series F e.g. BT136-500F	G to T <sub>1</sub>	$\left\{ \begin{array}{l} V_{GT} > 1.5 \\ I_{GT} > 25 \\ I_L < 20 \end{array} \right.$	1.5 25 30	1.5 25 20	1.5 V 70 mA 30 mA
BT136 series E	G to T <sub>1</sub>	$\left\{ \begin{array}{l} V_{GT} > 1.5 \\ I_{GT} > 15 \\ I_L < 20 \end{array} \right.$	1.5 15 20	1.5 15 20	1.5 V 50 mA 20 mA
BT136 series D (Note 2)	G to T <sub>1</sub>	$\left\{ \begin{array}{l} V_{GT} > 1.5 \\ I_{GT} > 8 \\ I_L < 15 \end{array} \right.$	1.5 8 20	1.5 8 15	** V ** mA ** mA

*Gate to terminal 1*

Voltage that will not trigger any device V<sub>D</sub> = V<sub>DRM max</sub>;

$$T_j = 120 \text{ }^\circ\text{C}; T_2 \text{ and G positive or negative} \qquad V_{GD} < 250 \text{ mV}$$

Note 1. Measured under pulse conditions to avoid excessive dissipation.

Note 2. A version with I<sub>GT</sub> = 5 mA max. is available on request.

\*\*Triggerable

### MOUNTING INSTRUCTIONS

1. The triac may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; it must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
2. The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending.
3. It is recommended that the circuit connection be made to tag T<sub>2</sub>, rather than direct to the heatsink.
4. Clip mounting offers lower thermal resistance than screw mounting. However, if a screw is used, it should be M3. Care should be taken to avoid damage to the plastic body.
5. The device should not be pop-riveted to the heatsink. However, it is permissible to press-rivet providing that rivets of soft material are used, and the press forces are slowly and carefully controlled so as to avoid shock and deformation of either heatsink or mounting tab.

### OPERATING NOTES

Dissipation and heatsink considerations:

- a. The various components of junction temperature rise above ambient are illustrated in Fig.3.

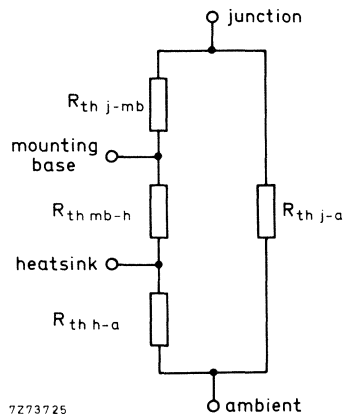


Fig.3

- b. The method of using Figs 4 and 5 is as follows:

Starting with the required current on the  $I_T(AV)$  or  $I_T(RMS)$  axis, trace upwards to meet the appropriate form factor or conduction angle curve. Trace right horizontally and upwards from the appropriate value on the  $T_{amb}$  scale. The intersection determines the  $R_{th mb-a}$ . The heatsink thermal resistance value ( $R_{th h-a}$ ) can now be calculated from:

$$R_{th h-a} = R_{th mb-a} - R_{th mb-h}$$

- c. Any measurement of heatsink temperature should be made immediately adjacent to the device.

FULL-CYCLE OPERATION

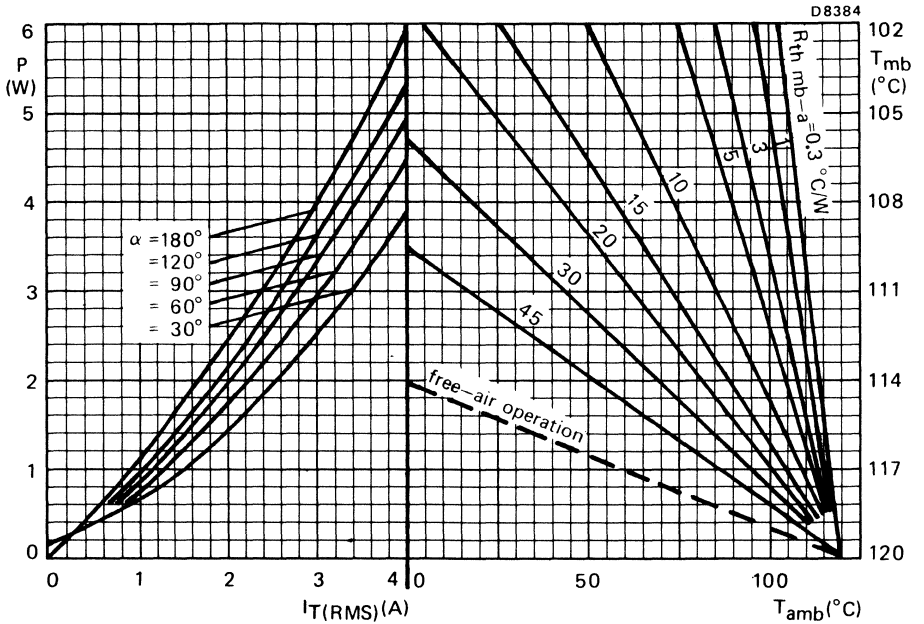
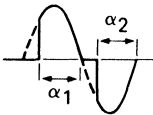


Fig.4 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.



$\alpha = \alpha_1 = \alpha_2$ : conduction angle per half cycle



HALF-CYCLE OPERATION

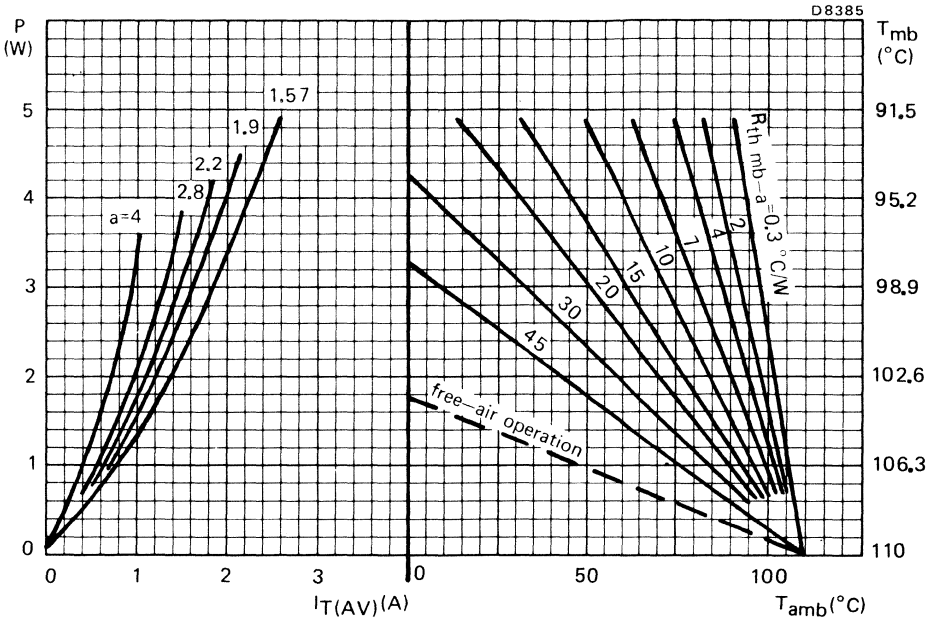


Fig.5 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.



$\alpha$  = conduction angle per half cycle

$$a = \text{form factor} = \frac{I_T(\text{RMS})}{I_T(\text{AV})}$$

$\alpha$	a
30°	4
60°	2.8
90°	2.2
120°	1.9
180°	1.57

OVERLOAD OPERATION

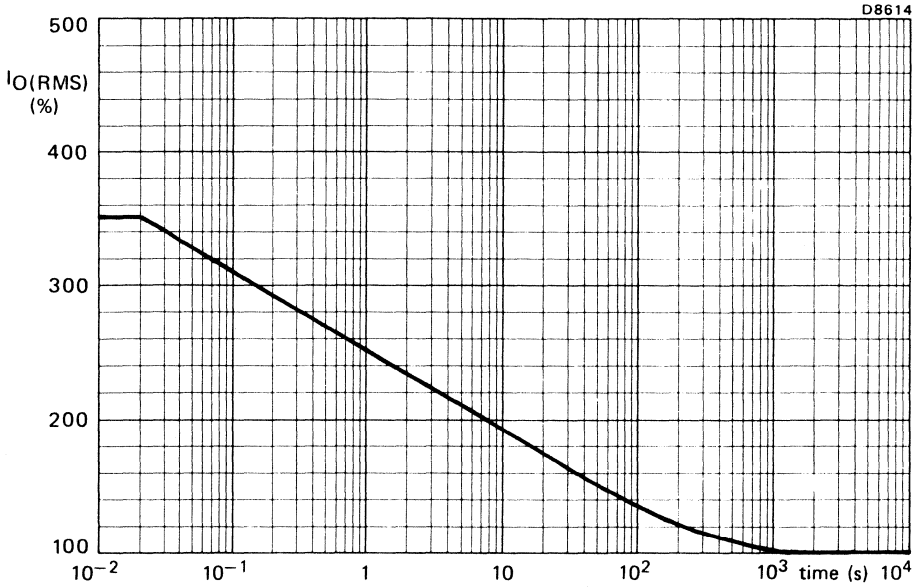


Fig.6 Maximum permissible duration of steady overload (provided that  $T_{mb}$  does not exceed  $120\text{ }^{\circ}\text{C}$  during and after overload) expressed as a percentage of the steady state r.m.s. rated current. For high r.m.s. overload currents precautions should be taken so that the temperature of the terminals does not exceed  $125\text{ }^{\circ}\text{C}$ . During these overload conditions the triac may lose control. Therefore the overload should be terminated by a separate protection device.

D8386

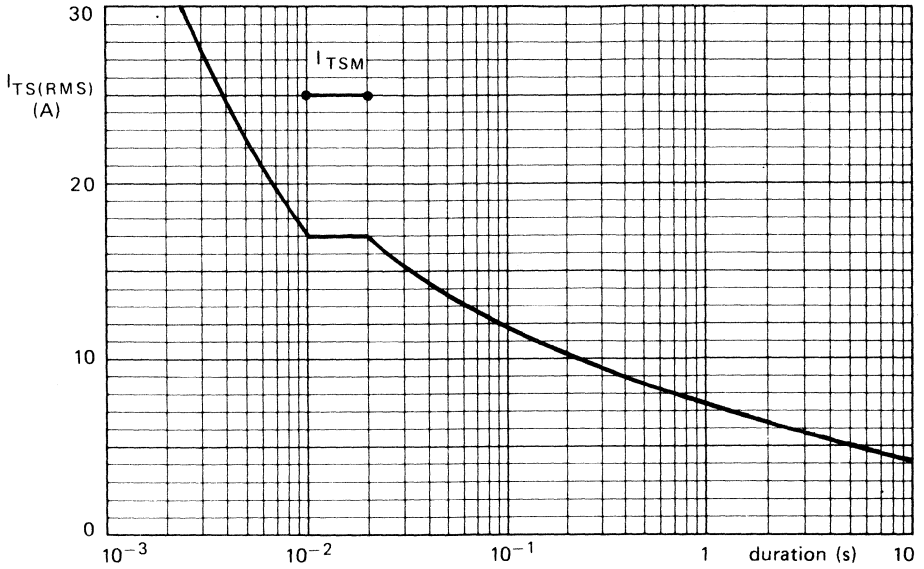


Fig.7 Maximum permissible non-repetitive r.m.s. on-state current based on sinusoidal currents ( $f = 50$  Hz);  $T_j = 120$  °C prior to surge. The triac may temporarily lose control following the surge.

D8387

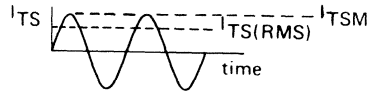
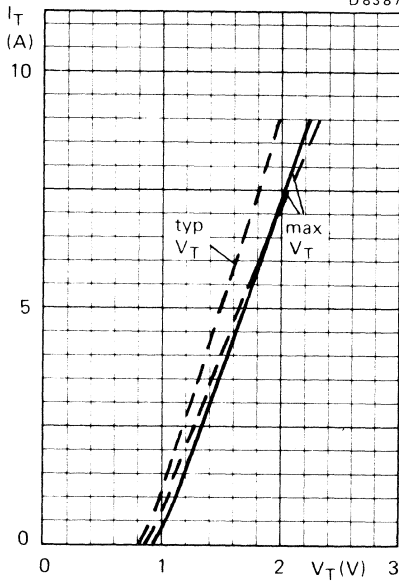


Fig.8 —  $T_j = 25$  °C; - - -  $T_j = 120$  °C

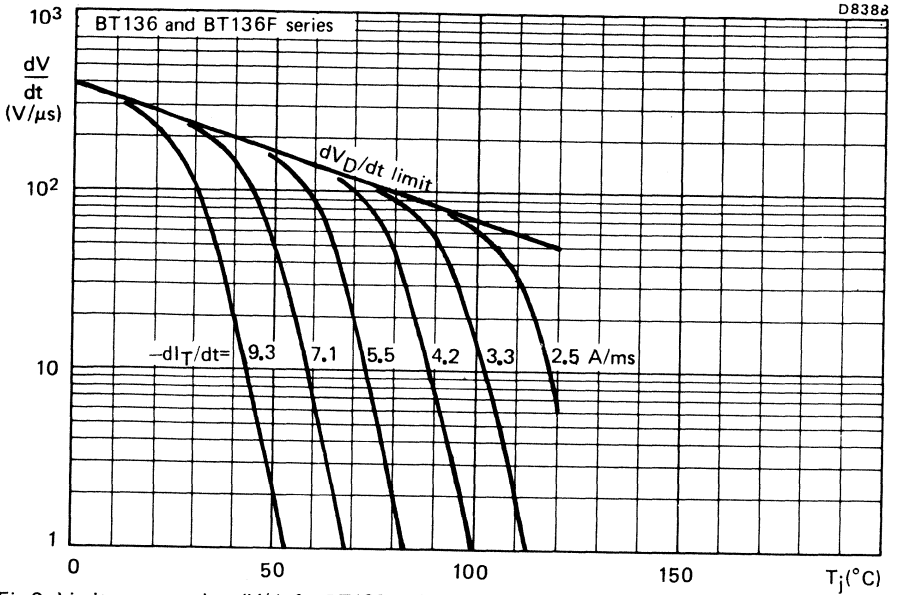


Fig.9 Limit commutation  $dV/dt$  for BT136 and F series versus  $T_j$ . The triac should commute when the  $dV/dt$  is below the value on the appropriate curve for pre-commutation  $dI_T/dt$ .

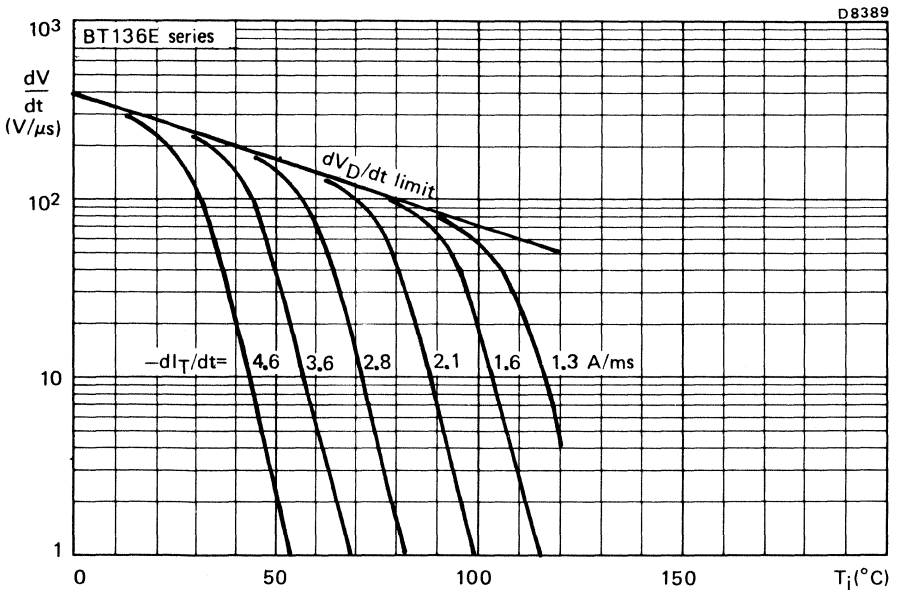


Fig.10 Limit commutation  $dV/dt$  for BT136E series versus  $T_j$ . The triac should commute when the  $dV/dt$  is below the value on the appropriate curve for pre-commutation  $dI_T/dt$ .

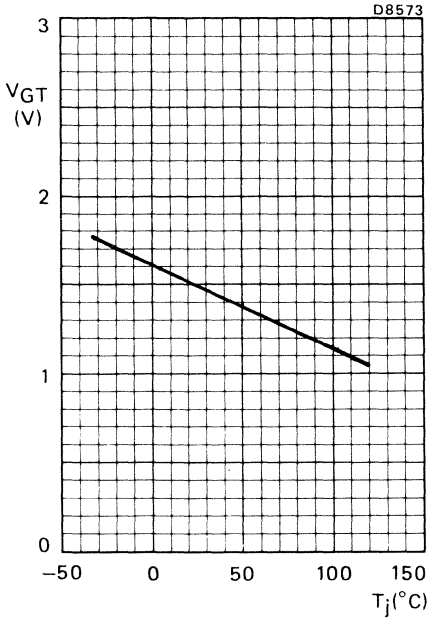


Fig.11 Minimum gate voltage that will trigger all devices; all conditions

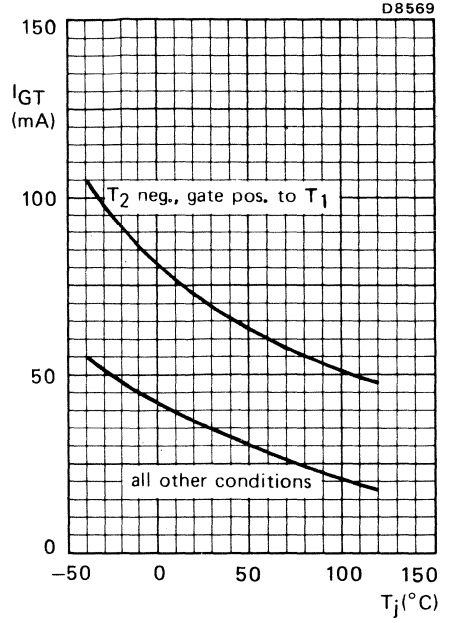


Fig.12 Minimum gate current that will trigger all devices

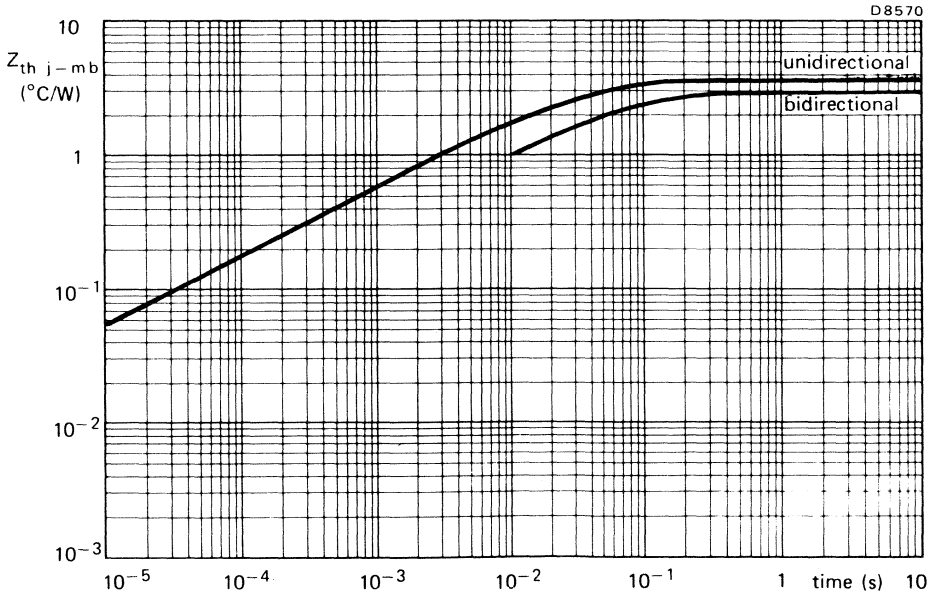


Fig.13



TRIACS

Glass-passivated, eutectic-bonded triacs intended for use in applications requiring high bidirectional transient and blocking voltage capability, and high thermal cycling performance with very low thermal resistances, e.g. a.c. power control applications such as lighting, industrial and domestic heating and motor control and switching systems.

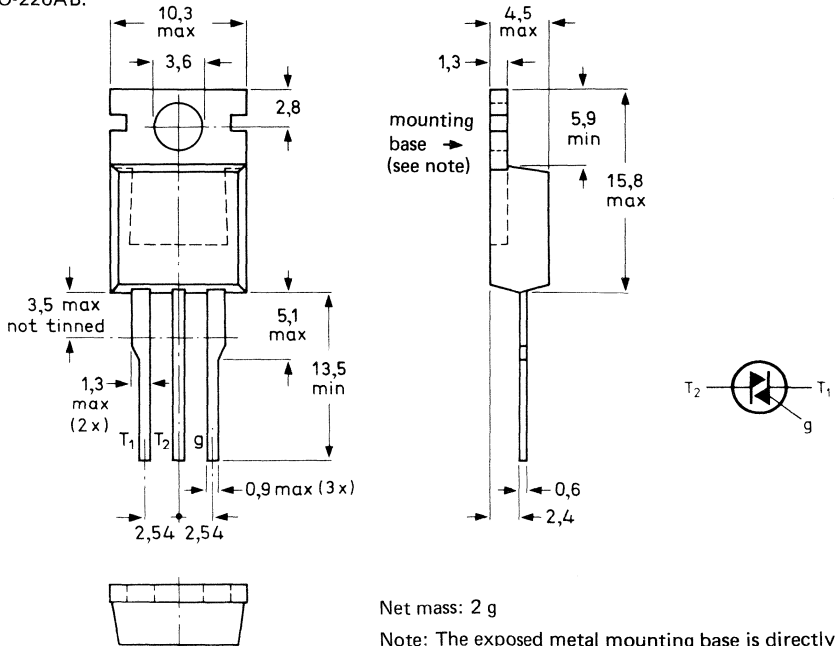
QUICK REFERENCE DATA

	BT137-500   600	
Repetitive peak off-state voltage	$V_{DRM}$ max.	500   600 V
R.M.S. on-state current	$I_{T(RMS)}$ max.	8 A
Non-repetitive peak on-state current	$I_{TSM}$ max.	55 A

MECHANICAL DATA

Dimensions in mm

Fig. 1 TO-220AB.



Net mass: 2 g

Note: The exposed metal mounting base is directly connected to terminal T<sub>2</sub>.

Supplied on request: accessories (see data sheets Mounting instructions and accessories for TO-220 envelopes)

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

### Voltages (in either direction)

		BT137-500	600
Non-repetitive peak off-state voltage ( $t \leq 10$ ms)	$V_{DSM}$	max. 500	600 V*
Repetitive peak off-state voltage ( $\delta \leq 0,01$ )	$V_{DRM}$	max. 500	600 V
Crest working off-state voltage	$V_{DWM}$	max. 400	400 V

### → Currents (in either direction)

R.M.S. on-state current (conduction angle $360^\circ$ ) up to $T_{mb} = 97^\circ\text{C}$	$I_T(\text{RMS})$	max.	8 A
Average on-state current for half-cycle operation (averaged over any 20 ms period) up to $T_{mb} = 87^\circ\text{C}$	$I_T(\text{AV})$	max.	5 A
Repetitive peak on-state current	$I_{TRM}$	max.	55 A
Non-repetitive peak on-state current; $T_j = 120^\circ\text{C}$ prior to surge; $t = 20$ ms; full sine-wave	$I_{TSM}$	max.	55 A
$I^2 t$ for fusing ( $t = 10$ ms)	$I^2 t$	max.	15 A <sup>2</sup> s
Rate of rise of on-state current after triggering with $I_G = 200$ mA to $I_T = 12$ A; $dI_G/dt = 0,2$ A/ $\mu\text{s}$	$dI_T/dt$	max.	20 A/ $\mu\text{s}$

*Gate to terminal 1*

### POWER DISSIPATION

Average power dissipation (averaged over any 20 ms period)	$P_{G(\text{AV})}$	max.	0,5 W
Peak power dissipation	$P_{GM}$	max.	5 W

### Temperatures

Storage temperature	$T_{stg}$		-40 to +125 °C
→ Operating junction temperature			
full-cycle operation	$T_j$	max.	120 °C
half-cycle operation	$T_j$	max.	110 °C

\* Although not recommended, off-state voltages up to 800 V may be applied without damage, but the triac may switch into the on-state. The rate of rise of on-state current should not exceed 6 A/ $\mu\text{s}$ .



**THERMAL RESISTANCE**

From junction to mounting base

- full-cycle operation
- half-cycle operation

$R_{th\ j-mb} = 2,0\ ^\circ C/W$

$R_{th\ j-mb} = 2,4\ ^\circ C/W$

Transient thermal impedance;  $t = 1\ ms$ 

$Z_{th\ j-mb} = 0,3\ ^\circ C/W$

**Influence of mounting method**

1. Heatsink mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound

$R_{th\ mb-h} = 0,3\ ^\circ C/W$

b. with heatsink compound and 0,06 mm maximum mica insulator

$R_{th\ mb-h} = 1,4\ ^\circ C/W$

c. with heatsink compound and 0,1 mm max. mica insulator (56369)

$R_{th\ mb-h} = 2,2\ ^\circ C/W$

d. with heatsink compound and 0,25 mm max. alumina insulator (56367)

$R_{th\ mb-h} = 0,8\ ^\circ C/W$

e. without heatsink compound

$R_{th\ mb-h} = 1,4\ ^\circ C/W$

2. Free-air operation

The quoted values of  $R_{th\ j-a}$  should be used only when no leads of other dissipating components run to the same tie-point.Thermal resistance from junction to ambient in free air:  
mounted on a printed-circuit board at  $a =$  any lead length

$R_{th\ j-a} = 60\ ^\circ C/W$

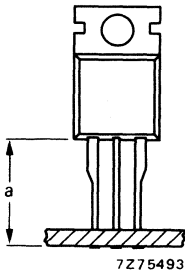


Fig. 2.

## CHARACTERISTICS

Polarities, positive or negative, are identified with respect to T<sub>1</sub>.

**Voltages and currents** (in either direction)

On-state voltage (Note 1)

$$I_T = 10 \text{ A}; T_j = 25 \text{ }^\circ\text{C} \quad V_T < 1,65 \text{ V}$$

Rate of rise of off-state voltage that will not trigger any device; T<sub>j</sub> = 120 °C; see also Figs. 9 and 10; gate open circuit

$$dV_D/dt < 50 \text{ V}/\mu\text{s}$$

Rate of rise of commutating voltage that will not trigger any device;

$$I_T(\text{RMS}) = 8 \text{ A}; V_D = V_{DWM} \text{ max};$$

$$T_j = 120 \text{ }^\circ\text{C}; \text{ gate open circuit; see also Figs. 9 and 10}$$

$$\text{BT137 series} \quad -di_T/dt = 4,2 \text{ A/ms}$$

$$\text{BT137 series F} \quad -di_T/dt = 4,2 \text{ A/ms}$$

$$\text{BT137 series E} \quad -di_T/dt = 2,1 \text{ A/ms}$$

$$dV_{com}/dt < 6 \text{ V}/\mu\text{s}$$

Off-state current

$$V_D = V_{DWM} \text{ max}; T_j = 120 \text{ }^\circ\text{C} \quad I_D < 0,5 \text{ mA}$$

Holding current; T<sub>j</sub> = 25 °C

$$T_2 \text{ and G positive or negative} \quad \begin{array}{l} \text{BT137, F and E series} \\ \text{BT137 D series} \end{array} \quad \begin{array}{l} I_H < 20 \text{ mA} \\ I_H < 15 \text{ mA} \end{array}$$

Gate voltage and current that will trigger all devices

Latching current

$$V_D = 12 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$$

		T <sub>2</sub> <sup>+</sup> G <sup>+</sup>	T <sub>2</sub> <sup>+</sup> G <sup>-</sup>	T <sub>2</sub> <sup>-</sup> G <sup>-</sup>	T <sub>2</sub> <sup>-</sup> G <sup>+</sup>	
BT137 series	G to T <sub>1</sub>	$\begin{array}{l} V_{GT} > 1,5 \\ I_{GT} > 35 \\ I_L < 30 \end{array}$	$\begin{array}{l} 1,5 \\ 35 \\ 45 \end{array}$	$\begin{array}{l} 1,5 \\ 35 \\ 30 \end{array}$	$\begin{array}{l} 1,5 \\ 70 \\ 30 \end{array}$	$\begin{array}{l} \text{V} \\ \text{mA} \\ \text{mA} \end{array}$
BT137 series F e.g. BT137-500F	G to T <sub>1</sub>	$\begin{array}{l} V_{GT} > 1,5 \\ I_{GT} > 25 \\ I_L < 30 \end{array}$	$\begin{array}{l} 1,5 \\ 25 \\ 45 \end{array}$	$\begin{array}{l} 1,5 \\ 25 \\ 30 \end{array}$	$\begin{array}{l} 1,5 \\ 70 \\ 30 \end{array}$	$\begin{array}{l} \text{V} \\ \text{mA} \\ \text{mA} \end{array}$
BT137 series E	G to T <sub>1</sub>	$\begin{array}{l} V_{GT} > 1,5 \\ I_{GT} > 15 \\ I_L < 25 \end{array}$	$\begin{array}{l} 1,5 \\ 15 \\ 35 \end{array}$	$\begin{array}{l} 1,5 \\ 15 \\ 25 \end{array}$	$\begin{array}{l} 1,5 \\ 50 \\ 25 \end{array}$	$\begin{array}{l} \text{V} \\ \text{mA} \\ \text{mA} \end{array}$
BT137 series D (Note 2)	G to T <sub>1</sub>	$\begin{array}{l} V_{GT} > 1,5 \\ I_{GT} > 8 \\ I_L < 15 \end{array}$	$\begin{array}{l} 1,5 \\ 8 \\ 20 \end{array}$	$\begin{array}{l} 1,5 \\ 8 \\ 15 \end{array}$	$\begin{array}{l} ** \\ ** \\ ** \end{array}$	$\begin{array}{l} \text{V} \\ \text{mA} \\ \text{mA} \end{array}$

*Gate to terminal 1*

Voltage that will not trigger any device V<sub>D</sub> = V<sub>DRM</sub> max;

$$T_j = 120 \text{ }^\circ\text{C}; T_2 \text{ and G positive or negative} \quad V_{GD} < 250 \text{ mV}$$

Note 1. Measured under pulse conditions to avoid excessive dissipation.

Note 2. A version with I<sub>GT</sub> = 5 mA max. is available on request.

\*\* Triggerable

### MOUNTING INSTRUCTIONS

1. The triac may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; it must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4,7 mm from the seal.
2. The leads should not be bent less than 2,4 mm from the seal, and should be supported during bending.
3. It is recommended that the circuit connection be made to tag T<sub>2</sub>, rather than direct to the heatsink.
4. Mounting by means of a spring clip is the best mounting method because it offers:
  - a. a good thermal contact under the crystal area and slightly lower R<sub>th mb-h</sub> values than screw mounting.
  - b. safe isolation for mains operation.
 However, if a screw is used, it should be M3 cross-recess pan-head. Care should be taken to avoid damage to the plastic body.
5. For good thermal contact heatsink compound should be used between mounting base and heatsink. Values of R<sub>th mb-h</sub> given for mounting with heatsink compound refer to the use of a metallic-oxide loaded compound. Ordinary silicone grease is not recommended.
6. The device should not be pop-riveted to the heatsink. However, it is permissible to press-rivet providing that rivets of soft material are used, and the press forces are slowly and carefully controlled so as to avoid shock and deformation of either heatsink or mounting tab.

### OPERATING NOTES

Dissipation and heatsink considerations:

- a. The various components of junction temperature rise above ambient are illustrated in Fig. 3.

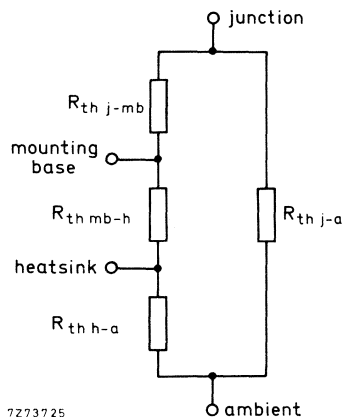


Fig. 3.

- b. The method of using Figs 4 and 5 is as follows:

Starting with the required current on the I<sub>T(AV)</sub> or I<sub>T(RMS)</sub> axis, trace upwards to meet the appropriate form factor or conduction angle curve. Trace right horizontally and upwards from the appropriate value on the T<sub>amb</sub> scale. The intersection determines the R<sub>th mb-a</sub>. The heatsink thermal resistance value (R<sub>th h-a</sub>) can now be calculated from:

$$R_{th h-a} = R_{th mb-a} - R_{th mb-h}$$

- c. Any measurement of heatsink temperature should be made immediately adjacent to the device.

FULL-CYCLE OPERATION

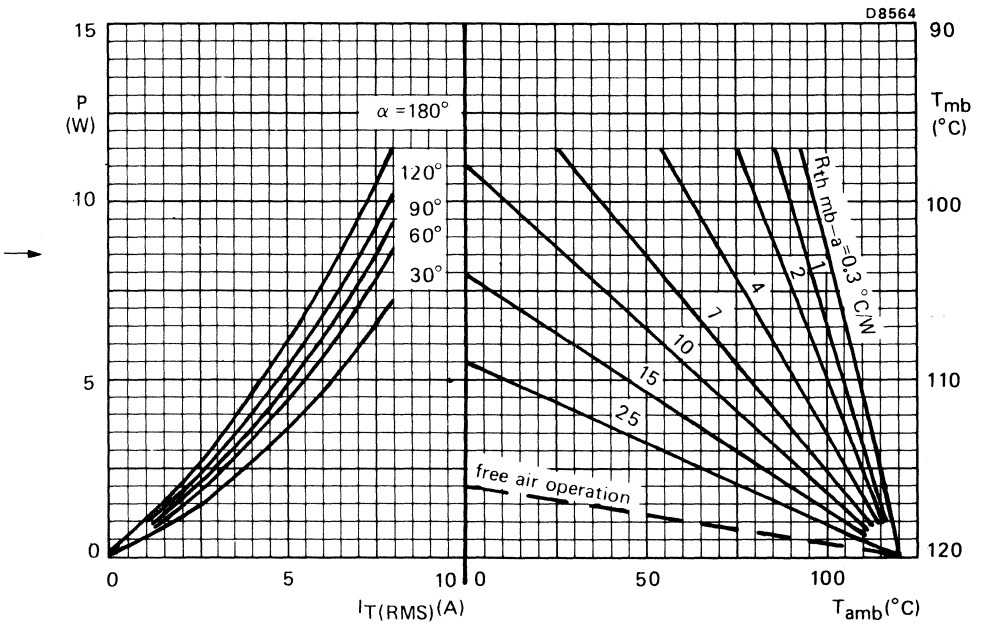
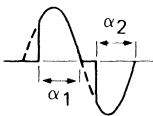


Fig.4 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.



$\alpha = \alpha_1 = \alpha_2$ : conduction angle per half cycle

HALF-CYCLE OPERATION

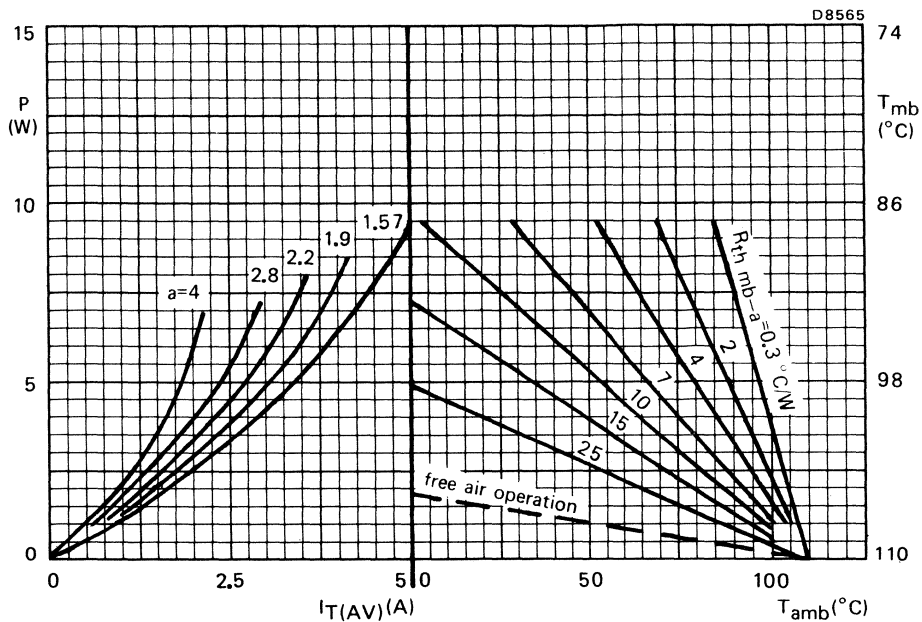


Fig. 5 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.



$\alpha$  = conduction angle per half cycle

$$a = \text{form factor} = \frac{I_T(RMS)}{I_T(AV)}$$

$\alpha$	a
30°	4
60°	2,8
90°	2,2
120°	1,9
180°	1,57

OVERLOAD OPERATION

D8614

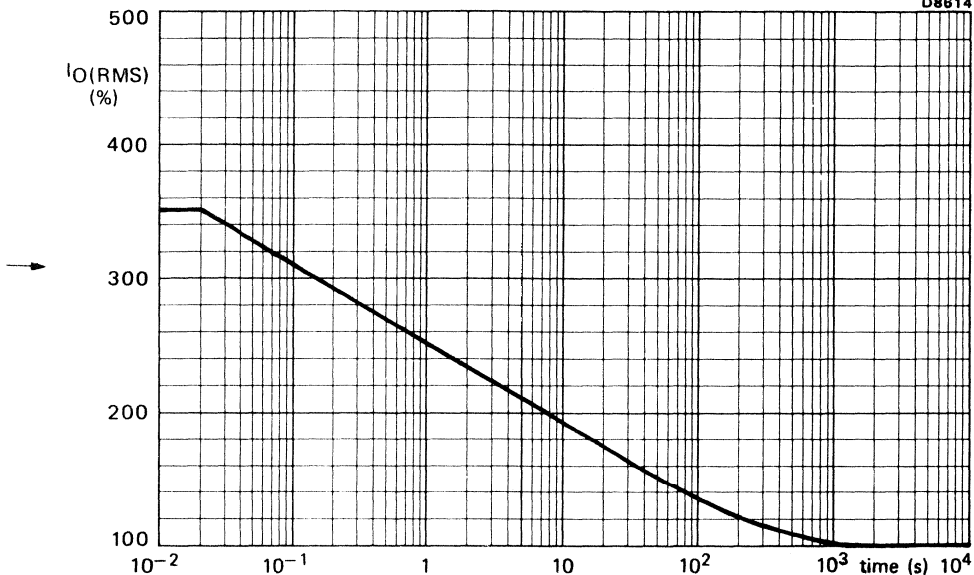


Fig.6 Maximum permissible duration of steady overload (provided that  $T_{mb}$  does not exceed  $120^\circ\text{C}$  during and after overload) expressed as a percentage of the steady state r.m.s. rated current. For high r.m.s. overload currents precautions should be taken so that the temperature of the terminals does not exceed  $125^\circ\text{C}$ . During these overload conditions the triac may lose control. Therefore the overload should be terminated by a separate protection device.

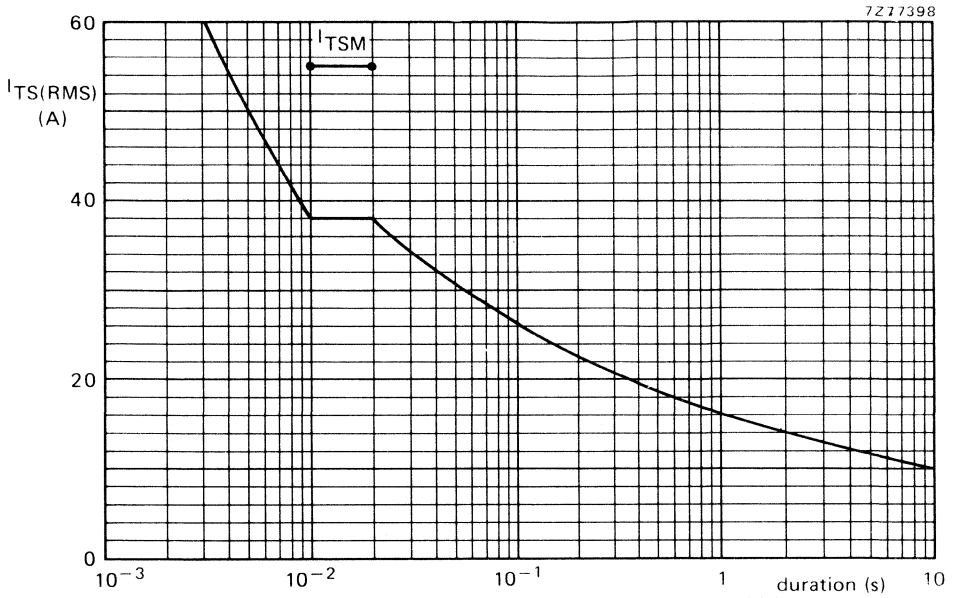


Fig.7 Maximum permissible non-repetitive r.m.s. on-state current based on sinusoidal currents ( $f = 50$  Hz);  $T_j = 120$  °C prior to surge. The triac may temporarily lose control following the surge.

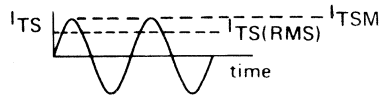
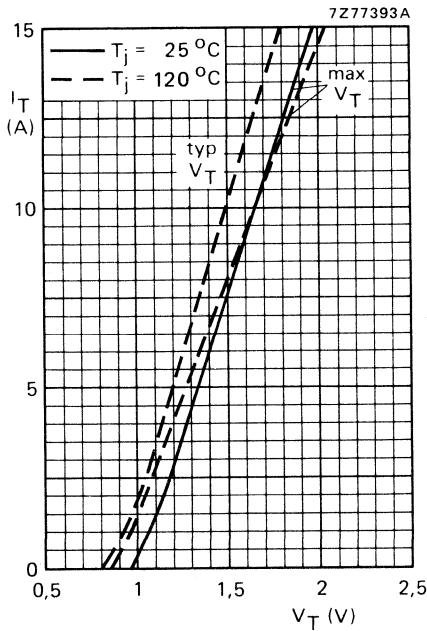
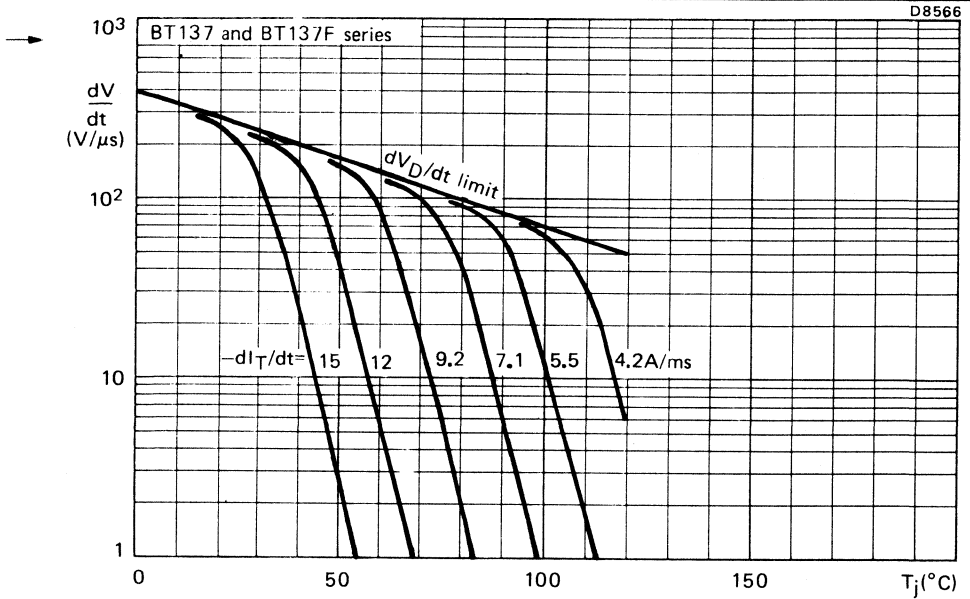
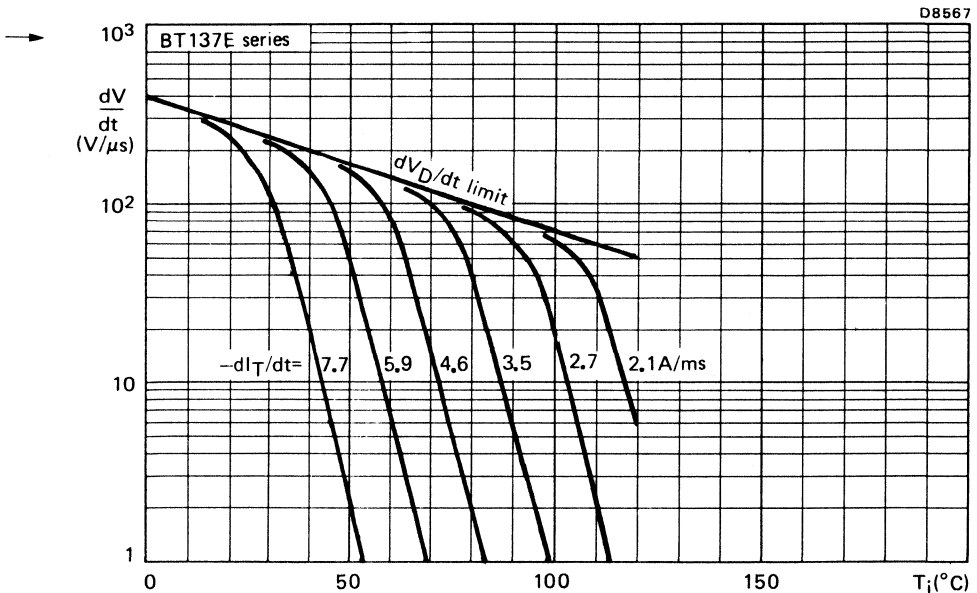


Fig.8



D8566

Fig.9 Limit commutation  $dV/dt$  for BT137 and F series versus  $T_j$ . The triac should commute when the  $dV/dt$  is below the value on the appropriate curve for pre-commutation  $dI_T/dt$ .



D8567

Fig.10 Limit commutation  $dV/dt$  for BT137E series versus  $T_j$ . The triac should commute when the  $dV/dt$  is below the value on the appropriate curve for pre-commutation  $dI_T/dt$ .



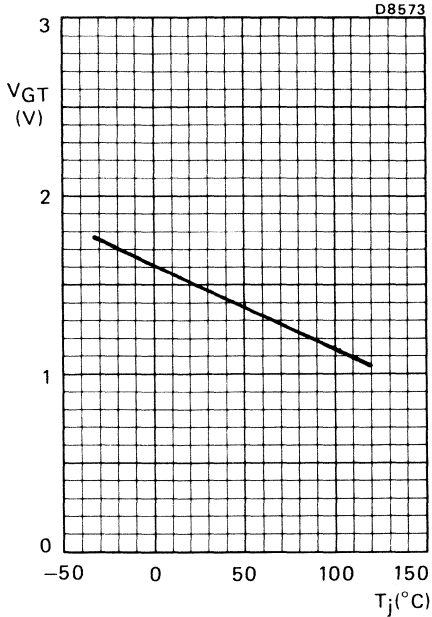


Fig.11 Minimum gate voltage that will trigger all devices; all conditions

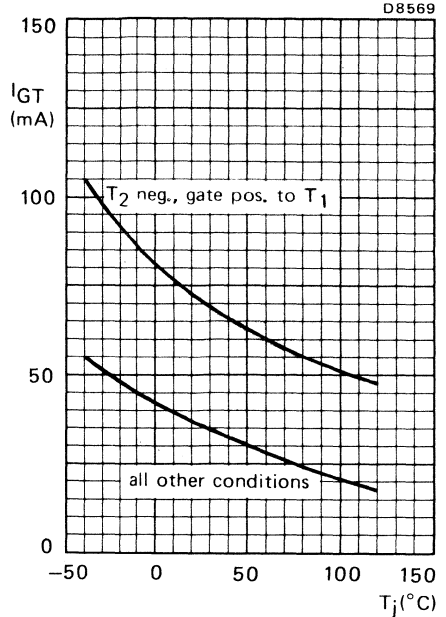


Fig.12 Minimum gate current that will trigger all devices.

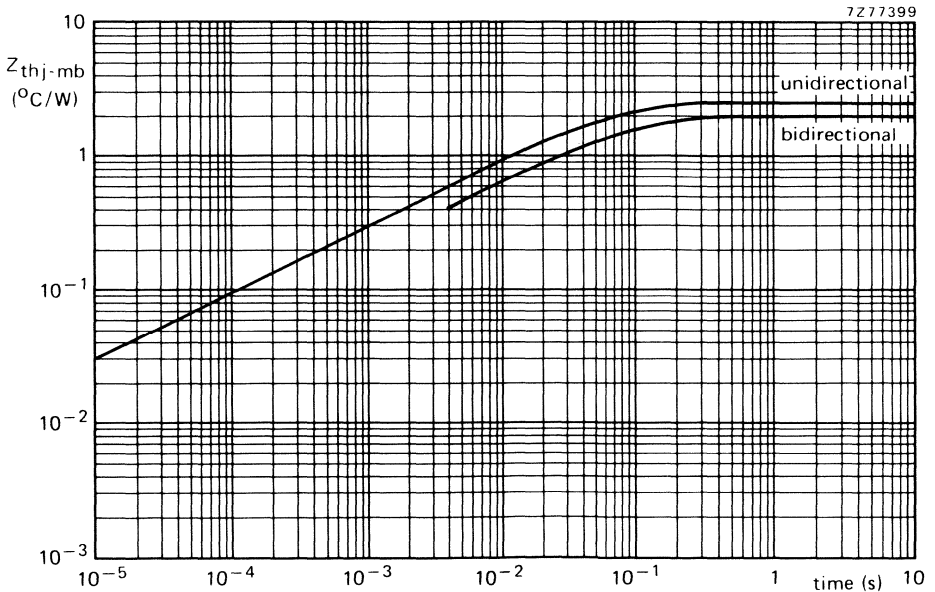


Fig.13



TRIACS

Glass-passivated, eutectic-bonded triacs intended for use in applications requiring high bidirectional transient and blocking voltage capability, and high thermal cycling performance with very low thermal resistances, e.g. a.c. power control applications such as motor, industrial lighting, industrial and domestic heating control and static switching systems.

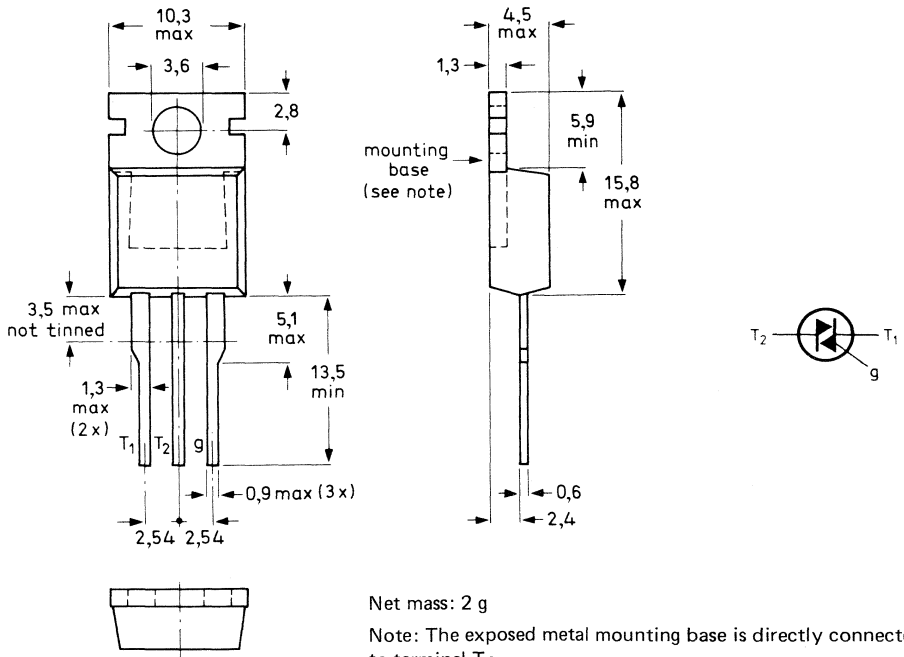
QUICK REFERENCE DATA

	BT138-500		600
Repetitive peak off-state voltage	$V_{DRM}$	max. 500	600 V
R.M.S. on-state current	$I_{T(RMS)}$	max. 12	A ←
Non-repetitive peak on-state current	$I_{TSM}$	max. 90	A

MECHANICAL DATA

Dimensions in mm ←

Fig.1 TO-220AB



Net mass: 2 g

Note: The exposed metal mounting base is directly connected to terminal T<sub>2</sub>.

Accessories supplied on request: see data sheet Mounting instructions and accessories for TO-220 envelopes.

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC134)

### Voltages (in either direction)

		BT138-500   600	
Non-repetitive peak off-state voltage ( $t \leq 10$ ms)	$V_{DSM}$	max. 500	600 V*
Repetitive peak off-state voltage ( $\delta \leq 0,01$ )	$V_{DRM}$	max. 500	600 V
Crest working off-state voltage	$V_{DWM}$	max. 400	400 V

### → Currents (in either direction)

R.M.S. on-state current (conduction angle 360°) up to $T_{mb} = 95$ °C	$I_T(RMS)$	max. 12	A
Average on-state current for half-cycle operation (averaged over any 20 ms period) up to $T_{mb} = 83$ °C	$I_T(AV)$	max. 7,5	A
Repetitive peak on-state current	$I_{TRM}$	max. 90	A
Non-repetitive peak on-state current; $T_j = 120$ °C prior to surge; $t = 20$ ms; full sine-wave	$I_{TSM}$	max. 90	A
$I^2 t$ for fusing ( $t = 10$ ms)	$I^2 t$	max. 40	A <sup>2</sup> s
Rate of rise of on-state current after triggering with $I_G = 200$ mA to $I_T = 20$ A; $dI_G/dt = 0,2$ A/ $\mu$ s	$dI_T/dt$	max. 30	A/ $\mu$ s

### Gate to terminal 1

### Power dissipation

Average power dissipation (averaged over any 20 ms period)	$P_G(AV)$	max. 0,5	W
Peak power dissipation	$P_{GM}$	max. 5,0	W

### Temperatures

Storage temperature	$T_{stg}$	-40 to +125	°C
→ Operating junction temperature			
full-cycle operation	$T_j$	max. 120	°C
half-cycle operation	$T_j$	max. 110	°C

\* Although not recommended, off-state voltages up to 800 V may be applied without damage, but the triac may switch into the on-state. The rate of rise of on-state current should not exceed 15 A/ $\mu$ s.

**THERMAL RESISTANCE**

From junction to mounting base

full-cycle operation

half-cycle operation

$$R_{th\ j-mb} = 1,5\ ^\circ C/W \leftarrow$$

$$R_{th\ j-mb} = 2,0\ ^\circ C/W \leftarrow$$

Transient thermal impedance;  $t = 1\ ms$ 

$$Z_{th\ j-mb} = 0,1\ ^\circ C/W$$

**Influence of mounting method**

## 1. Heatsink mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound

$$R_{th\ mb-h} = 0,3\ ^\circ C/W$$

b. with heatsink compound and 0,06 mm maximum mica insulator

$$R_{th\ mb-h} = 1,4\ ^\circ C/W$$

c. with heatsink compound and 0,1 mm maximum mica insulator (56369)

$$R_{th\ mb-h} = 2,2\ ^\circ C/W$$

d. with heatsink compound and 0,25 mm maximum alumina insulator (56367)

$$R_{th\ mb-h} = 0,8\ ^\circ C/W$$

e. without heatsink compound

$$R_{th\ mb-h} = 1,4\ ^\circ C/W$$

## 2. Free-air operation

The quoted values of  $R_{th\ j-a}$  should be used only when no leads of other dissipating components run to the same tie-point.Thermal resistance from junction to ambient in free air:  
mounted on a printed-circuit board at  $a =$  any lead length

$$R_{th\ j-a} = 60\ ^\circ C/W$$

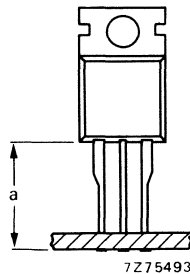


Fig.2

→ CHARACTERISTICS

Polarities, positive or negative, are identified with respect to T<sub>1</sub>.

**Voltages and currents** (in either direction)

On-state voltage (Note 1)

$$I_T = 15 \text{ A}; T_j = 25 \text{ }^\circ\text{C} \qquad V_T < 1,65 \text{ V}$$

Rate of rise of off-state voltage that will not trigger any device;

$$T_j = 120 \text{ }^\circ\text{C}; \text{ see also Figs.9 and 10; gate open circuit} \qquad dV_D/dt < 50 \text{ V}/\mu\text{s}$$

Rate of rise of commutating voltage that will not trigger any device;

$$I_T(\text{RMS}) = 12 \text{ A}; V_D = V_{DWM} \text{ max};$$

$$T_j = 120 \text{ }^\circ\text{C}; \text{ gate open circuit; see also Figs.9 and 10}$$

BT138 series	$-dI_T/dt = 4,2 \text{ A/ms}$	}	$dV_{com}/dt < 6 \text{ V}/\mu\text{s}$
BT138 series F	$-dI_T/dt = 4,2 \text{ A/ms}$		
BT138 series E	$-dI_T/dt = 2,1 \text{ A/ms}$		

Off-state current

$$V_D = V_{DWM} \text{ max}; T_j = 120 \text{ }^\circ\text{C} \qquad I_D < 0,5 \text{ mA}$$

Holding current; T<sub>j</sub> = 25 °C

T <sub>2</sub> and G positive or negative	BT138, F and E series	$I_H < 30 \text{ mA}$
	BT138 D series	$I_H < 20 \text{ mA}$

Gate voltage and current that will trigger all devices

Latching current

$$V_D = 12 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$$

		T <sub>2</sub> <sup>+</sup> G <sup>+</sup>	T <sub>2</sub> <sup>+</sup> G <sup>-</sup>	T <sub>2</sub> <sup>-</sup> G <sup>-</sup>	T <sub>2</sub> <sup>-</sup> G <sup>+</sup>	
BT138 series	G to T <sub>1</sub>	$V_{GT} > 1,5$ $I_{GT} > 35$ $I_L < 40$	1,5 35 60	1,5 35 40	1,5 70 40	V mA mA
BT138 series F e.g. BT138-500F	G to T <sub>1</sub>	$V_{GT} > 1,5$ $I_{GT} > 25$ $I_L < 40$	1,5 25 60	1,5 25 40	1,5 70 40	V mA mA
BT138 series E	G to T <sub>1</sub>	$V_{GT} > 1,5$ $I_{GT} > 15$ $I_L < 30$	1,5 15 40	1,5 15 30	1,5 50 30	V mA mA
BT138 series D (Note 2)	G to T <sub>1</sub>	$V_{GT} > 1,5$ $I_{GT} > 8$ $I_L < 25$	1,5 8 35	1,5 8 25	** ** **	V mA mA

*Gate to terminal 1*

Voltage that will not trigger any device V<sub>D</sub> = V<sub>DRM</sub> max;

$$T_j = 120 \text{ }^\circ\text{C}; T_2 \text{ and G positive or negative} \qquad V_{GD} < 250 \text{ mV}$$

Note 1. Measured under pulse conditions to avoid excessive dissipation.

Note 2. A version with I<sub>GT</sub> = 5 mA max. is available on request.

\*\* Triggerable

### MOUNTING INSTRUCTIONS

1. The triac may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; it must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4,7 mm from the seal.
2. The leads should not be bent less than 2,4 mm from the seal, and should be supported during bending.
3. It is recommended that the circuit connection be made to tag T<sub>2</sub>, rather than direct to the heatsink.
4. Mounting by means of a spring clip is the best mounting method because it offers:
  - a. a good thermal contact under the crystal area and slightly lower  $R_{th\ mb-h}$  values than screw mounting.
  - b. safe isolation for mains operation.
 However, if a screw is used, it should be M3 cross-recess pan head. Care should be taken to avoid damage to the plastic body.
5. For good thermal contact heatsink compound should be used between mounting base and heatsink. Values of  $R_{th\ mb-h}$  given for mounting with heatsink compound refer to the use of a metallic-oxide loaded compound. Ordinary silicone grease is not recommended.
6. The device should not be pop-riveted to the heatsink. However, it is permissible to press-rivet providing that rivets of soft material are used, and the press forces are slowly and carefully controlled so as to avoid shock and deformation of either heatsink or mounting tab.

### OPERATING NOTES

Dissipation and heatsink considerations:

- a. The various components of junction temperature rise above ambient are illustrated in Fig.3

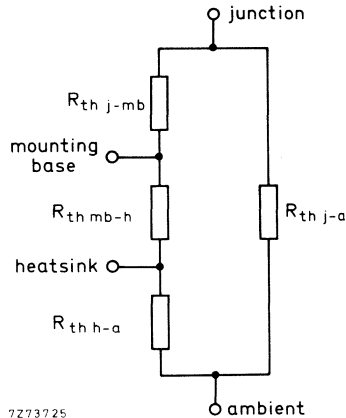


Fig.3

- b. The method of using Figs.4 and 5 is as follows:  
Starting with the required current on the  $I_T(AV)$  or  $I_T(RMS)$  axis, trace upwards to meet the appropriate form factor or conduction angle curve. Trace right horizontally and upwards from the appropriate value on the  $T_{amb}$  scale. The intersection determines the  $R_{th\ mb-a}$ . The heatsink thermal resistance value ( $R_{th\ h-a}$ ) can now be calculated from:

$$R_{th\ h-a} = R_{th\ mb-a} - R_{th\ mb-h}$$

- c. Any measurement of heatsink temperature should be made immediately adjacent to the device.

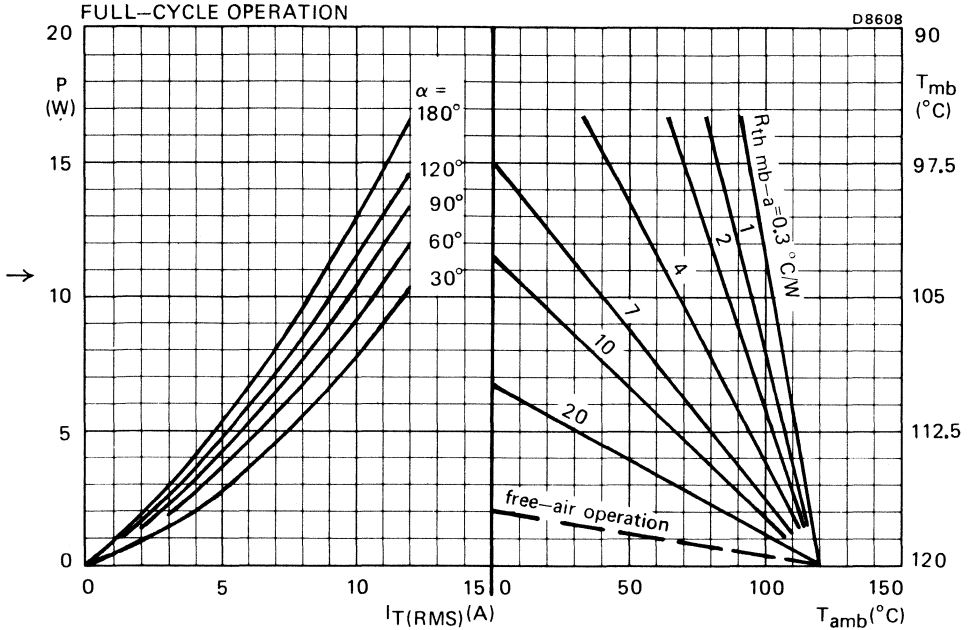
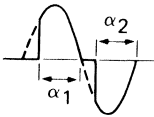


Fig.4 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.



$\alpha = \alpha_1 = \alpha_2$ : conduction angle per half cycle



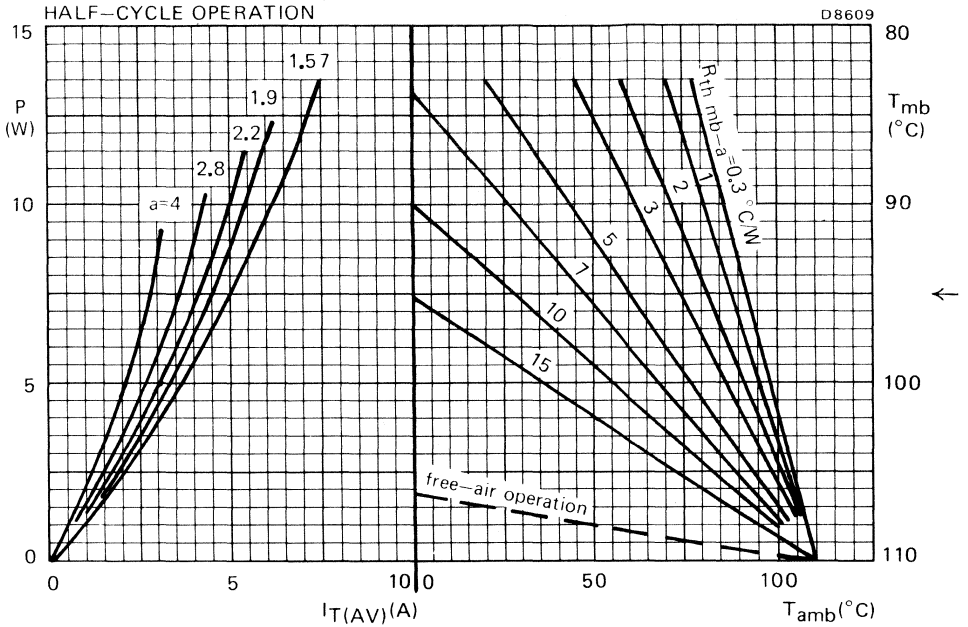


Fig.5 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

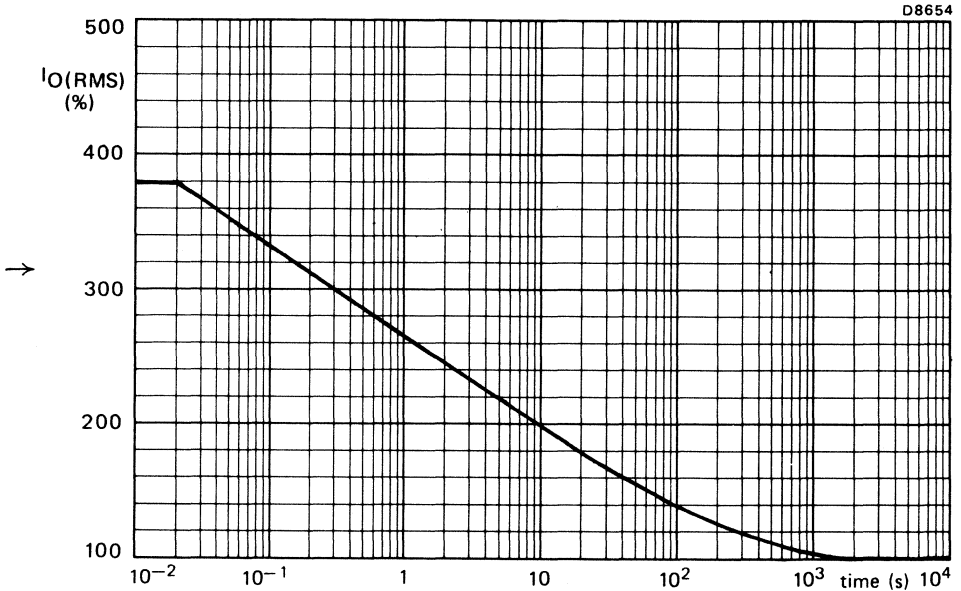


$\alpha$  = conduction angle per half cycle

$$a = \text{form factor} = \frac{I_T(\text{RMS})}{I_T(\text{AV})}$$

$\alpha$	a
30°	4
60°	2,8
90°	2,2
120°	1,9
180°	1,57

OVERLOAD OPERATION



→ Fig.6 Maximum permissible duration of steady overload (provided that  $T_{mb}$  does not exceed  $120\text{ }^\circ\text{C}$  during and after overload) expressed as a percentage of the steady state r.m.s. rated current. For high r.m.s. overload currents precautions should be taken so that the temperature of the terminals does not exceed  $125\text{ }^\circ\text{C}$ . During these overload conditions the triac may lose control. Therefore the overload should be terminated by a separate protection device.

7Z77138A

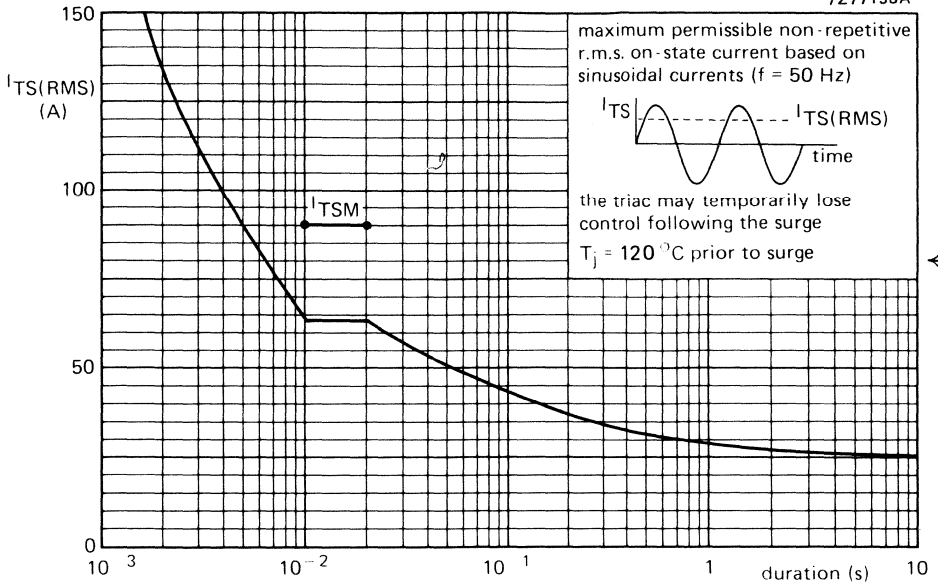


Fig.7

7Z77122A

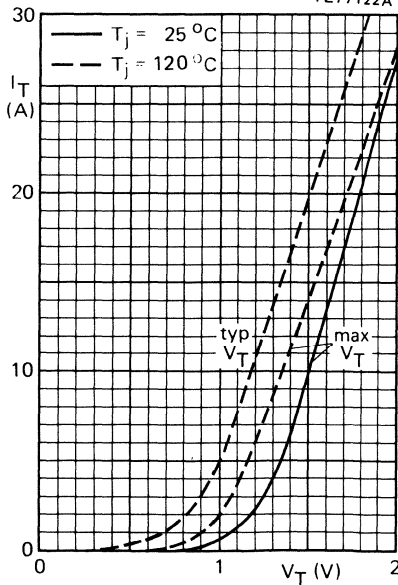


Fig.8

D8610

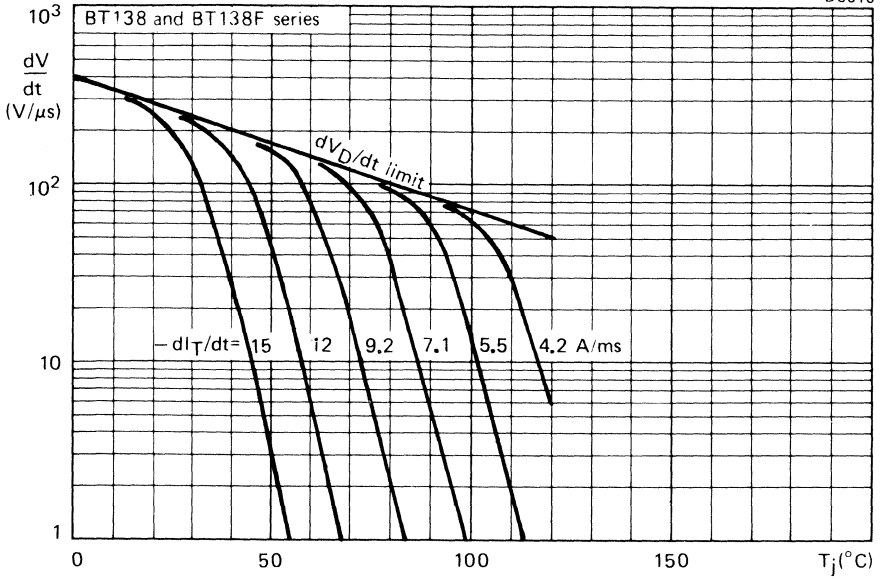


Fig.9 Limit commutation  $dV/dt$  for BT138 and F series versus  $T_j$ . The triac should commute when  $dV/dt$  is below the value on the appropriate curve for pre-commutation  $di_T/dt$ .

D8611

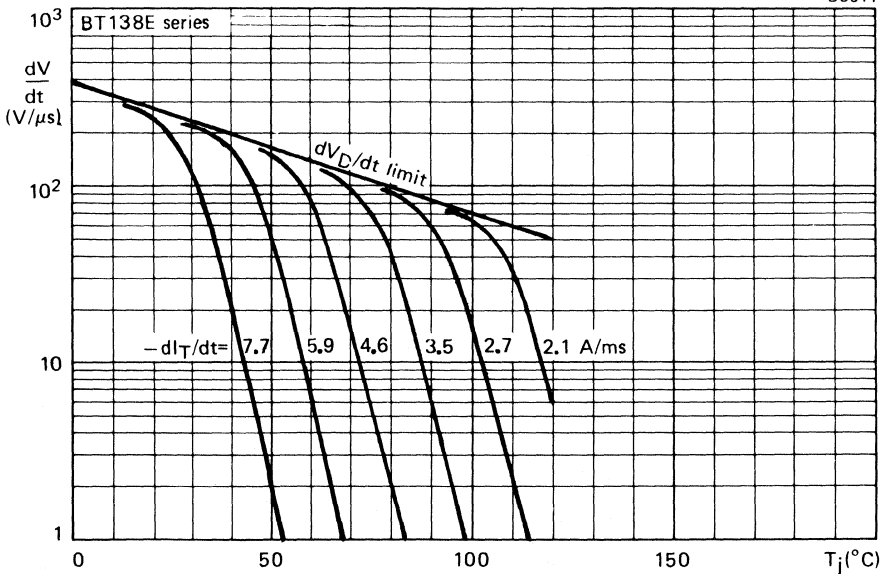


Fig.10 Limit commutation  $dV/dt$  for BT138E series versus  $T_j$ . The triac should commute when the  $dV/dt$  is below the value on the appropriate curve for pre-commutation  $di_T/dt$ .

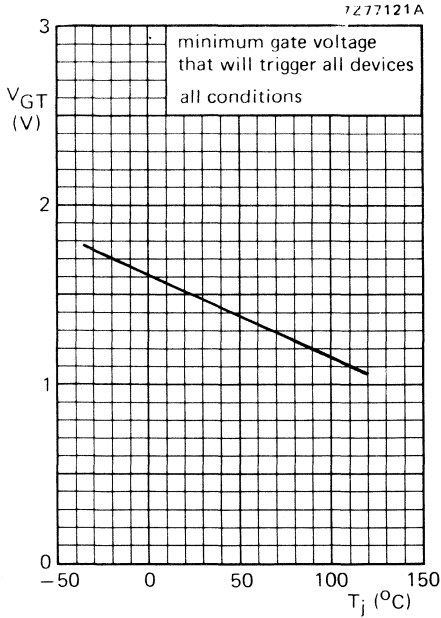


Fig. 11

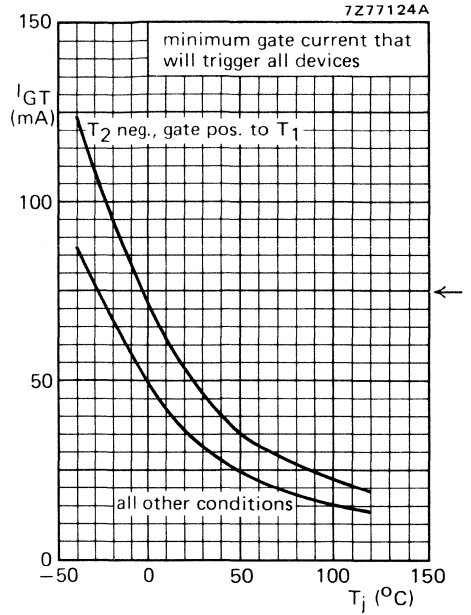


Fig. 12

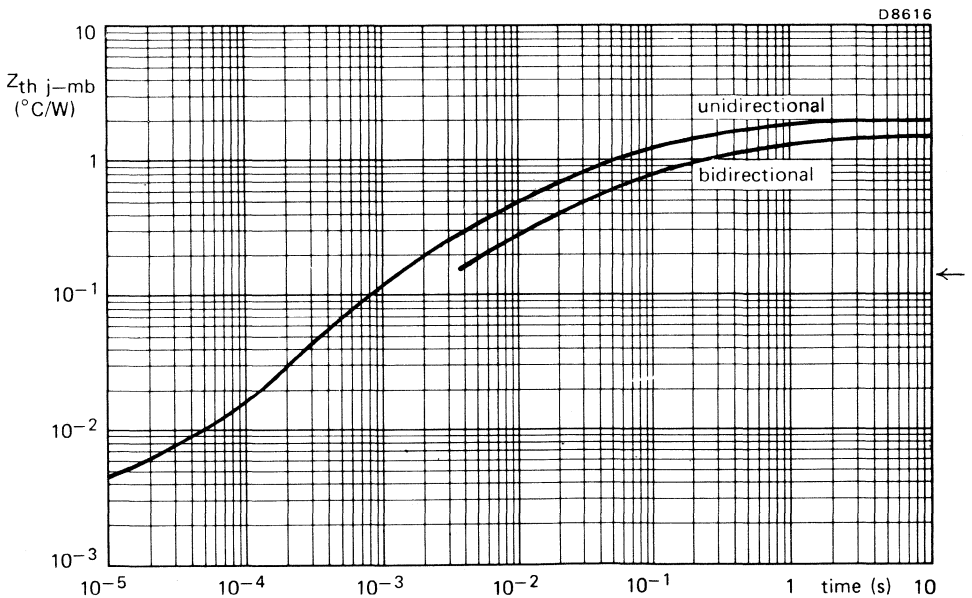


Fig.13

LIMITS FOR STARTING OR INRUSH CURRENTS – FULL-CYCLE OPERATION

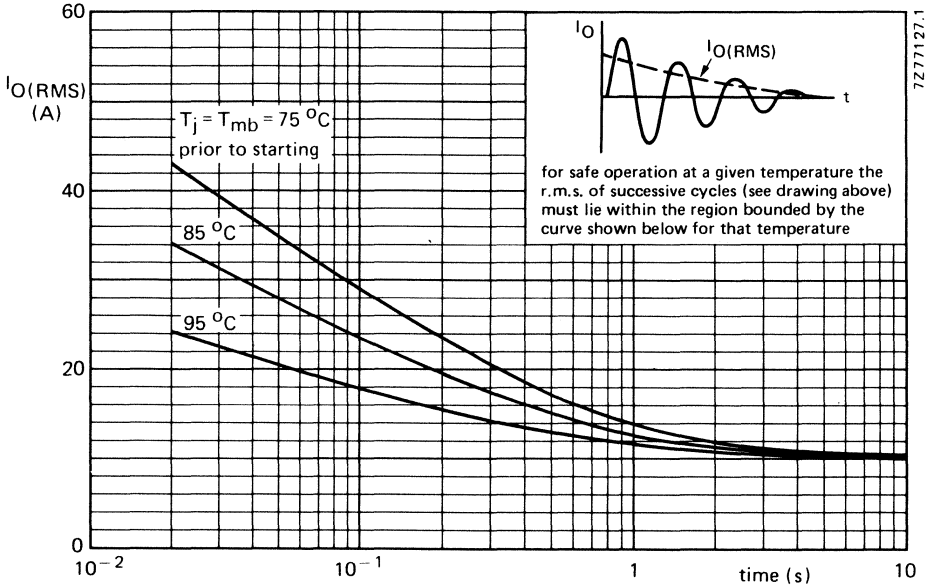


Fig.14

LIMITS FOR STARTING OR INRUSH CURRENTS – HALF-CYCLE OPERATION

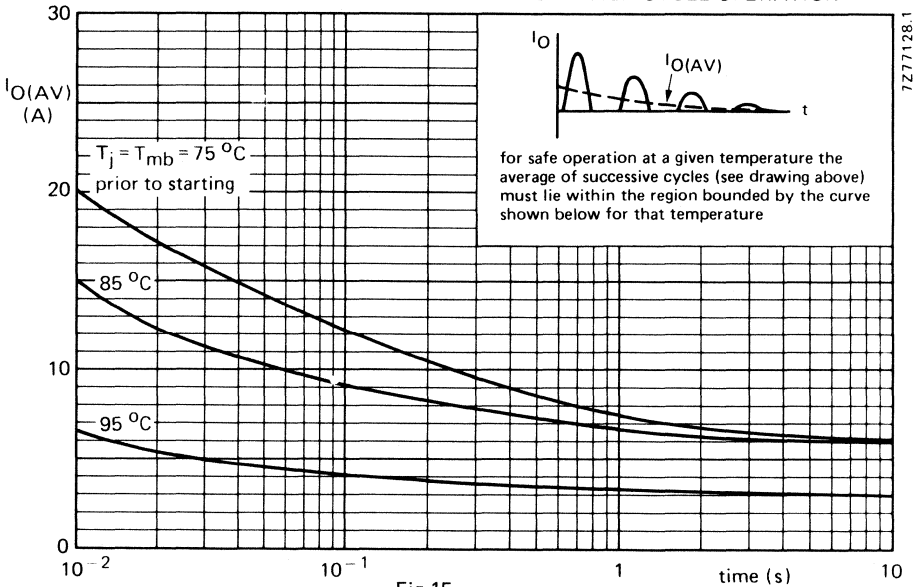


Fig.15

TRIACS

Glass-passivated eutectic-bonded triacs intended for use in applications requiring high bidirectional transient and blocking voltage capability, and high thermal cycling performance with very low thermal resistances, e.g. a.c. power control applications such as motor, industrial lighting, industrial and domestic heating control and static switching systems.

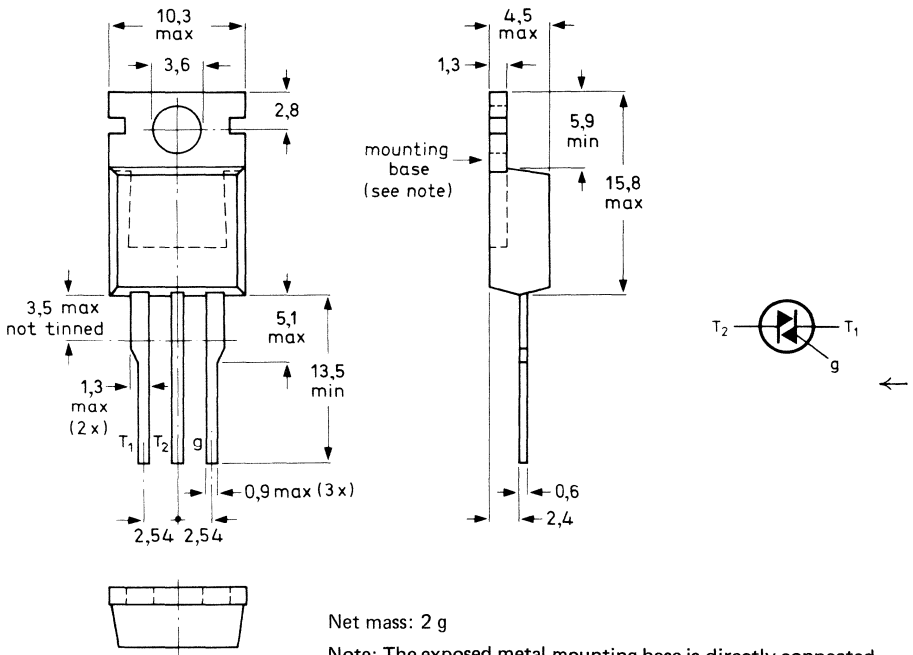
QUICK REFERENCE DATA

	BT139-500   600		
Repetitive peak off-state voltage	$V_{DRM}$ max.	500   600	V
R.M.S. on-state current	$I_T(RMS)$ max.	16	A ←
Non-repetitive peak on-state current	$I_{TSM}$ max.	115	A

MECHANICAL DATA

Dimensions in mm

Fig.1 TO-220AB



Net mass: 2 g

Note: The exposed metal mounting base is directly connected to terminal T<sub>2</sub>.

Accessories supplied on request: see data sheet Mounting instructions and accessories for TO-220 envelopes.

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

### Voltages (in either direction)

Non-repetitive peak off-state voltage ( $t \leq 10$  ms)

		BT139-500		600
$V_{DSM}$	max.	500	600	V*

Repetitive peak off-state voltage ( $\delta \leq 0,01$ )

$V_{DRM}$	max.	500	600	V
-----------	------	-----	-----	---

Crest working off-state voltage

$V_{DWM}$	max.	400	400	V
-----------	------	-----	-----	---

### → Currents (in either direction)

R.M.S. on-state current (conduction angle  $360^\circ$ )

up to  $T_{mb} = 93$  °C

$I_{T(RMS)}$	max.	16	A
--------------	------	----	---

Average on-state current for half-cycle operation

(averaged over any 20 ms period) up to  $T_{mb} = 79$  °C

$I_{T(AV)}$	max.	10	A
-------------	------	----	---

Repetitive peak on-state current

$I_{TRM}$	max.	115	A
-----------	------	-----	---

Non-repetitive peak on-state current;  $T_j = 120$  °C prior

to surge;  $t = 20$  ms; full sine-wave

$I_{TSM}$	max.	115	A
-----------	------	-----	---

$I^2 t$  for fusing ( $t = 10$  ms)

$I^2 t$	max.	65	A <sup>2</sup> s
---------	------	----	------------------

Rate of rise of on-state current after triggering with

$I_G = 200$  mA to  $I_T = 20$  A;  $dI_G/dt = 0,2$  A/ $\mu$ s

$dI_T/dt$	max.	30	A/ $\mu$ s
-----------	------	----	------------

### Gate to terminal 1

### Power dissipation

Average power dissipation (averaged over any 20 ms period)

$P_{G(AV)}$	max.	0,5	W
-------------	------	-----	---

Peak power dissipation

$P_{GM}$	max.	5	W
----------	------	---	---

### Temperatures

Storage temperature

$T_{stg}$		-40 to +125	°C
-----------	--	-------------	----

### → Operating junction temperature

full-cycle operation

$T_j$	max.	120	°C
-------	------	-----	----

half-cycle operation

$T_j$	max.	110	°C
-------	------	-----	----

\* Although not recommended, off-state voltages up to 800 V may be applied without damage, but the triac may switch into the on-state. The rate of rise of on-state current should not exceed 15 A/ $\mu$ s.



**THERMAL RESISTANCE**

From junction to mounting base

- full cycle operation
- half cycle operation

$R_{th\ j-mb}$	=	1,2 °C/W	←
$R_{th\ j-mb}$	=	1,7 °C/W	←
$Z_{th\ j-mb}$	=	0,1 °C/W	

Transient thermal impedance;  $t = 1\ ms$

**Influence of mounting method**

1. Heatsink mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

- a. with heatsink compound  $R_{th\ mb-h} = 0,3\ °C/W$
- b. with heatsink compound and 0,06 mm maximum mica insulator  $R_{th\ mb-h} = 1,4\ °C/W$
- c. with heatsink compound and 0,1 mm maximum mica insulator (56369)  $R_{th\ mb-h} = 2,2\ °C/W$
- d. with heatsink compound and 0,25 mm maximum alumina insulator (56367)  $R_{th\ mb-h} = 0,8\ °C/W$
- e. without heatsink compound  $R_{th\ mb-h} = 1,4\ °C/W$

2. Free-air operation

The quoted values of  $R_{th\ j-a}$  should be used only when no leads of other dissipating components run to the same tie-point.

Thermal resistance from junction to ambient in free air:  
mounted on a printed-circuit board at a = any lead length

$R_{th\ j-a} = 60\ °C/W$

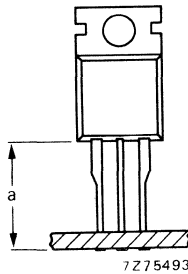


Fig.2

## CHARACTERISTICS

Polarities, positive or negative, are identified with respect to T<sub>1</sub>.

**Voltages and currents** (in either direction)

On-state voltage (Note 1)

$$I_T = 20 \text{ A}; T_j = 25 \text{ }^\circ\text{C} \qquad V_T < 1,6 \text{ V}$$

Rate of rise of off-state voltage that will not trigger any device;

$$T_j = 120 \text{ }^\circ\text{C}; \text{ see also Figs.9 and 10; gate open circuit} \qquad dV_D/dt < 50 \text{ V}/\mu\text{s}$$

Rate of rise of commutating voltage that will not trigger any device;

$$I_T(\text{RMS}) = 16 \text{ A}; V_D = V_{DWM} \text{ max};$$

$$T_j = 120 \text{ }^\circ\text{C}; \text{ gate open circuit; see also Figs.9 and 10}$$

BT139 series	$-di_T/dt = 6,7 \text{ A/ms}$	}	$dV_{com}/dt < 6 \text{ V}/\mu\text{s}$
BT139 series F	$-di_T/dt = 6,7 \text{ A/ms}$		
BT139 series E	$-di_T/dt = 3,35 \text{ A/ms}$		

Off-state current

$$V_D = V_{DWM} \text{ max}; T_j = 120 \text{ }^\circ\text{C} \qquad I_D < 0,5 \text{ mA}$$

Holding current; T<sub>j</sub> = 25 °C

T <sub>2</sub> and G positive or negative	BT139, F and E series	$I_H < 30 \text{ mA}$
	BT139 D series	$I_H < 20 \text{ mA}$

Gate voltage and current that will trigger all devices

Latching current

$$V_D = 12 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$$

		$T_2^+$ G <sup>+</sup>	$T_2^+$ G <sup>-</sup>	$T_2^-$ G <sup>-</sup>	$T_2^-$ G <sup>+</sup>
BT139 series	G to T <sub>1</sub>	$V_{GT} > 1,5$	1,5	1,5	1,5 V
		$I_{GT} > 35$	35	35	50 mA
		$I_L < 40$	60	40	40 mA
BT139 series F e.g. BT139-500F	G to T <sub>1</sub>	$V_{GT} > 1,5$	1,5	1,5	1,5 V
		$I_{GT} > 25$	25	25	50 mA
		$I_L < 40$	60	40	40 mA
BT139 series E	G to T <sub>1</sub>	$V_{GT} > 1,5$	1,5	1,5	1,5 V
		$I_{GT} > 15$	15	15	50 mA
		$I_L < 30$	40	30	30 mA
BT139 series D (Note 2)	G to T <sub>1</sub>	$V_{GT} > 1,5$	1,5	1,5	** V
		$I_{GT} > 8$	8	8	** mA
		$I_L < 25$	35	25	** mA

*Gate to terminal 1*

Voltage that will not trigger any device  $V_D = V_{DRM} \text{ max};$

$$T_j = 120 \text{ }^\circ\text{C}; T_2 \text{ and G positive or negative} \qquad V_{GD} < 250 \text{ mV}$$

Note 1. Measured under pulse conditions to avoid excessive dissipation.

Note 2. A version with  $I_{GT} = 5 \text{ mA}$  max. is available on request.

\*\* Triggerable

### MOUNTING INSTRUCTIONS

1. The triac may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; it must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4,7 mm from the seal.
2. The leads should not be bent less than 2,4 mm from the seal, and should be supported during bending.
3. It is recommended that the circuit connection be made to tag T<sub>2</sub>, rather than direct to the heatsink.
4. Mounting by means of a spring clip is the best mounting method because it offers:
  - a. a good thermal contact under the crystal area and slightly lower R<sub>th mb-h</sub> values than screw mounting.
  - b. safe isolation for mains operation.
 However, if a screw is used, it should be M3 cross-recess pan head. Care should be taken to avoid damage to the plastic body.
5. For good thermal contact heatsink compound should be used between mounting base and heatsink. Values of R<sub>th mb-h</sub> given for mounting with heatsink compound refer to the use of a metallic-oxide loaded compound. Ordinary silicone grease is not recommended.
6. The device should not be pop-riveted to the heatsink. However, it is permissible to press-rivet providing that rivets of soft material are used, and the press forces are slowly and carefully controlled so as to avoid shock and deformation of either heatsink or mounting tab.

### OPERATING NOTES

Dissipation and heatsink considerations:

- a. The various components of junction temperature rise above ambient are illustrated in Fig.3.

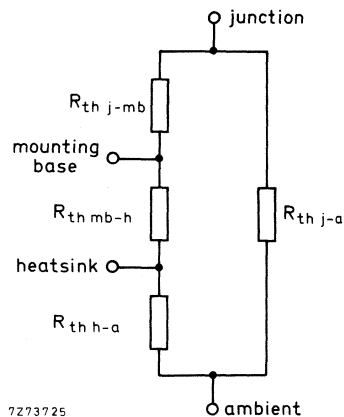


Fig.3

- b. The method of using Figs.4 and 5 is as follows:  
Starting with the required current on the I<sub>T(AV)</sub> or I<sub>T(RMS)</sub> axis, trace upwards to meet the appropriate form factor or conduction angle curve. Trace right horizontally and upwards from the appropriate value on the T<sub>amb</sub> scale. The intersection determines the R<sub>th mb-a</sub>. The heatsink thermal resistance value (R<sub>th h-a</sub>) can now be calculated from:

$$R_{th\ h-a} = R_{th\ mb-a} - R_{th\ mb-h}$$

- c. Any measurement of heatsink temperature should be made immediately adjacent to the device.

FULL-CYCLE OPERATION

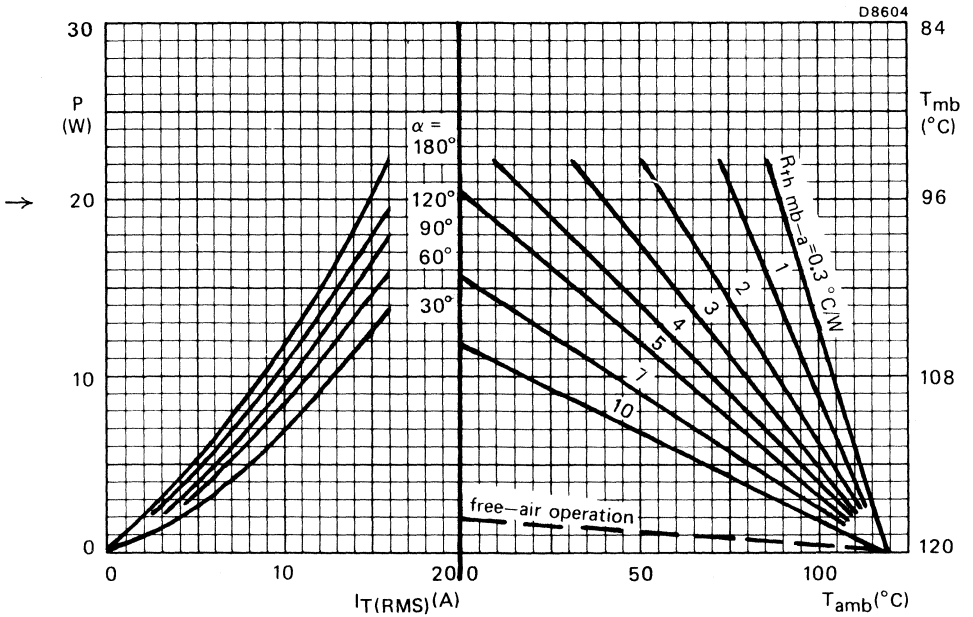
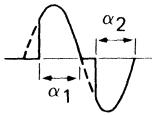


Fig. 4 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.



$\alpha = \alpha_1 = \alpha_2$ : conduction angle per half cycle

HALF-CYCLE OPERATION

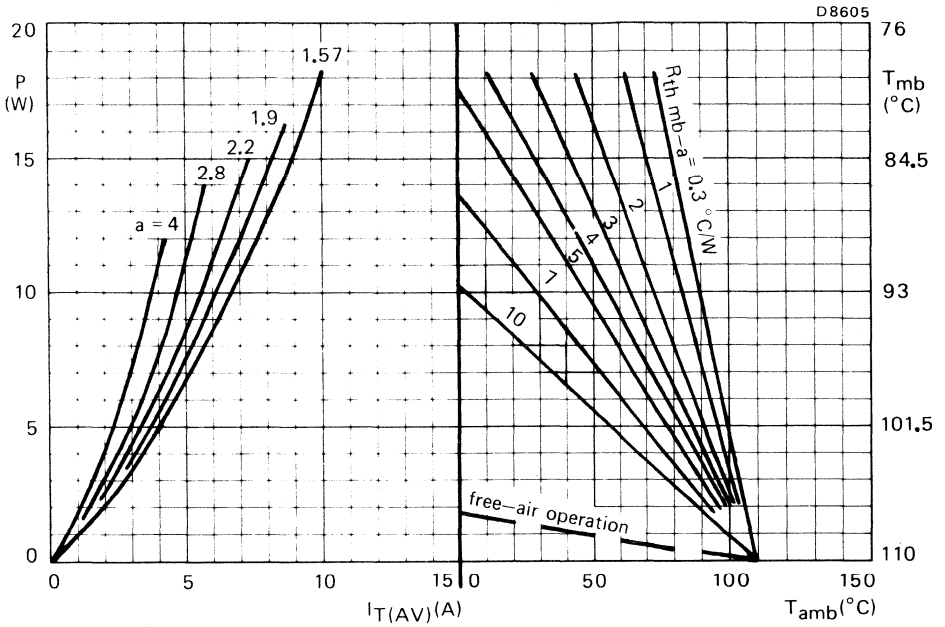


Fig.5 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

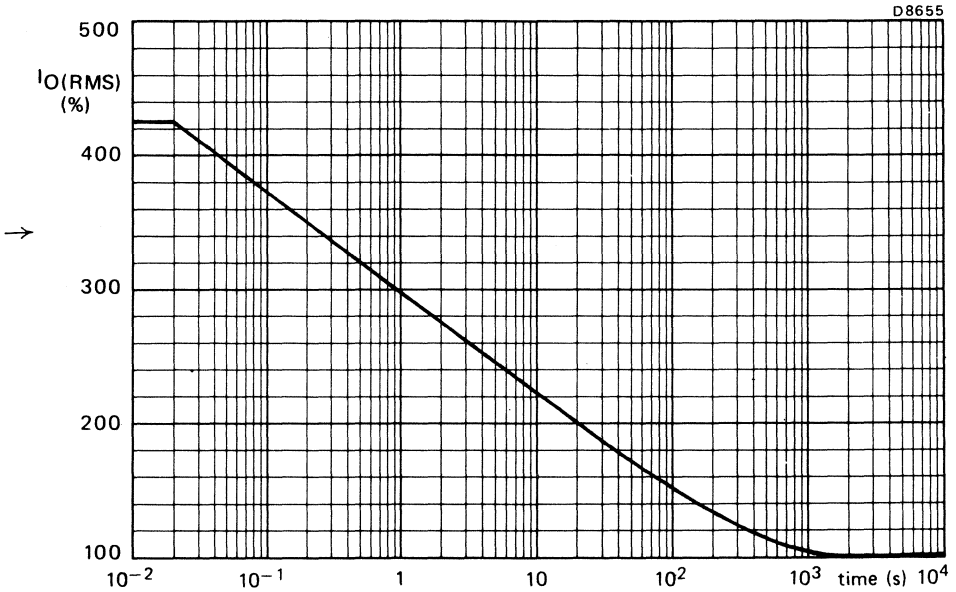


$\alpha$  = conduction angle per half cycle

$$a = \text{form factor} = \frac{I_T(\text{RMS})}{I_T(\text{AV})}$$

$\alpha$	a
30°	4
60°	2,8
90°	2,2
120°	1,9
180°	1,57

OVERLOAD OPERATION



→ Fig. 6 Maximum permissible duration of steady overload (provided that  $T_{mb}$  does not exceed  $120\text{ }^{\circ}\text{C}$  during and after overload) expressed as a percentage of the steady state r.m.s. rated current. For high r.m.s. overload currents precautions should be taken so that the temperature of the terminals does not exceed  $125\text{ }^{\circ}\text{C}$ . During these overload conditions the triac may lose control. Therefore the overload should be terminated by a separate protection device.

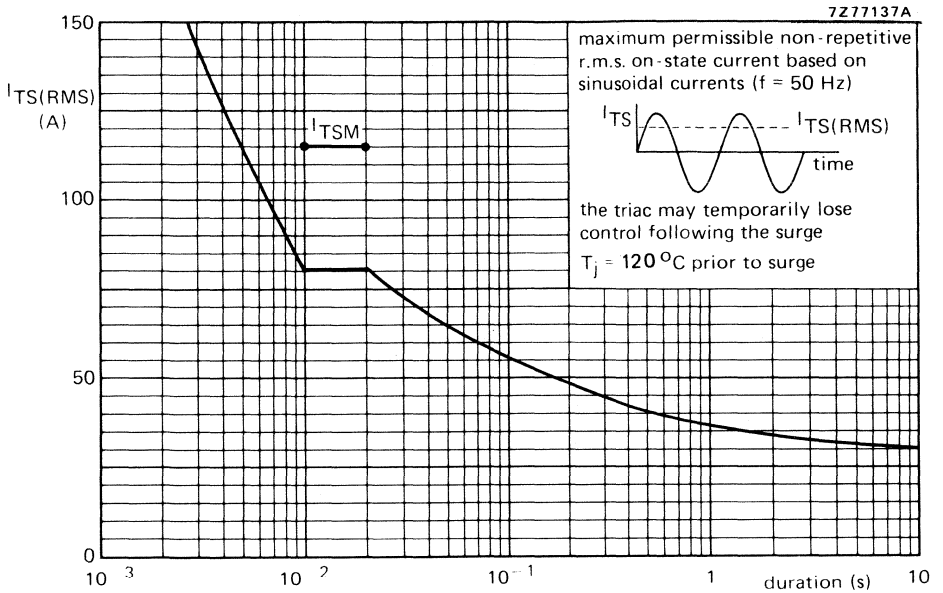


Fig.7

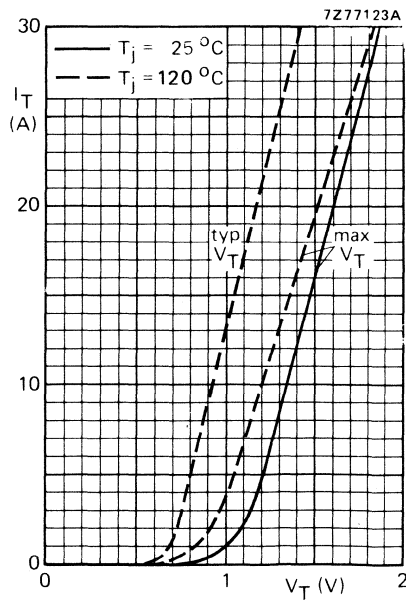


Fig.8

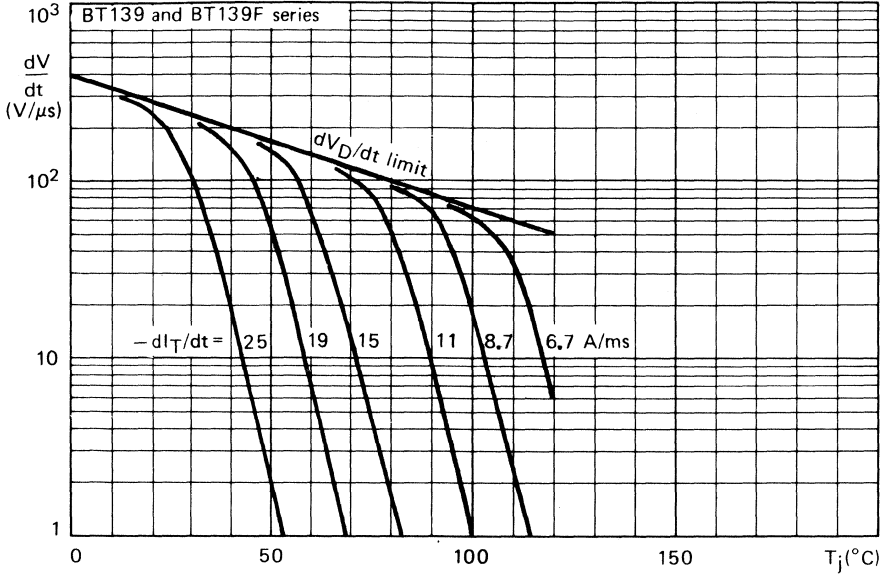


Fig.9 Limit commutation  $dV/dt$  for BT139 and F series versus  $T_j$ . The triac should commute when the  $dV/dt$  is below the value on the appropriate curve for pre-commutation  $dI_T/dt$ .

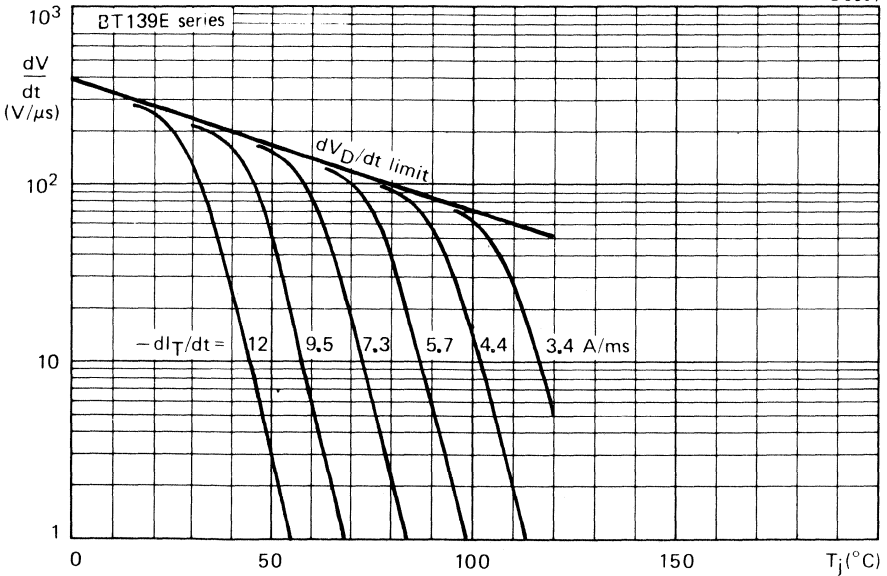


Fig.10 Limit commutation  $dV/dt$  for BT139E series versus  $T_j$ . The triac should commute when the  $dV/dt$  is below the value on the appropriate curve for pre-commutation  $dI_T/dt$ .



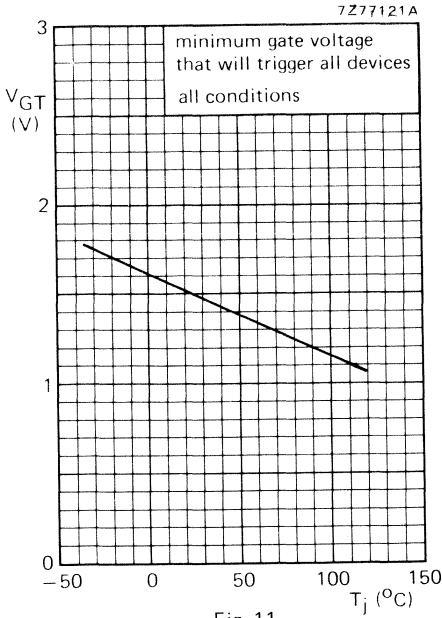


Fig. 11

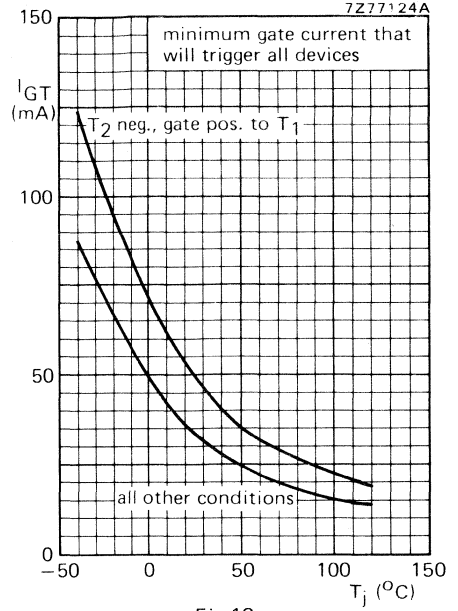


Fig. 12

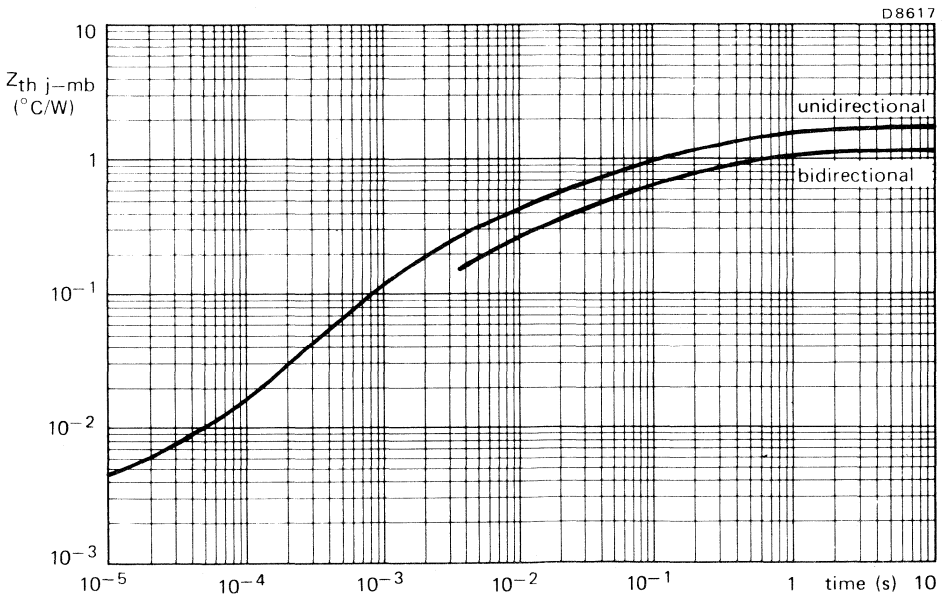


Fig. 13

LIMITS FOR STARTING OR INRUSH CURRENTS – FULL-CYCLE OPERATION

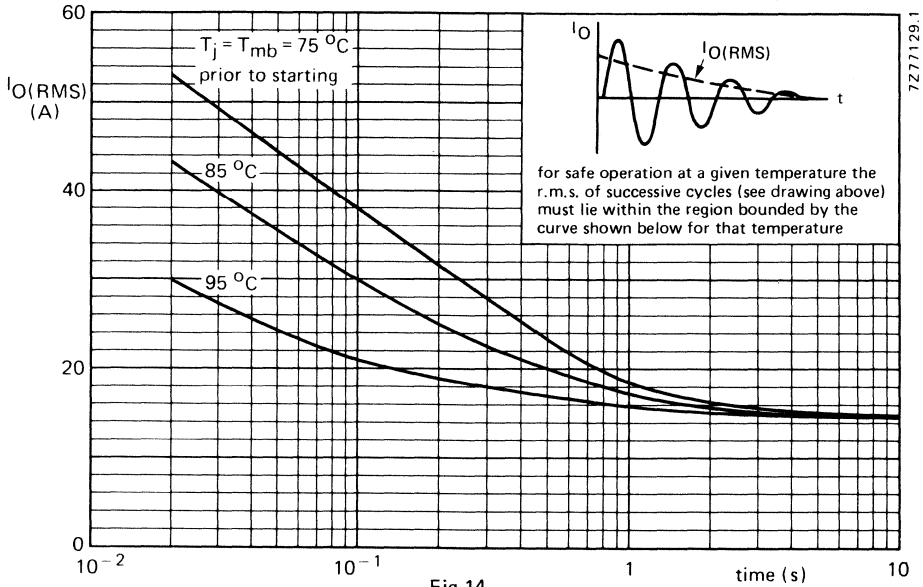


Fig.14

LIMITS FOR STARTING OR INRUSH CURRENTS – HALF-CYCLE OPERATION

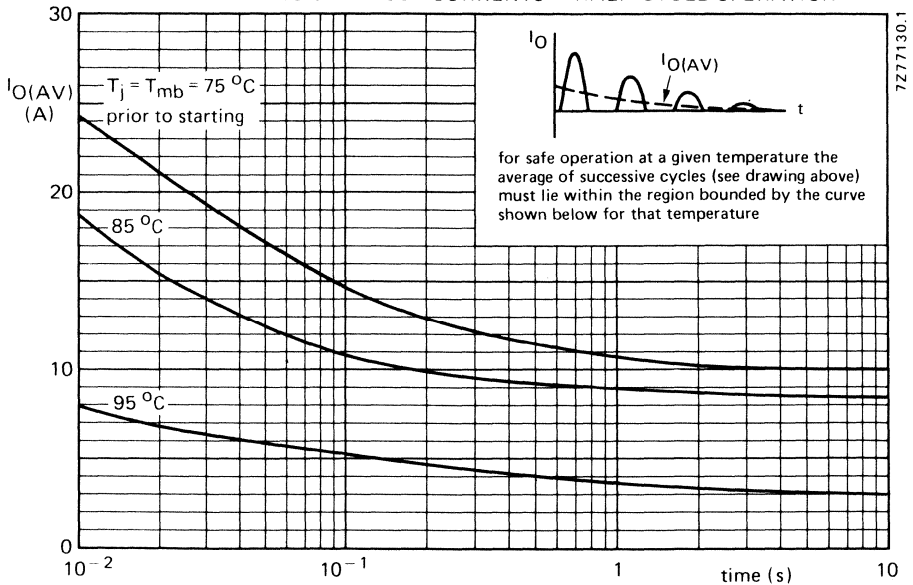


Fig.15

## TRIACS

Silicon triacs in metal envelopes, intended for industrial a.c. power control, and are particularly suitable for static switching of 3-phase induction motors. They may also be used for furnace control, lighting control and other static switching applications up to an r.m.s. on-state current of 55 A.

Two grades of commutation performance are available, 30 V/μs at 25 A/ms (suffix G) and 30 V/μs at 50 A/ms (suffix H).

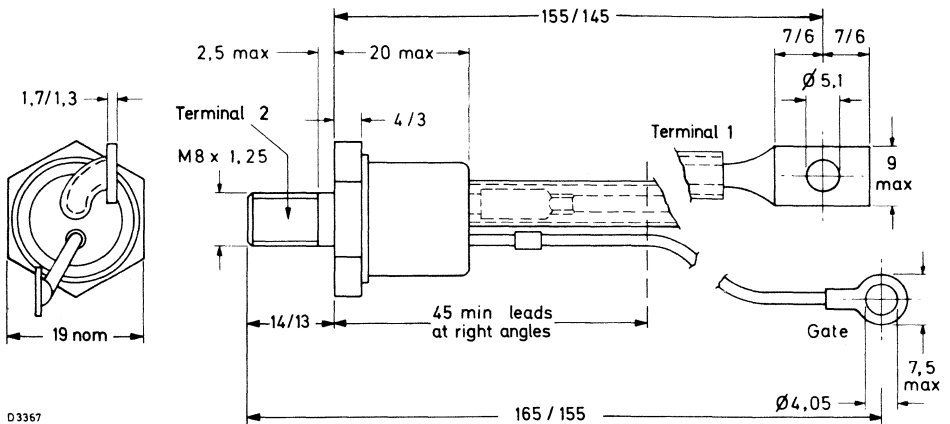
### QUICK REFERENCE DATA

	BTW34-600	800	1000	1200	1400	1600
Repetitive peak off-state voltage	$V_{DRM}$ max. 600   800   1000   1200   1400   1600 V					
R.M.S. on-state current	$I_T(RMS)$ max. 55 A					
Non-repetitive peak on-state current	$I_{TSM}$ max. 400 A					
Rate of rise of commutating voltage that will not trigger any device (see page 3)	$dV_{com}/dt < 30$ V/μs					

### MECHANICAL DATA

Dimensions in mm

Fig. 1 TO-103.



D3367

Net mass: 46 g  
 Diameter of clearance hole: 8,5 mm  
 Torque on nut: min. 4 Nm (40 kg cm)  
 max. 6 Nm (60 kg cm)

Supplied with device: 1 nut, 1 lock washer  
 Nut dimensions across the flats: 13 mm

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

### Voltages (in either direction)\*

		BTW34-600	800	1000	1200	1400	1600	
Non-repetitive peak off-state voltage ( $t \leq 10$ ms)	$V_{DSM}$	max. 700	900	1100	1300	1400	1600	V**
Repetitive peak off-state voltage	$V_{DRM}$	max. 600	800	1000	1200	1400	1600	V
Crest working off-state voltage	$V_{DWM}$	max. 400	600	700	800	800	800	V

### Currents (in either direction)

R.M.S. on-state current (conduction angle 360°)

up to  $T_{mb} = 75$  °C

at  $T_{mb} = 85$  °C

$I_T(RMS)$  max. 55 A

$I_T(RMS)$  max. 45 A

Average on-state current for half-cycle operation

(averaged over any 20 ms period) at  $T_{mb} = 85$  °C

$I_T(AV)$  max. 21 A

Repetitive peak on-state current

$I_{TRM}$  max. 300 A

Non-repetitive peak on-state current

$T_j = 125$  °C prior to surge;  $t = 20$  ms; full sine-wave

$I_{TSM}$  max. 400 A

$I^2 t$  for fusing ( $t = 10$  ms)

$I^2 t$  max. 800 A<sup>2</sup>s

Rate of rise of on-state current after triggering with

$I_G = 1$  A to  $I_T = 100$  A;  $dI_G/dt = 1A/\mu s$

$dI_T/dt$  max. 50 A/ $\mu s$

### Gate to terminal 1

### Power dissipation

Average power dissipation (averaged over any 20 ms period)

$P_{G(AV)}$  max. 2 W

Peak power dissipation

$P_{GM}$  max. 10 W

### Temperatures

Storage temperature

$T_{stg}$  -55 to + 125 °C

Junction temperature

$T_j$  max. 125 °C

### THERMAL RESISTANCE

From junction to mounting base

full-cycle operation

$R_{th j-mb}$  = 0,6 °C/W

half-cycle operation

$R_{th j-mb}$  = 1,2 °C/W

From mounting base to heatsink with heatsink compound

$R_{th mb-h}$  = 0,2 °C/W

Transient thermal impedance;  $t = 1$  ms

$Z_{th j-mb}$  = 0,08 °C/W

\* To ensure thermal stability:  $R_{th j-a} < 2$  °C/W (full-cycle or half-cycle operation). For smaller heatsinks  $T_{j max}$  should be derated (see Figs 2 and 3).

\*\* Although not recommended, higher off-state voltages may be applied without damage, but the triac may switch into the on-state. The rate of rise of on-state current should not exceed 20 A/ $\mu s$ .

**CHARACTERISTICS**

Polarities, positive or negative, are identified with respect to T<sub>1</sub>.

**Voltages** (in either direction)

On-state voltage

$I_T = 65 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_T < 2,1 \text{ V}^*$

Rate of rise of off-state voltage that will not trigger any device; exponential method;  $V_D = 2/3 V_{DRM \text{ max}}; T_j = 125 \text{ }^\circ\text{C}$

$dV_D/dt < 200 \text{ V}/\mu\text{s}$

Rate of rise of commutating voltage that will not trigger any device;

$I_T(\text{RMS}) = 45 \text{ A}; V_D = V_{DRM \text{ max}}; T_{mb} = 85 \text{ }^\circ\text{C}$

$dV_{com}/dt \text{ (V}/\mu\text{s)}$	$-dI_T/dt \text{ (A/ms)}$
---------------------------------------	---------------------------

BTW34-600G to 1600G

$< 30$

25

BTW34-600H to 1600H

$< 30$

50



**Currents** (in either direction)

Off-state current

$V_D = V_{DWM \text{ max}}; T_j = 125 \text{ }^\circ\text{C}$

$I_D < 10 \text{ mA}$

Latching current;  $T_j = 25 \text{ }^\circ\text{C}$

$T_2 \text{ pos.}$	$T_2 \text{ neg.}$
--------------------	--------------------

G positive

$I_L < 250$

– mA

G negative

$I_L < 500$

250 mA

Holding current;  $T_j = 25 \text{ }^\circ\text{C}$

G positive or negative

$I_H < 200$

200 mA

*Gate to terminal 1*

Voltage and current that will trigger all devices

$V_D = 12 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$

G positive

$\left\{ \begin{array}{l} V_{GT} > 2,5 \\ I_{GT} > 200 \end{array} \right.$

– V

$\left\{ \begin{array}{l} I_{GT} > 200 \end{array} \right.$

– mA

G negative

$\left\{ \begin{array}{l} -V_{GT} > 2,5 \\ -I_{GT} > 200 \end{array} \right.$

2,5 V

$\left\{ \begin{array}{l} -I_{GT} > 200 \end{array} \right.$

200 mA

Voltage that will not trigger any device

$V_D = V_{DRM \text{ max}}; T_j = 125 \text{ }^\circ\text{C}; \text{G positive or negative}$

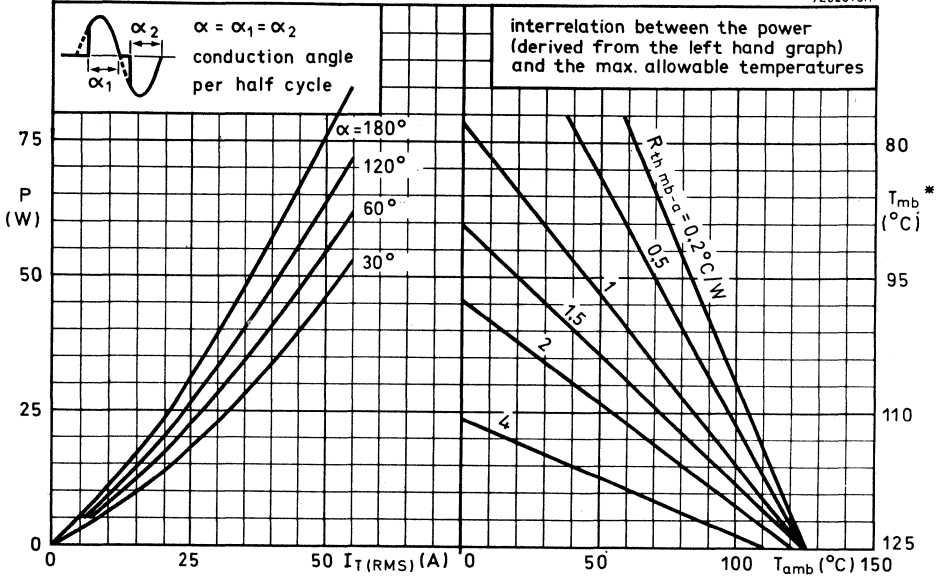
$V_{GD} < 0,2$

0,2 V

\* Measured under pulse conditions to avoid excessive dissipation.

FULL CYCLE OPERATION

7262078.1

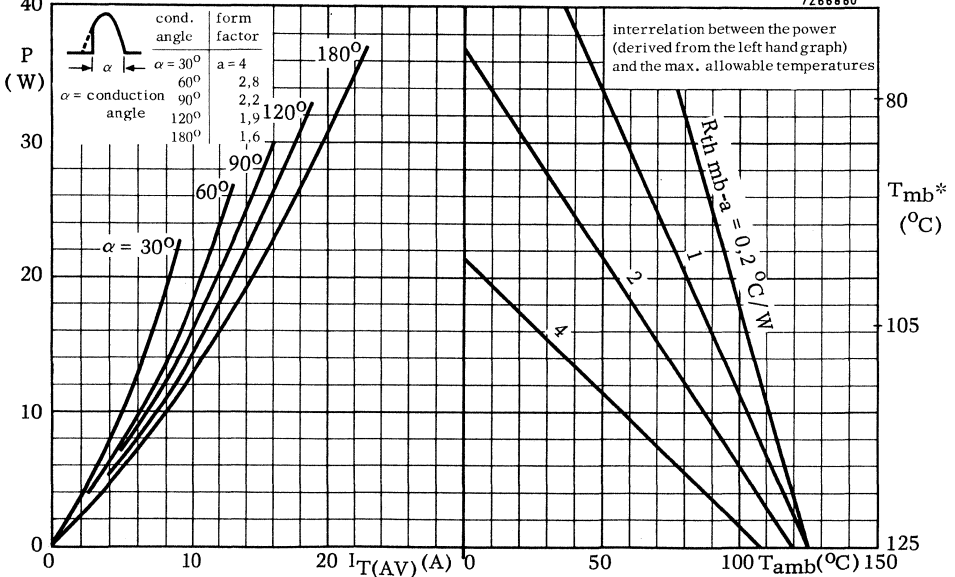


\*  $T_{mb}$ -scale is for comparison purposes only and is correct only for  $R_{th\ mb-a} \leq 1.4\ ^\circ C/W$

Fig. 2.

HALF CYCLE OPERATION

7266860



\*  $T_{mb}$ -scale is for comparison purposes only and is correct only for  $R_{th\ mb-a} \leq 0.8\ ^\circ C/W$

Fig. 3.

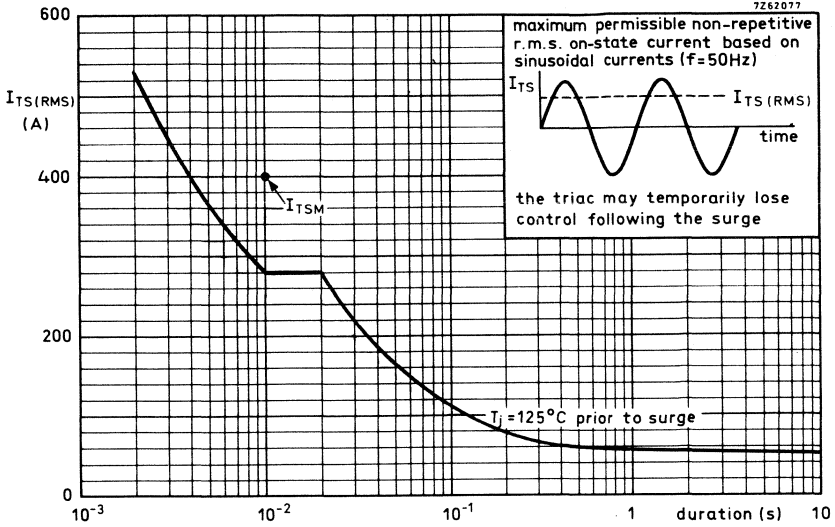


Fig. 4.

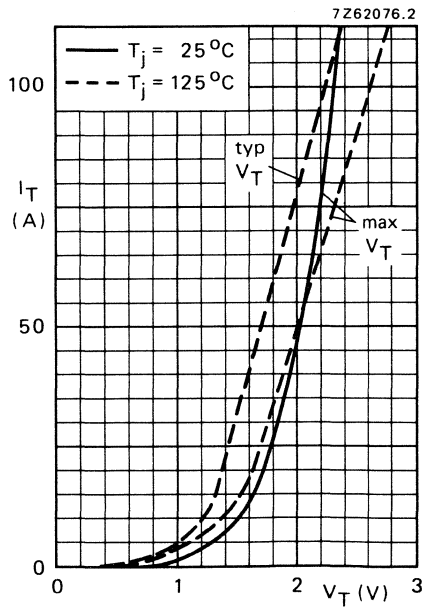


Fig. 5.

7Z62935

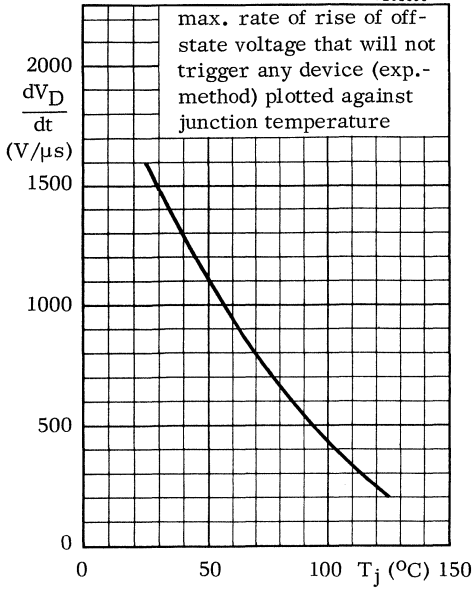


Fig. 6.

7Z62932

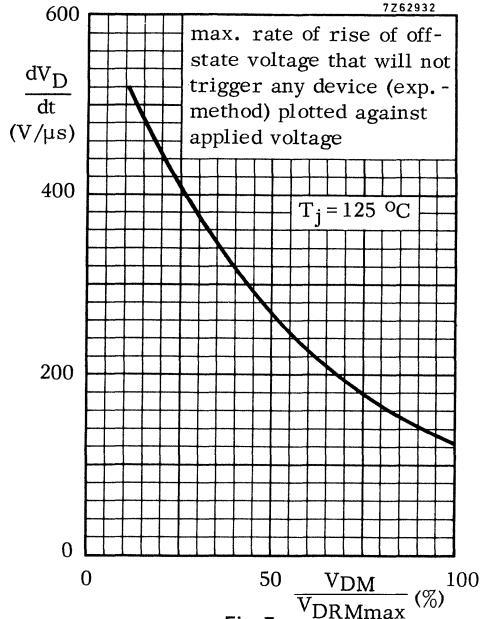


Fig. 7.

7Z62933

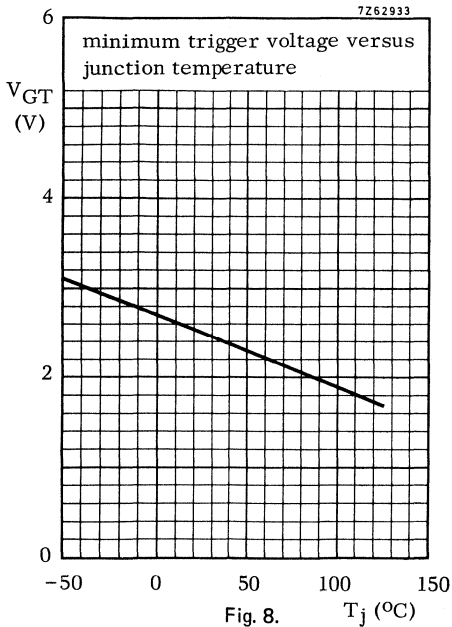


Fig. 8.

7Z62934

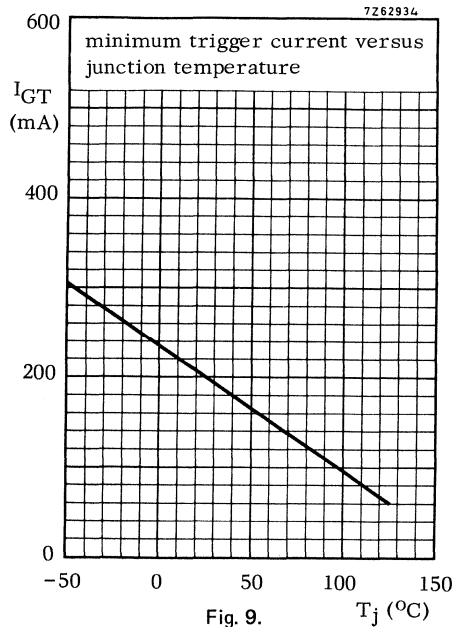


Fig. 9.



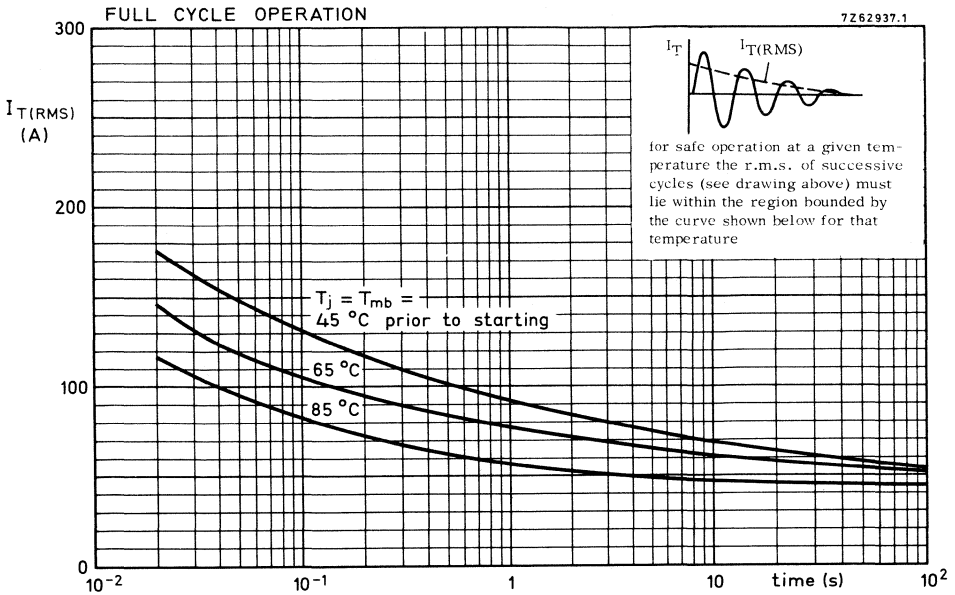


Fig. 10.

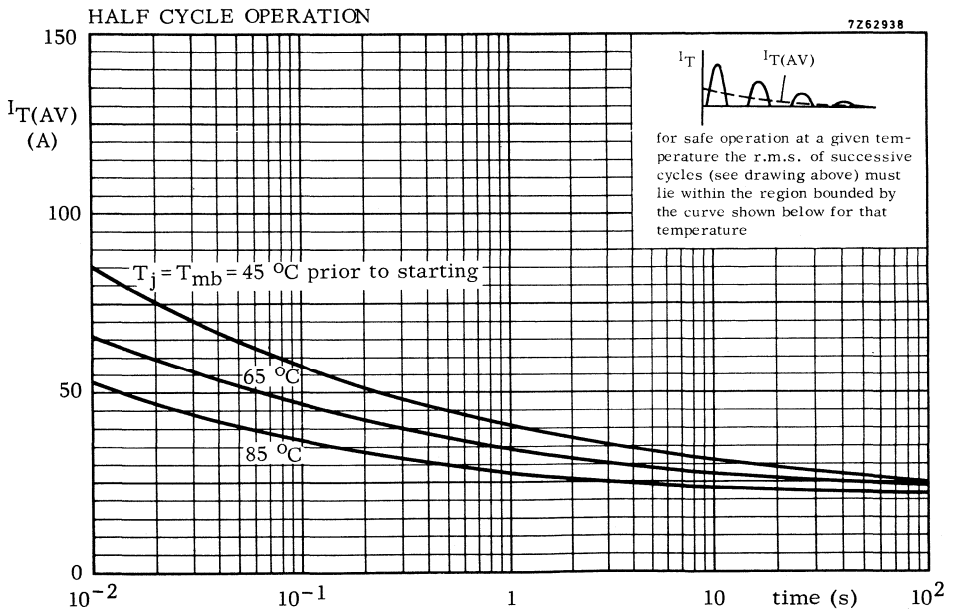


Fig. 11.

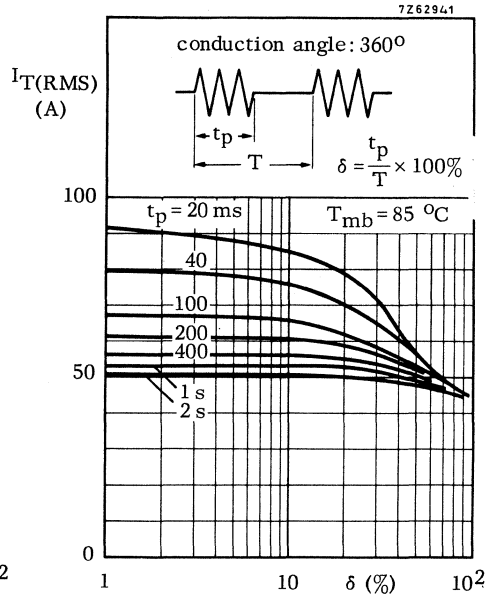
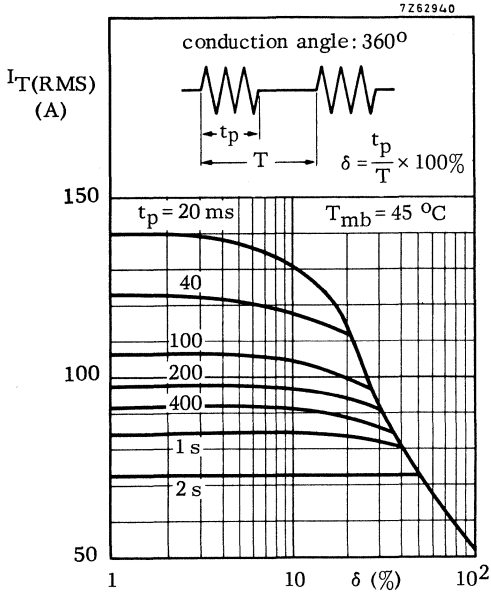


Fig. 12 Intermittent overload capability of one triac in a single phase a.c. control circuit.

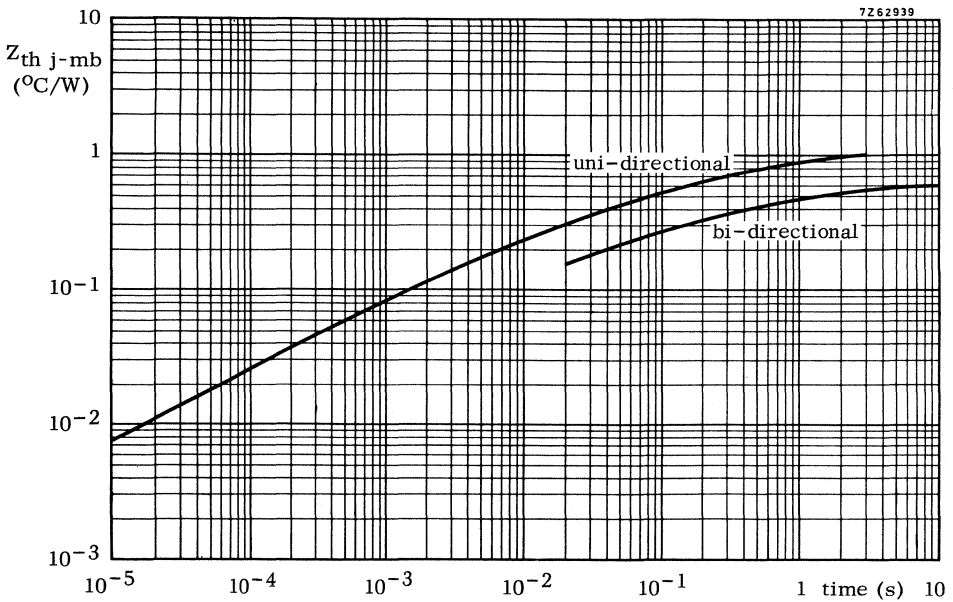


Fig. 13.

### TRIACS

A range of glass-passivated triacs in plastic envelopes with push-on connectors. They are intended for use in industrial a.c. power control applications such as motor and heating controls, and switching systems.

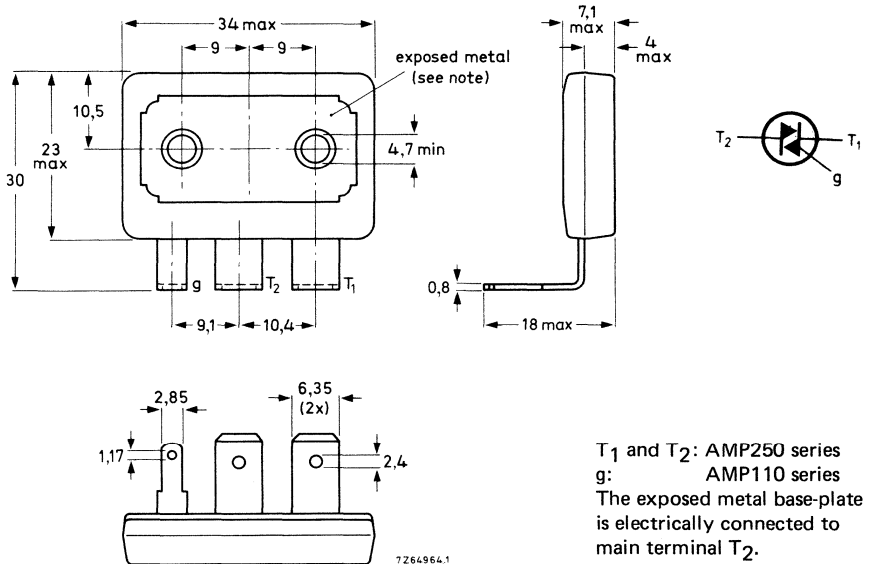
#### QUICK REFERENCE DATA

		BTW41-500G	600G	800G
Repetitive peak off-state voltage	$V_{DRM}$	max. 500	600	800 V
R.M.S. on-state current	$I_T(RMS)$	max.	40	A
Non-repetitive peak on-state current	$I_{TSM}$	max.	260	A
Rate of rise of commutating voltage that will not trigger any device	$dV_{com}/dt$	<	5	V/ $\mu$ s

#### MECHANICAL DATA

Dimensions in mm

Fig.1 SOT-80



T<sub>1</sub> and T<sub>2</sub>: AMP250 series  
 g: AMP110 series  
 The exposed metal base-plate is electrically connected to main terminal T<sub>2</sub>.

Recommended diameter of fixing screws: 4 mm

Net mass: 15 g  
 Torque on fixing screws:  
 min. 0,8 Nm (8 kg cm)  
 max. 1,5 Nm (15 kg cm)



## TRIACS

Also available to BS9343-F001

Silicon triacs in metal envelopes, intended for industrial a.c. power control and are particularly suitable for static switching of 3-phase induction motors. They may also be used for furnace control, lighting control and other static switching applications up to an r.m.s. on-state current of 15 A.

Two grades of commutation performance are available, 10 V/μs at 5 A/ms (suffix G) and 10 V/μs at 12 A/ms (suffix H).

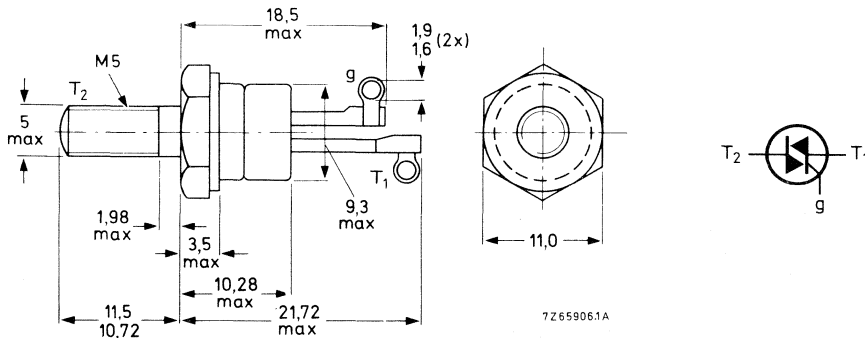
### QUICK REFERENCE DATA

	BTW43-600			
	800	1000	1200	
Repetitive peak off-state voltage	$V_{DRM}$ max. 600	800	1000	1200 V
R.M.S. on-state current	$I_T(RMS)$		max. 15 A	
Non-repetitive peak on-state current	$I_{TSM}$		max. 120 A	
Rate of rise of commutating voltage that will not trigger any device (see page 3)	$dV_{com}/dt$		<	10 V/μs

### MECHANICAL DATA

Dimensions in mm

Fig. 1 TO-64: with metric M5 stud (φ 5 mm).



Net mass: 7 g  
 Diameter of clearance hole: max. 5,2 mm  
 Accessories supplied on request: 56295  
 (PTFE bush, 2 mica washers, plain washer, tag)

Torque on nut: min. 0,9 Nm  
 (9 kg cm)  
 max. 1,7 Nm  
 (17 kg cm)

Supplied with the device: 1 nut, 1 lock washer  
 Nut dimensions across the flats: 8,0 mm

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

### Voltages (in either direction)\*

Non-repetitive peak off-state voltage  
( $t \leq 10$  ms)

	BTW43-600	800	1000	1200
$V_{DSM}$	max. 600	800	1000	1200 V

Repetitive peak off-state voltage

$V_{DRM}$	max. 600	800	1000	1200 V
-----------	----------	-----	------	--------

Crest working off-state voltage

$V_{DWM}$	max. 400	600	700	800 V
-----------	----------	-----	-----	-------

### Currents (in either direction)

R.M.S. on-state current (conduction angle  $360^\circ$ )

up to  $T_{mb} = 75^\circ\text{C}$

at  $T_{mb} = 85^\circ\text{C}$

$I_T(\text{RMS})$  max. 15 A

$I_T(\text{RMS})$  max. 12 A

Average on-state current for half-cycle operation

(averaged over any 20 ms period)

up to  $T_{mb} = 35^\circ\text{C}$

at  $T_{mb} = 85^\circ\text{C}$

$I_T(\text{AV})$  max. 9,5 A

$I_T(\text{AV})$  max. 5,5 A

Repetitive peak on-state current

$I_{TRM}$  max. 50 A

Non-repetitive peak on-state current

$T_j = 125^\circ\text{C}$  prior to surge;  $t = 20$  ms; full sine-wave

$I_{TSM}$  max. 120 A

$I^2 t$  for fusing ( $t = 10$  ms)

$I^2 t$  max. 72 A<sup>2</sup>s

Rate of rise of on-state current after triggering with

$I_G = 0,5$  A to  $I_T = 25$  A;  $dI_G/dt = 0,5$  A/ $\mu$ s

$dI_T/dt$  max. 50 A/ $\mu$ s

### Gate to terminal 1

#### Power dissipation

Average power dissipation (averaged over any 20 ms period)

$P_G(\text{AV})$  max. 1 W

Peak power dissipation

$P_{GM}$  max. 10 W

#### Temperatures

Storage temperature

$T_{stg}$  - 55 to + 125  $^\circ\text{C}$

Junction temperature

$T_j$  max. 125  $^\circ\text{C}$

## THERMAL RESISTANCE

From junction to mounting base

full-cycle operation

$R_{th\ j-mb}$  = 2,0  $^\circ\text{C/W}$

half-cycle operation

$R_{th\ j-mb}$  = 4,0  $^\circ\text{C/W}$

From mounting base to heatsink with heatsink compound

$R_{th\ mb-h}$  = 0,5  $^\circ\text{C/W}$

Transient thermal impedance;  $t = 1$  ms

$Z_{th\ j-mb}$  = 0,2  $^\circ\text{C/W}$

\* To ensure thermal stability:  $R_{th\ j-a} < 6$   $^\circ\text{C/W}$  (full-cycle or half-cycle operation). For smaller heat-sinks  $T_{j\ max}$  should be derated (see Figs 2 and 3).

**CHARACTERISTICS**

Polarities positive or negative, are identified with respect to  $T_1$ .

**Voltages** (in either direction)

On-state voltage

$$I_T = 20 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$$

$$V_T < 2,2 \text{ V}^*$$

Rate of rise of off-state voltage that will not trigger any device;

$$\text{exponential method; } V_D = 2/3 V_{DRMmax}; T_j = 125 \text{ }^\circ\text{C}$$

$$dV_D/dt < 200 \text{ V}/\mu\text{s}$$

Rate of rise of commutating voltage that will not trigger any device;

$$I_T(\text{RMS}) = 12 \text{ A}; V_D = V_{DWMmax}; T_{mb} = 85 \text{ }^\circ\text{C}$$

$$\frac{dV_{com}/dt \text{ (V}/\mu\text{s)}}{-dI_T/dt \text{ (A/ms)}}$$

BTW43-600G to 1200G

$$< 10$$

$$5$$

BTW43-600H to 1200H

$$< 10$$

$$12 \quad \leftarrow$$

**Currents** (in either direction)

Off-state current

$$V_D = V_{DWMmax}; T_j = 125 \text{ }^\circ\text{C}$$

$$I_D < 5 \text{ mA}$$

Latching current;  $T_j = 25 \text{ }^\circ\text{C}$

G positive

$$I_L < 200$$

$$200 \text{ mA}$$

G negative

$$I_L < 200$$

$$200 \text{ mA}$$

Holding current;  $T_j = 25 \text{ }^\circ\text{C}$

G positive or negative

$$I_H < 100$$

$$100 \text{ mA}$$

*Gate to terminal 1*

Voltage and current that will trigger all devices

$$V_D = 12 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$$

G positive

$$\begin{cases} V_{GT} > 2,5 \\ I_{GT} > 100 \end{cases}$$

$$5,0 \text{ V}$$

$$I_{GT} > 100$$

$$200 \text{ mA}$$

G negative

$$\begin{cases} -V_{GT} > 2,5 \\ -I_{GT} > 100 \end{cases}$$

$$2,5 \text{ V}$$

$$-I_{GT} > 100$$

$$100 \text{ mA}$$

Voltage that will not trigger any device

$$V_D = V_{DRMmax}; T_j = 125 \text{ }^\circ\text{C}; \text{G positive or negative}$$

$$V_{GD} < 0,2$$

$$0,2 \text{ V}$$

\* Measured under pulse conditions to avoid excessive dissipation.

Fig. 2. FULL CYCLE OPERATION

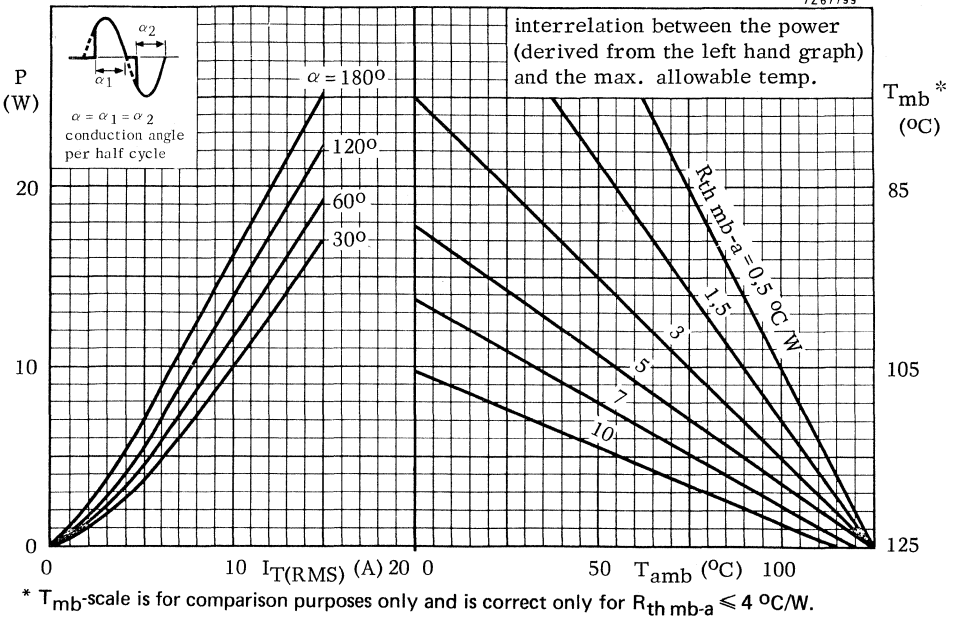
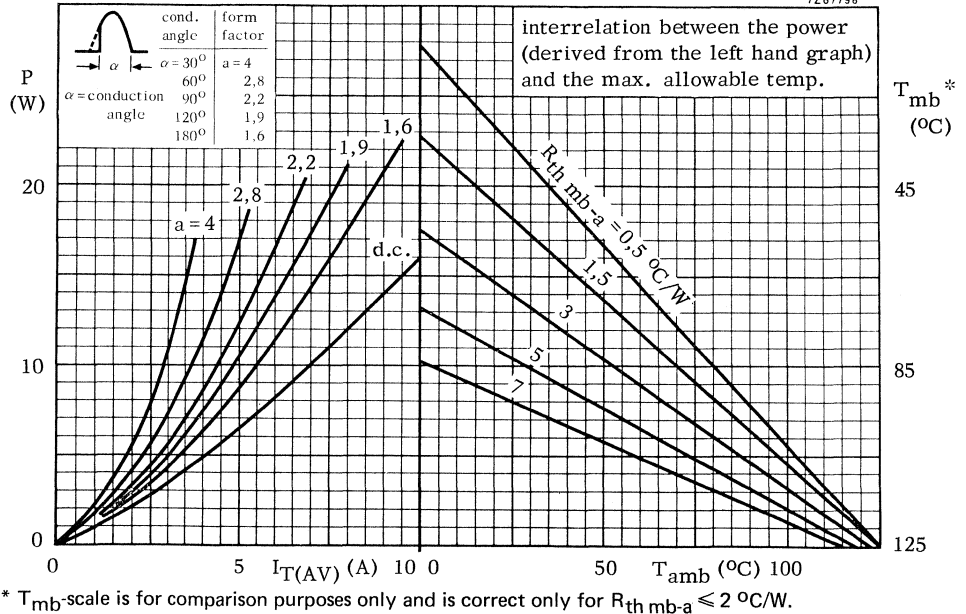
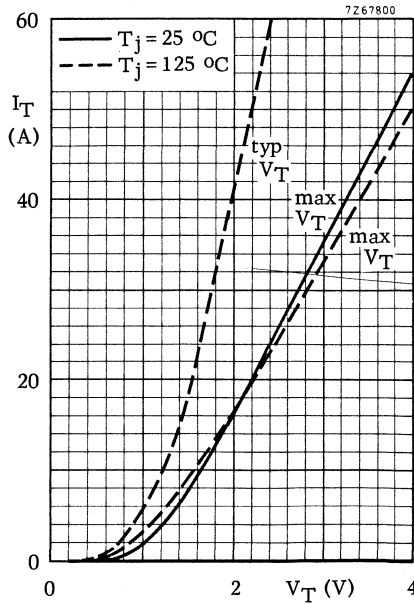
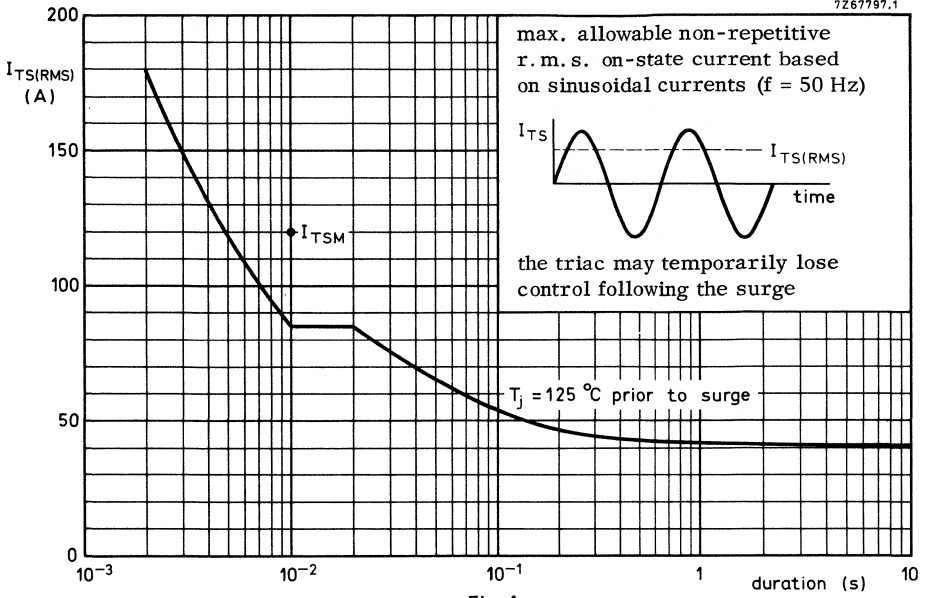


Fig. 3. HALF-CYCLE OPERATION







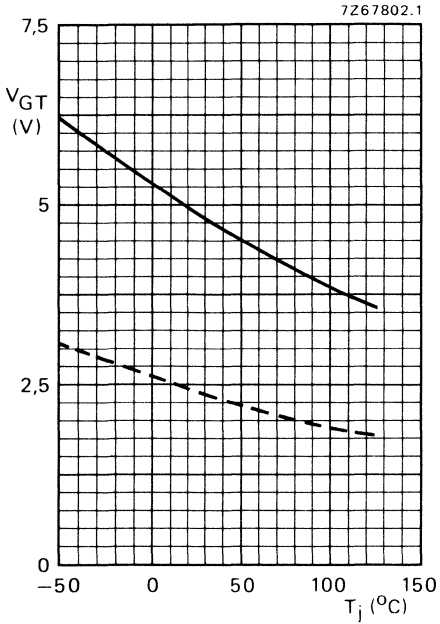


Fig. 6 Minimum gate voltage that will trigger all devices as a function of  $T_j$ .

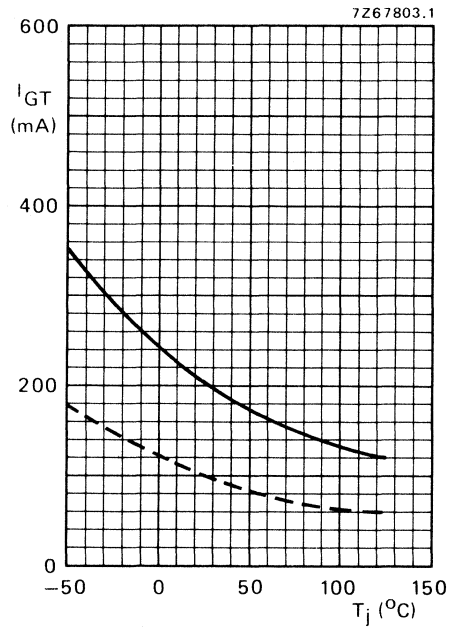


Fig. 7 Minimum gate current that will trigger all devices as a function of  $T_j$ .

Conditions for Figs 6 and 7:

- $T_2$  negative, gate positive with respect to  $T_1$
- all other conditions

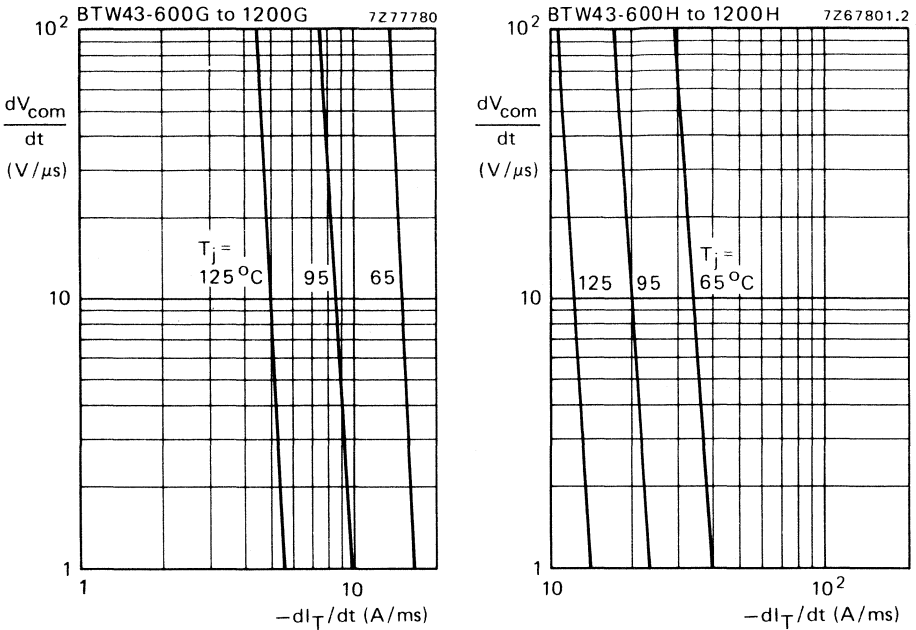


Fig. 8 Maximum rate of rise of commutating voltage that will not trigger any device as a function of rate of fall of on-state current;  $I_T(\text{RMS}) = 12 \text{ A}$ ;  $V_D = V_{DWMmax}$ .

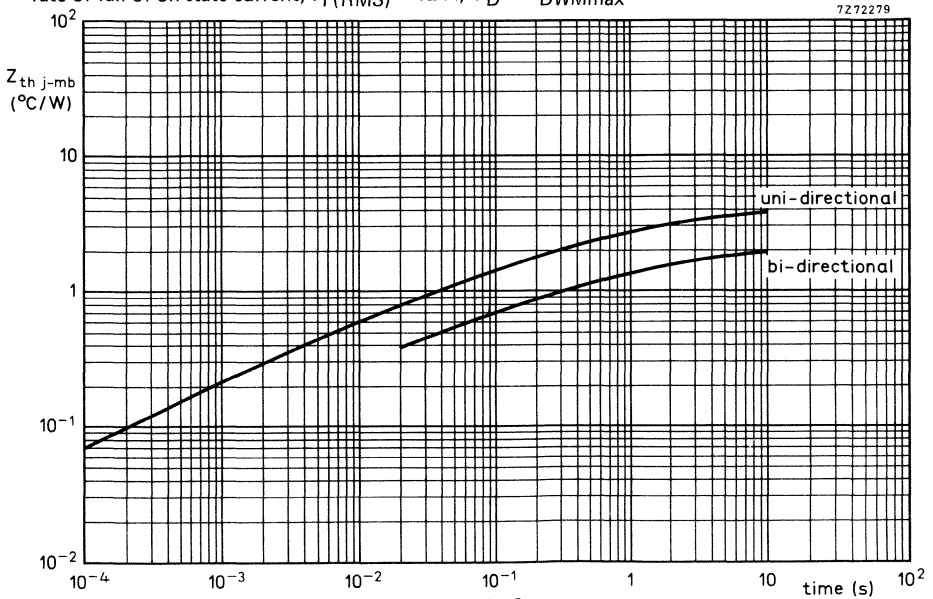


Fig. 9.

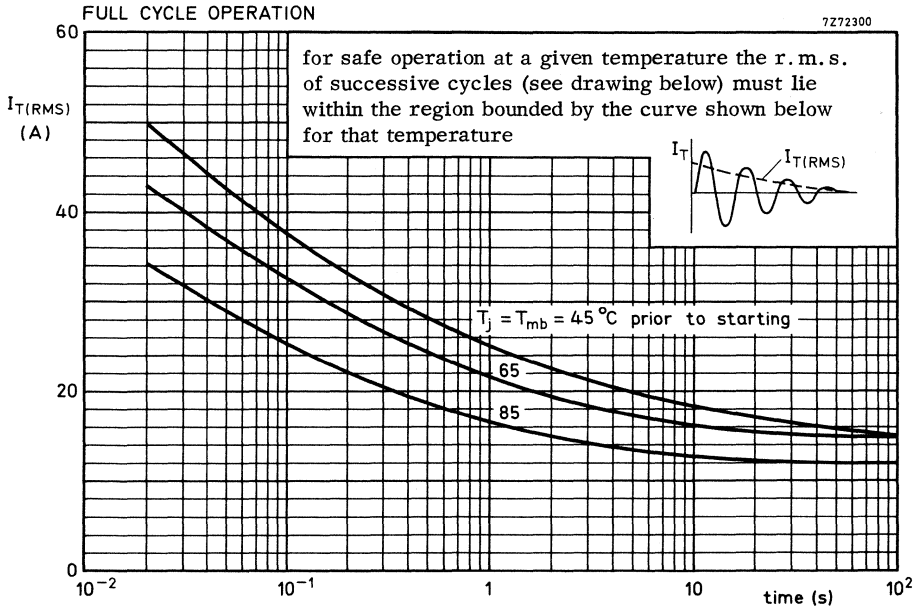


Fig. 10.

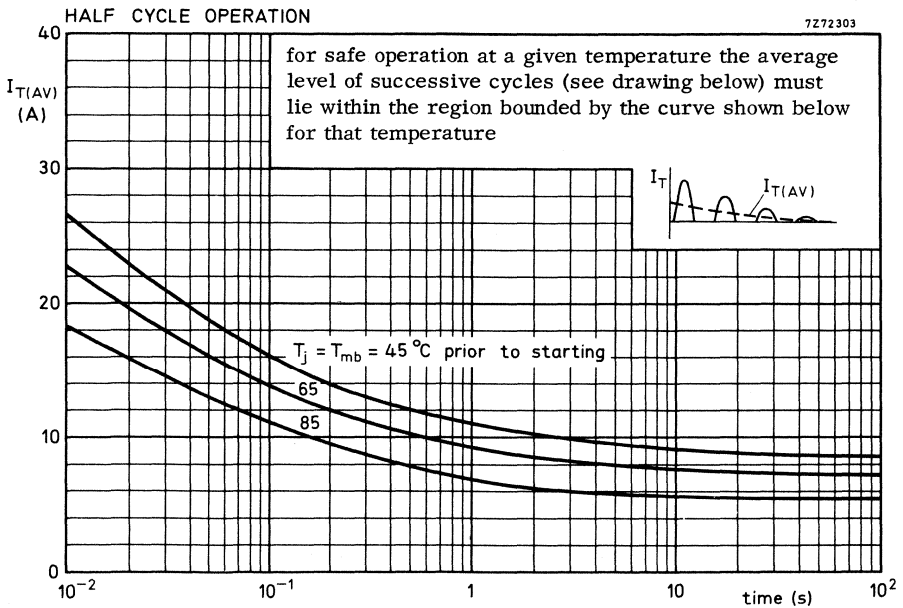


Fig. 11.

## TRIACS

Silicon triacs in metal envelopes, intended for industrial single-phase and three-phase inductive load applications such as regenerative motor control systems. They are also suitable for furnace temperature control and static switching systems.

Two grades of commutation performance are available, 30 V/μs at 25 A/ms (suffix H) and 30 V/μs at 50 A/ms (suffix J).

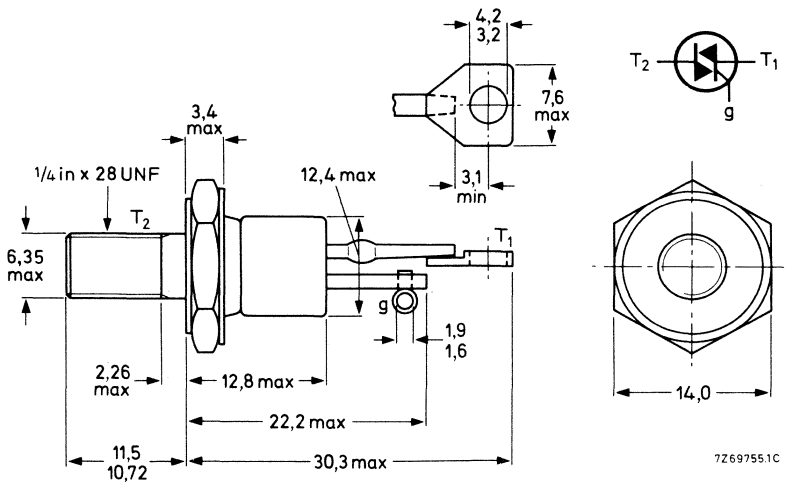
### QUICK REFERENCE DATA

		BTX94-400				600	800	1000	1200		
Repetitive peak off-state voltage	$V_{DRM}$	max.	400	600	800	1000	1200	V			
R.M.S. on-state current			$I_T(RMS)$		max.	25		A			
Non-repetitive peak on-state current			$I_{TSM}$		max.	250		A			
Rate of rise of commutating voltage that will not trigger any device (see page 3)			$dV_{com}/dt$		<	30		V/μs			

### MECHANICAL DATA

Dimensions in mm

Fig. 1 TO-48.



Net mass: 14 g  
 Diameter of clearance hole: max. 6,5 mm  
 Accessories supplied on request: 56264A  
 (mica washer, insulating ring, soldering tag)

Torque on nut: min. 1,7 Nm (17 kg cm)  
 max. 3,5 Nm (35 kg cm)  
 Supplied with the device:  
 1 nut, 1 lock washer  
 Nut dimensions across the flats; 11,1 mm

## RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

**Voltages** (in either direction) \*

		BTX94-400	600	800	1000	1200	
Non-repetitive peak off-state voltage ( $t \leq 10$ ms)	$V_{DSM}$	max. 400	600	800	1000	1200	V **
Repetitive peak off-state voltage	$V_{DRM}$	max. 400	600	800	1000	1200	V
Crest working off-state voltage	$V_{DWM}$	max. 200	400	600	700	800	V

**Currents** (in either direction)

R.M.S. on-state current (conduction angle 360°) at $T_{mb} = 85$ °C	$I_T(RMS)$	max.	25	A
Repetitive peak on-state current	$I_{TRM}$	max.	100	A
Non-repetitive peak on-state current $T_j = 125$ °C prior to surge; $t = 20$ ms; full sine-wave	$I_{TSM}$	max.	250	A
$I^2t$ for fusing ( $t = 10$ ms)	$I^2t$	max.	320	A <sup>2</sup> s
Rate of rise of on-state current after triggering with $I_G = 750$ mA to $I_T = 100$ A	$dI_T/dt$	max.	50	A/ $\mu$ s

*Gate to terminal 1*

**Power dissipation**

Average power dissipation (averaged over any 20 ms period)	$P_G(AV)$	max.	1	W
Peak power dissipation	$P_{GM}$	max.	5	W

**Temperatures**

Storage temperature	$T_{stg}$	-55 to + 125	°C	
Junction temperature	$T_j$	max.	125	°C

**THERMAL RESISTANCE**

From junction to mounting base full-cycle operation	$R_{th j-mb}$	=	1,0	°C/W
half-cycle operation	$R_{th j-mb}$	=	2,0	°C/W
From mounting base to heatsink with heatsink compound	$R_{th mb-h}$	=	0,2	°C/W
Transient thermal impedance; $t = 1$ ms	$Z_{th j-mb}$	=	0,12	°C/W

\* To ensure thermal stability:  $R_{th j-a} < 3,5$  °C/W (full-cycle or half-cycle operation). For smaller heatsinks  $T_{j max}$  should be derated (see Figs 2 and 3).

\*\* Although not recommended, higher off-state voltages may be applied without damage, but the triac may switch into the on-state. The rate of rise of on-state current should not exceed 50 A/ $\mu$ s.

**CHARACTERISTICS**

Polarities, positive or negative, are identified with respect to  $T_1$ .

**Voltages (in either direction)**

On-state voltage

$$I_T = 50 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$$

$$V_T < 2 \text{ V}^*$$

Rate of rise of off-state voltage that will not trigger any device; exponential method;

$$V_D = 2/3 V_{DRMmax}; T_j = 125 \text{ }^\circ\text{C}$$

$$dV_D/dt < 100 \text{ V}/\mu\text{s}$$

Rate of rise of commutating voltage that will not trigger any device;

$$I_T(\text{RMS}) = 25 \text{ A}; V_D = V_{DWMmax}; T_{mb} = 85 \text{ }^\circ\text{C}$$

$dV_{com}/dt \text{ (V}/\mu\text{s)}$	$-dI_T/dt \text{ (A/ms)}$
< 30	25
< 30	50

BTX94-400H to 1200H

BTX94-400J to 1200J

←

**Currents (in either direction)**

Off-state current

$$V_D = V_{DWMmax}; T_j = 125 \text{ }^\circ\text{C}$$

$$I_D < 5 \text{ mA}$$

Latching current;  $T_j = 25 \text{ }^\circ\text{C}$

G positive

G negative

	$T_2 \text{ pos.}$	$T_2 \text{ neg.}$
$I_L$	< 150	150 mA
$I_L$	< 350	150 mA

**Gate to terminal 1**

Voltage and current that will trigger all devices

$$V_D = 12 \text{ V}; T_j = 25 \text{ }^\circ\text{C}$$

G positive

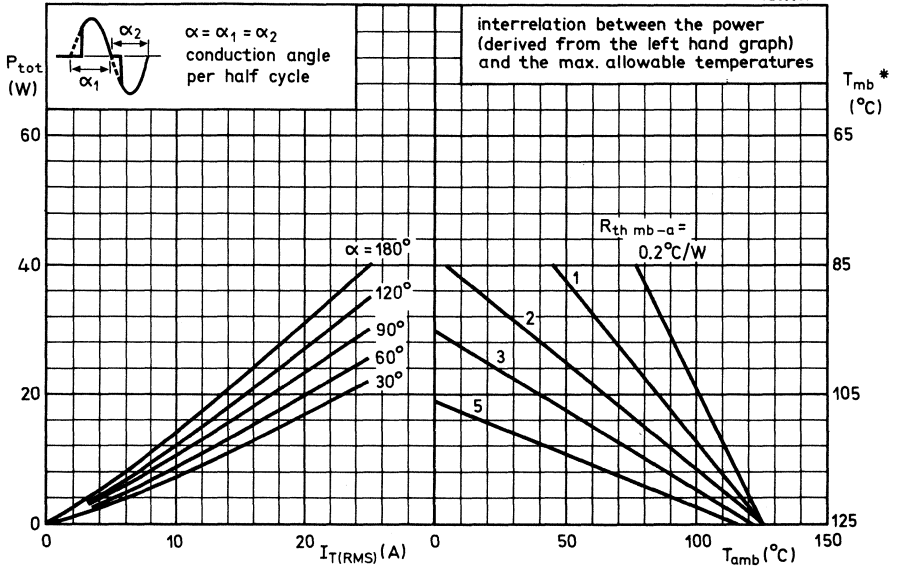
G negative

$V_{GT}$	> 3,0	5,0 V
$I_{GT}$	> 150	200 mA
$-V_{GT}$	> 3,0	3,0 V
$-I_{GT}$	> 150	150 mA

\* Measured under pulse conditions to avoid excessive dissipation.

FULL-CYCLE OPERATION

7259087

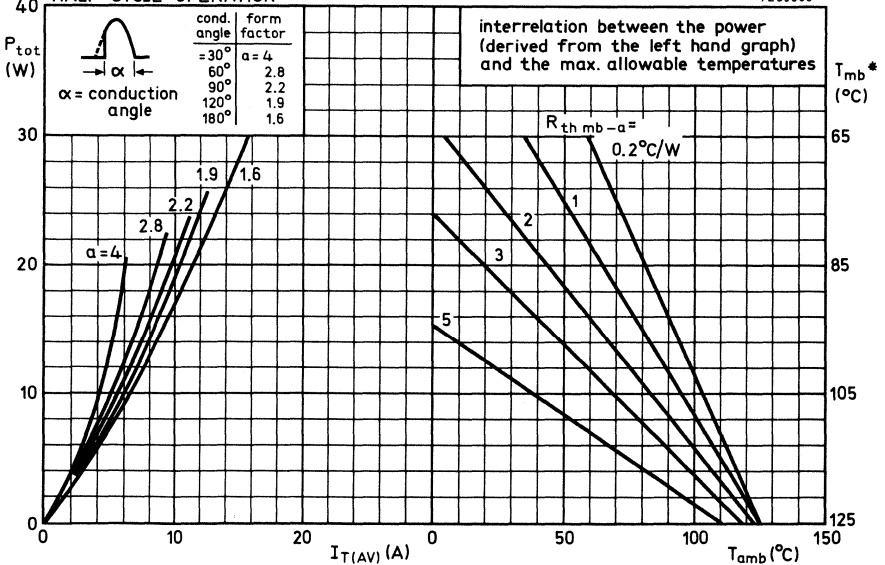


\*  $T_{mb}$ -scale is for comparison purposes only and is correct only for  $R_{th\ mb-a} \leq 2.5^\circ\text{C/W}$

Fig. 2.

HALF-CYCLE OPERATION

7259086



\*  $T_{mb}$ -scale is for comparison purposes only and is correct only for  $R_{th\ mb-a} \leq 1.5^\circ\text{C/W}$

Fig. 3.



7259088

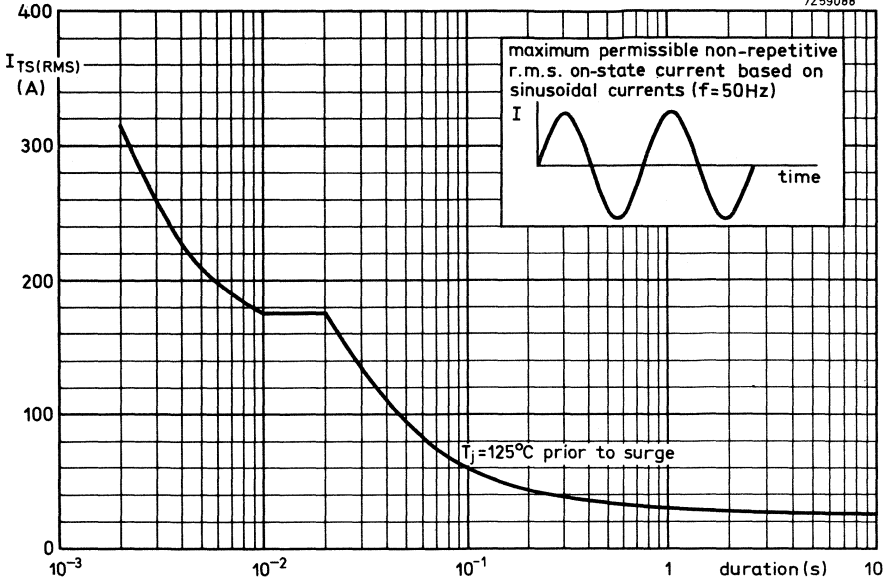


Fig. 4.

7259083.1

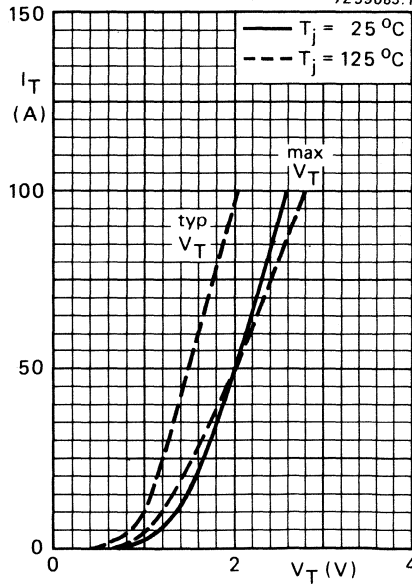


Fig. 5.

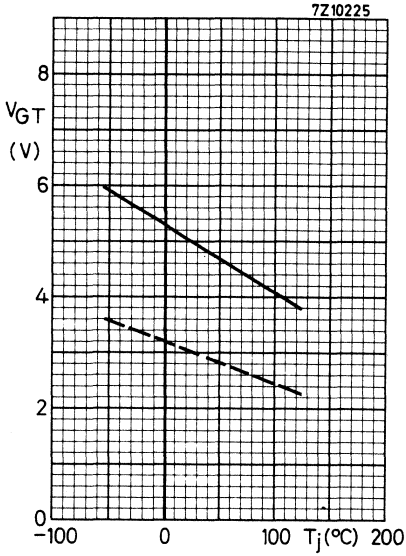


Fig. 6 Minimum gate voltage that will trigger all devices as a function of  $T_j$ .

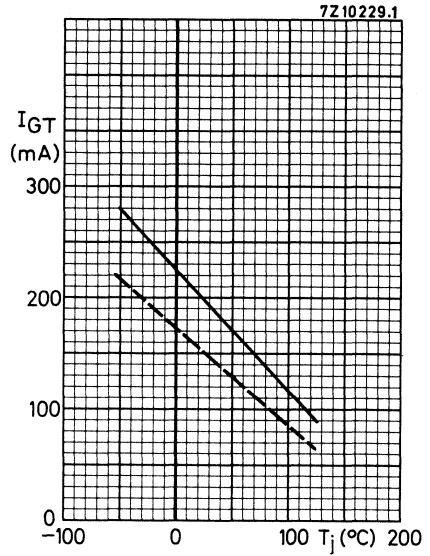


Fig. 7 Minimum gate current that will trigger all devices as a function of  $T_j$ .

Conditions for Figs 6 and 7:

- $T_2$  negative, gate positive with respect to  $T_1$
- - - all other conditions

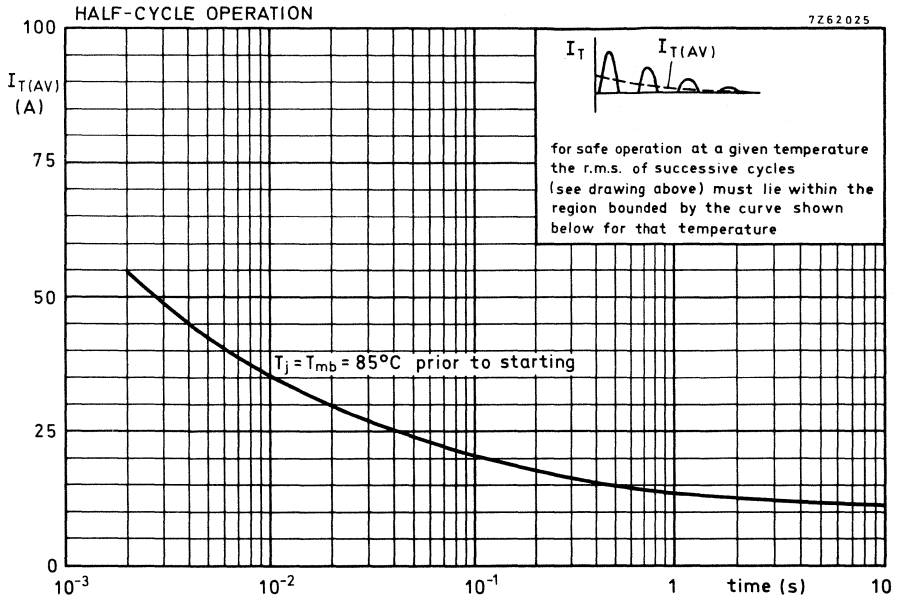


Fig. 8.

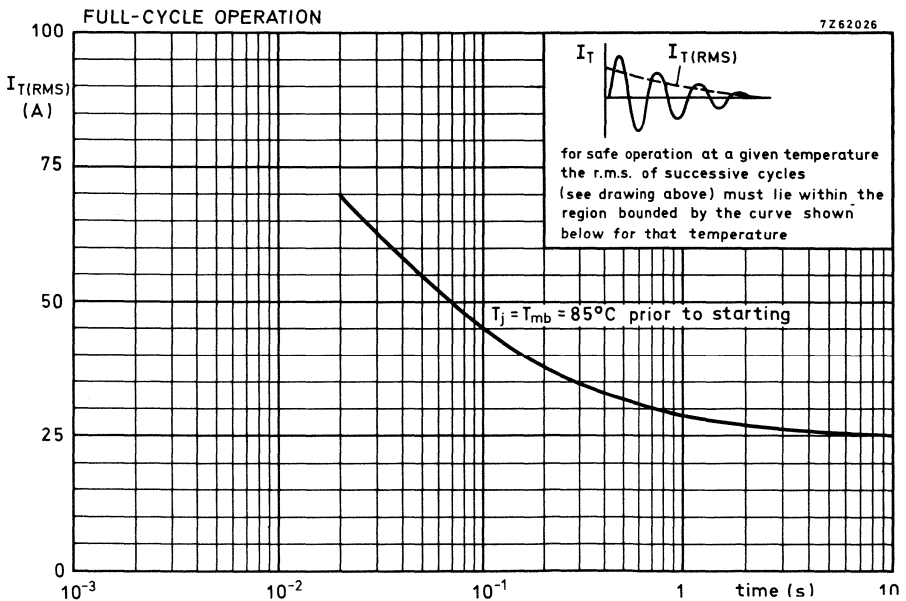


Fig. 9.

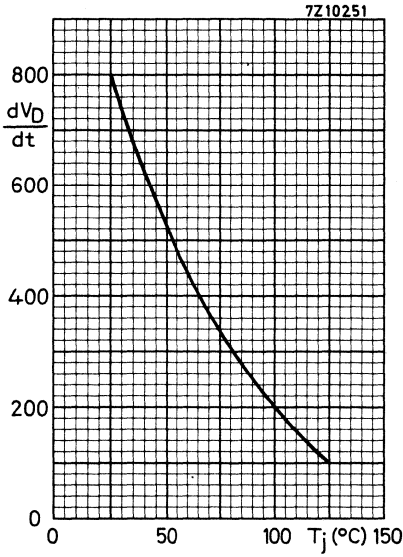


Fig. 10 Maximum rate of rise of off-state voltage that will not trigger any device (exponential method) as a function of  $T_j$ .

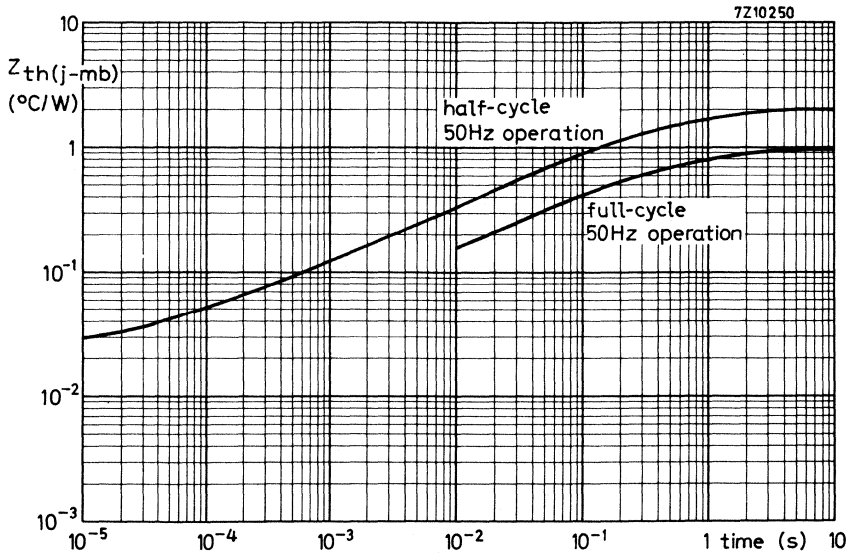


Fig. 11.

# ACCESSORIES

**G**

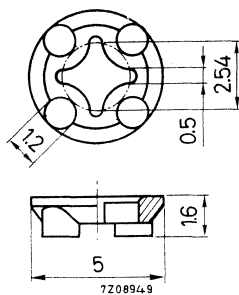


**G**

## DISTANCE DISC

For use with BRY39T  
MECHANICAL DATA

Dimensions in mm



Insulating material

## TEMPERATURE

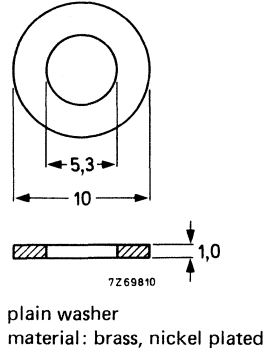
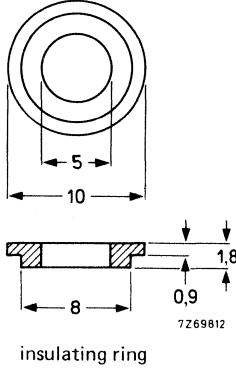
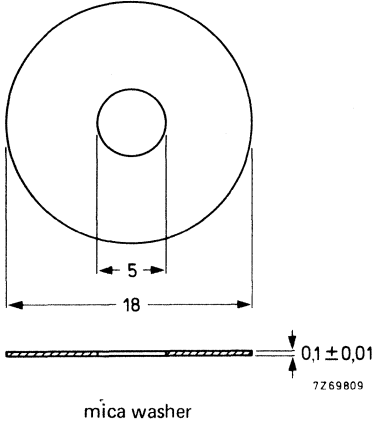
Maximum allowable temperature

 $T_{\max} = 100\text{ }^{\circ}\text{C}$

MOUNTING ACCESSORIES

MECHANICAL DATA

Dimensions in mm



→ THERMAL RESISTANCE

From mounting base to heatsink (with mica washer)  
without heatsink compound  
with heatsink compound

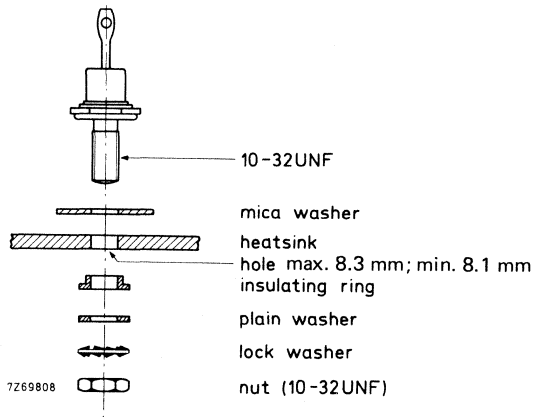
$R_{th\ mb-h}$	=	5	°C/W
$R_{th\ mb-h}$	=	2.5	°C/W

TEMPERATURE

Maximum permissible temperature

$T_{max.}$	=	125	°C
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→ MOUNTING INSTRUCTIONS



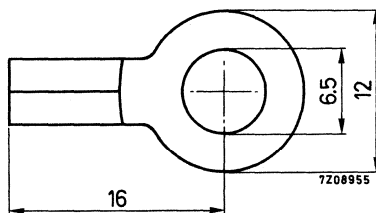
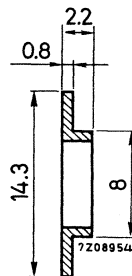
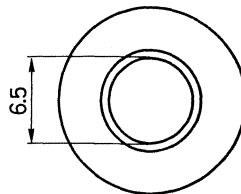
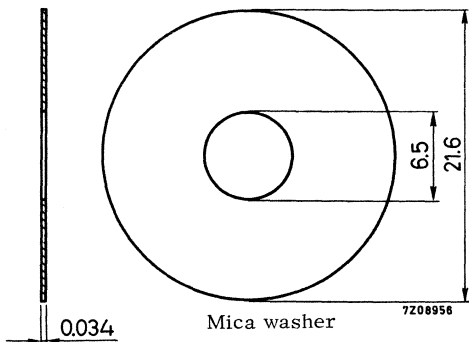
Note: When using a tag for electrical contact, insert tag between nut and plain washer or replace plain washer by tag.



## MOUNTING ACCESSORIES

### MECHANICAL DATA

Dimensions in mm



### THERMAL RESISTANCE

From mounting base to heatsink  
with mica washer, without heatsink compound  
with mica washer; with heatsink compound

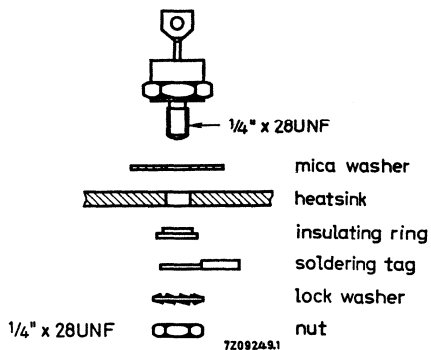
$R_{th\ mb-h}$	=	4	°C/W	
$R_{th\ mb-h}$	=	1.5	°C/W	←

### TEMPERATURE

Maximum allowable temperature

$T_{max}$	=	175	°C
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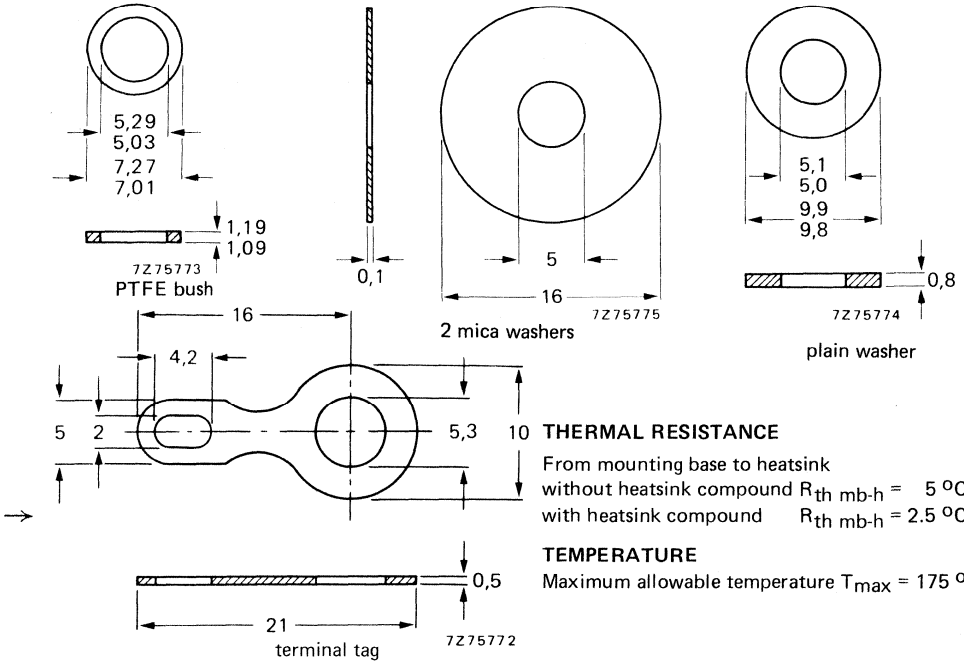
### MOUNTING INSTRUCTIONS



## MOUNTING ACCESSORIES

### MECHANICAL DATA

Dimensions in mm



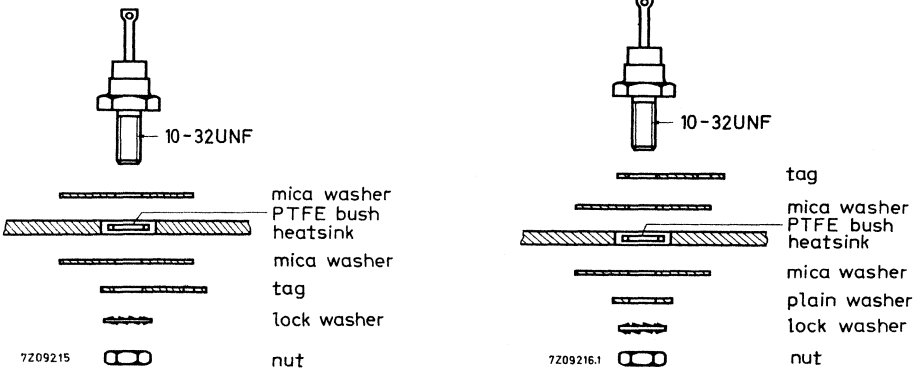
### THERMAL RESISTANCE

From mounting base to heatsink  
 without heatsink compound  $R_{th\ mb-h} = 5\text{ }^{\circ}\text{C/W}$   
 with heatsink compound  $R_{th\ mb-h} = 2.5\text{ }^{\circ}\text{C/W}$

### TEMPERATURE

Maximum allowable temperature  $T_{max} = 175\text{ }^{\circ}\text{C}$

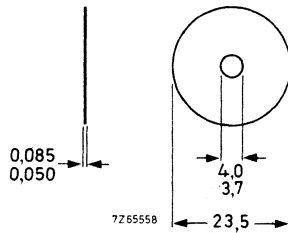
### MOUNTING INSTRUCTIONS



## MOUNTING ACCESSORIES

## MECHANICAL DATA

Dimensions in mm

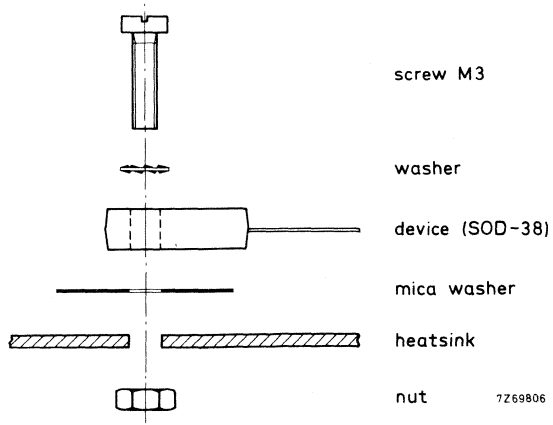


## THERMAL RESISTANCE

From mounting base to heatsink  
with heatsink compound  
without heatsink compound

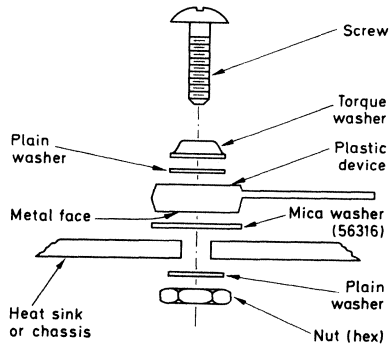
$R_{th\ mb-h}$	=	1.2	°C/W
$R_{th\ mb-h}$	=	2.3	°C/W

## MOUNTING INSTRUCTIONS



## MOUNTING ACCESSORIES

QUANTITY	DESCRIPTION
2	Steel washers, cadmium plated, I.D. 4.3 x O.D. 9.0 x 0.8 thick.
1	Hex. full nut, steel, cadmium plated 6-32 UNC.
1	Pan head screw, slotted, steel, cadmium plated, 6-32 UNC x 5/8" long.



Mounting method for plastic devices  
(Insulating method illustrated)

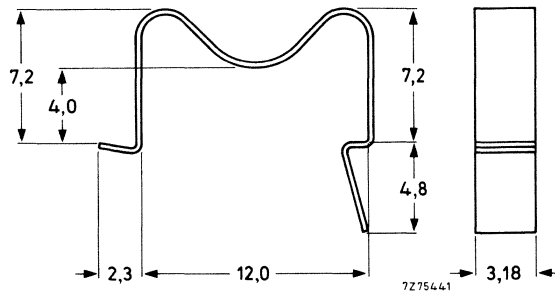
D6179

## CLIPS FOR TO-220 ENVELOPES

### MECHANICAL DATA

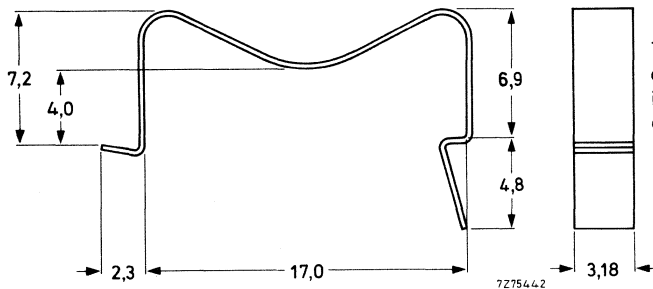
Dimensions in mm

#### 56363



Spring clip for direct mounting on heatsink of 1,0 to 2,0 mm;  
material: steel, zinc-chromate passivated.

#### 56364



Spring clip for insulated mounting on heatsink of 1,0 to 2,5 mm;  
material: steel, zinc-chromate passivated.

To be used in  
conjunction with  
insulators **56367**  
or **56369**.

Mounting instructions with  $R_{th}$  values are given separately.

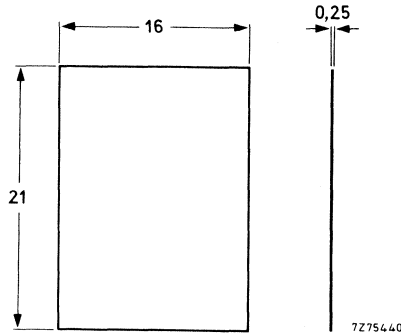
56367  
56369

## INSULATORS FOR TO-220 ENVELOPES

### MECHANICAL DATA

Dimensions in mm

56367



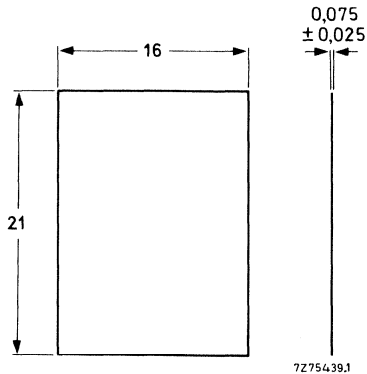
Alumina insulator (up to 2 kV) to be used in conjunction with spring clip **56364**; material: 96-alumina.\*

### THERMAL RESISTANCE

→ From mounting base to heatsink, with heatsink compound

$$R_{th\ mb-h} = 0.82\ \text{°C/W}$$

56369



Mica insulator (up to 2 kV) to be used in conjunction with spring clip **56364**.

### THERMAL RESISTANCE

→ From mounting base to heatsink, with heatsink compound

$$R_{th\ mb-h} = 2.2\ \text{°C/W}$$

\*Because alumina is brittle, extreme care must be taken, when mounting devices, not to crack the alumina, particularly when used without heatsink compound.

## CLIP FOR SOT-112 ENVELOPE

## MECHANICAL DATA

Dimensions in mm

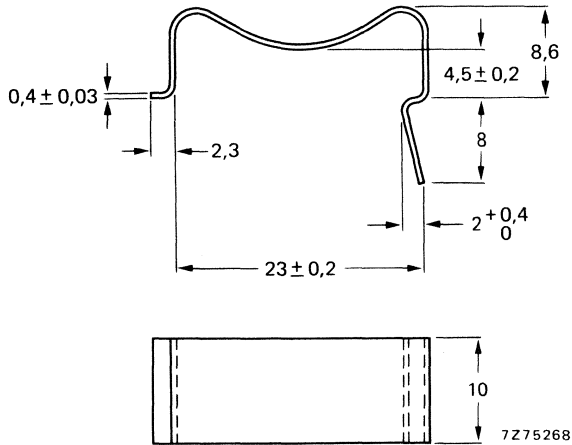


Fig. 1 Clip; material: steel, blackened (zinc-chromate passivated).

## THERMAL RESISTANCE

From mounting base to heatsink  
 with a metallic oxide-loaded compound  
 without heatsink compound

$$R_{th \text{ m-h}} = 1,0 \text{ } ^\circ\text{C/W}$$

$$R_{th \text{ m-h}} = 2,0 \text{ } ^\circ\text{C/W}$$

## MOUNTING INSTRUCTIONS

1. Place the device on the heatsink, applying a metallic oxide-loaded compound to the mounting base.
2. Push the short end of the clip into the narrow slot of the heatsink with the clip at an angle  $10^{\circ}$  to  $30^{\circ}$  to the vertical.
3. Push down the clip over the device until the long end of the clip snaps into the wide slot. The clip should bear on the middle of the plastic body.

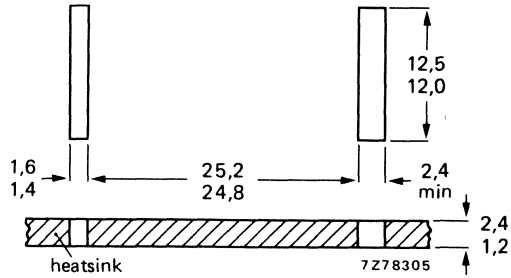


Fig. 2 Hole pattern for clip in heatsink.

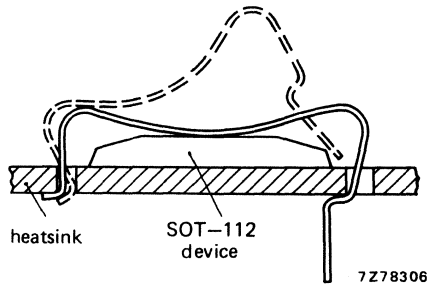


Fig. 3 Mounting of the clip.



**HEATSINKS**  
**Selection Guide**  
**General**  
**Flat Heatsinks**  
**Diecast Heatsinks**  
**Heatsink Extrusions**



**H**



Rectifier diodes  
Thyristors  
Triacs

K-code to DIN-41882

type	K15 56268	K9 56256	K9 56350	K3 56253	K3 56312	K3 56348	K1.1 56313	K1.1 56314	Extrusions 56230	56231	56290
BYX38	•								•		•
BYX39	•	•							•		•
BYX50	•								•		•
1N3879 to 3882	•								•		•
1N3889 to 3892	•	•							•	•	•
BYX98	•	•							•	•	•
BYX42	•	•							•	•	•
BYX99		•							•	•	•
BYX30		•							•	•	•
BYX25		•							•	•	•
BYX46		•							•	•	•
BYW30		•	•						•		•
BYV30		•							•		•
BYW31			•			•			•		•
BYV21		•							•		•
BYX96						•			•	•	•
BYW92				•	•		•		•	•	•
BYV92				•					•	•	•
BYW93				•					•	•	•
BYX56				•					•	•	•
BYX97					•		•		•	•	•
BYX32						•			•	•	•
BYX52				•					•	•	•
1N3899 to 3903				•					•	•	•
1N3909 to 3913				•					•	•	•
BYW25					•		•		•		•
BTY79	•	•							•		•
BTW38	•	•	•			•			•		•
BTW42	•	•	•			•			•		•
BTY87				•					•	•	•
BTY91				•					•	•	•
BTW47				•	•		•		•	•	•
BTW30S						•			•	•	•
BTW45				•	•		•		•	•	•
BTW40				•	•		•		•	•	•
BTW92				•	•		•		•	•	•
BTW31W					•		•		•	•	•
BTW24								•	•	•	•
BTW33									•	•	•
BTW23									•	•	•
BTW43			•						•	•	•
BTX94				•					•	•	•
BTW34								•	•	•	•

Heatsinks are used where a semiconductor device is unable of itself to dissipate the heat generated by its internal power losses without the junction temperature exceeding its maximum. The simplest form of heatsink is a flat metal plate, but for economy in weight, size, and cost, more complex shapes are usually used.

Apart from information on heat transfer and the construction of assemblies, this Section shows how to take advantage of reverse polarity types, describes three types of heatsink, and gives calculation examples.

**HEAT TRANSFER PATH**

In, for example, a silicon rectifier the heat is generated inside the wafer and flows mainly by way of the base, through a heatsink to the ambient air.

The heat flow can be likened to the flow of electric current, with thermal resistance ( $R_{th}$  in  $^{\circ}C/W$ ) analogous to the electric resistance ( $R$  in  $\Omega$ ).

Fig. 1 shows the heat path from junction to ambient as three thermal resistances in series:

- $R_{th\ j-mb}$  The thermal resistance from junction to mounting base. Its value is given in the data sheets of a device.
- $R_{th\ mb-h}$  The thermal resistance from mounting base to heatsink (contact thermal resistance). It is caused by the imperfect nature and limited size of the contact between the two. Its value is also given in the data sheets.
- $R_{th\ h-a}$  The thermal resistance between the contact surface mentioned above and the ambient air.

For thermal balance air warmed by the heatsink must be replaced by cool, i. e., there must be an air flow.

From Fig. 1:  $T_j - T_{amb} = P \times (R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a})$

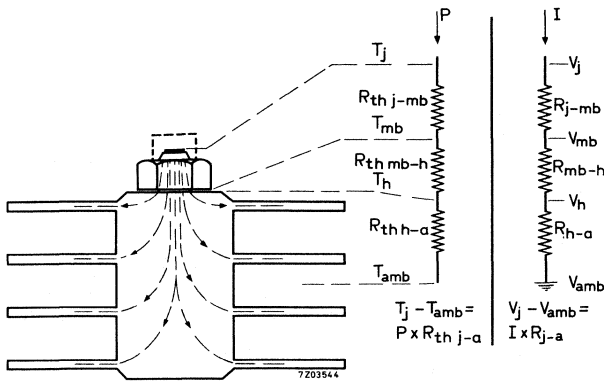


Fig. 1

## IMPROVING HEAT TRANSFER

Heat transfer can be improved by reducing the thermal resistance of the contact and the thermal resistance of the heatsink.

### Contact thermal resistance

- Make the contact area large
- Make the contact surfaces plane parallel by attention to drilling and punching, and make them burr-free.
- Apply sufficient pressure. Use a torque spanner adjusted to at least the rated minimum torque.
- Use metal oxide-loaded compound to fill air pockets.

←

### Heatsink thermal resistance

- Paint or anodise the surface to improve radiation
- Increase the flow of cooling air
- Use a larger heatsink

The simplest form of air flow is natural convection. Mount the fins vertically, make in-take and outlet apertures large, avoid obstructions, create a draught (chimney effect). A blower or fan must be used where free convection is not enough or where a smaller heatsink is wanted.

## INSULATED MOUNTING

Where a semiconductor must be insulated from its heatsink (e.g., in bridge rectifiers) by a mica or teflon washer, the contact thermal resistance will be about ten times higher than without insulation. This must be compensated by a reduction in  $R_{thh-a}$  to keep the total thermal resistance below the maximum given for  $P$  and  $T_{amb}$ . A larger heatsink may be necessary.

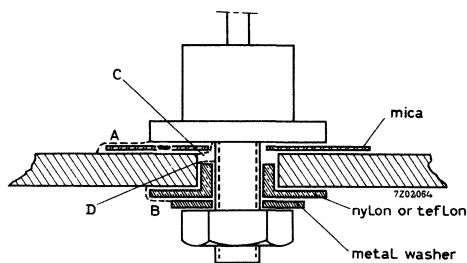


Fig. 2 Creepage distances with an insulated diode

Note: care must be taken that the creepage distances, see Fig. 2, are sufficient for the voltage involved. While A and B can be made large enough, C and D are likely to be the critical ones.

CONSTRUCTIONS

Good thermal coupling is essential to semiconductors connected in parallel to ensure good current sharing in view of the forward characteristics, and semiconductors in series in view of the reverse characteristics.

Mounting the semiconductors on the same heatsink not only saves mounting costs but also provides the needed thermal coupling.

Fig. 3 shows the construction for a plain heatsink, and Fig. 4 the construction for an extruded heatsink. The electrical connection is made with a copper strip at least 1 mm thick. For two diodes a plain heatsink should be twice the area, and an extruded heatsink twice the length needed for a single diode.

Reverse polarity devices are convenient for series connection of two diodes on a common heatsink. Figs. 5, 6 and 7 show how the use of normal polarity and reverse polarity diodes simplifies the construction of single-phase and three-phase bridge rectifiers.

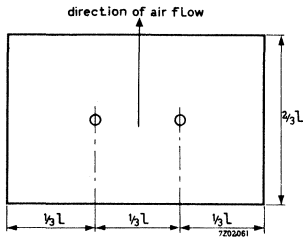


Fig. 3 Plain cooling fin with two diodes

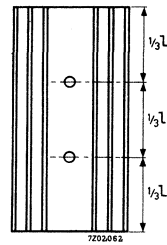


Fig. 4 Extruded aluminium heatsink with two diodes

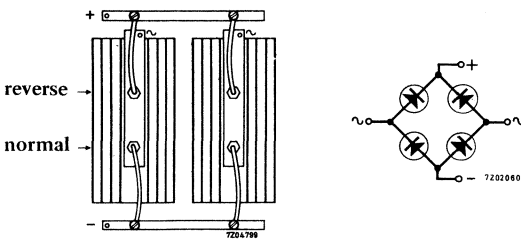


Fig. 5 Single phase full wave rectifier with diodes of different polarity on extruded aluminium heatsinks

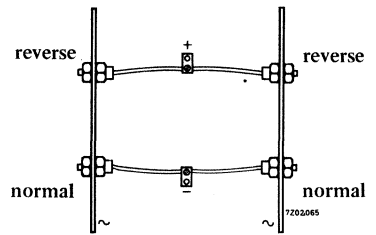


Fig. 6 Single phase full wave rectifier with diodes of different polarity on plain cooling fins (top view)



EXAMPLES OF HEATSINK CALCULATION

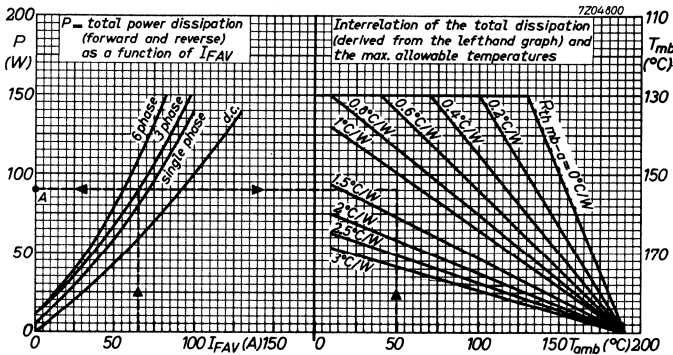
1. Devices without controlled avalanche properties.

Assume that the diode which the outlines are shown, is used in a three phase 50 Hz rectifier circuit at  $T_{amb} = 50\text{ }^{\circ}\text{C}$ . Further assume: average forward current per diode  $I_{F(AV)} = 65\text{ A}$ ; contact thermal resistance  $R_{th\text{ mb-h}} = 0,1\text{ }^{\circ}\text{C/W}$ .



Stud: M12  
Mounting base, across the flats: max. 27 mm

From the data of the diode the graph to be used is shown below.



From the lefthand graph it follows that  $P_{tot} = 90\text{ W}$  per diode (point A).  
From the righthand graph it follows that  $R_{th\text{ mb-a}} \approx 1,2\text{ }^{\circ}\text{C/W}$ .  
Thus  $R_{th\text{ h-a}} = R_{th\text{ mb-a}} - R_{th\text{ mb-h}} = (1,2 - 0,1)\text{ }^{\circ}\text{C/W} = 1,1\text{ }^{\circ}\text{C/W}$ .  
This may be achieved by different types of heatsinks as shown below.

Type	Free convection	Forced cooling
flat, blackened bright	- -	125 cm <sup>2</sup> ; 2 m/s or 300 cm <sup>2</sup> ; 1 m/s 175 cm <sup>2</sup> ; 2 m/s
diecast 56280	applicable	
extrusion		
56230 bright blackened	$l = 12\text{ cm}$ $l = 8\text{ cm}$	$l = 5\text{ cm }^1$ ; 1 m/s $l = 5\text{ cm }^1$ ; 1 m/s
56231 bright blackened	$l = 7\text{ cm}$ $l = 5\text{ cm }^1$ )	

<sup>1)</sup> Practical minimum length

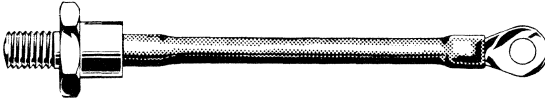


## EXAMPLES OF HEATSINK CALCULATION (continued)

### 2. Devices with controlled avalanche properties

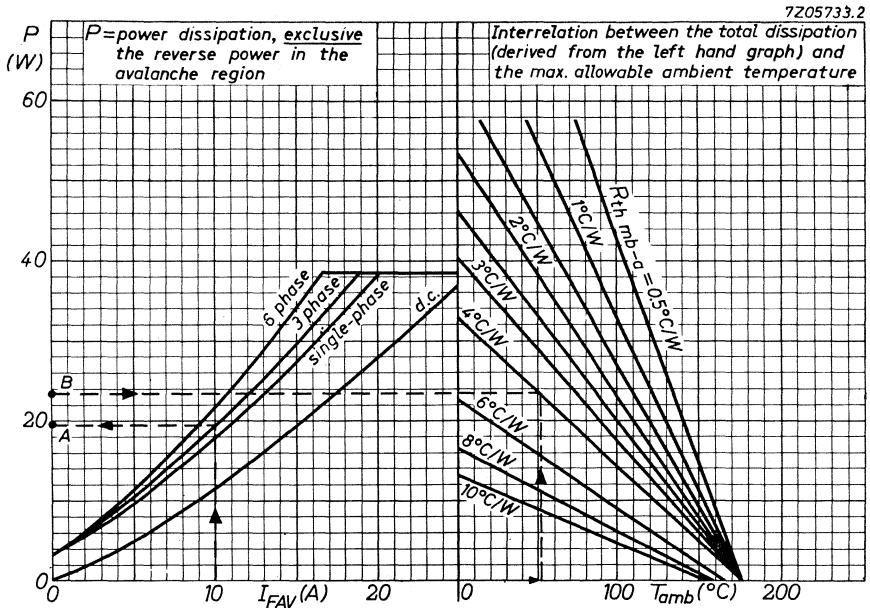
Assume that the diode of which the outlines are shown, is used in a three phase 50 Hz rectifier circuit at  $T_{amb} = 40\text{ }^{\circ}\text{C}$ . Further assume: average forward current per diode  $I_{F(AV)} = 10\text{ A}$ ; contact thermal resistance:

$R_{th\ mb-h} = 0,5\text{ }^{\circ}\text{C/W}$ ; repetitive peak reverse power in the avalanche region ( $t = 40\text{ }\mu\text{s}$ )  $P_{RRM} = 2\text{ kW}$  (per diode).



Stud: M12  
Mounting base, across the flats: max. 27 mm

From the data of this diode the graph to be used is shown below.



From the lefthand graph it follows that  $P_{tot} = 19,5\text{ W}$  per diode (point A). The average reverse power in the avalanche region, averaged over any cycle, follows from

$$P_{R(AV)} = \delta \times P_{RRM}, \text{ where the duty cycle } \delta = \frac{40\text{ }\mu\text{s}}{20\text{ ms}} = 0,002.$$

Thus  $P_{R(AV)} = 0,002 \times 2\text{ kW} = 4\text{ W}$ .

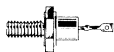
Therefore the total device power dissipation  $P_{tot} = 19,5 + 4 = 23,5\text{ W}$  (point B). From the righthand graph it follows that  $R_{th\ mb-a} = 4\text{ }^{\circ}\text{C/W}$ . Hence the heatsink thermal resistance should be:

$$R_{th\ h-a} = R_{th\ mb-a} - R_{th\ mb-h} = (4 - 0,5)\text{ }^{\circ}\text{C/W} = 3,5\text{ }^{\circ}\text{C/W}.$$

A table of applicable heatsinks, similar to that on the foregoing page, can be derived for this case.

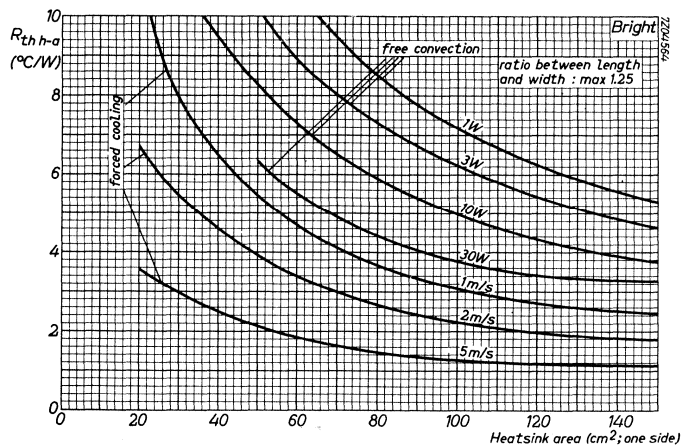
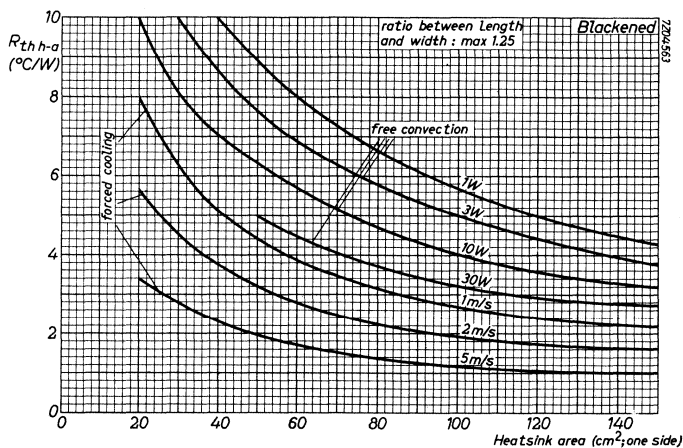
# Flat heatsink

Thermal resistance of flat heatsinks of 2 mm copper or 3 mm aluminium.  
The graphs are valid for the combination of device and heatsink.



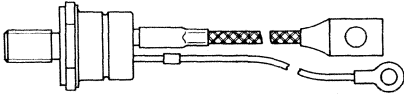
Studs: 10-32UNF

Mounting bases, across the flats; max. 11,0 mm

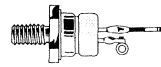


# Flat heatsink

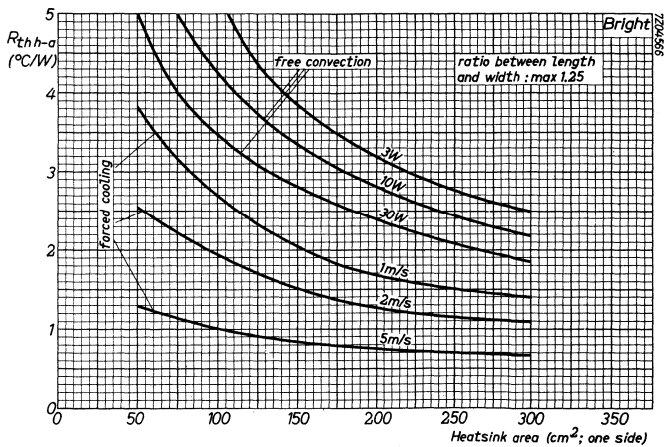
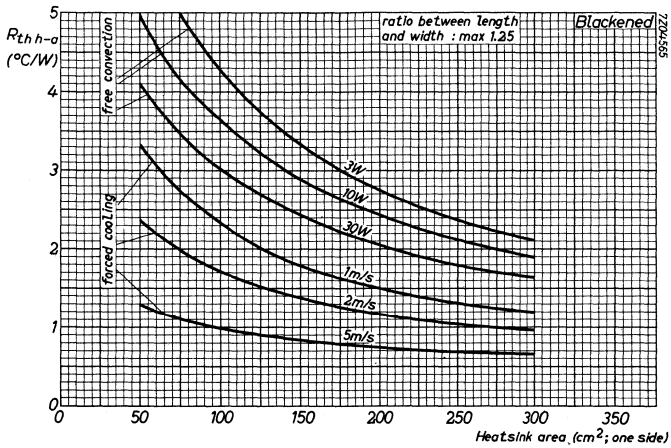
Thermal resistance of flat heatsinks of 2 mm copper or 3 mm aluminium.  
The graphs are valid for the combination of device and heatsink.



Stud: M8  
Mounting base, across the flats: max. 19 mm

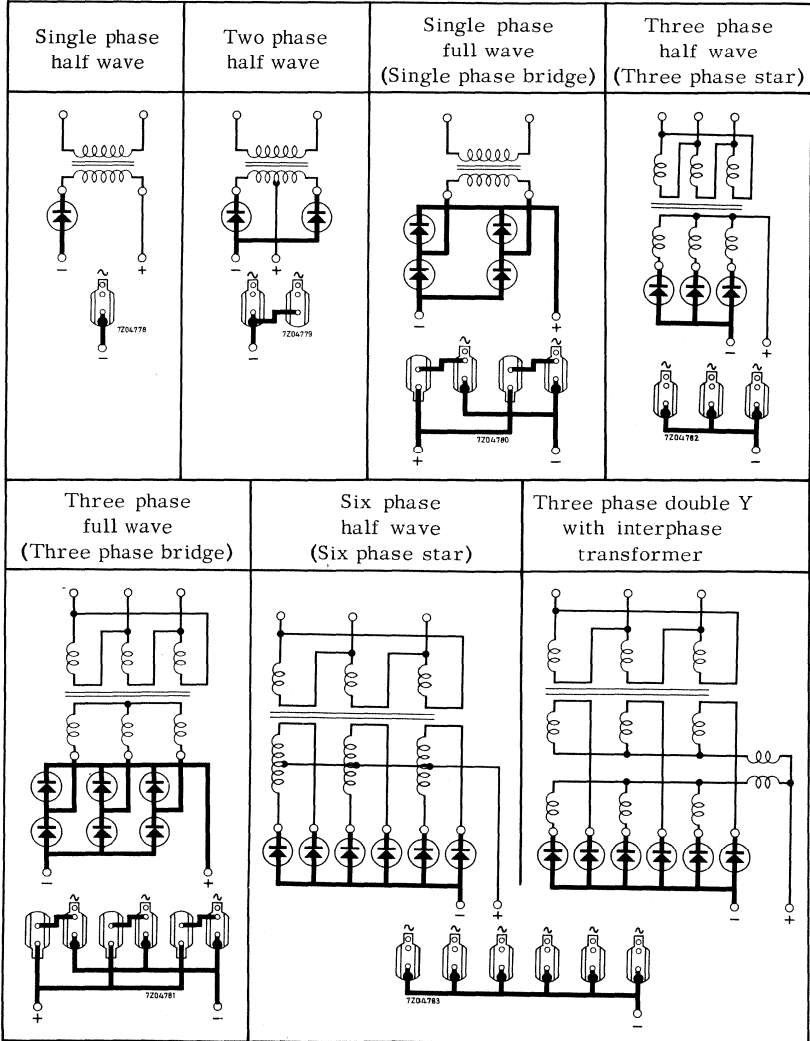


Stud: M6  
Stud:  $\frac{1}{4}$ " x 28 UNF  
Mounting base, across the flats: max. 14,0 mm



# Diecast heatsinks

## RECTIFIER CIRCUITS ON SINGLE HEATSINKS



Diecast heatsink  
without insulator



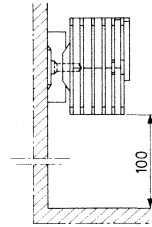
Diecast heatsink  
with insulator



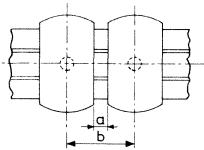
# Diecast heatsinks

## MOUNTING INSTRUCTION FOR DIECAST HEATSINKS

- At free convection cooling or forced air flow  $< 0,5 \text{ m/s}$  the heatsinks should be mounted with the fins vertical and with a distance to the chassis bottom  $> 100 \text{ mm}$ .

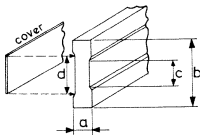


- At forced air flow  $> 0,5 \text{ m/s}$  the heatsinks may be mounted in any position.
- Minimum distance between heatsinks in a row.



Heatsink	Distance (mm)	
	a	b
56256/268	$> 5,0$	$> 25,0$
56334	$> 5,0$	$> 40,0$
56253/334	$> 10,0$	$> 50,0$
56271	$> 10,0$	$> 50,0$

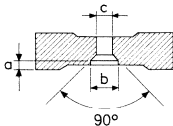
- The rectifier devices should be fixed to their heatsinks with the torques specified in the relevant published data. Use the torque spanner.
- For insulated mounting of heatsinks two sizes of mounting strips made of insulating material are available.



Length 750 mm

Strip	Dimensions (mm)				Weight (g) (with cover)
	a	b	c	d	
56233	10,0	36	14,1	22	330
56234	13,5	50	20,1	28	615

- Mounting holes to be made in the strips:



Heatsink	Strip	Dimensions in mm		
		a	b	c
56256/268	56233	$< 1,5$	7,5	4,3
56253/271	56234	$< 1,3$	10,2	6,3
56277/334	56234	$< 1,3$	10,2	6,3

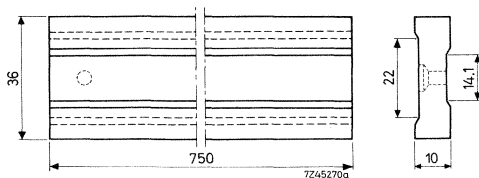


## MOUNTING STRIPS

**56233**

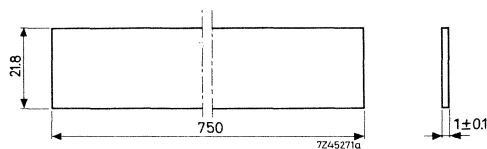
MECHANICAL DATA

Dimensions in mm



mounting strip of  
insulating material

Weight with cover:  
330 g

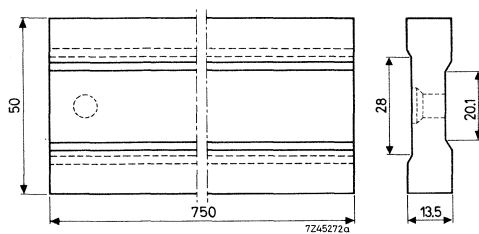


insulating plate (cover)

**56234**

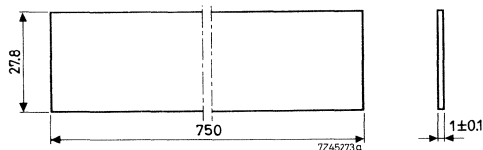
MECHANICAL DATA

Dimensions in mm



mounting strip of  
insulating material

Weight with cover:  
615 g



insulating plate (cover)

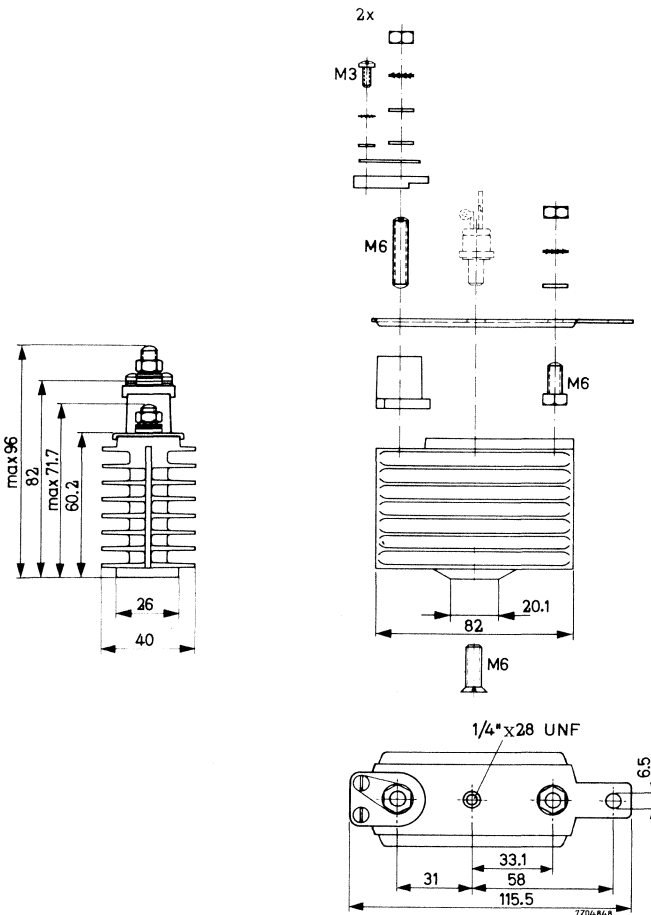
### DIECAST HEATSINK

Diecast heatsink of aluminium alloy, painted black, with 1/4" x 28 UNF tap hole for devices in DO-5 or TO-48 envelopes.

Weight: 305 g

Dimensions in mm

Fig. 1





The graphs are valid for the combination of device and heatsink.

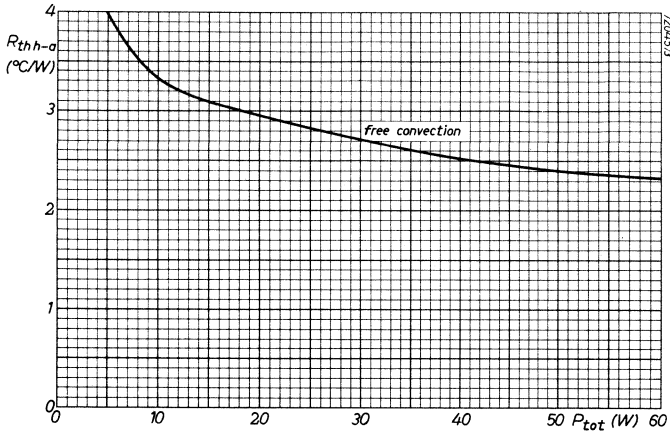


Fig.2

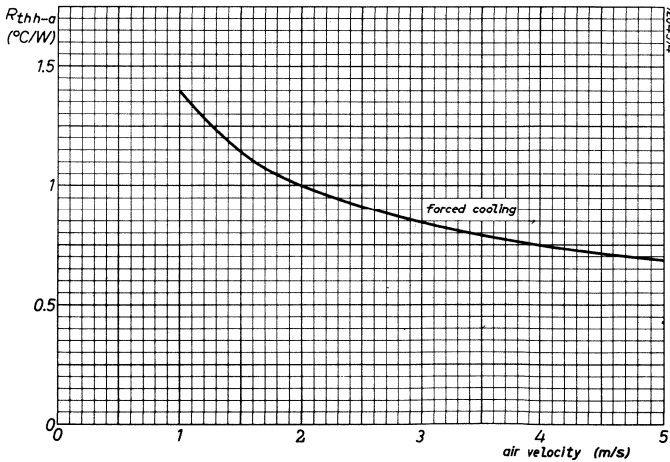


Fig.3

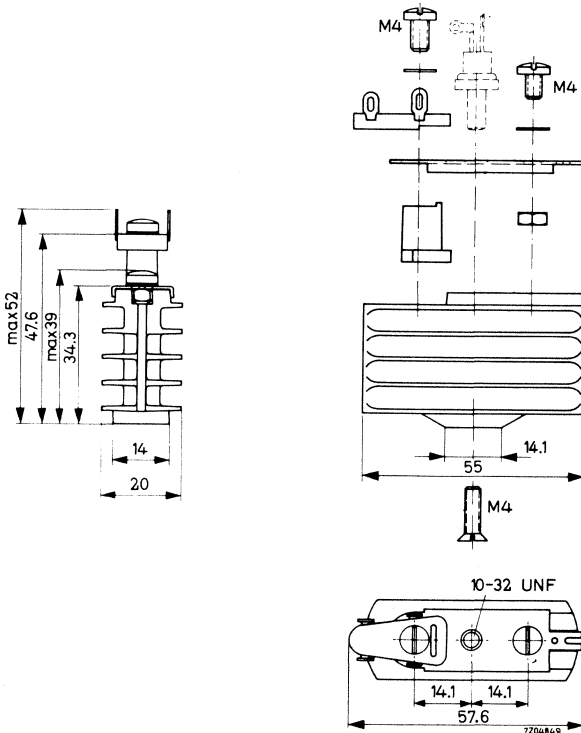
### DIECAST HEATSINK

Diecast heatsink of aluminium alloy, painted black, with 10-32 UNF tap hole for devices in DO-4 or TO-64 envelopes.

Weight: 55 g

Dimensions in mm

Fig.1



The graphs are valid for the combination of device and heatsink.

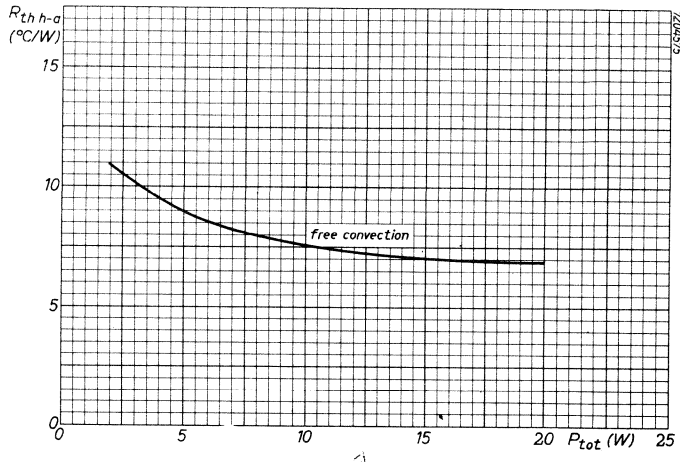


Fig.2

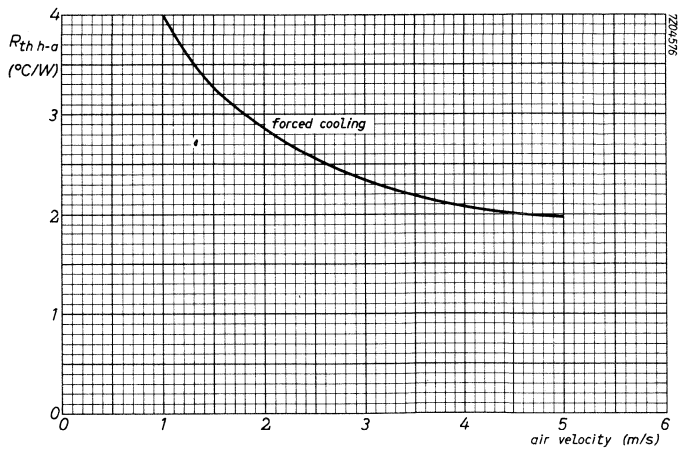


Fig.3

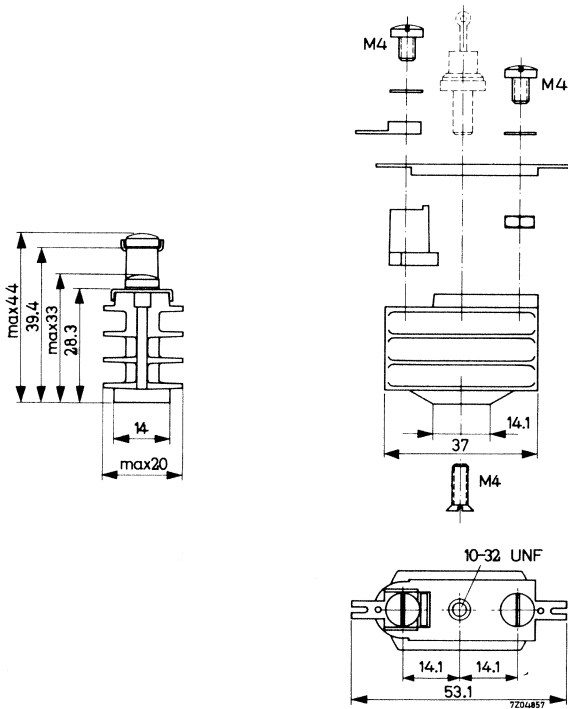
### DIECAST HEATSINK

Diecast heatsink of aluminium alloy, painted black, with 10-32 UNF tap hole for devices in DO-4 or TO-64 envelopes.

Weight: 33 g

Dimensions in mm

Fig.1



The graphs are valid for the combination of device and heatsink

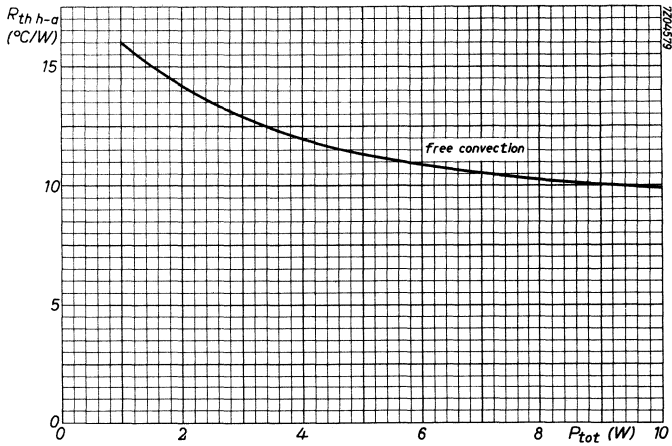


Fig.2

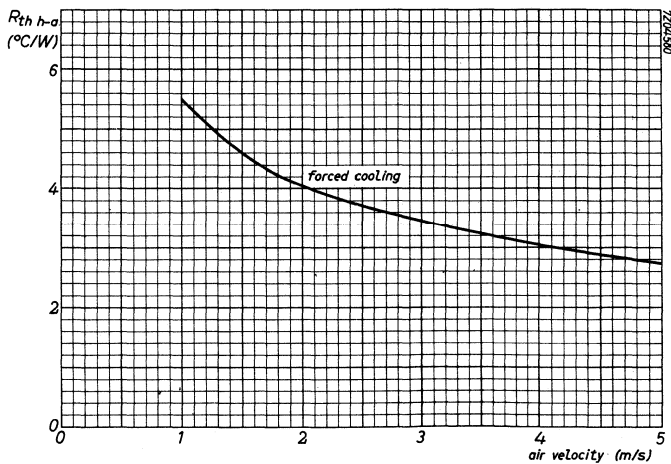


Fig.3

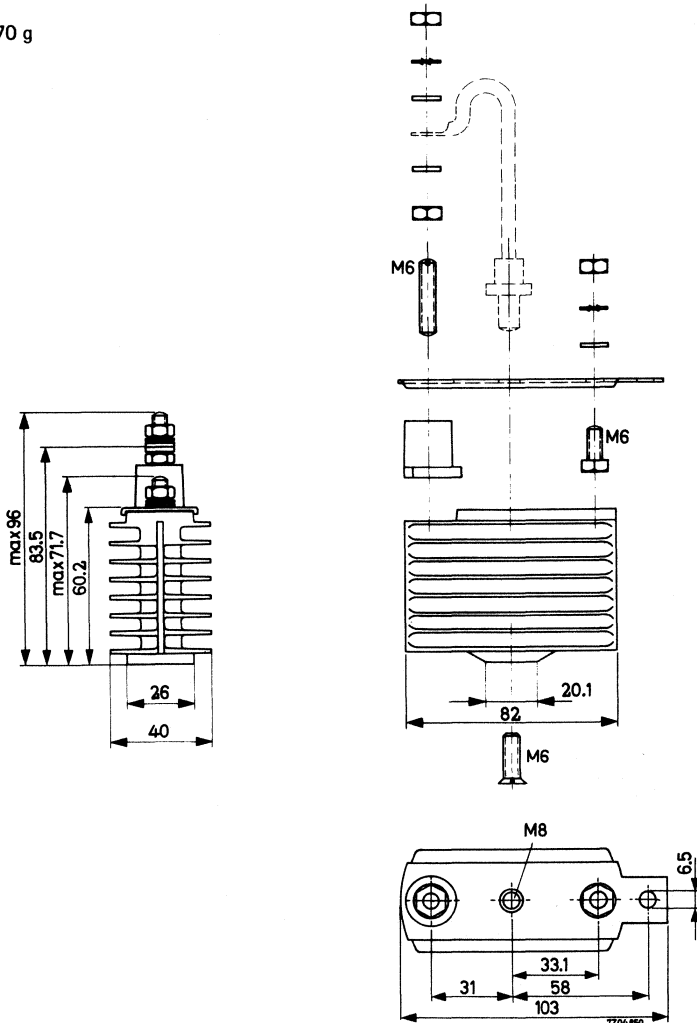
### DIECAST HEATSINK

Diecast heatsink of aluminium alloy, painted black, with M8 tap hole for rectifier device.

Dimensions in mm

Weight: 270 g

Fig. 1



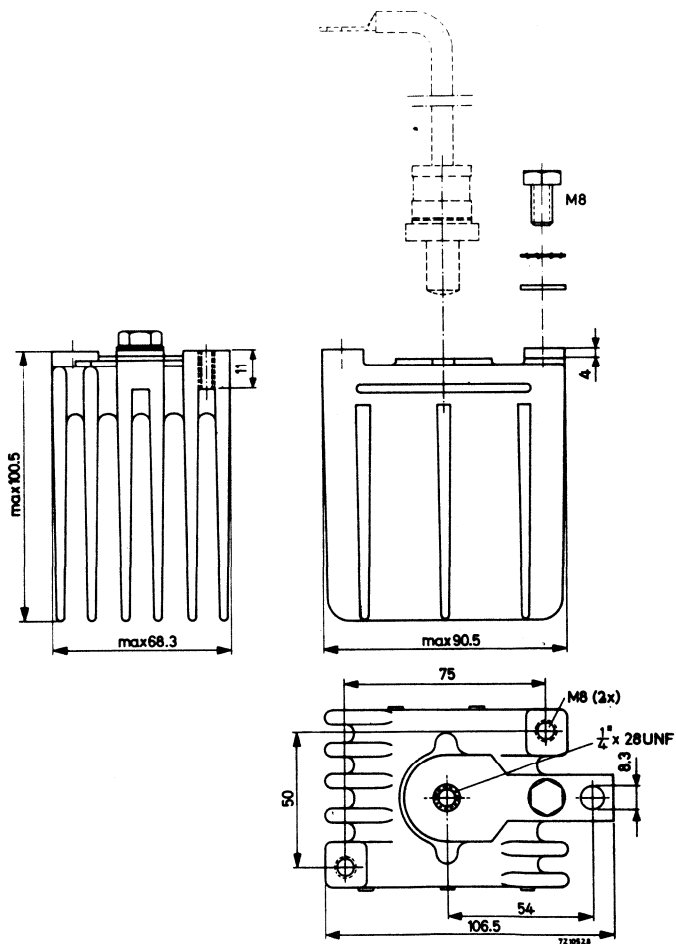
### DIECAST HEATSINK

Diecast heatsink of aluminium alloy, painted black, with  $\frac{1}{4}$ " x 28 UNF tap hole for rectifier device.

Weight: 690 g

Dimensions in mm

Fig.1







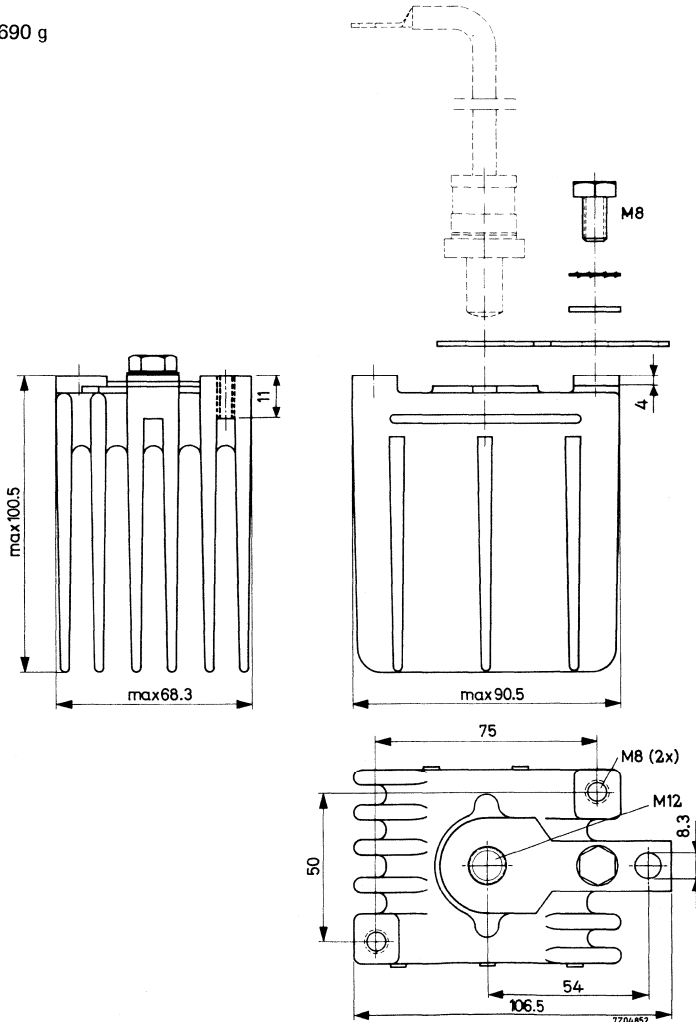
### DIECAST HEATSINK

Diecast heatsink of aluminium alloy, painted black, with M12 tap hole for rectifier device.

Dimensions in mm

Weight: 690 g

Fig.1



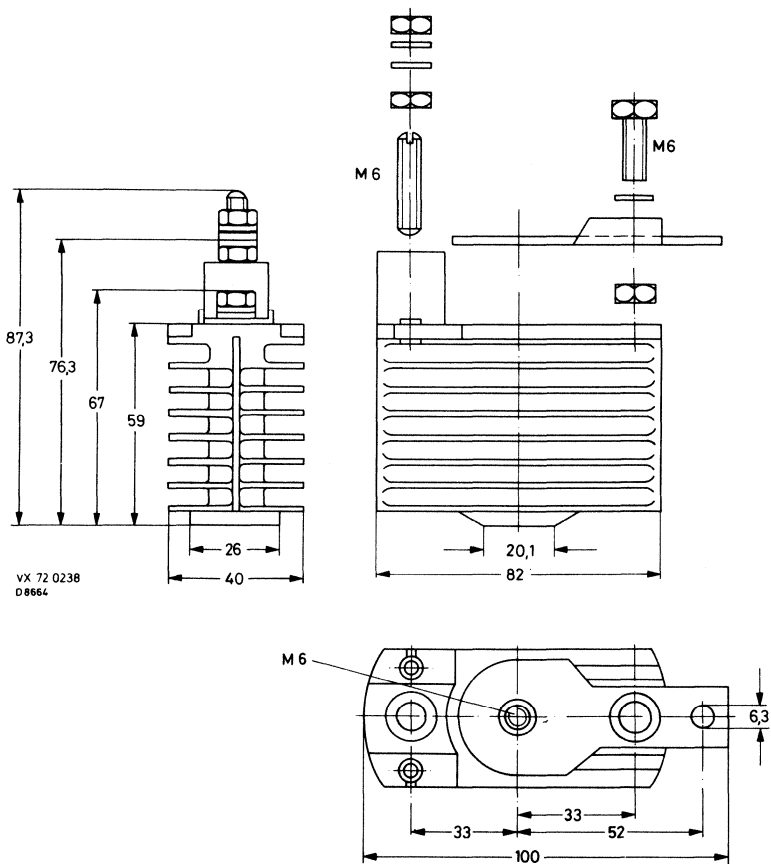
## DIECAST HEATSINK

For DO-5 rectifier diodes and TO-48 thyristors and triacs.

Weight: 270 g

Dimensions in mm

Fig. 1



Tap hole for fixing the heatsink: M6

The graphs are valid for the combination of device and heatsink.

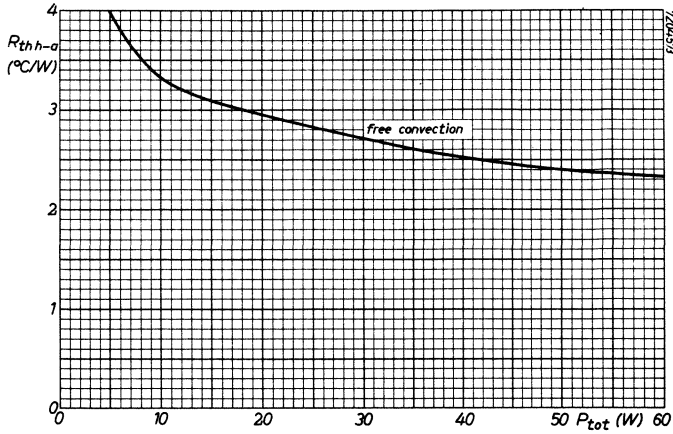


Fig.2

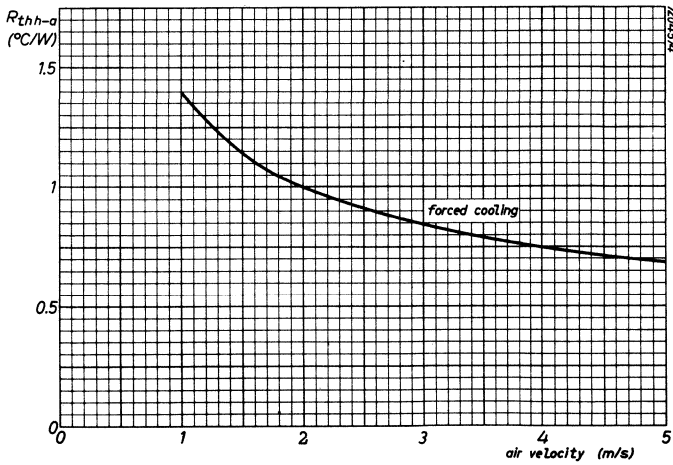


Fig.3

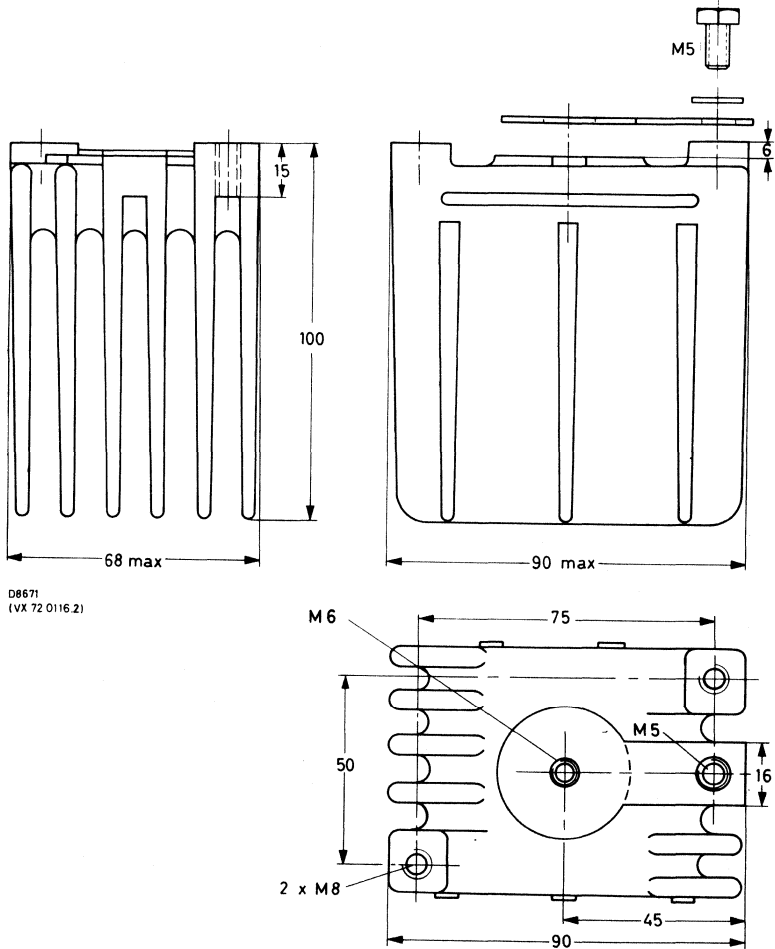
# DIECAST HEATSINK

For DO-5 rectifiers and TO-48 thyristors and triacs.

Weight: 690 g

Dimensions in mm

Fig.1



The graphs are valid for the combination of device and heatsink.

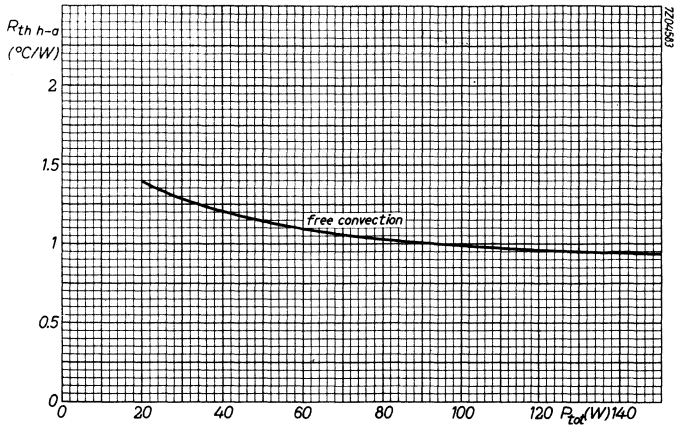


Fig.2

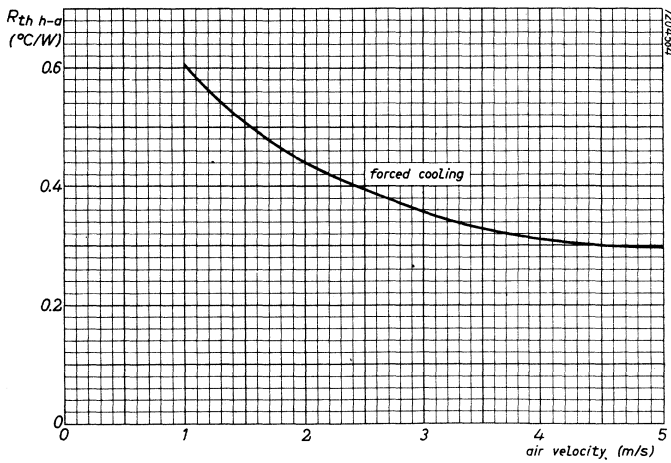


Fig.3

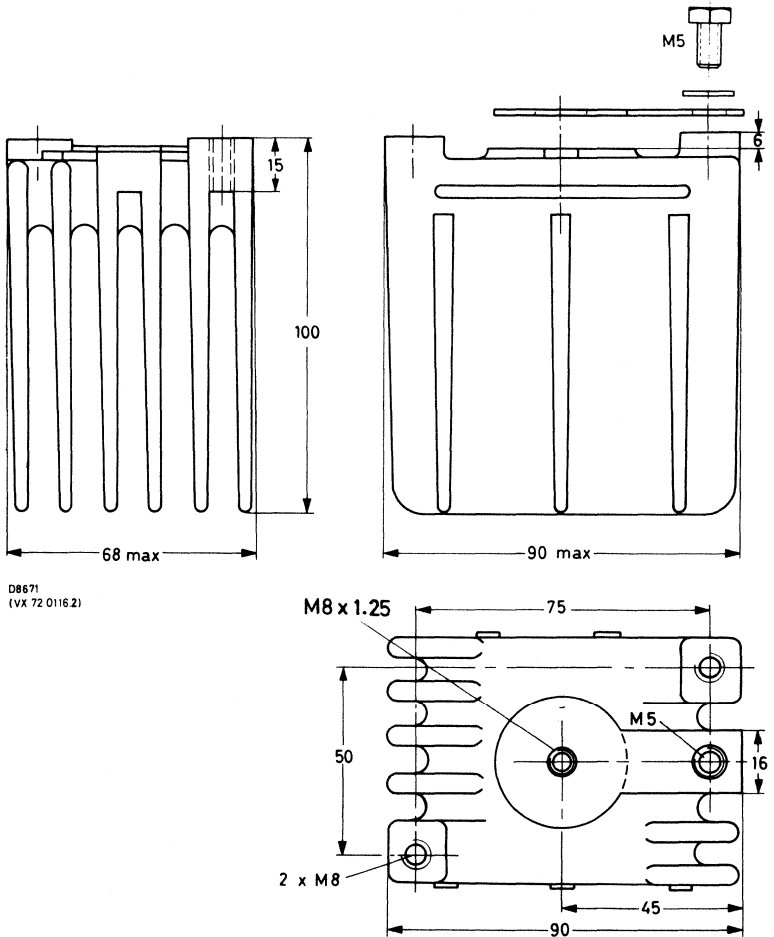
# DIECAST HEATSINK

For DO-5 rectifiers and TO-48 thyristors and triacs.

Weight: 690 g

Dimensions in mm

Fig.1



The graphs are valid for the combination of device and heatsink.

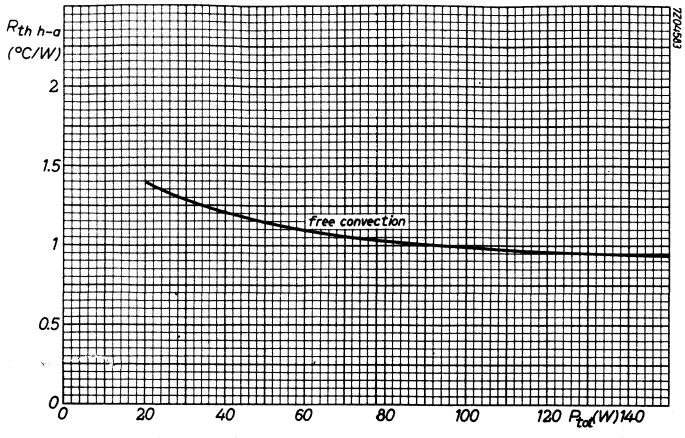


Fig.2

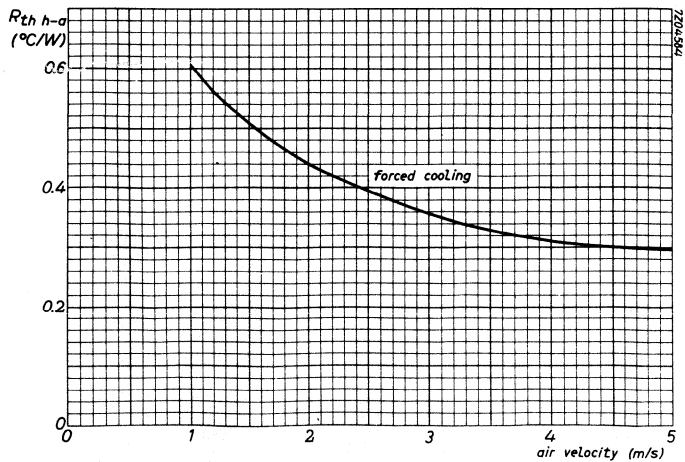


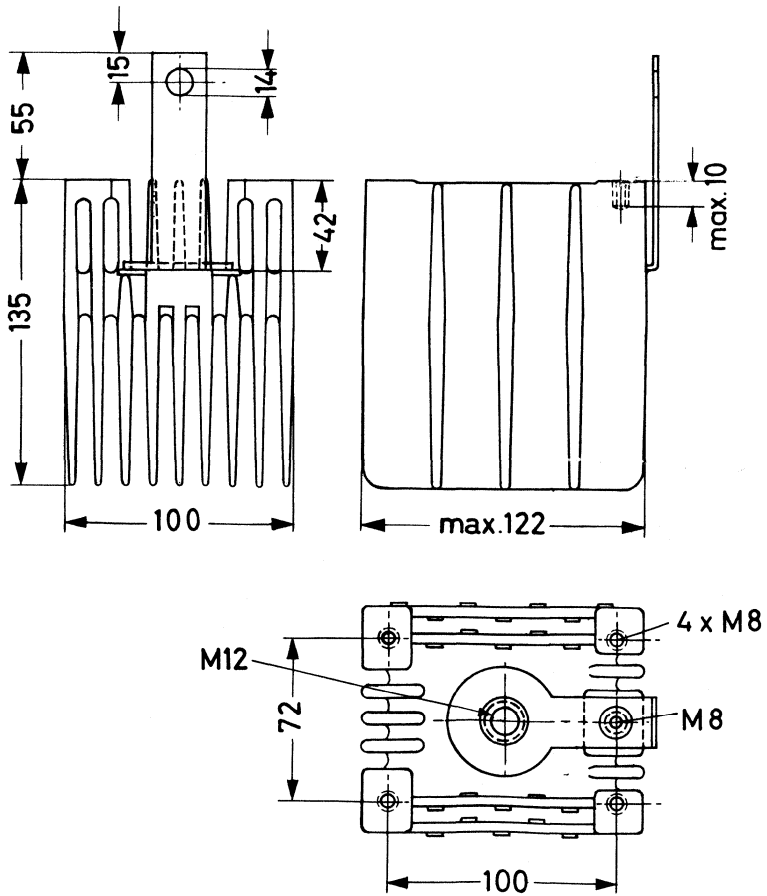
Fig.3

DIECAST HEATSINK

Weight: 1.9 kg

Dimensions in mm

Fig.1



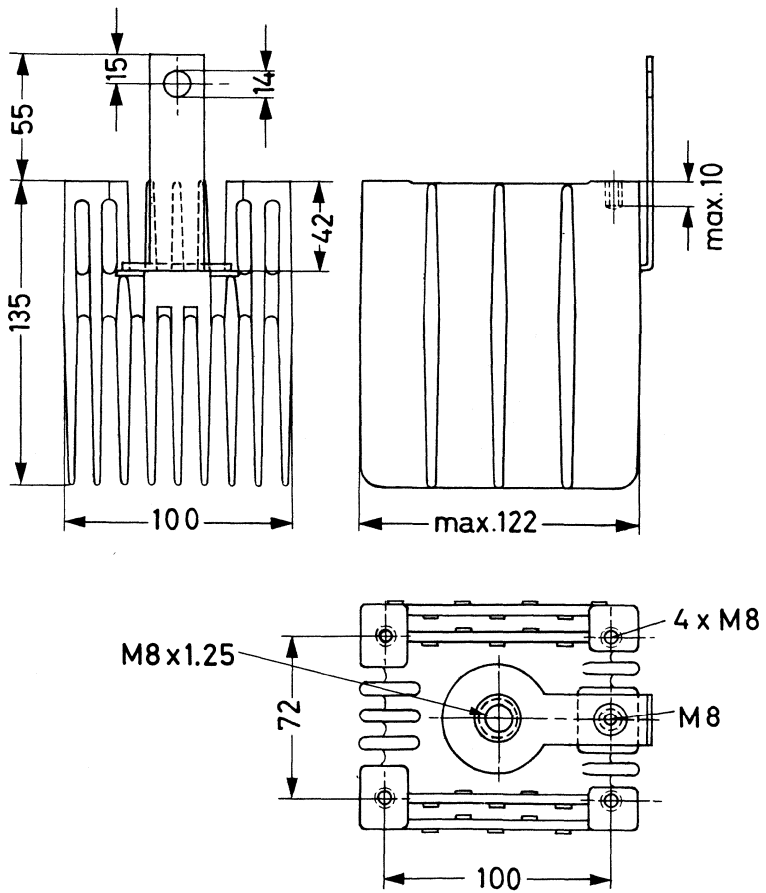


DIECAST HEATSINK

Weight: 1.9 kg

Dimensions in mm

Fig.1

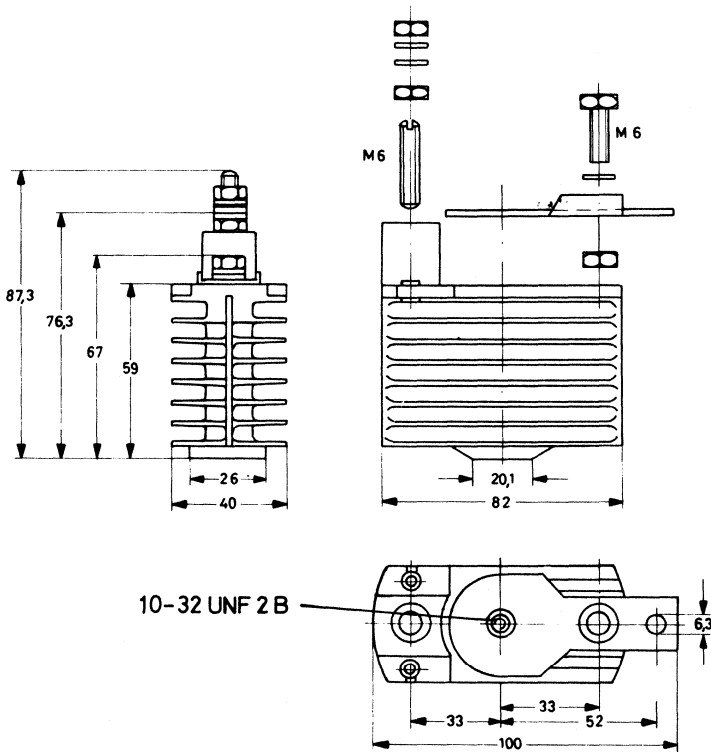


DIECAST HEATSINK

Weight: 270 g

Dimensions in mm

Fig.1



Tap hole for fixing the heatsink: M8

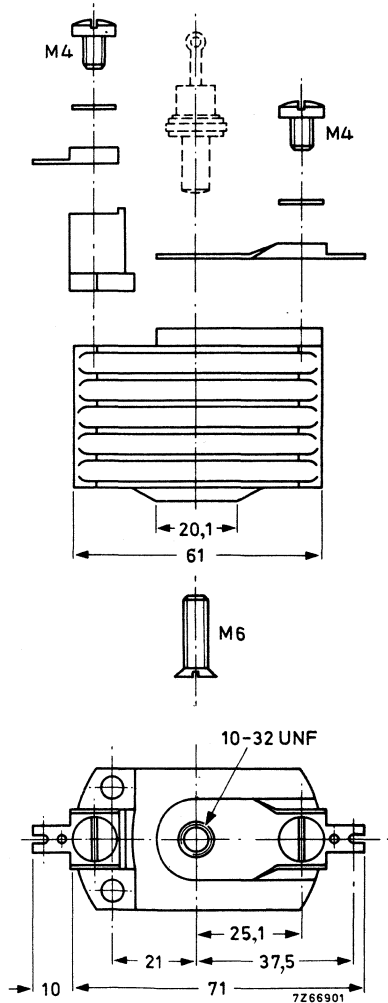
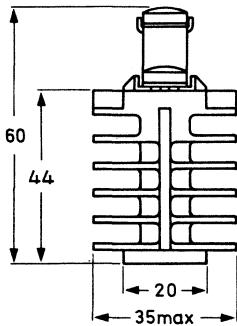
### DIECAST HEATSINK

Diecast heatsink of aluminium alloy, painted black, with 10-32 UNF tap hole for rectifier device.

Dimensions in mm

Weight: 135 g

Fig.1



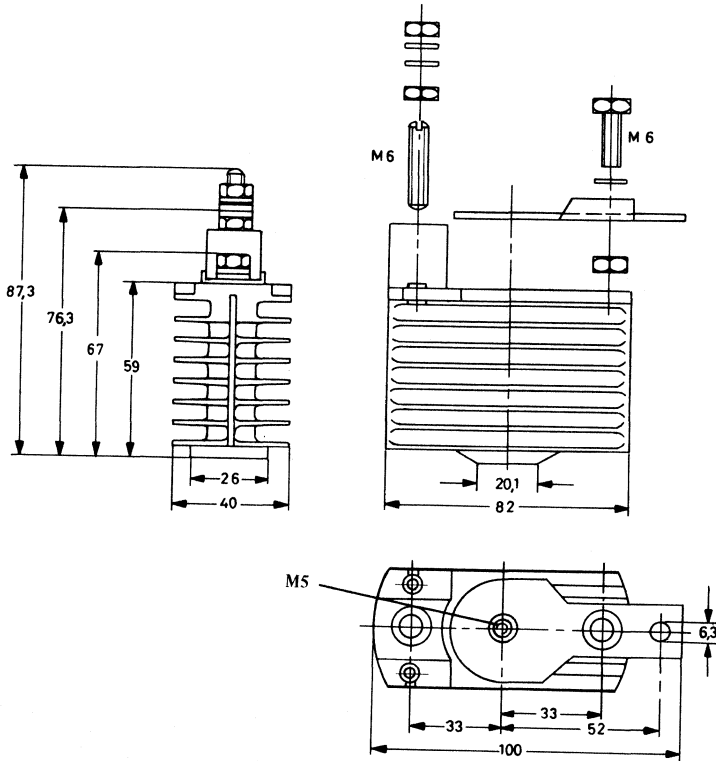
## DIECAST HEATSINK

For DO-4 and TO-64 devices with M5 stud

Weight: 270 g

Dimensions in mm

Fig.1



Tap hole for fixing the heatsink: M6

The graphs are valid for the combination of device and heatsink.

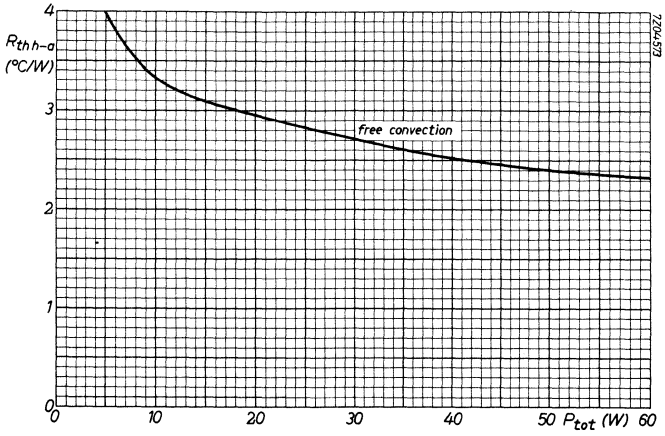


Fig.2

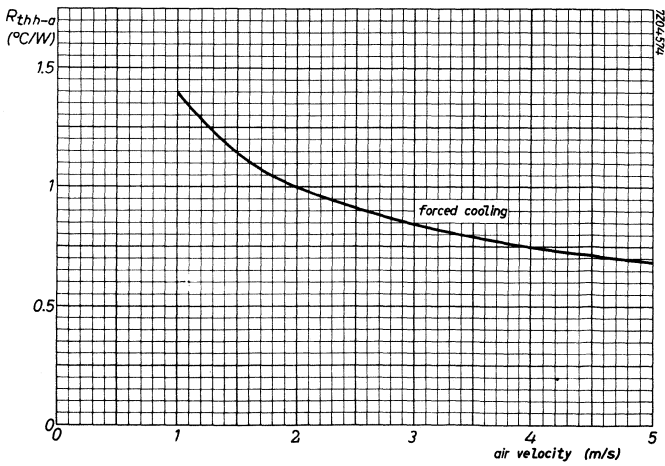


Fig.3



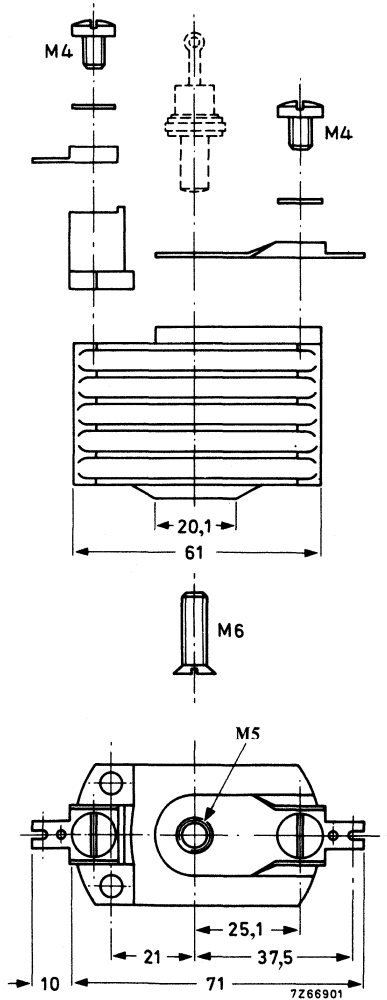
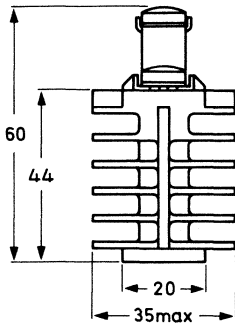
### DIECAST HEATSINK

Diecast heatsink of aluminium alloy, painted black, with M5 tap hole for rectifier device.

Dimensions in mm

Weight: 135 g

Fig.1



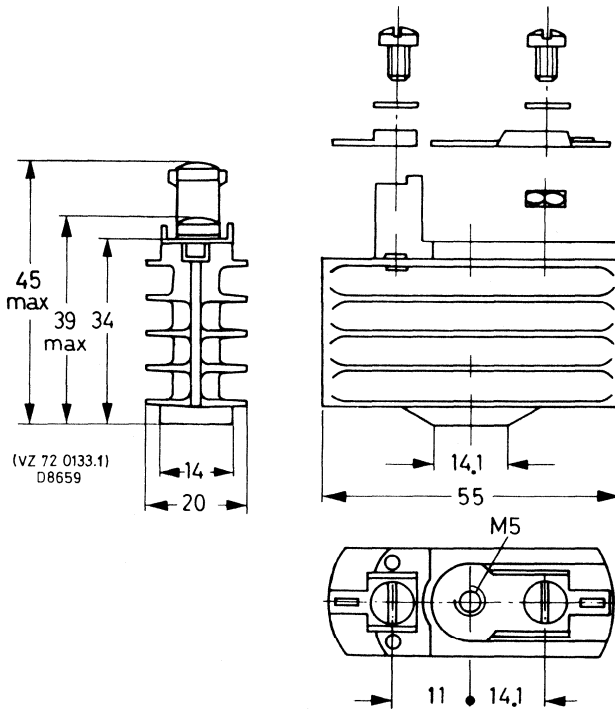
### DIECAST HEATSINK

Diecast heatsink of aluminium alloy, painted black, with M5 tap hole for devices in DO-4 and TO-64 envelopes.

Weight: 55 g

Dimensions in mm

Fig.1



Tap hole for fixing the heatsink: M4



The graphs are valid for the combination of device and heatsink.

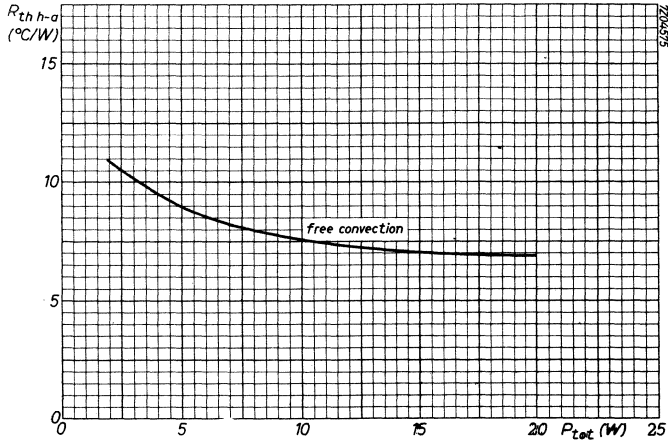


Fig.2

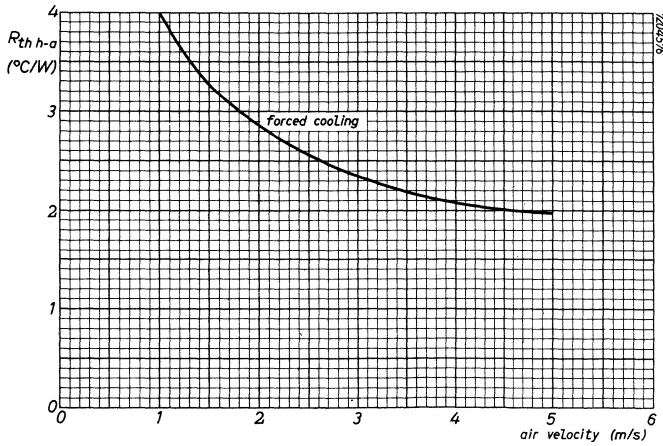


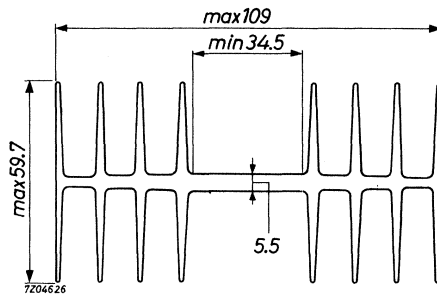
Fig.3

**EXTRUDED ALUMINIUM HEATSINK**

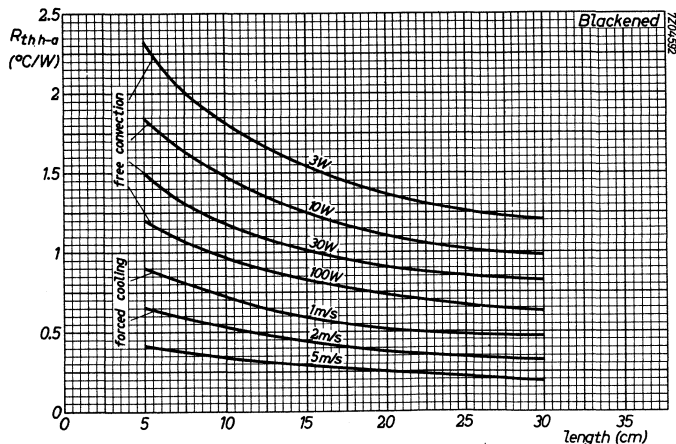
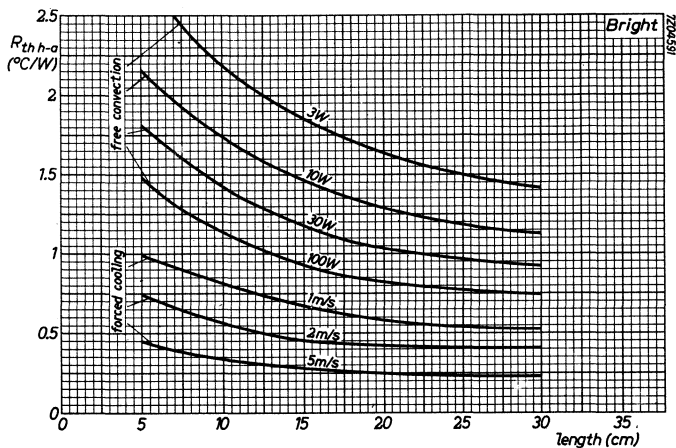
Extruded heatsink of aluminium alloy.  
The extrusion is supplied unpainted, in lengths of 1,5 m.

Weight: 4 kg per 1,5 m.

Dimensions in mm



The graphs are valid for the combination of device and heatsink.

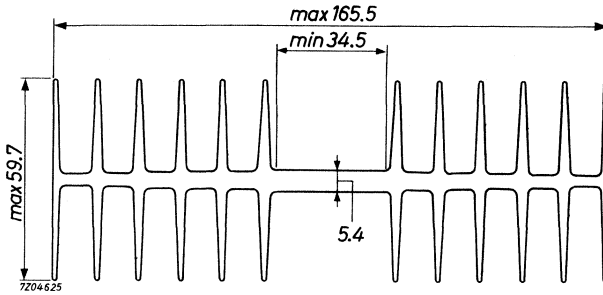


**EXTRUDED ALUMINIUM HEATSINK**

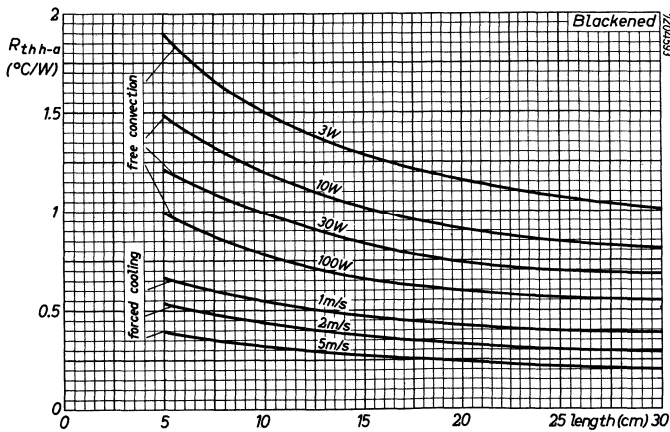
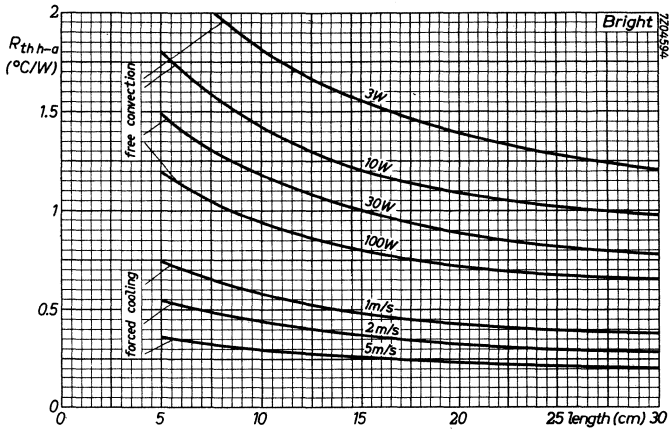
Extruded heatsink of aluminium alloy.  
The extrusion is supplied unpainted, in lengths of 1,5 m.

Weight: 6 kg per 1,5 m.

Dimensions in mm



The graphs are valid for the combination of device and heatsink.



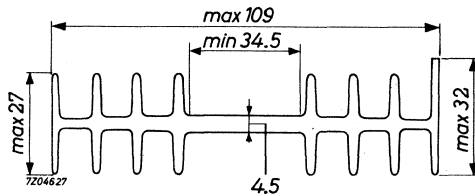
**EXTRUDED ALUMINIUM HEATSINK**

Extruded heatsink of aluminium alloy.

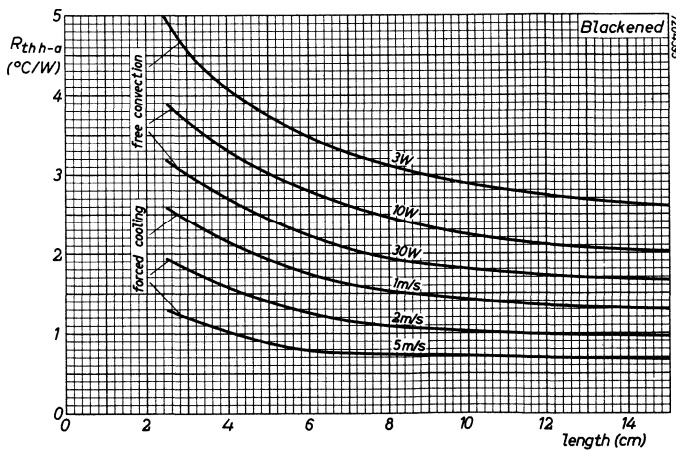
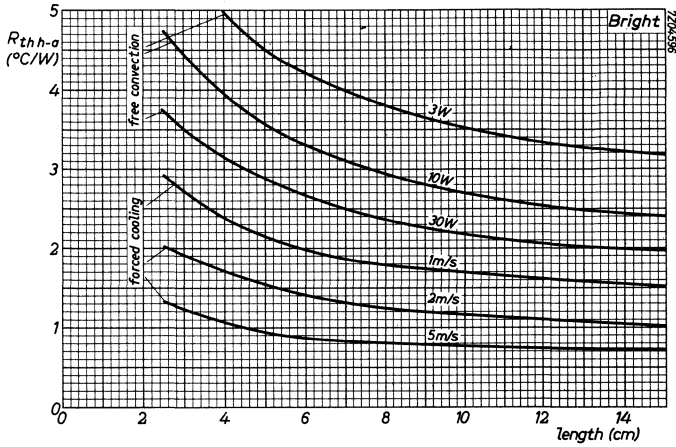
The extrusion is supplied unpainted, in lengths of 1,5 m.

Weight: 2,4 kg per 1,5 m.

Dimensions in mm



The graphs are valid for the combination of device and heatsink.



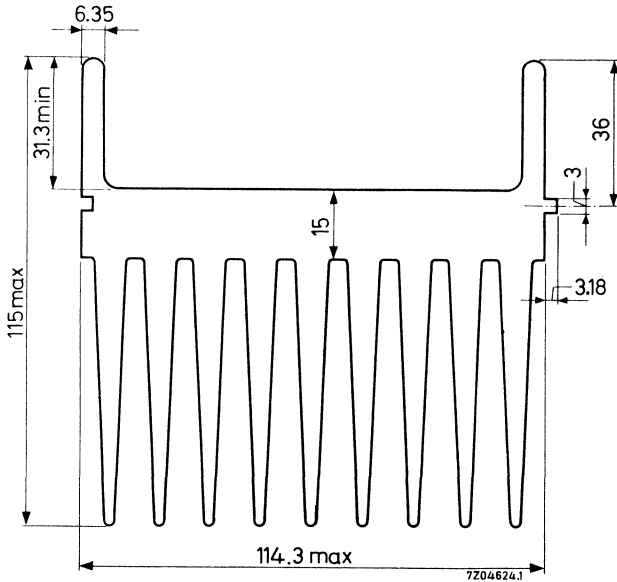
### EXTRUDED ALUMINIUM HEATSINK

Extruded heatsink of aluminium alloy.  
The extrusion is supplied unpainted, in lengths of 1.5 m.

Weight: 16.2 kg per 1.5 m.

Dimensions in mm

Fig.1





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# POWER DIODES, THYRISTORS, TRIACS

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